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Abstract. Linear time-invariant discrete digital plant, with no restrictions on the form of the state equation and the number of controls, is considered.

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Discrete time control systems. Operational amplifier 1 is an input r amplifier with a high input impedance. Operational amplifier 2 is the o amplifier; it buffers the voltage on the hold capacitor. There are two modes of operation for a sample-and-hold circuit: the tracking mode and the hold mode.

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Such a discrete-time control system consists of four major parts: 1 The Plant which is a continuous-time dynamic system. 2 The Analog-to-Digital Converter (ADC). 3 The Controller (μP), a microprocessor with a "real-time" OS. 4 The Digital-to-Analog Converter (DAC) .

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The new edition of this comprehensive digital controls book integrates MATLAB throughout the book. The book has also increased inflexibility and reader friendliness through the streamlining of coverage in Chapters 6 7 (controllability, pole placement and observability, and optimal control). The previous edition ISBN is: 0-13-216102-8.

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