Example evaluation of FOCUS dataset Z

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K	ey words: Kinetics, FOCUS, nonlinear optimisation	

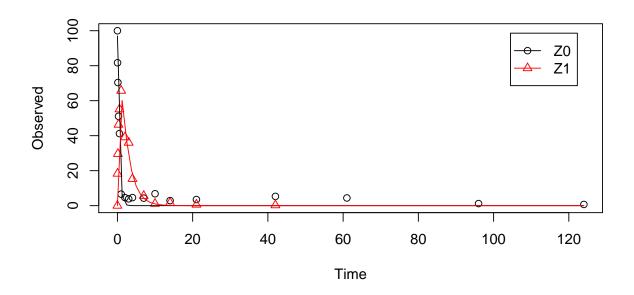
1 The data

The following code defines the example dataset from Appendix 7 to the FOCUS kinetics report (FOCUS Work Group on Degradation Kinetics, 2011), p.350.

2 Parent compound and one metabolite

The next step is to set up the models used for the kinetic analysis. As the simultaneous fit of parent and the first metabolite is usually straightforward, Step 1 (SFO for parent only) is skipped here. We start with the model 2a, with formation and decline of metabolite Z1 and the pathway from parent directly to sink included (default in mkin).

```
m.Z.2a <- mkinfit(Z.2a, FOCUS_2006_Z_mkin, quiet = TRUE)
plot(m.Z.2a)</pre>
```

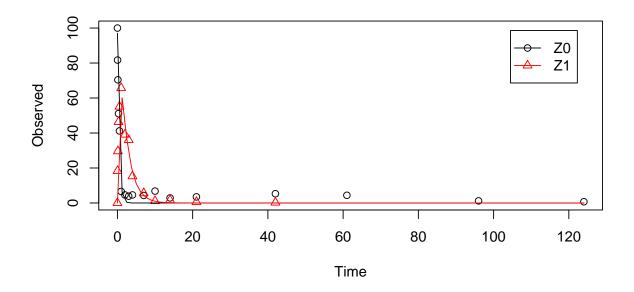


```
summary(m.Z.2a, data = FALSE)
## mkin version:
                                                                                                 0.9.27
## R version:
                                                                                                 3.1.0
## Date of fit:
                                                                                                 Thu May 8 20:33:26 2014
## Date of summary: Thu May 8 20:33:26 2014
##
## Equations:
## [1] d_{Z0} = - k_{Z0} = - k_
## [2] d_Z1 = + k_Z0_Z1 * Z0 - k_Z1_sink * Z1
##
## Method used for solution of differential equation system:
## eigen
##
## Weighting: none
## Starting values for optimised parameters:
##
                                                                             value
                                                                                                                  type transformed
                                                              100.0000 state
## ZO_0
                                                                                                                                                               100.000
## k_Z0_sink
                                                                        0.1000 deparm
                                                                                                                                                                    -2.303
                                                                                                                                                                    -2.302
## k_Z0_Z1
                                                                        0.1001 deparm
```

```
## k_Z1_sink 0.1002 deparm -2.301
##
## Fixed parameter values:
## value type
## Z1_0 0 state
##
## Optimised, transformed parameters:
##
            Estimate Std. Error Lower Upper t value Pr(>|t|) Pr(>t)
## ZO_0
              97.000
                              NA
                                    NA
                                          NA
                                                  NA
                                                           NA
                                                                  NA
## k_Z0_sink -36.400
                                    NA
                                          NA
                                                  NA
                              NA
                                                           NA
                                                                  NA
## k_Z0_Z1
              0.805
                                    NA
                                          NA
                                                  NA
                                                           NA
                              NA
                                                                  NA
## k_Z1_sink
              -0.730
                              NA
                                    NA
                                          NA
                                                  NA
                                                           NA
                                                                  NA
## Backtransformed parameters:
           Estimate Lower Upper
## ZO_0
           9.70e+01
                        NA
## k_Z0_sink 1.62e-16
                        NA
                               NA
## k_Z0_Z1 2.24e+00
                        NA
                               NA
## k_Z1_sink 4.82e-01
                        NA
                               NA
## Residual standard error: 5.06 on 27 degrees of freedom
## Chi2 error levels in percent:
            err.min n.optim df
## All data
             17.9
                         4 26
## Z0
               18.0
                          3 14
## Z1
              15.1
                         1 12
## Estimated disappearance times:
    DT50 DT90
## Z0 0.31 1.03
## Z1 1.44 4.78
## Estimated formation fractions:
## Z0_sink 7.23e-17
## Z0_Z1 1.00e+00
## Z1_sink 1.00e+00
##
## Parameter correlation:
## Could not estimate covariance matrix; singular system:
```

As obvious from the summary, the kinetic rate constant from parent compound Z to sink is negligible. Accordingly, the exact magnitude of the fitted parameter log k_Z_sink is ill-defined and the covariance matrix is not returned. This suggests, in agreement with the analysis in the FOCUS kinetics report, to simplify the model by removing the pathway to sink.

A similar result can be obtained when formation fractions are used in the model formulation:

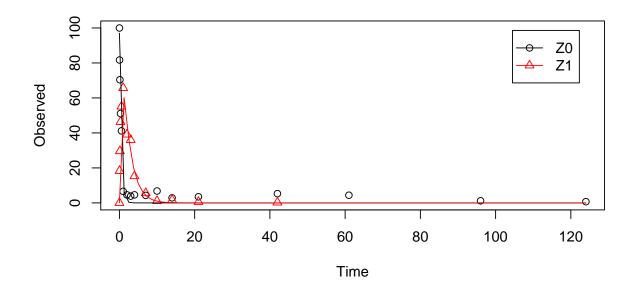


```
##
## Method used for solution of differential equation system:
## eigen
##
## Weighting: none
## Starting values for optimised parameters:
##
                 value
                       type transformed
## ZO_0
             100.0000 state
                               100.0000
## k_ZO
                                 -2.3026
               0.1000 deparm
## f_Z0_to_Z1 0.2000 deparm
                                 -0.9803
## k_Z1
               0.1001 deparm
                                 -2.3016
##
## Fixed parameter values:
## value type
## Z1_0 0 state
##
## Optimised, transformed parameters:
             Estimate Std. Error Lower Upper t value Pr(>|t|) Pr(>t)
##
## Z0_0
               97.000
                              NA
                                    NA
                                          NA
                                                   NA
                                                            NA
## k_Z0
                0.805
                               NA
                                     NA
                                           NA
                                                   NA
                                                            NA
                                                                   NA
## f_Z0_to_Z1
               24.100
                              NA
                                    NA
                                          NA
                                                   NA
                                                            NA
                                                                   NA
## k_Z1
               -0.730
                              NA
                                    NA
                                          NA
                                                   NA
                                                            NA
                                                                   NA
##
## Backtransformed parameters:
             Estimate Lower Upper
## ZO_0
                97.000
                          NA
## k_Z0
                 2.240
                          NA
                                NΑ
## f_Z0_to_Z1
                1.000
                                NA
                         NA
## k_Z1
                 0.482
                         NA
                               NA
##
## Residual standard error: 5.06 on 27 degrees of freedom
## Chi2 error levels in percent:
            err.min n.optim df
## All data
             17.9
                        4 26
## ZO
              17.6
                          2 15
## Z1
              15.6
                          2 11
## Estimated disappearance times:
## DT50 DT90
## Z0 0.31 1.03
```

```
## Z1 1.44 4.78
##
## Parameter correlation:
## Could not estimate covariance matrix; singular system:
```

Here, the ilr transformed formation fraction fitted in the model takes a very large value, and the backtransformed formation fraction from parent Z to Z1 is practically unity. Again, the covariance matrix is not returned as the model is overparameterised.

The simplified model is obtained by setting the list component sink to FALSE.



```
## [2] d_Z1 = + k_Z0_Z1 * Z0 - k_Z1_sink * Z1
## Method used for solution of differential equation system:
## eigen
##
## Weighting: none
## Starting values for optimised parameters:
                      type transformed
               value
## ZO_0
            100.0000 state
                               100.000
## k_Z0_Z1
            0.1000 deparm
                               -2.303
## k_Z1_sink 0.1001 deparm
                                -2.302
##
## Fixed parameter values:
## value type
## Z1_0
           0 state
##
## Optimised, transformed parameters:
##
           Estimate Std. Error Lower Upper t value Pr(>|t|) Pr(>t)
## ZO_0
              97.000
                        2.6800 91.500 103.000 36.20 4.73e-25 2.36e-25
## k_Z0_Z1
              0.805
                       0.0657 0.670 0.939 12.30 9.12e-13 4.56e-13
## k_Z1_sink
              -0.730
                       0.0885 -0.911 -0.548 -8.24 5.74e-09 2.87e-09
## Backtransformed parameters:
           Estimate Lower
                             Upper
## ZO_0
              97.000 91.500 103.000
## k_Z0_Z1
              2.240 1.950
                            2.560
## k_Z1_sink
               0.482 0.402
                             0.578
## Residual standard error: 4.97 on 28 degrees of freedom
## Chi2 error levels in percent:
           err.min n.optim df
           17.6
## All data
                        3 27
## Z0
              17.6
                         2 15
## Z1
              15.1
                        1 12
##
## Estimated disappearance times:
## DT50 DT90
## Z0 0.31 1.03
## Z1 1.44 4.78
##
```

```
## Estimated formation fractions:
##
          ff
## Z0_sink 1
## ZO_Z1
           1
## Z1_sink 1
##
## Parameter correlation:
##
             Z0_0 k_Z0_Z1 k_Z1_sink
## ZO_0
            1.000 0.1063
                          0.4104
## k_Z0_Z1
          0.106 1.0000
                             0.0434
## k_Z1_sink 0.410 0.0434
                          1.0000
```

This model definition is not supported when formation fractions are used, but the formation fraction can be fixed to unity.

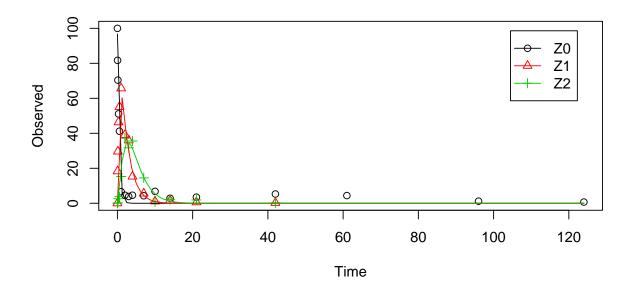
```
Z.3.ff \leftarrow mkinmod(ZO = list(type = "SFO", to = "Z1"),
               Z1 = list(type = "SFO"), use_of_ff = "max")
m.Z.3.ff <- mkinfit(Z.3.ff, FOCUS_2006_Z_mkin,</pre>
                    parms.ini = c(f_Z0_to_Z1 = 1),
                    fixed_parms = "f_Z0_to_Z1",
                    quiet = TRUE)
summary(m.Z.3.ff, data = FALSE)
## mkin version:
                    0.9.27
## R version:
                    3.1.0
## Date of fit:
                   Thu May 8 20:33:28 2014
## Date of summary: Thu May 8 20:33:28 2014
##
## Equations:
## [1] d_Z0 = - k_Z0 * Z0
## [2] d_Z1 = + f_Z0_to_Z1 * k_Z0 * Z0 - k_Z1 * Z1
## Method used for solution of differential equation system:
## eigen
##
## Weighting: none
##
## Starting values for optimised parameters:
           value
                   type transformed
## Z0_0 100.0000 state
                            100.000
## k_Z0 0.1000 deparm
                             -2.303
## k_Z1 0.1001 deparm
                             -2.302
##
```

```
## Fixed parameter values:
##
              value
                      type
## Z1_0
                  0
                     state
## f_Z0_to_Z1
                  1 deparm
## Optimised, transformed parameters:
        Estimate Std. Error Lower
                                      Upper t value Pr(>|t|)
## ZO_0
          97.000
                     2.6800 91.500 103.000
                                              36.20 4.73e-25 2.36e-25
                     0.0657 0.670
                                      0.939
                                              12.30 9.12e-13 4.56e-13
## k_Z0
           0.805
## k_Z1
          -0.730
                     0.0885 -0.911 -0.548
                                              -8.24 5.74e-09 2.87e-09
##
## Backtransformed parameters:
##
        Estimate Lower
                           Upper
## Z0_0
          97.000 91.500 103.000
## k_Z0
           2.240
                 1.950
                           2.560
## k_Z1
           0.482
                  0.402
                           0.578
##
## Residual standard error: 4.97 on 28 degrees of freedom
## Chi2 error levels in percent:
            err.min n.optim df
               17.6
                          3 27
## All data
               17.6
                           2 15
## Z0
## Z1
               15.1
                           1 12
##
## Estimated disappearance times:
##
      DT50 DT90
## Z0 0.31 1.03
## Z1 1.44 4.78
##
## Parameter correlation:
         Z0_0
               k_Z0
## Z0_0 1.000 0.1063 0.4104
## k_Z0 0.106 1.0000 0.0434
## k_Z1 0.410 0.0434 1.0000
```

3 Including metabolites Z2 and Z3

As suggested in the FOCUS report, the pathway to sink was removed for metabolite Z1 as well in the next step. While this step appears questionable on the basis of the above

results, it is followed here for the purpose of comparison. Also, in the FOCUS report, it is assumed that there is additional empirical evidence that Z1 quickly and exclusively hydrolyses to Z2.



```
summary(m.Z.5, data = FALSE)
## mkin version:
                    0.9.27
## R version:
                    3.1.0
## Date of fit:
                    Thu May 8 20:33:29 2014
## Date of summary: Thu May 8 20:33:29 2014
##
## Equations:
## [1] d_Z0 = -0 - k_Z0_Z1 * Z0
## [2] d_Z1 = + k_Z0_Z1 * Z0 - 0 - k_Z1_Z2 * Z1
## [3] d_Z2 = + k_Z1_Z2 * Z1 - k_Z2_sink * Z2
## Method used for solution of differential equation system:
## eigen
##
```

```
## Weighting: none
## Starting values for optimised parameters:
##
               value type transformed
## ZO_0
           100.0000 state
                              100.000
## k_Z0_Z1
           0.1000 deparm
                               -2.303
## k_Z1_Z2 0.1001 deparm
                                -2.302
## k_Z2_sink 0.1002 deparm
                               -2.301
##
## Fixed parameter values:
      value type
## Z1 0
        0 state
## Z2_0
         0 state
##
## Optimised, transformed parameters:
##
           Estimate Std. Error Lower
                                       Upper t value Pr(>|t|) Pr(>t)
## ZO_0
                        2.2700 92.200 101.000 42.70 5.43e-35 2.72e-35
             96.800
## k_Z0_Z1
              0.795
                       0.0584 0.677 0.913 13.60 1.36e-16 6.80e-17
                       0.0682 -0.879 -0.603 -10.90 1.68e-13 8.41e-14
## k_Z1_Z2
              -0.741
## k_Z2_sink -0.803
                    0.1110 -1.030 -0.579 -7.24 8.79e-09 4.39e-09
##
## Backtransformed parameters:
          Estimate Lower
                             Upper
## Z0_0
             96.800 92.200 101.000
## k_Z0_Z1
              2.210 1.970
                            2.490
## k_Z1_Z2
               0.477 0.415
                             0.547
## k_Z2_sink
              0.448 0.358
                            0.561
## Residual standard error: 4.49 on 40 degrees of freedom
## Chi2 error levels in percent:
     err.min n.optim df
## All data 19.1
                      4 38
## 7.0
             17.4
                        2 15
## Z1
              15.3
                       1 12
## Z2
             19.6
                       1 11
##
## Estimated disappearance times:
      DT50 DT90
## Z0 0.313 1.04
## Z1 1.454 4.83
## Z2 1.547 5.14
```

```
##
## Estimated formation fractions:
##
          ff
## Z0_sink 1
## ZO_Z1
## Z1_sink 1
## Z1_Z2
           1
## Z2_sink 1
##
## Parameter correlation:
##
              Z0_0 k_Z0_Z1 k_Z1_Z2 k_Z2_sink
## Z0_0
            1.0000 0.0578 0.2875
                                    0.3179
## k_Z0_Z1 0.0578 1.0000 -0.0436
                                      0.0121
## k_Z1_Z2
            0.2875 -0.0436 1.0000
                                      0.2402
## k_Z2_sink 0.3179 0.0121 0.2402
                                      1.0000
```

Finally, metabolite Z3 is added to the model. The fit is accellerated by using the starting parameters from the previous fit.

```
Z0
     8
                                                                                      Z1
                                                                                      Z2
Observed
     9
                                                                                      Z3
     4
     20
             0
                         20
                                     40
                                                  60
                                                              80
                                                                          100
                                                                                      120
                                                  Time
```

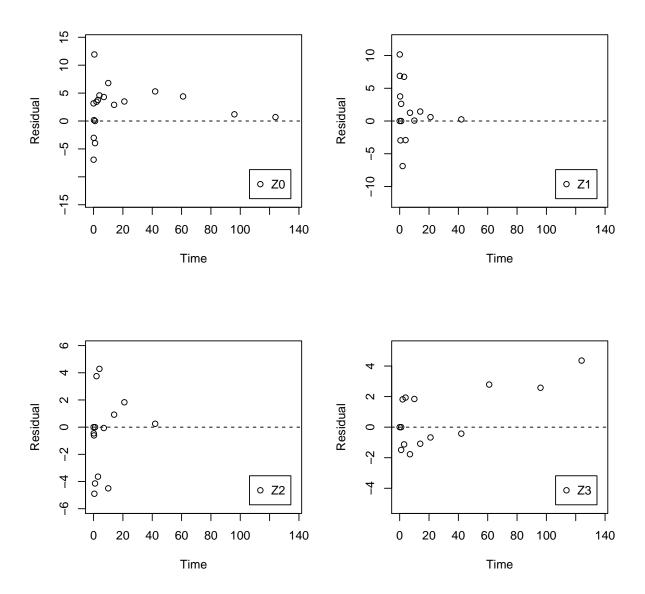
```
summary(m.Z.FOCUS, data = FALSE)
## mkin version:
                    0.9.27
## R version:
                    3.1.0
## Date of fit:
                    Thu May 8 20:33:30 2014
## Date of summary: Thu May 8 20:33:30 2014
##
## Equations:
## [1] d_Z0 = -0 - k_Z0_Z1 * Z0
## [2] d_Z1 = + k_Z0_Z1 * Z0 - 0 - k_Z1_Z2 * Z1
## [3] d_{Z2} = + k_{Z1}Z2 * Z1 - k_{Z2}sink * Z2 - k_{Z2}Z3 * Z2
## [4] d_Z3 = + k_Z2_Z3 * Z2 - k_Z3_sink * Z3
## Method used for solution of differential equation system:
## eigen
##
## Weighting: none
## Starting values for optimised parameters:
##
                value
                        type transformed
## ZO_0
             100.0000 state
                                 100.0000
## k_Z0_Z1
               2.2140 deparm
                                  0.7948
## k_Z1_Z2
               0.4766 deparm
                                 -0.7410
## k_Z2_sink
              0.4481 deparm
                                  -0.8027
```

```
## k_Z2_Z3 0.1000 deparm -2.3026
## k_Z3_sink 0.1001 deparm
                                -2.3016
##
## Fixed parameter values:
       value type
## Z1_0
           0 state
## Z2_0
           0 state
## Z3_0
           0 state
##
## Optimised, transformed parameters:
##
            Estimate Std. Error Lower
                                          Upper t value Pr(>|t|)
                         2.0600 92.700 101.000
                                                 47.00 1.12e-43 5.58e-44
## ZO_0
              96.800
## k_Z0_Z1
               0.795
                         0.0533 0.688
                                        0.902 14.90 3.08e-20 1.54e-20
## k_Z1_Z2
              -0.738
                         0.0612 -0.860 -0.615 -12.00 1.57e-16 7.84e-17
## k_Z2_sink
              -1.430
                        0.1720 -1.780 -1.090 -8.35 4.16e-11 2.08e-11
                         0.1230 -1.790 -1.300 -12.60 2.60e-17 1.30e-17
## k_Z2_Z3
              -1.550
## k_Z3_sink
                         0.2440 -3.320 -2.350 -11.60 5.64e-16 2.82e-16
              -2.840
##
## Backtransformed parameters:
            Estimate Lower
                               Upper
## ZO_0
             96.8000 92.700 101.0000
## k_Z0_Z1
              2.2200
                     1.990
                              2.4700
## k_Z1_Z2
              0.4780 0.423
                             0.5410
## k_Z2_sink
              0.2390 0.169
                              0.3370
## k_Z2_Z3
              0.2130
                      0.166
                               0.2720
## k_Z3_sink
              0.0587
                      0.036
                              0.0957
##
## Residual standard error: 4.1 on 51 degrees of freedom
## Chi2 error levels in percent:
            err.min n.optim df
## All data
              19.2
                         6 48
## Z0
              17.4
                          2 15
## 7.1
              15.2
                         1 12
## Z2
              20.3
                          2 10
## Z3
              11.9
                         1 11
##
## Estimated disappearance times:
##
       DT50 DT90
## Z0
     0.313 1.04
## Z1 1.449 4.81
## Z2 1.535 5.10
```

```
## Z3 11.810 39.23
##
## Estimated formation fractions:
##
              ff
## Z0_sink 1.000
## ZO_Z1
         1.000
## Z1_sink 1.000
## Z1_Z2 1.000
## Z2_sink 0.528
## Z2_Z3
          0.472
## Z3_sink 1.000
##
## Parameter correlation:
##
                ZO_O k_ZO_Z1 k_Z1_Z2 k_Z2_sink k_Z2_Z3 k_Z3_sink
             1.0000 0.0539 0.2727 0.3701 -0.0730 -0.1135
## Z0_0
## k_Z0_Z1 0.0539 1.0000 -0.0521 0.0244 -0.0358 -0.0252
## k_Z1_Z2 0.2727 -0.0521 1.0000 0.2938 -0.1213 -0.1915
## k_Z2_sink 0.3701 0.0244 0.2938 1.0000 -0.1889
                                                            -0.6430
## k_Z2_Z3
             -0.0730 -0.0358 -0.1213
                                         -0.1889
                                                  1.0000
                                                             0.5516
## k_Z3_sink -0.1135 -0.0252 -0.1915
                                         -0.6430 0.5516
                                                             1.0000
```

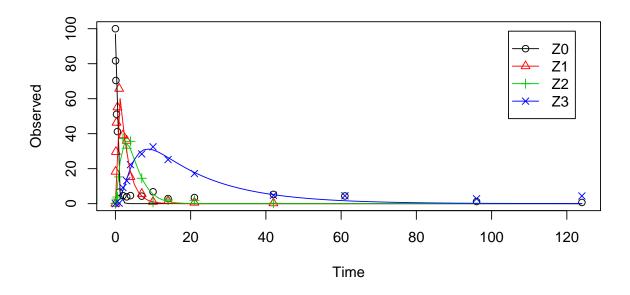
This is the fit corresponding to the final result chosen in Appendix 7 of the FOCUS report. The residual plots can be obtained by

```
par(mfrow = c(2, 2))
mkinresplot(m.Z.FOCUS, "ZO", lpos = "bottomright")
mkinresplot(m.Z.FOCUS, "Z1", lpos = "bottomright")
mkinresplot(m.Z.FOCUS, "Z2", lpos = "bottomright")
mkinresplot(m.Z.FOCUS, "Z3", lpos = "bottomright")
```



We can also investigate the confidence interval for the formation fraction from Z1 to Z2 by specifying the model using formation fractions, and fixing only the formation fraction from Z0 to Z1 to unity.

```
fixed_parms = c("f_Z0_to_Z1"), quiet = TRUE)
plot(m.Z.FOCUS.ff)
```



```
summary(m.Z.FOCUS.ff, data = FALSE)
## mkin version:
                    0.9.27
## R version:
                    3.1.0
## Date of fit:
                   Thu May 8 20:33:34 2014
## Date of summary: Thu May 8 20:33:34 2014
##
## Equations:
## [1] d_Z0 = - k_Z0 * Z0
## [2] d_Z1 = + f_Z0_to_Z1 * k_Z0 * Z0 - k_Z1 * Z1
## [3] d_Z2 = + f_Z1_{to}Z2 * k_Z1 * Z1 - k_Z2 * Z2
## [4] d_Z3 = + f_Z2_to_Z3 * k_Z2 * Z2 - k_Z3 * Z3
## Method used for solution of differential equation system:
## eigen
##
## Weighting: none
## Starting values for optimised parameters:
##
                       type transformed
                value
## Z0_0 100.0000 state 100.0000
```

```
## k_Z0
                0.1000 deparm
                                  -2.3026
## k_Z1
                0.1001 deparm
                                  -2.3016
## f_Z1_to_Z2
                0.2000 deparm
                                  -0.9803
## k_Z2
                0.1002 deparm
                                  -2.3006
## f_Z2_to_Z3
                0.2000 deparm
                                  -0.9803
## k_Z3
                0.1003 deparm
                                  -2.2996
##
## Fixed parameter values:
              value
                      type
## Z1_0
                  0 state
## Z2_0
                  0 state
## Z3_0
                  0 state
## f_Z0_to_Z1
                  1 deparm
##
## Optimised, transformed parameters:
              Estimate Std. Error Lower
                                           Upper t value Pr(>|t|)
                                                                     Pr(>t)
##
## ZO_0
                           2.2300 92.500 101.000 43.500 2.19e-41 1.10e-41
               97.0000
## k_Z0
                0.7970
                           0.0545 0.687
                                           0.906
                                                  14.600 1.06e-19 5.31e-20
## k_Z1
               -0.7320
                           0.0737 -0.880 -0.583
                                                  -9.920 2.10e-13 1.05e-13
              2.7100
## f_Z1_to_Z2
                           5.0200 -7.370 12.800
                                                  0.541 5.91e-01 2.95e-01
## k_Z2
               -0.8170
                           0.1930 -1.210 -0.430 -4.230 9.85e-05 4.92e-05
## f_Z2_to_Z3 -0.0445
                           0.3100 -0.667
                                         0.578 -0.144 8.86e-01 4.43e-01
                           0.2580 -3.340 -2.310 -11.000 6.84e-15 3.42e-15
## k_Z3
               -2.8200
##
## Backtransformed parameters:
                          Lower
              Estimate
                                   Upper
## ZO_0
               97.0000 9.25e+01 101.0000
## k_Z0
                2.2200 1.99e+00
                                  2.4800
## k_Z1
                0.4810 4.15e-01
                                  0.5580
## f_Z1_to_Z2
                0.9790 2.99e-05
                                1.0000
## k_Z2
                0.4420 3.00e-01
                                  0.6510
## f_Z2_to_Z3
                0.4840 2.80e-01
                                  0.6940
## k_Z3
                0.0594 3.54e-02
                                  0.0996
##
## Residual standard error: 4.14 on 50 degrees of freedom
##
## Chi2 error levels in percent:
            err.min n.optim df
## All data
               19.4
                          7 47
               17.5
## Z0
                          2 15
## Z1
               15.2
                          1 12
## Z2
               20.3
                          2 10
```

```
## Z3
                12.4
                           2 10
##
## Estimated disappearance times:
##
        DT50
              DT90
## Z0
       0.312
               1.04
## Z1
       1.441
               4.79
## Z2
       1.570
              5.21
## Z3 11.674 38.78
##
## Parameter correlation:
##
                  Z0_0
                          k_Z0
                                    k_Z1 f_Z1_to_Z2
                                                       k_Z2 f_Z2_to_Z3
                                                                             k_Z3
## ZO_0
                1.0000
                        0.1065
                                 0.40981
                                              -0.361 - 0.166
                                                                  0.142
                                                                          0.00530
## k_Z0
                0.1065
                        1.0000
                                 0.04236
                                              -0.155 -0.132
                                                                          0.02204
                                                                  0.110
## k_Z1
                0.4098
                        0.0424
                                 1.00000
                                              -0.543 - 0.380
                                                                  0.326
                                                                          0.00822
                                               1.000
                                                                 -0.839 -0.29748
## f_Z1_to_Z2 -0.3609 -0.1551 -0.54318
                                                     0.857
## k_Z2
               -0.1663 -0.1319 -0.38048
                                               0.857
                                                                 -0.829 -0.39055
                                                      1.000
## f_Z2_to_Z3 0.1421
                                 0.32586
                                              -0.839 -0.829
                        0.1097
                                                                  1.000
                                                                          0.65471
## k_Z3
                0.0053
                        0.0220
                                 0.00822
                                              -0.297 -0.391
                                                                  0.655
                                                                          1.00000
```

4 Using the SFORB model for parent and metabolites

As the FOCUS report states, there is a certain tailing of the time course of metabolite Z3. Also, the time course of the parent compound is not fitted very well using the SFO model, as residues at a certain low level remain.

Therefore, an additional model is offered here, using the single first-order reversible binding (SFORB) model for metabolite Z3. As expected, the χ^2 error level is lower for metabolite Z3 using this model and the graphical fit for Z3 is improved. However, the covariance matrix is not returned.

```
Z0
                                                                                       Z1
                                                                                       Z2
Observed
     9
                                                                                       Z3
     4
     20
             0
                         20
                                      40
                                                   60
                                                               80
                                                                           100
                                                                                        120
                                                  Time
```

```
summary(m.Z.mkin.1, data = FALSE)
## mkin version:
                     0.9.27
## R version:
                     3.1.0
## Date of fit:
                     Thu May
                             8 20:33:39 2014
## Date of summary: Thu May 8 20:33:39 2014
##
## Equations:
## [1] d_Z0 = -0 - k_Z0_Z1 * Z0
## [2] d_Z1 = + k_Z0_Z1 * Z0 - 0 - k_Z1_Z2 * Z1
## [3] d_{Z2} = + k_{Z1}_{Z2} * Z1 - k_{Z2}_{sink} * Z2 - k_{Z2}_{Z3}_{free} * Z2
## [4] d_Z3_free = + k_Z2_Z3_free * Z2 - k_Z3_free_sink * Z3_free - k_Z3_free_bound *
## [5] d_Z3_bound = + k_Z3_free_bound * Z3_free - k_Z3_bound_free * Z3_bound
##
## Method used for solution of differential equation system:
## eigen
##
## Weighting: none
## Starting values for optimised parameters:
##
                      value
                               type transformed
## ZO_0
                    100.0000 state
                                       100.0000
## k_Z0_Z1
                      0.5000 deparm
                                        -0.6931
## k_Z1_Z2
                      0.3000 deparm
                                        -1.2040
```

```
## k_Z2_sink
                      0.1000 deparm
                                          -2.3026
## k_Z2_Z3_free
                      0.1001 deparm
                                          -2.3016
## k_Z3_free_sink
                      0.1002 deparm
                                          -2.3006
## k_Z3_free_bound
                      0.1000 deparm
                                         -2.3026
## k_Z3_bound_free
                      0.0200 deparm
                                          -3.9120
## Fixed parameter values:
##
               value type
## Z1_0
                   0 state
## Z2_0
                   0 state
## Z3_free_0
                   0 state
## Z3_bound_0
                   0 state
##
## Optimised, transformed parameters:
                    Estimate Std. Error Lower Upper t value Pr(>|t|) Pr(>t)
## ZO_0
                      96.700
                                      NA
                                             NA
                                                   NA
                                                            NA
                                                                     NA
                                                                             NA
## k_Z0_Z1
                       0.795
                                             NA
                                                            NA
                                                                     NA
                                                                             NA
                                      NA
                                                   NA
## k_Z1_Z2
                      -0.743
                                      NA
                                             NA
                                                   NA
                                                            NA
                                                                     NA
                                                                             NA
## k_Z2_sink
                      -1.490
                                      NA
                                             NA
                                                   NA
                                                            NA
                                                                     NA
                                                                             NA
## k_Z2_Z3_free
                      -1.500
                                      NA
                                             NA
                                                   NA
                                                            NA
                                                                     NA
                                                                             NA
## k_Z3_free_sink
                      -2.650
                                      NA
                                             NA
                                                   NA
                                                            NA
                                                                     NA
                                                                             NA
## k_Z3_free_bound
                      -5.240
                                      NA
                                             NA
                                                   NA
                                                            NA
                                                                     NA
                                                                             NA
## k_Z3_bound_free
                     -21.400
                                      NA
                                             NA
                                                   NA
                                                            NA
                                                                     NA
                                                                             NA
##
## Backtransformed parameters:
                    Estimate Lower Upper
## ZO_0
                    9.67e+01
                                 NA
                                       NA
## k_Z0_Z1
                    2.21e+00
                                 NA
                                       NΑ
## k_Z1_Z2
                                       NA
                    4.76e-01
                                 NA
## k_Z2_sink
                    2.24e-01
                                       NA
                                 NA
## k_Z2_Z3_free
                    2.22e-01
                                 NA
                                       NA
## k_Z3_free_sink 7.03e-02
                                 NA
                                       NA
## k_Z3_free_bound 5.28e-03
                                       NA
                                 NA
## k_Z3_bound_free 5.06e-10
                                 NA
                                       NA
##
## Residual standard error: 4.11 on 49 degrees of freedom
## Chi2 error levels in percent:
            err.min n.optim df
               19.23
                            8 46
## All data
## Z0
               17.43
                            2 15
## Z1
               15.27
                            1 12
```

```
## Z2
              20.28
                           2 10
## Z3
               8.22
                           3 9
##
## Estimated disappearance times:
##
        DT50
             DT90
## Z0
       0.313
              1.04
## Z1
       1.457
             4.84
## Z2
      1.552 5.16
## Z3 10.198 45.33
##
## Estimated formation fractions:
                    ff
## Z0_sink
                1.000
## Z0_Z1
                1.000
## Z1_sink
                1.000
## Z1_Z2
                1.000
## Z2_sink
                0.502
## Z2_Z3_free
                0.498
## Z3_free_sink 1.000
##
## Estimated Eigenvalues of SFORB model(s):
      Z3_b1
               Z3_b2
##
## 7.56e-02 4.71e-10
##
## Parameter correlation:
## Could not estimate covariance matrix; singular system:
```

Therefore, a further stepwise model building is performed starting from the stage of parent and one metabolite, starting from the assumption that the model fit for the parent compound can be improved by using the SFORB model.

```
summary(m.Z.mkin.2, data = FALSE)
## mkin version:
                    0.9.27
## R version:
                    3.1.0
## Date of fit:
                    Thu May 8 20:33:40 2014
## Date of summary: Thu May 8 20:33:40 2014
##
## Equations:
## [1] d_ZO_free = - 0 - k_ZO_free_bound * ZO_free + k_ZO_bound_free * ZO_bound - k_Z
## [2] d_Z0_bound = + k_Z0_free_bound * Z0_free - k_Z0_bound_free * Z0_bound
## [3] d_Z1 = + k_Z0_free_Z1 * Z0_free - k_Z1_sink * Z1
## Method used for solution of differential equation system:
## eigen
##
## Weighting: none
## Starting values for optimised parameters:
                      value
                              type transformed
## Z0_free_0
                   100.0000 state
                                        100.000
## k_Z0_free_bound
                     0.1000 deparm
                                         -2.303
## k_Z0_bound_free
                     0.0200 deparm
                                         -3.912
## k_Z0_free_Z1
                     0.1002 deparm
                                         -2.301
## k_Z1_sink
                     0.1003 deparm
                                         -2.300
```

```
##
## Fixed parameter values:
##
              value type
## Z0_bound_0
                 0 state
## Z1_0
                  0 state
##
## Optimised, transformed parameters:
##
                   Estimate Std. Error Lower
                                                Upper t value Pr(>|t|)
## Z0_free_0
                     97.300
                                2.4000 92.400 102.000
                                                        40.60 4.73e-25
## k_Z0_free_bound
                                0.4320 -2.970 -1.190 -4.82 5.44e-05
                     -2.080
## k_Z0_bound_free
                     -4.720
                                1.6000 -8.020 -1.420
                                                        -2.94 6.78e-03
                                                      13.30 4.18e-13
## k_Z0_free_Z1
                     0.855
                                0.0643 0.723
                                              0.987
## k_Z1_sink
                     -0.793
                                0.0851 -0.968 -0.619
                                                        -9.33 8.86e-10
##
                     Pr(>t)
## Z0_free_0
                   2.36e-25
## k_Z0_free_bound 2.72e-05
## k_Z0_bound_free 3.39e-03
## k_Z0_free_Z1
                2.09e-13
## k_Z1_sink
                   4.43e-10
##
## Backtransformed parameters:
##
                   Estimate
                               Lower
                                       Upper
## Z0_free_0
                   97.30000 9.24e+01 102.000
## k_Z0_free_bound 0.12500 5.13e-02
                                      0.303
## k_Z0_bound_free 0.00891 3.29e-04
                                       0.241
## k_Z0_free_Z1
                    2.35000 2.06e+00
                                       2.680
## k_Z1_sink
                    0.45200 3.80e-01
                                       0.539
##
## Residual standard error: 4.44 on 26 degrees of freedom
## Chi2 error levels in percent:
           err.min n.optim df
## All data
              15.6
                          5 25
## 7.0
               14.7
                          4 13
## Z1
               14.3
                          1 12
## Estimated disappearance times:
##
       DT50 DT90
## Z0 0.302 1.19
## Z1 1.532 5.09
##
## Estimated formation fractions:
```

```
##
## Z0_free_sink
                 1
## Z0_free_Z1
                  1
## Z1_sink
                  1
## Estimated Eigenvalues of SFORB model(s):
##
     Z0_b1
             Z0_b2
## 2.47631 0.00846
##
## Parameter correlation:
##
                    Z0_free_0 k_Z0_free_bound k_Z0_bound_free k_Z0_free_Z1
## Z0_free_0
                      1.00000
                                       0.00649
                                                         0.0332
                                                                       0.1118
## k_Z0_free_bound
                      0.00649
                                       1.00000
                                                         0.5465
                                                                       0.4139
## k_Z0_bound_free
                      0.03324
                                       0.54647
                                                         1.0000
                                                                      0.1584
## k_Z0_free_Z1
                      0.11182
                                       0.41393
                                                         0.1584
                                                                       1.0000
## k_Z1_sink
                      0.39155
                                      -0.29191
                                                        -0.1260
                                                                     -0.0419
##
                    k_Z1_sink
## Z0_free_0
                       0.3916
## k_Z0_free_bound
                      -0.2919
## k_Z0_bound_free
                      -0.1260
## k_Z0_free_Z1
                      -0.0419
## k_Z1_sink
                       1.0000
```

When metabolite Z2 is added, the additional sink for Z1 is turned off again, for the same reasons as in the original analysis.

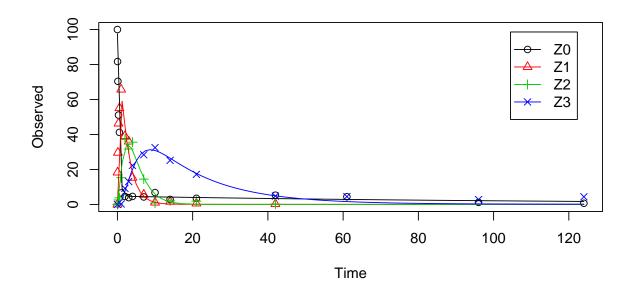
```
summary(m.Z.mkin.3, data = FALSE)
## mkin version:
                    0.9.27
## R version:
                    3.1.0
## Date of fit:
                    Thu May 8 20:33:41 2014
## Date of summary: Thu May 8 20:33:41 2014
##
## Equations:
## [1] d_ZO_free = - 0 - k_ZO_free_bound * ZO_free + k_ZO_bound_free * ZO_bound - k_Z
## [2] d_Z0_bound = + k_Z0_free_bound * Z0_free - k_Z0_bound_free * Z0_bound
## [3] d_Z1 = + k_Z0_free_Z1 * Z0_free - 0 - k_Z1_Z2 * Z1
## [4] d_Z2 = + k_Z1_Z2 * Z1 - k_Z2_sink * Z2
## Method used for solution of differential equation system:
## eigen
##
## Weighting: none
## Starting values for optimised parameters:
##
                      value
                              type transformed
## Z0_free_0
                   100.0000 state
                                        100.000
## k_ZO_free_bound
                     0.1000 deparm
                                         -2.303
## k_Z0_bound_free
                     0.0200 deparm
                                         -3.912
## k_Z0_free_Z1
                     0.1002 deparm
                                         -2.301
```

```
## k_Z1_Z2
                     0.1003 deparm
                                         -2.300
## k_Z2_sink
                     0.1004 deparm
                                         -2.299
##
## Fixed parameter values:
              value type
## Z0_bound_0
                  0 state
## Z1_0
                  0 state
## Z2_0
                  0 state
##
## Optimised, transformed parameters:
##
                   Estimate Std. Error Lower
                                                 Upper t value Pr(>|t|)
## Z0_free_0
                     97.400
                                 2.0700 93.200 102.000
                                                         47.00 2.70e-35
## k_ZO_free_bound
                     -2.150
                                 0.4040 - 2.970 - 1.330
                                                         -5.32 4.88e-06
## k_Z0_bound_free
                     -4.840
                                1.6100 -8.100 -1.580
                                                         -3.00 4.71e-03
## k_Z0_free_Z1
                     0.846
                                0.0583 0.728
                                               0.964
                                                        14.50 4.50e-17
## k_Z1_Z2
                     -0.781
                                0.0649 -0.912 -0.650 -12.00 1.52e-14
## k_Z2_sink
                     -0.861
                                0.1060 - 1.070 - 0.647
                                                       -8.14 7.47e-10
##
                     Pr(>t)
## Z0_free_0
                   1.35e-35
## k_Z0_free_bound 2.44e-06
## k_Z0_bound_free 2.35e-03
## k_ZO_free_Z1
                   2.25e-17
                   7.61e-15
## k_Z1_Z2
## k_Z2_sink
                   3.73e-10
##
## Backtransformed parameters:
##
                   Estimate
                               Lower
                                        Upper
## Z0_free_0
                   97.40000 9.32e+01 102.000
## k_Z0_free_bound 0.11700 5.15e-02
                                        0.264
## k_Z0_bound_free 0.00792 3.04e-04
                                        0.207
## k_Z0_free_Z1
                    2.33000 2.07e+00
                                        2.620
## k_Z1_Z2
                    0.45800 4.02e-01
                                        0.522
## k_Z2_sink
                    0.42300 3.41e-01
                                        0.524
##
## Residual standard error: 4.08 on 38 degrees of freedom
##
## Chi2 error levels in percent:
            err.min n.optim df
## All data
               17.3
                          6 36
               14.7
## Z0
                          4 13
## Z1
               14.4
                          1 12
## Z2
               20.3
                          1 11
```

```
##
## Estimated disappearance times:
##
       DT50 DT90
## Z0 0.304 1.18
## Z1 1.514 5.03
## Z2 1.639 5.44
##
## Estimated formation fractions:
                ff
## Z0_free_sink
                  1
## Z0_free_Z1
                  1
## Z1_sink
                  1
## Z1_Z2
                  1
## Z2_sink
                  1
##
## Estimated Eigenvalues of SFORB model(s):
##
     Z0_b1
             Z0_b2
## 2.44664 0.00754
## Parameter correlation:
##
                    Z0_free_0 k_Z0_free_bound k_Z0_bound_free k_Z0_free_Z1
## Z0_free_0
                       1.0000
                                         0.075
                                                         0.0708
                                                                       0.0908
## k_Z0_free_bound
                                         1.000
                                                         0.5425
                       0.0750
                                                                       0.4245
## k_Z0_bound_free
                                         0.543
                       0.0708
                                                         1.0000
                                                                       0.1632
## k_Z0_free_Z1
                       0.0908
                                         0.425
                                                         0.1632
                                                                      1.0000
## k_Z1_Z2
                       0.2572
                                        -0.228
                                                        -0.0863
                                                                      -0.1008
## k_Z2_sink
                       0.2888
                                        -0.211
                                                        -0.0792
                                                                      -0.0490
##
                   k_Z1_Z2 k_Z2_sink
## Z0_free_0
                     0.2572
                               0.2888
## k_Z0_free_bound -0.2276
                              -0.2105
## k_Z0_bound_free -0.0863
                              -0.0792
## k_Z0_free_Z1
                    -0.1008
                              -0.0490
## k_Z1_Z2
                     1.0000
                               0.2728
## k_Z2_sink
                     0.2728
                               1.0000
```

This results in a much better representation of the behaviour of the parent compound Z0.

Finally, Z3 is added as well. These models appear overparameterised (no covariance matrix returned) if the sink for Z1 is left in the models.



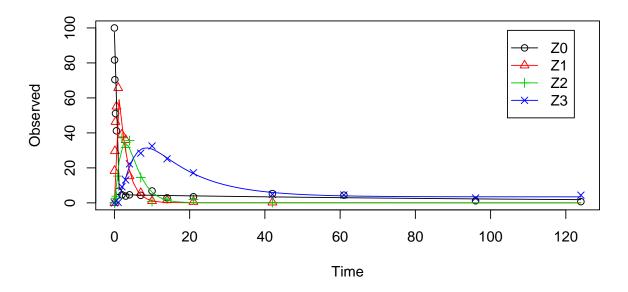
```
summary(m.Z.mkin.4, data = FALSE)
## mkin version:
                    0.9.27
## R version:
                    3.1.0
## Date of fit:
                    Thu May 8 20:33:46 2014
## Date of summary: Thu May 8 20:33:46 2014
##
## Equations:
## [1] d_ZO_free = - 0 - k_ZO_free_bound * ZO_free + k_ZO_bound_free * ZO_bound - k_Z
## [2] d_Z0_bound = + k_Z0_free_bound * Z0_free - k_Z0_bound_free * Z0_bound
## [3] d_Z1 = + k_Z0_free_Z1 * Z0_free - 0 - k_Z1_Z2 * Z1
## [4] d_Z2 = + k_Z1_Z2 * Z1 - k_Z2_sink * Z2 - k_Z2_Z3 * Z2
## [5] d_Z3 = + k_Z2_Z3 * Z2 - k_Z3_sink * Z3
## Method used for solution of differential equation system:
## eigen
##
## Weighting: none
```

```
##
## Starting values for optimised parameters:
##
                      value
                               type transformed
## Z0_free_0
                   100.0000
                             state
                                        100.000
## k_Z1_Z2
                     0.0500 deparm
                                         -2.996
## k_ZO_free_bound
                     0.1000 deparm
                                         -2.303
## k_Z0_bound_free
                     0.0200 deparm
                                         -3.912
## k_Z0_free_Z1
                     0.1002 deparm
                                         -2.301
## k_Z2_sink
                     0.1003 deparm
                                         -2.300
## k_Z2_Z3
                     0.1004 deparm
                                         -2.299
## k_Z3_sink
                     0.1005 deparm
                                         -2.298
##
## Fixed parameter values:
              value type
## Z0_bound_0
                  0 state
## Z1_0
                  0 state
## Z2_0
                  0 state
## Z3_0
                  0 state
##
## Optimised, transformed parameters:
##
                   Estimate Std. Error Lower
                                                 Upper t value Pr(>|t|)
## Z0_free_0
                     97.500
                                 1.8900 93.700 101.000
                                                         51.70 2.07e-44
## k_Z1_Z2
                     -0.777
                                 0.0583 -0.894
                                               -0.660
                                                        -13.30 6.66e-18
## k_Z0_free_bound
                     -2.140
                                 0.3680 - 2.880
                                               -1.400
                                                         -5.80 4.71e-07
## k_Z0_bound_free
                     -4.760
                                 1.4200 - 7.610
                                               -1.920
                                                         -3.36 1.52e-03
                      0.847
## k_Z0_free_Z1
                                 0.0534 0.740
                                                 0.954
                                                         15.90 6.13e-21
## k_Z2_sink
                                 0.1830 -1.930 -1.190
                     -1.560
                                                         -8.55 2.79e-11
                                 0.1140 -1.760 -1.300
## k_Z2_Z3
                     -1.530
                                                        -13.50 4.49e-18
## k_Z3_sink
                                 0.2250 -3.220 -2.320 -12.30 1.25e-16
                     -2.770
##
                     Pr(>t)
## Z0_free_0
                   1.03e-44
## k_Z1_Z2
                   3.33e-18
## k_Z0_free_bound 2.36e-07
## k_Z0_bound_free 7.58e-04
## k_Z0_free_Z1
                   3.06e-21
## k_Z2_sink
                   1.40e-11
## k_Z2_Z3
                   2.24e-18
## k_Z3_sink
                   6.23e-17
##
## Backtransformed parameters:
##
                   Estimate
                                Lower
                                         Upper
## Z0_free_0
                   97.50000 9.37e+01 101.0000
```

```
## k_Z1_Z2 0.46000 4.09e-01 0.5170
## k_Z0_free_bound 0.11800 5.64e-02 0.2480
## k_Z0_bound_free 0.00852 4.93e-04 0.1470
## k_Z0_free_Z1 2.33000 2.10e+00 2.6000
## k_Z2_sink
                   0.21000 1.45e-01 0.3030
## k_Z2_Z3
                   0.21700 1.73e-01 0.2730
## k_Z3_sink
                   0.06270 3.99e-02
                                     0.0985
## Residual standard error: 3.74 on 49 degrees of freedom
##
## Chi2 error levels in percent:
          err.min n.optim df
## All data 17.5
                       8 46
## Z0
              14.7
                        4 13
                        1 12
## Z1
             14.4
## Z2
              21.0
                         2 10
## Z3
              11.8
                        1 11
##
## Estimated disappearance times:
      DT50 DT90
## Z0 0.304 1.19
## Z1 1.507 5.01
## Z2 1.623 5.39
## Z3 11.051 36.71
## Estimated formation fractions:
##
## Z0_free_sink 1.000
## Z0_free_Z1 1.000
## Z1_sink
              1.000
## Z1_Z2
               1.000
## Z2_sink
              0.492
## Z2_Z3
               0.508
## Z3_sink
               1.000
##
## Estimated Eigenvalues of SFORB model(s):
## Z0_b1 Z0_b2
## 2.45127 0.00811
## Parameter correlation:
##
                  Z0_free_0 k_Z1_Z2 k_Z0_free_bound k_Z0_bound_free
## Z0_free_0
                     1.0000 0.2424
                                            0.0782
                                                           0.0692
```

```
## k_Z1_Z2
                       0.2424 1.0000
                                               -0.2274
                                                                -0.0894
## k_Z0_free_bound
                       0.0782 - 0.2274
                                                1.0000
                                                                 0.5398
## k_Z0_bound_free
                       0.0692 - 0.0894
                                                0.5398
                                                                 1.0000
## k_Z0_free_Z1
                       0.0888 - 0.1084
                                                                 0.1628
                                                0.4276
## k_Z2_sink
                       0.3299 0.3405
                                                -0.2633
                                                                 -0.1275
## k_Z2_Z3
                      -0.0749 -0.1489
                                                0.0670
                                                                 0.0608
                      -0.1046 -0.2249
## k_Z3_sink
                                                0.1384
                                                                 0.1252
##
                    k_Z0_free_Z1 k_Z2_sink k_Z2_Z3 k_Z3_sink
## Z0_free_0
                          0.0888
                                     0.3299 - 0.0749
                                                       -0.1046
## k_Z1_Z2
                         -0.1084
                                     0.3405 - 0.1489
                                                       -0.2249
## k_Z0_free_bound
                                    -0.2633 0.0670
                          0.4276
                                                        0.1384
## k_Z0_bound_free
                          0.1628
                                   -0.1275 0.0608
                                                        0.1252
## k_Z0_free_Z1
                          1.0000
                                    -0.0531 -0.0128
                                                        0.0186
## k_Z2_sink
                         -0.0531
                                     1.0000 - 0.2547
                                                       -0.6832
## k_Z2_Z3
                         -0.0128
                                    -0.2547
                                             1.0000
                                                        0.5639
## k_Z3_sink
                          0.0186
                                    -0.6832
                                             0.5639
                                                        1.0000
```

The error level of the fit, but especially of metabolite Z3, can be improved if the SFORB model is chosen for this metabolite, as this model is capable of representing the tailing of the metabolite decline phase.



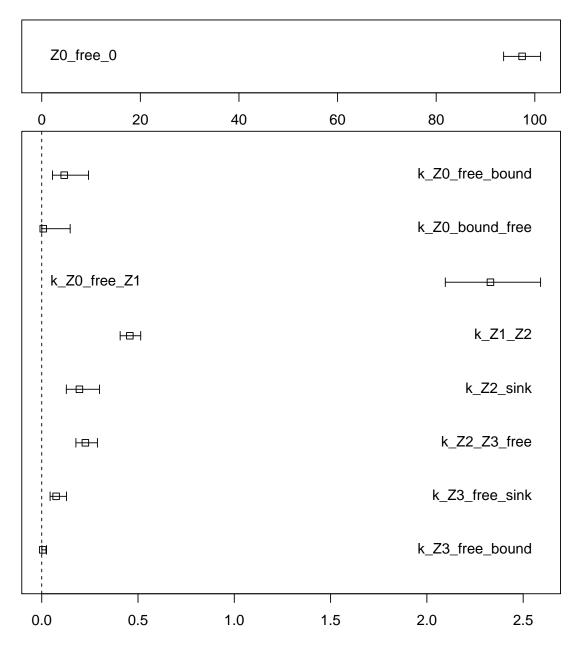
```
summary(m.Z.mkin.5, data = FALSE)$bpar
##
                     Estimate Lower Upper
## Z0_free_0
                    9.742e+01
                                  NA
                                        NA
## k_Z0_free_bound 1.168e-01
                                  NA
                                        NA
## k_Z0_bound_free 7.890e-03
                                  NA
                                        NA
## k_Z0_free_Z1
                    2.330e+00
                                  NA
                                        NA
## k_Z1_Z2
                    4.576e-01
                                  NA
                                        NA
## k_Z2_sink
                    1.957e-01
                                  NA
                                        NA
## k_Z2_Z3_free
                    2.266e-01
                                  NA
                                        NA
## k_Z3_free_sink
                    7.479e-02
                                  NA
                                        NA
## k_Z3_free_bound 5.218e-03
                                  NA
                                        NA
## k_Z3_bound_free 5.013e-22
                                  NA
                                        NA
```

The summary view of the backtransformed parameters shows that we get no confidence intervals due to overparameterisation. As the optimized k_Z3_bound_free is excessively small, it is reasonable to fix it to zero.

```
##
                    Estimate Lower
                                           Upper
## Z0_free_0
                   97.424939 9.368e+01 101.17374
## k_Z0_free_bound 0.116755 5.608e-02
                                         0.24306
## k_Z0_bound_free 0.007889 4.213e-04
                                         0.14772
## k_ZO_free_Z1
                    2.329999 2.096e+00
                                         2.59050
## k_Z1_Z2
                    0.457590 4.074e-01
                                         0.51402
## k_Z2_sink
                    0.195710 1.277e-01
                                         0.29984
                    0.226585 1.775e-01
## k_Z2_Z3_free
                                         0.28920
## k_Z3_free_sink
                    0.074789 4.354e-02
                                         0.12848
## k_Z3_free_bound 0.005218 1.093e-03
                                         0.02492
```

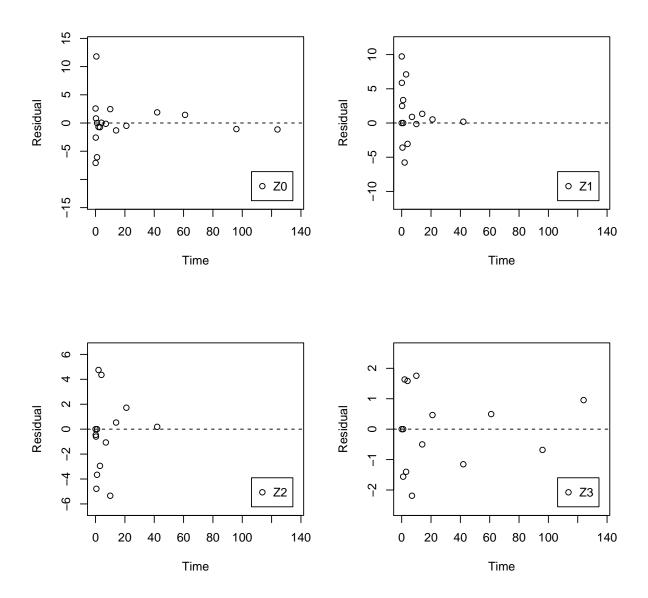
A graphical representation of the confidence intervals can finally be obtained.

```
mkinparplot(m.Z.mkin.5a)
```



It is clear that nothing can be said about the degradation rate of Z3 towards the end of the experiment. However, this appears to be a feature of the data.

```
par(mfrow = c(2, 2))
mkinresplot(m.Z.mkin.5, "Z0", lpos = "bottomright")
mkinresplot(m.Z.mkin.5, "Z1", lpos = "bottomright")
mkinresplot(m.Z.mkin.5, "Z2", lpos = "bottomright")
mkinresplot(m.Z.mkin.5, "Z3", lpos = "bottomright")
```



As expected, the residual plots are much more random than in the case of the all SFO model for which they were shown above. In conclusion, the model Z.mkin.5 is proposed as the best-fit model for the dataset from Appendix 7 of the FOCUS report.

References

FOCUS Work Group on Degradation Kinetics. Generic guidance for estimating persistence and degradation kinetics from environmental fate studies on pesticides in EU registration, 1.0 edition, November 2011. URL http://focus.jrc.ec.europa.eu/dk.