

A Coq Formalization of Taylor Models and Power Series for Solving Ordinary Differential Equations

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- Rounding and approximation errors in floating point implementations raise difficulties for verification of numerical programs.
 - Basic rules like associativity and commutativity of addition and multiplication, etc. do not hold.
 - Can not simply compose programs.
- Exact real computation is an alternative approach to computing with real numbers, where real numbers are represented exactly by infinite sequences.
- Theory based on Computable Analysis/Type-2 Theory of Effectivity.
- Nice mathematical properties \rightsquigarrow well-suited for formal verification.
- Implementations exist for many programming languages.

aern2-real: Real numbers as convergent sequences of intervals

[[bsd3](#), [library](#), [math](#)] [[Propose Tags](#)]

Please see the README on GitHub at <https://github.com/michalkonecny/aern2/#readme>

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[0.2.9.2](#), [0.2.10.0](#), [0.2.11.0](#), [0.2.12.0](#), [0.2.13.0](#), [0.2.14](#),
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0.2.9.2, 0.2.10.0, 0.2.11.0, 0.2.12.0, 0.2.13.0, 0.2.14,
0.2.14.1, 0.2.15

1. Data types

This package provides the following two data types:

- `CReal`: Exact real numbers via lazy sequences of interval approximations
- `CKleenean`: Lazy Kleeneans, naturally arising from comparisons of `CReals`

Real numbers can be approximated up to any desired output precision:

```
...> pi + pi*pi+2^(-3) ? (bits 60)
[13.1361970546791518572971076... ± 5.0568e-23 2^(-74)]
```

Internally real numbers are represented as converging intervals.

New real numbers can be defined as limits of fastly converging sequences:

```
e_sum n = sum $ map (recip . fact) [0..n]
my_e = limit $ \(n :: Integer) -> e_sum (n+2)
```

```
...> my_e ? (bits 1000)
[2.71828182845904523536028747... ± ~0.0000 ~2^(-1217)]
```

The result of comparisons can only be evaluated lazily:

```
...> pi > 0 ? (prec 10)
```

```
CertainTrue
```

```
...> pi == pi + 2(-100) ? (prec 60)
```

```
TrueOrFalse
```

```
...> (pi == pi + 2(-100)) ? (prec 1000)
```

```
CertainFalse
```

Verified exact real computation

- The cAERN library (Park, Konecný, T.) is a formalization of exact real computation in the Coq proof assistant.
 - <https://github.com/holgerthies/coq-aern>
- We axiomatically introduce computational types such as \mathbb{R} for real numbers, \mathbb{K} for Kleeneans, etc.
 - Characterized by classical axioms:
 - $\forall (x, y : \mathbb{R}). x < y \vee x = y \vee x > y$
 - ...
 - And computationally valid axioms:
 - $\forall (x, y : \mathbb{R}). \{k : \mathbb{K} \mid k = \text{true} \leftrightarrow x < y\}$
 - $\lim s : \forall (n, m : \mathbb{N}). |s_n - s_m| < 2^{-n-m} \rightarrow \{r : \mathbb{R} \mid \forall (k : \mathbb{N}). |r - s_k| < 2^{-k}\}$
 - ...
- By using Coq's code extraction features and mapping axiomatically defined types to basic types in AERN, we can extract AERN programs from proofs.

Code extraction example

```
Lemma real_max_prop :  
  forall x y, {z | (x >= y → z = x)  
                  ∧ (x < y → z = y)}.
```

Proof.

```
  intros.  
  apply real_mslimit_P_lt.  
  + (* max is single-valued *)  
  ...  
  + (* construct limit *)  
  intros.  
  apply (mjoin (x>y - prec n)  
            (y>x - prec n)).  
  ++ intros [c1|c2].  
    +++ (* when  $x > y - 2^{-n}$  *)  
    exists x.  
    ...  
    +++ (* when  $x < y - 2^{-n}$  *)  
    exists y.  
    ...  
  ++ apply M_split.  
  apply prec_pos.
```

Defined.

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real_max_prop ::  
  AERN2.CReal ->  
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real_max_prop x y =  
  AERN2.limit (\n ->  
    Prelude.id (\h -> case h of {  
      P.True  -> x;  
      P.False -> y}))  
    (m_split x y (prec n)))
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Ordinary Differential Equations

- Goal of this work: Extension to Ordinary Differential Equation Solving.
- More precisely, we consider initial values problems for (autonomous) ordinary differential equations of the form

$$\dot{y}(t) = f(y(t)) ; y(t_0) = y_0.$$

- By solving the IVP, we mean to compute $y(t)$ for any $t \in [t_0, t_0 + T]$ for some $T > 0$ exactly (i.e. being able to output approximations up to any desired precision).

ODE solving in cAERN

- In the Coq formalization for now we consider only 1-dimensional polynomial ODEs.
 - We define polynomials simply as list of coefficients with evaluation operator.
- The method itself works for analytic ODEs with arbitrary dimension.

We define g to be the derivative of f on the interval $[-r, r]$ by

Definition `uniform_derivative f g r` := `forall` $\epsilon, (\epsilon > 0) \rightarrow$
`exists` $\delta, \delta > 0 \wedge$ `forall` $(x\ y : \mathbb{I}\ r), \text{dist } x\ y \leq \delta$
 $\rightarrow \text{abs } (f\ y - f\ x - g\ x * (y - x)) \leq \epsilon * \text{abs } (y - x).$

We can then define y to be the solution of the polynomial IVP

$\dot{y} = p(y)$; $y(0) = y_0$ by

Definition `pivp_solution p y y0 r` :=
 $(y\ 0) = y_0 \wedge \text{uniform_derivative } y\ (\text{fun } t \Rightarrow (\text{eval_poly } p\ (y\ t)))\ r.$

- The solution $y(t)$ of a polynomial ODE is an analytic function, i.e., it is locally defined by its power series $\sum_{i=0}^{\infty} a_n t^n$
- Power series can be encoded as infinite sequences of reals.
- The partial sums $\sum_{i=0}^N a_n t^n$ are polynomial approximations for $y(t)$.
- However, the sequence alone is not sufficient to get rigorous error bounds.
- Thus, we want to represent analytic functions in a way that lets us evaluate the function.

Polynomials and Taylor models

- Instead of only for analytic functions, we consider rigorous polynomial approximations of functions in a more general setting.
- Let $f: D \subseteq \mathbb{R}^d \rightarrow \mathbb{R}$ be $(k+1)$ times continuously differentiable.
- A Taylor model [Makino, Berz] of order k for f over the domain D is a pair (P_k, Δ_k) of a d -variate polynomial of order k and a remainder $\Delta_k \in \mathbb{R}$ such that

$$|f(x) - P_k(x)| \leq \Delta_k,$$

for all $x \in D$.

- Sequences of Taylor models with $\Delta_k \rightarrow 0$ used to encode functions on an interval.

Analytic Functions

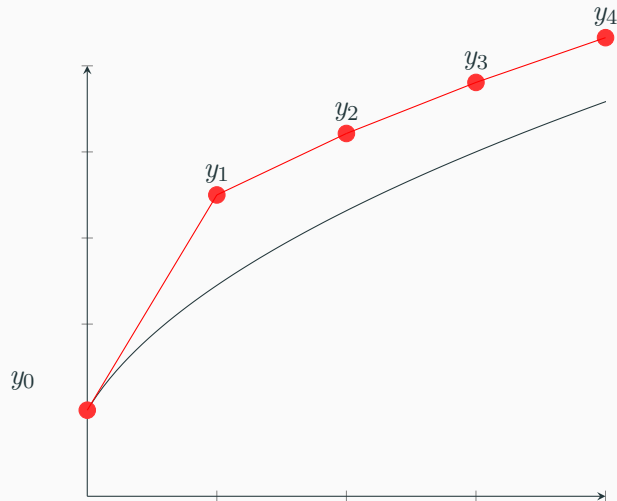
We enrich power series by simple real constants M, r that let us compute error bounds for Taylor models of arbitrary order on the interval $[-r, r]$:

```
Record bounded_ps : Type := mk_bounded_ps
{
  series : N → R;
  bounded_ps_M : N;
  bounded_ps_r : R;
  bounded_ps_rgt0 : bounded_ps_r > 0;
  bounded_ps_bounded: forall n, abs (a n) ≤
    bounded_ps_M * bounded_ps_r-n
}.
```

For $|x| < r$ we get the tail estimate

$$\left| \sum_{n=N+1}^{\infty} a_n x^n \right| \leq M \sum_{n=N+1}^{\infty} \left(\frac{x}{r}\right)^n = M \frac{\left(\frac{x}{r}\right)^{N+1}}{1 - \frac{x}{r}}.$$

Method overview

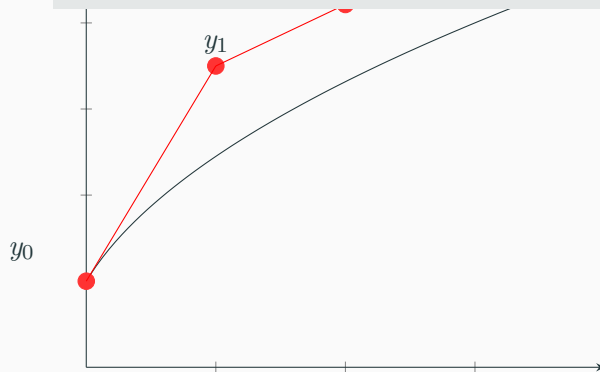


Example (Euler's method)

Choose some step size h and iterate

$$t_{n+1} = t_n + h$$

$$y_{n+1} = y_n + h \cdot F(y_n)$$

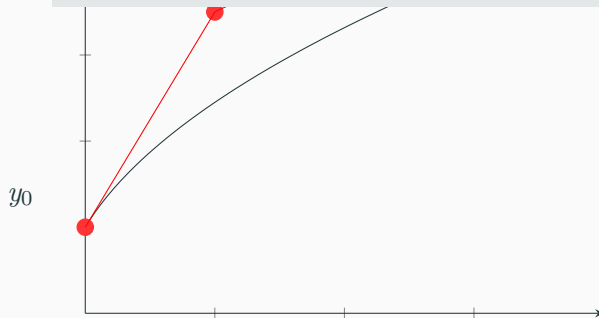


Example (Higher order method)

Choose some step size h and iterate

$$t_{n+1} = t_n + h$$

$$y_{n+1} = \sum_{m=0}^N \frac{y^{(m)}(t_n)}{m!} h^m$$



Solution algorithm (Power Series)

- Note that as the system is autonomous, the solution does not depend on the initial time t_0 (except for being shifted).
- We can also assume $y_0 = 0$ by shifting f .
- Thus, we can assume $t_0 = 0$ and $y_0 = 0$.
- By applying the chain rule

$$\ddot{y}(t) = \dot{y}(t)f'(y(t)) = f(y(t))f'(y(t))$$

we can compute the power series coefficients of $y(t)$ at 0.

- As the solution is analytic, there is some $R > 0$ such that $\sum_{n=0}^{\infty} a_n t^n$ converges whenever $|t| < R$.
- The partial sums $\sum_{k=0}^N \frac{y^{(k)}(0)}{k!} t^k$ are polynomial approximations of $y(t)$.

Error bounds

- We formalized a simple way to get an error bound on a small interval.
- As the solution is analytic, there exist constants $M, r \in \mathbb{R}$ such that $|a_n| \leq Mr^{-n}$ for all $n \in \mathbb{N}$.
- We can compute such constant from the coefficients of the polynomial (although not optimal ones).
- Given M and r , for any t with $|t| \leq \frac{r}{2}$ we have the tail estimate $|\sum_{n=N+1}^{\infty} a_n t^n| \leq M2^{-N}$.
- Thus, it is easy to compute how many coefficients are needed for error 2^{-N} .
- This lets us compute $y(t)$ for any $t \in [0, \frac{r}{2}]$.

Extending the solution

- By using $y(r/2)$ as new initial value, we can extend the solution.
- A new step size is computed in each step (i.e. the step size is adaptive).
- It depends only on the polynomial and the initial value and not on the precision for approximations.
- The step size goes to 0 when approaching the boundary of the interval of existence of the ODE.

Conclusion and Future work

- We extended the cAERN library to a theory of classical functions, polynomial approximations via Taylor models, analytic functions and ODE solving.
- From the proof we can extract programs to compute ODE solution up to any desired precision.
- Future work
 - Generalize to ODE systems of arbitrary dimension.
 - Improve the step size in the iterative algorithm.
 - Encode other methods for ODE solving and compare different methods in terms of efficiency of extracted programs.

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Thank you!