## Algorithm 1 Marie Curie Genetic Algorithm Overview

- 1: Let  $NUM\_GENS = 100$  represent the number of generations to evolve
- 2: Let  $POP\_SIZE = 100$  represent the size of the total population
- 3: Let NBPG = 50 represent the number of new candidates to breed every generation
- 4: Let  $S_{min}$  and  $S_{max}$  represent the vectors of servo limits
- 5: Let  $L_R$  represent the landmarks in the reference image
- 6: Let  $P = \{C_i, i \in \{0, 1, ..., POP\_SIZE\}\}$  where each  $C_i$  is a candidate expression
- 7: for  $i \in \{0, 1, .., POP\_SIZE 1\}$  do
- 8: Initialize  $C_i$ .chromosome to  $\mathcal{U}(S_{min}, S_{max})$
- 9: Score each candidate s.t.  $C_i.score = mc\_score()$
- 10: end for
- 11: **for**  $g \in \{0, 1, ..., NUM\_GENS\}$  **do**
- 12: Let  $N = \{N_i, i \in \{0, 1, ..., NBPG\}\} = mc\_breed\_new(NBPG)$  be the set of new candidates for this gen
- 13: Score N s.t.  $N_i.score = mc\_score(\mathbf{N_i.chromosome}, L_R)$
- 14: Set  $C = C \cup N$
- 15: Remove the NBPG elements with the worst score from C
- 16: end for
- 17: **return**  $C_{opt} = C_i$  where  $i = \underset{i}{\operatorname{argmin}} \{C_i.score\}$

## Algorithm 2 MC Score Algorithm (mc\_score( $X, L'_R$ ))

- 1: Let M=68 be the number of landmarks recognized in an image (constrained by dlib landmark recognition algorithm)
- 2: Let D=2 be the dimensionality of a single landmark
- 3: Let  $L \in \mathbb{R}^{D,M}$  represent the raw pixel valued landmarks
- 4: Let  $L'_R$  be the reference landmarks to score against
- 5: Let X be the chromosome to score
- 6: Actuate X on the face using the Maestro Controller
- 7: Capture an image,  $I_C$ , of the face
- 8: Get the bounding box B of the face
- 9: Detect the center of a rectangular bounding box,  $B_C = [x, y]^T \in \mathbb{R}^2$  of the
- 10: Detect raw landmarks for cand. image  $L_C = dlib\_predictor(I_C).landmarks$
- 11: Calculate new "centered" landmarks  $L_C^C = L_C (B_C \otimes \mathbf{1}^T)$
- 12: Calculate the horizontal scaling by  $x_s = B_{Right} B_{C,x}$

- 13: Calculate the vertical scaling by  $y_s = B_{Bottom} B_{C,y}$ 14: Get normalized landmarks  $L'_C = L^C_C \oslash ([x_s, y_s]^T \otimes \mathbf{1}^T)$ 15: Calculate difference in corresponding landmarks between the reference image and the candidate image  $L_D = L_C' - L_R'$
- 16: **return**  $||L_D||_F = \sqrt{tr(L_D^T L_D)}$  where  $L_D^T L_D \in \mathbb{R}^{(M,M)}$  is the Gramian matrix of  $L_D$  and the diagonal elements of  $L_D^T L_D$  represent the euclidean distance error of each landmark. This can also be expressed as the square root of the sum of the squared errors.

## **Algorithm 3** MC Breed New (mc\_breed\_new( $N_C$ , $N_{CpP}$ ))

- 1: Let  $N_C$  be the number of new candidates to breed
- 2: Let  $N_{CpP}$  be the maximum number of candidates to breed for a single set of parents
- 3: Calculate the number of pairs of parents  $N_{pP}$
- 4: Get the mating pool M which is comprised of the best (lowest) scoring  $2N_{pP}$  candidates in C
- 5: Create  $N_{pP}$  pairs of parents,  $P_p$ , by pairing the highest scoring parents together (i.e.  $P_p = \{\{M_0, M_1\}, \{M_2, M_3\}, \dots\}$ )
- 6: Initialize  $N = \emptyset$  where N is the set of all new candidates bred this generation.

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7: for p \in P_p do
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- 8: **for**  $j \in \{0, 1, \dots, N_{CpP} 1\}$  **do**
- 9: Let  $C_N$  represent the new candidate
- 10: Randomize order of p
- 11: Randomly select location i in which to perform crossover of chromosomes
- 12: Set  $\mathbf{C_N}$ .chromosome =  $[p_0[:i]^T, p_1[i:]^T]^T$  representing the concatenation of the two parent chromosomes sliced at index i
- 13: Set  $C_N$ .chromosome =  $\mathcal{N}(C_N$ .chromosome,  $50^2$ ) representing a mutation of the inherited chromosome with each gene varying in a normal distribution parameterized by  $\mu = C_N$ .chromosome and  $\sigma^2 = 50^2$  where 50 is the standard deviation in quarter microseconds
- 14: Saturate values in  $C_N$ .chromosome to safe limits for servos
- 15: Append  $C_N$  to N by  $N = N \cup C_N$
- 16: end for
- 17: end for
- 18:  $\mathbf{return}\ N$