
1. Lab 0 - Part 1

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1.1 - Variables

1. Execute and explain the following commands (pay attention to what variable `ans` points to):

This MATLAB command calculates 6^2 , finding the result of 36 and storing it into the `ans` variable.

```
6^2
```

```
ans =
```

```
36
```

This MATLAB command prints the value of the `ans` variable to the console.

```
ans
```

```
ans =
```

```
36
```

This MATLAB command takes the value of the `ans` variable, divides it by 6, stores it back into the `ans` variable, and prints it to the console

```
ans/6
```

```
ans =
```

```
6
```

This MATLAB command prints the value of the `ans` variable to the console (here, `ans` is the result of the last computation performed).

```
ans
```

```
ans =
```

```
6
```

2. MATLAB can be used as a very expensive calculator. Execute and explain the following commands:

This MATLAB equation makes use of the pi constant to evaluate $\pi^2 - 10$. It then stores the result into ans. I will omit this part about storing the result into ans hereinafter.

```
pi*pi-10
```

```
ans =
```

```
-0.1304
```

This calculates the sine of $\pi/4$, using the sine trigonometric function included with MATLAB and the pi constant.

```
sin(pi/4)
```

```
ans =
```

```
0.7071
```

This calculates the square of ans, where ans is the $\sin(\pi/4)$.

```
ans^2
```

```
ans =
```

```
0.5000
```

3. Just like in other programming languages, you can assign variables in MATLAB. Execute and explain the following commands and watch the area labeled ?workspace? on the side of your screen. The variables will appear as they are assigned.

This calculates the $\sin(\pi/5)$ and assigns it to the variable x for later use.

```
x = sin(pi/5)
```

```
x =
```

```
0.5878
```

This calculates the $\cos(\pi/5)$.

```
cos(pi/5)
```

```
ans =  
  
0.8090
```

This calculates the $\sqrt{1-x^2}$ and assigns it to y , where x was assigned to be the result of $\sin(\pi/5)$ in a previous step.

```
y = sqrt(1-x*x);
```

This prints `ans` to the console, where `ans` was assigned to be $\cos(\pi/5)$ in a previous step. Note that it was not the result of $\sqrt{1-x^2}$ in the previous step, as that result was stored in y .

```
ans
```

```
ans =  
  
0.8090
```

Question 1: What is the numerical value of x and y ?

We can see from the below that $x = 0.5878$ and $y = 0.8090$

```
x  
y  
  
x =  
  
0.5878
```

```
y =  
  
0.8090
```

1.2 - Vectors and Colon Operator

1. Execute and explain the following commands:

This command creates a series of values from 0 to 6, inclusive, with a step size of 1 and assigns it to x .

```
x = 0:6;
```

This command creates a series of values bounded by 2 and 17 with a step size of 4 and assigns it to y .

```
y = 2:4:17;
```

This command creates a series of values bounded by 2 and 4 with a step size of $1/9$ ($\sim .1111$) and assigns it to z .

```
z = 2:(1/9):4;
```

This command first creates a series of values bounded by 0 and 2 with a step size of .1, then multiplies π into each term, and finally assigns it to t .

```
t = pi*[0:0.1:2];
```

2. With this colon notation in MATLAB, extracting/inserting numbers into a vector is made easy. Execute and explain the following commands:

`zeros(1,3)` creates a vector of length 3 with all zeroes. `linspace(0,1,5)` creates a list of length 5 of evenly spaced elements that range from 0 -> 1. `ones(1,4)` creates a vector of length 4 with all ones. The square bracketed comma delimited list concatenates the three vectors together.

```
xx = [zeros(1,3), linspace(0,1,5), ones(1,4)];
```

This command returns the 4th through the 6th elements, inclusive, from `xx`.

```
xx(4:6)
```

```
ans =
```

```
0    0.2500    0.5000
```

This command returns the size of the rows and columns in this matrix. Here, the amount of rows is 1 and the amount of columns is 12.

```
size(xx)
```

```
ans =
```

```
1    12
```

This command returns the amount of columns in this matrix. As discussed above, that result is 12.

```
length(xx)
```

```
ans =
```

```
12
```

This command slices into the `xx` vector starting at the second element and continuing until the end, and uses a step size of 2.

```
xx(2:2:length(xx))
```

```
ans =
```

```
0    0    0.5000    1.0000    1.0000    1.0000
```

Execute and explain the following commands:

This command assigns `xx` to `yy`

```
yy = xx;
```

This command assigns yy from 4 to 6 inclusive to be pi multiplied into the vector pi*[1,2,3]

```
yy(4:6) = pi*(1:3);
```

3. Now, after learning how the above code works, Write one line of code (using vectorization) that will take the vector xx and take the elements with an even index {xx(2), xx(4), ...} and replace them with pi^pi (thats pi to the exponent pi).

```
xx(2:2:length(xx)) = pi^pi;
```

1.3 - Loops

1. Read help for page. Execute and explain the following commands:

The command x=x+1 iterates 4 times, as k=1 the first iteration, k=2 the second iteration, and so forth until k=4 the final iteration. The loop is bounded from 1 -> n so x = n at the commencement of the loop.

```
x = 0;
for k = 1:4
    x = x+1;
end
```

2. Using for loop, generate a vector containing the following elements: 1^1, 2^2, 3^3, ..., 9^9. Write code and explain.

This code first initializes a vector of length 9 to be all 0. Then, we have a for loop iterate i from 1->9 that sets the ith element to be i^i.

```
exponentiated = zeros(1,9);
for i = 1:9
    exponentiated(i) = i^i;
end
exponentiated
```

exponentiated =

Columns 1 through 6

	1	4	27	256	3125
46656					

Columns 7 through 9

823543	16777216	387420489
--------	----------	-----------

3. In many cases, code with loops can be optimized by vectorization. Functions like exp() and cos() are defined for vector inputs. Example:

```
M = 200;
for k = 1:M
    x(k) = k;
    y(k) = cos(0.001*pi*x(k)*x(k));
end
```

The piece of code above can be optimized as:

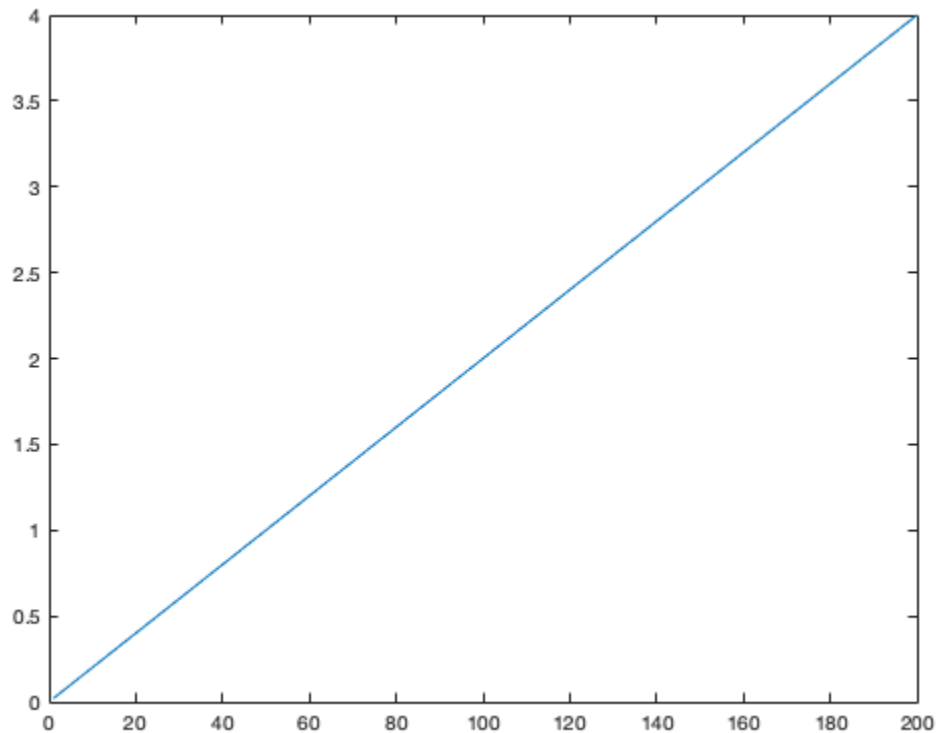
```
M = 200;  
y = cos(0.001*pi*(1:M).*(1:M));
```

Now use this same idea to optimize the following code by removing the for loop. Write 2 or 3 lines of code, plot, and explain:

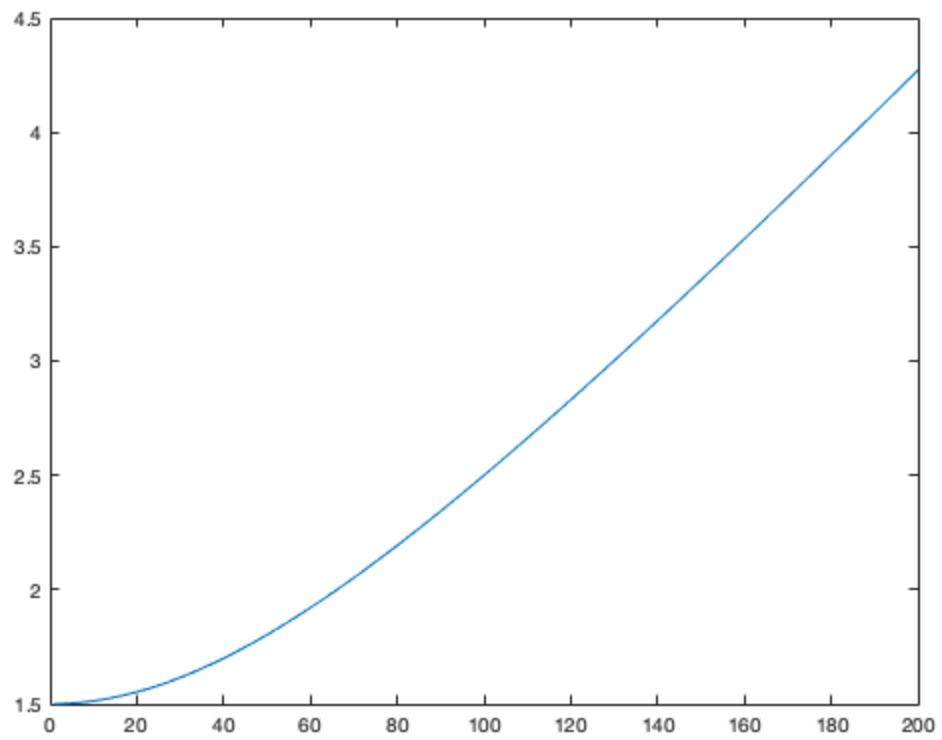
```
N = 200;  
for k = 1:N  
    xk(k) = k/50;  
    rk(k) = sqrt(xk(k)*xk(k) + 2.25);  
    sig(k) = exp(j*2*pi*rk(k));  
end
```

As each iteration of the previous for loop was not dependent on the other iterations of the for loop, it was quite easy to parallelize these operations with the use of matrices. Simply create a vector ranging from 1->200 and divide it by 50 for xk. For rk, perform element wise multiplication on rk*rk and then add 2.25 to each element as well. Finally, take the square root. To calculate sig, just calculate $j*2*\pi*rk$ and exponentiate it. This performs element wise operations for each element of sig.

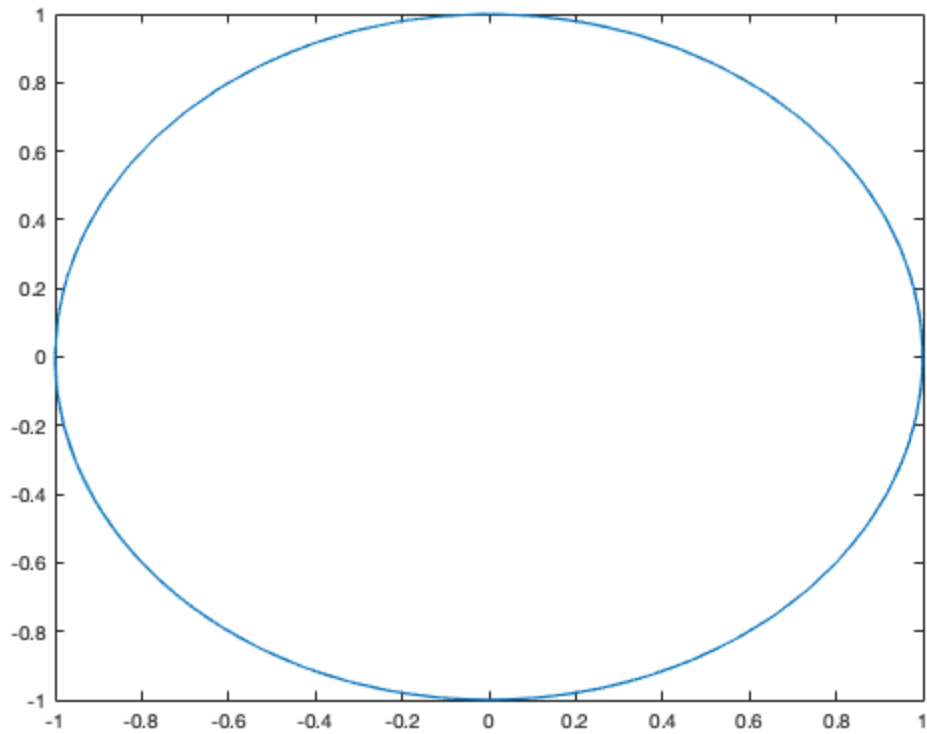
```
N = 200;  
xk = [1:200]/50;  
rk = sqrt(xk.*xk + 2.25);  
sig = exp(j*2*pi*rk);  
  
plot(xk);
```



```
plot(rk);
```



```
plot(sig);
```



Question 2: What's the value of x after the code executes?

As seen below, the value of x is equal to:

x

x =

Columns 1 through 13

	1	2	3	4	5	6	7	8	9	10	11
12	13										

Columns 14 through 26

	14	15	16	17	18	19	20	21	22	23	24
25	26										

Columns 27 through 39

	27	28	29	30	31	32	33	34	35	36	37
38	39										

Columns 40 through 52

40	41	42	43	44	45	46	47	48	49	50
51	52									

Columns 53 through 65

53	54	55	56	57	58	59	60	61	62	63
64	65									

Columns 66 through 78

66	67	68	69	70	71	72	73	74	75	76
77	78									

Columns 79 through 91

79	80	81	82	83	84	85	86	87	88	89
90	91									

Columns 92 through 104

92	93	94	95	96	97	98	99	100	101	102
103	104									

Columns 105 through 117

105	106	107	108	109	110	111	112	113	114	115
116	117									

Columns 118 through 130

118	119	120	121	122	123	124	125	126	127	128
129	130									

Columns 131 through 143

131	132	133	134	135	136	137	138	139	140	141
142	143									

Columns 144 through 156

144	145	146	147	148	149	150	151	152	153	154
155	156									

Columns 157 through 169

157	158	159	160	161	162	163	164	165	166	167
168	169									

Columns 170 through 182

170	171	172	173	174	175	176	177	178	179	180
181	182									

Columns 183 through 195

```
183 184 185 186 187 188 189 190 191 192 193
194 195
```

Columns 196 through 200

```
196 197 198 199 200
```

Question 3: What is the purpose of the dot before the asterisk in line two of the above?

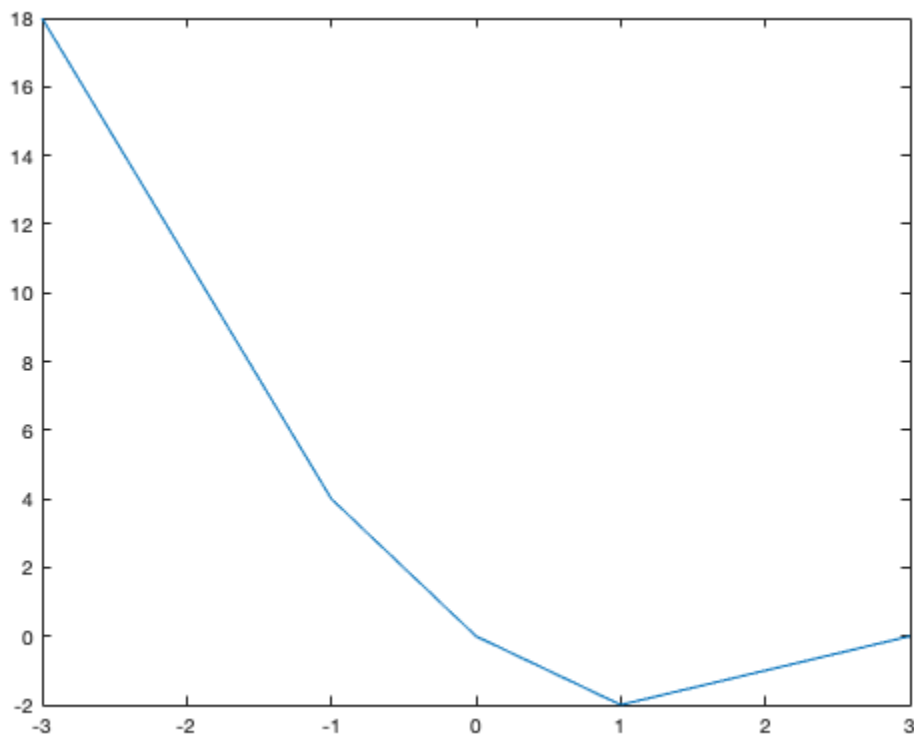
The purpose of the dot before the asterisk in line two of the above means that we want to perform element wise multiplication, NOT matrix multiplication. The dot is commonly used to denote this in many programming contexts.

1.4 - Plot

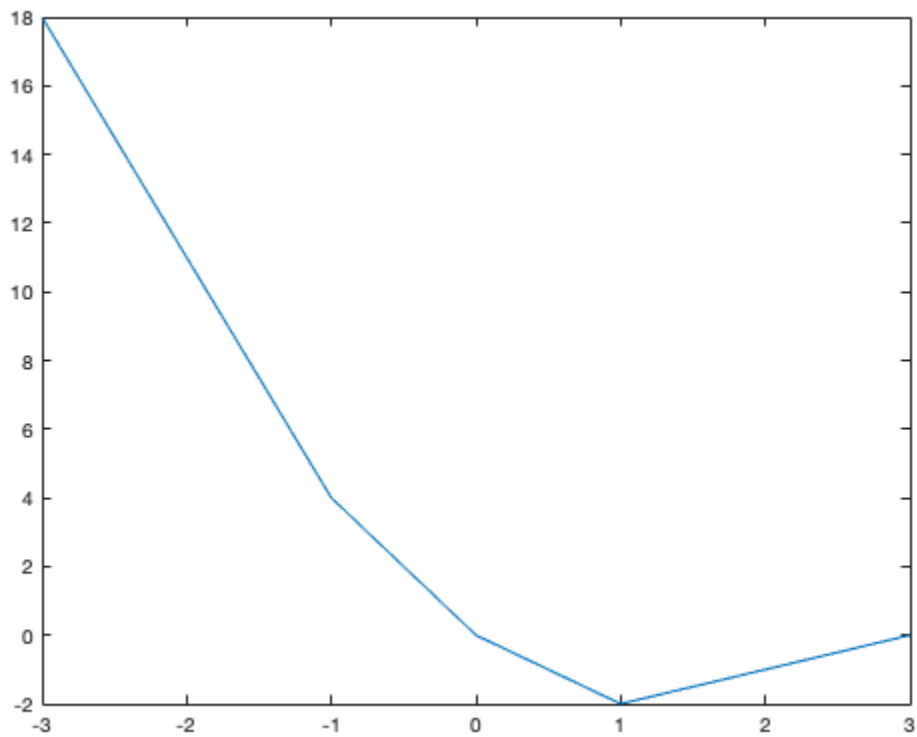
1. Execute and explain the following commands

The following code: Declares a vector x , equal to $[-3 \ -1 \ 0 \ 1 \ 3]$ Maps the vector x to a vector y using the equation $x.*x - 3*x$ Creates a new plot in figure 4, plotting x on the x axis and y on the y axis. Assigns z to be the sum of x and jy , and then plots it on figure 5.

```
x = [-3 -1 0 1 3];
y = x.*x - 3*x;
plot(x, y);
```



```
z = x + y * sqrt(-1);  
plot(z);
```



Question 4: What is the difference between $a*b$ and $a.*b$, where a and b are matrices?

The difference between $a*b$ and $a.*b$, where a and b are matrices, is as follows. $a*b$ means matrix multiplication, a special operation that can be performed on only matrices. This operation is very different than element wise multiplication, where each corresponding i and j value is multiplied together.

1.5 - Functions

1. Write a function called `oddsummer` that takes a positive integer n as its argument and returns the sum of all odd numbers between 1 and n .

```
oddsummer(3)
```

```
ans =
```

```
4
```

```
oddsummer(5)
```

```
ans =
```

9

```
oddsummer(99)
```

```
ans =
```

```
2500
```

2. Write a function called `hellos`, taking a positive integer `n` as its argument and displays the word 'hello' `n` times.

```
hellos(1)
```

```
hello
```

```
hellos(5)
```

```
hello
```

```
hello
```

```
hello
```

```
hello
```

```
hello
```

```
hellos(10)
```

```
hello
```

```
hello
```

```
hello
```

```
hello
```

```
hello
```

```
hello
```

```
hello
```

```
hello
```

```
hello
```

```
hello
```

1.6 - Comments

No work to be completed.

1.7 - Complex Numbers in MATLAB

1. MATLAB reserves the letter `i` or `j` as `sqrt(-1)`. In this class, the letter `i` is usually used as iterator of loops. Hence, the letter `j` will mostly be reserved as `sqrt(-1)`.

```
z = 3 + 4*j, w = -3 + 4*j % Declaring complex numbers
real(z), imag(z) % Real and imaginary components
abs([z,w]) % Computes magnitudes
conj(z+w) % Computes complex conjugate of the sum
angle(z) % Computes the phase of the complex number
```

```
% Also written as atan2(imag(z)/real(z))
exp(j*pi) % Using Euler's formula, cos(pi)+j*sin(pi)
exp(j*[pi/4, 0, -pi/4])

z =

    3.0000 + 4.0000i

w =

   -3.0000 + 4.0000i

ans =

     3

ans =

     4

ans =

     5     5

ans =

    0.0000 - 8.0000i

ans =

    0.9273

ans =

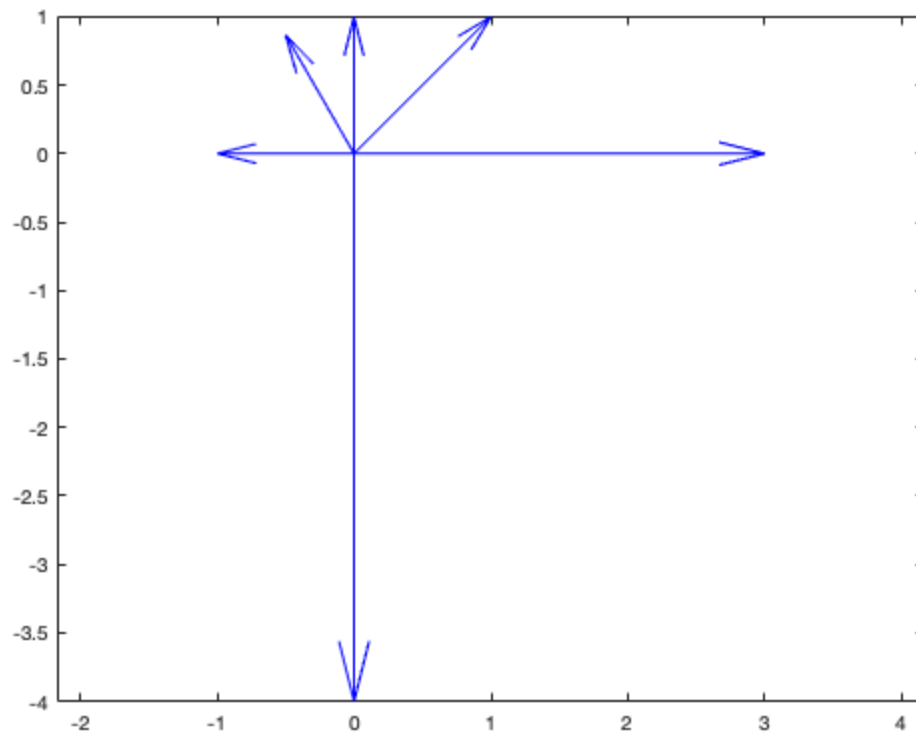
   -1.0000 + 0.0000i

ans =

    0.7071 + 0.7071i    1.0000 + 0.0000i    0.7071 - 0.7071i
```

2. MATLAB can compute complex valued formulas and display the results as phasor diagrams. Use the following `zvect` function to plot five vectors all on one graph. Execute and plot:

```
zvect([1 + j, j, 3 - 4*j, exp(j*pi), exp(2j*pi/3)]);
```



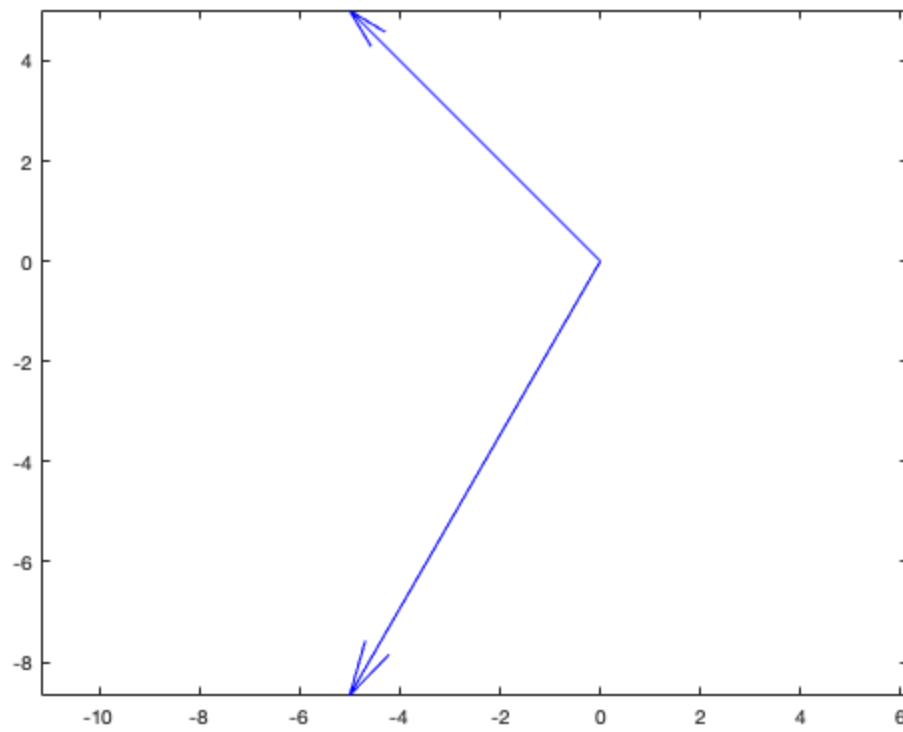
3. Use $z1 = 10e^{(-j*2*\pi/3)}$ and $z2 = -5 + 5j$ for all parts of this section.

```
z1 = 10*exp(-j*2*pi/3);
z2 = -5 + 5j;
```

a. Plot $z1$ and $z2$ using `zvect` and print them with `zprint`.

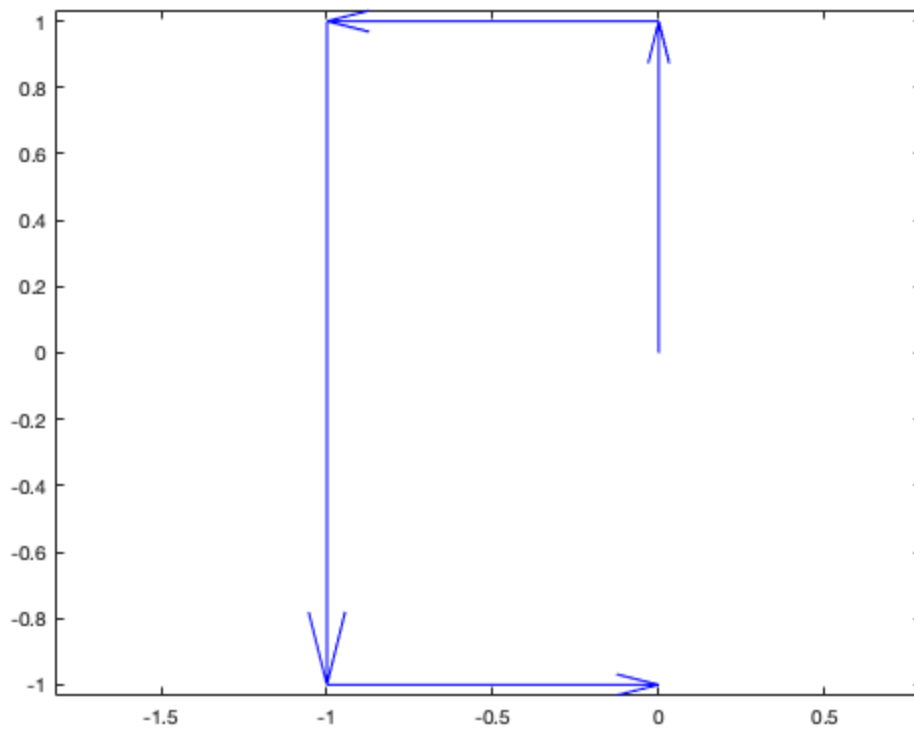
```
zvect([z1,z2]);
zprint([z1,z2])
```

$Z =$	X	$+ jY$	$Magnitude$	$Phase$	Ph/pi	$Ph(deg)$
	-5	-8.66	10	-2.094	-0.667	-120.00
	-5	5	7.071	2.356	0.750	135.00



b. Execute and explain: The following adds the vectors together and plots each step of the way.

```
zcat([1j, -1, -2j, 1]);
```



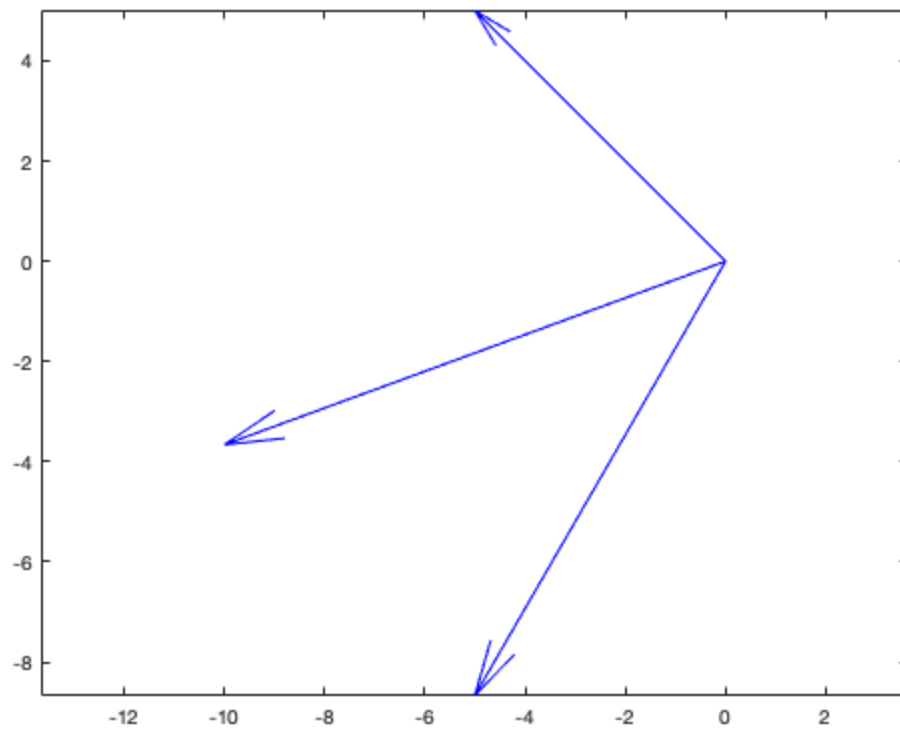
c. Compute $z_1 + z_2$, and plot the sum using `zvect`. Using `hold on`, Plot all three vectors (,,) on the same plot where and are concatenated using `zcat`. Display the numerical values of z_1 , z_2 , $z_1 + z_2$

```
zsum = z1+z2;
zprint(z1)
zprint(z2)
zprint(zsum)
zvect([zsum,z1,z2])
```

$Z =$	X	$+$	jY	<i>Magnitude</i>	<i>Phase</i>	<i>Ph/pi</i>	<i>Ph(deg)</i>
	-5		-8.66	10	-2.094	-0.667	-120.00

$Z =$	X	$+$	jY	<i>Magnitude</i>	<i>Phase</i>	<i>Ph/pi</i>	<i>Ph(deg)</i>
	-5		5	7.071	2.356	0.750	135.00

$Z =$	X	$+$	jY	<i>Magnitude</i>	<i>Phase</i>	<i>Ph/pi</i>	<i>Ph(deg)</i>
	-10		-3.66	10.65	-2.791	-0.888	-159.90



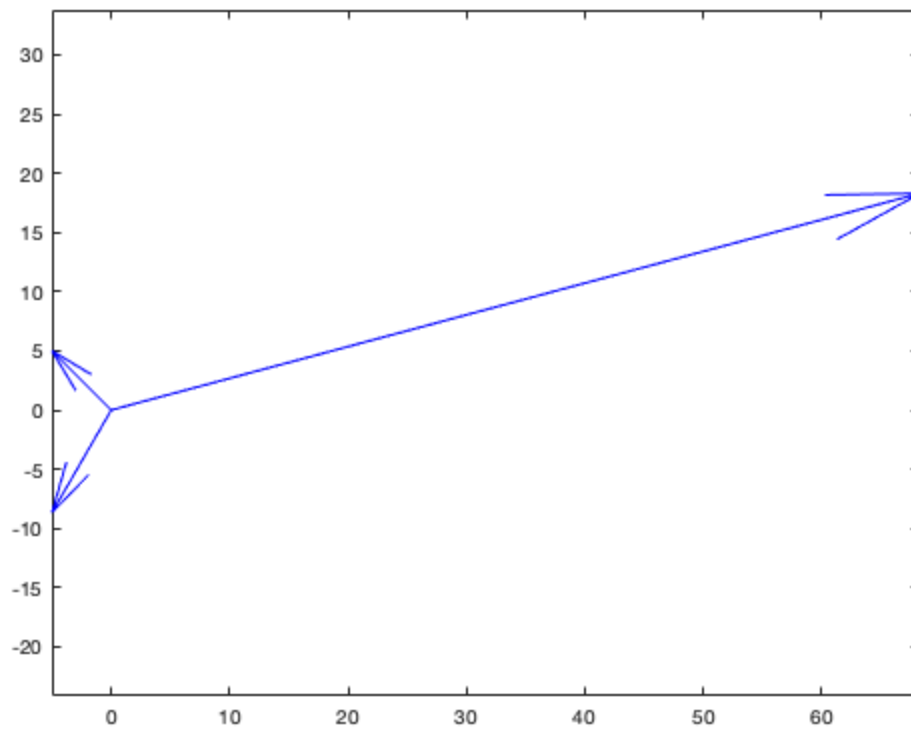
d. Compute the product and display the numerical result. Plot z_1 , z_2 , and z_1z_2 on the same plot.

```
zprod = z1*z2;
zprint(z1)
zprint(z2)
zprint(zprod)
zvect([zprod,z1,z2])
```

$Z =$	X	$+$	jY	Magnitude	Phase	Ph/pi	$Ph(deg)$
	-5		-8.66	10	-2.094	-0.667	-120.00

$Z =$	X	$+$	jY	Magnitude	Phase	Ph/pi	$Ph(deg)$
	-5		5	7.071	2.356	0.750	135.00

$Z =$	X	$+$	jY	Magnitude	Phase	Ph/pi	$Ph(deg)$
	68.3		18.3	70.71	0.262	0.083	15.00



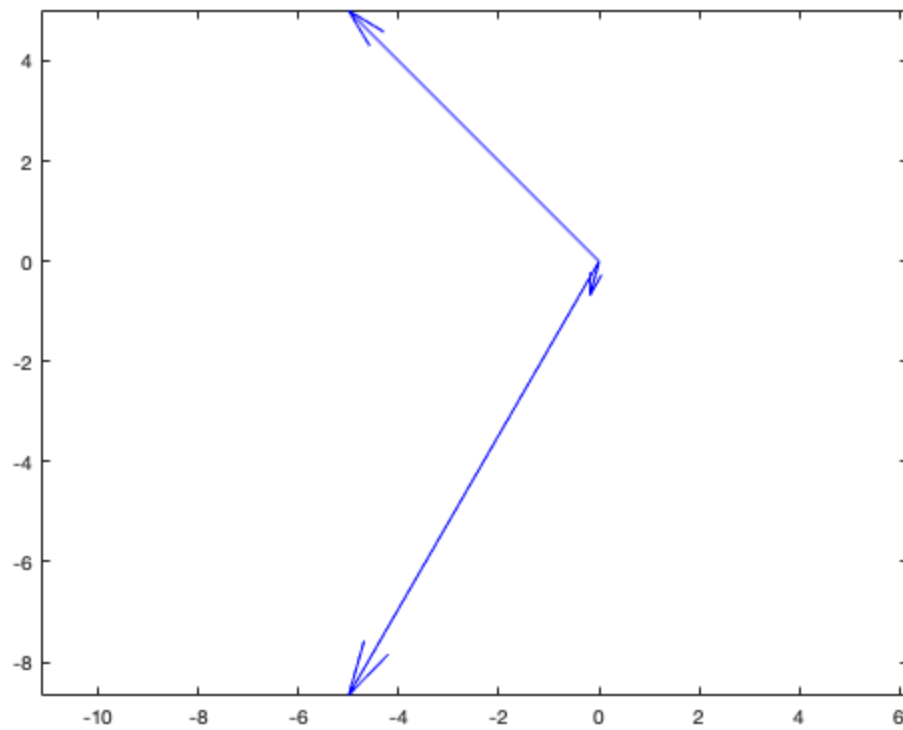
e. Compute the quotient $z2/z1$ and display the numerical result. Plot $z1$, $z2$, and $z2/z1$ on the same plot.

```
zquot = z2/z1;
zprint(z1)
zprint(z2)
zprint(zquot)
zvect([zquot,z1,z2])
```

$Z =$	X	$+$	jY	<i>Magnitude</i>	<i>Phase</i>	<i>Ph/pi</i>	<i>Ph(deg)</i>
	-5		-8.66	10	-2.094	-0.667	-120.00

$Z =$	X	$+$	jY	<i>Magnitude</i>	<i>Phase</i>	<i>Ph/pi</i>	<i>Ph(deg)</i>
	-5		5	7.071	2.356	0.750	135.00

$Z =$	X	$+$	jY	<i>Magnitude</i>	<i>Phase</i>	<i>Ph/pi</i>	<i>Ph(deg)</i>
	-0.183		-0.683	0.7071	-1.833	-0.583	-105.00

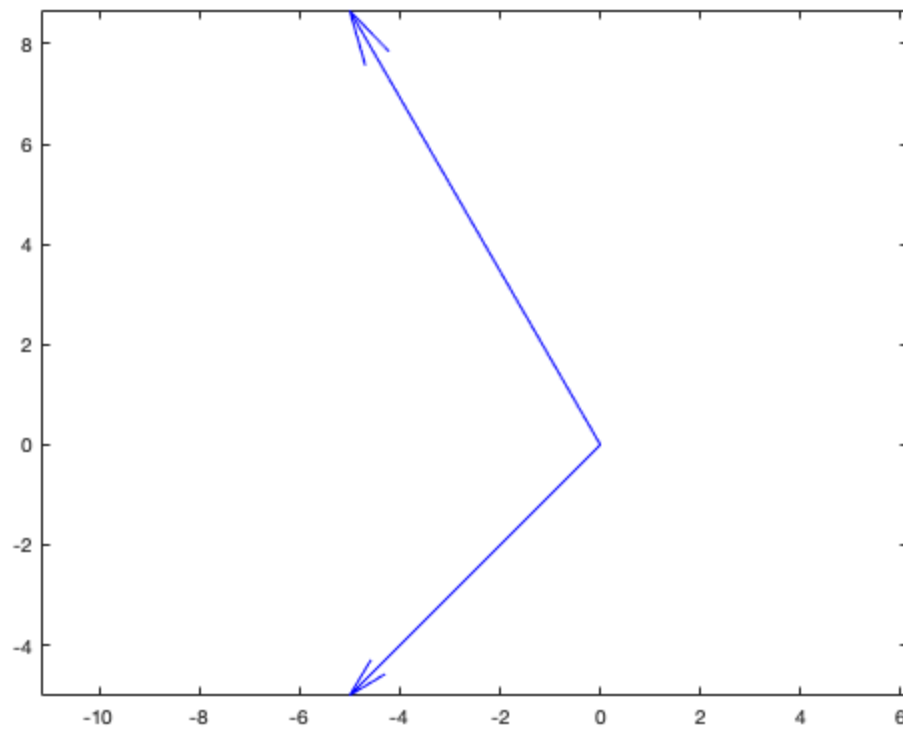


f. Compute the conjugates z_1 and z_2 and display the numerical result. Plot them on the same graph.

```
z1conj = conj(z1);
z2conj = conj(z2);
zprint(z1conj)
zprint(z2conj)
zvect([z1conj,z2conj])
```

$Z =$	X	$+$	jY	<i>Magnitude</i>	<i>Phase</i>	<i>Ph/pi</i>	<i>Ph(deg)</i>
	-5		8.66	10	2.094	0.667	120.00

$Z =$	X	$+$	jY	<i>Magnitude</i>	<i>Phase</i>	<i>Ph/pi</i>	<i>Ph(deg)</i>
	-5		-5	7.071	-2.356	-0.750	-135.00

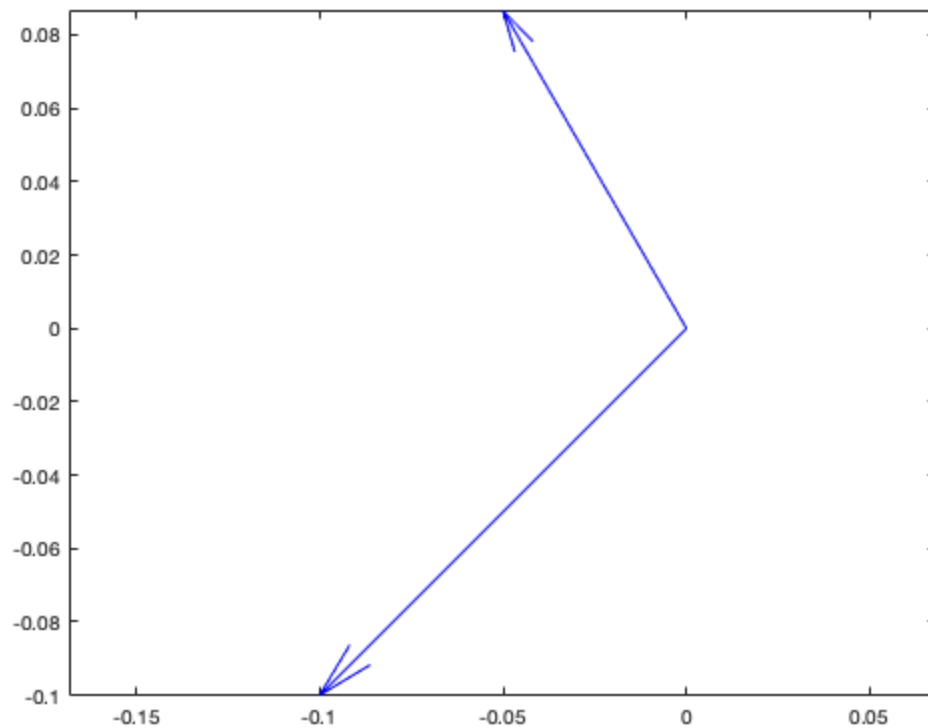


g. Compute $1/z_1$ and $1/z_2$ and display the numerical result. Plot them on the same graph.

```
z1inv = 1/z1;  
z2inv = 1/z2;  
zprint(z1inv)  
zprint(z2inv)  
zvect([z1inv,z2inv])
```

$Z =$	X	$+$	jY	<i>Magnitude</i>	<i>Phase</i>	<i>Ph/pi</i>	<i>Ph(deg)</i>
	-0.05		0.0866	0.1	2.094	0.667	120.00

$Z =$	X	$+$	jY	<i>Magnitude</i>	<i>Phase</i>	<i>Ph/pi</i>	<i>Ph(deg)</i>
	-0.1		-0.1	0.1414	-2.356	-0.750	-135.00



Question 5: What does `zcat()` do with a vector of complex numbers?

It sums them together as usual, adding real components and complex components of each of the numbers together and then plotting them.

Question 6: What is the relationship between the two initial angles and the angle of the product?

The relationship between the two initial angles and the angle of the product is that the two initial angles are summed together to get the angle of the product.

Question 7: Why is the plot of `real(zz)` a sinusoid even though no `cos` or `sin` is present in its equation?

Although there is no `cos` or `sin` present in the equation of `zz`, we know that the form that it is written in is equivalent to some $A\cos(\omega t) + jA\sin(\omega t)$, so it makes sense that its plot is sinusoidal.

Question 8: What are its phase and amplitude? Calculate the phase based on a time-shift measured from the plot. Take a screenshot of the plot.

From the equation $zz = 1.4 \cdot \exp(j\pi/2) \cdot \exp(j5\pi \cdot tt)$, we can see that the amplitude is equal to 1.4, as the amplitude is always equal to the simplified coefficient of the exponential. One can also clearly see this amplitude on the screenshot of the plot I have included. Additionally, I have extrapolated two `x` coordinates with the same height (1.3828). These data points occur at `x2 = 0.29` and `x1 = -0.09`. From these points, we can find ω (2.632) and τ (closest peak to origin, occurring at -0.09). From this, we can easily find ϕ , our phase shift, which is equal to ~ 0.237 .

```
x2 = 0.29 ;  
x1 = -0.09 ;
```

```
omega = 1/(x2-x1)
tau = x1
phi = -omega*tau
```

```
omega =
    2.6316
```

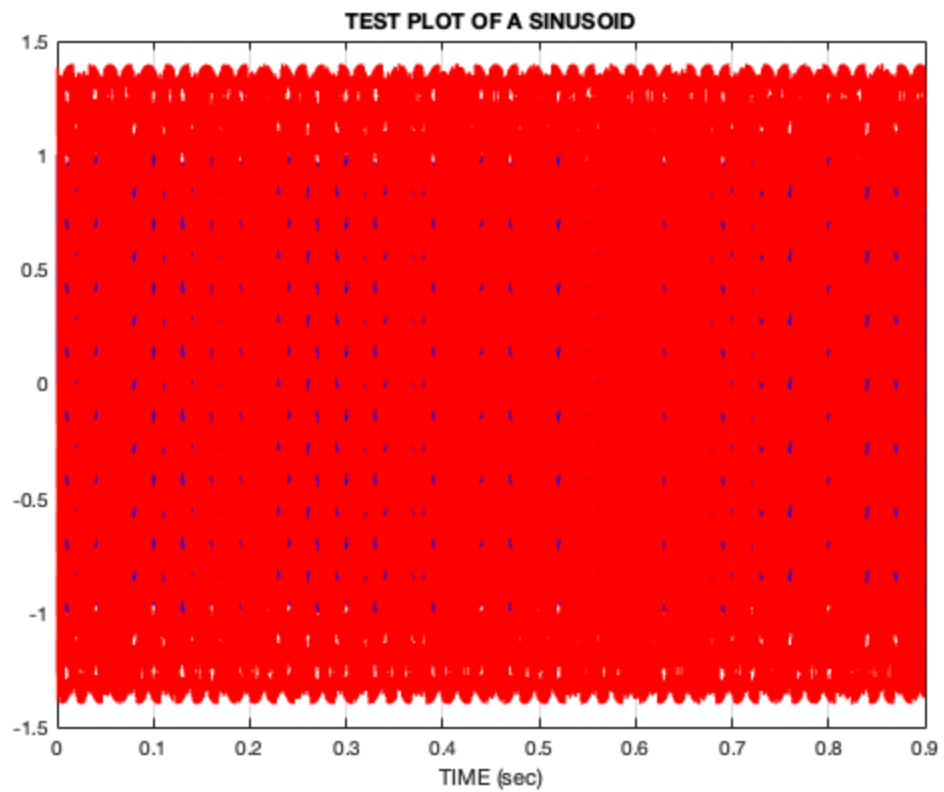
```
tau =
   -0.0900
```

```
phi =
    0.2368
```

1.8 - Sounds

1. Run the MATLAB sound demo by typing `xpsound`. Sounds are represented by sinusoids, so to create sound using MATLAB, you need to create a sinusoid. Your script `mylab1.m` creates a sinusoid with frequency 2.5 Hz. Modify your script so that it produces a 2000 Hz sound, with sampling frequency 11025 Hz, which is 0.9 seconds long. The appropriate time vector is therefore `tt = 0:1/11025:0.9`; Now use `soundsc()` in order play the sound. Play your generated sound for your TA, who will check you off on canvas.

```
mylab1
soundsc(real(zz))
```



Question 9: What is the length of your tt vector?

The length of the tt vector can be seen below, it is 9923.

```
length(tt)
```

```
ans =
```

```
9923
```

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