An efficient kinetic modeling of electrons with nonlocal Ohm's law in plasmas relevant to inertial confinement fusion by using the AWBS transport equation

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A preliminary version... The interaction of lasers with plasmas very often leads to nonlocal transport conditions, where the classical hydrodynamic model fails to describe physical phenomena related to highly mobile particles. In this study the electron distribution in plasma is investigated for the conditions relevant to ICF. In particular, we focus on the transport of nonlocal (supra-thermal) electrons streaming down the temperature gradient in the ablating plasma. Nevertheless, the nature of plasma (ionized gas) requires a correct response of background electrons too. This is achieved by the action of an electric field, which provides a self-consistent Ohms law based on the kinetic modeling. Our approach leans on the Albritton-Williams-Bernstein-Swartz collision operator providing a simple, computationally efficient, transport equation of electrons and is further benchmarked against Vlasov-Fokker-Planck codes Aladin and Impact and collisional PIC code Calder.

I. INTRODUCTION

The first attempts of modern kinetic modeling of plasma can be tracked back to the fifties, when Cohen, Spitzer, and Routly (CSR) [1] demonstrated that the effect of Coulomb collisions between electrons and ions in the ionized gas predominantly results from frequently occurring events of cumulative small deflections rather than occasional close encounters. This effect was originally described by Jeans in [2] and Chandrasekhar [3] proposed to use the diffusion equation model of the Vlasov-Fokker-Planck type (VFP) [4].

A classical paper by Spitzer and Harm (SH) [5] provides the computation of the electron distribution function (EDF) in a plasma (from low to high Z) with a temperature gradient accounting for e-e and e-i collisions. The expressions for current and heat flux are widely used in every plasma hydrodynamic models. The distribution function based on the spherical harmonics method in its first approximation (P1) [6] is of the form $f^0 + \mu f^1$, where

 f^0 and f^1 are isotropic and μ , is the direction cosine between the particle trajectory and some preferred direction in space. It should be emphasized that the SH solution expresses a small perturbation of equilibrium, i.e. that f^0 is the Maxwell-Boltzmann distribution and μf^1 represents a very small anisotropic deviation. This approximation holds for $L_T \gg \lambda_e$, a condition which is often invalid in laser plasmas, where L_T is the temperature length scale and λ_e the mean free path of electrons.

The actual cornerstone of the modern VFP simulations was set in place by Rosenbluth [7], when he derived a simplified form of the VFP equation for a finite expansion of the distribution function, where all the terms are computed according to plasma conditions, including f^0 , which of course needs to tend to the Maxwell-Boltzmann distribution. Consequently, the pioneering work on numerical solution of the VFP equation [8, 9] revealed the importance of the nonlocal electron transport in laser-heated plasmas. In particular, that the heat flow down steep temperature gradients in unmagnetised plasma cannot be described by the classical, local fluid description of transport [5, 10]. This is due to the classical f^1 is not a small deviation (especially for electrons faster than thermal velocity), i.e. $f^0 \sim f^1$, since the non-

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local regime is characterized by $L_T \sim \lambda_e$. It was also shown that a thermal transport inhibition [8] on one hand side, and a nonlocal preheat on the other hand side, naturally appear. These effects are attributed to significant deviations of f^0 from Maxwellian distribution.

Nevertheless, numerical solution of the VFP equation even in the Rosenbluth formalism remains very challenging computationally, because the e-e collision integral is nonlinear. More simple linear forms of e-e collision operator are needed.

It is the purpose of this paper to present an efficient alternative to VFP model based on the Albritton-Williams-Bernstein-Swartz collision operator (AWBS) [11]. In Section II we propose a modified form of the AWBS collision operator, where its important properties are further presented in Section III with the emphasis on its comparison to the full VFP solution in local diffusive regime. Section V focuses on the performance of the AWBS transport equation model compared to modern kinetic codes including VFP codes Aladin and Impact [12], and PIC code Calder [13], where the cases related to real laser generated plasma conditions are studied. Finally, the most important outcomes of our research are concluded in Section VI.

II. THE AWBS KINETIC MODEL

The electrons in plasma can be modeled by the deterministic Vlasov model of charged particles

$$\frac{\partial f}{\partial t} + \boldsymbol{v} \cdot \nabla_{\boldsymbol{x}} f + \frac{q_e}{m_e} \left(\boldsymbol{E} + \frac{\boldsymbol{v}}{c} \times \boldsymbol{B} \right) \cdot \nabla_{\boldsymbol{v}} f = C_{ee}(f) + C_{ei}(f),$$
(1)

where $f(t, \boldsymbol{x}, \boldsymbol{v})$ represents the density function of electrons at time t, spatial point \boldsymbol{x} , and velocity \boldsymbol{v} , \boldsymbol{E} and \boldsymbol{B} are the electric and magnetic fields in plasma, q_e and m_e being the charge and mass of electron.

The general form of the e-e collision operator C_{ee} is the Fokker-Planck form published by Landau [14]

$$C_{FP}(f) = \Gamma \int \nabla_{\boldsymbol{v}} \nabla_{\boldsymbol{v}} (\boldsymbol{v} - \tilde{\boldsymbol{v}}) \cdot (f \nabla_{\tilde{\boldsymbol{v}}} f - f \nabla_{\boldsymbol{v}} f) \, d\tilde{\boldsymbol{v}}, \tag{2}$$

where $\Gamma=\frac{4\pi q_e^4 \ln\Lambda}{m_e^2}$ and $\ln\Lambda$ is the Coulomb logarithm. The e-i collision operator C_{ei} could be expressed in a simpler form since massive ions are considered to be motionless compared to electrons. The scattering operator accounts for the change of electron velocity without change in the velocity magnitude. It is expressed in spherical coordinates as

$$C_{ei}(f) = \frac{\nu_{ei}}{2} \left(\frac{\partial}{\partial \mu} \left((1 - \mu^2) \frac{\partial f}{\partial \mu} \right) + \frac{1}{\sin^2 \phi} \frac{\partial^2 f}{\partial \theta^2} \right), \quad (3)$$

where $\mu=\cos\phi$, ϕ and θ are the polar and azimuthal angles, and $\nu_{ei}=\frac{Zn_e\Gamma}{v^3}$ is the e-i collision frequency.

The e-e collision operator needs to be linearized for efficient computations. Fish introduced a linear form of C_{ee} in [15] in the high-velocity limit $(v \gg v_{th})$ electron collision operator

$$C_H(f) = v\nu_e \frac{\partial}{\partial v} \left(f + \frac{v_{th}^2}{v} \frac{\partial f}{\partial v} \right) + \frac{\nu_e}{2} \left(1 - \frac{v_{th}^2}{2v^2} \right) \left(\frac{\partial}{\partial \mu} \left((1 - \mu^2) \frac{\partial f}{\partial \mu} \right) + \frac{1}{\sin^2 \phi} \frac{\partial^2 f}{\partial \theta^2} \right), \tag{4}$$

where $\nu_e = \frac{n_e \Gamma}{v^3}$ is the e-e collision frequency and $v_{th} = \sqrt{\frac{k_B T_e}{m_e}}$ is the electron thermal velocity. The linear form of C_H arises from an assumption that the fast electrons predominantly interact with the thermal (slow) electrons, which simplifies importantly the form (2). However the diffusion term in the e-e collision operator (4) still presents numerical difficulties.

A yet simpler form of the collision operator of electrons was proposed in [16]

$$C_{AWBS}(f) = v\nu_e^* \frac{\partial}{\partial v} (f - f_M) + \frac{\nu_{ei} + \nu_e^*}{2} \left(\frac{\partial}{\partial \mu} \left((1 - \mu^2) \frac{\partial f}{\partial \mu} \right) + \frac{1}{\sin^2 \phi} \frac{\partial^2 f}{\partial \theta^2} \right), \quad (5)$$

where $f_M = \frac{n_e}{(2\pi)^{\frac{3}{2}} v_{th}^3} \exp\left(-\frac{v^2}{2v_{th}^2}\right)$ is the Maxwell-Boltzmann equilibrium distribution. Here, the first term representing the AWBS operator [11] accounts for relaxation to equilibrium due to the e-e collisions, and the second term accounts for the e-i and e-e collisions contribution to scattering.

A method of angular momenta for the solution of the electron kinetic equation with the collision operator (5) was introduced in [16, 17].

In (5) we have introduced a modified e-e collision frequency ν_e^* in order to address a proper behavior with respect to Z, which is further analyzed in Section III and promising results compared to the full FP operator are presented.

III. BGK, AWBS, AND FOKKER-PLANCK MODELS IN LOCAL DIFFUSIVE REGIME

An approximate solution to the so-called *local diffusive* regime of electron transport can be found, since the *dif-* fusive regime refers to a low anisotropy given by the projection μ . i.e. modeled by a simple P1 form of EDF

$$\tilde{f}(z, v, \mu) = f^{0}(z, v) + \mu f^{1}(z, v),$$
 (6)

where z is the spatial coordinate along the axis z, v the magnitude of transport velocity, and $\mu = \cos \phi$, where ϕ is the pitch angle with respect to the axis z.

The approximate transport solution is then obtained when analyzing the action of the time-steady form of (1) in 1D on the approximation (6) as

$$\mu \left(\frac{\partial \tilde{f}}{\partial z} + \frac{q_e E_z}{m_e v} \frac{\partial \tilde{f}}{\partial v} \right) + \frac{q_e E_z}{m_e} \frac{(1 - \mu^2)}{v^2} \frac{\partial \tilde{f}}{\partial \mu} = \frac{1}{v} C(\tilde{f}), \quad (7)$$

where C is a given collision operator including both e-e and e-i collisions.

The locality of transport is the best expressed in terms of the Knudsen number $Kn=\frac{\lambda}{L},$ where λ is the mean free path of electron and L the characteristic length scale of plasma. Consequently, plasma conditions characterized by $Kn\ll 1$ exhibit a local transport regime. This measure then play a very important role in our analysis, where we use the electroni-electron and electronion mean free paths $\lambda_e=Z\lambda_{ei}=\frac{v}{\nu_e},$ and the density and temperature plasma scale lengths $L_{n_e}=n_e/\frac{\partial n_e}{\partial z}$ and $L_{T_e}=T_e/\frac{\partial T_e}{\partial z}.$

A. The BGK local diffusive electron transport

Bhatnagar, Gross, and Krook introduced a very simple form of a collision operator [18]

$$C_{BGK}(\tilde{f}) = \nu_e(\tilde{f} - f_M) + \frac{\nu_{ei} + \nu_e}{2} \frac{\partial}{\partial \mu} (1 - \mu^2) \frac{\partial \tilde{f}}{\partial \mu}.$$
 (8)

In spite of its simple form, BGK collision operator (8) serves as a useful model providing a relevant kinetic response, yet only qualitative with respect to the FP collision operator (2). In particular, the conservation of kinetic energy, momentum, and number of particles is often violated [19].

However, the form of (8) provides a simple analytical treatment of local diffusive transport regime, when used in (7). As a result, one finds a simple form of the BGK isotropic and anisotropic terms of (6) to be

$$f^0 = f_M + Kn \frac{v_{th}^2}{v^2} f^1, (9)$$

$$f^{1} = -\frac{\lambda_{e}}{Z} \left(\frac{\partial f^{0}}{\partial z} + \frac{q_{e} E_{z}}{m_{e} v} \frac{\partial f^{0}}{\partial v} \right), \tag{10}$$

where $Kn = \frac{\lambda_e}{L_{n_e}} + \frac{5}{2} \frac{\lambda_e}{L_{T_e}}$ and a detailed derivation of (9) and (10) can be found in Appendix A. Equation (9) states that $f^0 \to f_M$ when $Kn \ll 1$, and accordingly, $f^1 \to -\frac{\lambda_e}{Z} \left(\frac{\partial f_M}{\partial z} + \frac{q_e E_z}{m_e v} \frac{\partial f_M}{\partial v} \right)$. When the quasineutrality constraint on the electric field (A7) is used, one finally obtains the analytical BGK form of (6)

$$\tilde{f}_{BGK} = f_M - \mu \left(\frac{v^2}{2v_{th}^2} - 4\right) \frac{1}{Z} \frac{\lambda_e}{L_{T_e}} f_M,$$
 (11)

which recovers the Lorentz electron-ion collision gas model [20]. It should be noticed that f^0 equilibrates to f_M as $O(Kn^2)$ in (9), since $f^1 = \left(\frac{v^2}{2v_{th}^2} - 4\right) \frac{1}{Z} K n f_M$.

The details about the BGK distribution function compared to other collision operators can be found in Section III D.

B. The AWBS local diffusive electron transport

Similarly to the BGK model, the AWBS collision operator 5 explicitly uses equilibration to the Maxwell-Boltzmann distribution f_M . On the other hand side, AWBS originates from C_H , which is derived from the full FP operator (2). This makes the AWBS operator to be superior to the BGK operator, which is considered a pure phenomenological model.

If (5) is used in (7), one obtains the following equations governing the AWBS isotropic and anisotropic terms of (6)

$$\frac{\partial f^0}{\partial v} = \frac{\partial f_M}{\partial v} + K n \frac{v_{th}^2}{v^2} \frac{f^1}{v},\tag{12}$$

$$\frac{\partial f^1}{\partial v} - \frac{Z + \xi}{v\xi} f^1 = \frac{\lambda_e}{v\xi} \left(\frac{\partial f^0}{\partial z} + \frac{q_e E_z}{m_e v} \frac{\partial f^0}{\partial v} \right), \quad (13)$$

where ξ represents a scaling parameter defining the modified e-e collision frequency as $\nu_e^* = \xi \nu_e$. A detailed derivation of (12) and (13) can be found in Appendix A. One observes that f^0 goes to Maxwellian when the local regime of transport is settled. Indeed, according to equation (12) the derivative $\frac{\partial f^0}{\partial v} \to \frac{\partial f_M}{\partial v}$ when $Kn \ll 1$ for any electron velocity, thus leading to $f^0 \to f_M$. Consequently, one finds the AWBS model equation for f^1 in local diffusive regime to be

$$\frac{\partial f^{1}}{\partial v} + \frac{Z + \xi}{v\xi} f^{1} = \frac{\lambda_{e}}{v\xi} \left(\frac{1}{L_{n_{e}}} + \left(\frac{v^{2}}{2v_{th}^{2}} - \frac{3}{2} \right) \frac{1}{L_{T_{e}}} - \frac{q_{e}E_{z}}{m_{e}v_{th}^{2}} \right) f_{M}. \quad (14)$$

Since there is no simple analytical formula for f^1 solving (14), we adopt the implicit Euler numerical integration with $\Delta v < 0$, i.e. we integrate from high electron velocity ($v_{max} = 7v_{th}$) to the velocity equal to zero (using 10^4 steps). This mimics a particle deceleration due to collisions. The correct numerical solution of (14) corresponds to an appropriate value of E_z leading to a zero current. As in the BGK case, the numerical solution of (14) reveals that $f^1 \sim Knf_M$ and that f^0 equilibrates to f_M as $O(Kn^2)$ based on (12).

The details about the AWBS distribution function compared to other collision operators and a proper evaluation of the scaling parameter ξ can be found in Section III D.

C. The Fokker-Planck local diffusive electron transport

The solution to the 1D transport equation (7) using the Fokker-Planck collision operator (2) is very ambitious, as demonstrated in [1, 3, 7], fortunately, one can use the explicit evaluation of the electron distribution function published in [5], which takes the following form

$$f^{1}(z,v) = \frac{v_{2th}^{4}}{\Gamma Z n_{e}}$$

$$\left(2\tilde{D}_{T}\left(\frac{v}{v_{2th}}\right) + \frac{3}{2}\frac{\gamma_{T}}{\gamma_{E}}\tilde{D}_{E}\left(\frac{v}{v_{2th}}\right)\right)\frac{f_{M}}{T}\frac{\partial T_{e}}{\partial z}, \quad (15)$$

where $\tilde{D}_T(x) = ZD_T(x)/B$, $\tilde{D}_E(x) = ZD_E(x)/A$, γ_T , and γ_E are numerical values in TABLE I, TABLE II, and TABLE III in [5], and $v_{2th} = \sqrt{\frac{k_B T_e}{2m_e}}$.

One should be aware, that the solution of (7) equipped with the full FP collision operator reveals the importance of e-e Coulomb collisions, which is emphasized in the Z dependence of the distribution function, current, heat flux, electric field, etc. In particular, the latter exhibits the following dependence [5]

$$\mathbf{E} = \frac{m_e v_{th}^2}{q_e} \left(\frac{\nabla n_e}{n_e} + \left(1 + \frac{3}{2} \frac{Z + 0.477}{Z + 2.15} \right) \frac{\nabla T_e}{T_e} \right), \quad (16)$$

which for $Z \gg 1$ corresponds to the classical Lorentz electric field (A7).

D. Summary of the BGK, AWBS, and Fokker-Planck local diffusive transport

Ever since the SH paper [5], the effect of microscopic electron transport on the current $\int q_e v \tilde{f} \, dv$ and the heat flux $\int \frac{m_e |v|^2}{2} v \tilde{f} \, dv$ in plasmas under local diffusive conditions has been understood. By overcoming some delicate aspects of the numerical solution to (2) presented in the CSR paper [1], the effect of electron-electron collisions was properly quantified and the correct dependence on Z of the heat flux q was approximated as [5, 21]

$$q = \frac{Z + 0.24}{Z + 4.2} q_L, \tag{17}$$

where $\mathbf{q}_L = \kappa T_e^{\frac{5}{2}} \nabla T_e$ is the heat flux given by Lorentz gas model [20]. In the case of the BGK operator and its EDF formula (11), the correct dependence on Zcan be simply achieved by scaling the e-e and e-i collision frequencies as

$$\nu_e^{BGK} = \frac{\nu_{ei}^{BGK}}{Z} = \frac{Z + 4.2}{Z + 0.24} \nu_e, \tag{18}$$

which imposes a right heat flux magnitude (17).

We have performed an extensive computational analysis in the case of the AWBS operator in order to obtain the heat flux behavior while varying Z. As expected, the heat flux magnitude did not match exactly the Z-dependence (17), e.g. for Z=1 the AWBS heat flux was about 60% less than the SH calculation, while there was a perfect match in the case of $Z\gg 1$. By assuming that the e-e collisions are responsible for this inadequacy, we searched for a scaling of ν_e in (5). Interestingly, we

	Z=1	Z=2	Z=4	Z = 16	Z = 116
$ar{\Delta q}_{AWBS}$	0.057	0.004	0.037	0.021	0.004
$\phi(Z)$	-0.037	-0.003	0.04	0.058	0.065

TABLE I. Relative error $\bar{\Delta}q_{AWBS} = |q_{AWBS} - q_{SH}|/q_{SH}$ of the $\nu_e^* = \frac{\nu_e}{2}$ scaling used in the AWBS model (5) showing the discrepancy (maximum around 6%) with respect to the original solution of the heat flux given by numerical solution in Spitzer and Harm [5]. The values of $\phi(Z)$ (weak dependence) are also shown.

found an almost constant scaling ξ , i.e. with a very weak dependency on Z as

$$\nu_e^* = \xi \nu_e = \left(\frac{1}{2} + \phi(Z)\right) \nu_e \approx \frac{\nu_e}{2},\tag{19}$$

where the dependence $\phi(Z) = \frac{0.59Z - 1.11}{8.37Z + 5.15} \ll \frac{1}{2}$ for any Z. Indeed, TABLE I shows $\phi(Z)$ and its corresponding relative error (maximum around 6%) of the heat flux modeled by (5) vs. SH results represented by (17). It should be noted that the error is calculated with respect to original values presented in TABLE III in [5]. It is worth mentioning, that the zero current condition was followed in all AWBS calculations. The overall result is that the consistent electric field is always almost equal to the classical Lorentz value (A7) with the difference being less than 0.01 % for any Z.

Nevertheless, the electron-electron collisions effect represented by (17) provides only an integrated information about the heat flux magnitude. If one takes a closure look at the distribution function itself, the conformity of the modified AWBS collision operator is even more emphasized as can be seen in FIG. 1 showing the flux moment in spherical coordinates of velocity $q_1 = \frac{m_e v^2}{2} v f^1 v^2$. In the case of the high Z Livermorium plasma (Z = 116), AWBS exactly aligns with the Lorentz gas limit. In the opposite case of the low Z Hydrogen plasma (Z = 1), the AWBS distribution function approaches significantly the numerical SH solution. BGK takes the Lorentz gas distribution function form for any Z only taking into account the scaling (18).

It is worth mentioning that the first derivative term in the AWBS collision operator (5) (red dashed line) provides a significant model improvement with respect to the SH (Fokker-Planck) solution (solid black line) compared to the simplest BGK model (8) (dashed-dot blue line) in FIG. 1.

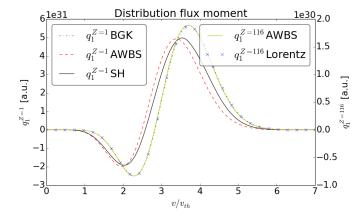


FIG. 1. The flux velocity moment of the anisotropic part of the electron distribution function in low Z=1 and high Z=116 plasmas in diffusive regime. In the case of Z=1 the AWBS model matches very well the reference solution given by the SH calculation [5] in comparison to the BGK model. In the case of Z=116 the AWBS model aligns exactly with the Lorentz gas approximation as expected. The BGK and the SH results are not shown, but correspond excatly to the Lorentz gas.

IV. THE AWBS NONLOCAL TRANSPORT MODEL OF ELECTRONS

In order to define a nonlocal transport model of electrons, we use the AWBS collision operator and the P1 angular discretization of the electron distribution function

$$\tilde{f}(\boldsymbol{x}, \boldsymbol{n}, v) = f_0(\boldsymbol{x}, v) + \boldsymbol{n} \cdot \boldsymbol{f_1}(\boldsymbol{x}, v),$$
 (20)

consisting of the isotropic part represented by the zeroth angular moment $f_0 = \frac{1}{4\pi} \int_{4\pi} \tilde{f} d\mathbf{n}$ and the directional part represented by the first angular moment $\mathbf{f_1} = \frac{3}{4\pi} \int_{4\pi} \mathbf{n} \tilde{f} d\mathbf{n}$, where \mathbf{n} is the transport direction (the solid angle). Then, the first two angular moments [19] applied to the steady form of (1) with collision operator (5) (extended by (19)) lead to the model equations

$$v\frac{\nu_{e}}{2}\frac{\partial}{\partial v}\left(f_{0}-f_{M}\right) = \frac{v}{3}\nabla\cdot\boldsymbol{f_{1}} + \frac{q_{e}}{m_{e}}\frac{\boldsymbol{E}}{3}\cdot\left(\frac{\partial\boldsymbol{f_{1}}}{\partial v} + \frac{2}{v}\boldsymbol{f_{1}}\right),$$

$$v\frac{\nu_{e}}{2}\frac{\partial\boldsymbol{f_{1}}}{\partial v} - \nu_{scat}\boldsymbol{f_{1}} = v\nabla f_{0} + \frac{q_{e}}{m_{e}}\boldsymbol{E}\frac{\partial f_{0}}{\partial v} + \frac{q_{e}\boldsymbol{B}}{m_{e}c}\times\boldsymbol{f_{1}},$$

$$(22)$$

where $\nu_{scat} = \nu_{ei} + \frac{\nu_e}{2}$. The system of equations (21) and (22) is called the **AP1 model** (AWBS + P1).

On the one hand side AP1 model gives us with the information about the electron distribution function, on the other hand side a macroscopic interpretation of the microscopic EDF properties are of great importance and provide the bridge between kinetic and fluid description of plasma. For example the flux quantities as electric

current and heat flux due to the motion of electrons

$$\boldsymbol{j} = \frac{4\pi}{3} q_e \int v \boldsymbol{f_1} \, d\tilde{v}, \quad \boldsymbol{q_h} = \frac{4\pi}{3} \frac{m_e}{2} \int v^3 \boldsymbol{f_1} \, d\tilde{v},$$

where $d\tilde{v} = v^2 dv$ the spherical coordinates metric, are based on corresponding velocity moments (integrals) of the first angular moment of EDF. Consequently, the explicit formula for the first angular moment from (22) (the inversion inspired by [22]) proves to be extremely useful

$$f_1 = \frac{\nu_{scat}^2 \mathbf{F}^* + \boldsymbol{\omega}_B \ \boldsymbol{\omega}_B \cdot \mathbf{F}^* - \nu_{scat} \ \boldsymbol{\omega}_B \times \mathbf{F}^*}{\nu_{scat}(\boldsymbol{\omega}_B^2 + \nu_{scat}^2)}, \quad (23)$$

because it provides a valuable information about the dependence of macroscopic flux quantities on electric and magnetic fields in plasma, where $\omega_B = \frac{q_e B}{m_e c}$ is the electron gyro-frequency and $F^* = v \frac{\nu_e}{2} \frac{\partial f_1}{\partial v} - v \nabla f_0 - \frac{q_e}{m_e} E \frac{\partial f_0}{\partial v}$.

A. Nonlocal Ohm's Law

The expression (23) becomes extremely useful when used to describe the electron fluid momentum, i.e. the current velocity moment

$$\dot{\mathbf{j}}_{(f,\mathbf{E},\mathbf{B})} = q_e \int v \mathbf{f}_1 v^2 \, dv =
-\frac{q_e^2}{m_e} \int v \frac{\nu_{ei}^2 \mathbf{E}^* + \omega_B \, \omega_B \cdot \mathbf{E}^* - \nu_{ei} \, \omega_B \times \mathbf{E}^*}{\nu_{ei} (\omega_B^2 + \nu_{ei}^2)} \, d\tilde{v},$$

where $\boldsymbol{E}^* = \boldsymbol{E} \; \frac{\partial f_0}{\partial v} + \frac{m_e}{q_e} v \nabla f_0$ is the effective electric field in plasma. This can be written as

$$\mathbf{j}_{(f,\mathbf{E},\mathbf{B})} = \mathbf{J}_{Ohm} \frac{\partial f_0}{\partial v} \mathbf{E} + \frac{m_e}{q_e} \mathbf{J}_{Ohm} v \nabla f_0, \qquad (24)$$

where we used the following notation $\mathbf{J}_{Ohm}\mathbf{g} = -\frac{q_e^2}{m_e} \int v \frac{\nu_{ei}^2 \mathbf{g} + \boldsymbol{\omega}_B \ \boldsymbol{\omega}_B \cdot \mathbf{g} - \nu_{ei} \ \boldsymbol{\omega}_B \times \mathbf{g}}{\nu_{ei}(\boldsymbol{\omega}_B^2 + \nu_{ei}^2)} \ \mathrm{d}\tilde{v}$ showing how \mathbf{J}_{Ohm} acts on a general vector field \mathbf{g} . We refer to (24) as to the **nonlocal Ohm's law**. Its relation and a proper local asymptotic to the standard Ohm's law can be found when $f_0 \to f_M$ and weak magnetization $(\boldsymbol{\omega}_B \ll \nu_{ei})$ is considered. Then (24) simplifies to

$$\mathbf{j} = -\frac{q_e^2}{m_e} \int \frac{v^3}{\nu_{ei}} \left(\mathbf{E} \frac{\partial f_M}{\partial v} + \frac{m_e}{q_e} v \nabla f_M \right) dv =
\frac{16\sqrt{\frac{2}{\pi}} q_e^2 k_B^3 T_e^{\frac{3}{2}}}{m_e^5 \Gamma Z} \left[\mathbf{E} - \frac{\frac{5}{2} n_e k_B \nabla T_e + \nabla n_e k_B T_e}{q_e n_e} \right], \quad (25)$$

which can be directly compared to the local fluid theory

$$\boldsymbol{E} = \sigma(f_0)^{-1} \boldsymbol{j} - \frac{\nabla P(f_0)}{q_e n_e} \xrightarrow{f_0 \to f_M} \boldsymbol{E}_l = \frac{\boldsymbol{j}}{\sigma_l} + \frac{\nabla p_e - \boldsymbol{R}_{T_e}}{q_e n_e},$$
(26)

while addressing properly the local electric field E_l given by the pressure $p_e = n_e k_B T_e$, the thermal force R_{T_e} =

 $-\frac{3}{2}n_ek_B\nabla T_e$ and the local electrical conductivity σ_l $16\sqrt{\frac{2}{\pi}}q_e^2k_B^{\frac{3}{2}}T_e^{\frac{3}{2}}/m_e^{\frac{5}{2}}\Gamma Z$ [10]. In (26) we defined the nonlocal electrical tensor conductivity

$$\sigma = \mathbf{J}_{Ohm} \frac{\partial f_0}{\partial v},\tag{27}$$

and the nonlocal microscopic force

$$\nabla P = \sigma^{-1} m_e n_e \mathbf{J}_{Ohm} v \nabla f_0, \tag{28}$$

based on (24).

The local dependence of the AP1 current (25) on electric field and gradients of n_e and T_e clearly demonstrates, that (26) is a local version of (24). This also implies that (24) provides a very important physics related to the magnetic field source in terms of nonlocal Biermann battery, since the curl on the electric field (26) gives

$$\nabla \times \frac{\nabla P}{q_e n_e} \xrightarrow{f_0 \to f_M} \nabla \times \frac{\nabla p_e - \mathbf{R}_{T_e}}{q_e n_e} = \frac{k_B}{q_e n_e} \nabla T_e \times \nabla n_e.$$
(29)

A local version of the **nonlocal Ohm's law** (24) compared to the *generalized Ohm's law* (26) when a magnetic field is applied would require a much more delicate analysis and we leave it as a future complementary work.

It should be noted, that ν_e -related terms in (23) have been omitted in (24), since the e-e collisions do not contribute (cancel out when integrated over velocity) to the momentum change, i.e. $\int v \left(v \frac{\nu_e}{2} \frac{\partial \mathbf{f_1}}{\partial v} - \frac{\nu_e}{2} \mathbf{f_1}\right) d\tilde{v} = 0.$

В. **AWBS Nonlocal Magneto-Hydrodynamics**

The AWBS nonlocal magneto-hydrodynamic model (Nonlocal-MHD) refers to two temperature single-fluid hydrodynamic model extended by a kinetic model of electrons using the AWBS transport equation, which provides a direct coupling between hydrodynamics and Maxwell equations.

Mass, momentum density, and total energy ρ , ρu , and $E = \frac{1}{2}\rho \mathbf{u} \cdot \mathbf{u} + \rho \varepsilon_i + \rho \varepsilon_e$, where ρ is the density of plasma, u the plasma fluid velocity, ε_i the specific internal ion energy density, and ε_e the specific internal electron energy density, are modeled by the Euler equations in Lagrangian frame [23, 24]

$$\frac{\mathrm{d}\rho}{\mathrm{d}t} = -\rho\nabla\cdot\boldsymbol{u},\tag{30}$$

$$\rho \frac{\mathrm{d}\boldsymbol{u}}{\mathrm{d}t} = -\nabla(p_i + p_e) + \boldsymbol{j}_{(f,\boldsymbol{E},\boldsymbol{B})} \times \boldsymbol{B}, \qquad (31)$$

$$\rho C_{V_i} \frac{\mathrm{d}T_i}{\mathrm{d}t} = \left(\rho^2 C_{T_i} - p_i\right) \nabla \cdot \boldsymbol{u} - G(T_i - T_e), \quad (32)$$

$$\rho C_{V_e} \frac{\mathrm{d}T_e}{\mathrm{d}t} = \left(\rho^2 C_{T_e} - p_e\right) \nabla \cdot \boldsymbol{u} + G(T_i - T_e) -\nabla \cdot \boldsymbol{q}_{h(f, \boldsymbol{E}, \boldsymbol{B})} + Q_{\mathrm{IB}},$$
(33)

where T_i is the temperature of ions, T_e the temperature of electrons, p_i the ion pressure, p_e the electron pressure, q_h the heat flux, $Q_{\rm IB}$ the inverse-bremsstrahlung

laser absorption, and $G = \rho C_{V_e} \nu_{ei}$ is the ion-electron energy exchange rate. The thermodynamic closure terms p_e , p_i , $C_{V_i} = \frac{\partial \varepsilon_i}{\partial T_i}$, $C_{T_i} = \frac{\partial \varepsilon_i}{\partial \rho}$, $C_{V_e} = \frac{\partial \varepsilon_e}{\partial T_e}$, $C_{T_e} = \frac{\partial \varepsilon_e}{\partial \rho}$ are obtained from an equation of state (EOS), e.g. the SESAME equation of state tables [25, 26].

The magnetic and electric fields are modeled by Maxwell equations

$$\frac{1}{c}\frac{\mathrm{d}\boldsymbol{B}}{\mathrm{d}t} = -\nabla \times \boldsymbol{E},\tag{34}$$

$$\frac{1}{c} \frac{\mathrm{d}\boldsymbol{B}}{\mathrm{d}t} = -\nabla \times \boldsymbol{E}, \qquad (34)$$

$$\frac{1}{c} \frac{\mathrm{d}\boldsymbol{E}}{\mathrm{d}t} = \nabla \times \boldsymbol{B} - \frac{4\pi}{c} \boldsymbol{j}_{(f,\boldsymbol{E},\boldsymbol{B})}, \qquad (35)$$

where the initial state of \boldsymbol{B} and \boldsymbol{E} obeys the Gauss's law.

We have explicitly written the current and heat flux as dependent on electron kinetics, represented by the electron distribution function f, and electric and magnetic fields. In principal, $j_{(f,E,B)}$ and $q_{h(f,E,B)}$ can be referred to as the kinetic closure and is provided by the AP1 **model** (21) and (22), where f_M is given on the spatial profile of T_e governed by (33). All quantities are defined in the fluid frame in the aforementioned Nonlocal-MHD model.

Numerical Implementation of the AWBS Electron Kinetics

It is well known, that as the electron transport exhibits a quasi-steady behavior, the same holds for the electric field in (35) on the time scale of the fluid. Consequently, the Ampere's law (35) usually takes a quasisteady form $\frac{4\pi}{c} j_{(f,E,B)} = \nabla \times B$ when used in hydrodynamics. Proceeding further, one can make use of the nonlocal Ohm's law (24) to write a fully kinetic form of the Ampere's law governing the electric field E

$$\mathbf{J}_{Ohm} \frac{\partial f_0}{\partial v} \mathbf{E} + \frac{m_e}{q_e} \mathbf{J}_{Ohm} v \nabla f_0 = \frac{c}{4\pi} \nabla \times \mathbf{B}. \tag{36}$$

In order to solve the kinetics of electrons, we adopt a high-order finite element discretization [27, 28] of the model equations (21), (22), (36)

$$\mathbf{M}_{(\frac{v\nu_e}{2})}^{L_2} \cdot \frac{\mathrm{d}\mathbf{f_0}}{\mathrm{d}v} - \mathbf{V}_{(\frac{q_eE}{3m_e})}^{L_2} \cdot \frac{\mathrm{d}\mathbf{f_1}}{\mathrm{d}v} = \mathbf{D}_{(\frac{v}{3})}^{L_2} \cdot \mathbf{f_1} + \mathbf{M}_{(\frac{2q_eE}{3m_ev})}^{L_2} \cdot \mathbf{f_1} + \mathbf{b}_{(\frac{v\nu_e}{3m_ev})}^{L_2}, \tag{37}$$

$$\mathbf{M}_{(\frac{v\nu_{e}}{2})}^{H_{1}} \cdot \frac{\mathrm{d}\boldsymbol{f_{1}}}{\mathrm{d}v} - \mathbf{V}_{(\frac{q_{e}\boldsymbol{E}}{m_{e}})}^{H_{1}} \cdot \frac{\mathrm{d}\boldsymbol{f_{0}}}{\mathrm{d}v} = \mathbf{G}_{(v)}^{H_{1}} \cdot \boldsymbol{f_{0}} + \mathbf{M}_{(\nu_{scat})}^{H_{1}} \cdot \boldsymbol{f_{1}} + \mathbf{C}_{(\frac{q_{e}\boldsymbol{B}}{m_{e}c}\times)}^{H_{1}} \cdot \boldsymbol{f_{1}}, \qquad (38)$$

$$\mathbf{J}_{(\frac{\partial f_{0}}{\partial v})}^{ND} \cdot \boldsymbol{E} = \mathbf{J}\mathbf{G}_{(\frac{m_{e}v}{q_{e}})}^{ND} \cdot \boldsymbol{f_{0}} + \boldsymbol{b}_{(\frac{c}{4\pi}\nabla\times\boldsymbol{B})}^{ND},$$

where the continuous differential operators are represented by standard discrete analogs (matrices of bilinear forms) M, G, D, V, C, i.e. mass, gradient, divergence, vector field dot product, and vector field curl, and by \mathbf{J}, \mathbf{JG} matrices specific to **nonlocal Ohm's law** (24). The linear form \mathbf{b} represents sources, i.e. temperature T_e via $\frac{\partial f_M}{\partial v}$ and the curl of the magnetic field \mathbf{B} . These finite element discrete analogs are defined on piece-wise continuous L_2 finite element space (domain of f_0), continuous H_1 finite element space (domain of f_1) [27], and Nedelec finite element space (domain of f_1). We do not show their definitions since it is out of the scope of this article.

The strategy of solving (37) and (38) resides in integrating $\frac{\mathrm{d}f_0}{\mathrm{d}v}$ and $\frac{\mathrm{d}f_1}{\mathrm{d}v}$ along the velocity magnitude. This is done by starting the integration from infinite velocity $(v=7v_{th}^{max})$ is a sufficiently high limit to zero velocity using the Implicit Runge-Kutta method. The value v_{th}^{max} equals the electron thermal velocity corresponding to the maximum electron temperature in the current profile of plasma. It should be noted, that the backward integration concept is crucial for the model, since it corresponds to the deceleration of electrons due to collisions [29], which leads to some limitations described in Appendix B.

V. BENCHMARKING THE AWBS NONLOCAL TRANSPORT MODEL

After having shown several encouraging properties of the AWBS transport equation defined by (5) under local diffusive conditions in Sec. III, this section provides a broader analysis of the electron transport and focuses on analyzing its behavior under variety of conditions in plasmas. In principle, this is characterized by allowing that electron mean free path can be arbitrarily long, which leads to so-called nonlocal electron transport extensively investigated in numerous publications [8, 16, 30–34]. Among a variety of tests suitable for benchmarking the nonlocal electron transport models published [16, 17, 21, 35–37], we focus on conditions relevant to inertial confinement fusion plasmas generated by lasers. We show results of our implementation of the AP1 nonlocal transport model presented in Sec. IV benchmarked against simulation results provided by Calder, a collisional Particle-In-Cell code, and by Aladin and Impact [12] VFP codes.

Calder PIC code

In the limit of classical physics, a fluid description of the particle phase-space, including small angle binary collisions, can be described with the Maxwell equations (34), (35) coupled with the ion and electron Vlasov equations with the Landau-Beliaev-Budker collisions integral (LBB) [14, 38]

$$\frac{\partial f_{\alpha}}{\partial t} + \mathbf{v} \cdot \nabla_{\mathbf{x}} f_{\alpha} + q_{\alpha} \left(\mathbf{E} + \mathbf{v} \times \mathbf{B} \right) \nabla_{\mathbf{p}} f_{\alpha} = C_{LBB}(f_{\alpha}, f_{\alpha}) + \sum_{\beta} C_{LBB}(f_{\alpha}, f_{\beta}). \quad (40)$$

The LBB collision integral takes the form

$$C_{LBB}(f_{\alpha}, f_{\beta}) = -\frac{\partial}{\partial \mathbf{p}} \cdot \frac{\Gamma_{\alpha\beta}}{2} \left[\int \mathbf{U}(\mathbf{p}, \mathbf{p}') \cdot (f_{\alpha} \nabla_{\mathbf{p}'} f_{\beta}' - f_{\beta}' \nabla_{\mathbf{p}} f_{\alpha}) \right] d^{3} \mathbf{p}',$$
(41)

where its relativistic kernel reads $\mathbf{U}(\mathbf{p}, \mathbf{p}') = \frac{r^2/\gamma\gamma'}{(r^2-1)^{3/2}}$ $\left[(r^2-1)\mathbf{I} - \mathbf{p} \otimes \mathbf{p} - \mathbf{p}' \otimes \mathbf{p}' + r(\mathbf{p} \otimes \mathbf{p}' + \mathbf{p}' \otimes \mathbf{p})\right]$ with $\gamma = \sqrt{1+\mathbf{p}^2}$, $\gamma' = \sqrt{1+\mathbf{p}'^2}$ and $r = \gamma\gamma' - \mathbf{p} \cdot \mathbf{p}'$. The momentum \mathbf{p}_{α} (\mathbf{p}_{β}) is normalized to $m_{\alpha}c$ (resp. $m_{\beta}c$). The collision operator (41) tends to (2) in the non-relativistic limit. The aforementioned model is solved in 3D by the PIC code CALDER. [13, 39].

Brief description of the Calder code FIG. 3.

Impact and Aladin VFP codes

The PIC code is extremely expensive as the collisions require the description of the velocity space in 3 dimensions. Yet, a reduction of dimensions can be done by developing the distribution function in a cartesian tensor series, equivalent to a serie along the spherical harmonics [40] as follows:

$$f(t, \mathbf{x}, \mathbf{v}) = f_0(t, \mathbf{x}, v) + \mathbf{n} \cdot \mathbf{f}_1(t, \mathbf{x}, v) + \mathbf{n} \otimes \mathbf{n} : \mathbf{f}_2(t, \mathbf{x}, v) + \dots$$
(42)

A P_n model refers to neglecting orders higher than \mathbf{f}_n . The distribution function approximation $f(t, \mathbf{x}, \mathbf{v}) \approx f_0(t, \mathbf{x}, v) + \mathbf{n} \cdot \mathbf{f}_1(t, \mathbf{x}, v)$ coupled with the Landau-Fokker-Planck collisional operator (2), leads to the P_1 -VFP model [12, 40]:

$$\frac{\partial f_0}{\partial t} + \frac{v}{3} \nabla \cdot f_1 + \frac{q_e}{3m_e v^2} \frac{\partial}{\partial v} (v^2 \mathbf{E} \cdot \mathbf{f}_1) = C_{ee}^0(f_0), (43)$$

$$\frac{\partial \mathbf{f}_1}{\partial t} + v \nabla f_0 + \frac{q_e \mathbf{E}}{m_e} \frac{\partial f_0}{\partial v} + \frac{q_e \mathbf{B}}{m_e} \times \mathbf{f}_1 = -\nu_{ei} \mathbf{f}_1. \tag{44}$$

where for simplicity only the isotropic contribution of (2) is used

$$C_{ee}^{0}(f_0) = \frac{\Gamma}{v^2} \frac{\partial}{\partial v} \left[C(f_0) f_0 + D(f_0) \frac{\partial f_0}{\partial v} \right], \quad (45)$$

$$C(f_0(v)) = 4\pi \int_0^v f_0(u)u^2 du,$$
 (46)

$$D(f_0(v)) = \frac{4\pi}{v} \int_0^v u^2 \int_u^\infty w f_0(w) dw du.$$
 (47)

Impact and Aladin solve the system (43) and (44) with the Maxwell equations (34) and (35) in two dimensions, assuming motionless ions.

It is worth mentioning that AP1 leans on similar model equations as Aladin and Impact with the difference, that AP1 describes electron distribution function as quasi steady with respect to the time evolution of ion fluid, and of course, AP1 is using a simple (linear) collision operator inherently coupled to ion fluid via f_M .

Brief description of the Aladin code FIG. 4, FIG. 2.

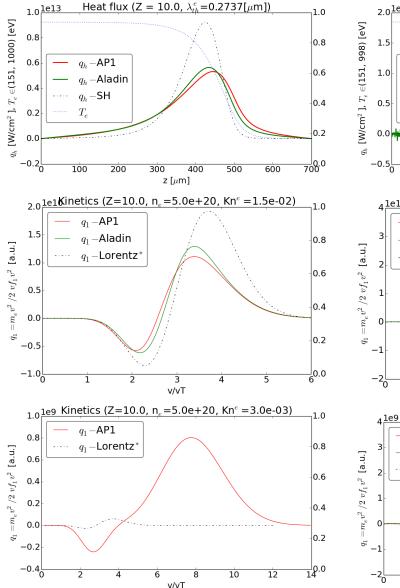


FIG. 2. Snapshot 12 ps. Top: correct steady solution of heat flux. Middle: correct comparison to kinetic profiles at point 442 μ m by Aladin. Velocity limit 3.4 v_{th} . Bottom: correct comparison to kinetic profiles at point 550 μ m by Aladin. Velocity limit 8.8 v_{th}

A. Heat-bath problem

The accuracy of the AP1 implementation is compared to Aladin, Impact and Calder codes by calculating the heat flow in the case where a large relative temperature variation

$$T_e(z) = 0.575 - 0.425 \tanh ((z - 450)s),$$
 (48)

which exhibits a smooth steep gradient at point 450 μ m connecting a hot bath ($T_e=1~{\rm keV}$) and cold bath ($T_e=1~{\rm keV}$)

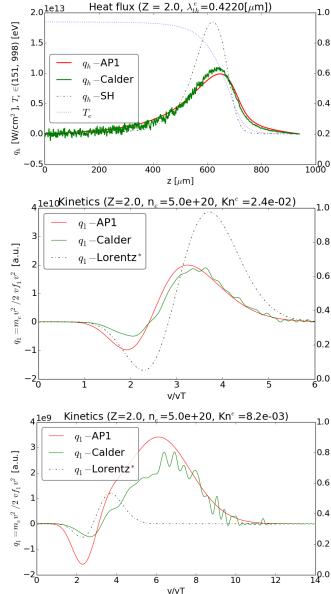


FIG. 3. Snapshot 11 ps. Left: correct steady solution of heat flux. Velocity limit 6.4 v_{th} .

 $0.17~{\rm keV})$ and s is the parameter of steepness. This test is referred to as a simple non-linear heat-bath problem and originally was introduced in [35] and further investigated in [16, 17, 36, 37].

The total computational box size is 700 μm in the case of Aladin and Impact and 1000 μm in the case of Calder. We performed Aladin, Impact, and Calder simulations showing an evolution of temperature starting from the initial profile (48). Due to an inexact initial distribution function (approximated by Maxwellian), the first phase of the simulation exhibits a transient behavior of the heat flux. After several ps the distribution adjusts properly to its nonlocal nature and the actual heat flux

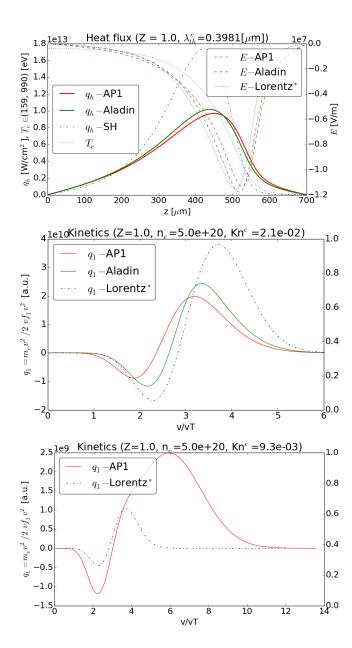


FIG. 4. Snapshot 20 ps. Top: correct steady solution of heat flux. Right: Aladins results are correct. Velocity limit 4.4 v_{th} . Snapshot 20 ps. AP1 kinetic profiles at point 580 μ m corresponding to a highly nonlocal nature of the heat flux and is in a good agreement with [36]. Velocity $max(q_1) = 6.0 \ v_{th}$. Velocity limit 9.0 v_{th} .

profile can be compared. We then take the temperature profile from Aladin/Impact/Calder and used our AP1 implementation to calculate the heat flow it would predict given this profile. For all heat-bath simulations the electron density, Coulomb logarithm and ionisation were kept constant and uniform. The coulomb logarithm was held fixed throughout, $\ln\Lambda=7.09$.

In FIG. 2, FIG. 3, and FIG. 4 we show AP1 results for various ionization states in the case of a moderate

nonlocality (Kn e $\sim 10^{-2}$) corresponding to a roungly 50 % inhibition of the heat flux maximum. We prefer to use $\operatorname{Kn}^e = \frac{\lambda_e}{\sqrt{Z+1}L_{T_e}}$ instead of $\operatorname{Kn}^e = \frac{\lambda_{ei}}{L_{T_e}}$, because $\sqrt{Z+1}$ provides a better scaling of nonlocality with respect to ionization [32], i.e. the flux inhibition and Kn^e are approximately the same when varying Z = 10, 2, 1 in FIG. 2, FIG. 3, and FIG. 4. In principle, a very good performance of AP1 can be observed in all three cases, where the heat flux profiles computed using AP1 model equations (21), (22), and (36) (no B field in 1D) match very well to the computed results by Aladin and Calder. The distribution function details related to the point of the heat flux maximum (644 μ m) and to the point of the nonlocal transport effect (750 μ m) are also shown in FIG. 3. The latter shows a very good agreement with a similar result published in [36]. Here comes the part commenting on distribution function details at two points of the heat flux profile: the heat flux maximum; and a highly nonlocal point down the temperature gradient. The Aladin nonlocal point EDF should be added very soon.

In addition, the Knudsen number Kn^e has been varied among the simulation runs in order to address a broad range of nonlocality of the electron transport corresponding to the laser-heated plasma conditions, i.e. $\mathrm{Kn}^e \in (0.0001,1)$. The variation of Kn^e arises from the variation of the uniform electron density $n_e \in (10^{19},10^{23})~\mathrm{cm}^{-3}$ or the length scale given by the slope of the temperature profile $s \in (1/2500,1/25)\mu\mathrm{m}$. Results of an extensive set of simulations of varying Kn^e is shown in FIG. 5.

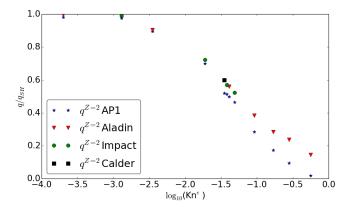


FIG. 5. Simulation results for the case Z=2 computed by AP1/Aladin/Impact/Calder. Every point corresponds to the maximum heat flux in a "tanh" temperature simulation, which can be characterized by Kn. The range of $\log_{10}(\mathrm{Kn}) \in (0,-4)$ can be expressed as equivalent to the electron density approximate range $n_e \in (1e19,3.5e22)$ of the 50 μ m slope tanh case. In the case of Kn = 0.56, $q_{Aladin}/q_{AP1} \approx 7.9$.

When analyzing the results of FIG. 5 we have found an interesting observation related to stopping effect of electrons. It turns out, that the force acting on electrons is dominated by electric field above some velocity limit v_{lim} and this limit drops down significantly when

$-$ Kn e	10^{-4}	10^{-3}	10^{-2}	10 ⁻¹	1
v_{lim}/v_{th}	70.8	22.4	7.3	3.1	1.8

TABLE II. Scan over varying nonlocality (Kn^e) showing the limit of the collision friction dominance over the acceleration of electrons due to the electric field force. The electric field effect is dominant for electrons with higher velocity than v_{lim} defined in (B3). Kn^e and v_{th} are evaluated from the same plasma profiles.

the plasma conditions are more nonlocal, i.e. with increasing Knudsen number as can be seen in TABLE II. As a consequence, one can see that when $\mathrm{Kn}^e \sim 10^{-1}$ the electrons responsible for the heat flux (velocity ~ 3.5 v_{th}) are preferably affected by the electric field rather than by collisions.

In every simulation run of AP1 we used 250 velocity groups in order to avoid numerical errors in modeling of the electron kinetics. However, a smaller number of groups, e.g. 50, provides a very similar results (an error around 10% in the heat flux).

B. Hohlraum problem

Additionally to the steep temperature gradients, the laser-heated plasma experiments also involve steep density gradients and variation in ionization, which is even more dominant in multi-material targets as in inertial fusion experiments, e.g. at the interface between the helium gas-fill and the ablated high Z plasma.

In [37], a kinetic simulation of such a test was introduced. Plasma profiles provided by a HYDRA simulation in 1D spherical geometry of a laser-heated gadolinium hohlraum containing a typical helium gas-fill were used as input for the IMPACT [12] VFP code. Electron temperature T_e , electron density n_e and ionisation Z profiles shown in FIG. 6 at 20 nanoseconds of the HYDRA simulation were used (after spline smoothing) as the initial conditions for the IMPACT run (in planar geometry). For simplicity, the Coulomb logarithm was treated as a constant $\ln \Lambda_{ei} = \ln \Lambda_{ee} = 2.1484$. In reality, in the low-density corona $\ln \Lambda$ reaches 8, which, however, does not affect the heat flux profile significantly.

It is worth mentioning that in the surroundings of the heat flux maximum ($\sim 1662\mu\mathrm{m}$) the profiles of all plasma variables exhibit steep gradients with a change from $T_e=2.5~\mathrm{keV},~n_e=5\times10^{20}~\mathrm{cm}^3,~Z=2~\mathrm{to}~T_e=0.3~\mathrm{keV},~n_e=6\times10^{21}~\mathrm{cm}^3$, $Z=44~\mathrm{across}$ approximately 100 $\mu\mathrm{m}$ (between 1600 $\mu\mathrm{m}$ and 1700 $\mu\mathrm{m}$), starting at the helium-gadolinium interface.

Of course this subsection is apparently missing some comments with respect to the simulations using different kinetic models. It is an ongoing process.

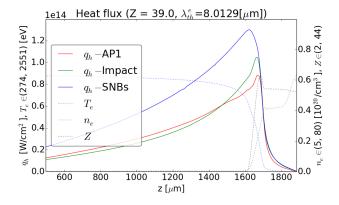


FIG. 6.

VI. CONCLUSIONS

- The most important point is that we introduce a collision operator, which is coherent with the full FP, i.e. no extra dependence on Z.
- Touch pros/contras of linearized FP in Aladin and Impact vs AWBS
- Raise discussion about what is the weakest point of AP1 for high Kns: the velocity limit or phenomenological Maxwellization?
- Summarize useful outcomes related to plasma physics as the competition between collisions and electric field in the electron stopping, then the knowledge about the nonlocal electron population (preheat electrons can be tracked back to the point of source according to their dominant velocity), and the last information about the tendency of the velocity maximum in q_1 with respect to Z and Kn^e .
- Emphasize the good results of Aladin (compared to Impact) and also outstanding results of Calder while being PIC.
- Electric field plays an important role in nonlocal electron kinetics and nonlocal Ohm's law provides the necessary equation to treat it properly.
- In coherence with the latter, the dfdv must be treated properly in nolocal electron kinetics, and so, AWBS can be included without any extra effort thus making it way much suitable than BGK, which is outperformed by AWBS when compared to FP.

ACKNOWLEDGMENTS

Appendix A: Background of the local diffusive regime theory

The left hand side of (7) acts on (6) as

$$\mu \left(\frac{\partial \tilde{f}}{\partial z} + \frac{q_e E_z}{m_e v} \frac{\partial \tilde{f}}{\partial v} \right) + \frac{q_e E_z}{m_e} \frac{1 - \mu^2}{v^2} \frac{\partial \tilde{f}}{\partial \mu} = \mu \left(\frac{\partial f^0}{\partial z} + \frac{q_e E_z}{m_e v} \frac{\partial f^0}{\partial v} \right) + \frac{q_e E_z}{m_e v^2} f^1 + O(\mu^2). \quad (A1)$$

The action on (6) of the BGK operator (8) as used in (7) reads

$$\frac{1}{v}C_{BGK}(\tilde{f}) = \frac{\tilde{f} - f_M}{\lambda_e} + \frac{1}{2}\left(\frac{Z}{\lambda_e} + \frac{1}{\lambda_e}\right)\frac{\partial}{\partial\mu}(1 - \mu^2)\frac{\partial\tilde{f}}{\partial\mu},$$

$$= \frac{f^0 - f_M}{\lambda_e} - \mu\frac{Z}{\lambda_e}f^1.$$
(A2)

Consequently, if the isotropic and anisotropic parts of (A1) and (A2) are compared, one finds the following equations

$$f^0 = f_M + \frac{\lambda_e q_e E_z}{m_e v^2} f^1, \tag{A3}$$

$$f^{1} = -\frac{\lambda_{e}}{Z} \left(\frac{\partial f^{0}}{\partial z} + \frac{q_{e} E_{z}}{m_{e} v} \frac{\partial f^{0}}{\partial v} \right). \tag{A4}$$

It is valid to assume that $f^0 = f_M$ from (A3). Then,

$$f_{BGK}^{1} = -\frac{\lambda_e}{Z} \left(\frac{\partial f_M}{\partial z} + \frac{q_e E_z}{m_e v} \frac{\partial f_M}{\partial v} \right). \tag{A5}$$

The quasi-neutrality constraint, corresponding to a zero electric reads

$$\mathbf{j} \equiv q_e \int \mathbf{v} \tilde{f} \, \mathrm{d} \mathbf{v} = \mathbf{0}. \tag{A6}$$

In the case of the BGK EDF, in particular its anisotropic part (A5), the zero current condition takes the form

$$2\pi \int_{-1}^{1} \int_{v} v \mu^{2} f_{BGK}^{1} \, \mathrm{d}v \mathrm{d}\mu = 0,$$

which leads to the electric field (same as the classical Lorentz electric field [20])

$$E_z = \frac{m_e v_{th}^2}{q_e} \left(\frac{1}{L_{n_e}} + \frac{5}{2} \frac{1}{L_{T_e}} \right). \tag{A7}$$

It is worth mentioning, that the deviation of f^0 from f_M in (A3) can be written as $\left(\frac{\lambda_e}{L_{n_e}} + \frac{5}{2} \frac{\lambda_e}{L_{T_e}}\right) \frac{v_{th}^2}{v^2} f^1$, where naturally arises the Knudsen number $Kn = \frac{\lambda_e}{L_{n_e}} + \frac{5}{2} \frac{\lambda_e}{L_{T_e}}$ comprising both contributions of electron density and temperature gradients.

In the case of the AWBS operator (5) used in (7), its action on (6) reads

$$\frac{1}{v}C_{AWBS}(\tilde{f}) = \frac{v\xi}{\lambda_e} \frac{\partial}{\partial v} \left(\tilde{f} - f_M \right)
+ \frac{1}{2} \left(\frac{Z}{\lambda_e} + \frac{\xi}{\lambda_e} \right) \frac{\partial}{\partial \mu} (1 - \mu^2) \frac{\partial \tilde{f}}{\partial \mu}
= \frac{v\xi}{\lambda_e} \frac{\partial}{\partial v} \left(f^0 - f_M \right)
+ \mu \left(\frac{v\xi}{\lambda_e} \frac{\partial f^1}{\partial v} - \frac{Z + \xi}{\lambda_e} f^1 \right), \quad (A8)$$

where $\nu_e^* = \xi \nu_e = \frac{v\xi}{\lambda_e}$ with ξ being a scaling parameter of the standard e-e collision frequency. Its purpose is to match AWBS heat flux to results obtained by Spitzer and Harm [5] obtained for any Z. Sec. III C shows that this match can be found with a constant $\xi = 0.5$.

One finds the following equations if the isotropic and anisotropic parts of (A1) and (A8) are compared

$$\frac{\partial}{\partial v} \left(f^0 - f_M \right) = \frac{\lambda_e q_e E_z}{\xi m_e v^2} \frac{f^1}{v},\tag{A9}$$

$$\frac{v\xi}{\lambda_e}\frac{\partial f^1}{\partial v} - \frac{Z+\xi}{\lambda_e}f^1 = \frac{\partial f^0}{\partial z} + \frac{q_e E_z}{m_e v}\frac{\partial f^0}{\partial v}.$$
 (A10)

If we assume that $\frac{\partial f^0}{\partial v} = \frac{\partial f_M}{\partial v}$, i.e. $f^0 = f_M$, the anisotropic part of the AWBS operator is governed by the equation

$$\frac{\partial f_{AWBS}^{1}}{\partial v} - \frac{Z + \xi}{v\xi} f_{AWBS}^{1} = \frac{\lambda_{e}}{v\xi} \left(\frac{\partial f_{M}}{\partial z} + \frac{q_{e}E_{z}}{m_{e}v} \frac{\partial f_{M}}{\partial v} \right). \tag{A11}$$

Even though it is not straightforward, the electric field in (A11) (solved numerically) providing a zero current exactly matches (A7). Consequently, the deviation of $\frac{\partial f^0}{\partial v}$ from $\frac{\partial f_M}{\partial v}$ in (A9) can be written as $Kn\frac{v_{th}^2}{\xi v^2}\frac{f^1}{v}$. Finally, it should be stressed, that the concept of lo-

Finally, it should be stressed, that the concept of locality expressed as $Kn \ll 1$ is crucial for our *local diffusive regime* analysis, because it provides sufficient Maxwellization, i.e. (A3) and (A9), and correspondingly, (A5) and (A11) are valid models.

Appendix B: AP1 electric field limit

Interestingly, we have encountered a very specific property of the AP1 model with respect to the electric field magnitude. The easiest way how to demonstrate this is to write the model equations (21) and (22) in 1D (z-axis). Then, due to its linear nature, it is easy to eliminate one of the partial derivatives with respect to v, i.e. $\frac{\partial f_0}{\partial v}$ or $\frac{\partial f_{1z}}{\partial v}$. In the case of elimination of $\frac{\partial f_0}{\partial v}$ one obtains the following equation

$$\left(v\frac{\nu_e}{2} - \frac{2q_e^2 E_z^2}{3m_e^2 v \nu_e}\right) \frac{\partial f_{1_z}}{\partial v} = \frac{2q_e E_z}{3m_e \nu_e} \frac{\partial f_{1_z}}{\partial z} + \frac{4\pi q_e E_z}{3m_e} \frac{\partial f_M}{\partial v} + \frac{v}{3} \frac{\partial f_0}{\partial z} + \left(\frac{4q_e^2 E_z^2}{3m_e^2 v^2 \nu_e} + \left(\nu_{ei} + \frac{\nu_e}{2}\right)\right) f_{1_z}.$$
(B1)

It is convenient to write the bracket on the left hand side of (B1) as $\frac{2}{3v\nu_e}\left(\left(\sqrt{3}v\frac{\nu_e}{2}\right)^2-\frac{q_e^2}{m_e^2}E_z^2\right)$ from where it is clear that the bracket is negative if $\sqrt{3}v\frac{\nu_e}{2}<\frac{q_e}{m_e}|\pmb{E}|,$ i.e. there is a velocity limit for a given magnitude $|\pmb{E}|,$ when the collisions are no more fully dominant and the electric field introduces a comparable effect to the collision friction in the electron transport.

It can be shown, that the last term on the right hand side of (B1) is dominant and the solution behaves as

$$\Delta \mathbf{f_1} \sim \exp\left(\frac{\frac{4q_e^2 E_z^2}{3m_e^2 v^2 \nu_e} + \left(\nu_{ei} + \frac{\nu_e}{2}\right)}{v \frac{\nu_e}{2} - \frac{2q_e^2 E_z^2}{3m_e^2 v \nu_e}} \Delta v\right), \quad (B2)$$

where $\Delta v < 0$ represents a velocity step of the implicit Euler numerical integration of decelerating electrons. However, (B2) exhibits an exponential growth for velocities above the friction limit (bracket on the left

hand side of (B1))

$$v_{lim} = \sqrt{\frac{\sqrt{3}\Gamma m_e}{2q_e}} \frac{n_e}{|\mathbf{E}|},\tag{B3}$$

which makes the problem to be ill-posed.

In order to provide a stable model, we introduce a reduced electric field to be acting as the accelerating force of electrons

$$|E_{red}| = \sqrt{3}v \frac{m_e}{q_e} \frac{\nu_e}{2}, \tag{B4}$$

ensuring that the bracket on the left hand side of (B1) remains positive. Further more we define two quantities

$$\omega_{red} = \frac{|\boldsymbol{E}_{red}|}{|\boldsymbol{E}|}, \quad \nu_{scat}^E = \frac{q_e}{m_e v} \left(|\boldsymbol{E}| - |\boldsymbol{E}_{red}| \right),$$

introducing the reduction factor of the electric field ω_{red} and the compensation of the electric field effect in terms of scattering ν_{scat}^E . Consequently, the AP1 model (21), (22), and (36) can be formulated as well posed with the help of ω_{red} and ν_{scat}^E .

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