Spectral clustering

Reading https://people.csail.mit.edu/dsontag/courses/ml14/notes/Luxburg07_tutorial_spectral_clustering.pdf

Spectral clustering

Steps

- Preprocess the data
- Find the graph Laplacian vector of the matrix
- Use K-means on eigenvectors of the graph Laplacian to cluster

First, compute AX for

$$X = \begin{bmatrix} -5 \\ -4 \\ 3 \end{bmatrix}$$

This product is given by

$$AX = \begin{bmatrix} 0 & 5 & -10 \\ 0 & 22 & 16 \\ 0 & -9 & -2 \end{bmatrix} \begin{bmatrix} -5 \\ -4 \\ 3 \end{bmatrix} = \begin{bmatrix} -50 \\ -40 \\ 30 \end{bmatrix} = 10 \begin{bmatrix} -5 \\ -4 \\ 3 \end{bmatrix}$$

In this case, the product AX resulted in a vector which is equal to 10 times the vector X. In other words, $AX = 10X$.

Perhaps this is a special matrix A which when multiplied by any vector $\mathbf{x}$ always equals $k\mathbf{x}$?

https://math.libretexts.org/Bookshelves/Linear_Algebra/A_First_Course_in_Linear_Algebra_(Kuttler)/07:_Spectral_Theory/7.01:_Eigenvalues_and_Eigenvectors_of_a_Matrix

$$\begin{bmatrix} 0 & 5 & -10 \\ 0 & 22 & 16 \\ 0 & -9 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -5 \\ 38 \\ -11 \end{bmatrix}$$

In this case, AX did not result in a vector of the form kX for some scalar k.

NOPE!

https://math.libretexts.org/Bookshelves/Linear_Algebra/A_First_Course_in_Linear_Algebra_(Kuttler)/07:_Spectral_Theory/7.01:_Eigenvalues_and_Eigenvectors_of_a_Matrix

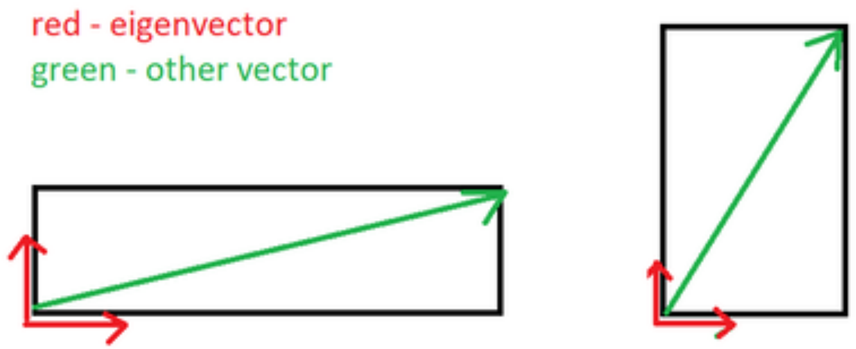
Eigenvectors and Eigenvalues

When $A \in \mathbb{R}^{n \times n}$ is positive semidefinite then a vector $\mathbf{v}$ is an eigenvector and has associated eigenvalue λ iff

$$(A - \lambda \mathrm{I})\mathbf{v} = 0$$

$$A\mathbf{v} = \lambda \mathbf{v}$$

That is eigenvectors do not change direction, they only scale linearly when A is subject to a linear transformation.



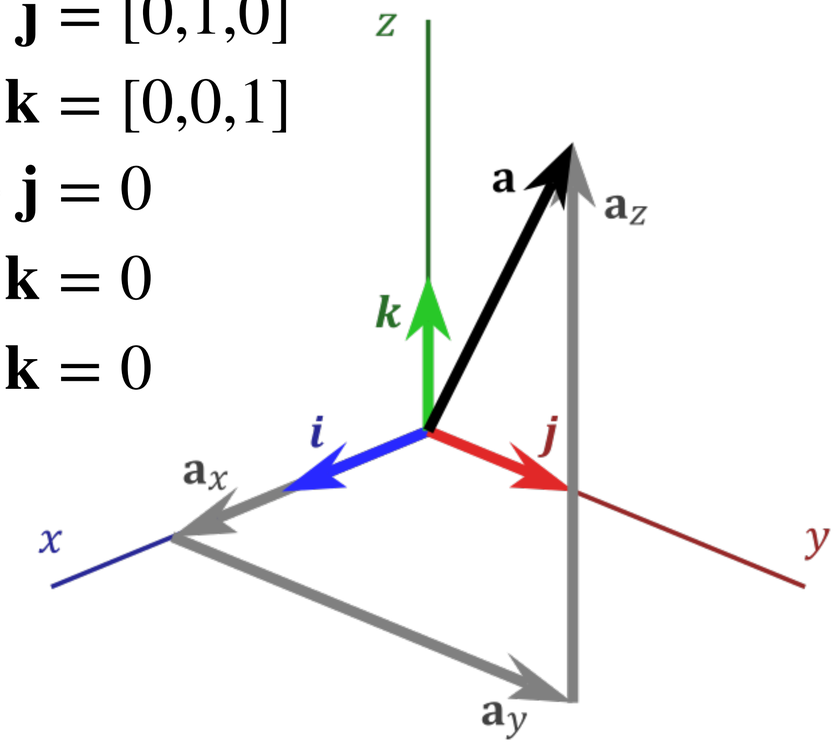
Eigenvectors and Eigenvalues

If $A \in \mathbb{R}^{n \times n}$ is symmetric then there exists an orthogonal set of eigenvectors.

Define $U = [\mathbf{v_1}, \mathbf{v_2} \ldots \mathbf{v_n}]$, a square matrix whose columns are the n linearly independent eigenvectors of $\mathbf{A}$. Also define the vector of matching eigenvalues $\sigma(A) = [\lambda_1, \lambda_2 \ldots \lambda_n]$; this vector is known as the spectrum of A. Lastly define Λ, the diagonalization of the spectrum $\Lambda = \mathrm{I}\sigma(A)$

It can be shown that $U^{-1}AU = \Lambda$

$$\mathbf{i} = [1,0,0]$$
$$\mathbf{j} = [0,1,0]$$
$$\mathbf{k} = [0,0,1]$$
$$\mathbf{i} \cdot \mathbf{j} = 0$$
$$\mathbf{j} \cdot \mathbf{k} = 0$$
$$\mathbf{i} \cdot \mathbf{k} = 0$$



Eigenvectors and Eigenvalues

Can be generalized to $A \in \mathbb{R}^{n \times m}$ if A is invertible (full rank/positive definite) through Singular Value Decomposition

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Let A be an $m \times n$ matrix. Then there exist orthogonal matrices U and V of the appropriate size such that $A = U\Sigma V^T$ where Σ is of the form

$$\Sigma = \begin{bmatrix} \sigma & 0 \\ 0 & 0 \end{bmatrix}$$

and σ is of the form

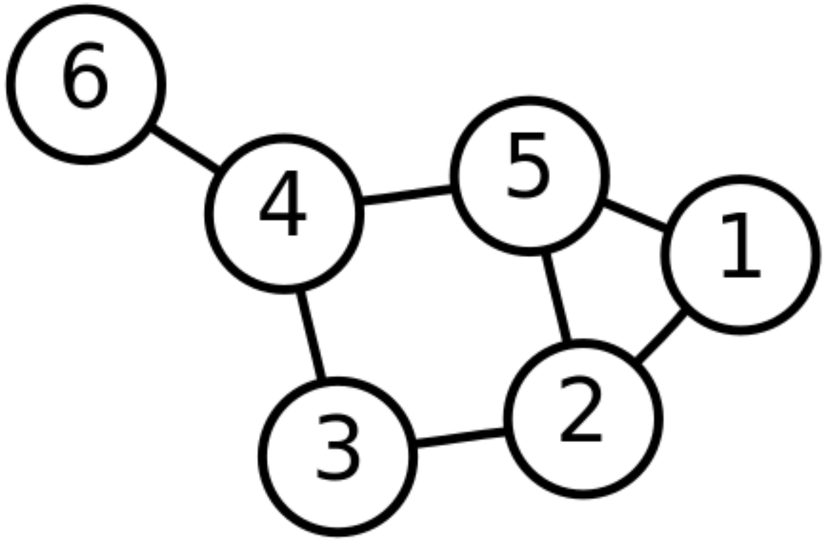
$$\sigma = \begin{bmatrix} \sigma_1 & & 0 \\ & \ddots & \\ 0 & & \sigma_k \end{bmatrix}$$

for the σ_i the singular values of A.

In one restricted but very common sense of the term,[1][2] a **graph** is an ordered pair $G = (V, E)$ comprising:

- V, a set of **vertices** (also called **nodes** or **points**);
- $E \subseteq \{\{x, y\} \mid x, y \in V \text{ and } x \neq y\}$, a set of **edges** (also called **links** or **lines**), which are unordered pairs of vertices (that is, an edge is associated with two distinct vertices).

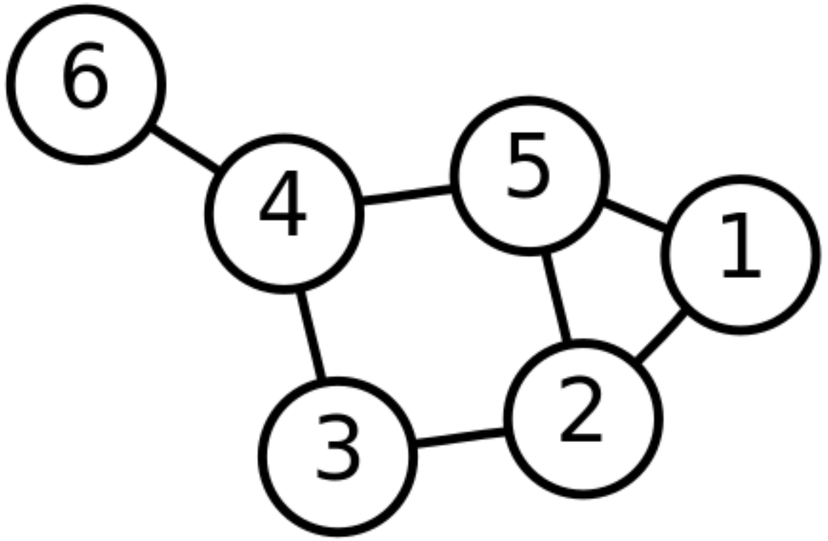
To avoid ambiguity, this type of object may be called precisely an **undirected simple graph**.



Similarity graph

There are many ways to make a graph from data

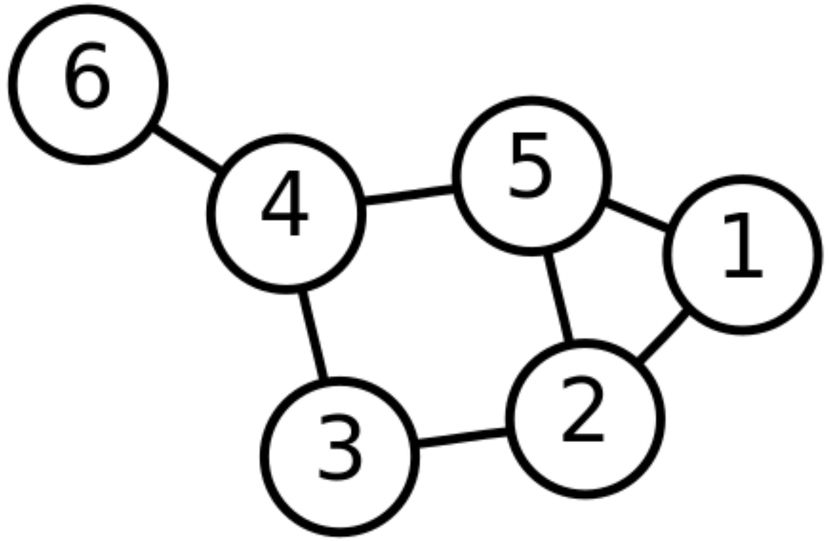
- Unweighted
  - $W_{i,j} = 1$ iff $d(x_i, x_j) < \epsilon \; \forall i, j \neq i \in G$; otherwise 0
  - $W_{i,j} = 1$ iff x_i is in the set of k nearest neighors of x_j; otherwise 0
- Weighted
  - $W_{i,j} = \exp(\frac{\|x_i - x_j\|^2}{2\sigma^2})$



Affinity matrix

Unweighted example

	1	2	3	4	5	6
1	0	1	0	0	1	0
2	1	0	1	0	1	0
3	0	1	0	1	0	0
4	0	0	1	0	1	1
5	1	1	0	1	0	0
6	0	0	0	1	0	0

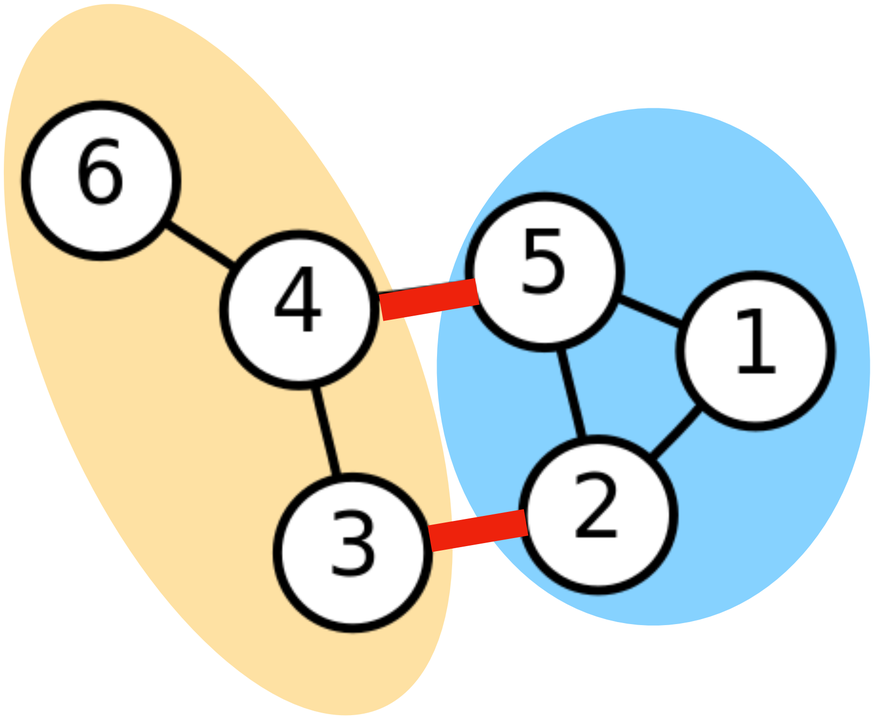


Clustering as a bi-partitioning task

Partition vertices into two disjoint groups A, B

How can we define a “good” partition?

How can we efficiently calculate such a partition?



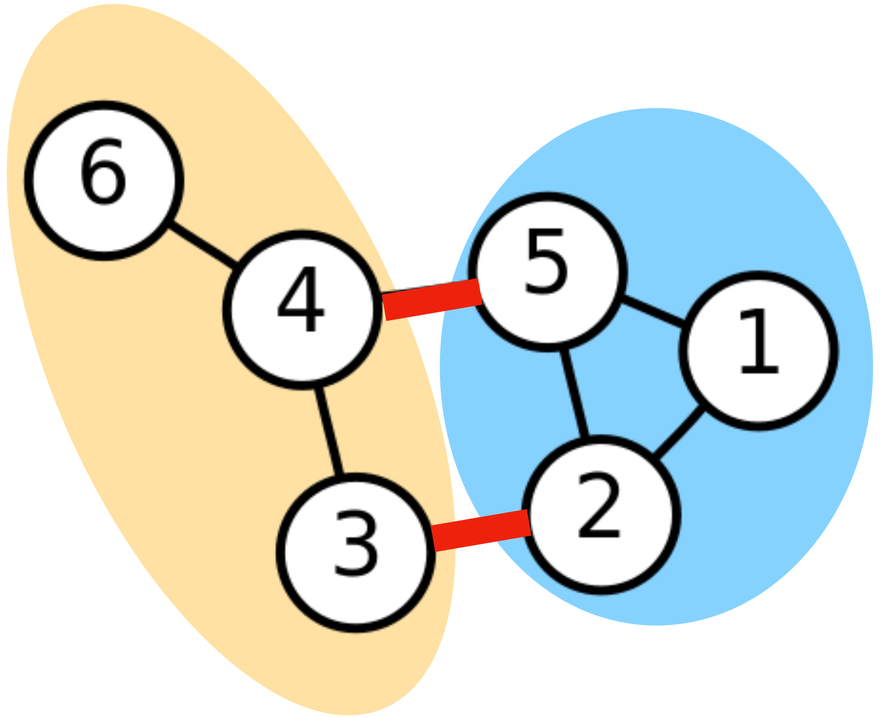
Clustering as a bi-partitioning task

Partition vertices into two disjoint groups A, B

$$\text{cut(A,B)} = \sum_{\forall i \in A, \forall j \in B} W_{i,j}$$

And just

$$\arg\min_{A,B} \text{cut(A,B)}?$$

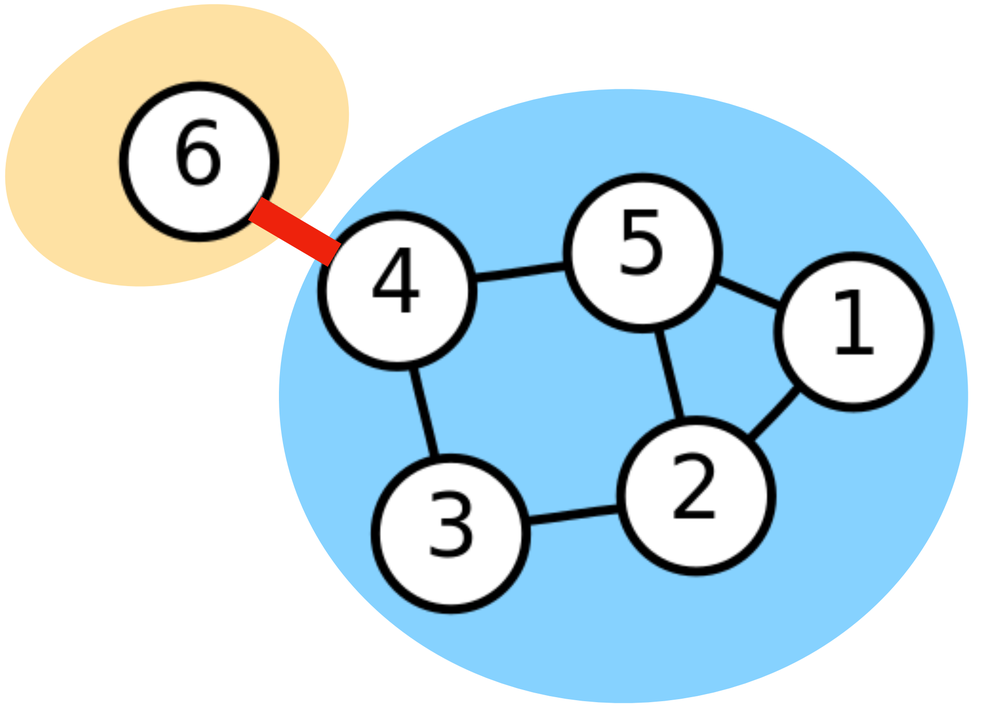


Clustering as a bi-partitioning task

Partition vertices into two disjoint groups A, B

$$\arg\min_{A,B} \text{cut}(A,B)$$

Degenerate case!



Clustering as a bi-partitioning task

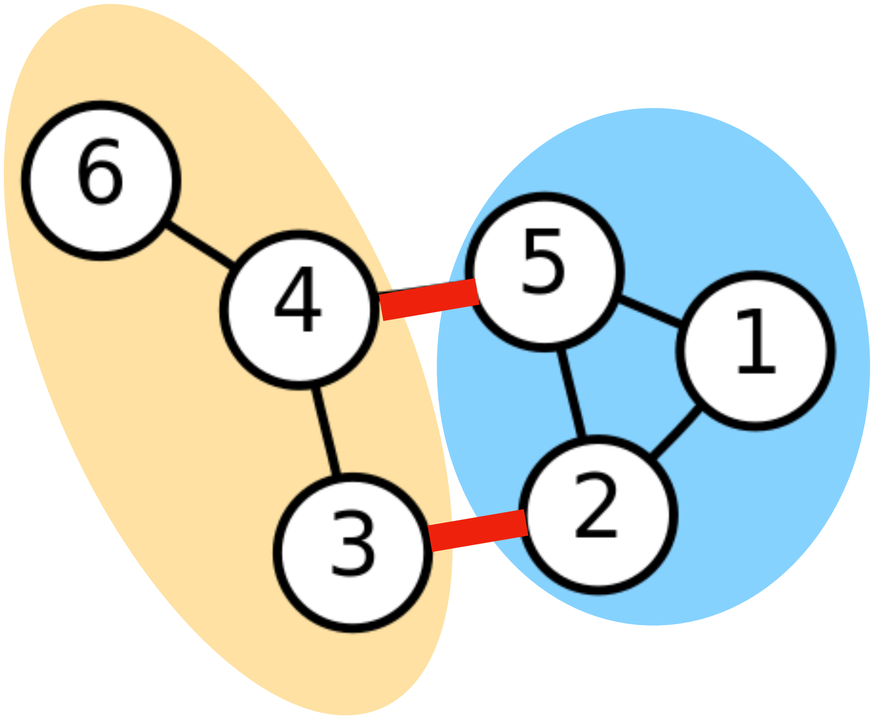
Partition vertices into two disjoint groups A, B

Normalized cut forces clusters to have larger size

$$\text{Ncut}(A,B) = \text{cut}(A,B)\left(\frac{1}{\text{Vol}(A)} + \frac{1}{\text{Vol}(B)}\right)$$

Where Vol(A) is the sum of the degrees of all of the nodes in A

Then we just $\arg\min_{A,B}$ Ncut(A,B)



Clustering as a bi-partitioning task

Partition vertices into two disjoint groups A, B

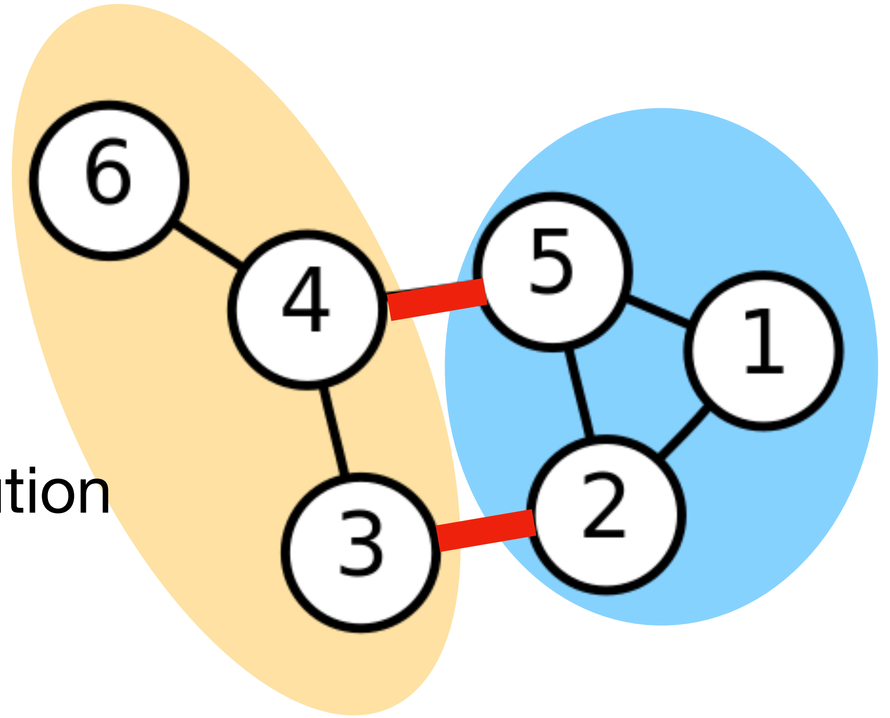
How can we define a “good” partition?

OK!

How can we efficiently calculate such a partition?

Not this way… NP-Hard… lets make a “relaxed” solution

Involving eigenvectors of the graph Laplacian matrix



Laplacian matrix [edit]

Given a simple graph G with n vertices $v_1, \ldots, v_n$, its Laplacian matrix $L_{n \times n}$ is defined element-wise as[1]

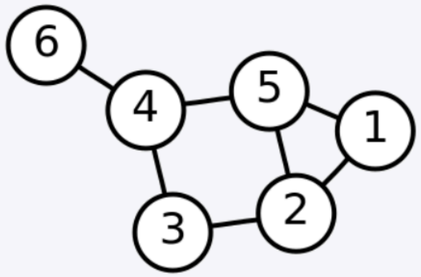
$$L_{i,j} := \begin{cases} \deg(v_i) & \text{if } i = j \\ -1 & \text{if } i \neq j \text{ and } v_i \text{ is adjacent to } v_j \\ 0 & \text{otherwise,} \end{cases}$$

or equivalently by the matrix

$$L = D - A,$$

where *D* is the degree matrix and *A* is the adjacency matrix of the graph. Since G is a simple graph, A only contains 1s or 0s and its diagonal elements are all 0s.

Here is a simple example of a labelled, undirected graph and its Laplacian matrix.

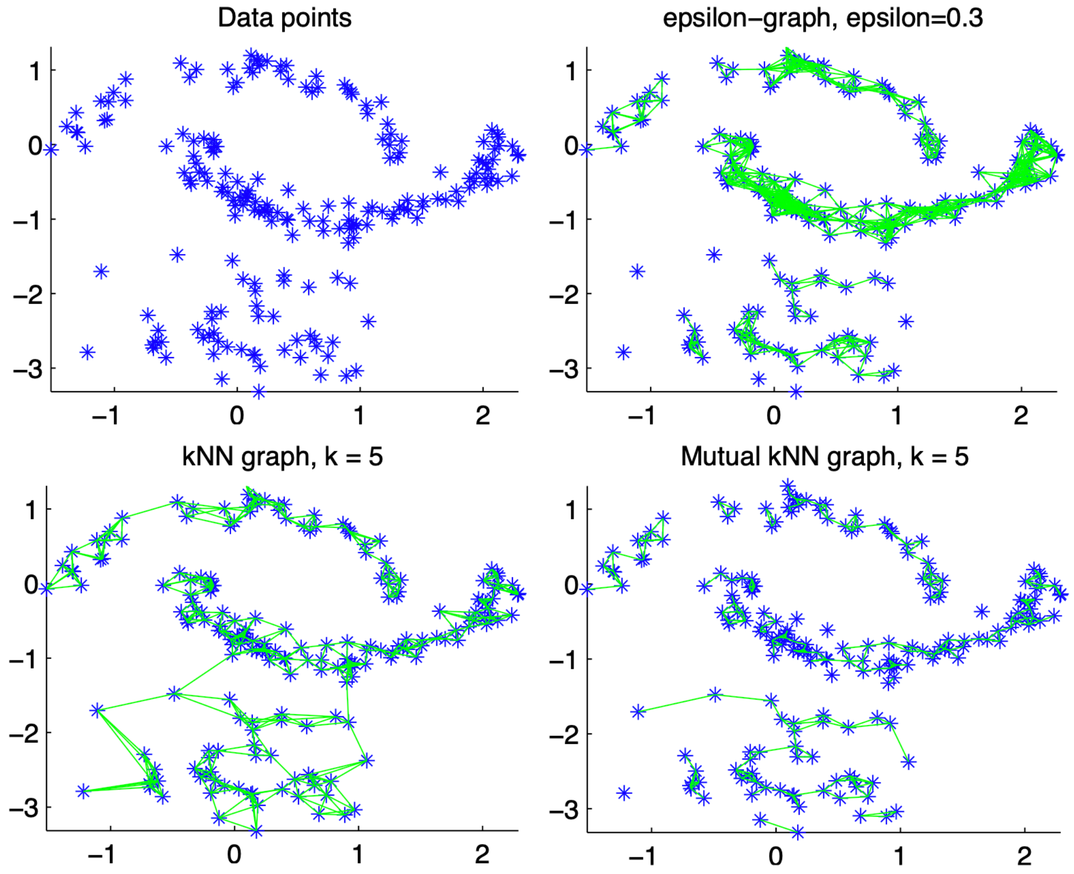
Labelled graph	Degree matrix	Adjacency matrix	Laplacian matrix
	$\begin{pmatrix} 2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$	$\begin{pmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{pmatrix}$	$\begin{pmatrix} 2 & -1 & 0 & 0 & -1 & 0 \\ -1 & 3 & -1 & 0 & -1 & 0 \\ 0 & -1 & 2 & -1 & 0 & 0 \\ 0 & 0 & -1 & 3 & -1 & -1 \\ -1 & -1 & 0 & -1 & 3 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{pmatrix}$

We observe for the undirected graph that both the adjacency matrix and the Laplacian matrix are symmetric, and that row- and column-sums of the Laplacian matrix are all zeros.

Lots of different similarity graphs and graph Laplacians!

$$L_{\mathrm{sym}} := D^{-1/2} L D^{-1/2} = I - D^{-1/2} W D^{-1/2}$$

$$L_{\mathrm{rw}} := D^{-1} L = I - D^{-1} W.$$



Normalized Cut and Graph Laplacian

$$\text{Ncut}(A, B) := \text{cut}(A, B)\left(\frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)}\right)$$

Let $f = [f_1\ f_2\ \ldots\ f_n]^T$ with $f_i = \begin{cases} \frac{1}{\text{vol}(A)} & \text{if } i \in A \\ -\frac{1}{\text{vol}(B)} & \text{if } i \in B \end{cases}$

$$\mathbf{f}^T\mathbf{L}\mathbf{f} = \sum_{ij} w_{ij}(\mathbf{f}_i - \mathbf{f}_j)^2 = \sum_{i\in A, j\in B} w_{ij}\left(\frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)}\right)^2$$

$$\mathbf{f}^T\mathbf{D}\mathbf{f} = \sum_j d_i\mathbf{f}_i^2 = \sum_{i\in A}\frac{d_i}{\text{vol}(A)^2} + \sum_{j\in B}\frac{d_i}{\text{vol}(B)^2} = \frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)}$$

$$\text{Ncut}(A, B) = \frac{\mathbf{f}^T\mathbf{L}\mathbf{f}}{\mathbf{f}^T\mathbf{D}\mathbf{f}}$$

Normalized Cut and Graph Laplacian

$$\min \text{Ncut}(A, B) = \min \frac{\mathbf{f}^T \mathbf{L}\mathbf{f}}{\mathbf{f}^T \mathbf{D}\mathbf{f}}$$

where $f = [f_1\ f_2\ \ldots\ f_n]^T$ with $f_i = \begin{cases} \frac{1}{\text{vol}(A)} & \text{if } i \in A \\ -\frac{1}{\text{vol}(B)} & \text{if } i \in B \end{cases}$

Relaxation: $\min \frac{\mathbf{f}^T \mathbf{L}\mathbf{f}}{\mathbf{f}^T \mathbf{D}\mathbf{f}}$ s.t. $f^T D1 = 0$

Solution: f – second eigenvector of generalized eval problem

$$\mathbf{L}\mathbf{f} = \lambda \mathbf{D}\mathbf{f}$$

Obtain cluster assignments by thresholding f at 0

Approximation of Normalized cut

$$\text{Ncut}(A, B) := \text{cut}(A, B)\left(\frac{1}{\text{vol}(A)} + \frac{1}{\text{vol}(B)}\right)$$

Let *f* be the eigenvector corresponding to the second smallest eval of the generalized eval problem.

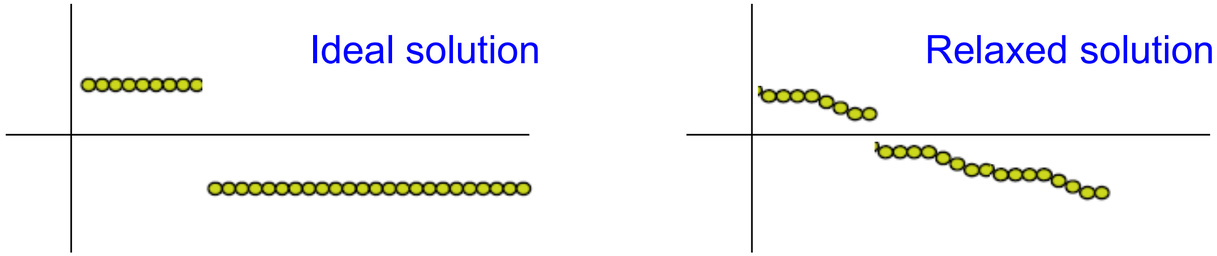
$$\mathbf{Lf} = \lambda \mathbf{Df}$$

Equivalent to eigenvector corresponding to the second smallest eval of the normalized Laplacian $L' = D^{-1}L = I - D^{-1}W$

Recover binary partition as follows:

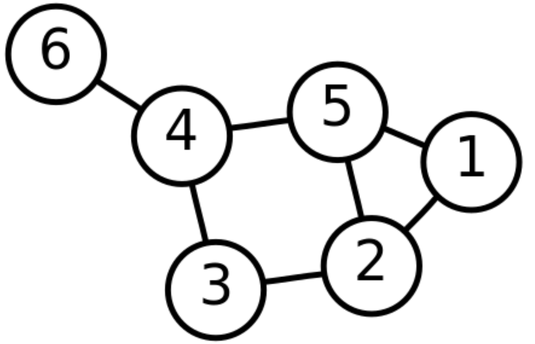
$i \in A$ *if* $f_i \geq 0$

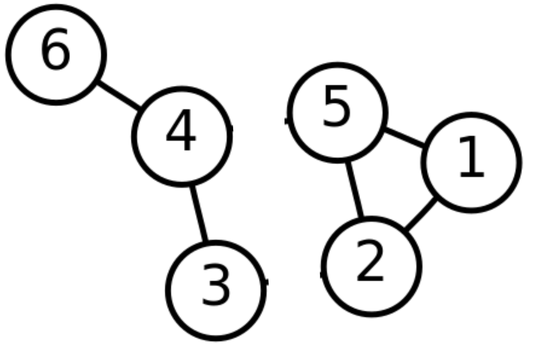
$i \in B$ *if* $f_i < 0$



How do points cluster?

- Single connected component in graph
  - Binary: sign of 2nd smallest eigenvector (Fiedler eigenvector
  - Multi: k-Means on 2nd through k+1 eigenvectors
- Multiple connected components in graph (well-separated clusters)
  - Multiplicity of components = multiplicity of 0 eigenvalues and each such eigenvector is a cluster





Spectral clustering

Steps

- Preprocess the data
  - Create a matrix describing connectivity between datapoints (e.g. kNN) or similarity between datapoints (Gaussian kernel)
- Find the graph Laplacian vector of the matrix
  - Several different Laplacians! Each have different properties! Not just one spectral clustering
- Use K-means on evecs/evals of the graph Laplacian to cluster
  - Multiplicity of 0 eigenvalues are the number of connected components in the graph. So if there's no overlap between clusters)… then these smaller evecs assign datapoints to clusters
  - Other options
    - If binary clustering: the 1st (smallest eigenvalue) eigenvector is al 1s, then the sign of the 2nd eigenvector (so-called Fiedler eigenvector) components are the cluster assignments
    - If k clusters: take eigenvectors 2 through k+1 as indicator variables