AI Safety

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Abstract

Abstract here.

outputs? It does something like argmax.

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1	Cartesian and naturalized agents	
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	1. Consider a robot thinking about a video game: what inputs would cause me to win?	
	It thinks about what happens if it puts in inputs A and B; which input would give g	ood

2. Now consider a different world. In this world the robot imagines itself in this world. The game involves robots thinking about things like robots.

In the first setting, the robot thinks: Here's one thing I can do, and what it does to the world. It has copies of the world inside it.

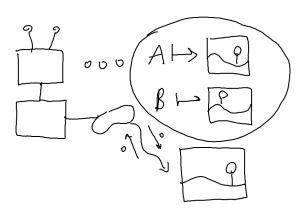


Figure 1: Cartesian agent

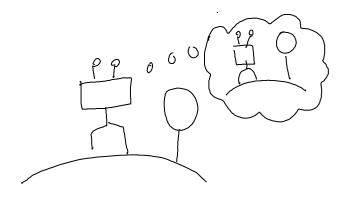


Figure 2: Naturalized agent

In the second setting: Here you can't fit a whole copy of the world inside the robot's brain because the robot's brain is in the world. There are no "functions."

We don't have a function the robot knows or a well-defined function the robot can learn about. There's nothing that feels like a "base" function.

There are other things that reason like the robot.

The first setting is a **Cartesian agent**—"plug into" the world. The second is a **naturalized agent**.

Question: what are naturalized agents like?

(You can introduce some complications in the Cartesian case by requiring the robot to be smaller than the world.)

There could be a thing in the video game that is a copy of the robot: the robot affects its input-output channel but also something else in the video game.

1.1 Discussion

1. Q: In practice don't fully simulate the world/other agents. What about a partial simulation? But some robot which did more can exploit you?

The mindset is: We're focusing on creating Euclidean geometry, not do the engineering.

- 2. Only thing that controls is input/output. Contents of agent's head and thought process. You can't split it into input/output channel.
- 3. Imagine I just thought of the world as neurons firing. But isn't that isomorphic to knowing about myself? The thought itself is an action.

"You're optimizing the thing that is doing the optimizing."