

Curriculum Vitae

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QUALIFICATIONS

Expected time for earning a PhD degree: 12/2023.

10/2022-Present Visiting PhD Student in Mechanical Engineering, The University of Auckland, New Zealand.
09/2018-Present Master and PhD Student in Mechanical Engineering, (Successive Master-Doctor Program),
Shanghai University, China.
09/2014-07/2018 Bachelor of Mechanical Engineering (Honours), Qingdao University of Science and
Technology, China.

SIGNIFICANT DISTINCTIONS

- Outstanding graduate, 10%, 2018, Qingdao University of Science and Technology, China
- First-class scholarship, 20%, 2019, 2020 and 2021, Shanghai University, China
- "FangYao" scholarship, $\approx 1\%$, 2021, Shanghai University, China

RESEARCH TOPICS

- Application of **artificial intelligence algorithms** to enhance pre-welding feature recognition.
- Development of **integrated vision sensors and software** to upgrade robotic welding.
- Construction of **a cloud-based pre-welding monitor system** to serve laser welding digital transformation.

REPRESENTATIVE PUBLICATIONS

- [1] (Under Review) **H. Liu**, Y. Tian, Y. Lu, J. Feng, T. Wang, L. Li, & M. Jiang. A systematic framework for tackling anomalous pre-welding workpiece postures with regular butt joints based on prototype features. *Journal of Manufacturing Systems*. (CiteScore:**16.0**, Impact Factor:**12.1**, Top Journal).
- [2] **H. Liu**, Y. Tian, L. Li, Y. Lu, J. Feng, & F. Xi, (2023). Full-cycle data purification strategy for multi-type weld seam classification with few-shot learning. *Computers in Industry*, 150, 103939. Doi: [10.1016/j.compind.2023.103939](https://doi.org/10.1016/j.compind.2023.103939), (CiteScore:**21.1**, Impact Factor:**10.0**, Top Journal).
- [3] **H. Liu**, Y. Tian, L. Li, Y. Lu, & F. Xi, (2023). One-shot, integrated positioning for welding initial points via co-mapping of cross and parallel stripes. *Robotics and Computer-Integrated Manufacturing*, 84, 102602. Doi: [10.1016/j.rcim.2023.102602](https://doi.org/10.1016/j.rcim.2023.102602), (CiteScore:**20.1**, Impact Factor:**10.4**, Top Journal).
- [4] Y. Tian, **H. Liu**, L. Li, W. Wang, J. Feng, F. Xi, & G. Yuan, (2020). Robust identification of weld seam based on region of interest operation. *Advances in Manufacturing*, 8, 473-485. Doi: [10.1007/s40436-020-00325-y](https://doi.org/10.1007/s40436-020-00325-y), (CiteScore:**7.1**, Impact Factor:**5.2**).
- [5] Y. Tian, **H. Liu**, L. Li, G. Yuan, J. Feng, Y. Chen, & W. Wang, (2020). Automatic identification of multi-type weld seam based on vision sensor with silhouette-mapping. *IEEE Sensors Journal*, 21(4), 5402-5412. Doi: [10.1109/JSEN.2020.3034382](https://doi.org/10.1109/JSEN.2020.3034382), (CiteScore:**7.0**, Impact Factor:**4.3**).

PROJECT CONTRIBUTION

- [1] Key Technology Research and Demonstration Line Construction of Advanced Laser Intelligent Manufacturing Equipment from Shanghai Lingang Area Development Administration. (Pre-welding system development)
- [2] Fully Automated Nucleic-acid Sampling Robot Development of Shanghai University. (Facial feature extraction and localization)
- [3] Terrazzo Grain Feature Extraction and Analysis System. (Grain feature extraction and analysis)

**Above data updated to August 2023.*