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Nonlinear Systems Third Edition Prentice Hall, 2002 ISBN 0-13-067389-7 Hassan K. Khalil The author is the winner of the IFAC Control Engineering Textbook Prize 2002 for the second edition of Nonlinear Systems. Table of Contents; Preface; Changes from the Second Edition; Errata - First Edition (updated on March 3, 2004)

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TTK4150 Nonlinear Control Systems Solution 6 Part 1. Department of Engineering Cybernetics Norwegian University of Science and Technology Fall 2003. Solution 1 (Exercise 13.1 in Khalil)

The system is given by  $M\ddot{\delta} = P - D\dot{\delta} + \eta_1 E \sin(\delta) - \tau E$ .  $q = -\eta_2 E q + \eta_3 \cos(\delta) + EFD$ . which is rewritten in the form  $\dot{x} = f(x) + g(x)u$  using  $x_1 = \delta$   $x_2 = \dot{\delta}$   $x_3 = E q$ .  $u = EFD$ .

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