# **Greedy Algorithms**

Bin Wang

School of Software Tsinghua University

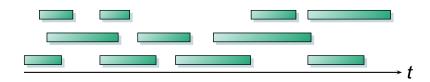
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### **Outline**

- An activity-selection problem
- Elements of the greedy strategy
- Huffman codes
- Matroids
- A task-scheduling problem

#### **Problem**

Scheduling several competing activities with a goal of selecting a maximum-size set of mutually compatible activities.



#### **Mathematical illustration**

- Suppose we have a set  $S = \{a_1, a_2, \dots, a_n\}$  of n proposed **activities**.
- Each activity  $a_i$  has a **start time**  $s_i$  and a **finish time**  $f_i$ , where  $0 < s_i < f_i < \infty$ .
- Activities  $a_i$  and  $a_j$  are **compatible** if  $s_i \ge f_j$  or  $s_i \ge f_i$ .

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#### **Mathematical illustration**

 To select a maximum-size subset of mutually compatible activities.

										9		
•	Si	1	3	0	5	3	5	6	8	8	2	12
	$f_i$	4	5	6	7	8	9	10	11	12	13	14

### Step1: optimal substructure

- Making a choice: Suppose a<sub>k</sub> is one of the activities selected.
- Space of subproblems:
  - 1. The activities before  $a_k$  starts.
  - 2. The activities after a finishes.

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### Step1: optimal substructure

• Can we combine the solution of subproblems into the solution of original problem?

Let us start by defining sets

$$S_{ij} = \{a_k \in S : f_i \le s_k < f_k \le s_j\},$$

### Step1: optimal substructure

•  $S_{ij}$  is the sub set of activities in S that start after activity  $a_i$  finishes and finish before activity  $a_j$  starts. Add  $f_0 = 0$  and  $s_{n+1} = \infty$ , then  $S = S_{0,n+1}$ . Suppose a solution to  $S_{ij}$  includes some activity  $a_k$ , so that  $f_i \leq s_k < f_k \leq s_j$ , then we get two subproblems,  $S_{ik}$  and  $S_{ki}$ .

### Step1: optimal substructure

Optimal Substructure: Suppose now that an optimal solution A<sub>ij</sub> to S<sub>ij</sub> includes activity a<sub>k</sub>. Then the solutions A<sub>ik</sub> to S<sub>ik</sub> and A<sub>kj</sub> to S<sub>kj</sub> used within this optimal solution to S<sub>ij</sub> must be optimal as well.

$$A_{ii} = A_{ik} \cup \{a_k\} \cup A_{ki}.$$

#### A recursive solution

Let c[i, j] be the number of activities in a maximum size subset of mutually compatible activities in  $S_{ij}$ .

$$c[i,j] = \begin{cases} 0 & \text{if } S_{ij} = \emptyset, \\ \max_{i \leq k \leq j} \{c[i,k] + c[k,j] + 1\} & \text{if } S \neq \emptyset. \end{cases}$$

# Converting a DM solution to a greedy one

#### Theorem 16.1

Consider any  $S_k \neq \emptyset$ , where

 $S_k = \{a_i \in S : s_i \ge f_k\}$ . Let  $a_m$  be the activity in  $S_k$  with the **earliest** finish time.

Then  $a_m$  is used in some maximum-size subset of mutually compatible activities of  $S_k$ .

# Converting a DM solution to a greedy one

#### Proof.

Suppose that  $A_k$  is a maximum-size subset of mutually compatible activities of  $S_k$ . Let  $a_j$  be the first activity in  $A_k$ . If  $a_j = a_m$ , we are done. If  $a_j \neq a_m$ , we construct the subset  $A'_k = \{A_k - \{a_j\}\} \cup \{a_m\}$ .  $A'_k$  is a maximum-size subset of mutually compatible activities of  $S_k$  that includes  $a_m$ .

# Converting a DM solution to a greedy one

### Why is Theorem 16.1 valuable?

Reduce the space of subproblems

- Only one subproblem is used in an optimal solution.
- We need consider only one choice when solving the subproblem.

# A recursive greedy algorithm

```
RECURSIVE-ACTIVITY-SELECTOR(s, f, k, n)
```

```
1 m = k + 1
2 while m \le n and s[m] < f[k] // find the first activity in S_k to finish
```

- 3 m = m + 1
- 4 if m < n
- 5 return  $\{a_m\} \cup$

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6 else return ∅

Running time

 $\Theta(n)$ 

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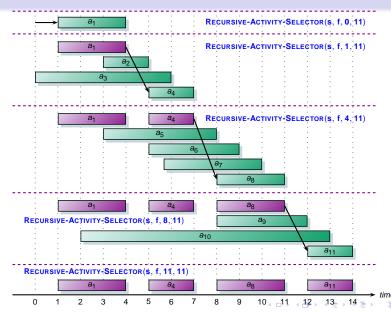
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### **Running time**

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### RECURSIVE-ACTIVITY-SELECTOR



## An iterative greedy algorithm

```
GREEDY-ACTIVITY-SELECTOR(s, f)
```

```
1  n = s.length

2  A = \{a_1\}

3  k = 1

4  for m = 2 to n

5  if s[m] \ge f[k]

6  A = A \cup \{a_m\}

7  k = m

8  return A
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### Steps of greedy algorithms

- Cast the optimization problem as one in which we make a choice and are left with one subproblem to solve.
- Prove that there is always an optimal solution to the original problem that makes the greedy choice, so that the greedy choice is always safe.

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### Steps of greedy algorithms

3. Demonstrate that, having made the greedy choice, what remains is a subproblem with the property that if we combine an optimal solution to the subpoblem with the greedy choice we have made, we arrive at an optimal solution to the original problem.

## **Greedy vs Dynamic programming**

### **Greedy-choice property**

- A globally optimal solution can be arrived at by making a locally optimal (greedy) choice.
- In other words, when we are considering which choice to make, we make the choice that looks best in the current problem, without considering results from subproblems.

## **Greedy vs Dynamic programming**

### **Greedy vs Dynamic programming**

- Dynamic programming solves the subproblems bottom up, a greedy strategy progresses in a top-down fashion.
- Greedy is more efficient.
- Dynamic programming is more powerful, greedy is a special case of Dynamic programming.

#### 0-1 knapsack problem

Given n items, the ith item is worth  $v_i$  dollars and weights  $w_i$  pounds, where  $v_i$  and  $w_i$  are integers. Give a knapsack with capacity W pounds, how to get a load with most valuable items?

Fractional knapsack problem

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### 0-1 knapsack problem

If we remove item j from this load, the remaining load must be at most valuable items weighing at most  $W - w_j$  from n - 1 items.

### Fractional knapsack problem

If we remove a weight w of one item j from the optimal load, then the remaining load must be the most valuable load weighing at most W-w that can be taken from the n-1 original items plus  $w_i-w$  pounds of item j.

### 0-1 knapsack problem

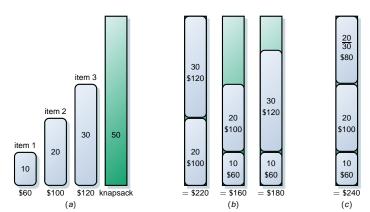
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# An example

Fractional knapsack problem is solvable by a greedy strategy, whereas the 0-1 problem is not.



### **Overview**

## Binary character code

A variable-length code can do considerably better than a fixed-length code.

## Prefix(-free) codes

The codes in which no codeword is also a prefix of some other codeword.

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### **Overview**

### **Huffman codes**

- Huffman codes are a widely use and very effective technique for compressing data: saving of 20% to 90% are typical, depending on the characteristics of the data being compressed.
- Huffman codes give frequent characters short codewords and infrequent characters long codewords.

# An Example

	а	b	С	d	е	f
Frequency	45	13	12	16	9	5
Fixed-length	000	001	010	011	100	101
Variable-length	0	101	100	111	1101	1100

# An Example

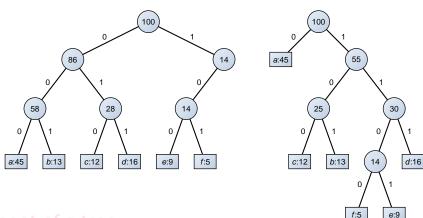
If each character is assigned a 3-bit codeword the file can be encoded in 300,000 bits.

Using the variable-length code shown, the file can be encoded in

$$(45 \cdot 1 + 13 \cdot 3 + 12 \cdot 3 + 16 \cdot 3 + 9 \cdot 4 + 5 \cdot 4) \cdot 1000 = 224,000$$
 bits.

Example: 001011101 parses uniquely as 0.0.101.1101, which decodes to *aabe* 

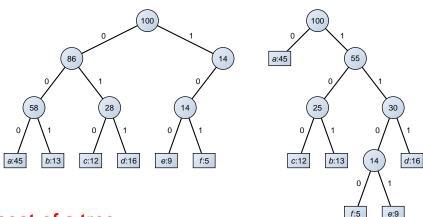
# Trees corresponding to the example



#### cost of a tree:

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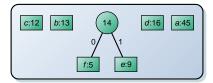
$$B(T) = \sum_{c \in C} c.freq \cdot d_T(c), d_T(c)$$
: depth.

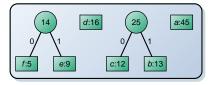
# **Constructing a Huffman code**

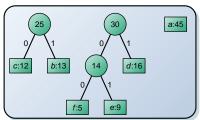
```
Huffman(C)
1 n = |C|
Q = C
  for i = 1 to n - 1
4
       allocate a new node z
5
       z.left = x = Extract-Min(Q)
6
       z.right = y = EXTRACT-MIN(Q)
       z.freq = x.freq + y.freq
8
        INSERT(Q, z)
9
   return EXTRACT-MIN(Q)
```

# The steps of Huffman's algorithm

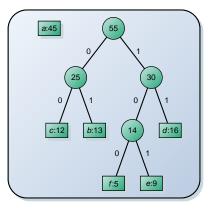


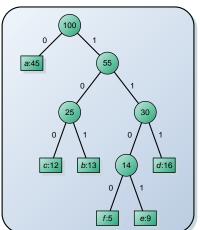






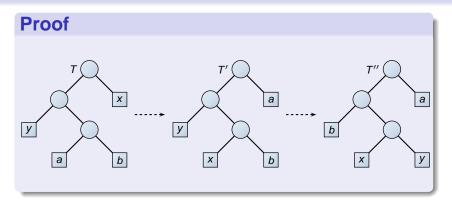
## The steps of Huffman's algorithm





#### **Lemma 16.2**

Let C be an alphabet in which each character  $c \in C$  has frequency c.freq. Let x and y be two characters in C having the lowest frequencies. Then there exists an optimal prefix code for C in which the codewords for x and y have the same length and differ only in the last bit.



$$B(T) - B(T')$$

$$= \sum_{c \in C} c.freq \cdot d_T(c) - \sum_{c \in C} c.freq \cdot d_{T'}(c)$$

$$= x.freq \cdot d_T(x) + a.freq \cdot d_T(a)$$

$$- x.freq \cdot d_{T'}(x) - a.freq \cdot d_{T'}(a)$$

$$= x.freq \cdot d_T(x) + a.freq \cdot d_T(a)$$

$$- x.freq \cdot d_T(a) - a.freq \cdot d_T(x)$$

$$= (a.freq - x.freq)(d_T(a) - d_T(x))$$

$$> 0$$

#### **Lemma 16.3**

Let  $C' = \{C - \{x, y\}\} \cup \{z\}$ , where z.freq = x.freq + y.freq. Let T' be any tree representing an optimal prefix code for the alphabet C'. Then the tree T, obtained from T' by replacing the leaf node for z with an internal node having x and y as children, represents an optimal prefix code for the alphabet C.

#### **Proof**

We first show that the cost B(T) of tree T can be expressed in terms of the cost B(T') of tree T'. For each  $c \in C - \{x, y\}$ , we have  $d_T(c) = d_{T'}(c)$ , and hence  $c.freq \cdot d_T(c) = c.freq \cdot d_{T'}(c)$ . Since  $d_T(x) = d_T(y) = d_{T'}(z) + 1$ , we have  $x.freq \cdot d_T(x) + y.freq \cdot d_T(y)$ 

$$x.freq \cdot d_T(x) + y.freq \cdot d_T(y)$$
  
=  $(x.freq + y.freq)(d_{T'}(z) + 1)$   
=  $z.freq \cdot d_{T'}(z) + (x.freq + y.freq)$ 

#### **Proof**

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#### **Proof**

from which we conclude that

$$B(T) = B(T') + x.freq + y.freq$$

Suppose that T does not represent an optimal prefix code for c. Then there exists a tree T'' such that B(T'') < B(T). T'' has x and y as siblings. Let T''' be the tree T'' with the common parent of x and y replaced by a leaf z with frequency z. freq = x. freq + y. freq.

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#### Proof.

Then

$$B(T''') = B(T'') - x.freq - y.freq$$
  
 $< B(T) - x.freq - y.freq$   
 $= B(T')$  Contradiction!



#### Theorem 16.4

Procedure HUFFMAN produces an optimal prefix code.

#### Proof.

Immediate from Lemmas 16.2 and 16.3.



## **History**

- The concept of a (finite) matroid was introduced by Hassler Whitney in 1935 in his paper "On the abstract properties of linear dependence".
- In 1971, Jack Edmonds connected weighted matroids to greedy algorithms in his paper "Matroids and the greedy algorithm".

## **History**

• In the early of 1980's, Korte and Lovász generalized these ideas to objects called greedoids, which allow even larger classes of problems to be solved by greedy algorithms.

### **Definition**

A *matroid* is an ordered pair  $M = (S, \mathcal{I})$  satisfying the following conditions.

- S is a finite nonempty set.
- $\mathcal{I}$  is **hereditary**:  $\mathcal{I}$  is a nonempty family of subsets of S, called the **independent** subsets of S, such that if  $B \in \mathcal{I}$  and  $A \subseteq B$ , then  $A \in \mathcal{I}$ . Obviously,  $\emptyset$  is a member of  $\mathcal{I}$ .

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#### **Definition**

• If  $A \in \mathcal{I}$ ,  $B \in \mathcal{I}$ , and |A| < |B|, then there is some element  $x \in B - A$  such that  $A \cup \{x\} \in \mathcal{I}$ . We say that M satisfies the exchange property.

### **Graphic matroid**

Given an undirected graph G = (V, E), the *graphic matroid* is defined as follows.

- The set  $S_G$  is defined to E, the set of edges of G.
- If A is a subset of E, the  $A \in \mathcal{I}_G$  if and only if A is acyclic. That is, a set of edges A is independent if and only if the subgraph  $G_A = (V, A)$  forms a forest.

#### Theorem 16.5

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- I<sub>G</sub> is hereditary, since a subset of a forest is a forest.

- Exchange property:
  - Suppose that  $G_A = (V, A)$  and  $G_B = (V, B)$  are forests of G and that |B| > |A|.
  - Thus, forest  $G_A$  contains |V| |A| trees which is more than |V| |B| trees of  $G_B$ .
  - So, G<sub>B</sub> must contain some tree T whose vertices are in two different trees in forest G<sub>A</sub>.
  - Moreover, since T is connect, there must be an edge (u, v) s.t. u and v are in different trees in  $G_A$ . x = (u, v) can be added to  $G_A$  without creating a cycle.

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#### **Definition**

Given a matroid  $M = (S, \mathcal{I})$ , we call an element  $x \notin A$  an **extension** of  $A \in \mathcal{I}$  if x can be added to A while preserving independence; that is, x is an **extension** of A if  $A \cup \{x\} \in \mathcal{I}$ .

#### Definition

If A is an *independent* subset in a matroid M, we say that A is *maximal* if it has no extensions. That is, A is maximal if it is not contained in any larger independent subset of M.

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### Theorem 16.6

All *maximal* independent subsets in a matroid has the **same** size.

- Suppose to the contrary that A is a maximal independent subset of M and there exists another larger maximal independent subset B of M.
- Then, the exchange property implies that A is extendible to a larger independent set A ∪ {x} for some x ∈ B − A, contradicting the assumption that A is maximal.

- Suppose to the contrary that A is a maximal independent subset of M and there exists another larger maximal independent subset B of M.
- Then, the exchange property implies that A is extendible to a *larger* independent set A ∪ {x} for some x ∈ B − A, contradicting the assumption that A is *maximal*.

## **Example**

Every maximal independent subset of  $M_G$  must be a free tree with exactly |V| - 1 edges that connects all the vertices of G. Such a tree is called a **spanning tree** of G.

### **Definition**

We say that a matroid  $M = (S, \mathcal{I})$  is **weighted** if there is an associated weight function w that assigns a strictly positive weight w(x) to each element  $x \in S$ . The weight function w extends to subsets of S by summation:

$$w(A) = \sum_{x \in A} w(x)$$

for any  $A \subset S$ .

## Why weighted matroid?

Many problems for which a greedy approach provides optimal solutions can be formulated in terms of finding a *maximum-weight independent subset* in a weighted matroid.

## **Example**

• Minimum-spanning-tree problem: Given a connected undirected graph G = (V, E) and a length function w such that w(e) is the (positive) length of edge e. We are asked to find a subset of the edges that connects all of the vertices together and has minimum total length.

## **Example**

Solution: Consider the weighted matroid M<sub>G</sub> with weight function w', where w'(e) = w<sub>0</sub> - w<sub>e</sub> and w<sub>0</sub> is larger than the maximum length of any edge. Each maximal independent subset A corresponds to a spanning tree, and since

$$w'(A) = (|V| - 1)w_0 - w(A),$$

## **Example**

Solution(cont.): for any maximal independent subset A, an independent subset that maximizes the quantity w'(A) must minimize w(A). Thus, any algorithm that can find an optimal subset A in an arbitrary matroid can solve the minimum spanning tree problem.

```
\mathsf{GREEDY}(M, w)
1 A = \emptyset
    sort M.S into monotonically
          decreasing order by weight w
    for each x \in M.S, taken in monotonically
         decreasing order by weight w(x)
          if A \cup \{x\} \in M.\mathcal{I}
               A = A \cup \{x\}
    return A
```

$$O(n \lg n + nf(n))$$

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         if A \cup \{x\} \in M.\mathcal{I}
               A = A \cup \{x\}
5
    return A
```

## Running time

$$O(n \lg n + nf(n))$$

# Lemma 16.7 (Matroids exhibit the greedy-choice property)

Suppose that  $M = (S, \mathcal{I})$  is a weighted matroid with weight function w and that S is sorted into monotonically decreasing order by weight. Let x be the first element of S such that  $\{x\}$  is independent, if any such x exists. If x exists, then there exists an optimal subset A of S that contains x.

- If no such x exists, then the only independent subset is the empty set and the lemma is vacuously true.
- Otherwise, let B be any nonempty optimal subset. Assume that x ∉ B; otherwise, letting A = B gives an optimal subset of S that contains x.

- $\forall y \in B$ , our choice of x ensures that  $w(x) \ge w(y)$ .
- Construct A as follows.
  - Begin with A = {x}. By the choice of x, A is independent.
  - Using the exchange property, repeatedly find a new element of B that can be added to A until |A| = |B| while preserving the independence of A.

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  - Using the exchange property, repeatedly find a new element of B that can be added to A until |A| = |B| while preserving the independence of A.

## Proof.

- Construct A as follows(Cont.).
  - Then,  $A = \{B \{y\}\} \cup \{x\}$  for some  $y \in B$ , and so

$$w(A) = w(B) - w(y) + w(x)$$

$$\geq w(B)$$

Because B is optimal, A must also be optimal, and because  $x \in A$ , the lemma is proven.



### **Lemma 16.8**

Let  $M = (S, \mathcal{I})$  be any matroid. If x is an element of S that is an extension of some independent subset A of S, then x is also an extension of  $\emptyset$ .

### Proof.

Since x is an extension of A, we have that  $A \cup \{x\}$  is independent. Since  $\mathcal{I}$  is hereditary,  $\{x\}$  must be independent. Thus, x is an extension of  $\emptyset$ 

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## **Corollary 16.9**

Let  $M = (S, \mathcal{I})$  be any matroid. If x is an element of S such that x is **not** an extension of  $\emptyset$ , then x is **not** an extension of any independent subset A of S.

# Lemma 16.10 (Matroids exhibit the optimal-substructure property)

Let x be the first element of S chosen by GREEDY for the weighted matroid  $M = (S, \mathcal{I})$ . The remaining problem of finding a maximum-weight independent subset containing x reduces to finding a maximum-weight independent subset of the weighted matroid  $M' = (S', \mathcal{I}')$ ,

# Lemma 16.10 (Matroids exhibit the optimal-substructure property)

where

$$S' = \{ y \in S : \{x, y\} \in \mathcal{I} \},$$
  
$$\mathcal{I}' = \{ B \subseteq S - \{x\} : B \cup \{x\} \in \mathcal{I} \},$$

and the weight function for M' is the weight function for M, restricted to S'. (We call M' the **contraction** of M by the element x.)

- If A is any maximum-weight independent subset of M containing x, then  $A' = A \{x\}$  is an independent subset of M'.
- Conversely, any independent subset A' of M' yields an independent subset A = A' ∪ {x} of M.

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## Proof.

Since we have in both cases that w(A) = w(A') + w(x), a maximum-weight solution in M containing x yields a maximum-weight solution in M', and vice versa.



# Theorem 16.11 (Correctness of the greedy algorithm on matroids)

If  $M = (S, \mathcal{I})$  is a weighted matroid with weight function w, then GREEDY(M, w) returns an optimal subset.

## Proof.

By Corollary 16.9, any elements that are passed over initially because they are not extensions of  $\emptyset$  can be forgotten about, since they can never be useful. Once the first element x is selected, Lemma 16.7 implies that GREEDY does not err by adding x to A, since there exists an optimal subset containing x.

## Proof.

Finally, Lemma 16.10 implies that the remaining problem is one of finding an optimal subset in the matroid M' that is the contraction of M by x.

B is independent in  $M' \iff B \cup \{x\}$  is independent in M.

## Proof.

Thus, the subsequent operation of GREEDY will find a maximum-weight independent subset for M', and the overall operation of GREEDY will find a maximum-weight independent subset for M.



### **Definition**

- A unit-time task is a job, such as a program to be run on a computer, that requires exactly one unit of time to complete.
- Given a finite set S of unit-time tasks, a schedule for S is a permutation of S specifying the order in which these tasks are to be performed.

### **Definition**

 The first task in the schedule begins at time 0 and finishes at time 1, the second task begins at time 1 and finishes at time 2, and so on.

### **Definition**

The problem of scheduling unit-time tasks with deadlines and penalties for a single processor has the following inputs:

- a set  $S = \{a_1, a_2, \dots, a_n\}$  of n unit-time tasks;
- a set of n integer **deadlines**  $d_1, d_2, \ldots, d_n$ , such that each  $d_i$  satisfies  $1 \le d_i \le n$  and task  $a_i$  is supposed to finish by time  $d_i$ ; and

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### **Definition**

a set of n nonnegative weights or penalties w<sub>1</sub>, w<sub>2</sub>,..., w<sub>n</sub>, such that we incur a penalty of w<sub>i</sub> if task a<sub>i</sub> is not finished by time d<sub>i</sub> and we incur no penalty if a task finishes by its deadline.

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### **Definition**

- A task is *late* in this schedule if it finishes after its deadline. Otherwise, the task is *early* in the schedule.
- An arbitrary schedule can always be put into early-first form, in which the early tasks precede the late tasks.

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- An arbitrary schedule can always be put into early-first form, in which the early tasks precede the late tasks.

#### **Definition**

• An arbitrary schedule can always be put into canonical form, in which the early tasks precede the late tasks and the early tasks are scheduled in order of monotonically increasing deadlines.

### Strategy of scheduling

- Find a set A of tasks that are to be early in the optimal schedule.
- Once A is determined, we can create the actual schedule by listing the elements of A in order of monotonically increasing deadline
- List the late tasks (i.e., S A) in any order, producing a canonical ordering of the optimal schedule.

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- List the late tasks (i.e., S A) in any order, producing a canonical ordering of the optimal schedule.

#### **Definition**

- We say that a set A of tasks is independent if there exists a schedule for these tasks such that no tasks are late. Clearly, the set of early tasks for a schedule forms an independent set of tasks. Let I denote the set of all independent sets of tasks.
- For t = 0, 1, 2, ..., n, let  $N_t(A)$  denote the number of tasks in A whose deadline is t or earlier. Note that  $N_0(A) = 0$  for any set A.

#### Lemma 16.12

For any set of tasks A, the following statements are equivalent.

- The set A is independent.
- ② For t = 0, 1, 2, ..., n, we have  $N_t(A) \le t$ .
- If the tasks in A are scheduled in order of monotonically increasing deadlines, then no task is late.

### Proof.

Trivial!



#### **Theorem 16.13**

If S is a set of unit-time tasks with deadlines, and  $\mathcal{I}$  is the set of all independent sets of tasks, then the corresponding system  $(S, \mathcal{I})$  is a matroid.

#### Proof.

 Hereditary: Every subset of an independent set of tasks is certainly independent.

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#### Proof.

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#### Proof.

**Exchange property:** Suppose *B* and *A* are independent sets of tasks and that |B| > |A|. Let *k* be the largest *t* such that  $N_t(B) \le N_t(A)$ . (Such a value of *t* exists, since  $N_0(A) = N_0(B) = 0$ .)

#### Proof.

Since  $N_n(B) = |B|$ ,  $N_n(A) = |A|$  and |B| > |A|, we must have that k < n and that  $N_j(B) > N_j(A)$  for all j in the range  $k+1 \le j \le n$ . Therefore, B contains more tasks with deadline k+1 than A does. Let  $a_i$  be a task in B-A with deadline k+1. Let  $A' = A \cup \{a_i\}$ .

#### Proof.

Exchange property(Cont.):

For  $0 \le t \le k$ , we have  $N_t(A') = N_t(A) \le t$ , since A is independent. For  $k < t \le n$ , we have  $N_t(A') \le N_t(B) \le t$ , since B is independent. Therefore, A' is independent, completing our proof that  $(S, \mathcal{I})$  is a matroid.



### **Example**

$a_i$	1	2	3	4	5	6	7	
di	4	2	4	3	1	4	6	
$W_i$	70	60	50	40	30	4 20	10	

The final optimal schedule is  $\langle a_2, a_4, a_1, a_3, a_7, a_5, a_6 \rangle$ , which has a total penalty incurred of  $w_5 + w_6 = 50$ .

### Running time

 $O(n^2)$ 

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