

# Causal Inference Despite Limited Global Confounding via Mixture Models

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#### Problem

# Setup

- A Bayesian Network is a directed acyclic graph (DAG)  $\mathcal{G} = (\mathbf{V}, \mathbf{E})$ .
- ullet A Bayesian Network Distribution on n random variables  $\mathbf V$  is Markovian on Bayesian Network  $\mathcal G$ .
- A k-mixture of such distributions (k-MixBND) is represented using one additional vertex U with CH(U) = V.

# Task

#### Knowns:

ullet The marginal probability distribution on  ${f V}$ :  $\Pr(\mathbf{V}) = \sum \Pr(u) \Pr(\mathbf{V} \mid u)$ 

#### **Unknowns:**

- The probability distribution on U, i.e. Pr(u) for  $u \in \{1, \ldots, k\}.$
- The within source probability distribution  $\Pr(\mathbf{V} \mid u) = \mathcal{P}_u(\mathbf{V}) \text{ for } u \in \{1, \dots, k\}.$
- $\mathcal{P}_u(\mathbf{V})$  is a Bayesian network distribution, so it suffices to find  $\mathcal{P}_u(V \mid \mathbf{pa}(V))$  for all  $V \in \mathbf{V}$ , and assignments pa(V) to PA(V).

#### **Motivation**

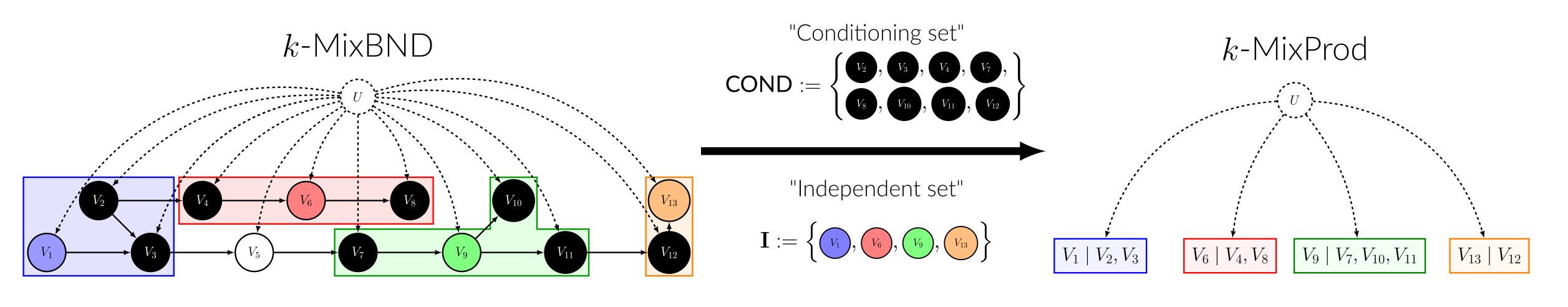
- Setting emerges when combining multiple... -Populations
  - -Environments k < observed support!-Datasets
- Graphically, the causal relationships are considered unidentifiable.
- Interventional probabilities can be calculated using the within source distributions,  $Pr(\mathbf{V} \mid u)$ .
- Solving the mixture model allows for a degree of deconfounding.

#### **Previous Work**

Using 3-independent variabls and larger alphabets (linear in k):

- E. S. Allman, 2009 use algebraic methods to exploit within-source independence.
- Anandkumar, Hsu, and Kakade, 2012 follows a similar strategy using tensor decomposition.
- Wang and Blei, 2019 introduced deconfounders using multiple causes.
- Criticized in Ogburn, Shpitser, and Tchetgen, 2019 and D'Amour, 2019
- Criticism is linked to the difference between learning parameters that generate similar statistics and identification of the true parameters.

#### Strategy



#### **Reduction to** *k***-MixProd**

- The conditional probability distribution I | COND is an instance of k-MixProd on the **independent set I**.
- We will create many such instances (called "runs") and stitch together the results. These runs will need to:
- Cover all of the variables and assignments to their parents. 2. Be alignable with eachother so their results can be synthesized.

Run *a*: 0

Run *b*: 0

Combined: 0

- Runtime of k-MixBND:  $n2^{\Delta^2}$  executions of k-MixProd where  $\Delta$  is a bound on the degree of  $\mathcal{G}$ .
- Runtime of k-MixProd:  $2^{\mathcal{O}(k^2)}n^{\mathcal{O}(k)}$  in Gordon et al., 2021 and  $2^{\mathcal{O}(k\log(k))}n^{\mathcal{O}(k)}$  in upcoming work.

#### **Difficulties**

- k-MixProd is symmetric to permutations in the labels of U. Solution: Alignment variables
- Conditioning (via post-selection) limits the variables whose information we have access to. How can we ensure we have obtained all of the necessary information?

Solution: "Good sets of runs" and alignment spanning trees

• The parameters returned from k-MixProd instances are of the form  $\mathcal{P}_u(V \mid \mathbf{mb}(V))$  -- we want them of the form  $\mathcal{P}_u(V \mid \mathbf{pa}(V))$  (which is standard for Bayesian networks).

Solution: Bayesian unzipping

# Assumptions

- 1. We have access to a k-MixProd oracle requiring O(k) variables that are independent within each source.
- 2. The observable variables in our BND are binary and discrete. Extensions exist for larger alphabets.
- 3. The mixture is supported on  $\leq k$  sources.
- 4. The underlying Bayesian DAG is sufficiently sparse.
  - The algorithm works if  $n \ge (\Delta + 1)^4 N_{\rm mp}$
- Milder requirements exist for specific graphs.
- 5. The resulting product mixtures are non-degenerate. 6. The DAG structure  $\mathcal{G}$  is known.
- Upcoming work on how to do causal discovery to learn  $\mathcal{G}$ .

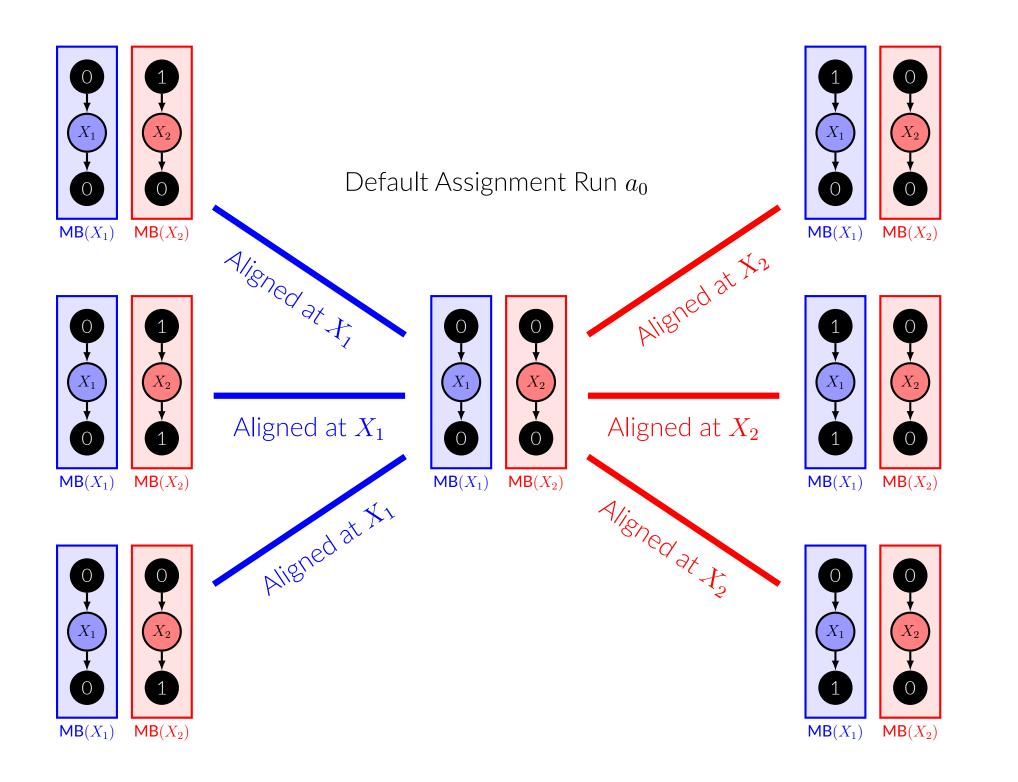
# **Alignment of Source Labels**

#### **Alignment Variables**

 $\left| \begin{array}{c|c} U^{(a)} & \mathcal{P}_{u^{(a)}}(X_1) & \mathcal{P}_{u^{(a)}}(X_2) \end{array} \right|$ 

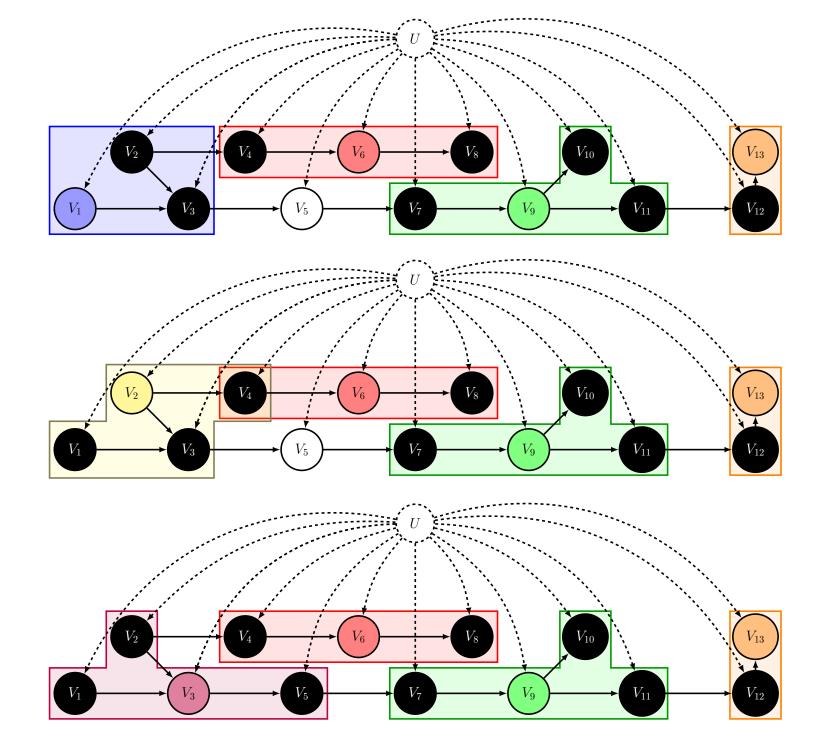
 $\left|\left.U\right|\mathcal{P}_{u}(X_{1})\right|\mathcal{P}_{u}(X_{2})\left|\left.\mathcal{P}_{u}(X_{3})\right|\right|$ 

## **Changing the Conditioned Values**



#### Change the assignments to Markov boundaries while leaving at least one assignment the same.

#### Varying the Independent Set

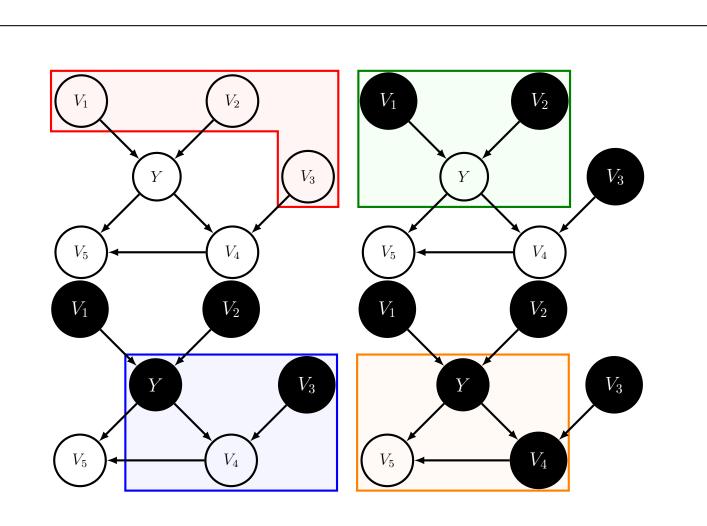


Disjoint Markov boundaries ensure that a single variable can be swapped without requiring others in the independent set to be conditioned on.

### • Runs a and b are aligned at $X_1$ , allowing $U^{(a)}$ and $U^{(b)}$ to be aligned.

■ To ensure we have a "good collection of runs," any two runs must be alignable via a chain of alignment variables - i.e. we must have an alignment spanning tree.

#### Bayesian Unzipping: From $Pr(V \mid MB(V)) \rightarrow Pr(V \mid PA(V))$



Let  $y^0$  denote ``y=0" and  $y^1$  denote ``y=1".

$$\mathcal{P}_u(y^1 \mid \mathsf{mb}(Y)) = \dfrac{\mathcal{P}_u(y^1, \mathsf{mb}(Y))}{\mathcal{P}_u(y^1, \mathsf{mb}(Y)) + \mathcal{P}_u(y^0, \mathsf{mb}(Y))}$$

We apply the standard factoring,

$$\mathcal{P}_u(y,\mathsf{mb}(Y)) = \mathcal{P}_u(v_1,v_2,v_3)\mathcal{P}_u(y\mid v_1,v_2)\mathcal{P}_u(v_4\mid y,v_3)\mathcal{P}_u(v_5\mid y,v_4),$$

to all three terms.

$$\mathcal{P}_{u}(y^{1} \mid \mathsf{mb}(Y)) = \frac{\mathcal{P}_{u}(y^{1} \mid v_{1}, v_{2})\mathcal{P}_{u}(v_{4} \mid y^{1}, v_{3})\mathcal{P}_{u}(v_{5} \mid y^{1}, v_{4})}{\mathcal{P}_{u}(y^{1} \mid v_{1}, v_{2})\mathcal{P}_{u}(v_{4} \mid y^{1}, v_{3})\mathcal{P}_{u}(v_{5} \mid y^{1}, v_{4})) + \mathcal{P}_{u}(y^{0} \mid v_{1}, v_{2})\mathcal{P}_{u}(v_{4} \mid y^{0}, v_{3})\mathcal{P}_{u}(v_{5} \mid y^{0}, v_{4})}$$

- $\mathcal{P}_u(v_1, v_2, v_3)$  appears in both numerator and
- denominator, so it cancels out. • If we traverse in reverse topological order, then
- $\mathcal{P}_u(v_4 \mid y, v_3)$  and  $\mathcal{P}_u(v_5 \mid y, v_4)$  terms are previously calculated for both  $y \in \{y^0, y^1\}$ . •  $\mathcal{P}_u(y^0 \mid v_1, v_2) + \mathcal{P}_u(y^1 \mid v_1, v_2) = 1$ , so we can solve
- for green terms. Iterating this process incurs stability costs
- proportional to the depth of the graph.
- This can be avoided by not conditioning on the children of the deepest variables in the independent set.

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