

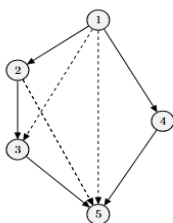
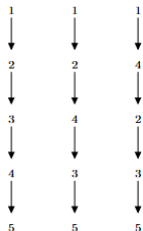
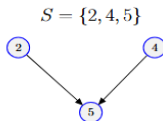
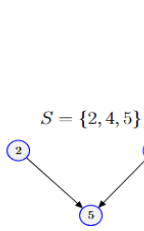
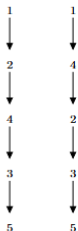
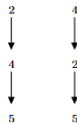
Bayesian Inference for Partial Orders from Rank-Order Data (part II)

PrefStat: Preference Statistics summer school
30 June - 4 July, 2025 (University of Oslo)

- Revision
- Bayesian inference framework
- R-simulation
- Other PO work
- Summary

Queues and partial orders (PO)

Queue of M actors $[M] = \{1, \dots, M\}$ constrained by PO $h \in \mathcal{H}_{[M]}$.
 $S \subseteq [M]$ be a suborder with the size of $m = |S|$.

Partial order h Linear extensions $\mathcal{L}(h)$ Sub-order $h[S]$  $\mathcal{L}(h[S])$

A random queue $y_{1:m} = (y_1, \dots, y_m)$ occurs at random

$$p(y_{1:m}|h) = \frac{1}{|\mathcal{L}(h[y_{1:m}])|} \mathbb{1}_{y_{1:m} \in \mathcal{L}(h[y_{1:m}])}$$

Noise free likelihood

If just $S \subseteq [M]$ are queuing, then the constraining suborder is $h[S]$.
A random queue $y_{1:m}$ respecting $h[S]$ is

$$p(y_{1:m}|h) = \frac{1}{|\mathcal{L}(h[y_{1:m}])|} \mathbb{1}_{y_{1:m} \in \mathcal{L}(h[y_{1:m}])} = \prod_{i=1}^{m-1} \frac{|\mathcal{L}_{y_i}[h[y_{i:m}]]|}{|\mathcal{L}[h[y_{i:m}]]|}$$

where

$\mathcal{L}[h[y_{i:m}]]$ is a list of linear extensions of $[y_{i:m}]$

$\mathcal{L}_{y_i}[h[y_{i:m}]]$ is a list of linear extensions of $[y_{i:m}]$ starting with y_i .

This is the noise-free likelihood. With a prior $\pi(h)$, the posterior density for h is

$$\pi(h|y_{1:m}) \propto \pi(h)p(y_{1:m}|h).$$

Noisy lists & likelihood

Queue jumping (QJ) noise: With the noise probability p , the next one is selected at random.

$$p^{(D)}(y_{1:m}|h, p) = \prod_{i=1}^{m-1} \frac{p}{m-i+1} + (1-p) \frac{|\mathcal{L}_{y_i}[h[y_{i:m}]]|}{|\mathcal{L}[h[y_{i:m}]]|}$$

Y_i observed on corresponding subsets $S_i \subseteq [M]$ for $i = 1, \dots, N$.
With a prior $\pi(h)$ and $\pi(p)$, the **posterior** distribution is

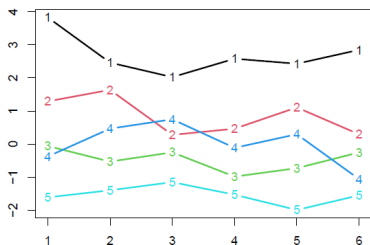
$$\pi(h, p|Y_1, \dots, Y_N) \propto \pi(h) \pi(p) \prod_{i=1}^N p^{(D)}(Y_i|h[S_i], p).$$

Latent variable $U_{[1]}$

K -dimensional latent variable $U_{j,:} \in \mathbb{R}^K$ for each object $j \in [M]$ defines order relations \succ_U .

$$j_1 \succ_U j_2 \Leftrightarrow j_1 \succ_k j_2, \forall k = 1, \dots, K.$$

This is called an intersection order $h(U) = \bigcap_{k=1}^K h(U_{:,k})$ as $h(U)$ contains just the order relations shared by all $h(U_{:,k})$, $k = 1, \dots, K$.



Deeper order with higher ρ & Lower order with lower ρ .
Dimension of PO, K is at least $M/2$.

Latent variable η [1]

With d -dimensional covariates X and their effects β ,

$$\eta = X\beta + U.$$

K -dimensional latent variable $\eta \in \mathbb{R}^K$ for each object $j \in [M]$ defines order relations \succ_η .

$$j_1 \succ_\eta j_2 \Leftrightarrow j_1 \succ_k j_2, \forall k = 1, \dots, K.$$

This is called an intersection order $h(\eta) = \bigcap_{k=1}^K h(\eta_{:,k})$ as $h(\eta)$ contains just the order relations shared by all $h(\eta_{:,k})$, $k = 1, \dots, K$.

$$U_{j,:} \sim N([0, \dots, 0], \Sigma_\rho) \text{ independent for each } j \in M$$

Alternatively, each $\eta_{:,k} \sim PL(\alpha_M + X\beta)$ if $U_{j,:} \sim \text{Gumbel}(\alpha_M)$.
In this tutorial, for simplicity, $\eta = U$.

In this tutorial, we will consider the two models.

1. PO with a fixed K

$$\pi(U, p, \rho | Y_1, \dots, Y_N) \propto \pi(\rho) \pi(p) \pi(U | \rho) L(h(U); Y_1, \dots, Y_N).$$

2. PO with a variable K

$$\pi(U, p, \rho, K | Y_1, \dots, Y_N) \propto \pi(\rho) \pi(p) \pi(U | \rho, K) \pi(K) L(h(U); Y_1, \dots, Y_N).$$

where $L(h(U); Y_1, \dots, Y_N) = \prod_{i=1}^N p^{(D)}(Y_i | h[S_i], p).$

Bayesian inference for h (fixed K)

Latent variable $U_{j,:} \sim N([0, \dots, 0], \Sigma_\rho)$ where $\text{Diag}(\Sigma_\rho) = 1$ and off-diagonals are ρ .

The random PO $h(U)$ has prior distribution

$$\pi(h|\rho) = \int \mathbb{1}_{h(U)=h} \pi(U|\rho) dU$$

where $\pi(U|\rho) = \prod_{j=1}^M N(U_{j,:}; [0, \dots, 0], \Sigma_\rho)$.

With priors $\pi(\rho)$, $\pi(U|\rho)$, $\pi(p)$, the joint posterior with latent variable U , is

$$\pi(U, p, \rho | Y_1, \dots, Y_N) \propto \pi(p) \pi(\rho) \pi(U|\rho) \prod_{i=1}^N p^{(D)}(Y_i | h(U), p).$$

Bayesian inference for h (fixed K)

The joint posterior is

$$\pi(U, p, \rho | Y_1, \dots, Y_N) \propto \pi(p)\pi(\rho)\pi(U|\rho) \prod_{i=1}^N p^{(D)}(Y_i | h(U), p).$$

The posterior simulation using the MCMC method is a natural approach.

The likelihood $p^{(D)}(Y_i | h(U), p)$ is a discrete problem and no derivatives with respect to parameters are available. No benefit from the gradient-based sampler.

The Metropolis-Hastings algorithm was used to simulate the conditional posterior.

Bayesian inference for h (variable K)

If K changes, the dimension of U changes. With a prior for K , $\pi(K)$ and $\pi(U|\rho, K)$, the conditional posterior is

$$\pi(K, U|\rho, \rho, Y_1, \dots, Y_N) \propto \pi(K)\pi(U|\rho, K) \prod_{i=1}^N p^{(D)}(Y_i, h(U), \rho).$$

The reversible-jump MCMC method is implemented. Jacobian = 1.

- If K is too small, deeper orders are likely to be generated.
e.g., $K = 1$ means the total order.
- If K is too large, shallow orders are likely to be generated.
e.g., $K = \infty$ means no order.

K and ρ trade-off if K is large enough. (see page 6)

Output summary

We have the posterior samples.

p Noise probability

ρ Order strictness; $\rho = 0$ means no order and $\rho = 1$ means the total order.

U Latent variables; $M \times K$ -matrix.

$h(U)$ PO; $M \times M$ -binary matrix

K PO dimension parameter

K posterior mean is not necessarily the true dimension of PO. However, it will put ≈ 0 mass for K less than the true PO dimension.

Output summary

From T -iterations, we get $(U^{(1)}, \dots, U^{(T)}), (\rho^{(1)}, \dots, \rho^{(T)}), (p^{(1)}, \dots, p^{(T)})$.

The posterior samples for PO, $(h^{(1)}, \dots, h^{(T)})$ is obtained.

The PO h is a $M \times M$ matrix; $h_{j_{w1}, j_{w2}} = 1$ if $j_{w1} \succ_h j_{w2}$ and otherwise $h_{j_{w1}, j_{w2}} = 0$.

For example,

$$h = \begin{bmatrix} 0 & 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$h_{j_{w1}, j_{w2}}$ is a probability for $j_{w1} \succ_h j_{w2}$.

Output summary

Evidence of order relationships

- The posterior mean probability for the order relationship $j_{w1} > j_{w2}$ is

$$\bar{h}_{j_{w1}, j_{w2}} = \frac{1}{T} \sum_t h_{j_{w1}, j_{w2}}^{(t)} \approx \mathbb{E}[h_{w1, w2} | Y_1, \dots, Y_N]$$

i.e., $\bar{h}_{j_{w1}, j_{w2}} \approx 1$ means strong evidence for $j_{w1} > j_{w2}$.

- Extension to the order relationship of $S \subseteq M$. For example, evidence for $j_{w1} > j_{w2} > j_{w3}$ is estimated as $\bar{h} = \frac{1}{T} \sum_t \mathbb{1}(h_{j_{w1}, j_{w2}}^{(t)} = h_{j_{w2}, j_{w3}}^{(t)} = 1)$.
- Credible intervals of order relationships can be computed.
- Consensus PO shows the order relationships with significant evidence. i.e., posterior probabilities over the threshold (0.5 or 0.9).

Output summary

Summary of other parameters

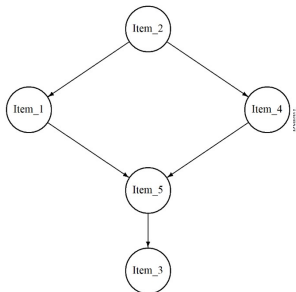
Posterior samples for ρ , p (and K) are summarized as usual.

Diagnostics

Once the MC is simulated, the rate of acceptance, trace plot or some diagnostics.

R-code

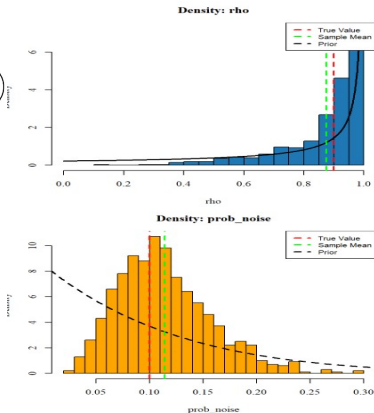
Let's implement the synthetic data and simulate MCMC ¹



$$p \sim \text{Beta}(1, 9),$$

$$\rho \sim \text{Beta}(1, 1/6)$$

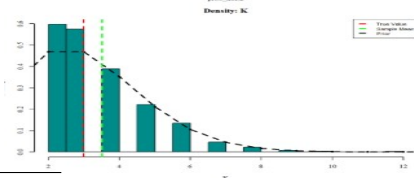
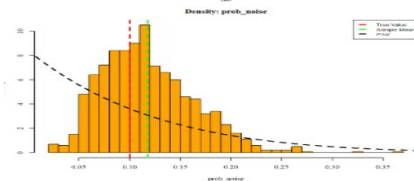
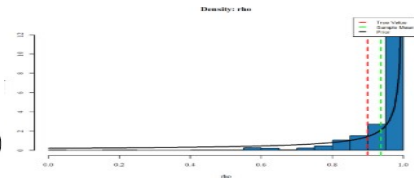
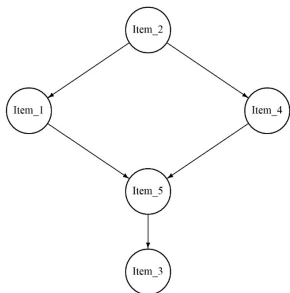
$$K = 3$$



¹https://github.com/hollyli-dq/BayesianPO_R
MCMC_Simulation_Tutorial.Rmd

Simulation study

Let's implement the synthetic data and simulate MCMC ²



$$p \sim \text{Beta}(1, 9),$$

$$\rho \sim \text{Beta}(1, 1/6),$$

$$K \sim \overline{\text{Pois}}(3)$$

²<https://github.com/hollyli-dq/BayesianPO-R>
MCMC_Simulation_Tutorial.Rmd

Scalability

Counting LE is #P-complete task and is easily expensive with M (number of actors) and N (data size).

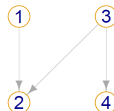
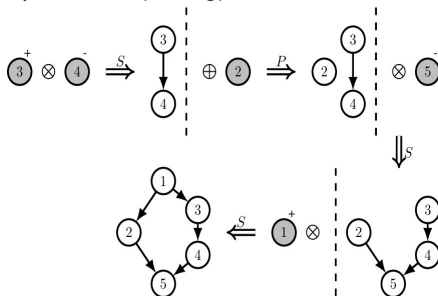
- Simpler model
- Faster LE counting algorithm
 - LEcount³ with $O(t!M^{(t+3)})$ for a tree width t (Kangas et al (2020))
- Posterior approximation
 - h -matrix approximation??

Restricted class of PO, "Vertex-Series-Parallel partial orders" (Mannila & Meek (2000))

³<https://www.rforge.net/lecount/>

Vertex-Series-Parallel partial orders (VSPs)

Sub-class of partial orders be formed by repeated series and parallel operations (left fig)



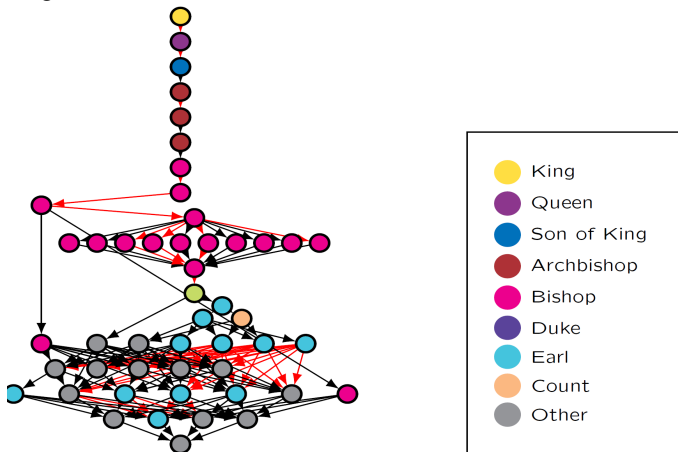
Two-dimensional POs ($K = 2$) except the forbidden graph order (right fig)

Binary decomposition trees (BDTs) representation with $O(M)$ cost!

With a prior for BDT, the posterior for h is formulated to do the uncertainty quantification.

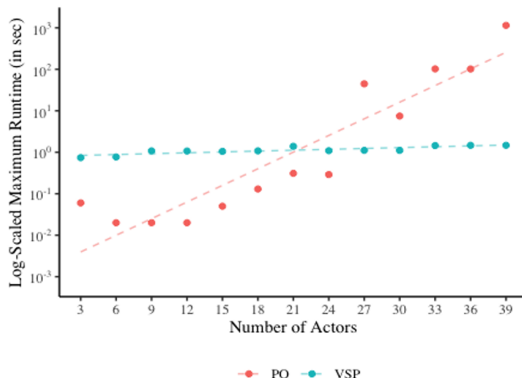
Vertex-Series-Parallel partial orders (VSPs)

Case study : Social hierarchy of $M = 49$ witnesses for 1134-1138 in England (Jiang et al (2023))



VSP/QJ-U model. Consensus order. Significant/strong order relations are indicated by black/red edges respectively.

Linear extension counting time comparison (Runtime for 20 lists)

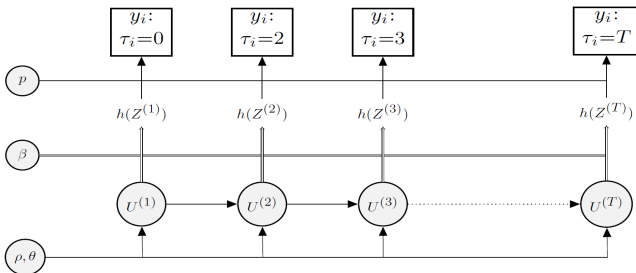


VSP counting method via the tree representation was scalable more than 200 actors while *LEcount* (PO) failed.

Other PO work

Time-varying PO (Nicholls et al (2025))

List data y_i come with time stamp $\tau_i \in \{1, \dots, T\}$. Extend to HMM using $U = (U^{(t)} \ t = 1, \dots, T)$ and $U \sim \text{VAR}_{\rho, \theta}(1)$.



PO with covariate effect (Nicholls et al (2025))

PO is $h(\eta)$ where the actor j specific covariate is X_j and latent variable is

$$\eta_{j,\tau} = U_{j,\tau} + \beta X_j.$$

Warning: A fixed covariate will yield an identifiable issue.

Summary

- PO offers flexible order structures; the biggest class of posets.
- PO includes a total order, bucket order, no order and VSP.
- Free from the total order assumption.
- VSP is an alternative option for high-dimensional PO.

Future work

- Noise model - Realistic noise, Mallows type noise, etc
- PO models for real-world problems
- Summary of uncertainty quantification
- Scalable methods

Reference

Jiang, C. and G. K. Nicholls (2024). Non-Parametric Bayesian Inference for Partial Orders with Ties from Rank Data observed with Mallows Noise.

<https://arxiv.org/abs/2408.14661>.

Jiang, C. et al. (2023). Bayesian inference for vertex-series-parallel partial orders. Proceedings of the Thirty-Ninth Conference on Uncertainty in Artificial Intelligence, pp. 995–1004. PMLR.

Nicholls, G. et al. (2025). Bayesian inference for partial orders from random linear extensions: power relations from 12th Century Royal Acta. Ann. Appl. Stat. 19(2): 1663-1690.

Kangas, K. et al. (2020). A faster tree-decomposition based algorithm for counting linear extensions. Algorithmica 82 2156–2173. MR4132887
<https://doi.org/10.1007/s00453-019-00633-1>

Mannila, H. and Meek, C. (2000) Global partial orders from sequential data. In Proceedings of the sixth ACM SIGKDD International conference on Knowledge discovery and data mining, pages 161-168.