

Homework 4

Ex 6.1

We define a matrix $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$. Compute its determinant using the MATLAB function `det`. Explain why the result is not an integer.

```
In [63]: A = [1 2 3; 4 5 6; 7 8 9];
det(A)

ans =

-9.5162e-16

In [67]: [L U] = lu(A)

L =

    0.1429    1.0000         0
    0.5714    0.5000    1.0000
    1.0000         0         0

U =

    7.0000    8.0000    9.0000
         0    0.8571    1.7143
         0         0   -0.0000
```

This error is due to round-off errors appearing in LU decomposition.

Ex 6.2

The goal of this exercise is to compare the performances of the LU and Cholesky methods.

- Write a function `LUFacto` returning the matrices L and U determined via Algorithm 6.1. If the algorithm cannot be executed (division by 0), return an error message.

```
In [129..] %%file LUFacto.m

function [L,U] = LUFacto(A)
n = size(A,1);

for k=1:(n-1)
    if (A(k,k)~=0)
        disp('Error! Pivot must be nonzero')
        L = NaN;
        U = NaN;
        return
    else
        for i=(k+1):n
            A(i,k) = A(i,k)/A(k,k);
            for j=(k+1):n
                A(i,j) = A(i,j) - A(i,k)*A(k,j);
            end
        end
    end
end
L = eye(n) + tril(A,-1);
U = triu(A);
end

Created file 'D:\GitHub\NLA-IMA\hw4\LUFacto.m'.
```

- Write a function `Cholesky` returning the matrix B computed by Algorithm 6.2. If the algorithm cannot be executed (nonsymmetric matrix, division by 0, negative square root), return an error message. Compare with the MATLAB function `chol`.

```
In [123..] %%file Cholesky.m

function B = Cholesky(A)
if (A~=A')
    disp('Input must be symmetric!')
    B = NaN;
    return
else
    B = tril(A);
    n = size(A,1);
    for j=1:n
        for k=1:(j-1)
            B(j,j) = B(j,j) - (B(j,k))^2;
        end
        if (B(j,j)<=0)
            disp('Error! Pivot must be positive')
            B = NaN;
            return
        else
            B(j,j) = sqrt(B(j,j));
            for i=(j+1):n
                for k=1:(j-1)
                    B(i,j) = B(i,j) - B(j,k)*B(i,k);
                end
                B(i,j) = B(i,j)/B(j,j);
            end
        end
    end
end
end

Created file 'D:\GitHub\NLA-IMA\hw4\Cholesky.m'.
```

```
In [23]: times = zeros(2,length(1:100));

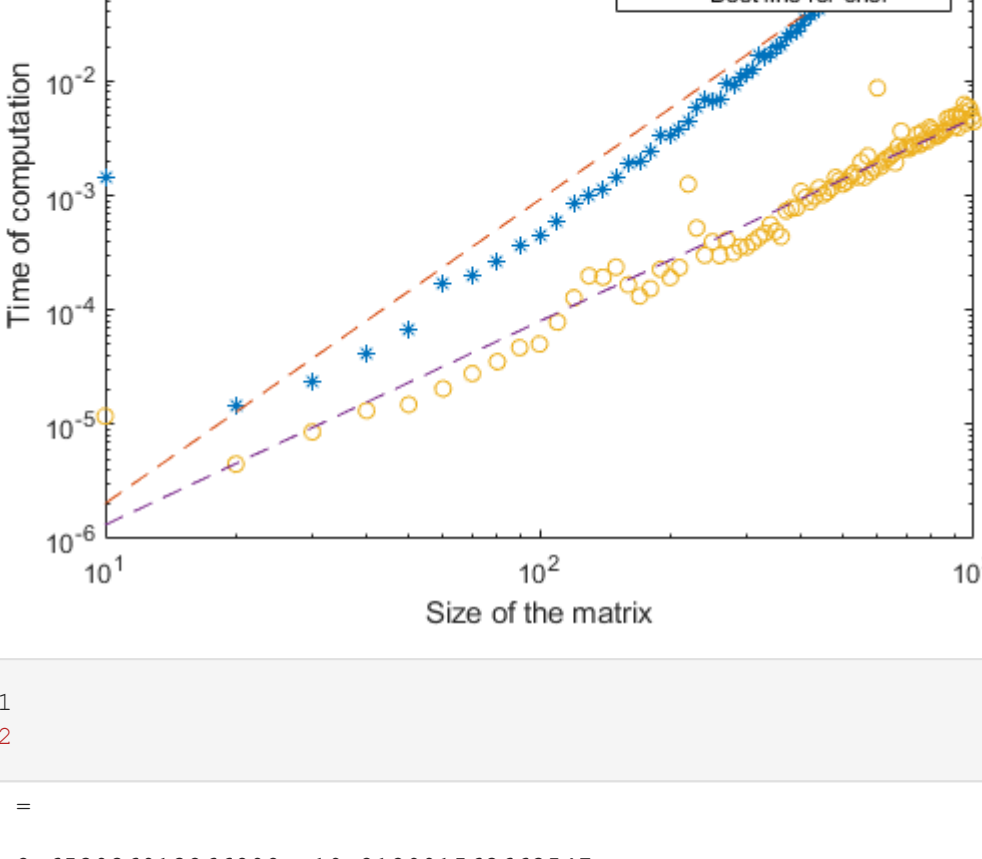
for i = 1:100
    n = i*10;
    A = PdSMat(n);

    tic
    B = Cholesky(A);
    times(1,i) = toc;

    tic
    B = chol(A);
    times(2,i) = toc;
end

x = 10:10:1000;
p1 = polyfit(log(x),log(times(1,:)),1);
p2 = polyfit(log(x),log(times(2,:)),1);

figure
loglog(x,times(1:,:),'*')
hold on
loglog(x,exp(p1(2)).*x.^p1(1),'--')
loglog(x,times(2:,:),'*o')
loglog(x,exp(p2(2)).*x.^p2(1),'--')
hold off
xlabel('Size of the matrix')
ylabel('Time of computation')
legend('Cholesky','Best line for Cholesky','chol','Best line for chol')
```



```
In [24]: p1
p2

p1 =

    2.653036013266808   -19.212901563663547

p2 =

    1.777763598656285   -17.626797864320473
```

We can see that $\text{time}_{\text{Cholesky}}(n) \approx \exp(-19.2129)n^{2.6530}$ and $\text{time}_{\text{chol}}(n) \approx \exp(-17.6267)n^{1.7777}$, under the assumption that computation time behaves like $C_1 \cdot n^{C_1}$.

- For $n = 10, 20, \dots, 100$, we define a matrix $A = \text{MatSdp}(n)$ (see Exercise 2.20) and a vector $b = \text{ones}(n,1)$. Compare:

- On the one hand, the running time for computing the matrices L and U given by the function `LUFacto`, then the solution x of the system $Ax = b$. Use the functions `BackSub` and `ForwSub` defined in Exercise 5.2.
- On the other hand, the running time for computing the matrix B given by the function `Cholesky`, then the solution x of the system $Ax = b$. Use the functions `BackSub` and `ForwSub`. Plot on the same graph the curves representing the running times in terms of n . Comment.

```
In [15]: %%file BackSub.m

function x = BackSub(U,y)
n = size(U,1);
x = zeros(n,1);
for i = n:-1:1
    s = 0;
    for j = n:-1:(i+1)
        s = s + U(i,j)*x(j);
    end
    x(i) = (y(i)-s)/U(i,i);
end
end

Created file 'D:\GitHub\NLA-IMA\hw4\BackSub.m'.
```

```
In [16]: %%file ForwSub.m

function x = ForwSub(L,y)
n = size(L,1);
x = zeros(n,1);
for i = 1:n
    s = 0;
    for j = 1:(i-1)
        s = s + L(i,j)*x(j);
    end
    x(i) = (y(i)-s)/L(i,i);
end
end

Created file 'D:\GitHub\NLA-IMA\hw4\ForwSub.m'.
```

```
In [17]: %%file SymmetricMat.m

function S = SymmetricMat(n)
S = rand(n);
S = S + S';
end

Created file 'D:\GitHub\NLA-IMA\hw4\SymmetricMat.m'.
```

```
In [18]: %%file PdSMat.m

function S = PdSMat(n)
S = SymmetricMat(n);
[P,D] = eig(S);
D = abs(D);
D = D + norm(D)*eye(size(D));
S = P*D*inv(P);
end

Created file 'D:\GitHub\NLA-IMA\hw4\PdSMat.m'.
```

```
In [25]: times = zeros(2,length(1:50));

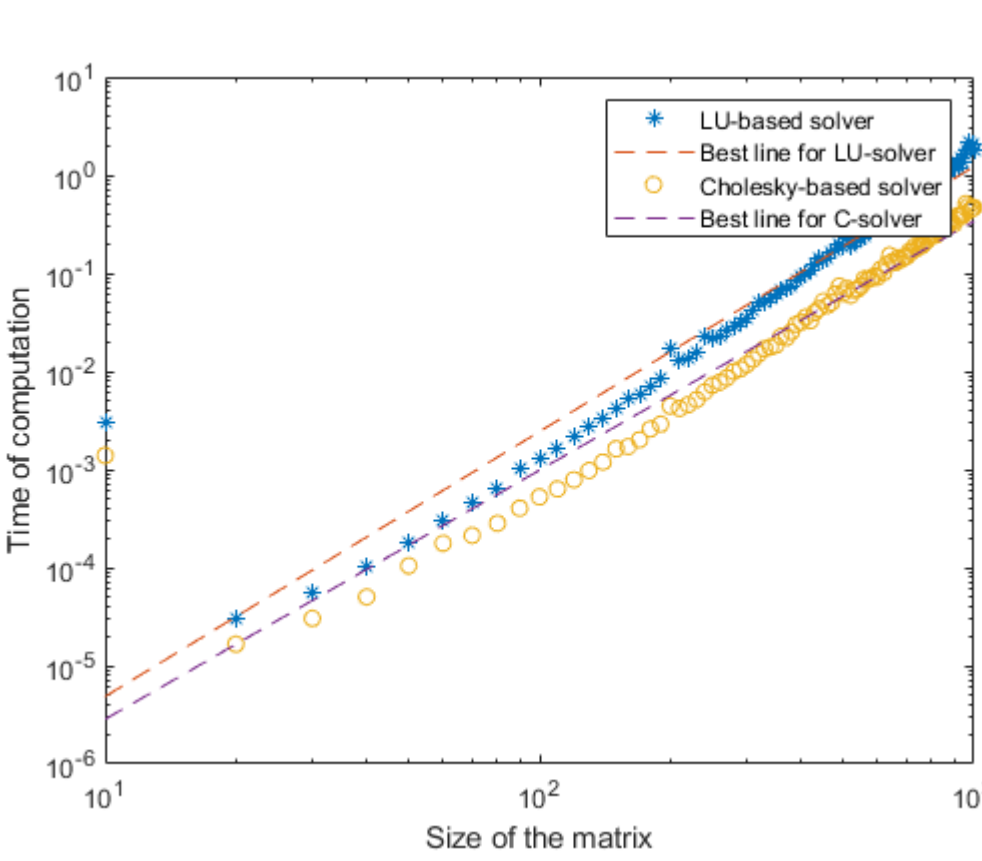
for i = 1:100
    n = i*10;
    A = PdSMat(n);
    b = ones(n,1);

    tic;
    [L U] = LUFacto(A);
    x1 = BackSub(U,ForwSub(L,b));
    times(1,i) = toc;

    tic;
    B = Cholesky(A);
    x2 = BackSub(B',ForwSub(B,b));
    times(2,i) = toc;
end

x = 10:10:1000;
p1 = polyfit(log(x),log(times(1,:)),1);
p2 = polyfit(log(x),log(times(2,:)),1);

figure
loglog(x,times(1:,:),'*')
hold on
loglog(x,exp(p1(2)).*x.^p1(1),'--')
loglog(x,times(2:,:),'*o')
loglog(x,exp(p2(2)).*x.^p2(1),'--')
hold off
xlabel('Size of the matrix')
ylabel('Time of computation')
legend('LU-based solver','Best line for LU-solver','Cholesky-based solver','Best line for C-solver')
```



```
In [26]: p1
p2

p1 =

    2.700435568617929   -18.452550099850395

p2 =

    2.538527947687385   -18.613953300022562
```

We see that $\text{time}_{\text{LU-Solver}}(n) \approx \exp(-18.4525)n^{2.7004}$ and $\text{time}_{\text{C-Solver}}(n) \approx \exp(-18.6139)n^{2.5385}$, under the assumption that computation time behaves like $C_1 \cdot n^{C_1}$.

Ex 6.4

The goal of this exercise is to evaluate the influence of row permutation in Gaussian elimination. Let A and b be defined by `e=1.E-15`, `A=[e 1 1;1 -1 1; 1 0 1]` and `b=[2 0 1]'`.

- Compute the matrices L and U given by the function `LUFacto` of Exercise 6.2.

```
In [11]: format long
e=1.E-16;
A=[e 1 1;-1 1 1; 1 0 1];
b=[2 0 1]';
[L,U] = LUFacto(A)
det(A)

L =

    1.0e+16 *

    0.0000000000000000         0         0
    1.0000000000000000    0.0000000000000000
    1.0000000000000000    0.0000000000000000    0.0000000000000000

U =

    1.0e+16 *

    0.0000000000000000    0.0000000000000000    0.0000000000000000
         0   -1.0000000000000000    0.0000000000000000
         0         0         0

ans =

    1.0000000000000000
```

- We define two matrices \tilde{L} and \tilde{u} by `[L u]=LUFacto(p*A)`, where p is the permutation matrix defined by the instruction `[w z p]=lu(A)`. Display the matrices \tilde{L} and \tilde{u} . What do you observe?

```
In [14]: [w z p]=lu(A);
p
[L u] = LUFacto(p*A)

p =

     0     1     0
     1     0     0
     0     0     1

L =

    1.0000000000000000         0         0
    0.0000000000000000    1.0000000000000000         0
    1.0000000000000000    1.0000000000000000    1.0000000000000000

u =

    1.0000000000000000   -1.0000000000000000    1.0000000000000000
         0         1.0000000000000000    1.0000000000000000
         0         0         -1.0000000000000000
```

First, notice that in this computation `e=1.E-16`. Notice that by permuting the rows of A we obtain a better-posed problem: the floating-point arithmetic neglects the small perturbation, avoiding losing the linear independence of the row of p^*A while doing Gaussian elimination. (See the notes attached to this document)

- Determine the solution of the system $Ax = b$ computed by the instruction `BackSub (U,ForwSub(L,b))`, then the solution computed by the instruction `BackSub (u,ForwSub(L,p*b))`. Compare with the exact solution $x = [0, 1, 1]^T$. Conclude.

```
In [13]: x1 = BackSub(U,ForwSub(L,b))
x2 = BackSub(u,ForwSub(L,p*b))

x1 =

    NaN
   -Inf
    Inf

x2 =

   -0.0000000000000000
    1.0000000000000000
    1.0000000000000000
```

The issue here is the floating-point arithmetic. Employing Gaussian elimination, we can see that we obtain a singular matrix U due to the round-off of the FP arithmetic. On the other hand, matrix U is non-singular due to the reorder of the rows of A . This reorder ensures longer pivots while doing Gaussian elimination. In conclusion, one way of precondition a matrix is to ensure pivots with a larger magnitude. In this manner, we avoid a magnification of tiny perturbations errors and undesired round-off errors of FP arithmetic.

Ex 6.9

Let A be a band matrix of order n and half bandwidth p . For $n \gg p \gg 1$ compute the number of operations $N_{\text{op}}(n,p)$ required for the LU factorization (having in mind Proposition 6.2.1).

Consider the Algorithm 6.1:

```
In [ ]: for k=1:(n-1)
    for i=(k+1):n
        A(i,k) = A(i,k)/A(k,k);
        for j=(k+1):n
            A(i,j) = A(i,j) - A(i,k)*A(k,j);
        end
    end
end
```

This algorithm is a compact form of Gaussian elimination. For each step k , we pick a row i below the k -th row and choose α to delete the first term of the k -th row by subtracting the i -th row. This α must be $a_{i,k}/a_{k,k}$. Then we apply the elementary row operation.

Due to the additional structure of the matrix A , we can truncate the inner loops until the half bandwidth instead of studying the whole row vector. The associated Algorithm is:

```
In [ ]: for k=1:(n-1)
    for i=(k+1):min([n k+p])
        A(i,k) = A(i,k)/A(k,k);
        for j=(k+1):min([n k+p])
            A(i,j) = A(i,j) - A(i,k)*A(k,j);
        end
    end
end
```

Due to the previous algorithm, we find that the number of operations is described by

$$N_{\text{op}}(n,p) = \sum_{k=1}^{n-1} \sum_{i=k+1}^{\min\{n,k+p\}} \left(1 + \sum_{j=k+1}^{\min\{n,k+p\}} 1 \right).$$

Notice that $k+p \leq n$ if and only if $k \leq n-p$. Thus,

$$\begin{aligned} N_{\text{op}}(n,p) &= \sum_{k=1}^{n-1} (\min\{n,k+p\} - k)(\min\{n,k+p\} - k - 1) \\ &= \sum_{k=1}^{n-p} p(p-1) + \sum_{k=n-p+1}^{n-1} (n-k)(n-k-1) \\ &= p(p-1)(n-p) + \sum_{k=0}^{p-2} k(k+1) \\ &= p(p-1)(n-p) + \frac{1}{3}p(p-1)(p-2). \end{aligned}$$

We conclude that $N_{\text{op}} = O(n)$ if p is fixed.