

Chap 2 - PAC learning framework

1. Reminder

(1) Risk or generalisation error

(2) Empirical risk or empirical error

(3) PAC learnability.

$(\mathcal{C}, \mathcal{H})$ is PAC-learnable
 $\subseteq X \rightarrow Y \subseteq X \rightarrow Y$

$$\begin{array}{c} \{0,1\} \\ \parallel \\ X \rightarrow Y \end{array}$$

$$R(h) = \mathbb{P}_{x \sim D} [h(x) \neq c(x)] = \mathbb{E}_{x \sim D} [\mathbb{1}_{\{h(x) \neq c(x)\}}].$$

$$\hat{R}_S(h) = \frac{1}{m} \sum_{i=1}^m \mathbb{1}_{\{h(x_i) \neq c(x_i)\}} = \mathbb{E}_{x \sim \hat{D}} [\mathbb{1}_{\{h(x) \neq c(x)\}}]$$

if \exists an algo. A and a poly $\text{poly}(\dots)$ s.t.

$$\forall c \in \mathcal{C} \forall D \in \mathcal{P}_r(X) \forall \epsilon > 0 \forall \delta > 0.$$

$$\forall m \geq \text{poly}\left(\frac{1}{\epsilon}, \frac{1}{\delta}, n\right).$$

size of the input

$$\mathbb{P}_{S \sim D^m} [R(h_S) \leq \epsilon] \geq 1 - \delta.$$