

State Complexity of Projection on Languages Recognized by Permutation Automata and Commuting Letters

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Outline

Basic Notions

Permutation Automata

The Projection Operation

State Complexity of Projection on Permutation Automata

General Result

Normal Subgroups

Commuting Letters & Projection

Notation

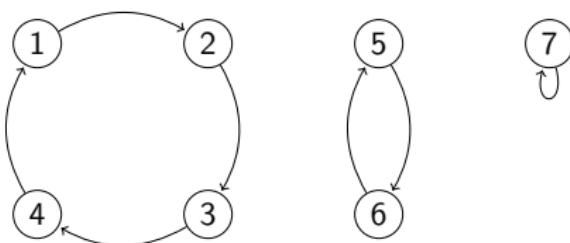
- ▶ Deterministic partial automata (PDFA) by $\mathcal{A} = (Q, \Sigma, \delta, q_0, F)$ as usual.
- ▶ Permutation automaton, if $q \mapsto \delta(q, a)$ is a permutation, i.e., bijective mapping, for every $a \in \Sigma$.
- ▶ Transformation monoid $\mathcal{T}_{\mathcal{A}}$: Monoid generated by the mappings $q \mapsto \delta(q, a)$, $q \in Q$, for $a \in \Sigma$.
- ▶ State complexity of a regularity-preserving operation: largest number of states of an automaton for the result of this operation as a function of the size of automata for the input languages.

Permutation Groups

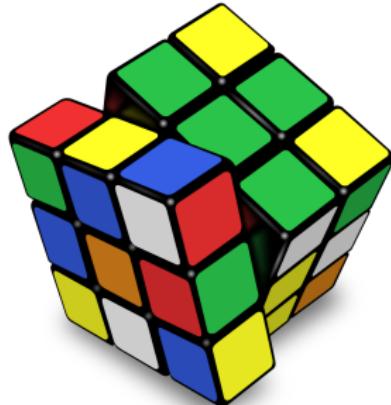
- ▶ Permutation groups are subgroups of the set of all permutations.
- ▶ Permutation groups model symmetries of objects (via automorphism groups).
- ▶ Example: Rubik's cube as a permutation group.

Denote permutations by the **cycle notation**.

$$(1, 2, 3, 4)(5, 6)(7) =$$



1	2	3									
4	top	5									
6	7	8									
9	10	11	17	18	19	25	26	27	33	34	35
12	left	13	20	front	21	28	right	29	36	rear	37
14	15	16	22	23	24	30	31	32	38	39	40
41	42	43									
44	bottom	45									
46	47	48									



Movements:

$$(1, 3, 8, 6)(2, 5, 7, 4)(9, 33, 25, 17)(10, 34, 26, 18)(11, 35, 27, 19)$$

$$(9, 11, 16, 14)(10, 13, 15, 12)(1, 17, 41, 40)(4, 20, 44, 37)(6, 22, 46, 35)$$

$$(17, 19, 24, 22)(18, 21, 23, 20)(6, 25, 43, 16)(7, 28, 42, 13)(8, 30, 41, 11)$$

$$(25, 27, 32, 30)(26, 29, 31, 28)(3, 38, 43, 19)(5, 36, 45, 21)(8, 33, 48, 24)$$

$$(33, 35, 40, 38)(34, 37, 39, 36)(3, 9, 46, 32)(2, 12, 47, 29)(1, 14, 48, 27)$$

$$(41, 43, 48, 46)(42, 45, 47, 44)(14, 22, 30, 38)(15, 23, 31, 39)(16, 24, 32, 40)$$

Aim:

To a given permutation, find inverse permutation.

Possible strategy: apply sequence of commutators.

Permutation Automata & State Complexity

1. McNaughton (Inf. & Contr. 1967) devised an algorithm for languages recognizable by permutation automata to **compute their star-height**.
2. Thierrin (Math. Sys. Theo., 1968) investigated **right-congruences induced by permutation automata** and some closure properties.
3. Hospodár & Mlynářčík (DLT 2020) investigated the state complexity of **various operations** on permutation automata.
4. **Commutative closure** was left open in Hospodár & Mlynářčík (DLT 2020). A bound was obtained in Hoffmann (DCFS 2020), but **tightness unknown**.

Permutation Automata & State Complexity

Operation	Closed?	State Complexity
L^C	Yes	n
$\cap, \cup, \setminus, \oplus$	Yes	nm
KL	No	$m2^n - 2^{n-1} - m + 1$
L^2	No	$n2^{n-1} - 2^{n-2}$
L^*	No	$2^{n-1} + 2^{n-2}$
L^R	Yes	$\binom{n}{\lfloor n/2 \rfloor}$
$L^{-1}K$	Yes	$\binom{m}{\lfloor m/2 \rfloor}, m \leq n$
KL^{-1}	Yes	$m, m \leq n$
$K!L$	No	$(m-1)n + m$
$\text{perm}(L)$	No	$O((n \exp(\sqrt{n \ln n}))^{ \Sigma })$

The Projection Operation

Definition

Let $\Gamma \subseteq \Sigma$. Then, we define the **projection homomorphism**
 $\pi_\Gamma : \Sigma^* \rightarrow \Gamma^*$ onto Γ^* by

$$\pi_\Gamma(x) = \begin{cases} x & \text{if } x \in \Gamma; \\ \varepsilon & \text{otherwise;} \end{cases}$$

on the letters $x \in \Sigma$ and set $\pi_\Gamma(\varepsilon) = \varepsilon$ and $\pi_\Gamma(wa) = \pi_\Gamma(w)\pi_\Gamma(a)$ for $w \in \Sigma^*$ and $a \in \Sigma$.

Projection corresponds to a simplified or restricted view of a modelled system (for example observable properties of a discrete event system).

The Projection Operation

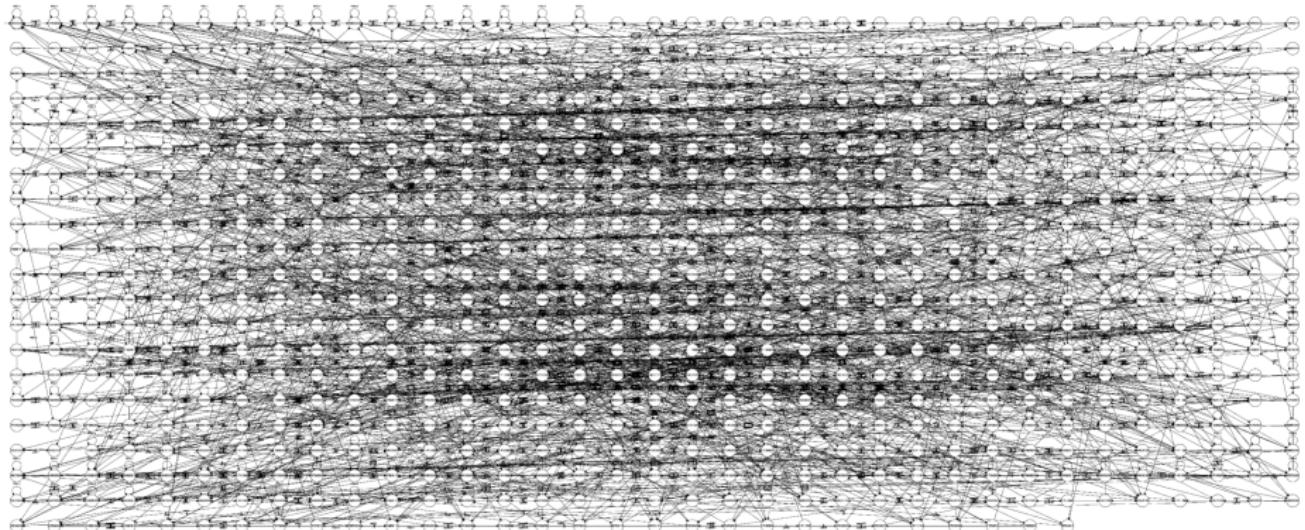


Fig. 1. An example of a simple system G : 729 states, 4400 transitions, 19 events.

Image from Jiráskova & Masopust, *On a Structural Property in the State Complexity of Projected Regular Languages* (2012)

The Projection Operation

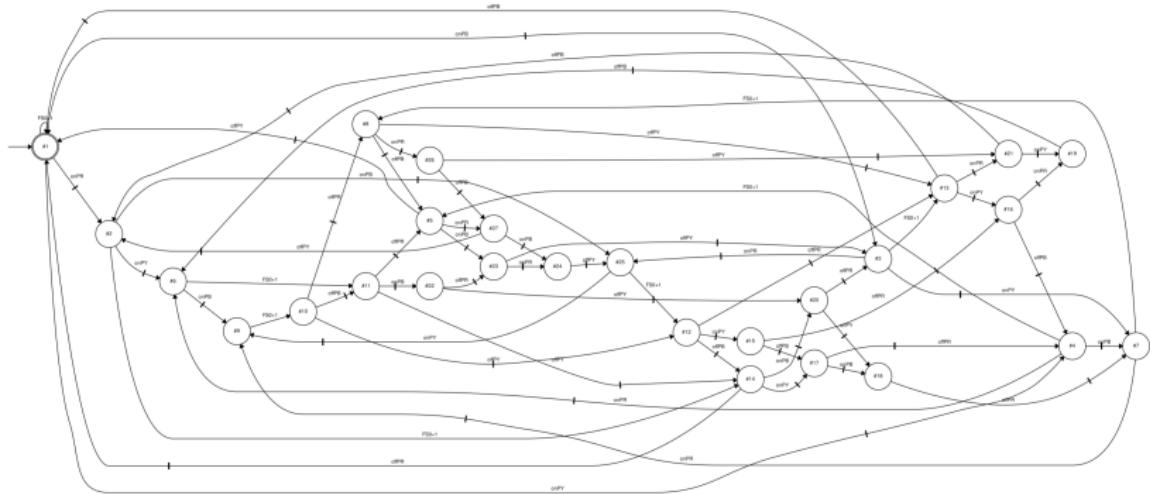


Fig. 2. Projection of G : 27 states, 62 transitions, 7 events.

Image from Jiráskova & Masopust, *On a Structural Property in the State Complexity of Projected Regular Languages* (2012)

Projection & State Complexity

The size of a recognizing automaton for a projected language is of interest, as it corresponds to the complexity of algorithms using a simplified view of a modelled system.

- ▶ Wong (1998), in the context of discrete event systems, has shown that the projection of a language recognized by an n -state PDFA is recognizable by a PDFA with at most $2^{n-1} + 2^{n-2} - 1$ states and this bound is tight.
- ▶ Refined by Jiráskova & Masopust (2012) to the tight bound

$$2^{n-1} + 2^{n-m} - 1$$

with $m = |\{p, q : p \neq q \text{ and } q \in \delta(p, \Sigma \setminus \Gamma)\}|$ (number of unobservable nonloop transitions) for π_Γ .

Orbits & The Projection Automaton

Definition

Let $\mathcal{A} = (Q, \Sigma, \delta, q_0, F)$ be a DFA. Suppose $\Sigma' \subseteq \Sigma$ and $S \subseteq Q$.

The Σ' -orbit of S is the set

$$\text{Orb}_{\Sigma'}(S) = \{\delta(q, u) \mid \delta(q, u) \text{ is defined, } q \in S \text{ and } u \in \Sigma'^*\}.$$

Also, for $q \in Q$, we set $\text{Orb}_{\Sigma'}(q) = \text{Orb}_{\Sigma'}(\{q\})$.

Orbits & The Projection Automaton

Let $\mathcal{A} = (Q, \Sigma, \delta, q_0, F)$ be a DFA and $\Gamma \subseteq \Sigma$. Set $\Delta = \Sigma \setminus \Gamma$. Next, we define the **projection automaton** of \mathcal{A} for Γ as

$\mathcal{R}_{\mathcal{A}}^{\Gamma} = (\mathcal{P}(Q), \Gamma, \mu, \text{Orb}_{\Delta}(q_0), E)$ with, for $S \subseteq Q$ and $x \in \Gamma$, the transition function

$$\mu(S, x) = \text{Orb}_{\Delta}(\delta(S, x)) \quad (1)$$

and $E = \{T \subseteq Q \mid T \cap F \neq \emptyset\}$.

Theorem

Let \mathcal{A} be a DFA and $\Gamma \subseteq \Sigma$. Then, $\pi_{\Gamma}(L(\mathcal{A})) = L(\mathcal{R}_{\mathcal{A}}^{\Gamma})$.

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Let \mathcal{A} be a DFA and $\Gamma \subseteq \Sigma$. Then, $\pi_{\Gamma}(L(\mathcal{A})) = L(\mathcal{R}_{\mathcal{A}}^{\Gamma})$.

Definition

An automaton \mathcal{A} is a **state-partition** automaton, if the set of reachable states of $\mathcal{R}_{\mathcal{A}}^{\Gamma}$ partitions Q .

For state-partition automata, $\pi_{\Gamma}(L(\mathcal{A}))$ is recognizable by an automaton with at most n states.

State Complexity of Projection on Permutation Automata

Theorem

1. $\mathcal{A} = (Q, \Sigma, \delta, q_0, F)$ is a permutation automaton.
2. $\Gamma \subseteq \Sigma$.
3. $m = |\{p, q \in Q : p \neq q, q \in \delta(p, \Sigma \setminus \Gamma)\}|$.

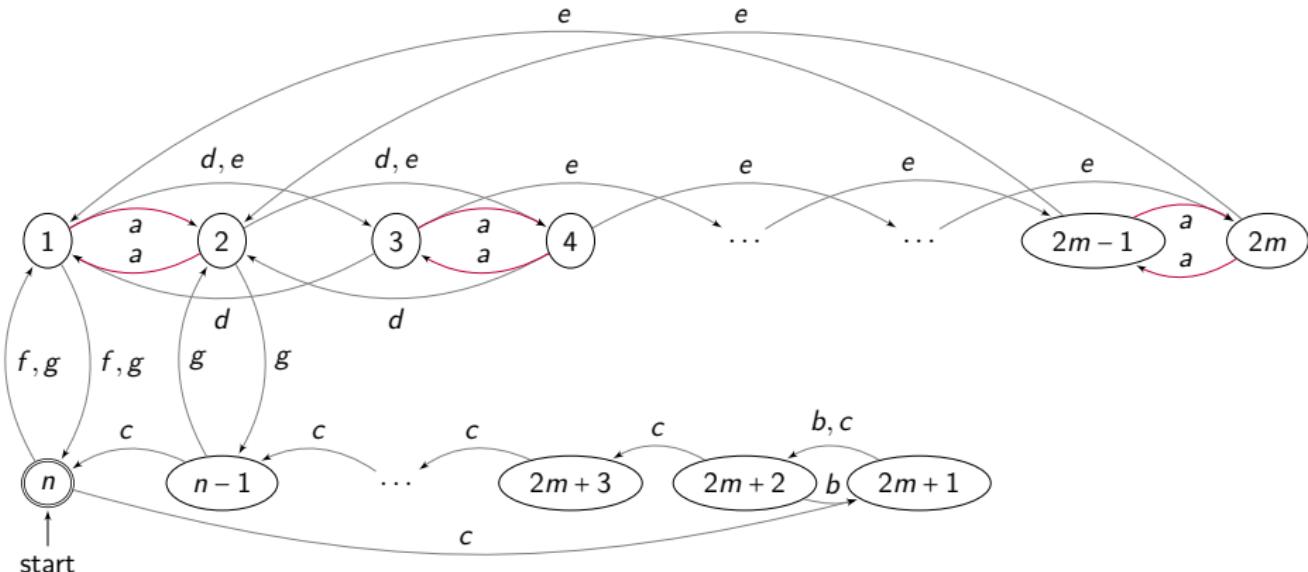
Then:

1. If $m = 0$, then $\pi_\Gamma(L(\mathcal{A}))$ is recognizable by an automaton with at most $|Q|$ states.
2. If $m > 0$, then $\pi_\Gamma(L(\mathcal{A}))$ is recognizable by an automaton with at most $2^{|Q| - \lceil \frac{m}{2} \rceil} - 1$ states.
3. These bounds are tight.

Proof Sketch.

The Γ -orbits partition the state set. Hence, the reachable states of $\mathcal{R}_\mathcal{A}^\Gamma$ are unions of Δ -orbits $\text{Orb}_\Gamma(q)$, $q \in Q$. We show tightness next.





$$a = (1, 2)(3, 4)\cdots(2m-1, 2m),$$

$$b = (2m+1, 2m+2),$$

$$d = (1, 3)(2, 4),$$

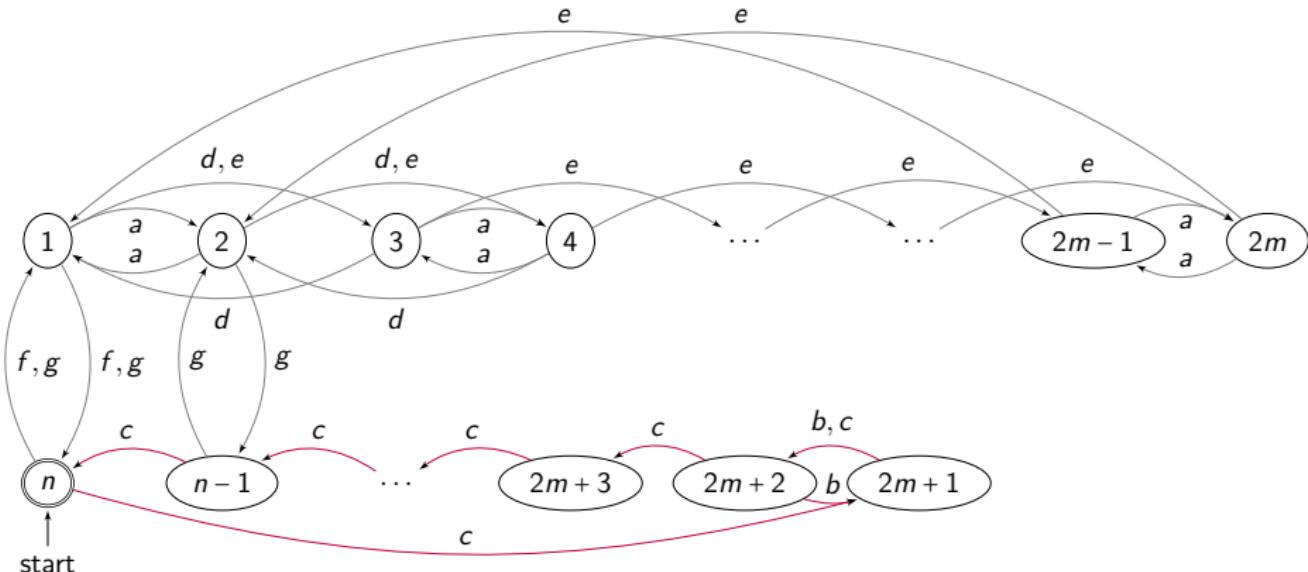
$$f = (1, n),$$

$$c = (2m+1, 2m+2, \dots, n),$$

$$e = (1, 3, \dots, 2m-1)(2, 4, \dots, 2m),$$

$$g = (1, n)(2, n-1).$$

$\pi_\Gamma : \Sigma^* \rightarrow \Gamma^*$ with $\Gamma = \{b, c, d, e, f, g\}$. Self-Loops omitted.



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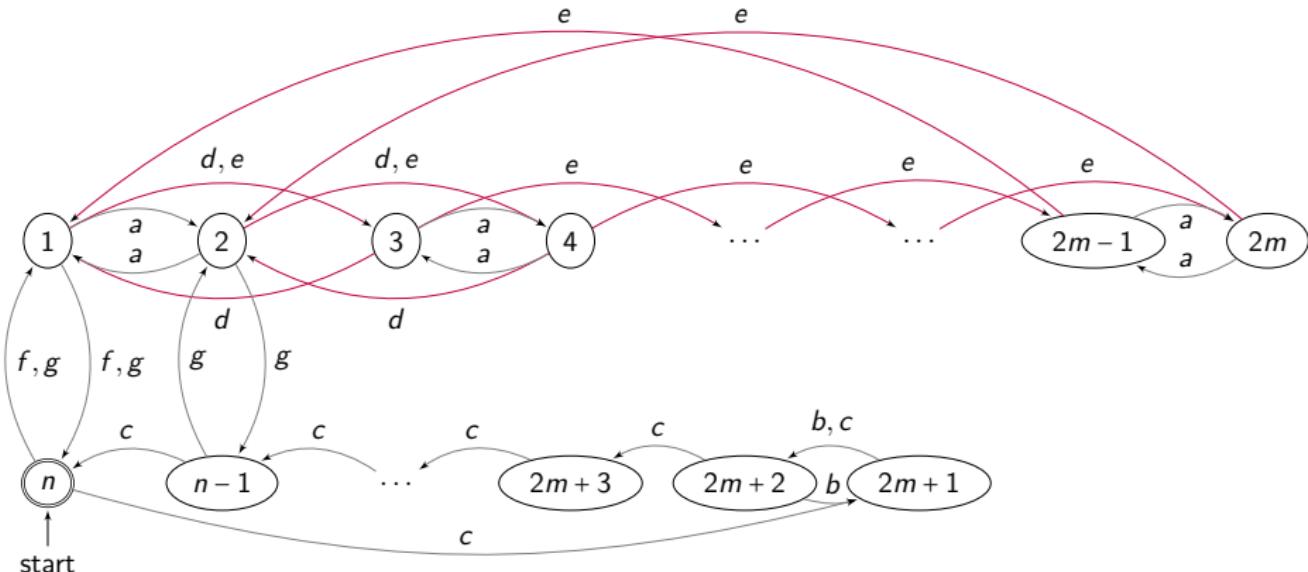
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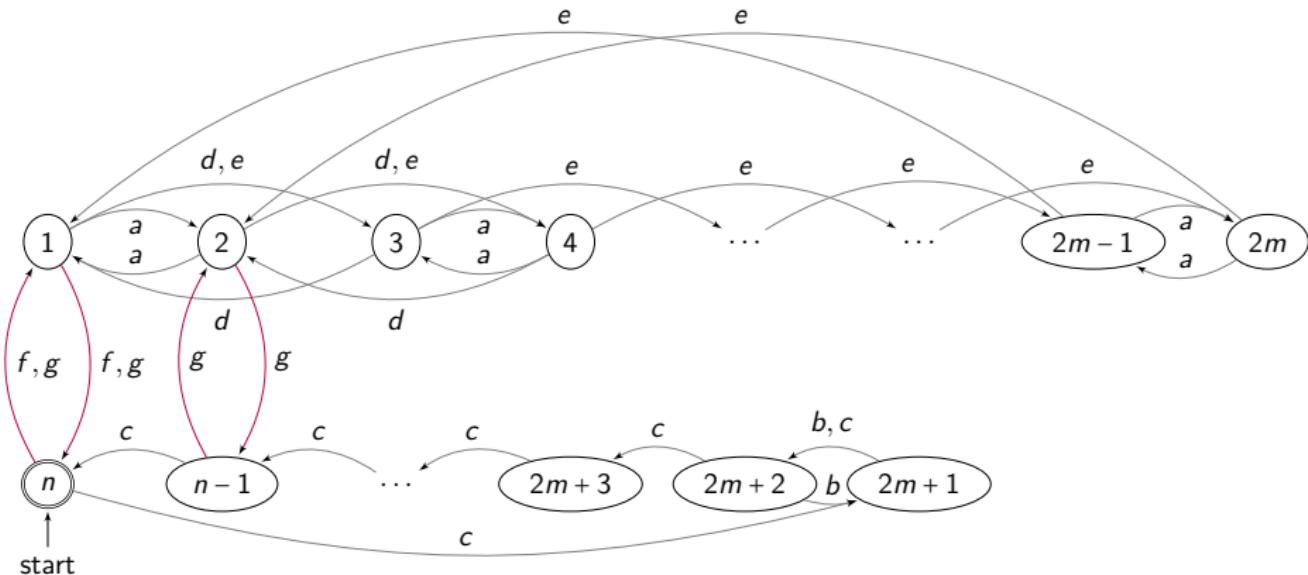
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Normal Subgroups

In a group G , a subgroup N is called **normal**, if for every $g \in G$ we have $gN = Ng$. In terms of automata:

Definition

Let $\mathcal{A} = (Q, \Sigma, \delta, q_0, F)$ be a permutation automaton. Then, a subgroup N of $\mathcal{T}_{\mathcal{A}}$ is called **normal**, if, for each $\delta_u, \delta_v \in \mathcal{T}_{\mathcal{A}}$ ($u, v \in \Sigma^*$),

$$(\exists \delta_w \in N : \delta_u = \delta_{wv}) \Leftrightarrow (\exists \delta_{w'} \in N : \delta_u = \delta_{vw'}).$$

Normal Subgroups

Theorem

1. $\mathcal{A} = (Q, \Sigma, \delta, q_0, F)$ permutation automaton, $\Gamma \subseteq \Sigma$.
2. $N = \{\delta_u : Q \rightarrow Q : u \in (\Sigma \setminus \Gamma)^*\}$ normal in $\mathcal{T}_{\mathcal{A}}$.

Then, \mathcal{A} is a state-partition automaton for π_{Γ} .

Proof.

The action of the letters is compatible with the orbits for $\Delta = \Sigma \setminus \Gamma$, more precisely $\delta(\text{Orb}_{\Delta}(q), x) = \text{Orb}_{\Delta}(\delta(q, x))$. □

Commuting Letters

Let $\mathcal{A} = (Q, \Sigma, \delta, q_0, F)$ be an automaton with n states.

1. When is $\pi_\Gamma(L(\mathcal{A}))$ recognizable by an automaton with at most n states?
2. Hitherto, only state-partition automata and automata recognizing finite languages projected onto unary languages have this property.

The following property of $\Gamma \subseteq \Sigma$ ensures this:

$$\delta(q, ab) = \delta(q, ba)$$

for all $q \in Q, a \in \Sigma \setminus \Gamma, b \in \Gamma$.

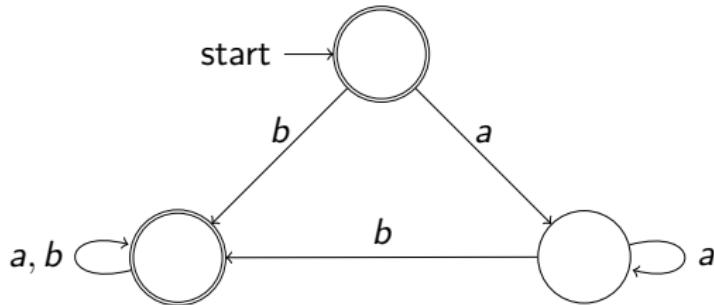
Commuting Letters

Theorem

Suppose $\mathcal{A} = (Q, \Sigma, \delta, q_0, F)$ is an arbitrary DFA. Let $\Gamma \subseteq \Sigma$ be such that, for each $a \in \Sigma \setminus \Gamma$, $b \in \Gamma$ and $q \in Q$, we have $\delta(q, ab) = \delta(q, ba)$. Then, $\pi_\Gamma(L)$ is recognizable by a DFA with at most $|Q|$ states.

Example

We have genuinely new automata whose projected image has state complexity at most $|Q|$. The following commutative automaton is neither a state-partition automaton, nor does it recognizes a finite language.



Varieties

A **variety** \mathcal{V} associates with every alphabet Σ a class of regular languages $\mathcal{V}(\Sigma^*)$ over Σ which is a

1. Boolean algebra,
2. closed under left- and right quotients, i.e.,

$$u^{-1}L = \{v \in \Sigma^* : uv \in L\}, \quad Lu^{-1}L = \{v \in \Sigma^* : vu \in L\}$$

for $u \in \Sigma^*$, $L \in \mathcal{V}(\Sigma^*)$,

3. closed under inverse homomorphic images.

The class of languages recognized by permutation automata could be seen as a variety.

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The class of languages recognized by permutation automata could be seen as a variety.

Our method of proofs implies the following:

Theorem

Let \mathcal{V} be a variety of commutative languages. If $L \in \mathcal{V}(\Sigma^*)$, then $\pi_\Gamma(L) \in \mathcal{V}(\Gamma^*)$.

Thank you for your attention!

All references could be found in the paper.