

高级数据结构

Advanced Data Structure

2. Primary key access methods

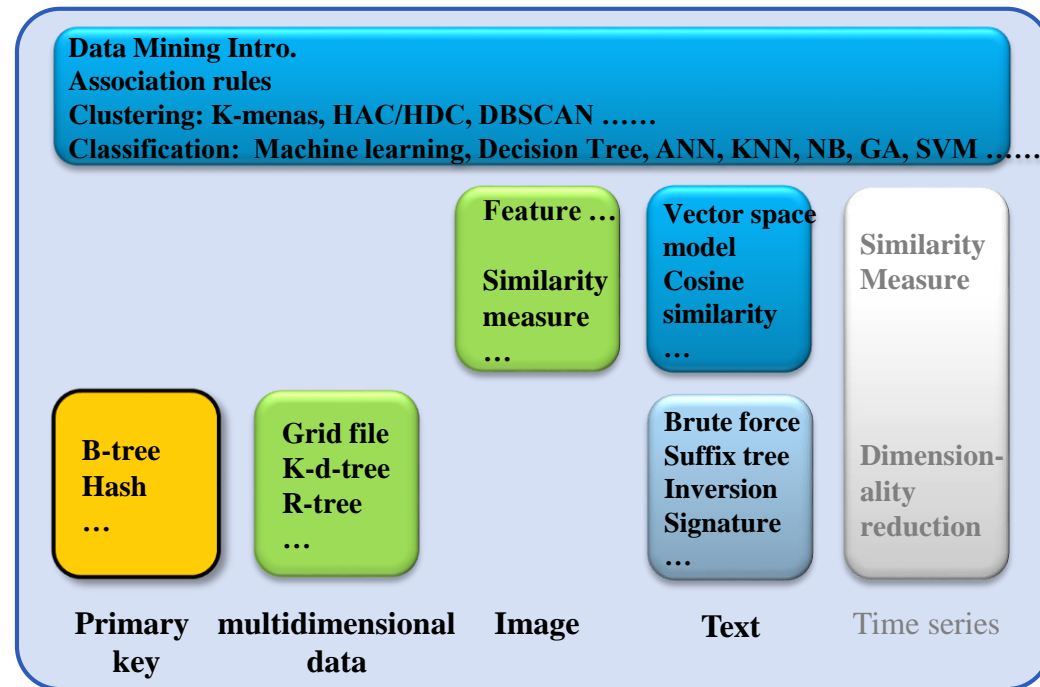
Agenda

■ Primary key access methods -

How to access a large collection of values?

- Application example:
 - Concept of RDBMS
 - Computational model
- Hash
- B-tree family

Efficiency Content based... AI/KDD



Agenda

■ Primary key access methods

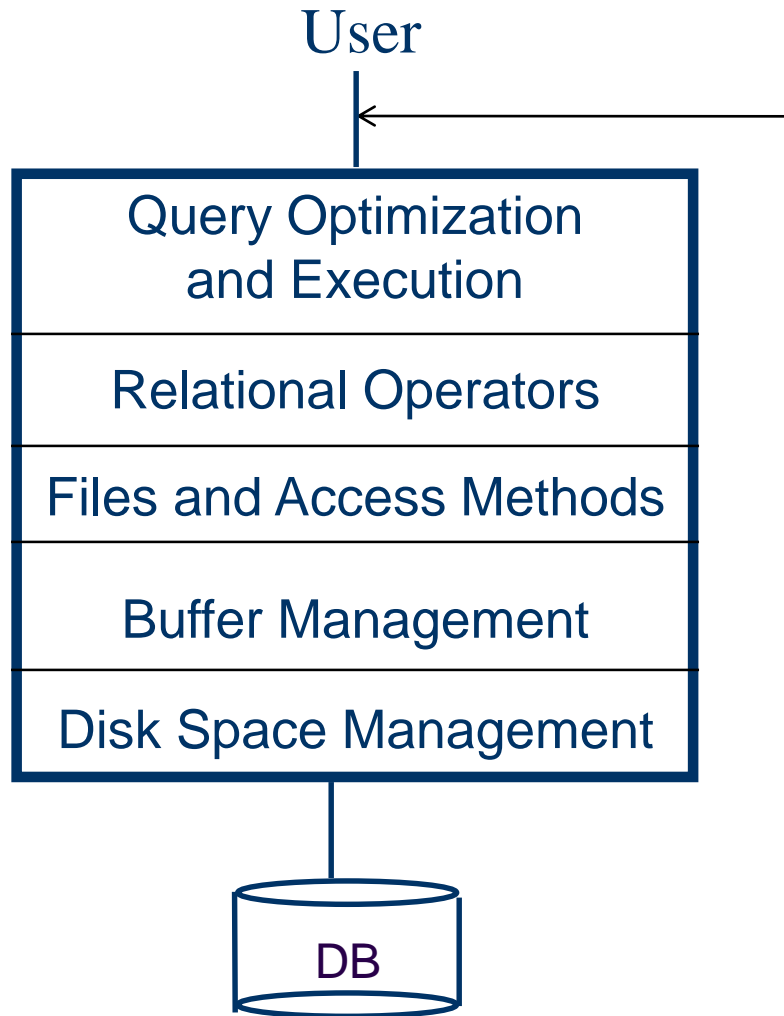
- Concept of RDBMS
Computational model
- Hash
- B-tree family

Concept of RDBMS (Relational DataBase Management System)

- Representing data using *Relational Model*
 - Data are organized in **tables** (*relations*)
 - Rows of table correspond to **records**
 - Columns correspond to **attributes**
- Access the data using **Structured Query Language** (SQL)
 - Handle queries on primary keys

ID	Name	Age	Salary
123	S. John	33	30000
456	E. Tom	22	3000
...

Query and Typical DBMS Architecture



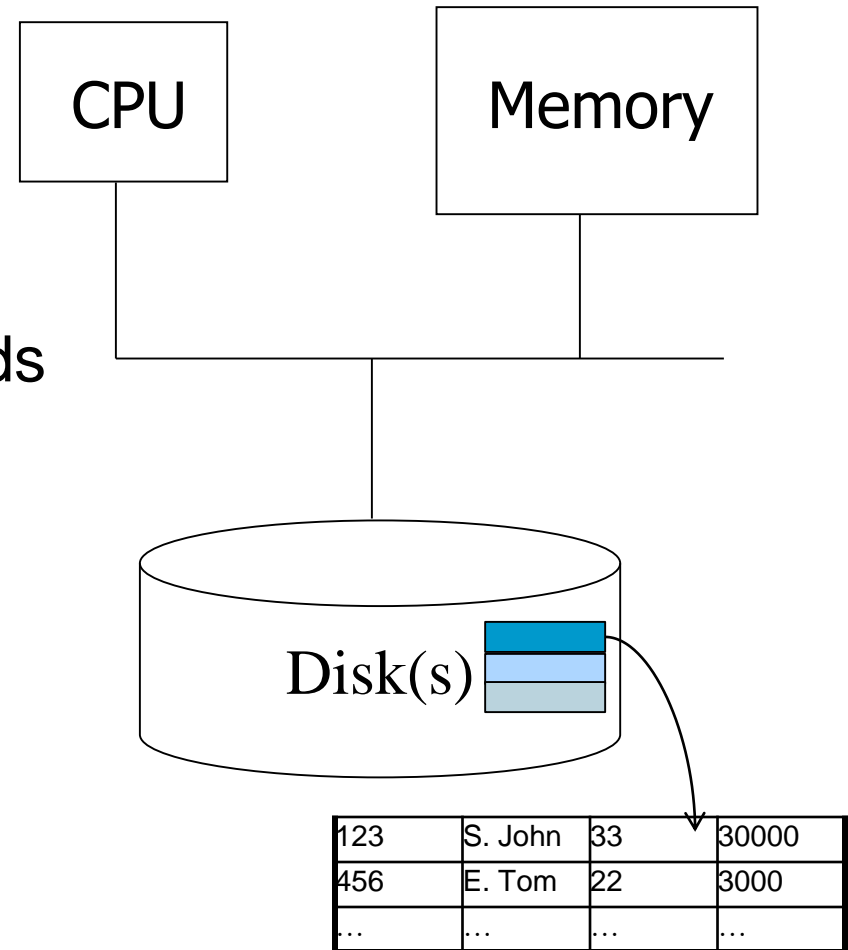
■ Query

1. Exact match
 - $x=10$
2. Range query
 - $10 < x < 100$
3. Nearest neighbor query
 - $\operatorname{argmin}_x(d(x, 10))$
 $d(x, y) = |x - y|$

.....

Model of Computation

- **Data stored on disk(s)**
- **Minimum transfer unit**
 - A *block (page)* = *B* records
- **I/O complexity**
 - Measured in number of blocks accessed



Model of Computation - Index

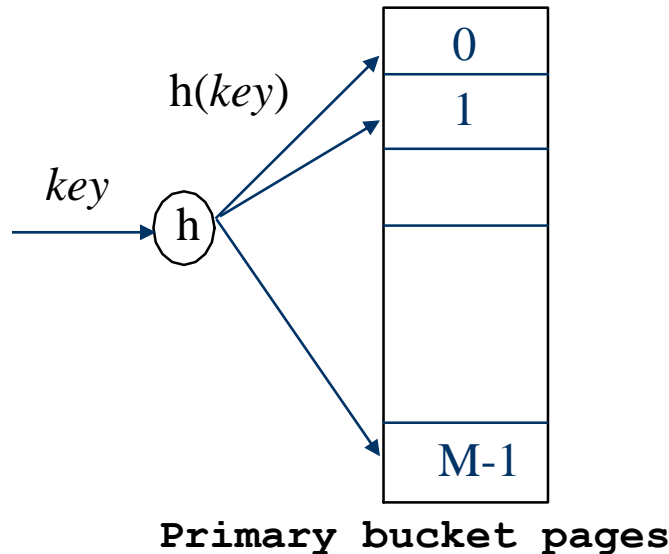
- Use index to speed up *value* \rightarrow *physical-storage* processing
- Loading Factor =
number of elements in the index / maximal number of elements in the index
- Classical index methods for RDBMS
 - **Hashing Methods:** Linear Hashing, extendible hashing
 - **B-tree family:** B tree, B⁺-tree, and variations

Agenda

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Computational Model
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Hash - Key Idea

- Use a key-to-address function to direct a record to a disk block
- $h(k)$ = *bucket* to which data entry with key k belongs
e.g. $h(\text{key}) = \text{key} \bmod M$

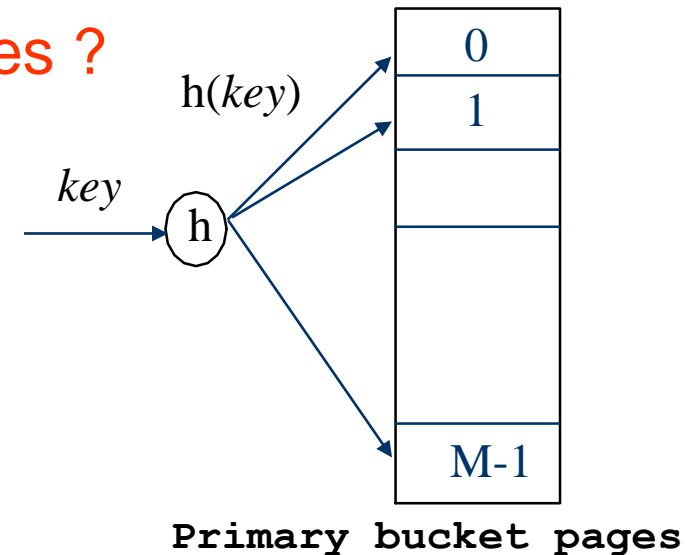


Hash - Challenges

■ Overflow handling:

- Open addressing: re-hashing to another bucket
- Separate chaining: use a separate *overflow area*

– Problem in **dynamic** databases ?



Dynamic Hashing Schemes

■ Extendible hashing:

- Uses a directory that grows or shrinks depending on the data distribution.
- No overflow buckets

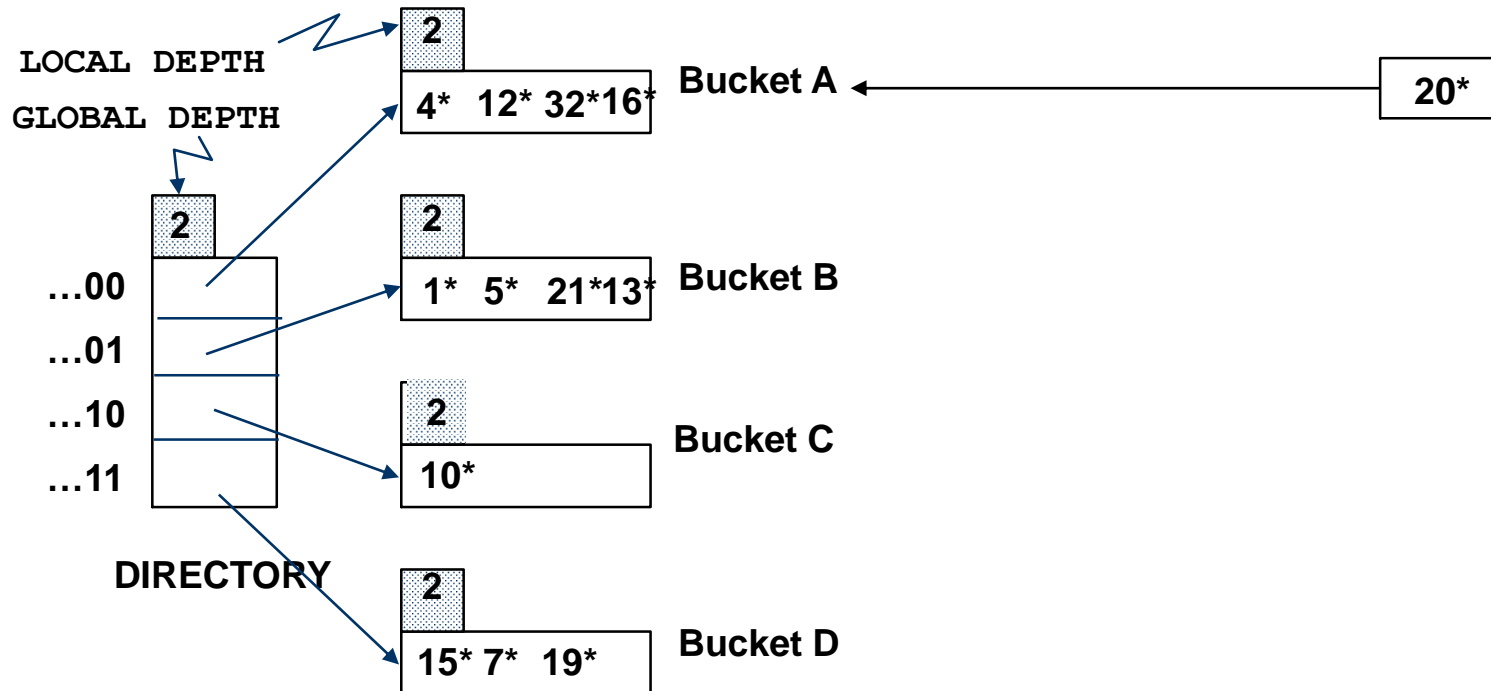
■ Linear hashing:

- No directory
- Splits buckets in linear order
- Uses overflow buckets

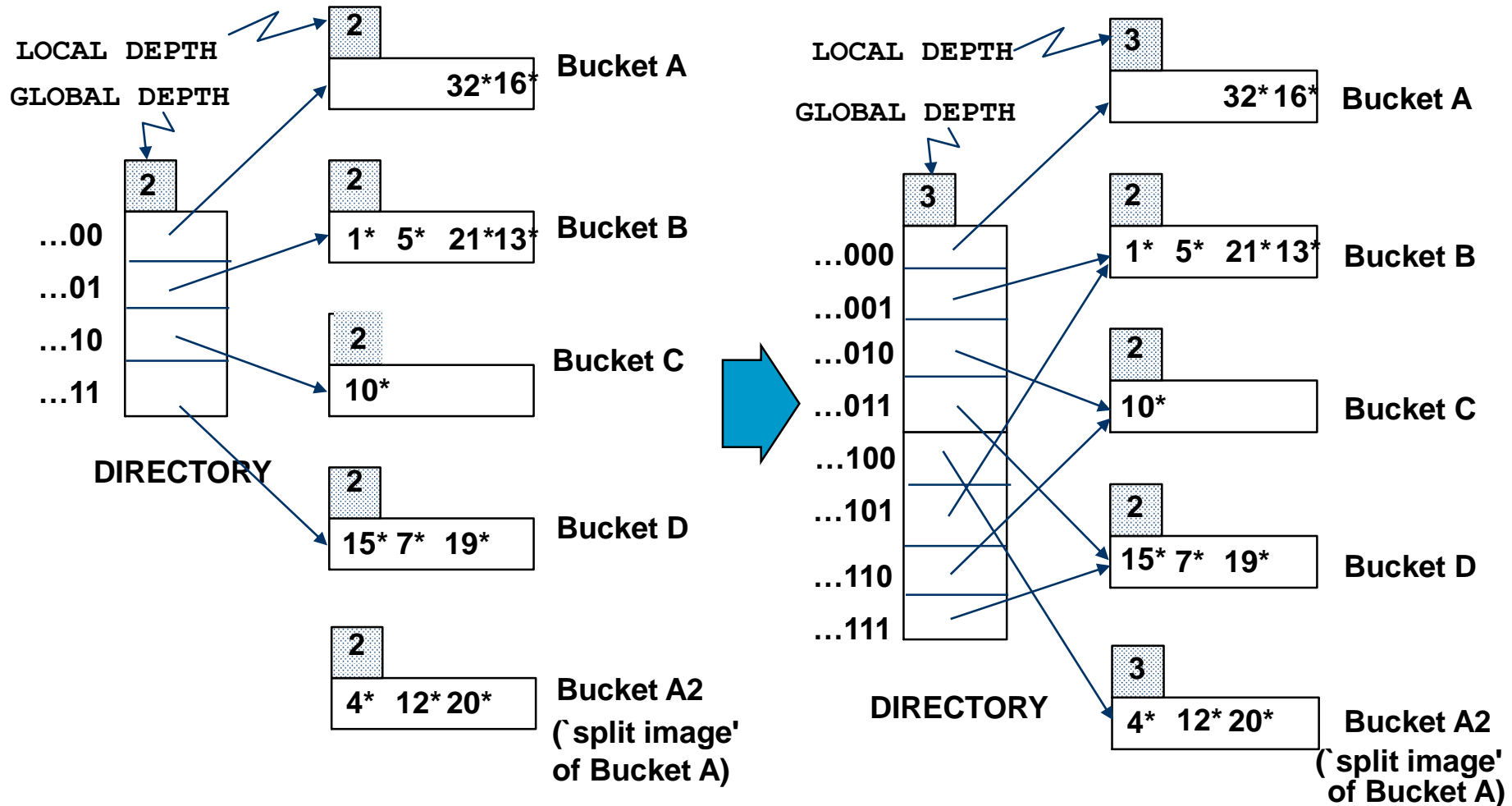
Extendible Hashing

- When bucket becomes full,
re-organize file by *doubling* the number of buckets?
 - Reading and writing all pages is expensive!
- Idea:
 - Use directory of pointers to buckets
 - Double # of buckets by *doubling the directory*
 - Splitting just the bucket that overflowed!

Insert 20



Insert 20



Remarks

- Directory is much smaller than the data file, so doubling it is much cheaper.
- Only one disk block (of data entries) is split.

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Computational Model
 - Hash
 - Extendible hash
 - Linear hash
 - B-tree family

Linear Hashing

■ Motivation:

- Ext. Hashing requires storage space for directory.
- Directory grows by doubling.
Can we do better? (smoother growth)

■ Linear Hashing (LH): another dynamic hashing scheme.

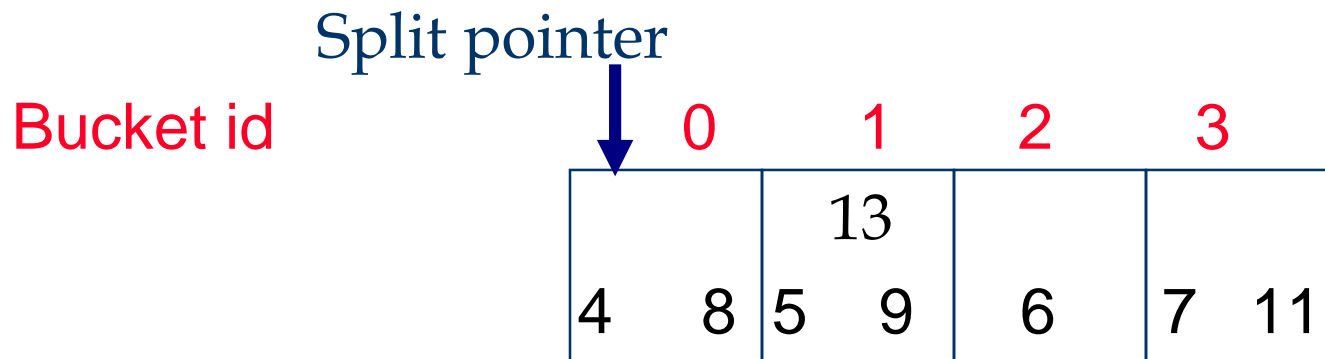
- Split buckets from “left” to “right”, regardless of which one overflowed (simple, but it works!)

Linear Hashing: Example

Initially: $h(x) = x \bmod N$ ($N=4$)

Assume **3** records/bucket

Insert 17 $17 \bmod 4 \rightarrow 1$



Linear Hashing: Example

Initially: $h(x) = x \bmod N$ ($N=4$)

Assume 3 records/bucket

Insert 17 = $17 \bmod 4 \rightarrow 1$ Overflow for Bucket 1

Split pointer

Bucket id

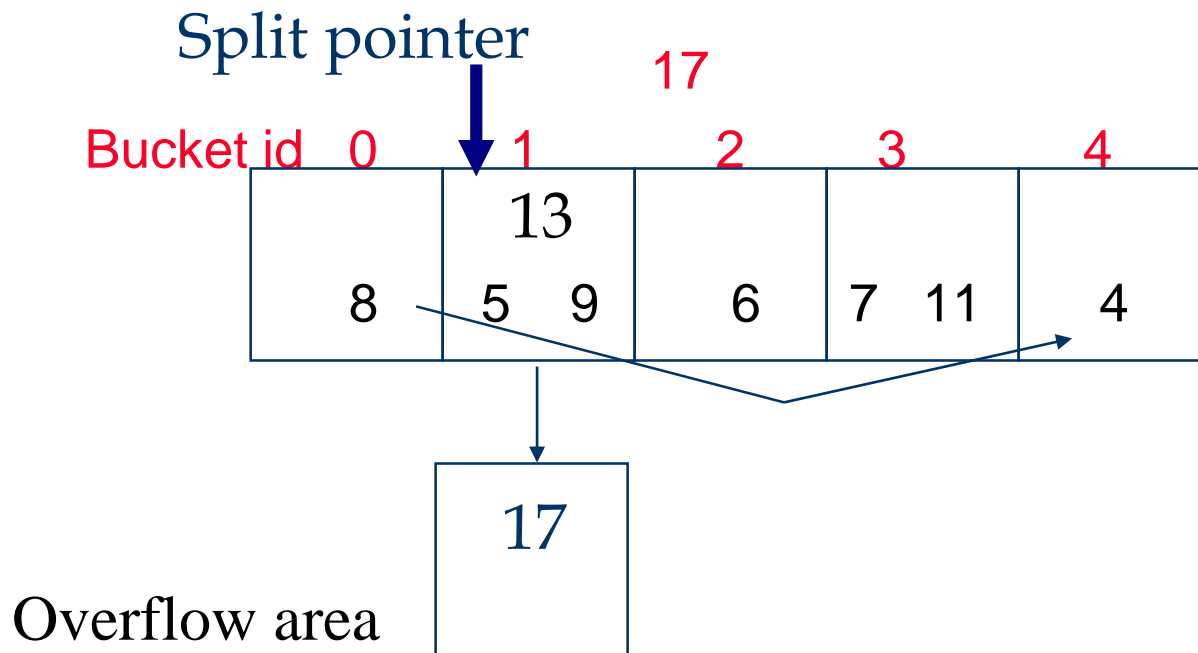
0	1	2	3
4 8	13 5 9	6	7 11

Split bucket 0, anyway!!

Linear Hashing: Example

To split bucket 0, use another function $h_1(x)$:

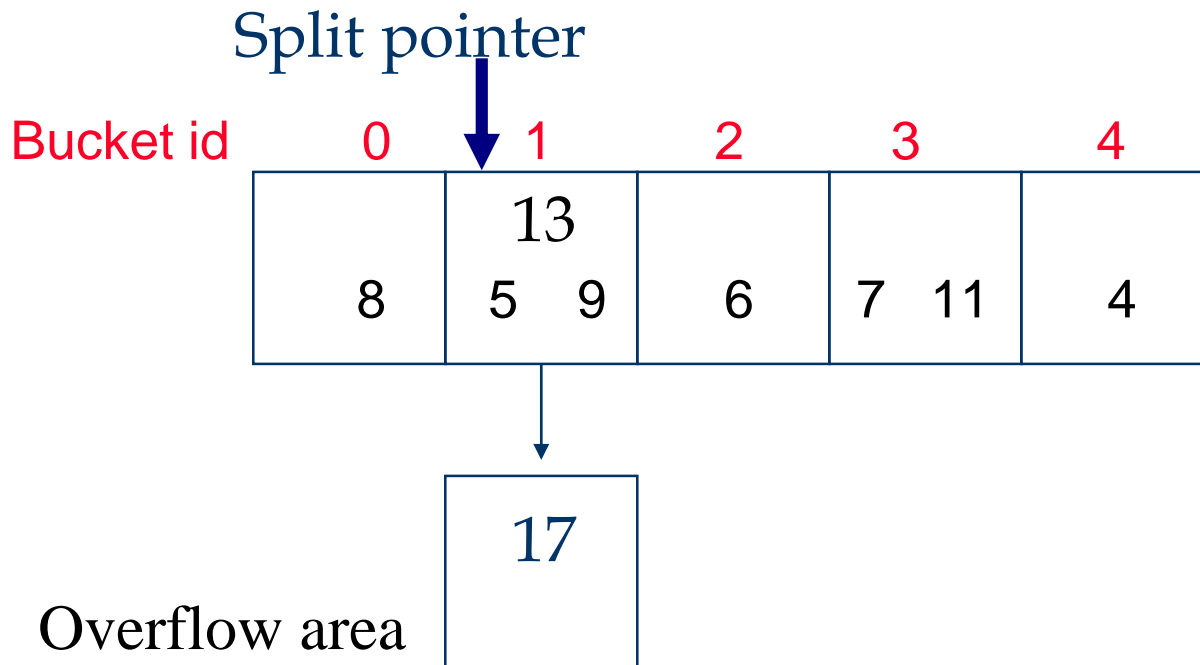
$$h_0(x) = x \bmod N, \quad h_1(x) = x \bmod (2 \cdot N)$$



Linear Hashing: Example

$$h_0(x) = x \bmod N, \quad h_1(x) = x \bmod (2 \cdot N)$$

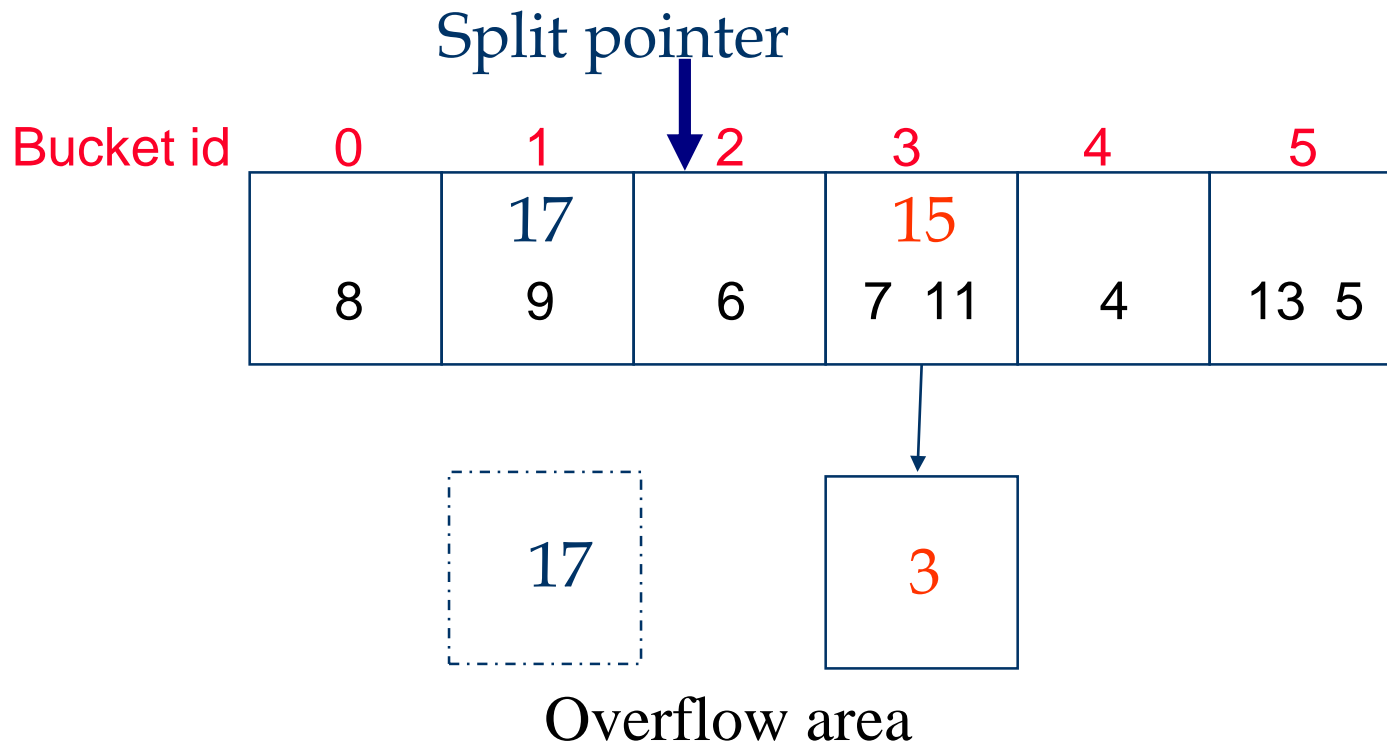
Insert 15 and 3: $15 \bmod 4 \rightarrow 3$, $3 \bmod 4 \rightarrow 3$



Linear Hashing: Example

$$h_0(x) = x \bmod N, \quad h_1(x) = x \bmod (2 \cdot N)$$

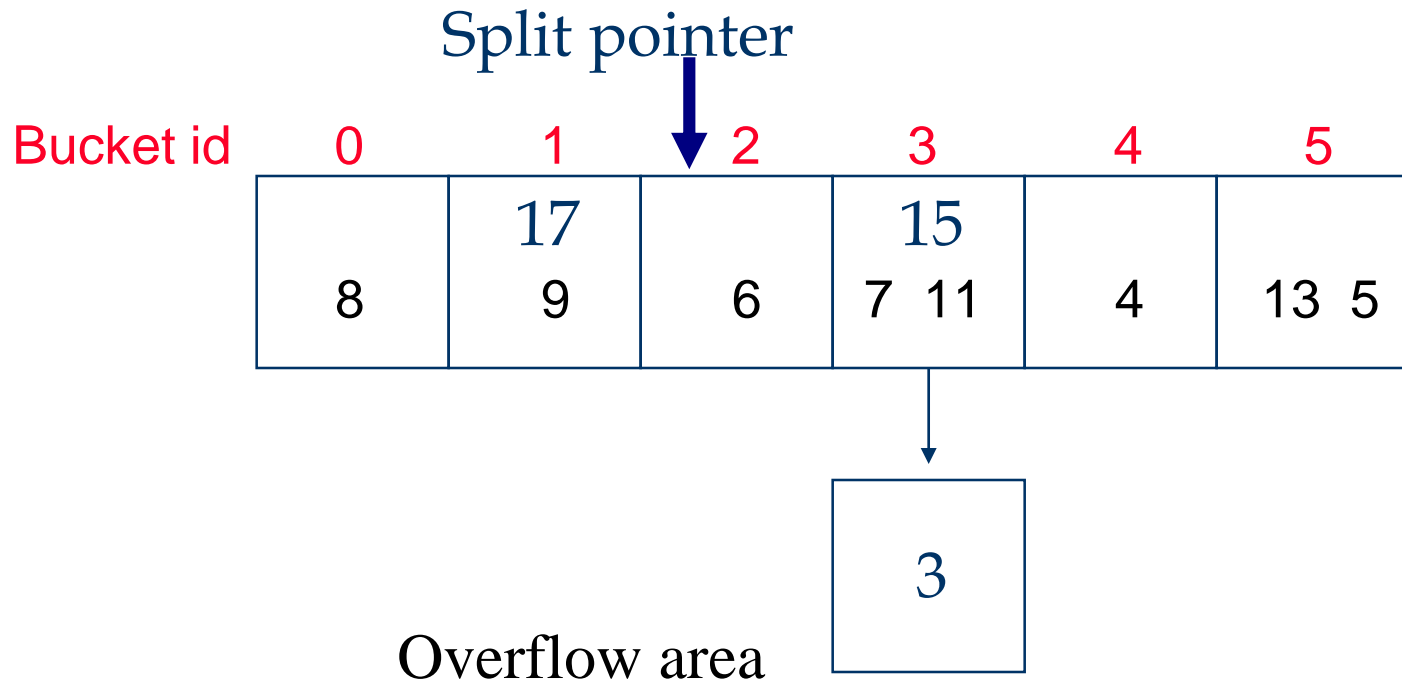
Insert 15 and 3



Linear Hashing: Search

$h_0(x) = x \bmod N$ (for the un-split buckets)

$h_1(x) = x \bmod (2 \cdot N)$ (for the split ones)



Problems of hash

- For records that can be sorted over an attribute
 - E.g., salary, age, etc.

How to answer range queries using Hash?

How to answer nearest neighbor queries using Hash?

Agenda

■ Primary key access methods

- Concept of DBMS
Computational Model
- Hash
- B tree family
 - B tree
 - B* tree
 - B+ tree

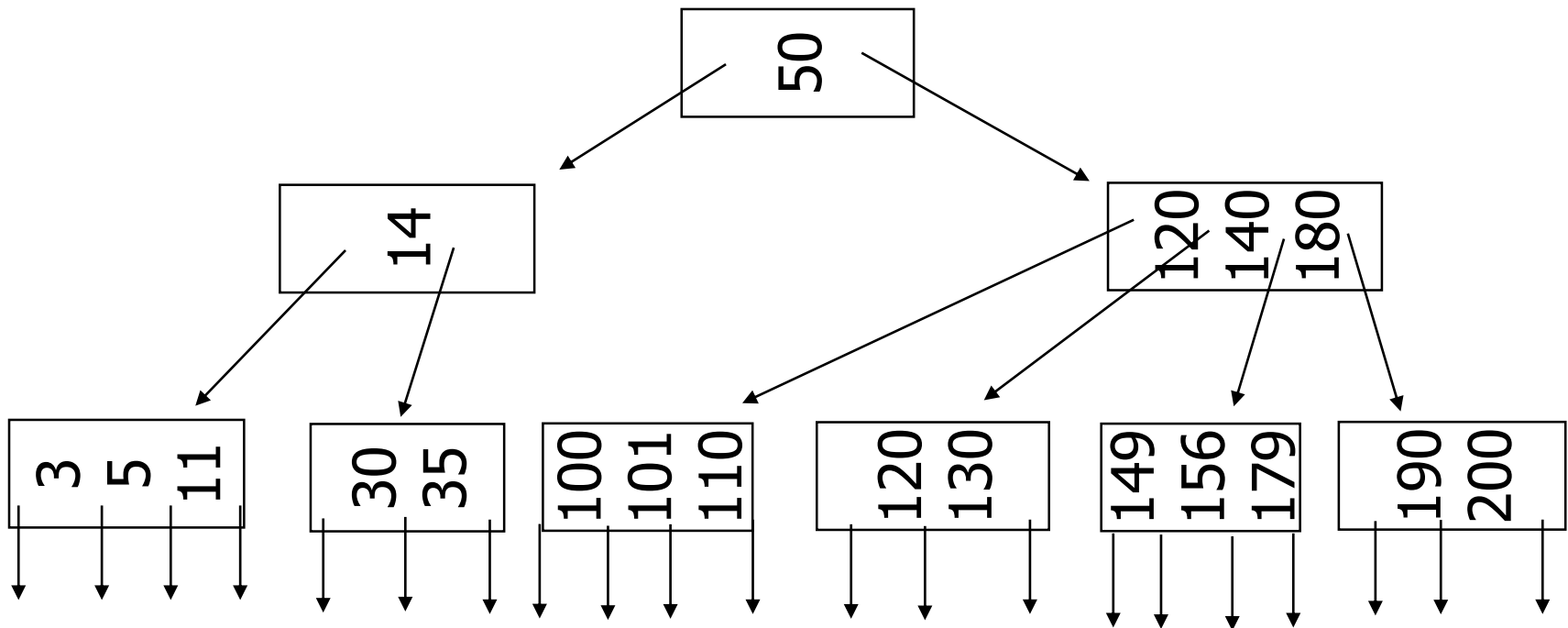
B tree

- B tree is a multi-way search tree with the following properties:
 - The root has at least two children unless it's a leaf
 - Each non-root internal node holds $k-1$ keys and **k pointers** to sub-trees where $\lceil m/2 \rceil \leq k \leq m$
 - Each leaf node holds $k-1$ keys where $\lceil m/2 \rceil \leq k \leq m$
 - All leaves are on the same level
- Each node is fit to one disk block

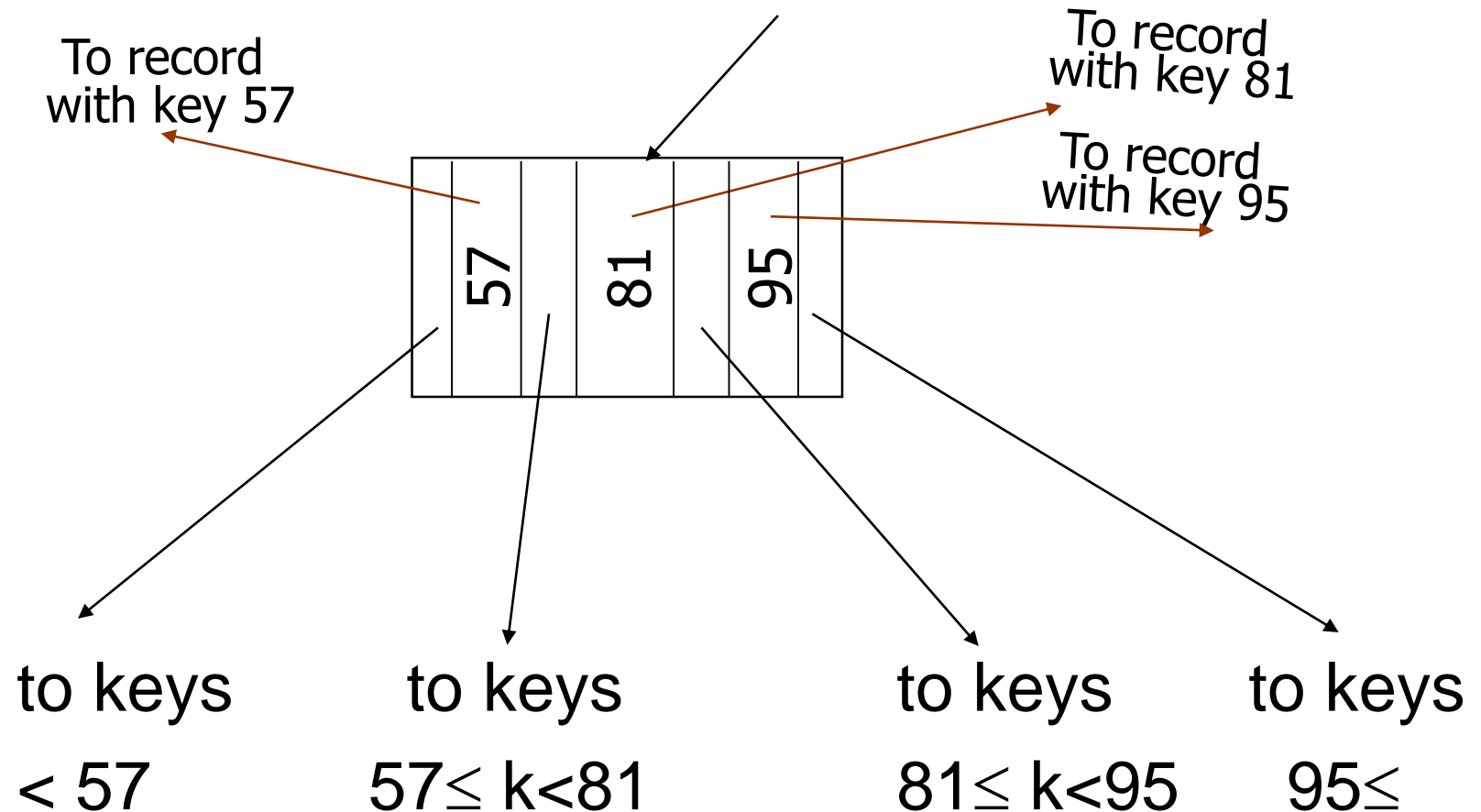
B tree - Example

$m=4$

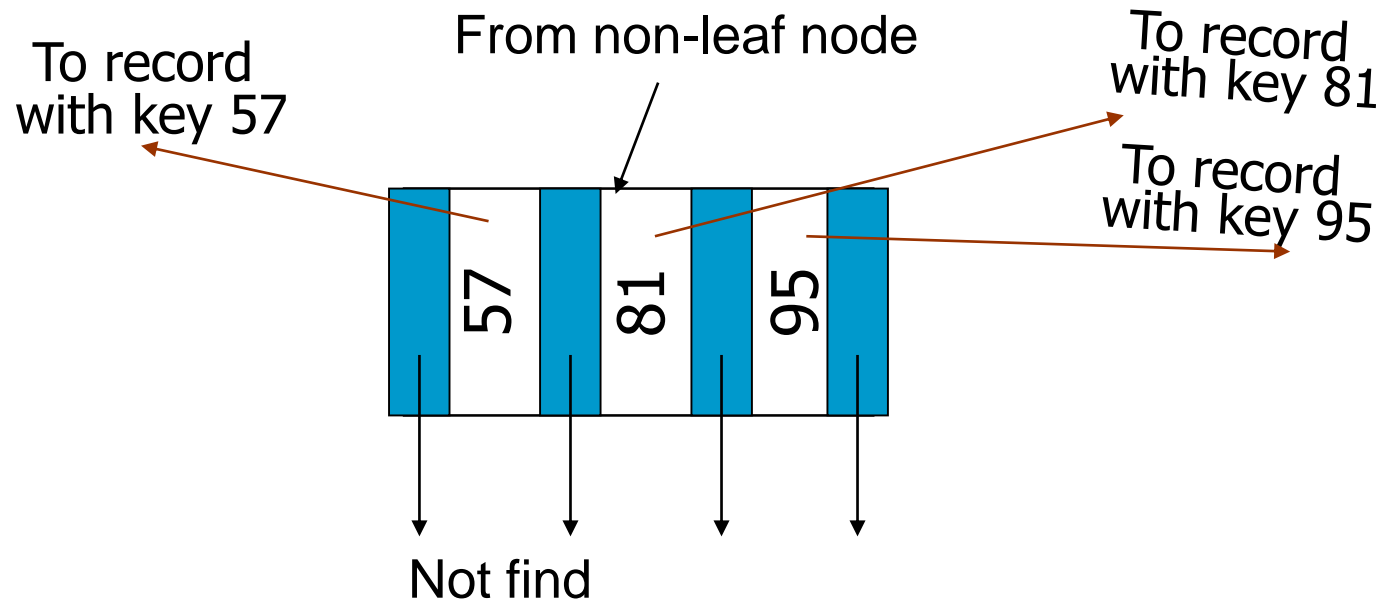
Root



B tree - internal node



B tree - Leaf node



B tree - Insertion

- 1) Find correct leaf *L*.
- 2) Put data entry onto *L*.
 - If *L* has enough space, *done!*
 - Else, split *L* (*into L and a new node*)
 - split, **move up** middle key.
- This can happen recursively
- Splits “grow” tree; root split increases height.
 - Tree growth: gets wider or one level taller at top.

B tree - Deletion

- Start at root, find node L where entry belongs.
- Remove the entry.
 - If L is at least half-full, *done!*
 - Otherwise,
 - Try to **re-distribute**, borrowing from **sibling** (*adjacent node with same parent as L*).
 - If re-distribution fails, **merge** L and sibling.
- Merge could propagate to root, decreasing height.

B tree - Characteristics

- Loading factor:
 - Minimum 50% occupancy (except for root)
 - Average 69% (Random insertion)
- Always balanced
- Space: linear
- Update and query: logarithmic (in number of I/Os).

Agenda

- Review of complexity analysis
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B* tree

- Motivation: The fewer nodes that are created, the better.
- Main idea: all nodes except the root are required to be at least $2/3$ full
- Split: when overflow:
 - Redistribute the keys by searching its sibling nodes
 - 2 nodes \rightarrow 3 nodes
- Generalization:
 - Bn tree: nodes are required to be $(n+1)/(n+2)$ full

B* tree - Characteristics

■ Decrease...

- Fewer splits and guarantee $2/3$ space utilization ($1/2$ for B tree)

■ Increase ...

- Programming complexity
- Insertion time

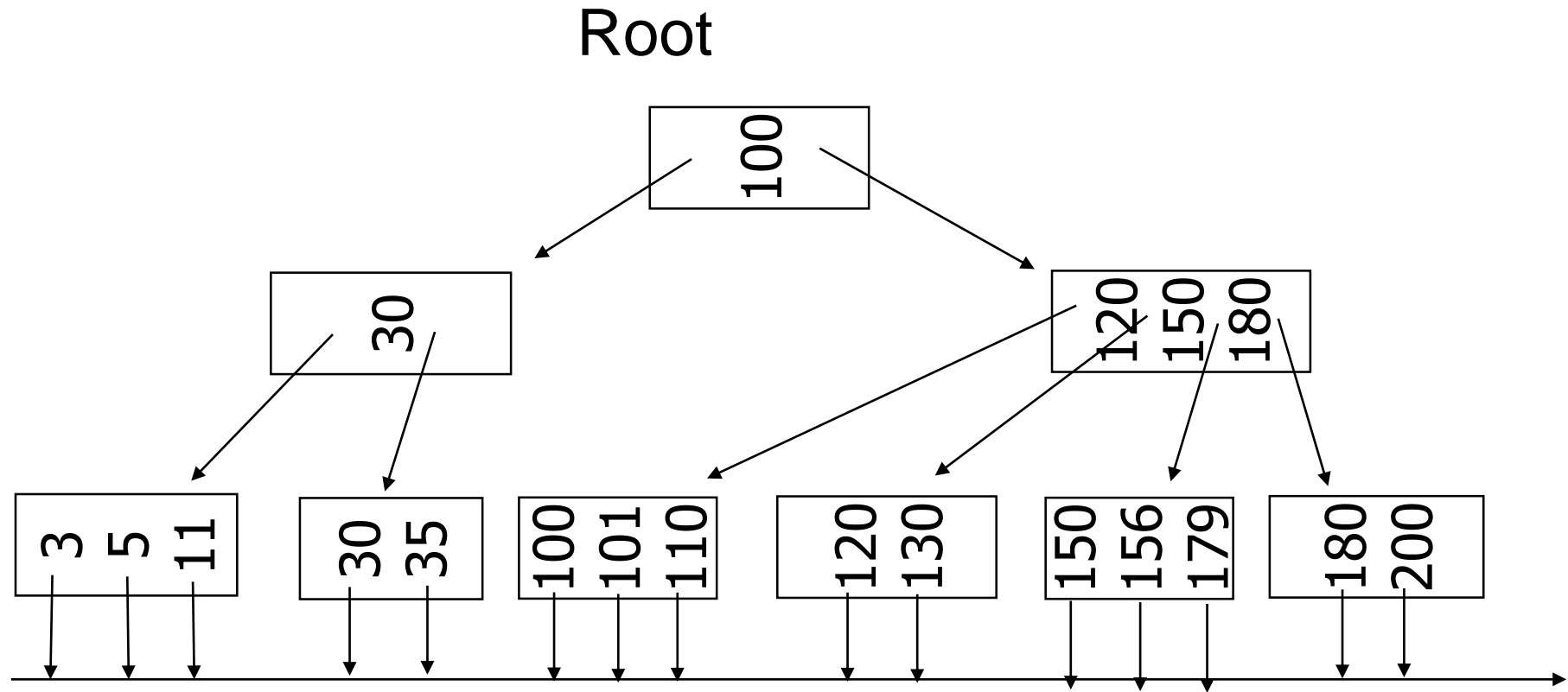
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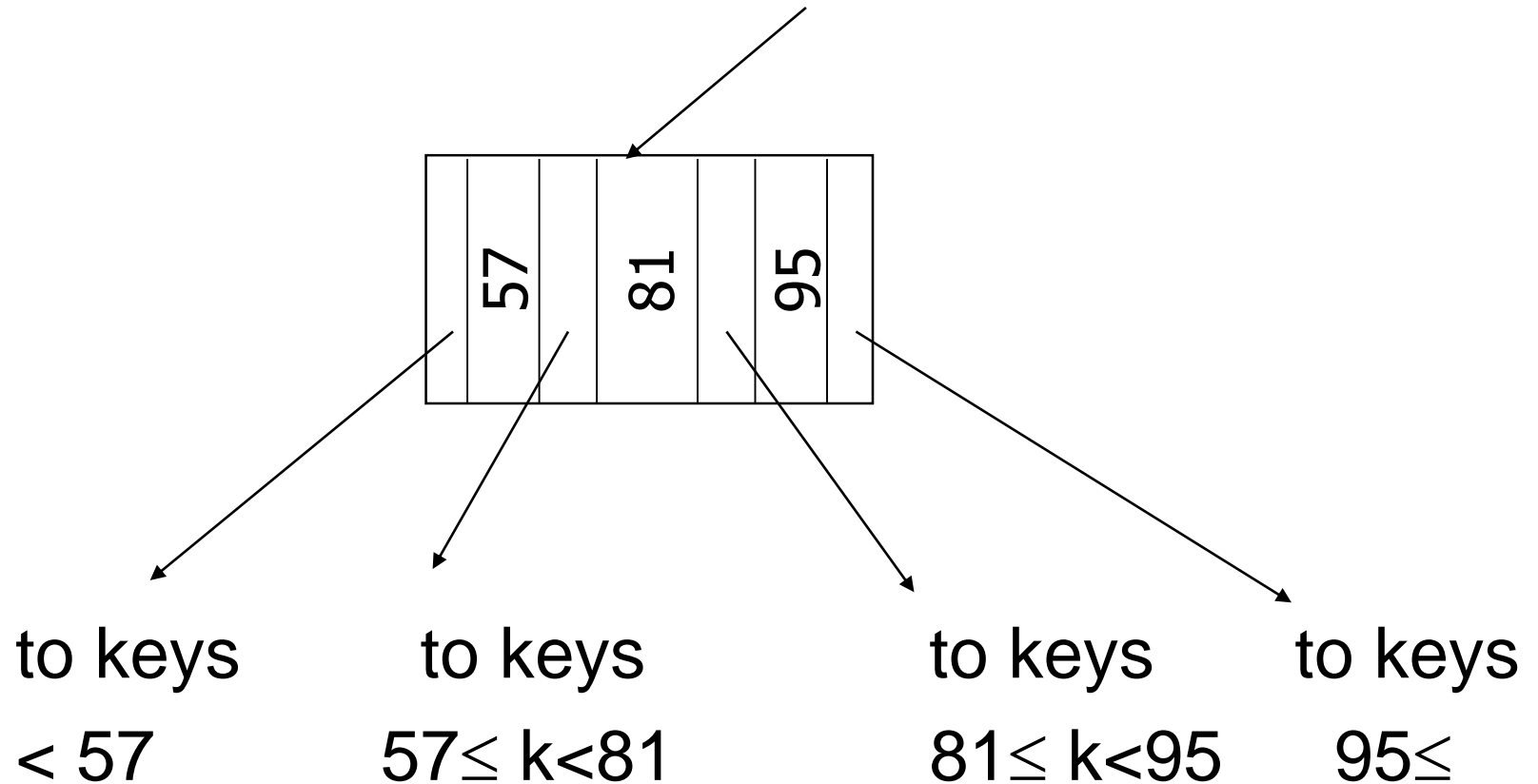
B+ tree

- Motivation: need for range queries.
- Two types of nodes:
index (internal) nodes and **data (leaf)** nodes
 - Data are stored in leaf nodes
- All leaves are chained up

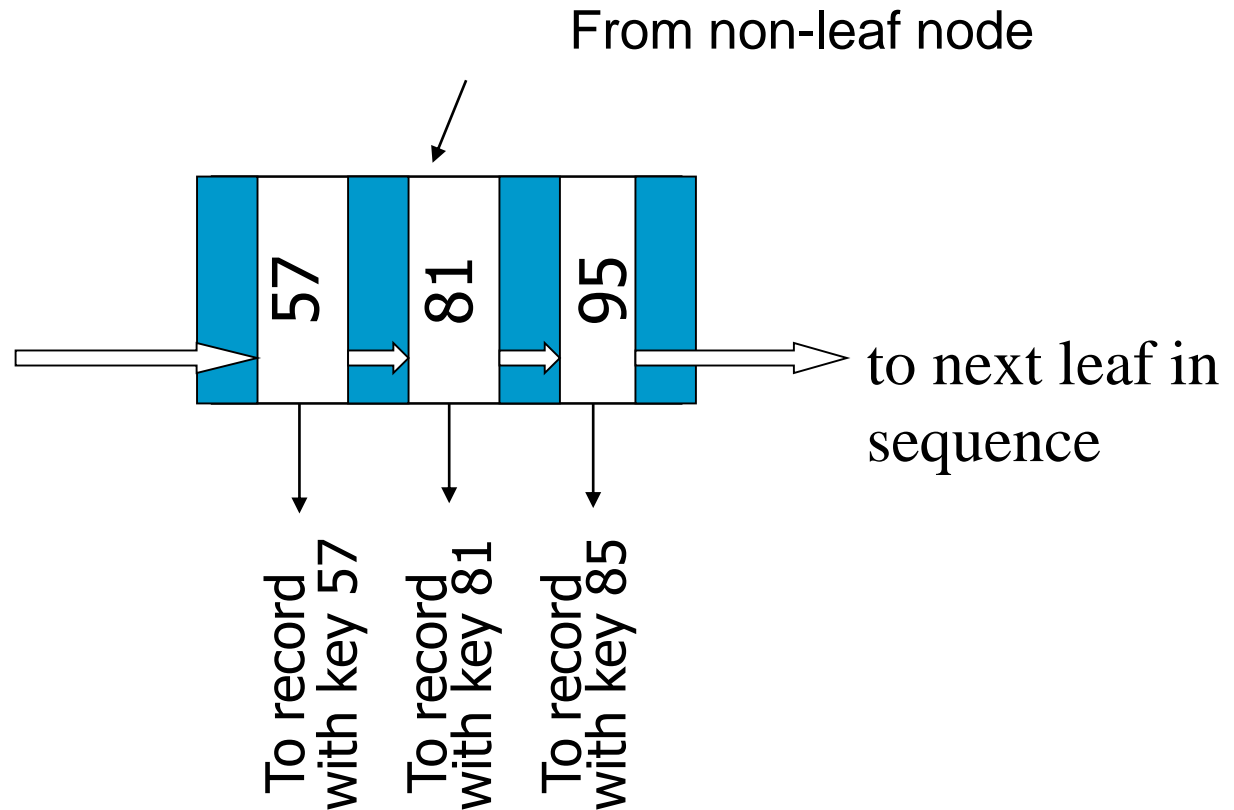
B+ tree - Example



B+ tree - Index node



B+ tree - Data node



B+ tree - Characteristics

- Optimal method for 1-d range queries:
- Space: linear
- Update and query: logarithmic (in number of I/Os)

Conclusions: Primary key access methods

■ Application: RDBMS

- Problem:
 - Minimize the number of transfer units (disk blocks)
 - Handle dynamic database
- Key idea: Indexing
- Loading factor

Conclusions: B-tree family vs. Hashing

- *Hash-based* indices are best for exact match queries. Faster than *B+-tree*!
 - *Hash-based* indices typically require 1-2 I/Os per query
 - *B+-tree* requires 4-5 I/Os (logarithmic)
 - *B family tree* support answering
 - *range queries*
 - *nearest neighbor queries*
 - *ordered sequential scanning...*
- Hash-based* indices don't support.

Homework

- Read chapters 2, 3
- Homework
 - In linear hash (p23 in ppt), insert some keys
 - In B tree (p28 in ppt), insert some keys and remove some keys

Thanks

Feedback welcome