

# Point-process based representation learning for Electronic Health Records

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**Abstract**—It is very well accepted that missingness in electronic health records (EHRs) are not at random which is regarded as informative missingness. The clinician's decision on when to observe lab tests over time can be modeled using point processes. We propose a novel framework based on neural point process to analyze laboratory tests of ICU patients. This framework can take into account additional information for better characterization of conditional intensity function (CIF) as well as better accuracy in prediction of future timestamp and labels.

**Index Terms**—Enter keywords or phrases in alphabetical order, separated by commas. For a list of suggested keywords, send a blank e-mail to [keywords@ieee.org](mailto:keywords@ieee.org) or visit the site.

## I. INTRODUCTION

Writing an effective abstract is an indispensable part of any form of research, since it that can motivate the audience to read follow the rest of the text. In this task, I have analyzed five abstracts from the field of artificial intelligence (AI). The table in section 2 shows a summary of the most important aspects of the analyzed abstracts.

## II. BACKGROUND

**Temporal point process**

**Neural temporal point process**

**Handling irregular sampling**

## III. RELATED WORKS

## IV. PROPOSED MODEL

Event sequence data consists of  $N$  sequences  $\{\mathcal{S}_i\}_{i=1}^N$ , where each sequence  $\mathcal{S}_i$  is a series of  $L_i$  events  $\{(t_j, e_j)\}_{j=1}^{L_i}$ . Here,  $e_j$  represents events that could be independent or mutually exclusive occurring at  $t_i$ .

In addition to the event data, we might have additional

information  $\{\mathcal{D}_i\}_{i=1}^N$ . Suppose that each state is represented as  $\{(t_k, v_k, m_k)\}_{k=1}^{P_i}$ , consisting of a time value  $t_k \in \mathbb{R}^+$ , an observed value  $z_k \in \mathbb{R}$  and a modality indicator  $m_k \in \{1, \dots, M\}$ .

### A. Event Encoder

We use a similar transformer architecture [thp] for encoding events. The advantage of the attention mechanism is that it discards recurrent architecture. it is necessary to include temporal information. Similar to the original positional encoding [vaswani], we use a temporal encoding procedure:

$$[z(t_j)]_k = \begin{cases} \sin\left(\frac{t_j}{T^{(k-1)/d_t}}\right) & \text{if } k \text{ is odd} \\ \sin\left(\frac{t_j}{T^{k/d_t}}\right) & \text{if } k \text{ is even} \end{cases} \quad (1)$$

Here,  $d_t \in \mathbb{N}$  is the dimensionality of encoded timestamp and  $z \in \mathbb{R}^{d_t}$  is the embedding vector of timestamp.

Each event mark  $e_j$  is projected to a sparse binary vector representation. We add an embedding layer to achieve a more compact and efficient representation  $emb$ . Here,  $w$  and  $b$  are weights and biases of the embedding layer which can be learned during network training.

While previous works suggested adding temporal encoding to the embedded events, we propose to concatenate these two vectors. The effectiveness of this concatenation is further investigated in the results.

$$x_{emb} = [y(k_j), z(t_j)] \quad (2)$$

Now that the  $x_{emb}$  is ready for encoding, it is encoded through a standard transformer encoder with multiple layers and attention heads.

$$x_{enc} = TE(x_{emb}) \quad (3)$$

### B. State Encoder

Here, we propose a method to incorporate additional information for a better representation. In healthcare, much data is available from different modalities such as vital signs and laboratory values.

Similar to [setF], we use an attention-based aggregation approach for encoding all additional information. Each side information  $(t_k, v_k, m_k)$  can be represented by  $s_k = (z(t_k), v_k, m_k)$ . we define attention  $a(\mathcal{S}_k, s_k)$

We define  $\mathcal{S}_p$  to be the set of the first  $p$  available information. The goal is to calculate  $a(\mathcal{S}_p, s_k)$ ,  $k \leq p$  that is the

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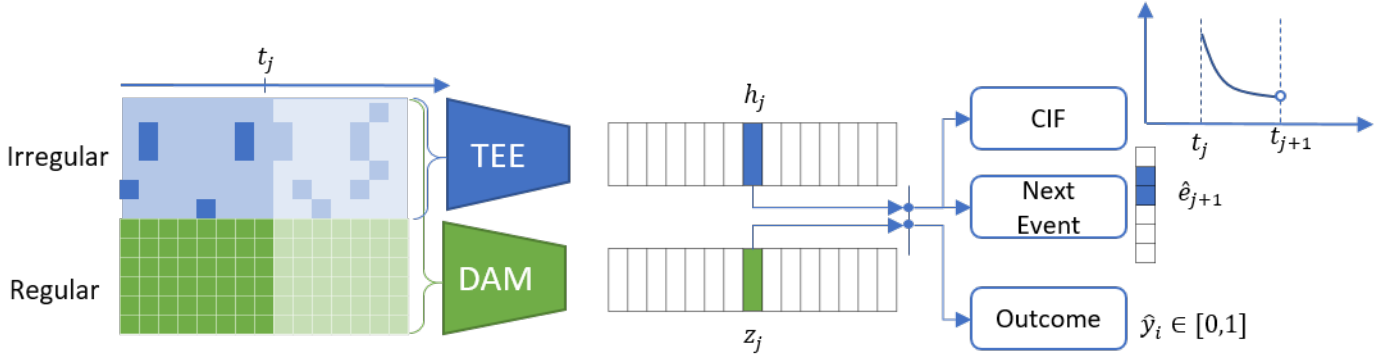


Fig. 1. Magnetization as a function of applied field. It is good practice to explain the significance of the figure in the caption.

relevance of  $k$ -th observation  $s_k$  to the first  $p$  observed values  $\mathcal{S}_p$ . This is achieved by computing an embedding of the set elements using a smaller set functions  $f'$ , and projecting the concatenation of the set representation and the individual set element into  $d$ -dimensional space:

$$f'(\mathcal{S}_p) = g' \left( \frac{1}{p} \sum_{s_k \in \mathcal{S}_p} h'_\theta(s_k) \right)$$

$$K_p = [f'(\mathcal{S}_p), s_p]^T W^K$$

Furthermore, we define a query vector  $w^q \in \mathbb{R}^d$ , which allows the model to summarize different aspects of the dataset via

$$e_p = \frac{K_p \cdot w^q}{\sqrt{d}}$$

Now, the desired attention can be computed as follows:

$$a(\mathcal{S}_p, s_k) = \frac{\exp(e_p)}{\sum_{k \leq p} \exp(e_k)}$$

Finally, we compute a weighted aggregation of set elements:

$$f(\mathcal{S}_p) = g_\psi \left( \sum_{s_k \in \mathcal{S}_p} a(\mathcal{S}_p, s_k) h_\theta(s_k) \right)$$

Without loss of generality, we can consider multiple heads by adding an additional dimension to keys and queries.

All formulas are:

$$\begin{cases} f'(\mathcal{S}_p) = g' \left( \frac{1}{p} \sum_{s_k \in \mathcal{S}_p} h'_\theta(s_k) \right) \\ K_p = [f'(\mathcal{S}_p), s_p]^T W^K \\ e_p = \frac{K_p \cdot w^q}{\sqrt{d}} \\ a(\mathcal{S}_p, s_k) = \frac{\exp(e_p)}{\sum_{k \leq p} \exp(e_k)} \\ f(\mathcal{S}_p) = \sum_{s_k \in \mathcal{S}_p} a(\mathcal{S}_p, s_k) h_\theta(s_k) \\ z_p = g_\psi(f(\mathcal{S}_p)) \end{cases}$$

### C. Mark and Time Decoder

by concatenating encoded events  $x_{enc}$  and additional information  $f'(\mathcal{S}_p)$ , we can predict next marks and times as follows:

$$\hat{e}_{j+1} = MLP([x_j, f'(\mathcal{S}_j)]) \quad (4)$$

$$\hat{t}_{j+1} = MLP([x_j, f'(\mathcal{S}_j)]) \quad (5)$$

$$\mathcal{L}_{mark} = \quad (6)$$

$$\mathcal{L}_{time} = \sum_{j=1}^{L-1} ((\hat{t}_{j+1} - t_j) - (t_{j+1} - t_j))^2 \quad (7)$$

### D. Event Decoder

Once we obtain a representation of a patient using embedded events and states, we can try to parameterize conditional intensity functions (CIFs) of the events.

In neural point process literature, many approaches have been propose to decode either conditional or cumulative intensity function.

$$\lambda_k(t|\mathcal{H}_t) = f_k \left( \alpha_k \frac{t - t_j}{t_j} + \mathbf{w}_k^T \mathbf{x}_{enc}(t_j) + \mathbf{y}_k^T \mathbf{s}_{enc}(t_j) + b_k \right) \quad (8)$$

$$\lambda_k(t|\mathcal{H}_t) = f_k \left( \alpha_k \frac{t - t_j}{t_j} + \mathbf{w}_k^T \mathbf{x}_{enc}(t_j) + b_k \right) \quad (9)$$

## V. EXPERIMENTS

### Datasets

#### Physionet 2019 Sepsis Early Prediction Challenge (P19).

This dataset contains clinical data of about 40k patients in ICU. Clinical data consist of demographics, vital signs and laboratory values as well as sepsis label in a one-hour time grid. Our objective is to predict the timestamp of next lab sampling events as well as measured variables (event marks) given the patient history.

**MIMIC-IV (M4).** We selected Medical Information Mart for Intensive Care (MIMIC) IV [1], which is a real-world

clinical database comprising health data relating to over 40,000 patients admitted to ICU at the Beth Israel Deaconess Medical Center.

**Synthea(Syn).** We used the Synthea simulator (Walonoski et al., 2018) which generates patient-level EHRs using human expert curated Markov processes. Here, we reused the already processed version of this data by Edgaurd.

**Stackoverflow (SO).** StackOverflow is a question-answering website. The website rewards users with badges to promote engagement in the community, and the same badge can be rewarded multiple times to the same user. We collect data in a two-year period, and we treat each user’s reward history as a sequence. Each event in the sequence signifies receipt of a particular medal.

### Scenarios

To investigate the effectiveness of the proposed method, we consider three input scenarios (TE, DA, TE+DA) as well as three loss functions (next event, CIF, next event+CIF) which would result in nine scenarios.

The first series of experiments are conducted to investigate the advantage of encoding additional information for parameterization of intensity functions. We consider seven scenarios: Here, the baseline models

To show the effectiveness of time concatenation we report.

### Baselines

we use NEURALTPP that is already developed pipeline by as they already considered a lot of combinations.

### Metrics

We report the weighted AUPRC, AUROC of next predicted event as well as root mean square error (RMSE) of next measurement interval. For evaluating the goodness of fit for the parameterized point process, we report normalized negative likelihood normalized by number of occurred event (NLL/events). Furthermore, we can also evaluate the learned representation of each patient to predict the sepsis label in a binary classification task.

## VI. RESULTS AND DISCUSSION

In this section, we present our results regarding the advantage of state and event encoding.

### A. Effect of minor improvements

- effect of time concatenation
- compare single+mark with mc or ml

### B. Negative Likelihood with state encoding

Table 1 shows the result for estimation of negative likelihood in different datasets and scenarios. It is obvious that state encoding has led to lower NLL.

can u provide one example patient?

TABLE I

EFFECT

Dataset	Metric	shp+mark	baseline
		concat	sum
SO	NLL AUROC time		
Synthea	NLL AUROC time		
ReTweet	NLL AUROC time		

TABLE II

NLL ESTIMATION

Dataset	setting	Model		
		TE	TE+DAM	TE+noise
P12	sc mc1 mc2			
p19	sc mc1 mc2			

### C. Downstream task with event encoding

Another key element of our work is to show the effectiveness of point process modeling for a down-stream task. In Table, we have reported the performance metrics for the mortality prediction task. We have compared our results with several sota’s DL models that are compatible with irregular time series.

### D. Learned representations

Fig 1 visualizes the tsne plot for the two scenarios.

### E. Model interpretability

one advantage of proposed method is use of attention mechanisms in both event and state encoder. Fig 1 shows the attention mechanism

### F. Likelihood estimation

Although CIF does not improve mark prediction, it has led to better representation of patient for downstream task such as sepsis prediction.

In addition, we can interpret some of learned CIF patterns. explain the effect of time concatenation in SO dataset tsne of learned representation. 4 modes:

- (DA,TE)- $i$ (Mark, CIF)
- attention of DA for sepsis prediction
- attention matrix of events for SO dataset

## VII. CONCLUSION

## VIII. INTRODUCTION

TABLE III  
DOWN STREAM TASK

Dataset	Setting	Center	F1		AUPRC		AUROC	
			DAM	TE+DAM	DAM	TE+DAM	DAM	TE+DAM
P12	sc	1	0.55	0.55	0.55	0.55	0.55	0.55
		2	0.55	0.55	0.55	0.55	0.55	0.55
		3	0.55	0.55	0.55	0.55	0.55	0.55
	mc1	1	0.55	0.55	0.55	0.55	0.55	0.55
		2	0.55	0.55	0.55	0.55	0.55	0.55
		3	0.55	0.55	0.55	0.55	0.55	0.55
	mc2	-	0.55	0.55	0.55	0.55	0.55	0.55
	seft	-	0.55	0.55	0.55	0.55	0.55	0.55
	sc	1	0.55	0.55	0.55	0.55	0.55	0.55
		2	0.55	0.55	0.55	0.55	0.55	0.55
		3	0.55	0.55	0.55	0.55	0.55	0.55
P19	mc1	1	0.55	0.55	0.55	0.55	0.55	0.55
		2	0.55	0.55	0.55	0.55	0.55	0.55
		3	0.55	0.55	0.55	0.55	0.55	0.55
	mc2	-	0.55	0.55	0.55	0.55	0.55	0.55
	seft	-	0.55	0.55	0.55	0.55	0.55	0.55

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Define abbreviations and acronyms the first time they are used in the text, even after they have already been defined in the abstract. Abbreviations such as IEEE, SI, ac, and dc do not have to be defined. Abbreviations that incorporate periods should not have spaces: write "C.N.R.S.," not "C. N. R. S." Do not use abbreviations in the title unless they are unavoidable (for example, "IEEE" in the title of this article).

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Use one space after periods and colons. Hyphenate complex modifiers: "zero-field-cooled magnetization." Avoid dangling participles, such as, "Using (10), the potential was calculated." [It is not clear who or what used (10).] Write instead, "The potential was calculated by using (10)," or "Using (10), we calculated the potential."

Use a zero before decimal points: "0.25," not ".25." Use "cm<sup>3</sup>," not "cc." Indicate sample dimensions as "0.1 cm × 0.2 cm," not "0.1 × 0.2 cm<sup>2</sup>." The abbreviation for "seconds" is "s," not "sec." Use "Wb/m<sup>2</sup>" or "webers per square meter,"

not "webers/m<sup>2</sup>." When expressing a range of values, write "7 to 9" or "7–9," not "7~9."

A parenthetical statement at the end of a sentence is punctuated outside of the closing parenthesis (like this). (A parenthetical sentence is punctuated within the parentheses.) In American English, periods and commas are within quotation marks, like "this period." Other punctuation is "outside"! Avoid contractions; for example, write "do not" instead of "don't." The serial comma is preferred: "A, B, and C" instead of "A, B and C."

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```
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\usepackage{Journal_Name}
```

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Use either SI (MKS) or CGS as primary units. (SI units are strongly encouraged.) English units may be used as secondary units (in parentheses). This applies to papers in data storage. For example, write "15 Gb/cm<sup>2</sup> (100 Gb/in<sup>2</sup>).". An exception is when English units are used as identifiers in trade, such as "3½-in disk drive." Avoid combining SI and CGS units, such as current in amperes and magnetic field in oersteds. This often leads to confusion because equations do not balance dimensionally. If you must use mixed units, clearly state the units for each quantity in an equation.

The SI unit for magnetic field strength  $H$  is A/m. However, if you wish to use units of T, either refer to magnetic flux density  $B$  or magnetic field strength symbolized as  $\mu_0 H$ . Use the center dot to separate compound units, e.g., "A·m<sup>2</sup>."

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The word "data" is plural, not singular. The subscript for the permeability of vacuum  $\mu_0$  is zero, not a lowercase letter "o." The term for residual magnetization is "remanence"; the adjective is "remanent"; do not write "remnance" or "remnant." Use the word "micrometer" instead of "micron." A graph within a graph is an "inset," not an "insert." The

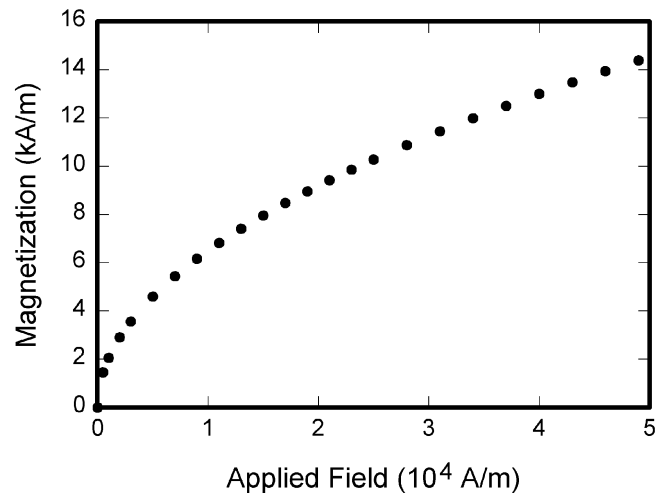


Fig. 2. Magnetization as a function of applied field. It is good practice to explain the significance of the figure in the caption.

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2) *Line Art figures*: Figures that are composed of only black lines and shapes. These figures should have no shades or half-tones of gray, only black and white.



TABLE IV  
UNITS FOR MAGNETIC PROPERTIES

Symbol	Quantity	Conversion from Gaussian and CGS EMU to SI <sup>a</sup>
$\Phi$	magnetic flux	1 Mx $\rightarrow 10^{-8}$ Wb = $10^{-8}$ V·s
$B$	magnetic flux density, magnetic induction	1 G $\rightarrow 10^{-4}$ T = $10^{-4}$ Wb/m <sup>2</sup>
$H$	magnetic field strength	1 Oe $\rightarrow 10^3/(4\pi)$ A/m
$m$	magnetic moment	1 erg/G = 1 emu $\rightarrow 10^{-3}$ A·m <sup>2</sup> = $10^{-3}$ J/T
$M$	magnetization	1 erg/(G·cm <sup>3</sup> ) = 1 emu/cm <sup>3</sup> $\rightarrow 10^3$ A/m
$4\pi M$	magnetization	1 G $\rightarrow 10^3/(4\pi)$ A/m
$\sigma$	specific magnetization	1 erg/(G·g) = 1 emu/g $\rightarrow 1$ A·m <sup>2</sup> /kg
$j$	magnetic dipole moment	1 erg/G = 1 emu $\rightarrow 4\pi \times 10^{-10}$ Wb·m
$J$	magnetic polarization	1 erg/(G·cm <sup>3</sup> ) = 1 emu/cm <sup>3</sup> $\rightarrow 4\pi \times 10^{-4}$ T
$\chi, \kappa$	susceptibility	1 $\rightarrow 4\pi$
$\chi_\rho$	mass susceptibility	1 cm <sup>3</sup> /g $\rightarrow 4\pi \times 10^{-3}$ m <sup>3</sup> /kg
$\mu$	permeability	1 $\rightarrow 4\pi \times 10^{-7}$ H/m = $4\pi \times 10^{-7}$ Wb/(A·m)
$\mu_r$	relative permeability	$\mu \rightarrow \mu_r$
$w, W$	energy density	1 erg/cm <sup>3</sup> $\rightarrow 10^{-1}$ J/m <sup>3</sup>
$N, D$	demagnetizing factor	1 $\rightarrow 1/(4\pi)$

Vertical lines are optional in tables. Statements that serve as captions for the entire table do not need footnote letters.

<sup>a</sup>Gaussian units are the same as cg emu for magnetostatics; Mx = maxwell, G = gauss, Oe = oersted; Wb = weber, V = volt, s = second, T = tesla, m = meter, A = ampere, J = joule, kg = kilogram, H = henry.

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## XII. CONCLUSION

A conclusion section is not required. Although a conclusion may review the main points of the paper, do not replicate the abstract as the conclusion. A conclusion might elaborate on the importance of the work or suggest applications and extensions.

Appendixes, if needed, appear before the acknowledgment.

## ACKNOWLEDGMENT

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## APPENDIX I

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J. K. Author, “Title of chapter in the book,” in *Title of His Published Book*, *x*th ed. City of Publisher, (only U.S. State), Country: Abbrev. of Publisher, year, ch. *x*, sec. *x*, pp. *xxx–xxx*.  
See [1], [2].
- *Basic format for periodicals:*  
J. K. Author, “Name of paper,” *Abbrev. Title of Periodical*, vol. *x*, no. *x*, pp. *xxx–xxx*, Abbrev. Month, year, DOI: 10.1109.XXX.123456.  
See [3]– [5].
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J. K. Author, “Title of report,” Abbrev. Name of Co., City of Co., Abbrev. State, Country, Rep. *xxx*, year.  
See [6], [7].
- *Basic format for handbooks:*  
*Name of Manual/Handbook*, *x* ed., Abbrev. Name of Co., City of Co., Abbrev. State, Country, year, pp. *xxx–xxx*.  
See [8], [9].
- *Basic format for books (when available online):*  
J. K. Author, “Title of chapter in the book,” in *Title of Published Book*, *x*th ed. City of Publisher, State, Country: Abbrev. of Publisher, year, ch. *x*, sec. *x*, pp. *xxx–xxx*. [Online]. Available: <http://www.web.com>  
See [10]– [13].
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J. K. Author, “Name of paper,” *Abbrev. Title of Periodical*, vol. *x*, no. *x*, pp. *xxx–xxx*, Abbrev. Month, year. Accessed on: Month, Day, year, DOI: 10.1109.XXX.123456, [Online].  
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J. K. Author. “Title of report,” Company. City, State, Country. Rep. no., (optional: vol./issue), Date. [Online] Available: site/path/file  
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J. K. Author, "Title of paper," in *Abbreviated Name of Conf.*, City of Conf., Abbrev. State (if given), Country, year, pp. xxxxxx.  
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See [23].
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J. K. Author, "Title of patent," U.S. Patent x xxx xxx, Abbrev. Month, day, year.  
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**Second B. Author** was born in Greenwich Village, New York, NY, USA in 1977. He received the B.S. and M.S. degrees in aerospace engineering from the University of Virginia, Charlottesville, in 2001 and the Ph.D. degree in mechanical engineering from Drexel University, Philadelphia, PA, in 2008.

From 2001 to 2004, he was a Research Assistant with the Princeton Plasma Physics Laboratory. Since 2009, he has been an Assistant Professor with the Mechanical Engineering Department, Texas A&M University, College Station. He is the author of three books, more than 150 articles, and more than 70 inventions. His research interests include high-pressure and high-density nonthermal plasma discharge processes and applications, microscale plasma discharges, discharges in liquids, spectroscopic diagnostics, plasma propulsion, and innovation plasma applications. He is an Associate Editor of the journal *Earth, Moon, Planets*, and holds two patents.

Dr. Author was a recipient of the International Association of Geomagnetism and Aeronomy Young Scientist Award for Excellence in 2008, and the IEEE Electromagnetic Compatibility Society Best Symposium Paper Award in 2011.



**Third C. Author, Jr.** (M'87) received the B.S. degree in mechanical engineering from National Chung Cheng University, Chiayi, Taiwan, in 2004 and the M.S. degree in mechanical engineering from National Tsing Hua University, Hsinchu, Taiwan, in 2006. He is currently pursuing the Ph.D. degree in mechanical engineering at Texas A&M University, College Station, TX, USA.

From 2008 to 2009, he was a Research Assistant with the Institute of Physics, Academia Sinica, Taipei, Taiwan. His research interest includes the development of surface processing and biological/medical treatment techniques using nonthermal atmospheric pressure plasmas, fundamental study of plasma sources, and fabrication of micro- or nanostructured surfaces.

Mr. Author's awards and honors include the Frew Fellowship (Australian Academy of Science), the I. I. Rabi Prize (APS), the European Frequency and Time Forum Award, the Carl Zeiss Research Award, the William F. Meggers Award and the Adolph Lomb Medal (OSA).