

# **KDM-202 Series Conductivity (Salinity) Transmitter User Manual**



---

# Catalog

|       |  |                                     |
|-------|--|-------------------------------------|
| 1.    | Equipment Application Environment .....              | 3                                   |
| 2.    | Technical Parameters, Functions, Specifications..... | 3                                   |
| 2.1.  | Technical Parameters .....                           | 3                                   |
| 2.2.  | Size chart.....                                      | 4                                   |
| 2.3.  | Data communication.....                              | 6                                   |
| 2.5.1 | Data format .....                                    | 6                                   |
| 2.5.2 | Message frame format.....                            | 6                                   |
| 2.5.3 | Register address .....                               | 6                                   |
| 2.5.4 | Command sample .....                                 | 8                                   |
| 2.5.5 | Error response.....                                  | 9                                   |
| 2.4.  | Installation method.....                             | 10                                  |
| 2.5.  | Wiring .....   | 10                                  |
| 2.5.1 | Cable information .....                              | 10                                  |
| 2.5.2 | Cable specification.....                             | 11                                  |
| 2.6.  | Maintenance.....                                     | 11                                  |
| 2.7.  | Parts And Spare Parts.....                           | 12                                  |
| 2.8.  | Quality Assurance .....                              | 12                                  |
| 2.9.  | Electrode selection common sense .....               | <b>Error! Bookmark not defined.</b> |

---

# 1. Equipment Application Environment

- Pure water / drinking water / surface water / various water supply / industrial wastewater treatment
- A variety of signal output: 4-20mA (2-wire analog signal), RS485 (Modbus / RTU digital signal).
- Easy to connect to PLC, DCS, industrial control computer, general controller, paperless recording instrument or touch screen and other third party equipment.
- The electrode can use a variety of connectors, including gold-plated VP connector, BNC connector and so on. It is easy to change the electrode by screwing.
- Easy to install: 3/4-inch NPT thread (pipe thread), easy to install in the pipeline and tank. The probe and display section can be separated and connected by a cable.
- IP65 / IP68 degree of protection.

## 2. Technical Parameters, Functions, Specifications

### 2.1. Technical Parameters

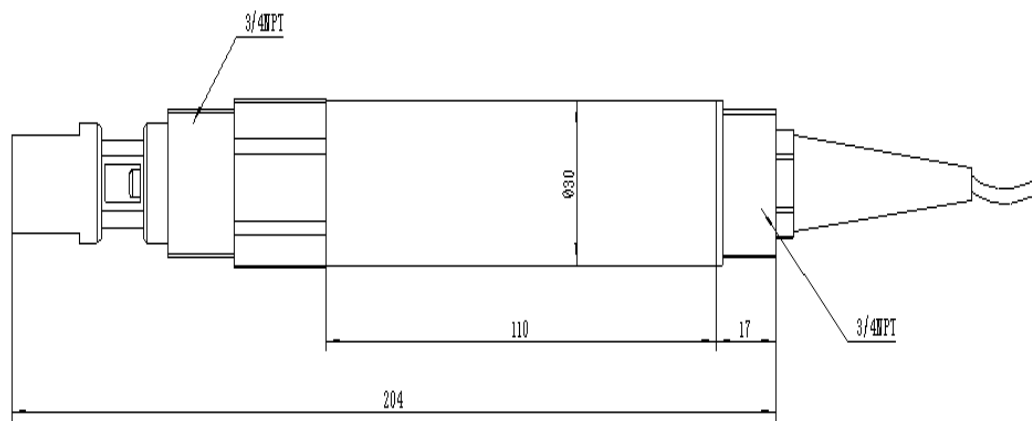
|                              |  |
|------------------------------|--|
| <b>Model</b>                 | KDM-202<br>KDM-203   |
| <b>Measurement Range</b>     | 0.01 $\mu$ S/cm $\sim$ 600mS/cm or 0 $\sim$ 100PSU<br>Range can be customized according to customer needs. |
| <b>Resolution</b>            | 0.1mS/cm or 0.1PSU   |
| <b>Accuracy</b>              | $\pm 1.5\%$ F.S.   |
| <b>Operating temperature</b> | 0 $\sim$ 65 $^{\circ}$ C   |
| <b>Working pressure</b>      | <0.6MPa  |

---

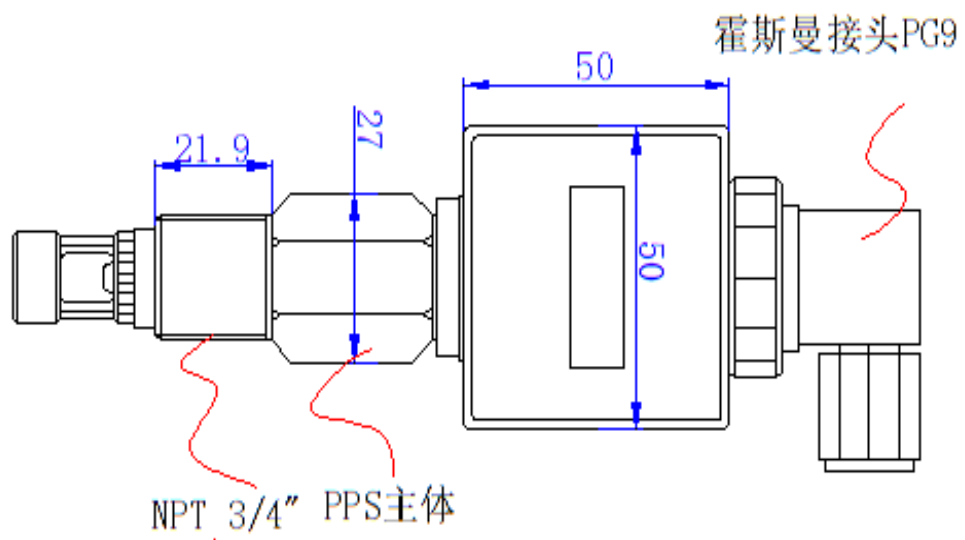
|                                 |  |
|---------------------------------|--|
| <b>Power Supply</b>             | KDM-202: 12VDC~24VDC $\pm 10\%$<br>KDM-203: 24VDC $\pm 10\%$               |
| <b>Output Mode</b>              | KDM-202: Rs485(Modbus/RTU)<br>KDM-203 : 4 ~ 20mA(Two-wire isolated signal) |
| <b>Wetted material</b>          | PP(default) /PPS/PVC(customizable)   |
| <b>Installation</b>             | 3/4 "NPT thread, immersion mounting  |
| <b>Cable Length</b>             | 5m, other length can be customized   |
| <b>Display method</b>           | KDM-202: No display<br>KDM-203: 4 LED display                              |
| <b>Temperature compensation</b> | Automatic temperature compensation (PT1000)                                |
| <b>Calibration method</b>       | Two-point calibration  |
| <b>Degree of protection</b>     | IP68/IP65  |

## 2.2. Size chart

DDM-202:



DDM-203:



---

## 2.3. Data communication

### 2.5.1 Data format

Default data format: 9600,N, 8, 1 (baud rate 9600 bps, 1 start bit, 8 data bits, no parity, 1 stop bit).

Data type: Float Type

### 2.5.2 Message frame format

#### a) Data read instruction

|        |               |                  |                |                           |
|--------|---------------|------------------|----------------|---------------------------|
| 06     | 03            | xx xx            | xx xx          | xx xx                     |
| Device | Function code | Register address | Register count | CRC code (low byte first) |

#### b) Data read response

|        |               |                  |            |                           |
|--------|---------------|------------------|------------|---------------------------|
| 06     | 03            | xx               | xx.....xx  | xx xx                     |
| Device | Function code | Data bytes count | Data bytes | CRC code (low byte first) |

#### c) Data write instruction

|        |               |                  |               |                           |
|--------|---------------|------------------|---------------|---------------------------|
| 06     | 06            | xx xx            | xx xx         | xx xx                     |
| Device | Function code | Register address | Data to write | CRC code (low byte first) |

#### d) Data write response(same with data write instruction)

|        |               |                  |               |                           |
|--------|---------------|------------------|---------------|---------------------------|
| 06     | 06            | xx xx            | xx xx         | xx xx                     |
| Device | Function code | Register address | Data to write | CRC code (low byte first) |

### 2.5.3 Register address

| Register address | Name | Instruction | Number of registers | Access method |
|------------------|------|-------------|---------------------|---------------|
|------------------|------|-------------|---------------------|---------------|

---

|                   |                               |  |             |                |
|-------------------|-------------------------------|--|-------------|----------------|
| 40001<br>(0x0000) | value and<br>temperature      | 4 double-byte integers,<br>which are DO value, DO<br>value decimal digits,<br>temperature value,<br>temperature value<br>decimal digits. | 4 (8 bytes) | Read           |
| 44097<br>(0x1000) | Zero<br>calibration           | Calibrate in air, write<br>data to zero.   | 1 (2 bytes) | Write          |
| 44101<br>(0x1004) | Slope<br>calibration          | Calibrate and write the<br>actual value of the<br>standard solution in the<br>full scale standard.                                       | 1 (2 bytes) | Write          |
| 44103<br>(0x1006) | Zero<br>calibration<br>value  | Returns the zero point of<br>the calibration.  | 1 (2 bytes) | Read           |
| 44105<br>(0x1008) | Slope<br>calibration<br>value | The slope calibration<br>value is multiplied by<br>1000.   | 1 (2 bytes) | Read           |
| 48195<br>(0x2002) | Device<br>address             | Default address is 6,<br>data range is 1-64.   | 1 (2 bytes) | Write/Re<br>ad |
| 48225<br>(0x2020) | factory reset                 | Restore calibration<br>values to factory<br>settings, write data to 0.   | 1 (2 bytes) | Write          |

---

Note:

- a) The register address defined here is the register address with the type of the register. (The actual register address is represented in the bracket).
- b) When address of the device is changed, the response to the data write instruction would contain the new changed address.
- c) The data definition of the read response value:

|                    |                        |                    |                        |
|--------------------|------------------------|--------------------|------------------------|
| XX XX              | XX XX                  | XX XX              | XX XX                  |
| 2 bytes test value | 2 bytes decimal digits | 2 bytes temp value | 2 bytes decimal digits |

The default data type is double-byte integer (high byte first), other data format such as floating point type is optional.

## 2.5.4 Command sample

- a) set the device address

Function: setting the Modbus device address of the sensor meter;

Change the device address 06 to 01, and the example is as follows:

Request frame: 06 06 20 02 00 01 E3 BD

Response frame: 01 06 20 02 00 01 E2 0A

- b) began to measure instructions

The temperature is measured in degrees Celsius and the conductivity (or salinity) is expressed in mS / cm (or uS / cm or PSU). The value of the conductivity (or salinity)

Request frame: 06 03 00 00 00 04 45 BE

Response frame: 06 03 08 01 02 00 01 00 B0 00 01 14 B4



---

Reading sample:

| <b>Conductivity<br/>(Salinity) value</b> | <b>Temperature<br/>value</b> |
|--|------------------------------|
| 01 02 00 01                              | 00 B0 00 01                  |

For example:

The conductivity (or salinity) value 01 02 indicates the conductivity (or salinity) value in hexadecimal, 00 01 indicates the conductivity (or salinity) value with 1 decimal place;

Temperature value 00 B0 is the hexadecimal reading temperature value, 00 01 is the temperature value 1 decimal place

c) calibration instructions

Zero calibration, the role of: set the electrode conductivity (or salinity) zero calibration value; where the zero calibration in the air;

Request frame: 06 06 10 00 00 00 8C BD

Response frame: 06 06 10 00 00 00 8C BD

Slope calibration, the role of: set the electrode conductivity (or salinity) slope calibration value; where the slope of the actual standard solution value, Example See Calibration;

Request frame: 06 06 10 04 01 F4 CD 6B

Response frame: 06 06 10 04 01 F4 CD 6B

## 2.5.5 Error response

If the sensor does not correctly execute the host command, it will return the following format information:

| <b>Definition</b> | <b>Address</b> | <b>Function<br/>code</b> | <b>CODE</b> | <b>CRC<br/>check</b> |
|-------------------|----------------|--------------------------|-------------|----------------------|
| Data              | ADDR           | COM+80<br>H              | xx          | CRC 16               |
| Number of bytes   | 1              | 1                        | 1           | 2                    |

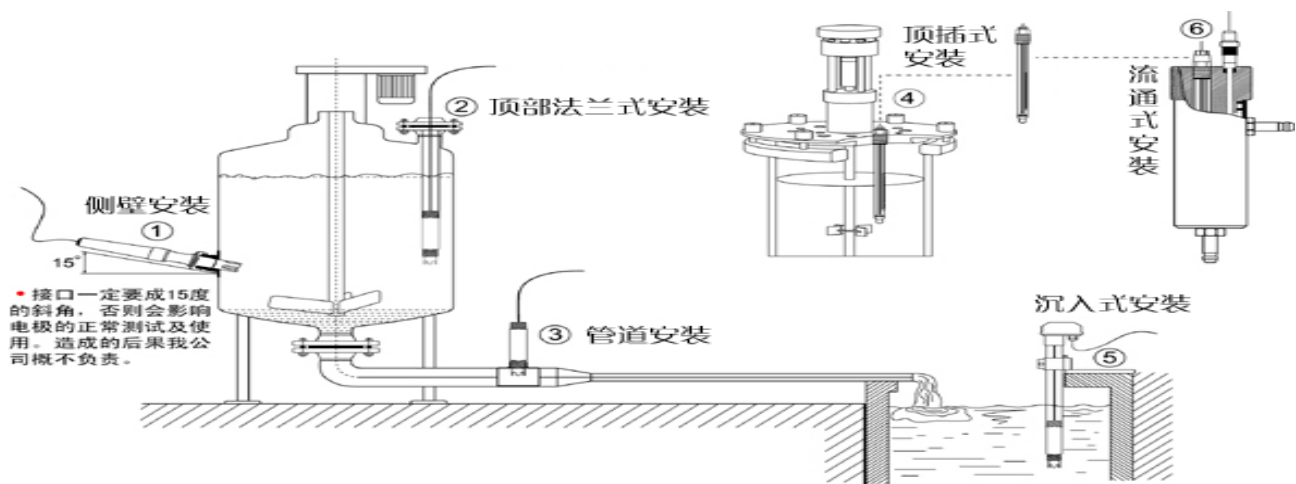
a) CODE: 01 – Functional code error

03 – Data error

b) COM: Received function code

## 2.4. Installation method

When installing the transmitter, avoid excessive force and sharp impact to damage the electrode. After completing the wiring, it should be carefully checked to avoid the wrong connection before powering on. In the normal operation of the instrument, to ensure that the sensor and the measured medium full contact. The measurement error is often due to air filling the electrode internal space or unreasonable installation caused.



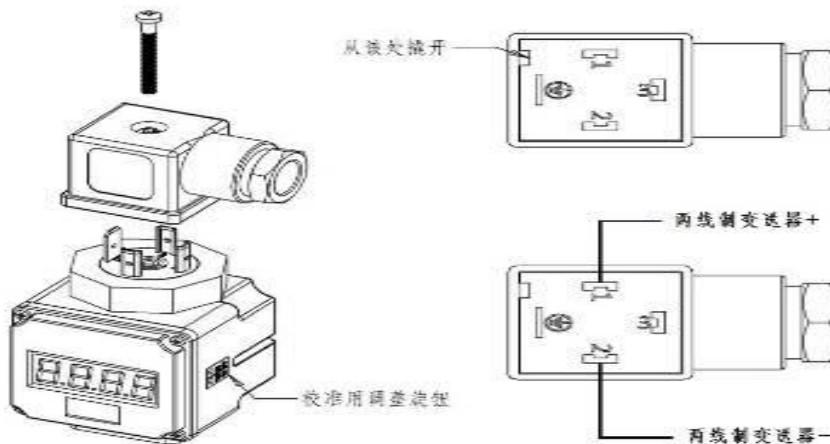
## 2.5. Wiring

### 2.5.1 Cable information

- 485 signal output is defined as:
  1. Red wire - Power cord (12 ~ 24V)
  2. Black wire - ground (GND)
  3. Blue line-485A
  4. White wire-485B
  5. Bare wire – shield
- 4 ~ 20mA signal output and its definition:

1. 拧下螺丝，向上拔出插头

2. 撬开插头，按照接线标签进行接线



## 2.5.2 Cable specification

It is required that the cables have a certain degree of corrosion resistance, taking into account long-term immersion in water (including seawater) or exposure to air. Cable diameter  $\Phi 6$  mm, all interfaces are required to do waterproofing.

## 2.6. Maintenance

Conventional electrodes need to be periodically cleaned and calibrated, the maintenance cycle by the customer according to their own conditions to decide. Conventional electrode cleaning methods: with a soft brush to remove the attachment (note to avoid scratching the electrode surface), then distilled water, after the calibration operation.

Inductive electrode cleaning method:

- Inductive electrode is basically maintenance-free, shell pollution or mild scaling does not affect its normal work.
- For cleaning, use a soft brush or sandpaper to remove the deposit, and then wash with distilled water, and then perform the calibration operation.
- As the inductive electrodes often work in the easy to fouling or dirty environment, cleaning may be appropriate to increase the intensity. Minor scratches the surface of the electrode does not affect the normal working electrode, but avoid penetrating the housing electrodes.

---

## 2.7. Parts And Spare Parts

This product includes:

- Transmitter
- Specification
- certificate
- Calibration solution (optional)
- Threaded seat (optional)

## 2.8. Quality Assurance

The company provides sales from the date of the play within one year of the machine warranty, but do not cover damage caused by improper use. If you need to repair or adjustment, please return, but the freight to be conceited, sent back to determine the fine packing to avoid damage during transport, the company will repair it free of charge damage to the instrument.