

# main.c

```
1 /*
2 * Quad Infrared Detector Version 1.2
3 * COPYRIGHT 2013 S.D. "Hoffy" Hofmeister
4 * http://www.hoffysworld.com
5 * Provided under a Creative Commons Attribution, Non-Commercial Share Alike,3.0 Unported
   License
6 * TARGETED TO MSP430 LANUCHPAD W/MSP430G2553 PROCESSOR
7 *
8 * Design Notes:
9 *
10 * This code is designed to control 4 IR Sensors and light 4 independent indicator LEDs to
   signal that an object as been detected.
11 *
12 * Distance between Tip of Emitter and Tip of Detector has only been tested upto 3.5 Inches
   under incandescent and floroescant
13 * lighting conditions with no failures.
14 *
15 * Circuit Pinout:
16 * PIN 1.0 = Cathode of IR Receiver #1    > Anode to Ground
17 * PIN 1.1 = UNASSIGNED - UART
18 * PIN 1.2 = UNASSIGNED - UART
19 * PIN 1.3 = Cathode of IR Receiver #2    > Anode to Ground
20 * PIN 1.4 = Cathode of IR Receiver #3    > Anode to Ground
21 * PIN 1.5 = Cathode of IR Receiver #4    > Anode to Ground
22 * PIN 1.6 = Anode of Indicator LED #1 \
23 * PIN 1.7 = Anode of Indicator LED #2 \ Cathodes to ground
24 * PIN 2.0 = Anode of Indicator LED #3 /
25 * PIN 2.1 = Anode of Indicator LED #4 /
26 * PIN 2.2 = UNASSIGNED
27 * PIN 2.3 = UNASSIGNED
28 * PIN 2.4 = UNASSIGNED
29 * PIN 2.5 = Circuit Power Indicator
30 *
31 * PINS 1.1, 1.2, 2.2, 2.3, 2.4 are left open for integration into other projects
32 *
33 * Note Anodes for the IR Emitters connect to VCC and Cathodes to Ground
34 */
35
36 #include <msp430g2553.h>
37
38 void main(void) {
39
40     WDTCTL = WDTPW + WDTHOLD;           // Stop watchdog timer
41
42
43     P2DIR |= BIT5; // Circuit Power Indicator
44     P2OUT |= BIT5; // Used to Trouble Shooting
45
46
47     //Configure IR Detectors
48
49     P1DIR &= ~BIT0;                      // Port 1 P1.0 (IR Detector #1) as input
50     P1REN |= BIT0;                      // Enable Port 1 P1.0 (IR Detector #1) pull-up resistor
51     P1SEL &= ~BIT0;                      // Select Port 1 P1.0 (IR Detector #1)
52
53     P1DIR &= ~BIT3;                      // Port 1 P1.3 (IR Detector #2) as input
54     P1REN |= BIT3;                      // Enable Port 1 P1.3 (IR Detector #2) pull-up resistor
```

# main.c

```
55  P1SEL &= ~BIT3;           // Select Port 1 P1.3 (IR Detector #2)
56
57  P1DIR &= ~BIT4;           // Port 1 P1.4 (IR Detector #3) as input
58  P1REN |= BIT4;            // Enable Port 1 P1.4 (IR Detector #3) pull-up resistor
59  P1SEL &= ~BIT4;           // Select Port 1 P1.4 (IR Detector #3)
60
61  P1DIR &= ~BIT5;           // Port 1 P1.5 (IR Detector #4) as input
62  P1REN |= BIT5;            // Enable Port 1 P1.5 (IR Detector #4) pull-up resistor
63  P1SEL &= ~BIT5;           // Select Port 1 P1.5 (IR Detector #4)
64
65  //Configure Outputs
66
67  P1DIR |= BIT6;             // Port 1 P1.6 (Indicator #1) as output
68  P1OUT &= ~BIT6;           // Port 1 P1.6 (Indicator #1) Set to off State
69
70  P1DIR |= BIT7;             // Port 1 P1.7 (Indicator #1) as output
71  P1OUT &= ~BIT7;           // Port 1 P1.7 (Indicator #1) Set to off State
72
73  P2DIR |= BIT0;             // Port 2 P2.0 (Indicator #1) as output
74  P2OUT &= ~BIT0;           // Port 1 P2.0 (Indicator #1) Set to off State
75
76
77  P2DIR |= BIT1;             // Port 2 P2.1 (Indicator #1) as output
78  P2OUT &= ~BIT1;           // Port 2 P2.1 (Indicator #1) Set to off State
79
80 // Let's Get Down to Business
81
82 while( 1 ) // While this value remains equal to 1 the code will loop continuously, there is
    no code written to
83 // change this state in this particular program.
84 {
85
86     //Detector #1
87     if( (P1IN & BIT0) > 0) // When IR Detector #1 detects an object breaking the IR
    Beam
88
89         P1OUT |= BIT6;      // Set LED Indicator #1 to ON
90
91         else                // Otherwise
92
93         P1OUT &= ~BIT6;     // Set LED Indicator #1 to OFF
94     //END of Detector #1
95
96
97     //Detector #2
98     if( (P1IN & BIT3) > 0) // When IR Detector #2 detects an object breaking the IR
    Beam
99
100         P1OUT |= BIT7;      // Set LED Indicator #2 to ON
101
102         else                // Otherwise
103
104         P1OUT &= ~BIT7;     // Set LED Indicator #2 to OFF
105     //END of Detector #2
106
107
108
```

main.c

```
109      //Detector #3
110      if( (P1IN & BIT4) > 0)      // When IR Detector #3 detects an object breaking the IR
Beam
111
112          P2OUT |= BIT0;          // Set LED Indicator #3 to ON
113
114          else                    // Otherwise
115
116          P2OUT &= ~BIT0;         // Set LED Indicator #3 to OFF
117      //END of Detector #3
118
119
120
121      //Detector #4
122      if( (P1IN & BIT5) > 0)      // When IR Detector #4 detects an object breaking the IR
Beam
123
124          P2OUT |= BIT1;          // Set LED Indicator #4 to ON
125
126          else                    // Otherwise
127
128          P2OUT &= ~BIT1;         // Set LED Indicator #4 to OFF
129      //End of Detector #4
130
131
132  } End of While
133
134 } // END OF MAIN
135
136
137
```