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Recall our setting

$$F(x) = (x - \lambda_1)^{n_1} \dots (x - \lambda_i)^{n_i} \dots (x - \lambda_k)^{n_k}$$

We define  $K_i(x)$  to be the **complementary factor** such that

$$F(x) = K_i(x)(x - \lambda_i)^{n_i}$$

Note that  $K_i(\lambda_i) \neq 0$ .

The symbol  $\epsilon$  represents infinitesimal (very very small) and

$$\infty := \frac{1}{\epsilon}$$

represents infinity. We are allowing arithmetic calculation with symbols  $\infty$  and  $\epsilon$  so one can talk about  $a_{-N}\infty+\cdots+a_0+a_1\epsilon+\cdots$ .

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Recall our original formula of partial fraction decomposition

$$\frac{g(x)}{F(x)} = Q(x) + \sum_{i=1}^{k} \mathsf{Const}_{\epsilon} \left( g(\lambda_i + \epsilon) \cdot \frac{1}{\epsilon^{n_i - 1}} \cdot \frac{1}{K_i(\lambda_i + \epsilon)} \cdot \frac{1}{x - \lambda_i - \epsilon} \right)$$

We may multiply F(x) on both sides and obtain

$$Q(x)F(x) + \sum_{i=1}^{k} F(x) \cdot \mathsf{Const}_{\epsilon} \left( g(\lambda_i + \epsilon) \cdot \infty^{n_i - 1} \cdot \frac{1}{K_i(\lambda_i + \epsilon)} \cdot \frac{1}{x - \lambda_i - \epsilon} \right)$$
interpolation summand

g(x) =

Why each interpolation summand a polynomial?

Since

$$F(x) = \ldots + 0\infty^2 + 0\infty + F(x) + 0\epsilon + 0\epsilon^2 + \ldots$$

, we may put F(x) inside, and note  $F(x) = (x - \lambda_i)^{n_i} K_i(x)$  write

$$\mathsf{Interpolation \ summand} = \mathsf{Const}_{\epsilon} \left( g(\lambda_i + \epsilon) \cdot \infty^{n_i - 1} \cdot \frac{\mathcal{K}_i(x)}{\mathcal{K}_i(\lambda_i + \epsilon)} \cdot \frac{(x - \lambda_i)^{n_i}}{x - \lambda_i - \epsilon} \right)$$

At this far, since x appears in denomenator, we have no idea why this is a polynomial.

However, consider

$$\mathsf{Const}_{\epsilon} \left( \underbrace{\frac{=a_0b_0K_i(x)\epsilon + *\epsilon^2 + *\epsilon^3 + \cdots}{g(\lambda_i + \epsilon) \cdot \infty^{n_i - 1} \cdot K_i(x) \cdot \underbrace{\frac{1}{K_i(\lambda_i + \epsilon)} \cdot \underbrace{\frac{\epsilon^{n_i}}{x - \lambda_i - \epsilon}}_{=b_0 + b_1\epsilon + \cdots; = \epsilon^{n_i} + \frac{\epsilon^{n_i + 1}}{x - \lambda_i} + \cdots;} \right) = 0$$

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Subtract one equation from another, you see that the whole term is indeed a polynomial.

Interpolation summand =

$$\mathsf{Const}_{\epsilon} \left( g(\lambda_i + \epsilon) \cdot \infty^{n_i - 1} \cdot \frac{K_i(x)}{K_i(\lambda_i + \epsilon)} \cdot \underbrace{\frac{(x - \lambda_i)^{n_i} - \epsilon^{n_i}}{x - \lambda_i - \epsilon}}_{\mathsf{polynomial}} \right)$$

Hint: 
$$\frac{A^{n}-B^{n}}{A-B}=A^{n-1}+A^{n-2}B+A^{n-3}B^{2}+\cdots+B^{n-1}$$

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#### **Definition** 1

Define the polynomial (involving  $\epsilon$  and  $\infty$  as coefficients)

$$f_{\lambda_i}(x) = \infty^{n_i-1} \cdot \frac{K_i(x)}{K_i(\lambda_i + \epsilon)} \cdot \frac{(x - \lambda_i)^{n_i} - \epsilon^{n_i}}{x - \lambda_i - \epsilon}$$

and call it the infinite interpolation polynomial at  $\lambda_i$  for  $F(x) = (x - \lambda_1)^{n_1} \cdots (x - \lambda_k)^{n_k}$ 

### Proposition 1

We have infinite Lagurange interpolation theroem

$$g(x) = Q(x)F(x) + \sum_{i=1}^{k} \mathsf{Const}_{\epsilon}(g(\lambda_i + \epsilon)f_{\lambda_i}(x)).$$

In the previous argument, we are using the idea that small enough scalars does not change the computation of constant part

$$\begin{aligned} \mathsf{Const}((a_n \infty^n + \ldots + a_0 + \underbrace{a_{-1}\epsilon + \ldots})(b_0 + b_1\epsilon + \ldots + b_n\epsilon^n + \underbrace{b_{n+1}\epsilon^{n+1} + \ldots})) \\ &= a_n b_n + a_{n-1}b_{n-1} + \cdots + a_0b_0. \end{aligned}$$

In other words, we do not need take care of all coefficient.

## Big O notation

To make the notation lighter, we write any terms like

$$a_n\epsilon^n + a_{n+1}\epsilon^{n+1} + a_{n+2}\epsilon^{n+2} \cdots \sim O(\epsilon^n)$$

In other words, we may write both  $\epsilon + 3\epsilon^2$  and  $\epsilon + 5\epsilon^2 + 6\epsilon^3$  as  $\epsilon + O(\epsilon^2)$ . The notation  $O(\epsilon^n)$  introduces some ambiguity.

The infinite scalar can be thought of some expression as

$$a_n \infty^n + \cdots + a_0 + O(\epsilon).$$

The multiplication of formal and infinite scalar has already determined up to  $\epsilon^n$  and nothing to do with  $\epsilon^{n+1}$ 

Const 
$$((a_n \infty^n + \cdots + a_0 + O(\epsilon))(b_0 + b_1 \epsilon + \cdots + b_n \epsilon^n + O(\epsilon^{n+1})))$$

the result has determined and has nothing to do with  $O(\epsilon)$  of first factor and  $O(\epsilon^{n+1})$  of second factor.

The big O notation follows the rule

$$O(\epsilon^n) \pm O(\epsilon^m) \sim O(\epsilon^{\min\{n,m\}})$$
 $O(\epsilon^n) \cdot O(\epsilon^m) \sim O(\epsilon^{n+m})$ 

Intuitively, we don't care  $O(\epsilon)$  since it vanishes as  $\epsilon \longrightarrow 0$ , the infinitesimal part will have no influence of the limit at all.

#### **Definition** 2

We call

$$a_{-n}\infty^n + a_{-n+1}\infty^{n-1} + \cdots + a_0 + O(\epsilon)$$

an infinite scalar, and when the context is clear, we simply write it as

$$a_{-n}\infty^n + a_{-n+1}\infty^{n-1} + \cdots + a_0$$



Each Laurent scalar corresponds to a unique infinite scalar, we denote such correspondence by

$$a_{-n}\infty^n + a_{-n+1}\infty^{n-1} + \dots + a_0 + a_1\epsilon + a_2\epsilon^2 + \dots$$

$$\equiv a_{-n}\infty^n + a_{-n+1}\infty^{n-1} + \dots + a_0 + O(\epsilon)$$

#### **Definition** 3

Two different Laurent scalars  $\alpha$ ,  $\beta$  might corresponds to the same infinite scalar. When this happens, we simply denote by  $\alpha \equiv \beta$ .

#### **Definition** 4

Further abuse the notation, no matter  $\alpha$  or  $\beta$  is infinite scalars or Laurent scalars, by  $\alpha \equiv \beta$  we always mean they are the same as infinite scalars.

$$3\infty + 2 + \epsilon \equiv 3\infty + 2 + 3\epsilon + 2\epsilon^2 \equiv 3\infty + 2 + O(\epsilon).$$

Because infinite scalars has ambiguity of  $O(\epsilon)$ , we only allow infinite scalar to add or subtract since  $O(\epsilon) \pm O(\epsilon) = O(\epsilon)$ , multiplication or division is not allowed.

Nevertheless, we can still multiply a formal scalar to an infinite scalar, the result is another infinite scalar.

$$(2+3\epsilon)(3\infty+2)\equiv 6\infty+13.$$

```
Infinite scalar + Infinite scalar \equiv Infinite scalar
   Infinite scalar - Infinite scalar \equiv Infinite scalar
 Infinite scalar \times Infinite scalar = NOT ALLOWED
 Infinite scalar \div Infinite scalar = NOT ALLOWED
   Formal scalar + Formal scalar = Formal scalar
   Formal scalar — Formal scalar — Formal scalar
   Formal scalar \times Formal scalar = Formal scalar
  Formal scalar ÷ Formal scalar = Laurent scalar
                        non-zero
   Formal scalar \times Infinite scalar \equiv Infinite scalar
 Laurent scalar ×Infinite scalar = NOT ALLOWED
that not a formal scalar
```

#### **Definition** 5

Call an infinite scalar

$$a_n \infty^n + a_{n-1} \infty^{n-1} + \cdots + a_0$$

of degree n if  $a_n \neq 0$ .

#### **Definition** 6

An infinite matrix is a matrix of infinite scalars. Define the degree of such matrix to be the maximal degree of its entries.

#### **Definition** 7

An infinite vector is a  $n \times 1$  infinite matrix.

#### **Proposition** 2

The set of  $m \times n$  infinite matrix is closed under addition, subtraction, and formal scalar multiplication. But we can not define product of two infinite matrix!

Recall the infinite interpolation formula

$$f_{\lambda_i}(x) = \infty^{n_i - 1} \cdot \frac{K_i(x)}{K_i(\lambda_i + \epsilon)} \cdot \frac{(x - \lambda_i)^{n_i} - \epsilon^{n_i}}{x - \lambda_i - \epsilon}$$
$$g(x) = Q(x)F(x) + \sum_{i=1}^k \mathsf{Const}_{\epsilon} \left( g(\lambda_i + \epsilon) \cdot f_{\lambda_i}(x) \right)$$

Let A be a matrix with F(A) = 0, we have specutral decomposition

### **Proposition** 3

$$g(A) = \sum_{i=1}^k \mathsf{Const}_\epsilon \left( g(\lambda_i + \epsilon) \cdot \mathscr{P}_{\lambda_i} \right)$$

where

$$\mathscr{P}_{\lambda_i} := f_{\lambda_i}(A)$$

#### Recall our settings

- $F(x) = (x \lambda_1)^{n_1} \cdots (x \lambda_k)^{n_k} = K_i(x)(x \lambda_i)^{n_i}$  for all i.
- F(A) = 0
- $f_{\lambda_i}(x) = \infty^{n_i 1} \cdot \frac{K_i(x)}{K_i(\lambda_i + \epsilon)} \cdot \frac{(x \lambda_i)^{n_i} \epsilon^{n_i}}{x \lambda_i \epsilon}$
- $\mathscr{P}_{\lambda_i} = f_{\lambda_i}(A)$

Our goal in this lecture:

1. We have

$$A\mathscr{P}_{\lambda_i} \equiv \mathscr{P}_{\lambda_i} A \equiv (\lambda_i + \epsilon) \mathscr{P}_{\lambda_i}$$

Later on we call such thing an **infinite eigenmatrix** of A with eigenvalue  $\lambda_i + \epsilon$ .

2. We have

$$\mathscr{P}_{\lambda_i} \equiv P_{\lambda_i} + N_{\lambda_i} + N_{\lambda_i}^2 + \dots + N_{\lambda_i}^{n_i-1} + \dots + N_{\lambda_i}^{n_i-1}$$

for some  $P_{\lambda_i}^2 = P_{\lambda_i}$ ,  $N_{\lambda_i}^{n_i} = 0$  and  $N_{\lambda_i} P_{\lambda_i} = P_{\lambda_i} N_{\lambda_i}$ . Later on, we will call such thing **infinite projection matrix**.

3. We have

$$P_{\lambda_1} + P_{\lambda_2} + \cdots + P_{\lambda_k} = I.$$

Let us prove the first, note that our goal is equivalent to show

$$(A - (\lambda_i + \epsilon)I)\mathscr{P}_{\lambda_i} \equiv \mathscr{P}_{\lambda_i}(A - (\lambda_i + \epsilon)I) \equiv 0.$$

Note that

$$\underbrace{(x - (\lambda_i + \epsilon))} \cdot \underbrace{\infty^{n_i - 1}} \cdot \underbrace{\frac{K_i(x)}{K_i(\lambda_i + \epsilon)}} \cdot \underbrace{\frac{(x - \lambda_i)^{n_i} - \epsilon^{n_i}}{x - \lambda_i - \epsilon}}$$

$$= \underbrace{\infty^{n_i - 1}} \cdot \underbrace{\frac{K_i(x) \cdot ((x - \lambda_i)^{n_i} - \epsilon^{n_i})}{K_i(\lambda_i + \epsilon)}}_{=F(x)}$$

$$= \underbrace{\infty^{n_i - 1}}_{K_i(x) \cdot (x - \lambda_i)^{n_i}} - \underbrace{\frac{\epsilon^{n_i}}{K_i(x) \cdot \infty^{n_i - 1} \cdot \epsilon^{n_i}}}_{K_i(\lambda_i + \epsilon)}$$

**Conclusion**: 
$$(x - (\lambda_i + \epsilon)) f_{\lambda_i}(x) \equiv \infty^{n_i - 1} F(x) / K_i(\lambda_i + \epsilon)$$

Since 
$$F(A) = 0$$
,  $\mathscr{P}_{\lambda_i} = f_{\lambda_i}(A)$ , plug in  $x = A$ ,

$$(A - (\lambda_i + \epsilon))f_{\lambda_i}(A) \equiv \infty^{n_i - 1}F(A)/K_i(\lambda_i + \epsilon) = \infty^{n_i - 1}0/K_i(\lambda_i + \epsilon) = 0$$
 we finish the proof.

#### **Definition** 8

We call an infinite square matrix  ${\mathscr P}$  an infinite eigenmatrix of eigenvalue  $\lambda+\epsilon$  of A if

$$A\mathscr{P} \equiv \mathscr{P}A \equiv (\lambda + \epsilon)\mathscr{P}.$$

#### **Definition** 9

We call a non-zero infinite vector  $\vec{v}$  the infinite eigenvector of eigenvalue  $\lambda + \epsilon$  if

$$A\vec{v} \equiv (\lambda + \epsilon)\vec{v}.$$

Example.

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \qquad \vec{v} \equiv \begin{pmatrix} \infty \\ 1 \end{pmatrix}$$

is an infinite eigenvector of eigenvalue  $1+\epsilon$ . Indeed

$$A\vec{v} \equiv \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \infty \\ 1 \end{pmatrix} \equiv \begin{pmatrix} \infty + 1 \\ 1 \end{pmatrix} \equiv (1 + \epsilon) \cdot \begin{pmatrix} \infty \\ 1 \end{pmatrix}$$

Infinite eigenvector are generalizations of eigenvector:



- A (classical) eigenvector is an infinite eigenvector of degree
   0.
- A constant matrix A has a non-classical infinite eigenvector of eigenvalue λ + ε (λ ∈ ℂ) if and only if it is non-digaonalizable. (Try to prove it yourself.)

### Scaling property

#### **Proposition** 4

Any formal scalar multiple of infinite eigen vector  $\mu \vec{v}$  is either zero vector or an infinite eigenvector of the same eigenvalue.

$$A\vec{v} = (\lambda + \epsilon)\vec{v} \implies A\mu\vec{v} = \mu A\vec{v} = \mu(\lambda + \epsilon)\vec{v} = (\lambda + \epsilon)\mu\vec{v}$$

Example:

$$\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \infty \\ 1 \end{pmatrix} \equiv (1+\epsilon) \begin{pmatrix} \infty \\ 1 \end{pmatrix} \qquad \text{Infinite eigenvector of degree 1}$$

$$\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \equiv (1+\epsilon) \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$
 Classical eigenvector; Infinite eigenvector of degree 0

Relation of these two infinite eigenvectors

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \equiv \underbrace{\epsilon}_{\substack{\text{formal scalar} \\ \text{scalar multiple}}} \begin{pmatrix} \infty \\ 1 \end{pmatrix}$$

The appearance of infinite eigenvectors indicates that there are multiple eigenspaces repeated to each other. And the infinite eigenvector have some cosins.

**Philosophy** Recall the theory of interpolation polynomials, the appearance of interpolation polynomial

$$f_{\lambda_i}(x) = *\infty^{n_i-1} + *\infty^{n_i-2} + \dots + *\infty + *$$

indicates the existence of repeated root of multiplicity  $n_i$ , and  $f_{\lambda_i}$  has  $n_i-1$  other cosins, when summing them up, the infinity cancels and it gives a finite value  $\mathsf{Const}(f_{\lambda_i})$ .

How to understand the infinite eigenvector? Let's introduce a variable a.

$$\begin{pmatrix} 1+a & 1 \\ 0 & 1 \end{pmatrix}$$

When a=0, the matrix is NOT diagonalizable and results an infinite eigenvector

$$\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \infty \\ 1 \end{pmatrix} = (1 + \epsilon) \begin{pmatrix} \infty \\ 1 \end{pmatrix}$$

However, when  $a \neq 0$ , the matrix is always diagonalizable and admits a spectural decomposition

$$g\begin{pmatrix}1+a&1\\0&1\end{pmatrix}=g(1+a)\begin{pmatrix}1&\frac{1}{a}\\0&0\end{pmatrix}+g(1)\begin{pmatrix}0&-\frac{1}{a}\\0&1\end{pmatrix}.$$

To visualize the change of eigenvector along a, we fix a vector and look its eigenvector decomposition (which is unique)

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} = \underbrace{\begin{pmatrix} \frac{1}{a} \\ 0 \end{pmatrix}}_{\text{eigenvalue}} + \underbrace{\begin{pmatrix} -\frac{1}{a} \\ 1 \end{pmatrix}}_{\text{eigenvalue}}$$

$$= 1 + a$$

$$= 1 + a$$

Let's visualize what happens when  $a\longrightarrow 0$  The blue vector is our fixed vector, and red vector is its decomposition as eigenvectors

This is what happend for a = 0.1



This is what happend for a = 0.05



This is what happend for a = 0.03



When a = 0, eigenvectors goes to infinities in opposite direction. But the sum of this two eigenvector is a finite vector, which is our fixed one.

The supper big red vector is described by infinite eigenvector

$$\binom{\infty}{1}$$

The sum of these two supper big eigenvector, is described as what we known as the constant part

$$\mathsf{Const}\begin{pmatrix}\infty\\1\end{pmatrix}=\begin{pmatrix}0\\1\end{pmatrix}$$

From the perspective of eigenspace, as  $a \longrightarrow 0$ , the eigenspaces are running close to each other.

This is what happend for a = 0.1

This is what happend for a = 0.05

This is what happend for a = 0.03

This is what happend for a = 0.01

We now answer the second question, determine the structure of  $\mathscr{P}_{\lambda_i}$ .

Recall that

$$f_{\lambda_i}(x) = \infty^{n_i - 1} \cdot \frac{K_i(x)}{K_i(\lambda_i + \epsilon)} \cdot \frac{(x - \lambda_i)^{n_i} - \epsilon^{n_i}}{x - \lambda_i - \epsilon},$$

and

$$\mathscr{P}_{\lambda_i} := f_{\lambda_i}(A).$$

the coefficients of  $f_{\lambda_i}$  has  $\infty$ -degree at most  $n_i - 1$ .

Therefore,  $\mathscr{P}_{\lambda_i}$  is a matrix with  $\infty$ -degree at most  $n_i-1$ , we have

$$\mathscr{P}_{\lambda_i} \equiv P_0 + N_1 \infty + N_2 \infty^2 + \ldots + N_{n_i-1} \infty^{n_i-1}$$

for some constant matrices  $P_0, N_1, \ldots, N_{n_i-1}$ . Now we determine the properties of these matrices.

Using spectral decomposition, we obtain two expressions for g(A)h(A)

$$\underbrace{\sum_{i=1}^{k} \mathsf{Const}_{\epsilon} \left( g(\lambda_i + \epsilon) \cdot h(\lambda_i + \epsilon) \cdot \mathscr{P}_{\lambda_i} \right)}_{g(A)h(A)} =$$

$$\underbrace{\left(\sum_{i=1}^{k}\mathsf{Const}_{\epsilon}\left(g(\lambda_{i}+\epsilon)\cdot\mathscr{P}_{\lambda_{i}}\right)\right)}_{g(A)}\cdot\underbrace{\left(\sum_{i=1}^{k}\mathsf{Const}_{\epsilon}\left(h(\lambda_{i}+\epsilon)\cdot\mathscr{P}_{\lambda_{i}}\right)\right)}_{h(A)}$$

Let  $\alpha, \beta$  be two arbitrary formal scalars, put

	$\lambda_1 + \epsilon$	$\lambda_2 + \epsilon$	 $\lambda_i + \epsilon$	 $\lambda_k + \epsilon$
g(x)	$0+O(\epsilon^{n_1})$	$0+O(\epsilon^{n_2})$	 $\alpha + O(\epsilon^{n_i})$	 $0+O(\epsilon^{n_k})$
h(x)	$0+O(\epsilon^{n_1})$	$0+O(\epsilon^{n_2})$	 $\beta + O(\epsilon^{n_i})$	 $0+O(\epsilon^{n_k})$
g(x)h(x)	$0+O(\epsilon^{n_1})$	$0+O(\epsilon^{n_2})$	 $\alpha\beta + O(\epsilon^{n_i})$	 $0+O(\epsilon^{n_k})$

From the table,

$$g(A) = \sum_{i=1}^{k} \mathsf{Const}_{\epsilon} (g(\lambda_i + \epsilon) \cdot \mathscr{P}_{\lambda_i}) = \mathsf{Const}_{\epsilon} (\alpha \cdot \mathscr{P}_{\lambda_i})$$

$$h(A) = \sum_{i=1}^{k} \mathsf{Const}_{\epsilon} (h(\lambda_i + \epsilon) \cdot \mathscr{P}_{\lambda_i}) = \mathsf{Const}_{\epsilon} (\beta \cdot \mathscr{P}_{\lambda_i})$$

$$g(A)h(A) = \sum_{i=1}^k \mathsf{Const}_{\epsilon} \left( g(\lambda_i + \epsilon)h(\lambda_i + \epsilon) \cdot \mathscr{P}_{\lambda_i} \right) = \mathsf{Const}_{\epsilon} \left( \alpha\beta \cdot \mathscr{P}_{\lambda_i} \right)$$

The above argument proves that

$$\mathsf{Const}_{\epsilon} \left( \alpha \cdot \mathscr{P}_{\lambda_i} \right) \mathsf{Const}_{\epsilon} \left( \beta \cdot \mathscr{P}_{\lambda_i} \right) = \mathsf{Const}_{\epsilon} \left( \alpha \beta \cdot \mathscr{P}_{\lambda_i} \right)$$

for any formal scalar  $\alpha, \beta$ .

#### **Definition** 10

We call an infinite matrix  ${\mathscr P}$  an infinite projection matrix, if

$$Const(x\mathscr{P})Const(y\mathscr{P}) = Const(xy\mathscr{P})$$

for any formal scalar x, y

#### **Definition** 11

A constant matrix P is called **projection** if  $P^2 = P$ .



To see analogue with infinite projection,  $P^2 = P$  is equivalent to (aP)(bP) = (abP).

#### **Definition** 12

A constant matrix N is called **nilpotent** if  $N^k = 0$  for some integer k.

#### Theorem 1

An infinite matrix  $\mathscr P$  of degree at most m-1 is an infinite projection matrix if and only if

$$\mathscr{P} = P + N\infty + N^2\infty^2 + \cdots + N^{m-1}\infty^{m-1}$$

with  $P^2 = P$ , PN = NP = N, and  $N^m = 0$ .

**Proof**: If  $\mathscr{P}$  is an infinite projection, assume

$$\mathscr{P} = P + N\infty + N_2 \infty^2 + \dots + N_{m-1} \infty^{m-1}$$

$$PP = \mathsf{Const}(1 \cdot \mathscr{P}) \mathsf{Const}(1 \cdot \mathscr{P}) = \mathsf{Const}(1 \cdot 1 \cdot \mathscr{P}) = P.$$

$$PN = \mathsf{Const}(1 \cdot \mathscr{P}) \mathsf{Const}(\epsilon \cdot \mathscr{P}) = \mathsf{Const}(1 \cdot \epsilon \cdot \mathscr{P}) = \mathsf{Const}(\epsilon \cdot \mathscr{P}) = N.$$

$$\mathit{NP} = \mathsf{Const}(\epsilon \cdot \mathscr{P}) \mathsf{Const}(1 \cdot \mathscr{P}) = \mathsf{Const}(\epsilon \cdot 1 \cdot \mathscr{P}) = \mathsf{Const}(\epsilon \cdot \mathscr{P}) = \mathit{N}.$$

$$N_k = \operatorname{Const}(\epsilon^k \mathscr{P}) = \operatorname{Const}(\epsilon \mathscr{P})^k = N^k \implies N_k = N^k$$
  
 $N^m = \operatorname{Const}(\epsilon \cdot \mathscr{P})^m = \operatorname{Const}(\epsilon^m \cdot \mathscr{P}) = 0.$ 

**Proof of the other direction**: Suppose  $P^2 = P$ , PN = NP = N, and  $N^m = 0$ , and

$$\mathscr{P} = P + N\infty + N^2\infty^2 + \cdots + N^{m-1}\infty^{m-1}$$

To prove

$$\operatorname{Const}(\underbrace{(a_0 + a_1 \epsilon + \ldots + O(\epsilon^m))}_{\alpha} \mathscr{P}) \operatorname{Const}(\underbrace{(b_0 + b_1 \epsilon + \ldots + O(\epsilon^m))}_{\beta} \mathscr{P})$$

$$= \operatorname{Const}(\underbrace{(a_0 + a_1 \epsilon + \ldots + O(\epsilon^m))(b_0 + b_1 \epsilon + \ldots + O(\epsilon^m))}_{\alpha\beta} \mathscr{P})$$

It suffices to prove

$$\mathsf{Const}(\epsilon^k \mathscr{P}) \mathsf{Const}(\epsilon^n \mathscr{P}) = \mathsf{Const}(\epsilon^{k+n} \mathscr{P})$$

for  $m, n \ge 0$ . This is the same as proving

$$P^{2} = P, PN^{n} = N^{n}, N^{k}P = N^{k}, N^{k}N^{n} = N^{k+n}, N^{m} = 0,$$

which is obviously true.



A classical projection is an infinite projection  $\mathscr{P} = P$ 

$$\mathscr{P} = P + N\infty + N^2 \infty^2 + \dots + N^{m-1} \infty^{m-1}$$

with the case N = 0.

Therefore, the appearence of non-zero nilpotent matrix indicates the eigenspace projection could go to infinity, making non-classical infinite eigenvectors possible, and therefore implies the matrix non-diagonalizable.

Recall that when A satisfies  $(A - \lambda_1)^{n_1} \dots (A - \lambda_k)^{n_k} = 0$ , our method to check diagonalizability of A is by checking whether

$$(A - \lambda_1) \dots (A - \lambda_k) = 0.$$

The reason behind it is because that

$$(A-\lambda_1)^{n_1}\dots(A-\lambda_k)^{n_k}=0 \ \Longrightarrow \ (A-\lambda_1)\dots(A-\lambda_k) \text{ nilpotent.}$$

Intuitively, if the nilpotent part = 0, we were in the situation that no eigenspace projection goes to infinity, and therefore the matrix is diagonalizable.

The philosophy that nilpotent matrix is the infinite part of infinite projection seems deep. Let's consider this.

It is true that

$$\frac{wv^T}{v^Tw}$$

is always a rank 1 projection matrix. What happens if  $v^T w = 0$ ? Then the denomenator is 0, the whole matrix goes to infinity. However, when  $v^T w = 0$ , the matrix  $wv^T$  must be nilpotent since

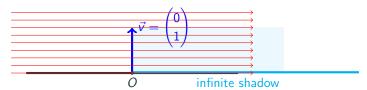
$$(wv^{T})^{2} = wv^{T}wv^{T} = w\underbrace{(v^{T}w)}_{=0}v^{T} = 0.$$

Therefore, when  $v^T w = 0$ , you may view this as a

$$\underbrace{\frac{1}{v^T w}}_{\substack{\text{scalar} \\ \text{roughly } \infty}} \cdot \underbrace{wv^T}_{\substack{\text{nilpotent matrix}}}$$

This gives you an idea why nilpotency is an inifnite part of infinite projection.

Sun set: Please visualize infinite projection  ${\mathscr P}$  in the following picture.



The vector  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  is on the groud, so its shadow is itself. We have

$$\mathscr{P}\begin{pmatrix}1\\0\end{pmatrix}=\begin{pmatrix}1\\0\end{pmatrix}$$

The vector  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$  stands up, and its shadow goes to infinity, so

$$\mathscr{P}\begin{pmatrix}0\\1\end{pmatrix}=\begin{pmatrix}\infty\\1\end{pmatrix}$$

Therefore, this infinite projection takes the form

$$\mathscr{P} = \mathscr{P} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & \infty \\ 0 & 1 \end{pmatrix} = \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}}_{\text{projection matrix}} + \infty \underbrace{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}}_{\text{nilpotent matrix}}.$$

**Excercise.** For  $\mathscr{P}_{\lambda_i} = P_{\lambda_i} + N_{\lambda_i} \infty + \ldots + N_{\lambda_i}^{n_i-1} \infty^{n_i-1}$ . What is the relation between A,  $P_{\lambda_i}$  and  $N_{\lambda_i}$ ?

**Solution.**
$$A\mathscr{P}_{\lambda_i} = (\lambda_i + \epsilon)\mathscr{P}$$

So  $(A-\lambda_i)\mathscr{P}_{\lambda_i}=\epsilon\mathscr{P}_{\lambda_i}.$  Taking the constant part on both sides,

$$(A - \lambda_i I) \mathsf{Const}(\mathscr{P}_{\lambda_i}) = \mathsf{Const}(\epsilon \mathscr{P}_{\lambda_i})$$

SO

$$(A - \lambda_i I) P_{\lambda_i} = N_{\lambda_i}$$

### Infinite eigenvector decomposition

We have left the last property

$$P_{\lambda_1} + P_{\lambda_2} + \ldots + P_{\lambda_k} = I.$$

This is easist property by taking g(x) = 1, then

$$I = g(A) = \sum_{i=1}^{k} (g(\lambda_i + \epsilon) \mathscr{P}_{\lambda_i}) = \sum_{i=1}^{k} (\mathscr{P}_{\lambda_i}) = \sum_{i=1}^{k} P_{\lambda_i}.$$

# Infinite eigenvector decomposition

#### Theorem 2

For  $(A-\lambda_1)^{n_1}...(A-\lambda_k)^{n_k}=0$ , there are infinite-matrix  $\mathscr{P}_{\lambda_i}$  with

1.  $\mathscr{P}_{\lambda_i}$  is infinite eigenmatrix of eigenvalue  $\lambda_i + \epsilon$ 

$$A\mathscr{P}_{\lambda_i} \equiv \mathscr{P}_{\lambda_i} A \equiv (\lambda_i + \epsilon) \mathscr{P}_{\lambda_i}$$

2.  $\mathcal{P}_{\lambda_i}$  is infinite projection

$$\mathscr{P}_{\lambda_i} \equiv P_{\lambda_i} + N_{\lambda_i} + N_{\lambda_i}^2 + \dots + N_{\lambda_i}^{n_i-1} + N_{\lambda_i}^{n_i-1}$$

3. We have

$$P_{\lambda_1} + P_{\lambda_2} + \dots + P_{\lambda_k} = I.$$

4. We have for any polynomial g,

$$g(A) = \sum_{i=1}^{k} \mathsf{Const}(g(\lambda_i)\mathscr{P}_{\lambda_i}).$$

# Infinite eigenvector decomposition

In this lecture, we introduce two big picture:

- Infinite eigenvector decomposition: Decomposing every vector into infinite eigenvectors.
- **Infinite eigenbasis**: Fix some infinite eigenvectors so that every vector can be represents as their linear combination.

We review eigenvector decomposition in diagonalizable cases. Let us just say a matrix

$$A = \begin{pmatrix} \lambda_1 & & & \\ & \lambda_1 & & \\ & & \lambda_2 & \\ & & & \lambda_3 \end{pmatrix}$$

with  $\lambda_1 \neq \lambda_2 \neq \lambda_3 \neq \lambda_1$ . Then every vector can be decomposed into eigenvectors of A

$$\begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} = \begin{pmatrix} a \\ b \\ 0 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ c \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \end{pmatrix}$$

$$\begin{array}{c} \text{eigenvalue} \\ = \lambda_1 \\ = \lambda_2 \\ = \lambda_3 \\ \end{array}$$

$$\begin{array}{c} \text{eigenvalue} \\ = \lambda_3 \\ \end{array}$$

This is eigenvector decomposition.

However, eigenbasis means a fixed eigen vector, and we are writing any vector into linear combination of them. For example, the list

$$\underbrace{\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}}_{\text{o}}, \qquad \underbrace{\begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}}_{\text{o}}, \qquad \underbrace{\begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}}_{\text{o}}, \qquad \underbrace{\begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}}_{\text{eigenvalue}}, \qquad \underbrace{\begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}}_{\text{eigenvalue}}, \qquad \underbrace{\begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}}_{\text{eigenvalue}}$$

is an eigenbasis and we gonna write any vector by linear combination of them

$$\begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} a + \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} b + \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} c + \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} d$$

For non-diagonalizable matrices, its anihilating polynomial have repeated roots. We imagine its roots come together as clusters.



It is hard to seperate them, so we should not consider just one eigenvalue, consider them together.

 $Let's\ come\ back\ tO\ easie R\ diAgonaliza Ble\ CAs Es$ 

In the above decomposition,

$$\begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} = \begin{pmatrix} a \\ b \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ c \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 0 \\ d \end{pmatrix}$$
eigenvalue eigenvalue eigenvalue
$$= \lambda_1 = \lambda_2$$

$$= \lambda_3$$

We can say

$$\begin{pmatrix} a \\ b \\ c \\ 0 \end{pmatrix} \qquad \mathsf{the}(\lambda_1, \lambda_2) - \mathsf{component} \qquad \begin{pmatrix} a \\ b \\ 0 \\ d \end{pmatrix} \qquad \mathsf{the}(\lambda_1, \lambda_3) - \mathsf{component}$$

$$\begin{pmatrix} 0 \\ 0 \\ c \\ d \end{pmatrix} \qquad \mathsf{the}(\lambda_2, \lambda_3) - \mathsf{component} \qquad \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} \qquad \mathsf{the}(\lambda_1, \lambda_2, \lambda_3) - \mathsf{component}$$

Note that multivalue component are no longer eigenvectors!

The idea of multi-eigenvalue component is that when eigenvalue are given

$$(\lambda_1, \lambda_2, \ldots, \lambda_n)$$

Any partitioN oF the above list would give a decomposition, where  $(\lambda_i, \lambda_j, ..., \lambda_k)$ -component means a vector  $\vec{w}$  with

$$(A - \lambda_i I)(A - \lambda_j I) \dots (A - \lambda_k I) \vec{w} = \vec{0}.$$

$$\lambda_1$$
-component means  $(A-\lambda_1I)\vec{v}=\vec{0}$   $(\lambda_1,\lambda_2)$ -component means  $(A-\lambda_1I)(A-\lambda_2I)\vec{v}=\vec{0}$ 

For 
$$\mathscr{P}_{\lambda_i} = P_{\lambda_i} + N_{\lambda_i} \infty + \ldots + N_{\lambda_i}^{n_i-1} \infty^{n_i-1}$$
.

Any classical vector  $\vec{v}$  can be decomposed into

$$\vec{v} = I\vec{v} = P_{\lambda_1}\vec{v} + P_{\lambda_2}\vec{v} + \dots + P_{\lambda_k}\vec{v}.$$

Note that

$$\begin{split} (A - \lambda_i I)^{n_i} P_{\lambda_i} &= (A - \lambda_i I)^{n_i} \mathsf{Const}(\mathscr{D}_{\lambda_i}) = \mathsf{Const}((A - \lambda_i I)^{n_i} \mathscr{D}_{\lambda_i}) \\ &= \mathsf{Const}(\epsilon^{n_i} \mathscr{D}_{\lambda_i}) = 0. \end{split}$$

Therefore,

$$P_{\lambda_i} \vec{v}$$

is an 
$$(\underbrace{\lambda_i,\lambda_i,\dots\lambda_i}_{n_i\mathsf{many}})$$
-component of  $\vec{v}$ 

Similar to diagonalizable cases, in the decomposition

$$\vec{v} = I\vec{v} = P_{\lambda_1}\vec{v} + P_{\lambda_2}\vec{v} + \dots + P_{\lambda_k}\vec{v}.$$

Each  $P_{\lambda_i} \vec{v}$  is not an eigenvector if  $n_i \geq 2$ . Instead, it represents the sum of certain eigenvectors. In the non-diagonalizable cases, it can be viewed as the sum of infinite eigenvectors, and it is finite since the infinite part has been canceled.

To decompose further, we may see

the sum of each 
$$\lambda_i$$
 – component 
$$\underbrace{P_{\lambda_i} \vec{v}}_{n_i - \text{many}} = \underbrace{Const(\underbrace{\mathscr{P}_{\lambda_i} \vec{v}}_{n_i - \text{component eigenvector}}_{\lambda_i - \text{component eigenvector}}$$
Not an eigenvector if  $n_i > 2$ 

Taking constant part of an infinite vector is analogue of summing up infinite eigenvector of **the same**, **but infinitesimally different** eigenvalues. This euqaion represents the decomposition of  $(\lambda_i, \lambda_i, \ldots, \lambda_i)$ -component to  $\lambda_i$ -component, which is a true infinite eigenvector.

Therefore, we regard

$$\vec{v} = \mathsf{Const}(\mathscr{P}_{\lambda_1}\vec{v}) + \mathsf{Const}(\mathscr{P}_{\lambda_2}\vec{v}) + \ldots + \mathsf{Const}(\mathscr{P}_{\lambda_k}\vec{v})$$

as the infinite eigenvector decomposition of any vector  $\vec{v}$ .

Review In diagonalization theory, we also have a theorem

#### Theorem 3

Suppose A is diagonalizable matrix, eigenvectors with different eigenvalues must be linearly independent.

The proof is easy, since we have spectural decomposition

$$P_{\lambda_1} + P_{\lambda_2} + \ldots + P_{\lambda_k} = I$$

Suppose  $A\vec{v}=\lambda_i\vec{v} \implies P_{\lambda_j}\vec{v}=\vec{0}$  for  $i\neq j$  because the construction of  $P_{\lambda_j}$  has the factor of  $(A-\lambda_iI)$ . Therefore only  $P_{\lambda_i}\vec{v}=I\vec{v}=\vec{v}$ .

Suppose  $\vec{v}_{\lambda_1}, \dots, \vec{v}_{\lambda_k}$  are eigenvectors of eigenvalues  $\lambda_1, \dots \lambda_k$ .

$$a_1\vec{v}_{\lambda_1}+a_2\vec{v}_{\lambda_2}+\ldots+a_k\vec{v}_{\lambda_k}=\vec{0}.$$

$$a_i \vec{v}_{\lambda_i} = P_{\lambda_i} \vec{0} = \vec{0}. \implies a_i = 0.$$

To summarise, if 
$$A\vec{v}_{\lambda_i} = \lambda_i \vec{v}_{\lambda_i}$$
, then

$$a_1 \vec{v}_{\lambda_1} + \dots + a_k \vec{v}_{\lambda_k} = \vec{0} \implies a_i \vec{v}_{\lambda_i} = \vec{0}$$
 for all  $i$ .

We carry out the similar situation.

#### Lemma 1

Suppose  $\vec{v}$  is an infinite eigenvector of A with eigenvalue  $\lambda + \epsilon$ , then

$$\mathsf{Const}(\vec{v}) = 0 \iff \vec{v} \equiv 0.$$

**Understanding(not proof)**:Const( $\vec{v}$ ) may be understood as the sum of the inifinte eigenvector with its friends, different friend have slightly different eigenvalue, so the sum is zero implies each individual is zero.

**Proof**: If  $\vec{v} \equiv 0$ , then clearly Const $(\vec{v}) = 0$ .

On the contary, suppose 
$$\vec{v} = \vec{v}_0 + \vec{v}_1 \infty + \vec{v}_2 \infty^2 + \dots$$

$$\vec{v}_0 = \mathsf{Const}(\vec{v}) = \vec{0}$$

$$\implies \vec{v}_n = \mathsf{Const}(\epsilon^n \vec{v}) = \mathsf{Const}((A - \lambda I)^n \vec{v}) = (A - \lambda I)^n \mathsf{Const}(\vec{v})$$

$$= (A - \lambda I)^n \vec{0} = \vec{0}.$$

Therefore  $\vec{v} = \vec{0} + \vec{0}\infty + \vec{0}\infty^2 + \cdots = \vec{0}$ .

Now we proceed to infinite eigenbasis.

#### **Definition** 13

An infinite eigenbasis is a list of infinite eigenvectors

$$\vec{w}_{\lambda_1,1}, \qquad \vec{w}_{\lambda_1,2} \qquad \ldots, \qquad \vec{w}_{\lambda_k,s_k},$$

such that for all classical vector  $\vec{v}$ , there exists formal scalars  $a_{\lambda_1,1},\ldots,a_{\lambda_k,s_k}$  and unique  $a_{\lambda_1,1}\vec{w}_{\lambda_1,1},\ldots,a_{\lambda_k,s_k}\vec{w}_{\lambda_k,s_k}$  such that we may represent  $\vec{v}$  as the constant part of a linear combination of fixed those vectors

$$\vec{v} = \mathsf{Const}(a_{\lambda_1,1}\vec{w}_{\lambda_1,1}) + \mathsf{Const}(a_{\lambda_1,2}\vec{w}_{\lambda_1,2}) + \ldots + \mathsf{Const}(a_{\lambda_k,s_k}\vec{w}_{\lambda_k,s_k})$$

In this part, we will give algorithm on finding those  $\vec{w}_{\lambda_1,1}$ . Again, when finding a basis, we use **cross-filling**.

We say unique  $a\vec{w}$  instead of unique a since  $\vec{w}$  is an infinite vector, and a is a formal scalar, we would view a,b equivalent when  $a\vec{w} \equiv b\vec{w}$ .

Therefore, it is more accurate to say unique  $a\vec{w}$  instead of unique a.

For examle,

$$(3+\epsilon)$$
  $\binom{\infty}{2}$   $\equiv (3+\epsilon+5\epsilon^2)$   $\binom{\infty}{2}$ 

but as a formal scalar  $3 + \epsilon \neq 3 + \epsilon + 5\epsilon^2$ .

To obtain such a basis, we apply cross-filling to the infinite matrix.

#### **Definition** 14

Let  $\vec{v}_1, \dots, \vec{v}_n$  be a list of **non-zero** infinite vectors. We say they are **linearly independent** if any linear combination of formal scalars

$$a_1\vec{v}_1 + a_2\vec{v}_2 + \cdots + a_n\vec{v}_n \equiv \vec{0}$$

implies

$$a_1\vec{v}_1 \equiv a_2\vec{v}_2 \equiv \cdots \equiv a_n\vec{v}_n \equiv 0.$$

when cross-filling infinite matrix, the cross-center must choose at the largest degree

$$\begin{pmatrix} 2\infty - 1 & 2\infty & \infty \\ \infty^2 & \infty^2 & \infty^2 \\ \infty & \infty & 1 \end{pmatrix}$$

$$= \begin{pmatrix} \infty & \infty & \infty \\ \frac{\infty^2 & \infty^2}{1} & 1 \end{pmatrix} + \begin{pmatrix} \frac{\infty - 1}{0} & \frac{\infty}{0} & 0 \\ 0 & 0 & 0 \\ \infty - 2 & \infty - 1 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

The cross cOlumns must be IInEARly iNDEpenDENt

$$egin{array}{c} \infty \ \infty^2 \ 1 \ \end{pmatrix} + a_2 egin{bmatrix} \infty \ 0 \ \infty - 1 \ \end{pmatrix} + a_3 egin{bmatrix} 0 \ 0 \ 1 \ \end{pmatrix} \equiv 0$$

by looking at the rows from the first cross center,

$$a_1 \infty^2 \equiv 0 \implies a_1 \ O(\epsilon^2) \implies a_1$$
  $\begin{bmatrix} \infty \\ \infty^2 \\ 1 \end{bmatrix} \equiv \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ 

Therefore

$$\begin{vmatrix} \infty \\ 0 \\ \infty - 1 \end{vmatrix} + a_3 \begin{vmatrix} 0 \\ 0 \\ 1 \end{vmatrix} \equiv 0$$

Looking at the first cross center

$$a_2\infty=0$$
 so

$$\begin{array}{c|c} a_2 & \infty \\ 0 \\ \infty - 1 \end{array} \equiv \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Inductively, we also show

$$a_3$$
  $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \equiv 0.$ 

This inductively shows that the cross-filling will always produce linearly independent vectors. In fact, it produces basis for the column space of the matrix.

#### **Definition** 15

For an infinite vector

$$\vec{v} = \vec{v}_0 + \vec{v}_1 \infty + \vec{v}_2 \infty^2 + \dots + \vec{v}_m \infty^m$$

we call  $\vec{v_0}$ ,  $\vec{v_1}$ , ...,  $\vec{v_m}$  its components.

#### Lemma 2

Suppose infinite vectors  $\vec{w}_1, \vec{w}_2, \dots, \vec{w}_k$  is a basis of  $\text{Im}(\mathscr{P}_{\lambda})$ , then the collection of its non-zero components is a (classical) basis of  $\text{Im}(P_{\lambda})$ .

**Proof**: Since

$$\epsilon^j \vec{w}_i \in \operatorname{Im}(\mathscr{P})$$

$$\operatorname{Const}(\epsilon^j \vec{w}_i) \in \operatorname{Im}(P).$$

Let  $e_k$  be k'th column of  $I_n$ 

$$\mathscr{P}e_k = \sum_i \sum_j a_{i,j} \epsilon^j \vec{w}_i$$

$$Pe_k = \sum_i \sum_j a_{i,j} \mathsf{Const}\left(\epsilon^j \vec{w}_i
ight)$$

Therefore, Const  $(e^j \vec{w}_i)$  spans Im(P).

Test of linearly independency. Assume  $a_{i,j}$  are constant scalars with

$$\sum_{i} \sum_{j} a_{i,j} \operatorname{Const} \left( e^{j} \vec{w}_{i} \right) = \vec{0}$$

$$\Longrightarrow \operatorname{Const} \left( \sum_{i} \sum_{j} a_{i,j} e^{j} \vec{w}_{i} \right) = \vec{0}$$

$$\Longrightarrow \sum_{i} \sum_{j} a_{i,j} e^{j} \vec{w}_{i} = \vec{0}$$

$$\Longrightarrow a_{i,j} e^{j} \vec{w}_{i} = \vec{0} \text{ by linearly independence of } \vec{w}_{i}$$

$$\Longrightarrow a_{i,j} \operatorname{Const} \left( e^{j} \vec{w}_{i} \right) = \vec{0}$$

This implies non-zero vectors in set  $\{Const(e^j \vec{w_i})\}_{i,j}$  is linearly independent.

Let  $\vec{e_i}$  be j'th column of  $I_n$ . We have

$$\mathscr{P}_{\lambda_i} \vec{e_j} = a_1 \vec{w}_1 + \ldots + a_l \vec{w}_l.$$

$$\mathsf{Const}(\mathscr{P}_{\lambda_i} \vec{e_j}) = P_{\lambda_i} \vec{e_j} = \underbrace{\mathsf{Const}(a_1 \vec{w}_1)}_{\substack{\mathsf{linear combination of } \\ \mathsf{components of } \vec{w}_1}}_{} + \ldots + \mathsf{Const}(a_l \vec{w}_l)$$

Therefore, components of  $\{\vec{w_i}\}$  forms a basis of  $P_{\lambda_i}$ 

Since  $P_{\lambda_i}$  is projection, a basis of  $Im(P_{\lambda_i})$  has  $tr(P_{\lambda_i})$  many element, denote these elements by

$$V_{\lambda_i,1},\ldots,V_{\lambda_i,\operatorname{tr}(P_{\lambda_i})}$$

It is basis, any vector of the form  $P_{\lambda_i} \vec{v}$  can be written into linear combinations of them.

Collecting all these basis across all  $\lambda_i$ ,

$$\mathscr{E} := \{v_{\lambda_1,1}, \dots, v_{\lambda_1, \operatorname{tr}(P_{\lambda_1})} v_{\lambda_i,1}, \dots, v_{\lambda_i, \operatorname{tr}(P_{\lambda_i})} \dots v_{\lambda_k,1}, \dots, v_{\lambda_k, \operatorname{tr}(P_{\lambda_k})}\}$$

Then any vector  $\vec{v}=P_{\lambda_1}\vec{v}+P_{\lambda_2}\vec{v}+\ldots+P_{\lambda_k}\vec{v}$  can be written as linear combination of them, then  $\mathscr E$  span the whole space .

Counting the element,  $\mathscr E$  has  $\operatorname{tr}(P_{\lambda_1})+\operatorname{tr}(P_{\lambda_2})+\ldots+\operatorname{tr}(P_{\lambda_k})=\operatorname{tr}(I_n)=n$  many element, the dimension of the whole space. So  $\mathscr E$  is basis . This basis is called the Canonical basis.

Using canonical basis, the matrix A is similar to Jordan canonical form. Jordan canonical form is a **block-digaonal matrix** with Jordan block

$$\begin{pmatrix} \lambda & 1 & 0 & \cdots & 0 \\ 0 & \lambda & 1 & \cdots & 0 \\ 0 & 0 & \lambda & \ddots & 0 \\ \vdots & \vdots & \vdots & \ddots & 1 \\ 0 & 0 & 0 & \cdots & \lambda \end{pmatrix}$$

The Following is a spctural decoMpositION oF JordAn cAnOnIcAL ForM

characteristic polynomial  $(t-1)^5(t-2)^2(t-3)$ 

**Excercise.** Find the matrix P such that  $P^{-1}AP$  is a Jordan Canonical form, and find this Jordan canonical form.

$$A = \begin{pmatrix} 2 & 0 & 0 & 1 \\ -2 & 2 & 2 & 5 \\ -2 & 0 & 4 & 3 \\ 1 & 0 & -1 & 1 \end{pmatrix}$$

By calculation, the characteritic polynomial is.

$$\det(tI_4 - A) = (t - 2)^3(t - 3)$$

Note , the index of t-3 implies that  $\mathcal{P}_3$  is a classical projection. We would first caluclate that by interpolation.

$$\mathscr{P}_3 = P_3 = \frac{(A-2I)^3}{(3-2)^3} = \begin{pmatrix} 1 & 0 & -1 & -1 \\ 1 & 0 & -1 & -1 \\ -1 & 0 & 1 & 1 \\ 1 & 0 & -1 & -1 \end{pmatrix}$$

This is already a rank 1 matrix.

We have no idea what  $\mathscr{P}_2$  is, let us assume

$$\mathscr{P}_2 = P_2 + N_2 \infty + N_2^2 \infty^2.$$

Use the fact that  $P_2 + P_3 = I_4$ , we know

$$P_2 = \begin{pmatrix} 0 & 0 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ 1 & 0 & 0 & -1 \\ -1 & 0 & 1 & 2 \end{pmatrix}$$

To find the nilpotent part, use that

$$A = \text{Const}((3+\epsilon)\mathscr{P}_3 + (2+\epsilon)\mathscr{P}_2) = 3P_3 + 2P_2 + N_2$$

So

$$N_2 = A - 3P_3 - 2P_2 = \begin{pmatrix} -1 & 0 & 1 & 2 \\ -3 & 0 & 3 & 6 \\ -1 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

By a simple calculation, we see

$$N_2^2=0$$

Therefore

$$\mathscr{P}_2 = \underbrace{\begin{pmatrix} 0 & 0 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ 1 & 0 & 0 & -1 \\ -1 & 0 & 1 & 2 \end{pmatrix}}_{P_2} + \infty \underbrace{\begin{pmatrix} -1 & 0 & 1 & 2 \\ -3 & 0 & 3 & 6 \\ -1 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix}}_{N_2}$$

Or we can write

$$\mathscr{P}_2 = \begin{pmatrix} -\infty & 0 & \infty + 1 & 2\infty + 1 \\ -3\infty - 1 & 1 & 3\infty + 1 & 6\infty + 1 \\ -\infty + 1 & 0 & \infty & 2\infty - 1 \\ -1 & 0 & 1 & 2 \end{pmatrix}$$

Since this is not a rank 1 matrix, we can do cross-filling decomposition

$$\begin{pmatrix} -\infty & 0 & \infty + 1 & 2\infty + 1 \\ -3\infty - 1 & 1 & 3\infty + 1 & 6\infty + 1 \\ -\infty + 1 & 0 & \infty & 2\infty - 1 \\ -1 & 0 & 1 & 2 \end{pmatrix}$$

$$= \begin{pmatrix} -\infty & 0 & \infty+1 & 2\infty+1 \\ -3\infty+2 & 0 & 3\infty+1 & 6\infty-1 \\ -\infty+1 & 0 & \infty & 2\infty-1 \\ -1 & 0 & 1 & 2 \end{pmatrix} + \begin{pmatrix} 0 & 0 & 0 & 0 \\ 3 & 1 & 0 & -2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Eigenvector of eigenvalue  $3+\epsilon$ 

$$\begin{pmatrix} 1 \\ 1 \\ -1 \\ 1 \end{pmatrix}$$

Eigenvector of eigenvalue  $2+\epsilon$ 

$$\begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \qquad \begin{pmatrix} \infty + 1 \\ 3\infty + 1 \\ \infty \\ 1 \end{pmatrix}$$

All vectors can be decomposed as

$$a_1 \begin{pmatrix} 1 \\ 1 \\ -1 \\ 1 \end{pmatrix} + a_2 \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} + \mathsf{Const} \begin{pmatrix} (a_3 + a_4 \epsilon) \begin{pmatrix} \infty + 1 \\ 3\infty + 1 \\ \infty \\ 1 \end{pmatrix} \end{pmatrix}$$

However, if we just trying to decompose vectors into only classical eigenvectors, we are making  $a_3=0$ 

$$a_1 \begin{pmatrix} 1 \\ 1 \\ -1 \\ 1 \end{pmatrix} + a_2 \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} + (0 + a_4 \epsilon) \begin{pmatrix} \infty + 1 \\ 3\infty + 1 \\ \infty \\ 1 \end{pmatrix}$$

$$a_1 \begin{pmatrix} 1 \\ 1 \\ -1 \\ 1 \end{pmatrix} + a_2 \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} + a_4 \begin{pmatrix} 1 \\ 3 \\ 1 \\ 0 \end{pmatrix}$$

Then there are not enough eigenvectors.

$$A \begin{pmatrix} 1 & 0 & 1 & 1 \\ 1 & 1 & 3 & 1 \\ -1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 1 & 1 \\ 1 & 1 & 3 & 1 \\ -1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 3 & & & \\ & 2 & & \\ & & 2 & 1 \\ & & & 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 1 & 1 \\ 1 & 1 & 3 & 1 \\ -1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix}^{-1} A \begin{pmatrix} 1 & 0 & 1 & 1 \\ 1 & 1 & 3 & 1 \\ -1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 3 & & & \\ & 2 & & \\ & & 2 & 1 \\ & & & 2 \end{pmatrix}$$

**Excercise.** Solve the differential equation

$$y' = \begin{pmatrix} 2 & 0 & 0 & 1 \\ -2 & 2 & 2 & 5 \\ -2 & 0 & 4 & 3 \\ 1 & 0 & -1 & 1 \end{pmatrix} y$$

for

$$y(0) = \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}$$

**Solution.** The solution is give by

$$y(t) = exp \begin{pmatrix} 2 & 0 & 0 & 1 \\ -2 & 2 & 2 & 5 \\ -2 & 0 & 4 & 3 \\ 1 & 0 & -1 & 1 \end{pmatrix} ty(0).$$

By spectural decomposition

$$g(3) \begin{pmatrix} 1 & 0 & -1 & -1 \\ 1 & 0 & -1 & -1 \\ -1 & 0 & 1 & 1 \\ 1 & 0 & -1 & -1 \end{pmatrix}$$

$$+ \text{Const} \begin{pmatrix} g(2+\epsilon) \begin{pmatrix} -\infty & 0 & \infty+1 & 2\infty+1 \\ -3\infty-1 & 1 & 3\infty+1 & 6\infty+1 \\ -\infty+1 & 0 & \infty & 2\infty-1 \\ -1 & 0 & 1 & 2 \end{pmatrix}$$

Note that  $e^{2t+\epsilon t} = e^{2t}(1+\epsilon t + O(\epsilon^2))$ 

Therefore

$$e^{3t}\begin{pmatrix} 1 & 0 & -1 & -1 \\ 1 & 0 & -1 & -1 \\ -1 & 0 & 1 & 1 \\ 1 & 0 & -1 & -1 \end{pmatrix}$$
 +Const 
$$\begin{pmatrix} -\infty & 0 & \infty + 1 & 2\infty + 1 \\ -3\infty - 1 & 1 & 3\infty + 1 & 6\infty + 1 \\ -\infty + 1 & 0 & \infty & 2\infty - 1 \\ -1 & 0 & 1 & 2 \end{pmatrix}$$

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where

$$\begin{aligned} & \mathsf{Const} \left( e^{(2+\epsilon)t} \begin{pmatrix} -\infty & 0 & \infty+1 & 2\infty+1 \\ -3\infty-1 & 1 & 3\infty+1 & 6\infty+1 \\ -\infty+1 & 0 & \infty & 2\infty-1 \\ -1 & 0 & 1 & 2 \end{pmatrix} \right) \\ & = e^{2t} \begin{pmatrix} 0 & 0 & 1 & 1 \\ -1 & 1 & 1 & 1 \\ 1 & 0 & 0 & -1 \\ -1 & 0 & 1 & 2 \end{pmatrix} + te^{2t} \begin{pmatrix} -1 & 0 & 1 & 2 \\ -3 & 0 & 3 & 6 \\ -1 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

So the complete solution  $e^{At}$  equals to

$$e^{3t}\begin{pmatrix}1&0&-1&-1\\1&0&-1&-1\\-1&0&1&1\\1&0&-1&-1\end{pmatrix}+e^{2t}\begin{pmatrix}0&0&1&1\\-1&1&1&1\\1&0&0&-1\\-1&0&1&2\end{pmatrix}+te^{2t}\begin{pmatrix}-1&0&1&2\\-3&0&3&6\\-1&0&1&2\\0&0&0&0\end{pmatrix}$$