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1.1 PROBLEM DEFINITION. The control of physical systems with a digital computer is becoming more and more common. Aircraft autopilots, mass-transit vehicles, oil refineries, paper-making machines, and countless electromechanical servomechanisms are among the many existing examples.

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3.3 Discretization Methods 19 • If the PI controller is designed only with continuous-time considerations, i.e., the DAC and ADC are not considered, a decrease in control performance is expected with the digital controller compared to the continuous-time (analog) controller.

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