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Calculation Strategy :

$$A = \begin{pmatrix} \vec{v}_1 & \vec{v}_2 & \vec{v}_3 \end{pmatrix}$$

Find orthonormal basis $\vec{u}_1, \vec{u}_2, \vec{u}_3$ such that

$$\vec{v}_1 \in \mathsf{span}\{\vec{u}_1\}$$

$$\vec{v}_2 \in \mathsf{span}\{\vec{u}_1,\vec{u}_2\}$$

$$\vec{v}_3 \in \mathsf{span}\{\vec{u}_1, \vec{u}_2, \vec{u}_3\}$$

Then

$$A = QR$$

where
$$Q = \begin{pmatrix} \vec{u_1} & \vec{u_2} & \vec{u_3} \end{pmatrix}$$

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The method: Find orthogonal basis first, then normalize it. Do not compute with unit vector.

Key formula:

Orthogonal Projection induced by a vector v: $\frac{vv^T}{v^Tv}$.

For simplicity, in test we will only test you about QR of square matrices.

Excercise.QR the following matrix

$$A = \begin{pmatrix} 1 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{pmatrix}$$

Solution.: Assume $A = \begin{pmatrix} \vec{v}_1 & \vec{v}_2 & \vec{v}_3 & \vec{v}_4 \end{pmatrix}$ We first find orthogonal vectors $\vec{w}_1, \vec{w}_2, \vec{w}_3, \vec{w}_4$

$$ec{w}_1 := ec{v}_1 = egin{pmatrix} 1 \ -1 \ 0 \ 0 \end{pmatrix}; \qquad ec{w}_1^{\mathcal{T}} ec{w}_1 = 2.$$

Now directly calculate \vec{w}_2 . A vector perpendicular to \vec{w}_1 , we consider

$$\vec{v}_2 - rac{\vec{w}_1^T \vec{v}_2}{\vec{w}_1^T \vec{w}_1} \vec{w}_1$$

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$$\vec{v}_2 - \frac{\vec{w}_1' \vec{v}_2}{\vec{w}_1'' \vec{w}_1} \vec{w}_1$$

equals to

$$\begin{pmatrix} -1\\2\\-1\\0 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1\\-1\\0\\0 \end{pmatrix} \begin{pmatrix} 1\\-1\\0\\0 \end{pmatrix} \begin{pmatrix} 1\\-1\\0\\0 \end{pmatrix}$$
$$= \begin{pmatrix} -1\\2\\-1\\0\\0 \end{pmatrix} + \frac{3}{2} \begin{pmatrix} 1\\-1\\0\\0\\0 \end{pmatrix}$$
$$\vec{v}_2 + \frac{3}{2}\vec{w}_1 = \frac{1}{2} \begin{pmatrix} 1\\1\\-2\\0 \end{pmatrix}$$

So we obtain

$$\vec{v}_2 = -\frac{3}{2}\vec{w}_1 + \frac{1}{2}\vec{w}_2$$

With

$$\vec{w}_2 = \begin{pmatrix} 1 \\ 1 \\ -2 \\ 0 \end{pmatrix}; \qquad \vec{w}_2^T \vec{w}_2 = 6.$$

Now dealing with \vec{v}_3 , Consider

$$\vec{v}_{3} - \frac{\vec{w}_{1}^{7} \vec{v}_{3}}{\vec{w}_{1}^{7} \vec{w}_{1}} \vec{w}_{1} - \frac{\vec{w}_{2}^{7} \vec{v}_{3}}{\vec{w}_{2}^{7} \vec{w}_{2}} \vec{w}_{2}$$

$$\begin{pmatrix} 0 \\ -1 \\ 2 \\ -1 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix} + \frac{5}{6} \begin{pmatrix} 1 \\ 1 \\ -2 \\ 0 \end{pmatrix} = \frac{1}{6} \begin{pmatrix} 2 \\ 2 \\ 2 \\ -6 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 1 \\ 1 \\ 1 \\ -3 \end{pmatrix}$$

So we may take

$$w_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ -3 \end{pmatrix} \qquad w_3^T w_3 = 12.$$
$$\vec{v}_3 = \frac{1}{2} w_1 - \frac{5}{6} w_2 + \frac{1}{3} w_3.$$

Use the above information fill in to the matrix, you got QR decomposition.

$$\underbrace{\begin{pmatrix} \vec{v}_1 & \vec{v}_2 & \vec{v}_3 & \vec{v}_4 \end{pmatrix}}_{A} = \underbrace{\begin{pmatrix} \vec{w}_1 & \vec{w}_2 & \vec{w}_3 & \vec{w}_4 \\ \frac{|\vec{w}_1|}{|\vec{w}_1||} & \frac{\vec{w}_2}{||\vec{w}_2||} & \frac{\vec{w}_3}{||\vec{w}_3||} & \frac{\vec{w}_4}{||\vec{w}_4||} \end{pmatrix}}_{Q} \underbrace{\begin{pmatrix} ||\vec{w}_1|| & 0 & 0 & 0 \\ 0 & ||\vec{w}_2|| & 0 & 0 \\ 0 & 0 & ||\vec{w}_3|| & 0 \\ 0 & 0 & 0 & ||\vec{w}_4|| \end{pmatrix}}_{R} \begin{pmatrix} * & * & * & * \\ 0 & * & * & * \\ 0 & 0 & * & * \\ 0 & 0 & 0 & * \end{pmatrix}}_{R}$$

Recall the notion of Jordan canonical form

$$A \underbrace{\begin{pmatrix} 1 & 2 & 3 & 1 & 4 & 1 \\ 1 & 2 & 1 & 1 & 2 & 2 \\ 4 & 1 & 2 & 0 & 1 & 3 \\ 1 & 1 & 1 & 0 & 0 & 4 \\ 0 & 0 & 0 & 1 & 0 & 5 \\ 1 & 1 & 2 & 2 & 2 & 2 \end{pmatrix}}_{P} = \underbrace{\begin{pmatrix} 1 & 2 & 3 & 1 & 4 & 1 \\ 1 & 2 & 1 & 1 & 2 & 2 \\ 4 & 1 & 2 & 0 & 1 & 3 \\ 1 & 1 & 1 & 0 & 0 & 4 \\ 0 & 0 & 0 & 1 & 0 & 5 \\ 1 & 1 & 2 & 2 & 2 & 2 \end{pmatrix}}_{P} J$$

where

$$J = \begin{pmatrix} \textcircled{1} & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 & 0 & 2 \end{pmatrix}$$

We use colors to make it more clear

$$A \begin{pmatrix} \vec{v}_1 & \vec{u}_1 & \vec{u}_2 & \vec{w}_1 & \vec{w}_2 & \vec{w}_3 \end{pmatrix}$$

$$= \begin{pmatrix} \vec{v}_1 & \vec{u}_1 & \vec{u}_2 & \vec{w}_1 & \vec{w}_2 & \vec{w}_3 \end{pmatrix} \begin{pmatrix} \begin{pmatrix} \mathbb{D} & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 & 0 & 2 \end{pmatrix}$$

Each color represents an infinite eigenvector, and those infinite eigen vectors are linearly independent.

$$A\vec{v}_{1} = (1 + \epsilon)\vec{v}_{1}$$

$$A(\vec{u}_{1}\infty + \vec{u}_{2}) = (1 + \epsilon)(\vec{u}_{1}\infty + \vec{u}_{2})$$

$$A(\vec{w}_{1}\infty^{2} + \vec{w}_{2}\infty + \vec{w}_{3}) = (2 + \epsilon)(\vec{w}_{1}\infty^{2} + \vec{w}_{2}\infty + \vec{w}_{3})$$

This is called Yang Tableau, it represents an infinite vector by its components, for example

$$\boxed{\vec{u_2} \ \vec{u_1}} = u_2 + u_1 \infty$$

We collect vectors by putting them row by row.

$$\begin{vmatrix} \vec{v_1} \\ \vec{u_2} & \vec{u_1} \end{vmatrix} = \vec{v_1} , \ \vec{u_2} + \vec{u_1} \infty$$

InfiniteEigenvectors of eigenvalue $1+\epsilon$



InfiniteEigenvectors of eigenvalue $2 + \epsilon$



Each row represents an infinite eigenvector, and corresponds to a **Jordan Block**

Now let us try to multiply formal scalar $\lambda + \epsilon$ on the infinite vector. If $\lambda \neq 0$, then

$$(\lambda) v_0 v_1 v_2 = \lambda v_0 \lambda v_1 \lambda v_2$$

However, for the case $\lambda = 0$

$$0 \overline{\begin{array}{c|c} v_0 & v_1 & v_2 \\ \hline \end{array}} = \text{Empty}$$

$$\epsilon \overline{\begin{array}{c|c} v_0 & v_1 & v_2 \\ \hline \end{array}} = \overline{\begin{array}{c|c} v_1 & v_2 \\ \hline \end{array}}.$$

One box will vanish.

If $\lambda \neq 0$, then

$$(\lambda+\epsilon)$$
 v_0 v_1 v_2 $=$ λv_0+v_1 λv_1+v_2 λv_2

Roughly speaking,

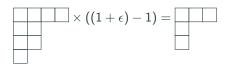
$$\begin{cases} (\lambda + \epsilon) \boxed{ } = \boxed{ } & \text{if } \lambda \neq 0 \\ (\lambda + \epsilon) \boxed{ } = \boxed{ } & \text{if } \lambda = 0 \end{cases}$$

Excercise. Suppose A is a 17×17 matrix of eigenvalue 1, 2, 3 and one have the following shape of infinite-eigenbasis of the space

Eigenvalue 1 Eigenvalue 2 Eigenvalue3

Use this diagram, describe how to calculate rank(p(A)) for any polynomial p.

If we multiply A - I, then this is the effect: Eigenvalue 1

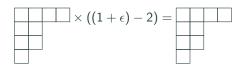


Eigenvalue 2

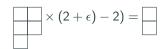
$$\times (2+\epsilon)-1)=$$

Eigenvalue3

If we multiply A - 2I, then this is the effect: Eigenvalue 1

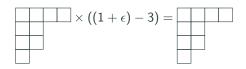


Eigenvalue 2



Eigenvalue3

If we multiply A - 3I, then this is the effect: Eigenvalue 1

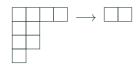


Eigenvalue 2

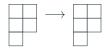
Eigenvalue3

If we multiply $(A - I)^2(A - 3I)$, then this is the effect:

Eigenvalue $1+\epsilon$



Eigenvalue $2 + \epsilon$



 $\mathsf{Eigenvalue3} + \epsilon$



Excercise. Find the Jordan form of the following matrix

$$\begin{pmatrix} 2 & 4 \\ -1 & -2 \end{pmatrix}$$

Recall if

$$\det(tI-A)=(t-\lambda_1)^{n_1}\dots(t-\lambda_k)^{n_k}$$

Then

$$g(A) = \sum_{i=1}^k \mathsf{Const}(g(\lambda_i + \epsilon)\mathscr{P}_{\lambda_i})$$

with

$$\mathscr{P}_{\lambda_i} = P_{\lambda_i} + \infty N_{\lambda_i} + \infty^2 N_{\lambda_i}^2 + \dots + \infty^{n_i - 1} N_{\lambda_i}^{n_i - 1}$$

In particular, we have

$$P_{\lambda_1} + P_{\lambda_2} + \dots P_{\lambda_k} = I$$
 ; $A = \sum_{i=1}^k (\lambda_i P_{\lambda_i} + N_{\lambda_i})$

and

$$\operatorname{tr}(P_{\lambda_i}) = n_i$$
.

A is diagonalizable \iff $N_{\lambda_i} = 0$ for all λ_i .

The best way to compute A^n and e^A is by spectural decomposition! We will only test you when A is at most 3×3 matrix.

For the following matrix

$$A = \begin{pmatrix} 1 & 1 \\ -6 & 6 \end{pmatrix}$$

Compute a formula for A^n and e^A .

We use spectural decomposition. Note that tr(A) = 7 and det(A) = 12. The characteristic polynomial is $det(tI - A) = t^2 - 7t + 12$

We have

$$\det(tI - A) = (t - 3)(t - 4).$$

By spectural decomposition

$$A = 3P_3 + 4P_4;$$
 $P_3 + P_4 = I.$

Therefore

$$P_4 = (3P_3 + 4P_4) - 3(P_3 + P_4) = A - 3I = \begin{pmatrix} -2 & 1 \\ -6 & 3 \end{pmatrix}$$

Now

$$P_3 = I - P_4 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} -2 & 1 \\ -6 & 3 \end{pmatrix} = \begin{pmatrix} 3 & -1 \\ 6 & -2 \end{pmatrix}$$

Therefore

$$A^{n} = 3^{n} P_{3} + 4^{n} P_{4} = 3^{n} \begin{pmatrix} 3 & -1 \\ 6 & -2 \end{pmatrix} + 4^{n} \begin{pmatrix} -2 & 1 \\ -6 & 3 \end{pmatrix}$$
$$e^{A} = e^{3} \begin{pmatrix} 3 & -1 \\ 6 & -2 \end{pmatrix} + e^{4} \begin{pmatrix} -2 & 1 \\ -6 & 3 \end{pmatrix}$$

Excercise. Solving the equation

$$\frac{dy}{dt} = \underbrace{\begin{pmatrix} 1 & 1 \\ -6 & 6 \end{pmatrix}}_{A} y, \qquad y(0) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

By **definition** of e^{At} , we directly have

$$y(t) = e^{At}y(0)$$

$$\begin{pmatrix} e^{3t} \begin{pmatrix} 3 & -1 \\ 6 & -2 \end{pmatrix} + e^{4t} \begin{pmatrix} -2 & 1 \\ -6 & 3 \end{pmatrix} \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$= e^{3t} \begin{pmatrix} 1 \\ 2 \end{pmatrix} + e^{4t} \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Excercise. Solving the following diffrential equation

$$\frac{dy}{dt} = \begin{pmatrix} 0 & 2 & -1 \\ -2 & 0 & -2 \\ 1 & 2 & 0 \end{pmatrix} y(t) \qquad y(0) = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

Look at this matrix, it is skew symmetric. So all its eigenvalues are purly imaginary!

Since it has 3 eigenvalues, and if z is an eignevalue, so is \overline{z} , therefore, 0 must be an eigenvalue of it! Therefore, its characteristic polynomial must be of the form

$$\det(tI - A) = (t - bi)(t + bi)t = t^3 + b^2t.$$

We have

$$b^2 = \det \begin{pmatrix} 0 & 2 \\ -2 & 0 \end{pmatrix} + \det \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} + \det \begin{pmatrix} 0 & -2 \\ 2 & 0 \end{pmatrix} = 4 + 1 + 4 = 9$$

Therefore, its eigenvalues are 0, 3i, -3i. Note that skew Hermitian matrices are normal, and therefore always diagonalizable. So, we have

$$P_0 + P_{3i} + P_{-3i} = I$$
. $3iP_{3i} + (-3i)P_{-3i} = A$.

Since A is real matrix, we must have $P_{-3i} = \overline{P_{3i}}$. We may write

$$P_{3i} = X + Yi, \qquad P_{-3i} = X - Yi$$

Therefore

$$3i(2Yi) = A \implies Y = -\frac{1}{6}A = -\frac{1}{6}\begin{pmatrix} 0 & 2 & -1 \\ -2 & 0 & -2 \\ 1 & 2 & 0 \end{pmatrix}$$

To determine X, we may calculate A^2 . Note that it must be a symmetric matrix

$$A^{2} = \begin{pmatrix} 0 & 2 & -1 \\ -2 & 0 & -2 \\ 1 & 2 & 0 \end{pmatrix} \begin{pmatrix} 0 & 2 & -1 \\ -2 & 0 & -2 \\ 1 & 2 & 0 \end{pmatrix} = \begin{pmatrix} -5 & -2 & -4 \\ -2 & -8 & 2 \\ -4 & 2 & -5 \end{pmatrix}$$

Note that
$$A^2 = (3i)^2 P_{3i} + (-3i)^2 P_{-3i} = (-9)(P_{3i} + P_{-3i})$$

So

$$X = -\frac{1}{18} \begin{pmatrix} -5 & -2 & -4 \\ -2 & -8 & 2 \\ -4 & 2 & -5 \end{pmatrix}$$

Now
$$P_0 + P_{3i} + P_{3i} = I$$
, we obtain

$$P_0 = I - 2X = \frac{1}{9} \begin{pmatrix} 4 & -2 & -4 \\ -2 & 1 & 2 \\ -4 & 2 & 4 \end{pmatrix}$$

So the spectral decomposition is

$$g\begin{pmatrix} 0 & 2 & -1 \\ -2 & 0 & -2 \\ 1 & 2 & 0 \end{pmatrix}$$

$$= g(0)\frac{1}{9}\begin{pmatrix} 4 & -2 & -4 \\ -2 & 1 & 2 \\ -4 & 2 & 4 \end{pmatrix}$$

$$+g(3i)\begin{pmatrix} -\frac{1}{18}\begin{pmatrix} -5 & -2 & -4 \\ -2 & -8 & 2 \\ -4 & 2 & -5 \end{pmatrix} - \frac{i}{6}\begin{pmatrix} 0 & 2 & -1 \\ -2 & 0 & -2 \\ 1 & 2 & 0 \end{pmatrix}$$

$$+g(-3i)\begin{pmatrix} -\frac{1}{18}\begin{pmatrix} -5 & -2 & -4 \\ -2 & -8 & 2 \\ -4 & 2 & -5 \end{pmatrix} + \frac{i}{6}\begin{pmatrix} 0 & 2 & -1 \\ -2 & 0 & -2 \\ 1 & 2 & 0 \end{pmatrix}$$

Don't be scared, if g is a real polynomial, then we may write

$$= g(0)\frac{1}{9} \begin{pmatrix} 4 & -2 & -4 \\ -2 & 1 & 2 \\ -4 & 2 & 4 \end{pmatrix}$$

$$+ \operatorname{Re} \left(g(3i) \left(-\frac{1}{9} \begin{pmatrix} -5 & -2 & -4 \\ -2 & -8 & 2 \\ -4 & 2 & -5 \end{pmatrix} - \frac{i}{3} \begin{pmatrix} 0 & 2 & -1 \\ -2 & 0 & -2 \\ 1 & 2 & 0 \end{pmatrix} \right) \right)$$

Therefore

$$e^{At} = \frac{1}{9} \begin{pmatrix} 4 & -2 & -4 \\ -2 & 1 & 2 \\ -4 & 2 & 4 \end{pmatrix} +$$

$$\operatorname{Re}\left(\left(\cos(3t) + i\sin(3t)\right)\left(-\frac{1}{9}\begin{pmatrix} -5 & -2 & -4\\ -2 & -8 & 2\\ -4 & 2 & -5 \end{pmatrix} - \frac{i}{3}\begin{pmatrix} 0 & 2 & -1\\ -2 & 0 & -2\\ 1 & 2 & 0 \end{pmatrix}\right)\right)$$

This equals to e^{At}

$$\frac{1}{9} \begin{pmatrix} 4 & -2 & -4 \\ -2 & 1 & 2 \\ -4 & 2 & 4 \end{pmatrix} - \frac{\cos(3t)}{9} \begin{pmatrix} -5 & -2 & -4 \\ -2 & -8 & 2 \\ -4 & 2 & -5 \end{pmatrix} + \frac{\sin(3t)}{3} \begin{pmatrix} 0 & 2 & -1 \\ -2 & 0 & -2 \\ 1 & 2 & 0 \end{pmatrix}$$

The solution is given by

$$y(t) = e^{At}y(0)$$

$$= \frac{1}{9} \begin{pmatrix} 4 & -2 & -4 \\ -2 & 1 & 2 \\ -4 & 2 & 4 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

$$-\frac{\cos(3t)}{9} \begin{pmatrix} -5 & -2 & -4 \\ -2 & -8 & 2 \\ -4 & 2 & -5 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + \frac{\sin(3t)}{3} \begin{pmatrix} 0 & 2 & -1 \\ -2 & 0 & -2 \\ 1 & 2 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

$$= \frac{1}{3} \begin{pmatrix} -4 \\ 2 \\ 4 \end{pmatrix} + \frac{\cos(3t)}{3} \begin{pmatrix} -7 \\ -4 \\ -5 \end{pmatrix} + \frac{\sin(3t)}{3} \begin{pmatrix} 1 \\ -8 \\ 5 \end{pmatrix}$$



In general, if AB = BA, then $e^A e^B = e^{A+B}$. If A is a skew Hermitian matrix, then e^A is always unitary, indeed.

$$e^{A}(e^{A})^{H} = e^{A}e^{A^{H}} = e^{A+A^{H}} = e^{0} = I.$$

Therefore, for skew symmetric real matrices $A = -A^T$, the system y' = Ay always represents rotation.

For 3×3 matrix. It is easier if it is diagonalizable and have repeated roots.

Excercise. Consider the following matrix

$$A = \begin{pmatrix} 2 & 2 & 3 \\ 2 & 5 & 6 \\ 3 & 6 & 10 \end{pmatrix}$$

Find a unitary matrix U such that U^HAU is diagonal.

Suppose one find the characteristic polynomial $\det(tI-A)=(t-1)^2(t-15)$

The eigenvalue $1+\epsilon$ is suspicious, We find

$$rank(A - I) = rank \begin{pmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 9 \end{pmatrix} = 1$$

This implies the Yang tableau of eigenvalue $1+\epsilon$ looks like



This means all its eigenvectors of $1+\epsilon$ are finite. Therefore A is diagonalizable. By spectural decomposition,

$$A = P_1 + 15P_{15}$$
 , $P_1 + P_{15} = I$ $\operatorname{tr}(P_1) = 2$, $\operatorname{tr}(P_{15}) = 1$

Therefore,

$$A - I = (P_1 + 15P_1) - (P_1 + P_{15}) = 14P_{15}$$

So

$$P_{15} = \frac{1}{14}(A - I) = \frac{1}{14} \begin{pmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 9 \end{pmatrix}$$

and

$$P_1 = I - P_{15} = \frac{1}{14} \begin{pmatrix} 13 & -2 & -3 \\ -2 & 10 & -6 \\ -3 & -6 & 5 \end{pmatrix}$$

The eigenspace of eigenvalue 15 is 1-dimensional and for eigenvalue 1 is 2-dimensional.

, From here we already have

$$A^{n} = \frac{1}{14} \begin{pmatrix} 13 & -2 & -3 \\ -2 & 10 & -6 \\ -3 & -6 & 5 \end{pmatrix} + \frac{15^{n}}{14} \begin{pmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 9 \end{pmatrix}$$

and

$$e^{At} = \frac{e^t}{14} \begin{pmatrix} 13 & -2 & -3 \\ -2 & 10 & -6 \\ -3 & -6 & 5 \end{pmatrix} + \frac{e^{15t}}{14} \begin{pmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 9 \end{pmatrix}$$

The above formula enable us to do other exercises, but in this question we particularly need diagoanalization.



In most applicational problems, spectural decomposition is sufficient, one need not to diagonalize a matrix. Diagonalization is useful only when you wanna decompse matrix.

We already have $Col(P_{15}) \perp Col(P_1)$. But we need orthogonal basis in P_1 also. For this purpose, we use **diagonal cross filling**. It is up to you

$$\begin{pmatrix} 13 & -2 & -3 \\ -2 & 10 & -6 \\ -3 & -6 & 5 \end{pmatrix} = \begin{pmatrix} 0.4 & -2 & 1.2 \\ -2 & 10 & -6 \\ 1.2 & -6 & 3.6 \end{pmatrix} + \begin{pmatrix} 12.6 & 0 & -4.2 \\ 0 & 0 & 0 \\ -4.2 & 0 & 1.4 \end{pmatrix}$$

Using this, we obtain an ortho, but not yet normal eigenvectors!

$$\underbrace{\begin{pmatrix}1\\2\\3\end{pmatrix}}_{15},\underbrace{\begin{pmatrix}-1\\5\\-3\end{pmatrix}}_{1},\underbrace{\begin{pmatrix}-3\\0\\1\end{pmatrix}}_{1}$$



We only need corss-filling for eigenvalues shown as repeated roots. The difference between unitary diagonalization and typical diagonalization is that unitary diagonalization you choose diagonal as center, but general diagonalization you do not have to.

Now the length of it is

$$\underbrace{\begin{pmatrix}1\\2\\3\end{pmatrix}}_{\sqrt{14}},\underbrace{\begin{pmatrix}-1\\5\\-3\end{pmatrix}}_{\sqrt{35}},\underbrace{\begin{pmatrix}-3\\0\\1\end{pmatrix}}_{\sqrt{10}}$$

Collecting these as

$$U = \begin{pmatrix} \frac{1}{\sqrt{14}} & \frac{-1}{\sqrt{35}} & \frac{-3}{\sqrt{10}} \\ \frac{2}{\sqrt{14}} & \frac{5}{\sqrt{35}} & \frac{0}{\sqrt{10}} \\ \frac{3}{\sqrt{14}} & \frac{-3}{\sqrt{35}} & \frac{1}{\sqrt{10}} \end{pmatrix}$$

$$AU = U \begin{pmatrix} 15 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \implies U^{H}AU = \begin{pmatrix} 15 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

The most important is to determine P_{λ} and N_{λ} for each eigenvalue λ .

Excercise. For the following matrix A, try to solve A^n and e^A

$$A = \begin{pmatrix} 0 & -1 & -2 \\ 1 & 2 & 2 \\ 0 & 0 & 1 \end{pmatrix}$$

We have

$$\det(\lambda I - A) = (\lambda - 1)^3.$$

So $P_1 = I$,

$$A=1\cdot P_1+N_1$$

Therefore

$$N_1 = \begin{pmatrix} -1 & -1 & -2 \\ 1 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

You observe that

$$rank(N_1) = rank(A - I) = 1$$

Therefore, its Yang tableau must be the form



This implies $N_1^2 = 0$ Therefore

$$g(A) = \mathsf{Const}\left(g(1+\epsilon)\left(\mathit{I}_{3} + \infty \mathit{N}_{1}\right)\right)$$

For
$$A^n$$
, we have $(1+\epsilon+O(\epsilon))^n=1+n\epsilon+O(\epsilon)$

$$A^n = \mathsf{Const}\left(\left(1 + n\epsilon\right)\left(I_3 + \infty N_1\right)\right)$$

$$A^n = I_3 + nN_1$$

And for e^{At} , we note that

$$e^{(1+\epsilon)t} = e^t e^{\epsilon t} = e^t (1+\epsilon t + O(\epsilon))$$

Therefore

$$e^{At} = e^{t} P_{1} + t e^{t} N_{1}$$

$$= e^{t} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + t e^{t} \begin{pmatrix} -1 & -1 & -2 \\ 1 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

Do the same problem with

$$A = \begin{pmatrix} -6 & -5 & -1 \\ 10 & 8 & 1 \\ -2 & -1 & 2 \end{pmatrix}$$

Suppose you know eigenvalue are 1 and 2.

Solution. From here we know the characteristic polynomial is given by

$$\det(tI - A) = (t - 1)^2(t - 2)$$

Therefore, the spectural decomposition is

$$g(A) = \operatorname{Const}(g(1+\epsilon)(P_1 + N_1\infty)) + g(2)P_2.$$

To detect each matrix. Note that

	$1+\epsilon$	2
$(t-1)^2$	$0+O(\epsilon)$	1

Therefore

$$P_2 = (A - I)^2$$

Note that $tr(P_2) = rank(P_2)$ is the multiplicity of 2, so $rank(P_2) = 1$. So $(A - I)^2$ will be a rank 1 trace 1 matrix

$$A - I = \begin{pmatrix} -7 & -5 & -1 \\ 10 & 7 & 1 \\ -2 & -1 & 1 \end{pmatrix}$$

$$(A-I)^2 = \begin{pmatrix} 1 & 1 & 1 \\ -2 & -2 & -2 \\ 2 & 2 & 2 \end{pmatrix}$$

This implies that

$$P_1 = \begin{pmatrix} 0 & -1 & -1 \\ 2 & 3 & 2 \\ -2 & -2 & -1 \end{pmatrix}$$

Note that

$$A = P_1 + N_1 + 2P_2 = I + P_2 + N_1$$

This implies that

$$N_{1} = A - I - P_{2}$$

$$= \begin{pmatrix} -7 & -5 & -1 \\ 10 & 7 & 1 \\ -2 & -1 & 1 \end{pmatrix} - \begin{pmatrix} 1 & 1 & 1 \\ -2 & -2 & -2 \\ 2 & 2 & 2 \end{pmatrix}$$

$$= \begin{pmatrix} -8 & -6 & -2 \\ 12 & 9 & 3 \\ -4 & -3 & -1 \end{pmatrix} \neq 0$$

Therefore, its Yang tableau must be of this form

Eigenvalue $1 + \epsilon$:

Eigenvalue $2 + \epsilon$:

This means all columns of \mathscr{P}_1 must be colinear to each other, we do not need cross-filling

$$\mathcal{P}_1 = \begin{pmatrix} -8\infty & -6\infty - 1 & -2\infty - 1 \\ 12\infty + 2 & 9\infty + 3 & 3\infty + 2 \\ -4\infty - 2 & -3\infty - 2 & -\infty - 1 \end{pmatrix}$$

So we may take any column of \mathscr{P}_1 to be infinite eigenvector, we take half of the first column

$$\begin{pmatrix} -4\infty \\ 6\infty + 1 \\ -2\infty - 1 \end{pmatrix}$$

We can write it as

$$\begin{pmatrix} 0\\1\\-1 \end{pmatrix} + \begin{pmatrix} -4\\6\\-2 \end{pmatrix} \infty$$

$$\begin{array}{|c|c|c|c|}
\hline
\begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} & \begin{pmatrix} -4 \\ 6 \\ -2 \end{pmatrix}
\end{array}$$

Now

$$P_2 = \begin{pmatrix} 1 & 1 & 1 \\ -2 & -2 & -2 \\ 2 & 2 & 2 \end{pmatrix}$$

Take any problem of P_2 we obtain eigenvector

$$\begin{pmatrix} 1 \\ -2 \\ 2 \end{pmatrix}$$

The Jordan canonical form, is

$$A = \begin{pmatrix} 1 & -4 & 0 \\ -2 & 6 & 1 \\ 2 & -2 & -1 \end{pmatrix}^{-1} \begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \underbrace{\begin{pmatrix} 1 & -4 & 0 \\ -2 & 6 & 1 \\ 2 & -2 & -1 \end{pmatrix}}_{P}$$