



TEF6606

Advanced tuner on main-board IC

Rev. 01.03 — 12 June 2007

Objective data sheet

AFTRA T

1. General description

The TEF6606 is an AM/FM radio including Phase-Locked Loop (PLL) tuning system. The system is designed in such a way, that it can be used as a world-wide tuner covering common FM and AM bands for radio reception. All functions are controlled by the I²C-bus. Besides the basic feature set it provides a good weak signal processing function and a dynamic bandwidth control at FM reception.

2. Features

- FM tuner for Japan, Europe, US and OIRT reception
- AM tuner for Long Wave (LW), Medium Wave (MW) and Short Wave (SW) reception
- Integrated AM Radio Frequency (RF) selectivity
- Integrated PLL tuning system; controlled via I²C-bus including automatic low/high side Local Oscillator (LO) injection
- Fully integrated LO
- No alignment needed
- Very easy application on the main board
- No critical RF components
- Fully integrated Intermediate Frequency (IF) filters and FM stereo decoder
- Fully integrated FM noise blanker
- Fully integrated AM audio noise blanker
- Field strength (LEVEL), multipath [Wideband AM (WAM)], noise [UltraSonic Noise (USN)] and deviation dependent stereo blend
- Field strength (LEVEL), multipath (WAM), noise (USN) and deviation dependent High-Cut Control (HCC)
- Field strength (LEVEL), multipath (WAM) and noise (USN) dependent soft mute
- Adjacent channel and deviation dependent IF bandwidth control [Precision Adjacent Channel Suppression (PACS)]
- Single power supply
- Qualified in accordance with AEC-Q100

3. Quick reference data

Table 1. Quick reference data

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|----------|----------------|--|-----|-----|-----|------|
| V_{CC} | supply voltage | on pins V_{CC1} and V_{CC2} | 8 | 8.5 | 9 | V |
| I_{CC} | supply current | into pins V_{CC1} , V_{CC2} and V_{REGSUP} | | | | |
| | | FM | 90 | 120 | 140 | mA |
| | | AM | 100 | 134 | 150 | mA |

FM path

| | | | | | | |
|------------------|----------------------------------|--|----|-----|-----|------------|
| f_{RF} | RF frequency | FM tuning range | 65 | - | 108 | MHz |
| $V_{i(sens)}$ | input sensitivity voltage | (S+N)/N = 26 dB; including weak signal handling | - | 5 | - | dB μ V |
| (S+N)/N | signal plus noise-to-noise ratio | $V_{i(RF)} = 1$ mV; $\Delta f = 22.5$ kHz | 55 | 60 | - | dB |
| THD | total harmonic distortion | mono; $\Delta f = 75$ kHz; $V_{i(RF)} = 1$ mV | - | 0.4 | 0.8 | % |
| α_{image} | image rejection | $f_{RF(image)} = f_{RF(wanted)} \pm 2 \times f_{IF}$ | 50 | 60 | - | dB |
| α_{cs} | channel separation | $V_{i(RF)} = 1$ mV; data byte Fh bits CHSEP[2:0] = 100 | 26 | 40 | - | dB |

AM path

| | | | | | | |
|------------------|----------------------------------|--|------|-----|--------|------------|
| f_{RF} | RF frequency | tuning range | | | | |
| | | AM (LW) tuning range | 144 | - | 288 | kHz |
| | | AM (MW) tuning range | 522 | - | 1710 | kHz |
| | | AM (SW) tuning range | 2.94 | - | 18.135 | MHz |
| $V_{i(sens)}$ | input sensitivity voltage | S/N = 26 dB; data byte 3h bits DEMP[1:0] = 10; MW | - | 34 | - | dB μ V |
| (S+N)/N | signal plus noise-to-noise ratio | $V_{i(RF)} = 10$ mV | 50 | 56 | - | dB |
| THD | total harmonic distortion | $V_{i(RF)} = 1$ mV; m = 80 % | - | 0.7 | 1 | % |
| α_{image} | image rejection | $f_{RF(image)} = f_{RF(wanted)} \pm 2 \times f_{IF}$ | 45 | 55 | - | dB |

4. Ordering information

Table 2. Ordering information

| Type number | Package | | Version |
|-------------|---------|--|----------|
| | Name | Description | |
| TEF6606T | SO32 | plastic small outline package; 32 leads; body width 7.5 mm | SOT287-1 |

5. Block diagram

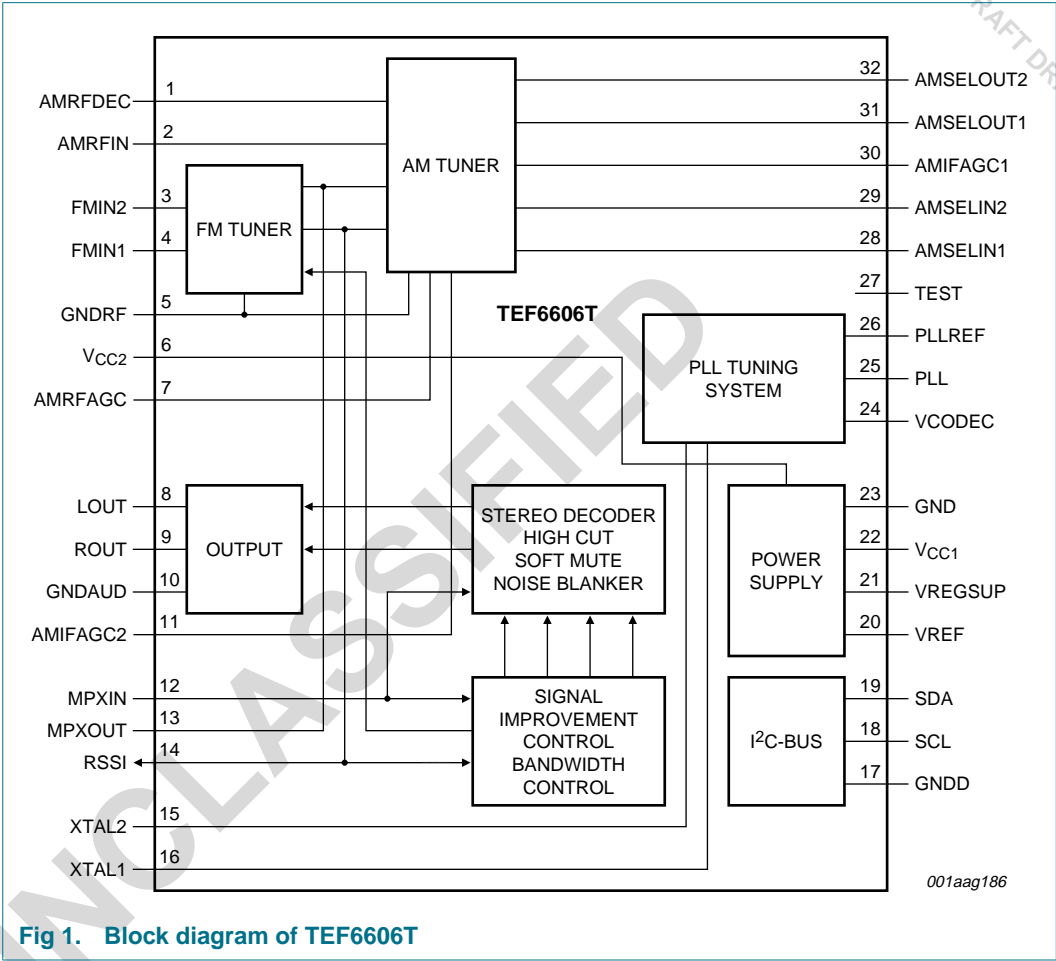


Fig 1. Block diagram of TEF6606T

6. Pinning information

6.1 Pinning

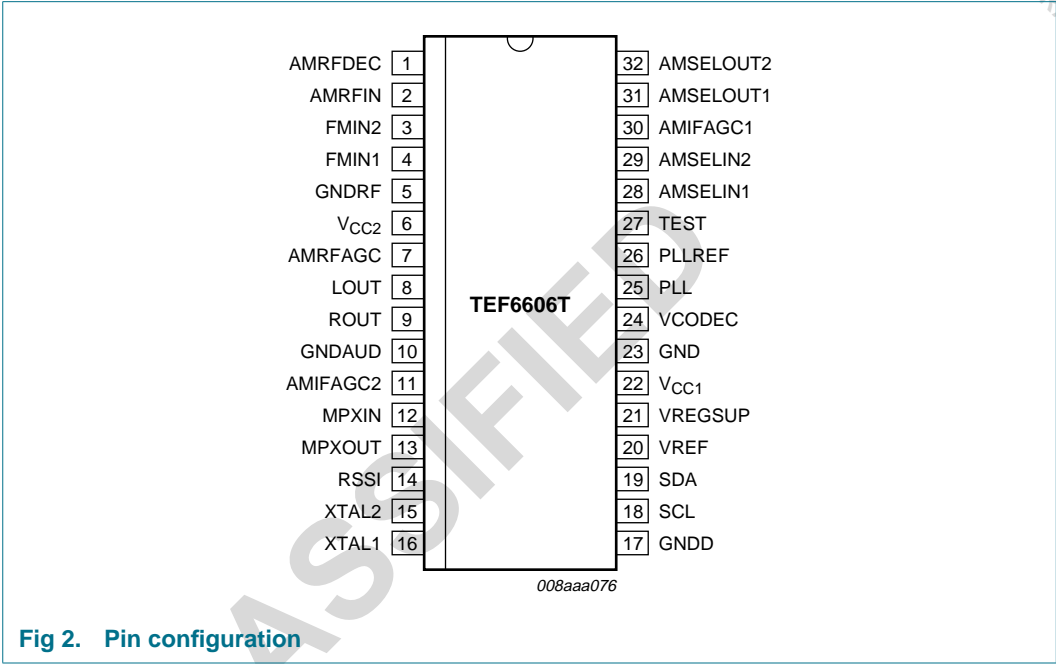


Fig 2. Pin configuration

6.2 Pin description

Table 3. Pin description

| Symbol | Pin | Description |
|------------------|-----|---|
| AMRFDEC | 1 | AM RF decoupling |
| AMRFIN | 2 | AM RF single-ended input |
| FMIN2 | 3 | FM RF differential input 2 |
| FMIN1 | 4 | FM RF differential input 1 |
| GNDRF | 5 | RF ground |
| V _{CC2} | 6 | supply voltage 2 |
| AMRFAGC | 7 | AM RF Automatic Gain Control (AGC) |
| LOUT | 8 | audio left output |
| ROUT | 9 | audio right output |
| GNDAUD | 10 | audio ground |
| AMIFAGC2 | 11 | AM IF AGC 2 |
| MPXIN | 12 | FM Multiplex (MPX) and AM audio input to stereo decoder |
| MPXOUT | 13 | FM MPX and AM audio output from tuner part |
| RSSI | 14 | Received Signal Strength Indication (RSSI) |
| XTAL2 | 15 | 4 MHz crystal oscillator pin 2 |
| XTAL1 | 16 | 4 MHz crystal oscillator pin 1 |
| GNDD | 17 | digital ground |
| SCL | 18 | I ² C-bus clock input |

Table 3. Pin description ...continued

| Symbol | Pin | Description |
|------------------|-----|---|
| SDA | 19 | I ² C-bus data input and output |
| VREF | 20 | reference voltage decoupling |
| VREGSUP | 21 | supply voltage internal voltage regulators |
| V _{CC1} | 22 | supply voltage 1 |
| GND | 23 | ground |
| VCODEC | 24 | decoupling for Voltage-Controlled Oscillator (VCO) supply voltage |
| PLL | 25 | PLL tuning voltage |
| PLLREF | 26 | PLL reference voltage |
| TEST | 27 | test pin; leave open in normal operation |
| AMSELIN1 | 28 | AM selectivity input 1 |
| AMSELIN2 | 29 | AM selectivity input 2 |
| AMIFAGC1 | 30 | AM IF AGC 1 |
| AMSELOUT1 | 31 | AM selectivity output 1 |
| AMSELOUT2 | 32 | AM selectivity output 2 |

7. Functional description

7.1 FM tuner

The RF input signal is mixed to a low IF with inherent image suppression. The IF signal is filtered and demodulated. The complete signal path is fully integrated.

7.2 AM tuner

The RF signal is filtered and mixed to a low IF with inherent image suppression. The IF signals are filtered and demodulated. The signal path is highly integrated.

7.3 PLL tuning system

The PLL tuning system includes a fully integrated VCO. To avoid problems with unwanted signals on image side, the receiver controls automatically high-side or low-side injection.

7.4 Signal dependent FM IF bandwidth control

The bandwidth of the FM IF filter will be controlled by an adjacent channel detector and a deviation detector to optimize the reception.

7.5 FM stereo decoder

The MPX signal from the FM tuner is translated by the stereo decoder into a left and right audio channel. Good channel separation is achieved without alignment.

7.6 Weak signal processing and noise blanker

The reception quality of the station received is measured by a combination of detectors: field strength (LEVEL), multipath (WAM) and noise (USN). The audio processing functions soft mute, HCC and stereo blend are controlled accordingly to maintain the best possible

audio quality in case of poor signal conditions. Audio disturbances like e.g. ignition noise are suppressed by the noise blanker circuit, using USN detection on MPX and spike detection on the level signal.

7.7 I²C-bus transceiver

The IC can be controlled by means of the I²C-bus including fast mode.

8. I²C-bus protocol

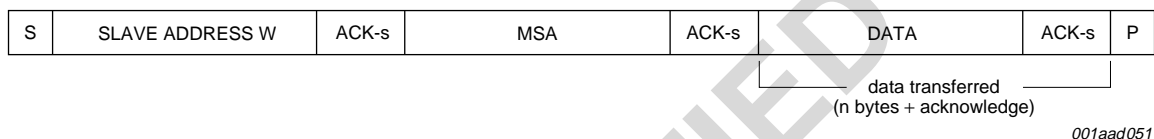


Fig 3. Write mode

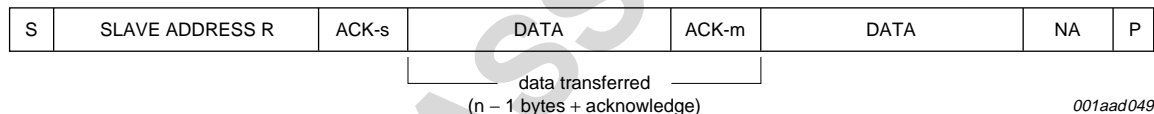


Fig 4. Read mode

Table 4. Description of I²C-bus format

| Code | Description |
|-----------------|-------------------------------------|
| S | START condition |
| Slave address W | 1100 0000b |
| Slave address R | 1100 0001b |
| ACK-s | acknowledge generated by the slave |
| ACK-m | acknowledge generated by the master |
| NA | not acknowledge |
| MSA | mode and subaddress byte |
| Data | data byte |
| P | STOP condition |

8.1 Read mode

Table 5. Read register overview

| Data byte | Name | Reference |
|-----------|-----------|-------------------------------|
| 0h | STATUS | Section 8.1.1 |
| 1h | LEVEL | Section 8.1.2 |
| 2h | USN_WAM | Section 8.1.3 |
| 3h | IFCOUNTER | Section 8.1.4 |
| 4h | ID | Section 8.1.5 |

8.1.1 Read mode: data byte STATUS

Table 6. STATUS - data byte 0h bit allocation

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------|-----|------|---|---|------|------|
| QRS1 | QRS0 | POR | STIN | - | - | TAS1 | TAS0 |

Table 7. STATUS - data byte 0h bit description

| Bit | Symbol | Description |
|---------|----------|---|
| 7 and 6 | QRS[1:0] | quality read status ^[1] <ul style="list-style-type: none"> 00 = no quality data available (tuning is in progress or quality data is settling) 01 = quality data (LEVEL, USN and WAM) available; for IF counter check the IFCS status 10 = AF update quality data available of LEVEL, USN, WAM and IF counter 11 = not used |
| 5 | POR | power-on reset indicator <ul style="list-style-type: none"> 0 = standard operation 1 = power on or power dip detected; I²C-bus settings are lost |
| 4 | STIN | stereo indicator <ul style="list-style-type: none"> 0 = no pilot detected 1 = stereo pilot detected |
| 3 and 2 | - | not used |
| 1 and 0 | TAS[1:0] | tuning action state <ul style="list-style-type: none"> 00 = tuning not active; not muted 01 = muting in progress 10 = tuning in progress 11 = tuning ready and muted |

[1] When PLL tuning is ready the quality detectors are reset for fastest result. In FM mode the first reliable quality result of LEVEL, USN and WAM is available from 1 ms after reset. In AM mode the first level result is available from 1 ms, gradually changing from peak LEVEL towards average LEVEL realizing the maximum attenuation of AM modulation influence from 32 ms. The quality result of an AF update tuning is stored and can be read at any time later.

8.1.2 Read mode: data byte LEVEL

Table 8. LEVEL - data byte 1h bit allocation

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------|------|------|------|------|------|------|
| LEV7 | LEV6 | LEV5 | LEV4 | LEV3 | LEV2 | LEV1 | LEV0 |

Table 9. LEVEL - data byte 1h bit description

| Bit | Symbol | Description |
|--------|----------|--|
| 7 to 0 | LEV[7:0] | level detector (RSSI) output signal via fast level detector timing <ul style="list-style-type: none"> 0 to 255 = 0.25 V to 4.25 V |

8.1.3 Read mode: data byte USN_WAM

Table 10. USN_WAM - data byte 2h bit allocation

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------|------|------|------|------|------|------|
| USN3 | USN2 | USN1 | USN0 | WAM3 | WAM2 | WAM1 | WAM0 |

Table 11. USN_WAM - data byte 2h bit description

| Bit | Symbol | Description |
|--------|----------|--|
| 7 to 4 | USN[3:0] | FM ultrasonic noise 0 to 15 = 0 % to 100 % equivalent FM modulation at 100 kHz ultrasonic noise content (USN) |
| 3 to 0 | WAM[3:0] | FM wideband AM (multipath) 0 to 15 = 0 % to 100 % AM modulation at 20 kHz wideband AM content (WAM) |

8.1.4 Read mode: data byte IFCOUNTER

Table 12. IFCOUNTER - data byte 3h bit allocation

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-------|------|------|------|------|------|------|
| IFCS1 | IFCS0 | IFCN | IFC4 | IFC3 | IFC2 | IFC1 | IFC0 |

Table 13. IFCOUNTER - data byte 3h bit description

| Bit | Symbol | Description |
|---------|-----------|---|
| 7 and 6 | IFCS[1:0] | IF counter status ^[1] 00 = no first counter result available 01 = first counter result available from 2 ms count time 10 = counter result available from 8 ms count time 11 = counter result available from 32 ms count time |
| 5 | IFCN | IF count result negative 0 = positive RF frequency difference 1 = negative RF frequency difference |
| 4 to 0 | IFC[4:0] | IF counter result; see Table 14 |

[1] When PLL tuning is ready the IF counter and other quality detectors are reset for fastest result. The first IF counter result is available from 2 ms after reset. Further results are available from 8 ms and 32 ms after reset, reducing the influence of FM modulation on the counter result. Later counter results are available at a count time of 32 ms.

Table 14. IF counter result

| IFC4 | IFC3 | IFC2 | IFC1 | IFC0 | Frequency difference | |
|------|------|------|------|------|----------------------|------------------|
| | | | | | FM | AM |
| 0 | 0 | 0 | 0 | 0 | 0 kHz to 5 kHz | 0 kHz to 0.5 kHz |
| 0 | 0 | 0 | 0 | 1 | 5 kHz to 10 kHz | 0.5 kHz to 1 kHz |
| 0 | 0 | 0 | 1 | 0 | 10 kHz to 15 kHz | 1 kHz to 1.5 kHz |
| 0 | 0 | 0 | 1 | 1 | 15 kHz to 20 kHz | 1.5 kHz to 2 kHz |
| 0 | 0 | 1 | 0 | 0 | 20 kHz to 25 kHz | 2 kHz to 2.5 kHz |

Table 14. IF counter result ...continued

| IFC4 | IFC3 | IFC2 | IFC1 | IFC0 | Frequency difference | |
|------|------|------|------|------|----------------------|--------------------|
| | | | | | FM | AM |
| : | : | : | : | : | : | : |
| 1 | 1 | 1 | 1 | 0 | 150 kHz to 155 kHz | 15 kHz to 15.5 kHz |
| 1 | 1 | 1 | 1 | 1 | > 155 kHz | > 15.5 kHz |

8.1.5 Read mode: data byte ID

Table 15. ID - data byte 4h bit allocation

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|-------|-------|-------|---|-----|-----|-----|
| TINJ | IFBW2 | IFBW1 | IFBW0 | - | ID2 | ID1 | ID0 |

Table 16. ID - data byte 4h bit description

| Bit | Symbol | Description |
|--------|-----------|--|
| 7 | TINJ | LO injection 0 = low injection LO 1 = high injection LO |
| 6 to 4 | IFBW[2:0] | IF bandwidth information 000 to 111 = narrow to wide FM IF filter bandwidth |
| 3 | - | not used |
| 2 to 0 | ID[2:0] | device type identification 010 = TEF6606 |

8.2 Write mode

Table 17. Write mode subaddress overview

| Subaddress | Name | Default | Reference |
|------------|--------------|------------|--------------------------------|
| 0h | TUNER0 | 0010 0110b | Section 8.2.2 |
| 1h | TUNER1 | 1111 1010b | Section 8.2.3 |
| 2h | TUNER2 | 0000 0000b | Section 8.2.4 |
| 3h | RADIO | 1000 0000b | Section 8.2.5 |
| 4h | SOFTMUTE0 | 0000 0000b | Section 8.2.6 |
| 5h | SOFTMUTE1 | 0000 0000b | Section 8.2.7 |
| 6h | SOFTMUTE2_FM | 0000 0000b | Section 8.2.8 |
| 6h | SOFTMUTE2_AM | 0000 0000b | Section 8.2.9 |
| 7h | HIGHCUT0 | 0000 0000b | Section 8.2.10 |
| 8h | HIGHCUT1 | 0000 0000b | Section 8.2.11 |
| 9h | HIGHCUT2 | 0000 0000b | Section 8.2.12 |
| Ah | STEREO0 | 0000 0000b | Section 8.2.13 |
| Bh | STEREO1 | 0000 0000b | Section 8.2.14 |
| Ch | STEREO2 | 0000 0000b | Section 8.2.15 |
| Dh | CONTROL | 0001 0100b | Section 8.2.16 |
| Eh | LEVEL_OFFSET | 0100 0000b | Section 8.2.17 |
| Fh | AM_LNA | 0011 1100b | Section 8.2.18 |

8.2.1 Mode and subaddress byte for write

Table 18. MSA - mode and subaddress byte bit allocation

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-------|-------|---|-----|-----|-----|-----|
| MODE2 | MODE1 | MODE0 | 0 | SA3 | SA2 | SA1 | SA0 |

Table 19. MSA - mode and subaddress byte bit description

| Bit | Symbol | Description |
|--------|-----------|------------------------------------|
| 7 to 5 | MODE[2:0] | mode; see Table 20 |
| 4 | - | not used, must be set to logic 0 |
| 3 to 0 | SA[3:0] | subaddress |

Table 20. Tuning action modes

| MODE2 | MODE1 | MODE0 | Symbol | Description |
|-------|-------|-------|-------------|--|
| 0 | 0 | 0 | standard | write without tuning action |
| 0 | 0 | 1 | preset | tune to new station with short mute time; see Figure 5 |
| 0 | 1 | 0 | search | tune to new station and stay muted; see Figure 6 and Figure 7 |
| 0 | 1 | 1 | AF update | tune to AF station; store AF quality and tune back to main station; see Figure 8 and Figure 9 |
| 1 | 0 | 0 | AF jump | tune to AF station in minimum mute time; see Figure 10 and Figure 11 |
| 1 | 0 | 1 | AF check | tune to AF station and stay muted; swap; see Figure 12 , Figure 13 and Figure 14 |
| 1 | 1 | 0 | mirror test | check current image situation and select injection mode for best result; see Figure 15 |
| 1 | 1 | 1 | end | end; release mute from search mode or AF check mode |

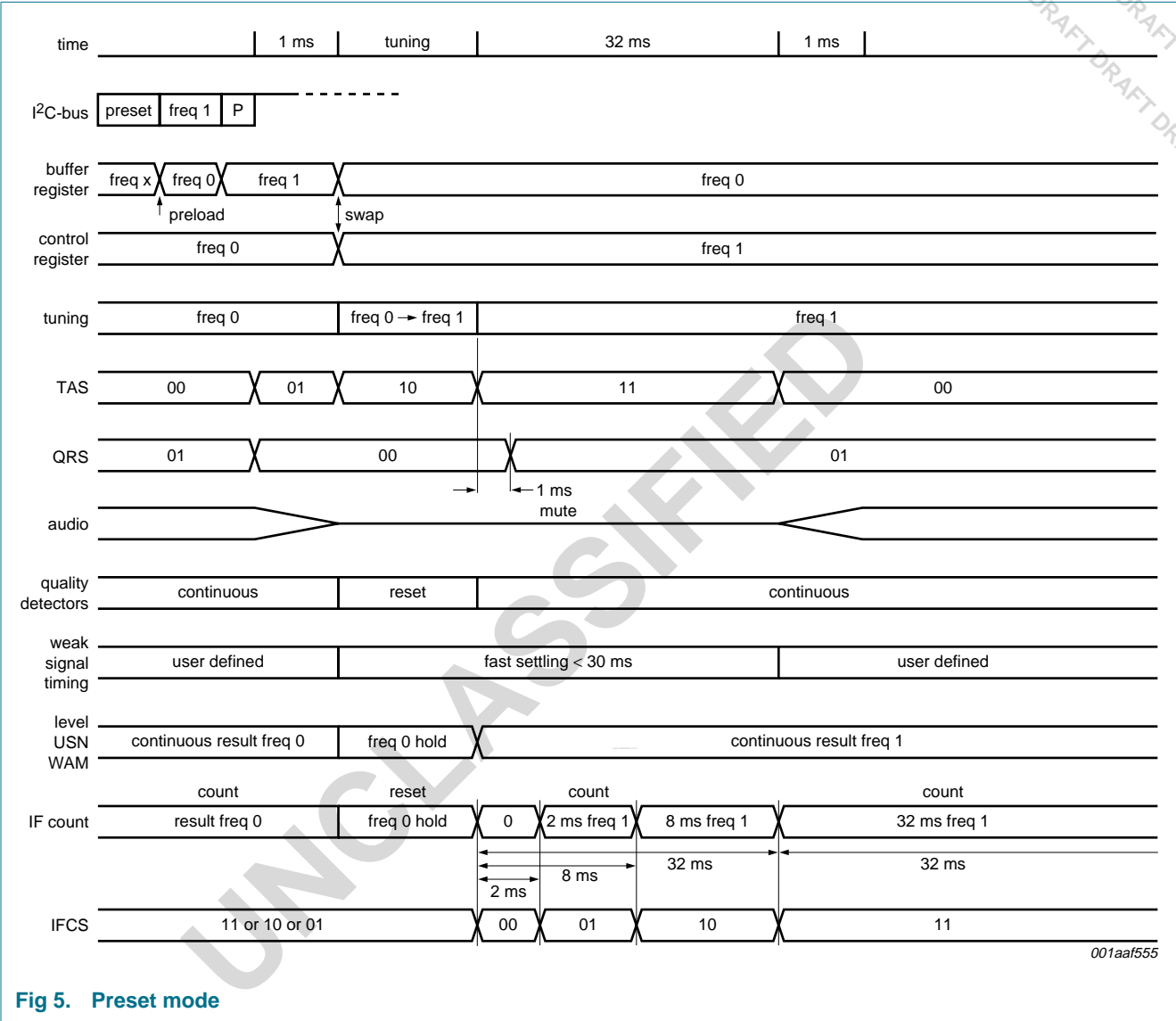


Fig 5. Preset mode

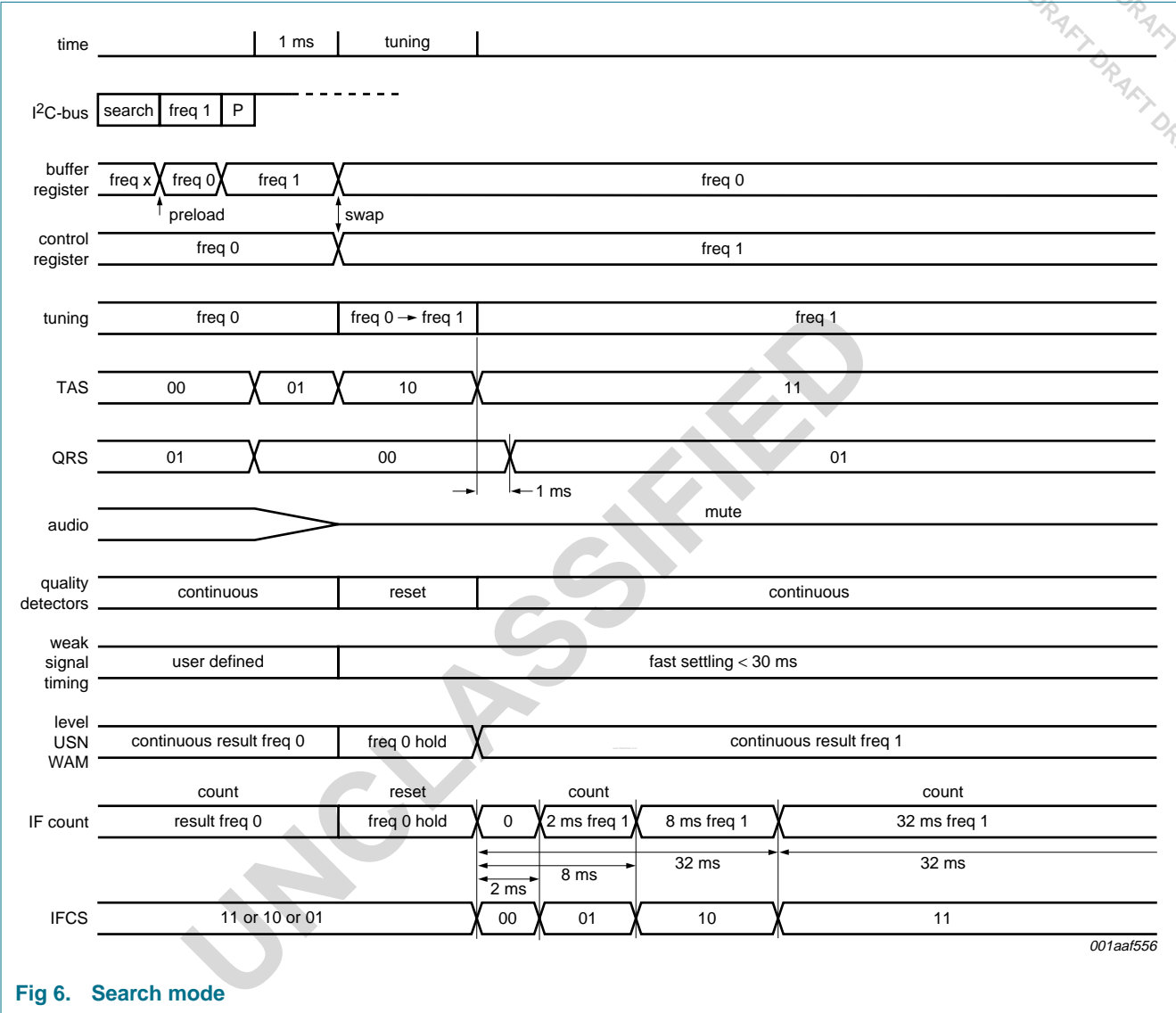


Fig 6. Search mode

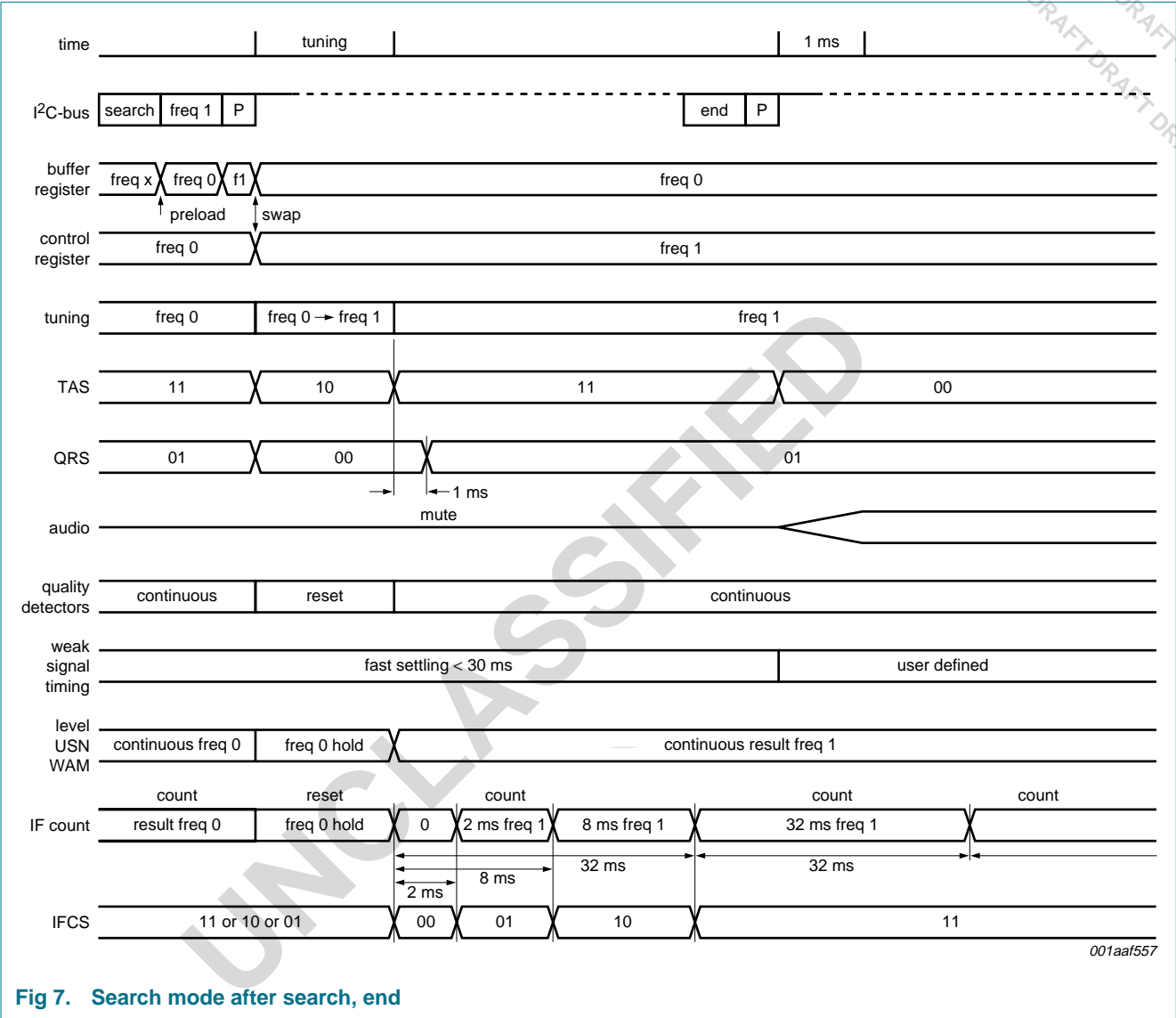


Fig 7. Search mode after search, end

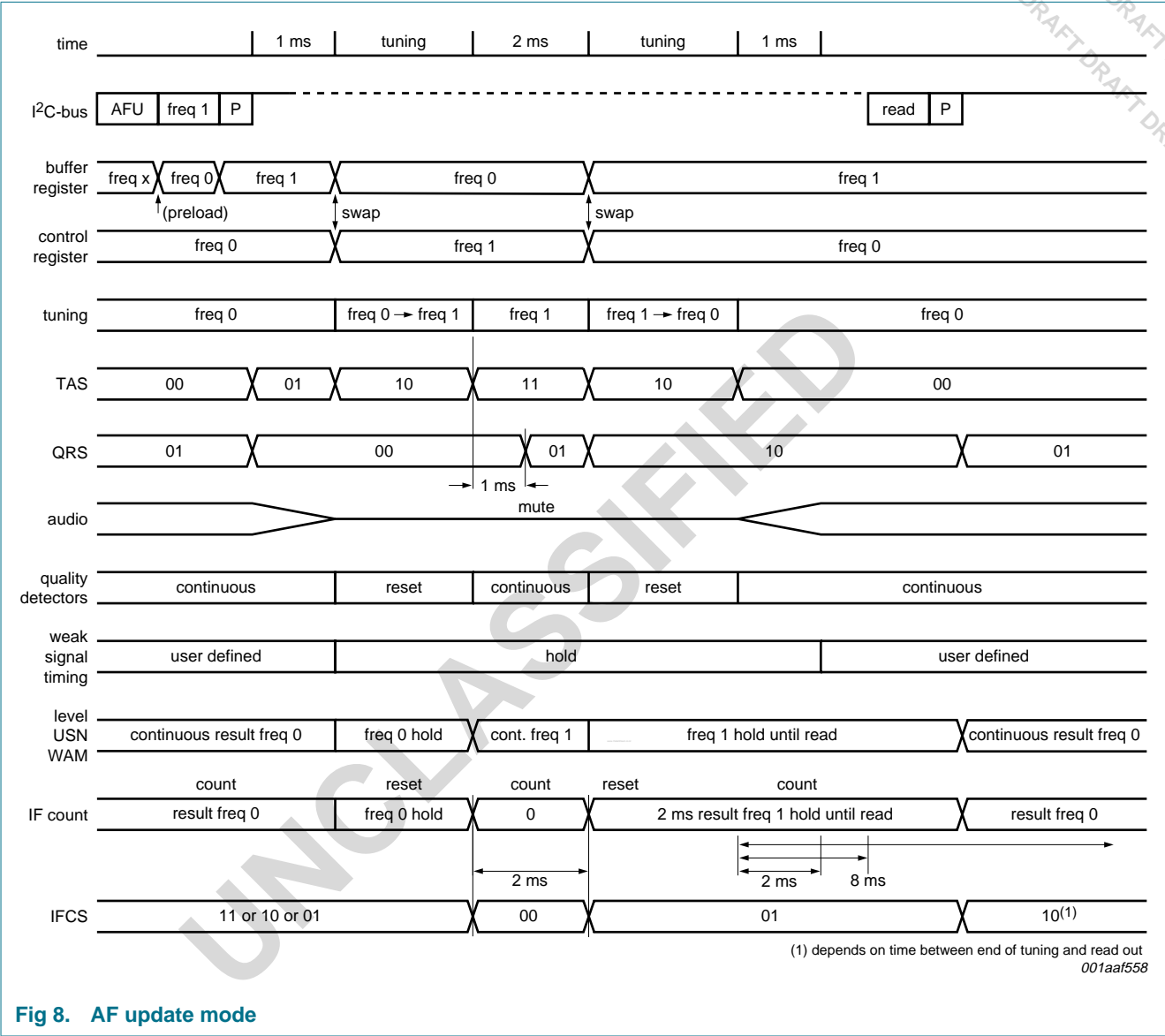


Fig 8. AF update mode

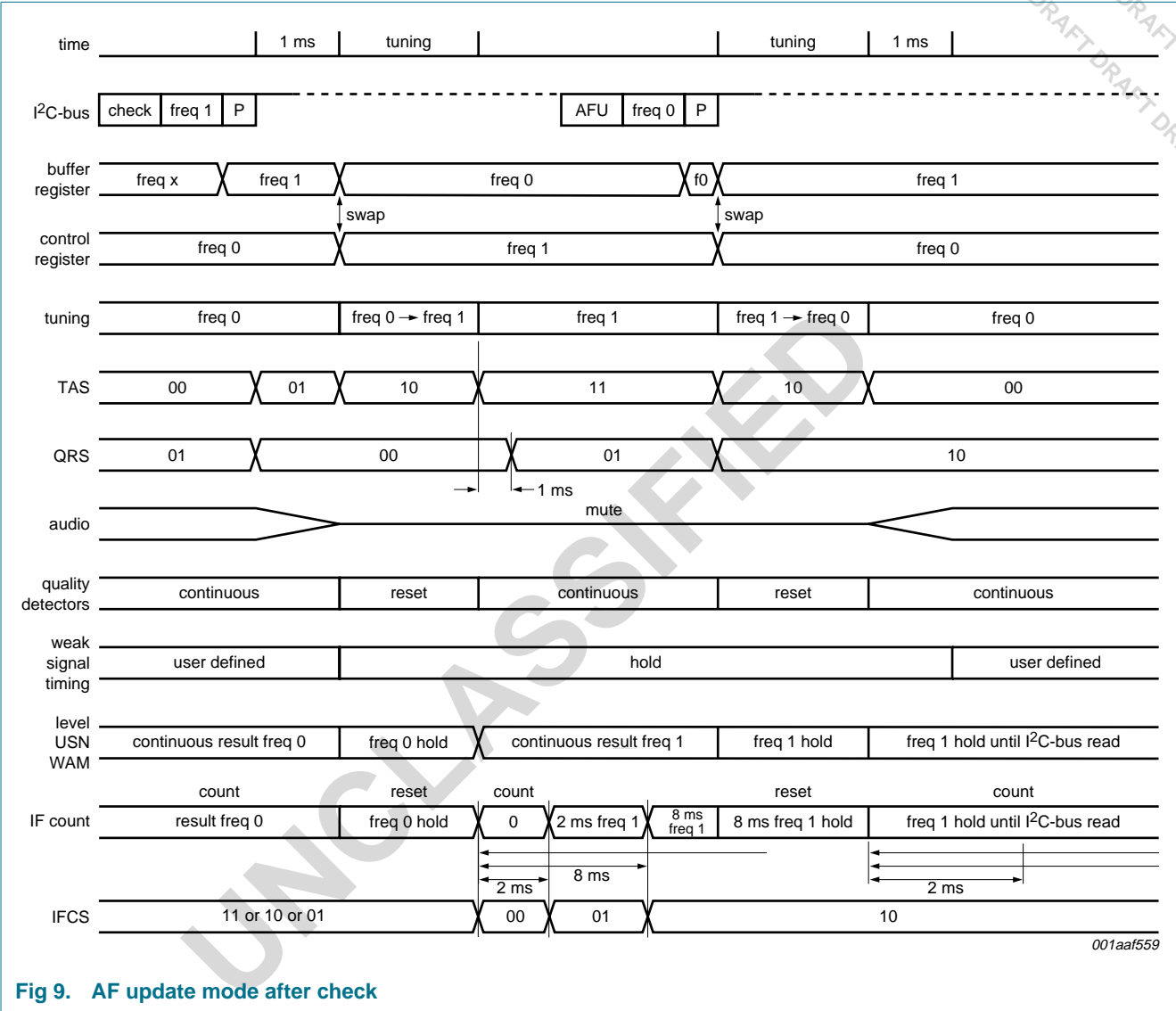


Fig 9. AF update mode after check

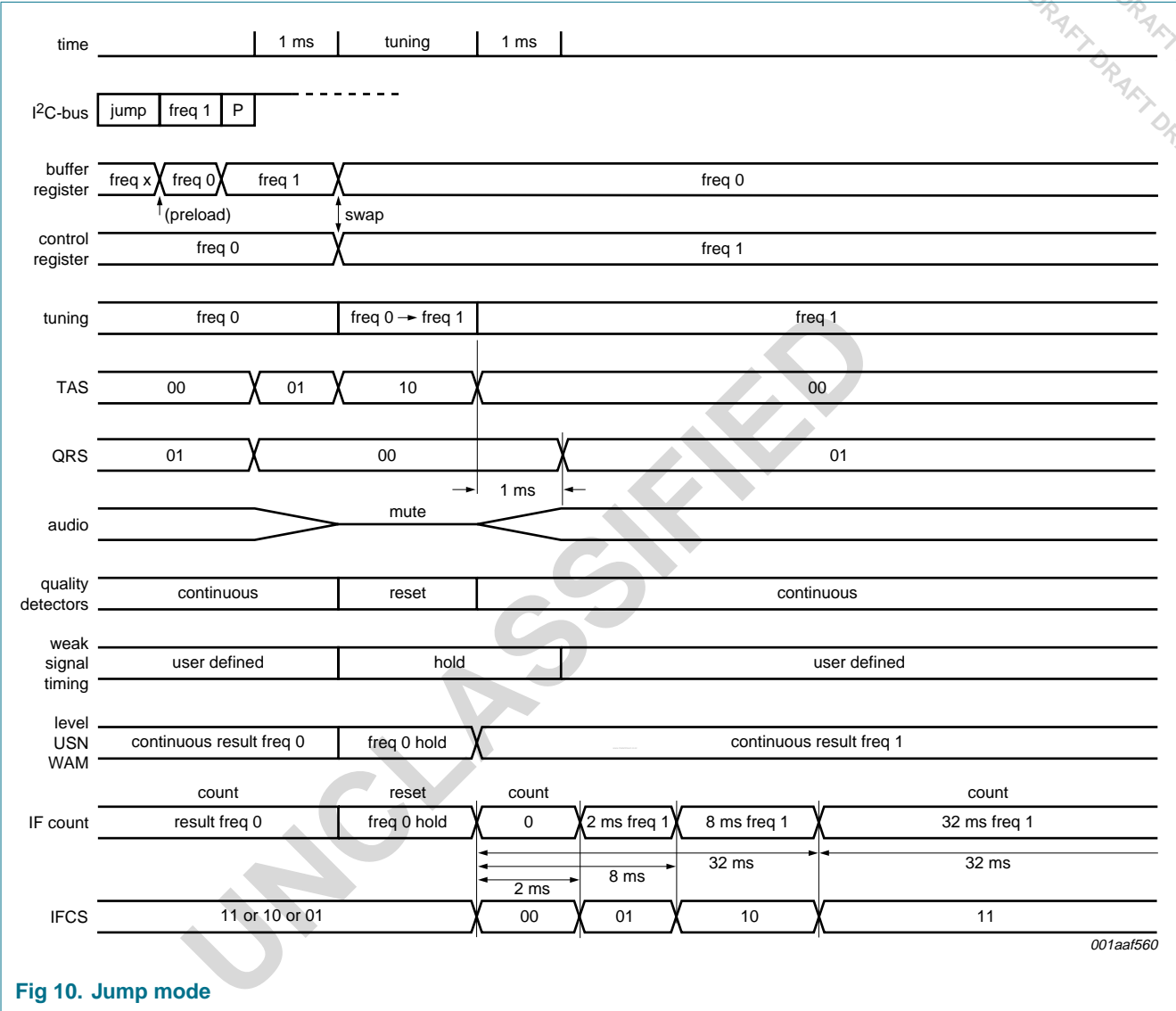


Fig 10. Jump mode

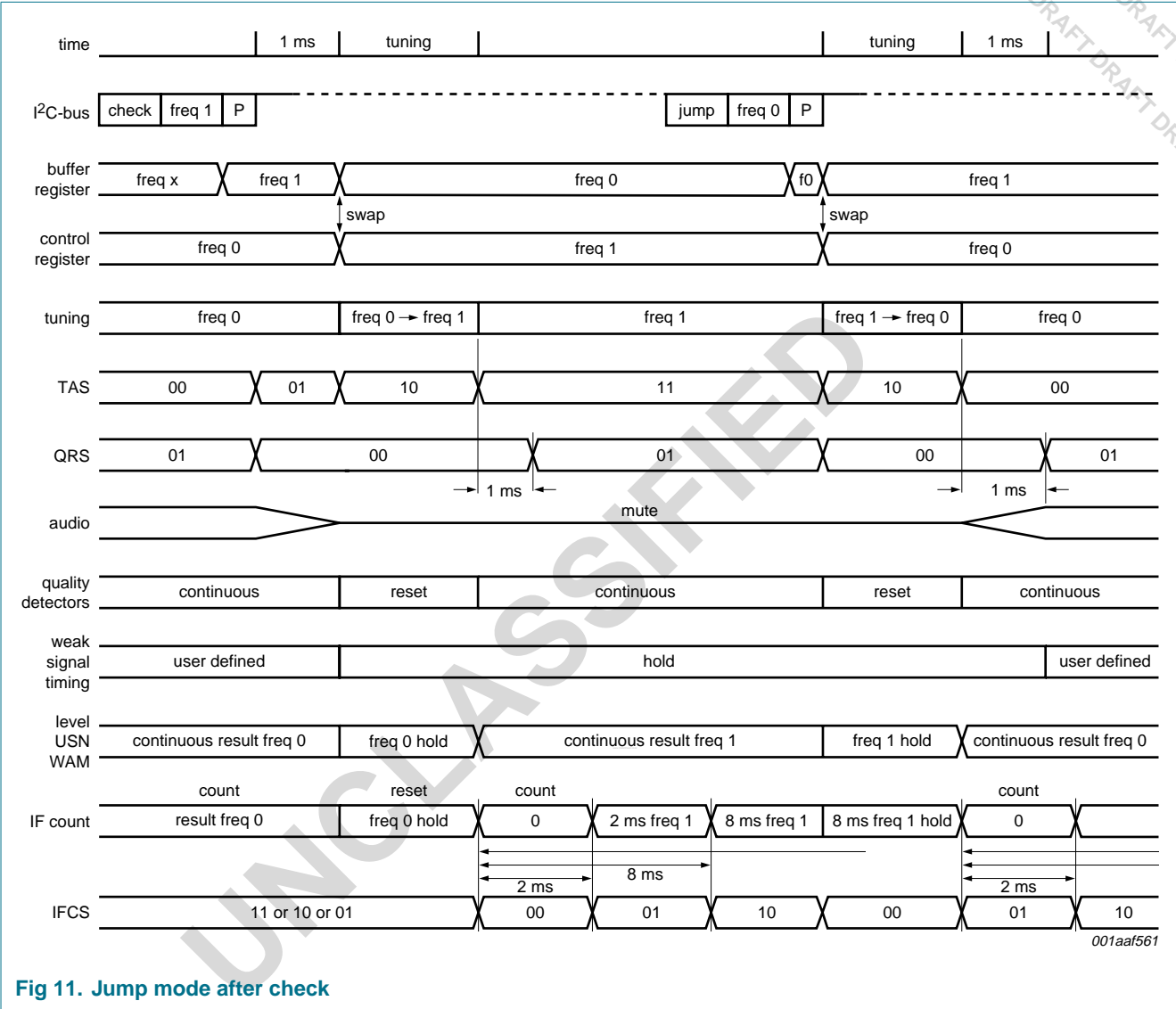


Fig 11. Jump mode after check

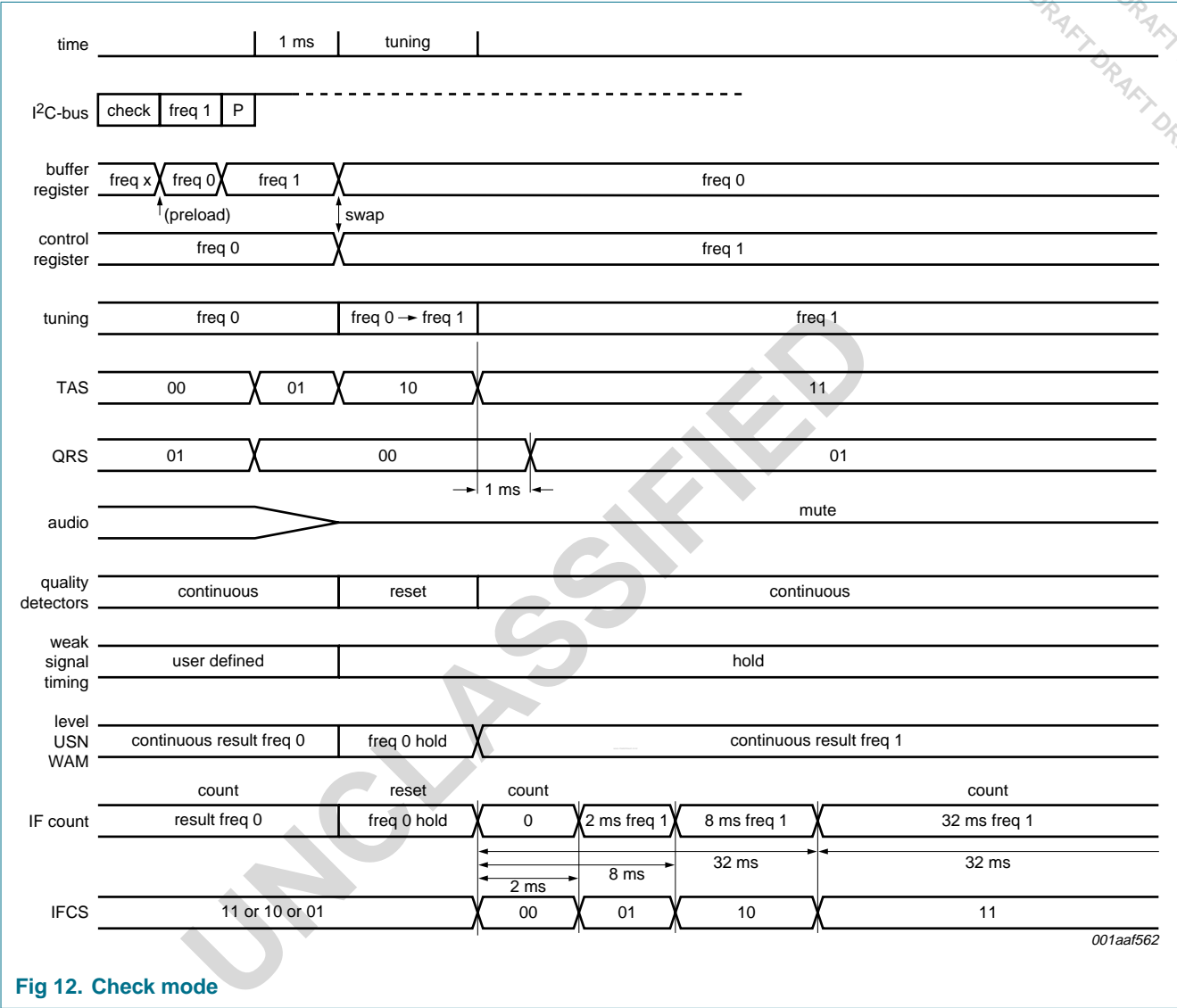


Fig 12. Check mode

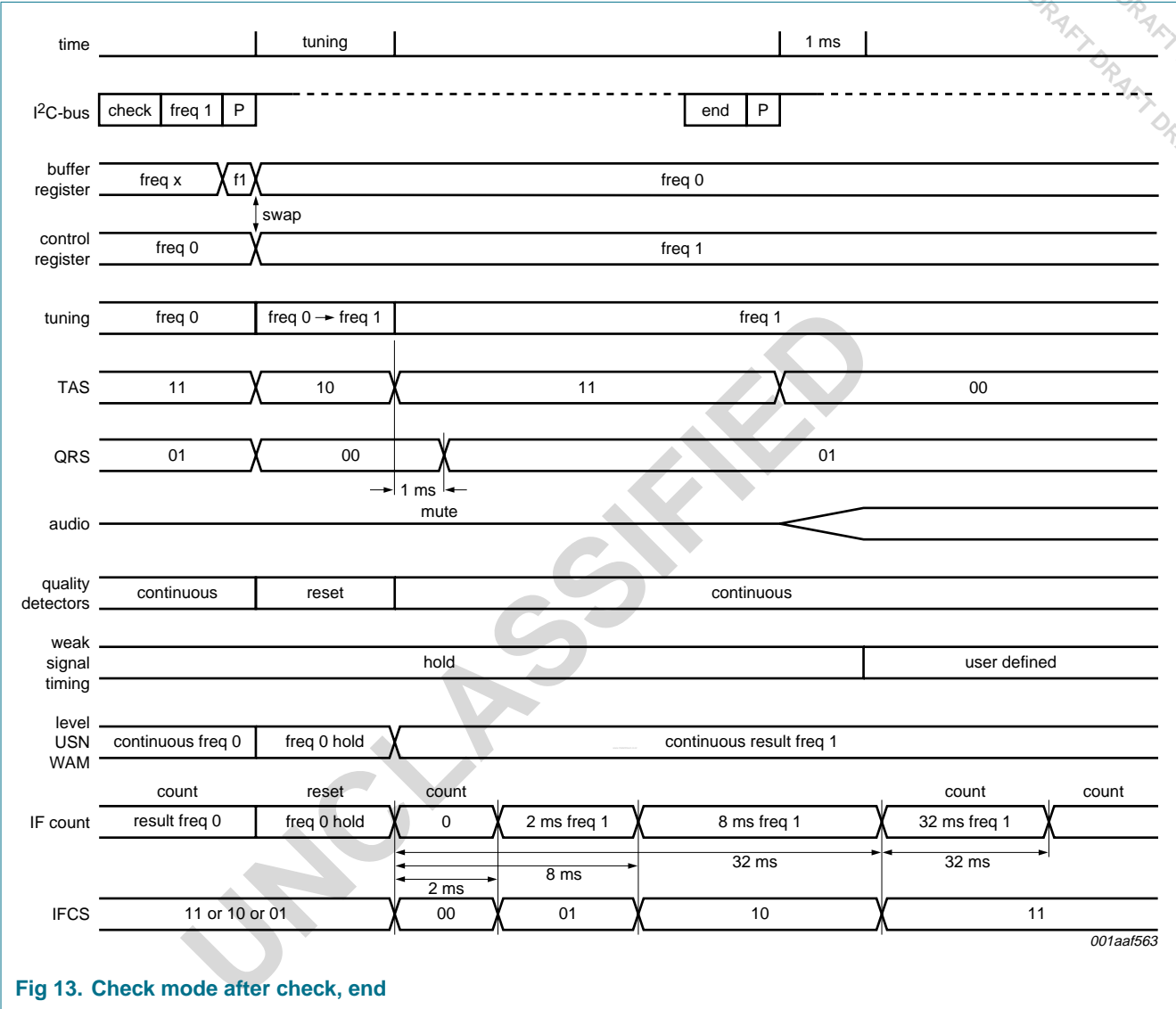


Fig 13. Check mode after check, end

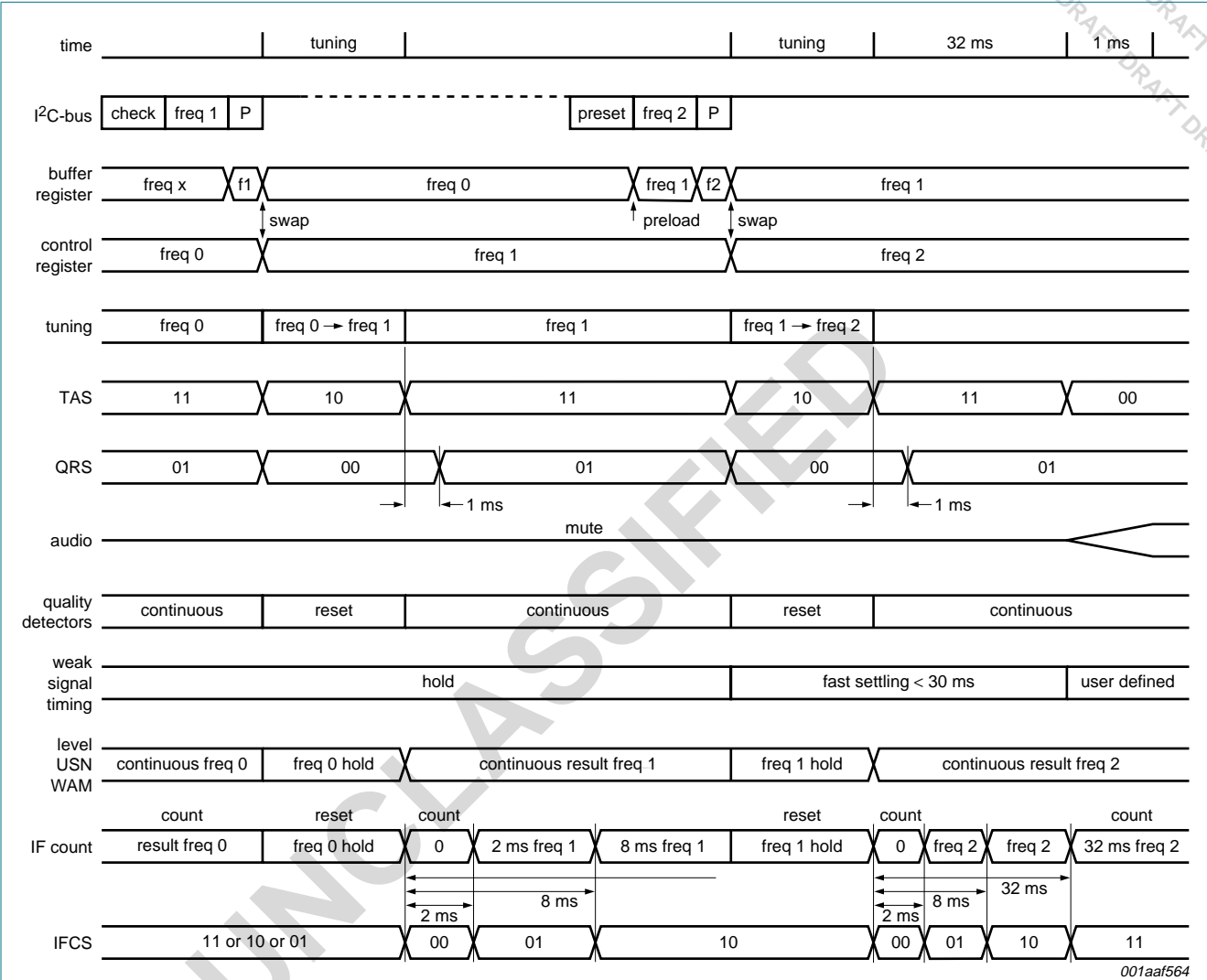


Fig 14. Check mode after check, preset

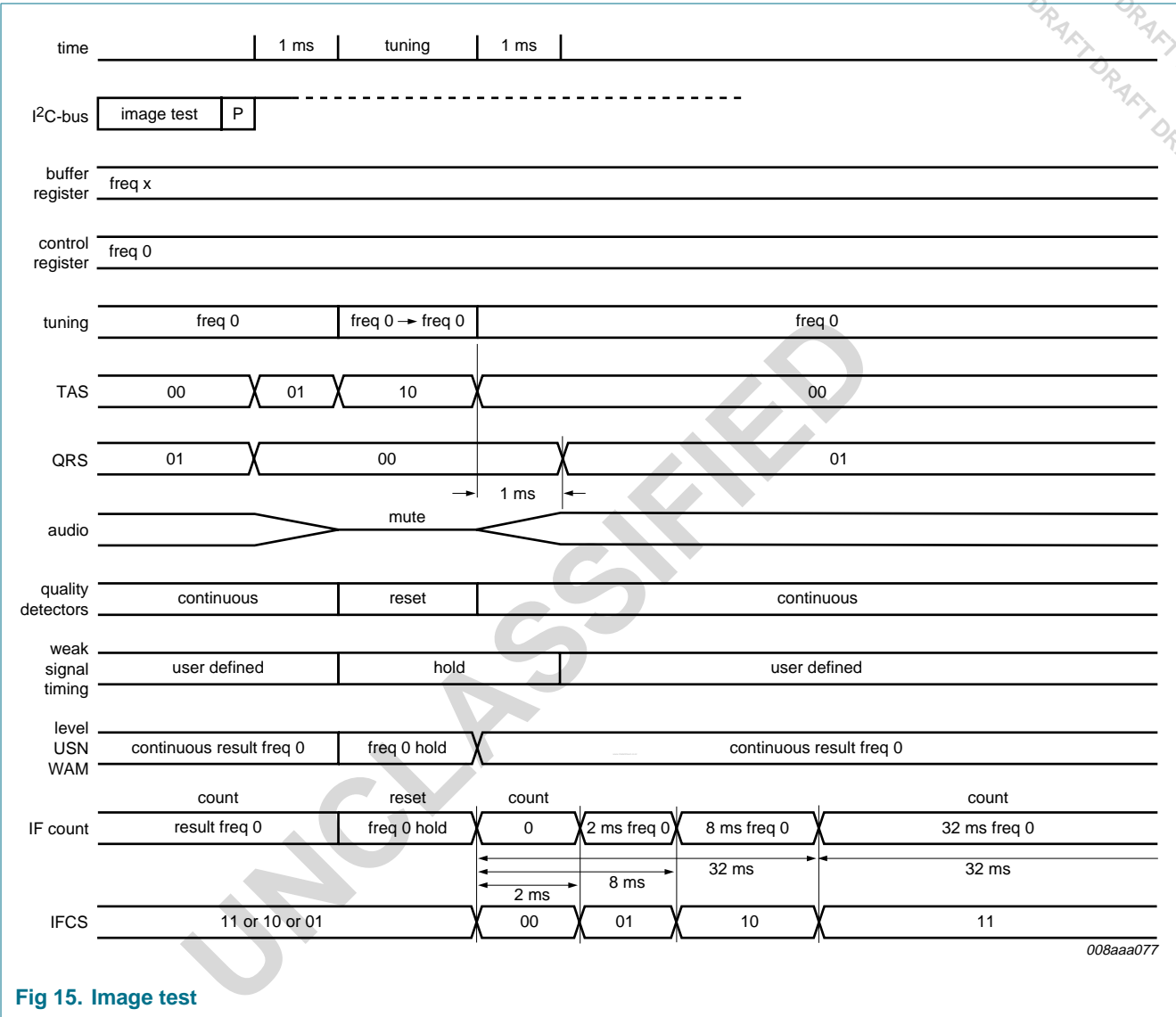


Fig 15. Image test

8.2.2 Write mode: data byte TUNER0

Table 21. TUNER0 - data byte 0h bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|-------|-------|--------|--------|--------|-------|-------|
| 0 | BAND1 | BAND0 | FREQ12 | FREQ11 | FREQ10 | FREQ9 | FREQ8 |
| | 0 | 1 | 0 | 0 | 1 | 1 | 0 |

Table 22. TUNER0 - data byte 0h bit description

| Bit | Symbol | Description |
|---------|------------|---|
| 7 | - | not used, must be set to logic 0 |
| 6 and 5 | BAND[1:0] | frequency band ^[1] 00 = AM: LW and MW 01 = FM: standard Europe, USA and Japan 10 = AM: SW 11 = FM: OIRT (eastern Europe) |
| 4 to 0 | FREQ[12:8] | upper byte of tuning frequency word ^[1] ; see Table 25 |

[1] For a correct tuning result a change in the BAND or FREQ setting should always be combined with a tuning action of modes 001 to 101.

8.2.3 Write mode: data byte TUNER1

Table 23. TUNER1 - data byte 1h bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| FREQ7 | FREQ6 | FREQ5 | FREQ4 | FREQ3 | FREQ2 | FREQ1 | FREQ0 |
| 1 | 1 | 1 | 1 | 1 | 0 | 1 | 0 |

Table 24. TUNER1 - data byte 1h bit description

| Bit | Symbol | Description |
|--------|-----------|---|
| 7 to 0 | FREQ[7:0] | lower byte of tuning frequency word ^[1] ; see Table 25 |

[1] For a correct tuning result a change in the BAND or FREQ setting should always be combined with a tuning action of MODE[2:0] = 001 to 101.

Table 25. Tuning frequency

| BAND | FREQ[12:0] value | Reception frequency | Frequency correlation | Step |
|------------------------------------|------------------|-----------------------|--|--------|
| AM: LW and MW | 144 to 1720 | 144 kHz to 1720 kHz | $FREQ[12:0] = f_{RF} \text{ [kHz]}$ | 1 kHz |
| FM: standard Europe, USA and Japan | 1520 to 2160 | 76 MHz to 108 MHz | $FREQ[12:0] = f_{RF} \text{ [MHz]} \times 20$ | 50 kHz |
| AM: SW | 588 to 3627 | 2940 kHz to 18135 kHz | $FREQ[12:0] = f_{RF} \text{ [kHz]} \times 5$ | 5 kHz |
| FM: OIRT (eastern Europe) | 6581 to 7400 | 65 MHz to 74 MHz | $FREQ[12:0] = f_{RF} \text{ [MHz]} \times 100$ | 10 kHz |

8.2.4 Write mode: data byte TUNER2

Table 26. TUNER2 - data byte 2h bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|------|------|---|-------|-------|-------|
| RFAGC1 | RFAGC0 | INJ1 | INJ0 | 0 | FMBW2 | FMBW1 | FMBW0 |
| 0 | 0 | 0 | 0 | | 0 | 0 | 0 |

Table 27. TUNER2 - data byte 2h bit description

| Bit | Symbol | Description |
|---------|------------|--|
| 7 and 6 | RFAGC[1:0] | AM RF AGC sensitivity control 00 = AGC threshold not reduced 01 = AGC threshold reduced by 2 dB 10 = AGC threshold reduced by 4 dB 11 = AGC threshold reduced by 6 dB FM RF AGC sensitivity control 00 = AGC threshold reduced by 6 dB 01 = AGC threshold reduced by 4 dB 10 = AGC threshold reduced by 2 dB 11 = AGC threshold not reduced |
| 5 and 4 | INJ[1:0] | injection ^[1] 00 = automatic injection 01 = high injection LO 10 = low injection LO 11 = undefined, do not use |
| 3 | - | not used, must be set to logic 0 |
| 2 to 0 | FMBW[2:0] | FM bandwidth control 0 = dynamic mode (optimum bandwidth is selected depending on reception conditions) 001 to 111 = narrow to wide FM IF filter bandwidth |

[1] For a correct tuning result a change in the INJ setting should always be combined with MODE[2:0] = 110 or a tuning action of MODE[2:0] = 001 to 101.

8.2.5 Write mode: data byte RADIO

Table 28. RADIO - data byte 3h bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------|-------|------|-------|-------|---|------|
| NBS1 | NBS0 | LOCUT | MONO | DEMP1 | DEMP0 | 0 | OUTA |
| 1 | 0 | 0 | 0 | 0 | 0 | | 0 |

Table 29. RADIO - data byte 3h bit description

| Bit | Symbol | Description |
|---------|-----------|---|
| 7 and 6 | NBS[1:0] | AM and FM noise blanker sensitivity control 00 = AM and FM noise blanker off 01 = low AM and FM noise blanker sensitivity 10 = medium AM and FM noise blanker sensitivity 11 = high AM and FM noise blanker sensitivity |
| 5 | LOCUT | control of audio high-pass filter 0 = no limitation (−3 dB at 7 Hz) 1 = high-pass function (−3 dB at 100 Hz) |
| 4 | MONO | mono/stereo switch 0 = FM stereo enabled 1 = FM stereo disabled (forced mono) |
| 3 and 2 | DEMP[1:0] | de-emphasis setting 00 = 50 μs de-emphasis 01 = 75 μs de-emphasis 10 = 103 μs low-pass 11 = not used |
| 1 | - | not used, must be set to logic 0 |
| 0 | OUTA | audio output gain 0 = low audio gain at LOUT and ROUT 1 = high audio gain at LOUT and ROUT |

8.2.6 Write mode: data byte SOFTMUTE0

Table 30. SOFTMUTE0 - data byte 4h bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|---|---|------|------|------|------|------|
| 0 | 0 | 0 | MAT2 | MAT1 | MAT0 | MRT1 | MRT0 |
| | | | 0 | 0 | 0 | 0 | 0 |

Table 31. SOFTMUTE0 - data byte 4h bit description

| Bit | Symbol | Description |
|---------|----------|--|
| 7 to 5 | - | not used, must be set to logic 0 |
| 4 to 2 | MAT[2:0] | soft mute slow attack time; see Table 32 |
| 1 and 0 | MRT[1:0] | soft mute slow recovery time |
| | | 00 = 2 times attack time |
| | | 01 = 4 times attack time |
| | | 10 = 8 times attack time |
| | | 11 = 16 times attack time |

Table 32. Soft mute attack time

| MAT2 | MAT1 | MAT0 | Soft mute attack time |
|------|------|------|-----------------------|
| 0 | 0 | 0 | 60 ms |
| 0 | 0 | 1 | 125 ms |
| 0 | 1 | 0 | 250 ms |
| 0 | 1 | 1 | 0.5 s |
| 1 | 0 | 0 | 1 s |
| 1 | 0 | 1 | 2 s |
| 1 | 1 | 0 | 4 s |
| 1 | 1 | 1 | 8 s |

8.2.7 Write mode: data byte SOFTMUTE1

Table 33. SOFTMUTE1 - data byte 5h bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------|---|------|------|------|------|------|
| MFOL | MSOL | 0 | MST2 | MST1 | MST0 | MSL1 | MSL0 |
| 0 | 0 | | 0 | 0 | 0 | 0 | 0 |

Table 34. SOFTMUTE1 - data byte 5h bit description

| Bit | Symbol | Description |
|---------|----------|---|
| 7 | MFOL | soft mute fast on level |
| | | 0 = no fast control on level |
| | | 1 = fast control on level active |
| 6 | MSOL | soft mute slow on level |
| | | 0 = no slow control on level |
| | | 1 = slow control on level active |
| 5 | - | not used, must be set to logic 0 |
| 4 to 2 | MST[2:0] | soft mute start on level |
| | | 000 to 111 = high threshold to low threshold of weak signal soft mute control; see Figure 16 and Figure 17 |
| 1 and 0 | MSL[1:0] | soft mute slope on level |
| | | 00 to 11 = low steepness to high steepness of slope of weak signal soft mute control; see Figure 16 and Figure 17 |

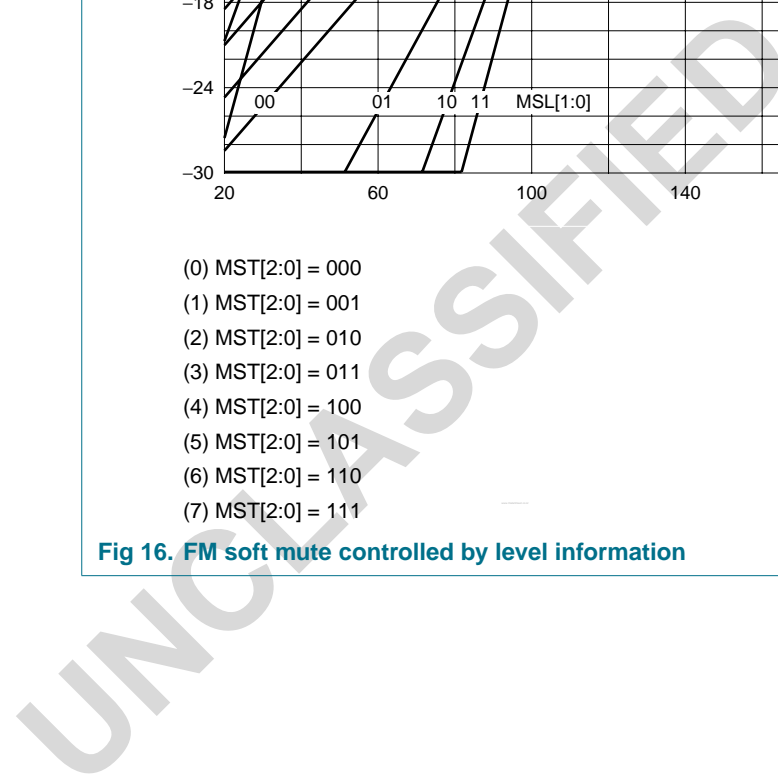
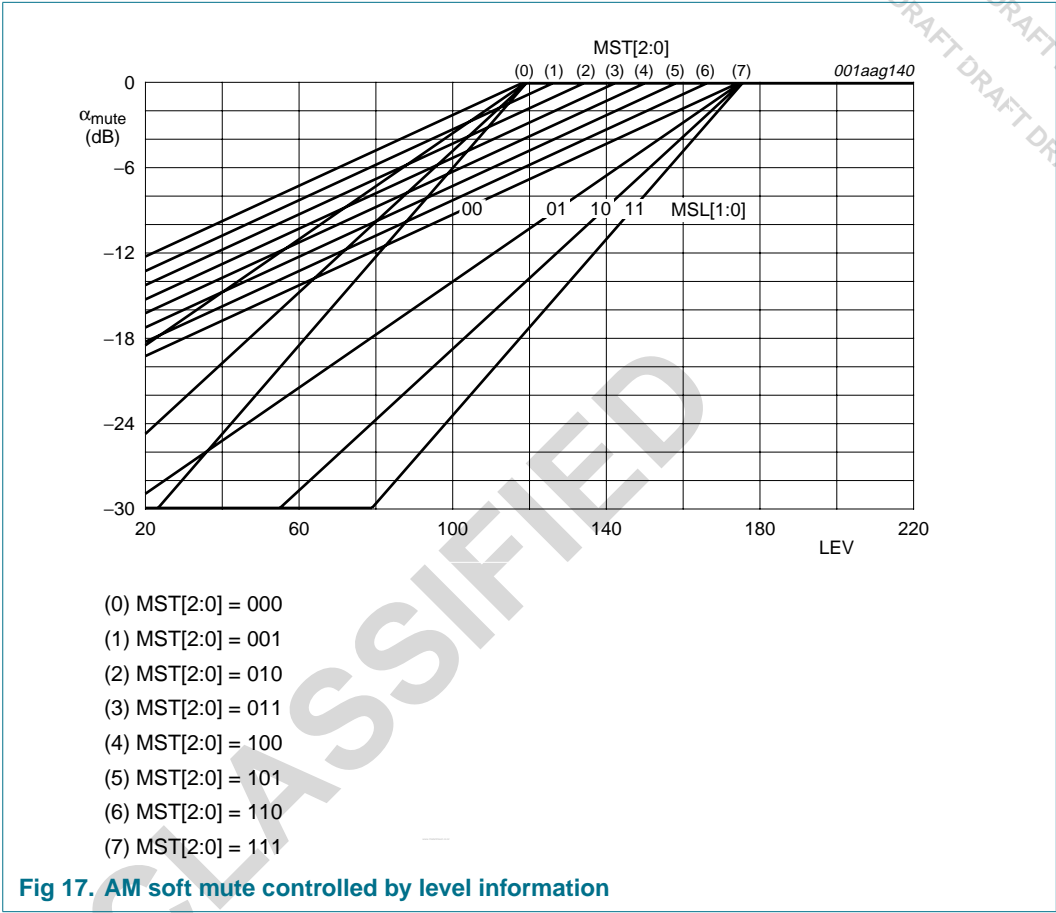


Fig 16. FM soft mute controlled by level information



8.2.8 Write mode: data byte SOFTMUTE2_FM

Table 35. SOFTMUTE2_FM - data byte 6h bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------|------|------|------|------|------|------|
| MFON | MSON | MNS1 | MNS0 | MFOM | MSOM | MMS1 | MMS0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Table 36. SOFTMUTE2_FM - data byte 6h bit description

| Bit | Symbol | Description |
|---------|----------|--|
| 7 | MFON | soft mute fast on noise (USN) 0 = no fast control on noise (USN) 1 = fast control on noise (USN) active |
| 6 | MSON | soft mute slow on noise (USN) 0 = no slow control on noise (USN) 1 = slow control on noise (USN) active |
| 5 and 4 | MNS[1:0] | sensitivity of soft mute on noise (USN) 00 to 11 = weak to strong soft mute control by FM noise (USN); see Figure 18 |

Table 36. SOFTMUTE2_FM - data byte 6h bit description ...continued

| Bit | Symbol | Description |
|---------|----------|--|
| 3 | MFOM | soft mute fast on multipath (WAM) 0 = no fast control on multipath (WAM) 1 = fast control on multipath (WAM) active |
| 2 | MSOM | soft mute slow on multipath (WAM) 0 = no slow control on multipath (WAM) 1 = slow control on multipath (WAM) active |
| 1 and 0 | MMS[1:0] | sensitivity of soft mute on multipath (WAM) 00 to 11 = weak to strong soft mute control by FM multipath (WAM); see Figure 19 |

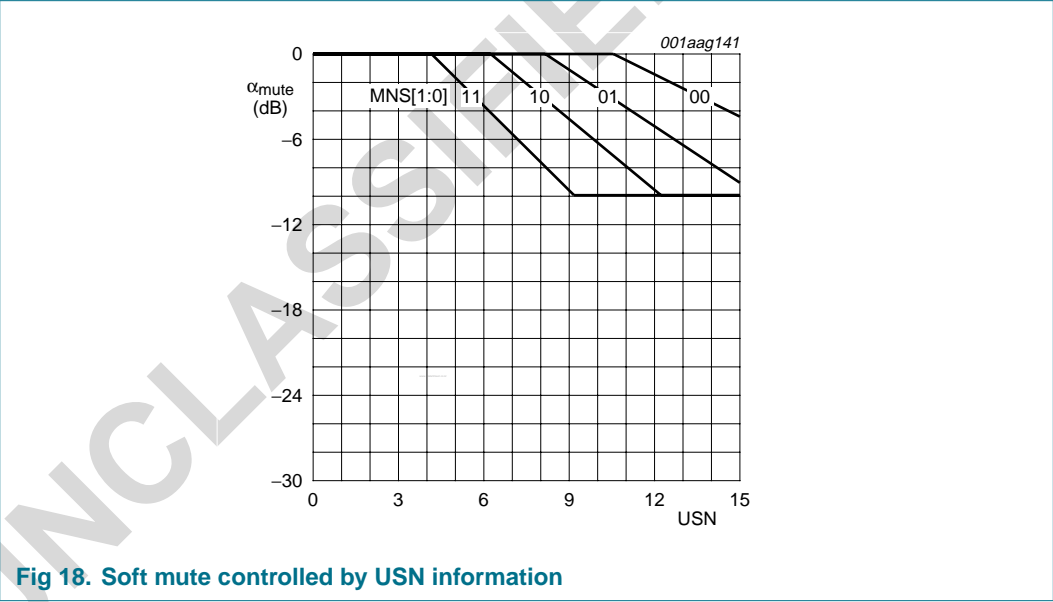


Fig 18. Soft mute controlled by USN information

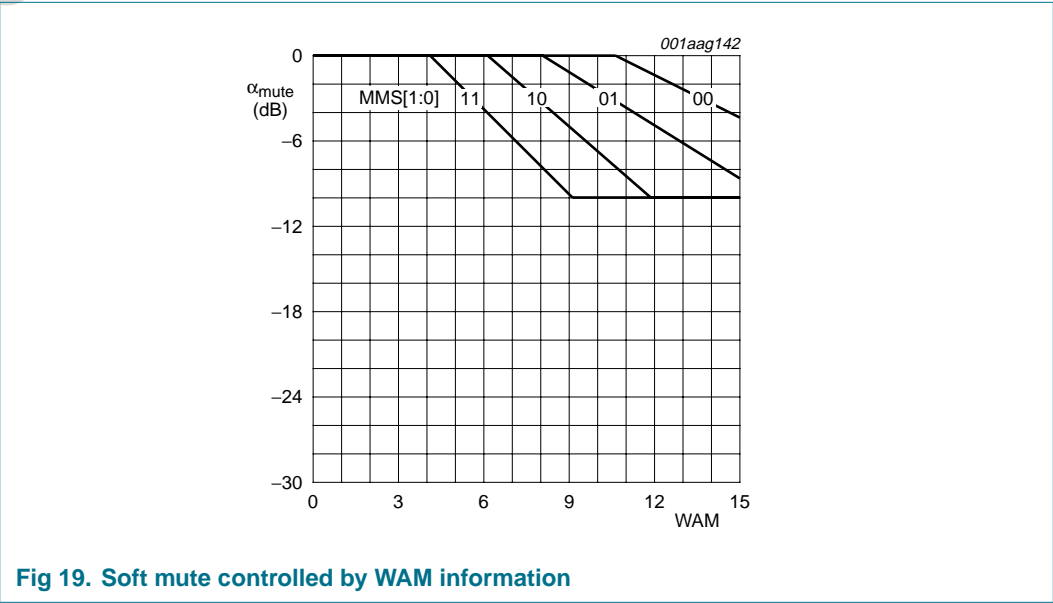


Fig 19. Soft mute controlled by WAM information

8.2.9 Write mode: data byte SOFTMUTE2_AM

Table 37. SOFTMUTE2_AM - data byte 6h bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|---|---|-------|-------|-------|-------|-------|
| 0 | 0 | 0 | MLIM4 | MLIM3 | MLIM2 | MLIM1 | MLIM0 |
| | | | 0 | 0 | 0 | 0 | 0 |

Table 38. SOFTMUTE2_AM - data byte 6h bit description

| Bit | Symbol | Description |
|--------|-----------|---|
| 7 to 5 | - | not used, must be set to logic 0 |
| 4 to 0 | MLIM[4:0] | soft mute limit 0 0000 to 1 1110 = soft mute control limited at 0 dB to 30 dB; the soft mute control can be limited to the point at which natural soft mute starts |

8.2.10 Write mode: data byte HIGHCUT0

Table 39. HIGHCUT0 - data byte 7h bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-------|------|------|------|------|------|------|
| HMOD1 | HMOD0 | HLIM | HAT2 | HAT1 | HAT0 | HRT1 | HRT0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Table 40. HIGHCUT0 - data byte 7h bit description

| Bit | Symbol | Description |
|---------|-----------|--|
| 7 and 6 | HMOD[1:0] | high-cut on modulation; see Figure 20 00 = no modulation control 01 = high-cut (50 μ s to 103 μ s) for < 30 % modulation 10 = high-cut (50 μ s to 103 μ s) for < 50 % modulation 11 = high-cut (50 μ s to 165 μ s) for < 50 % modulation |
| 5 | HLIM | limitation of high-cut control on level, noise (USN) and multipath (WAM) 0 = high-cut limit at 165 μ s, -10 dB at 10 kHz (for 50 μ s de-emphasis) 1 = high-cut limit at 103 μ s, -6 dB at 10 kHz (for 50 μ s de-emphasis) |
| 4 to 2 | HAT[2:0] | high-cut slow attack time; see Table 41 |
| 1 and 0 | HRT[1:0] | high-cut slow recovery time 00 = 2 times attack time 01 = 4 times attack time 10 = 8 times attack time 11 = 16 times attack time |

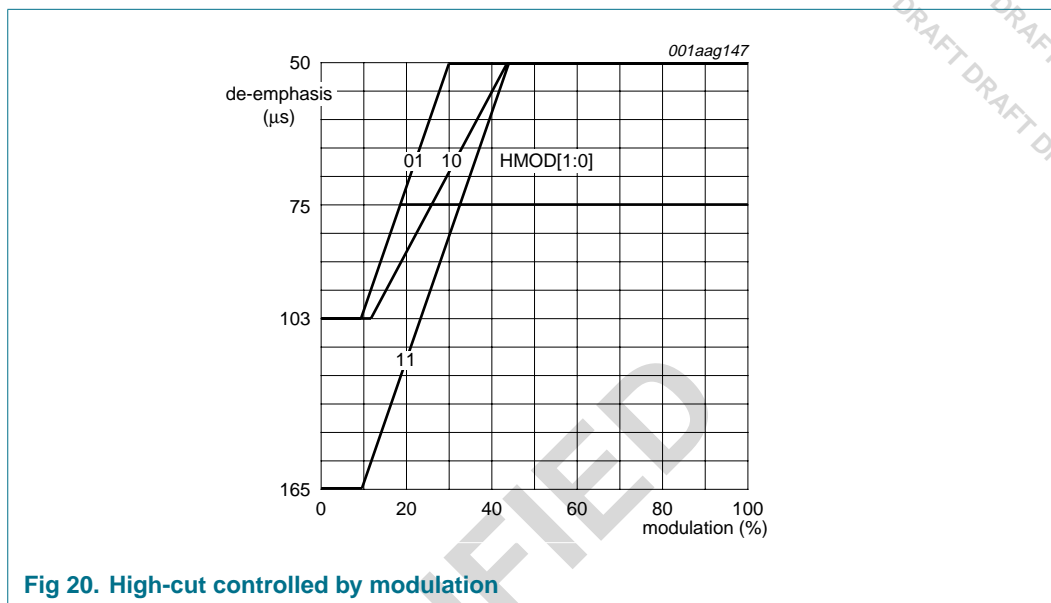


Table 41. High-cut attack time

| HAT2 | HAT1 | HAT0 | High-cut attack time |
|------|------|------|----------------------|
| 0 | 0 | 0 | 60 ms |
| 0 | 0 | 1 | 125 ms |
| 0 | 1 | 0 | 250 ms |
| 0 | 1 | 1 | 0.5 s |
| 1 | 0 | 0 | 1 s |
| 1 | 0 | 1 | 2 s |
| 1 | 1 | 0 | 4 s |
| 1 | 1 | 1 | 8 s |

8.2.11 Write mode: data byte HIGHCUT1

Table 42. HIGHCUT1 - data byte 8h bit allocation with default setting

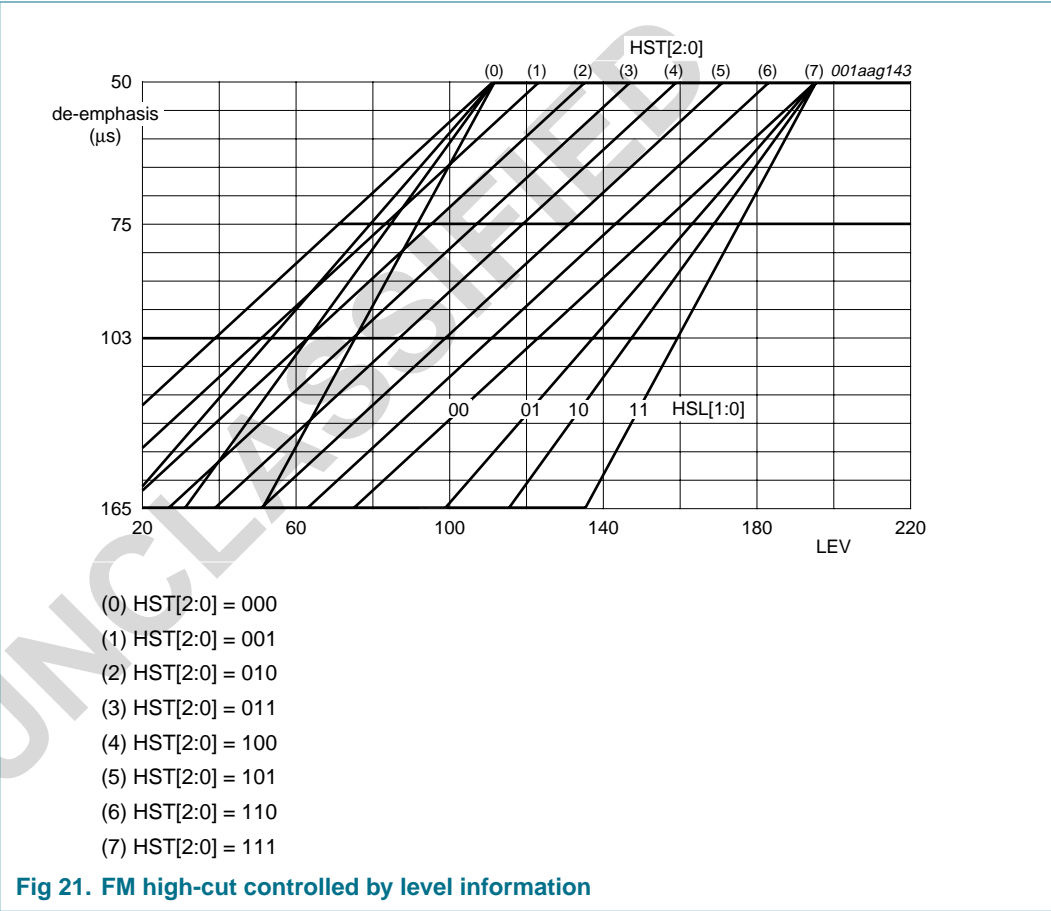
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------|---|------|------|------|------|------|
| HFOL | HSOL | 0 | HST2 | HST1 | HST0 | HSL1 | HSL0 |
| 0 | 0 | | 0 | 0 | 0 | 0 | 0 |

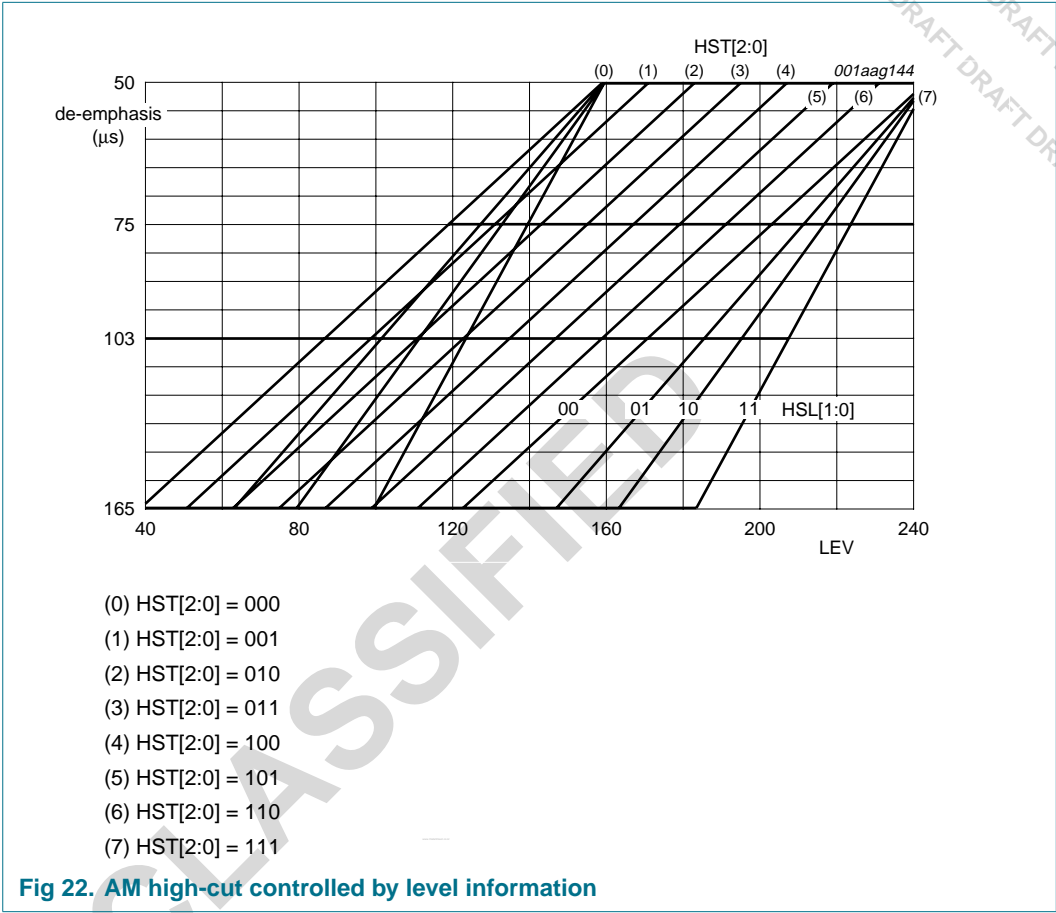
Table 43. HIGHCUT1 - data byte 8h bit description

| Bit | Symbol | Description |
|-----|--------|--|
| 7 | HFOL | high-cut fast on level 0 = no fast control on level 1 = fast control on level active |
| 6 | HSOL | high-cut slow on level 0 = no slow control on level 1 = slow control on level active |
| 5 | - | not used, must be set to logic 0 |

Table 43. HIGHCUT1 - data byte 8h bit description ...continued

| Bit | Symbol | Description |
|---------|----------|---|
| 4 to 2 | HST[2:0] | high-cut start on level 000 to 111 = high threshold to low threshold of weak signal high-cut control; see Figure 21 and Figure 22 |
| 1 and 0 | HSL[1:0] | high-cut slope on level 00 to 11 = low steepness to high steepness of slope of weak signal high-cut control; see Figure 21 and Figure 22 |





8.2.12 Write mode: data byte HIGHCUT2

Table 44. HIGHCUT2 - data byte 9h bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|-----|------|------|------|------|------|------|
| HFON | HSN | HNS1 | HNS0 | HFOM | HSOM | HMS1 | HMS0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Table 45. HIGHCUT2 - data byte 9h bit description

| Bit | Symbol | Description |
|---------|----------|--|
| 7 | HFON | high-cut fast on noise (USN) 0 = no fast control on noise (USN) 1 = fast control on noise (USN) active |
| 6 | HSN | high-cut slow on noise (USN) 0 = no slow control on noise (USN) 1 = slow control on noise (USN) active |
| 5 and 4 | HNS[1:0] | sensitivity of high-cut on noise (USN) 00 to 11 = weak to strong high-cut control by FM noise (USN); see Figure 23 |

Table 45. HIGHCUT2 - data byte 9h bit description ...continued

| Bit | Symbol | Description |
|---------|----------|--|
| 3 | HFOM | high-cut fast on multipath (WAM) 0 = no fast control on multipath (WAM) 1 = fast control on multipath (WAM) active |
| 2 | HSOM | high-cut slow on multipath (WAM) 0 = no slow control on multipath (WAM) 1 = slow control on multipath (WAM) active |
| 1 and 0 | HMS[1:0] | sensitivity of high-cut on multipath (WAM) 00 to 11 = weak to strong high-cut control by FM multipath (WAM); see Figure 24 |

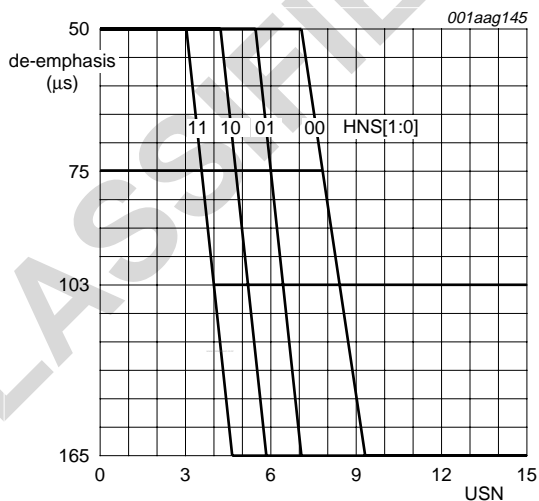


Fig 23. High-cut controlled by USN information

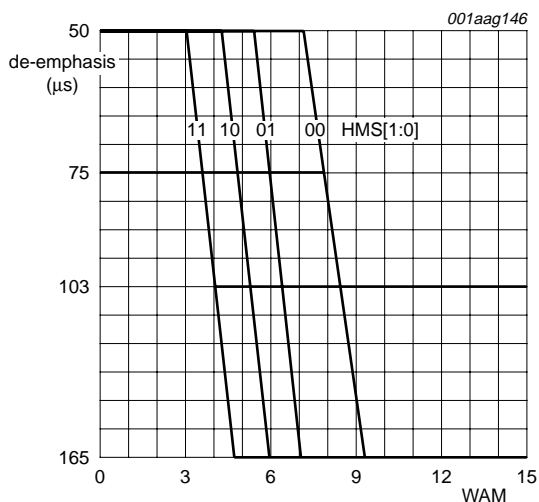


Fig 24. High-cut controlled by WAM information

8.2.13 Write mode: data byte STEREO0

Table 46. STEREO0 - data byte Ah bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-------|---|------|------|------|------|------|
| SMOD1 | SMOD0 | 0 | SAT2 | SAT1 | SAT0 | SRT1 | SRT0 |
| 0 | 0 | | 0 | 0 | 0 | 0 | 0 |

Table 47. STEREO0 - data byte Ah bit description

| Bit | Symbol | Description |
|---------|-----------|--|
| 7 and 6 | SMOD[1:0] | stereo blend on modulation; see Figure 25 00 = no modulation control 01 = stereo blend (stereo to mono) for < 30 % modulation 10 = stereo blend (stereo to 6 dB channel separation) for < 30 % modulation 11 = stereo blend (stereo to mono) for < 15 % modulation |
| 5 | - | not used, must be set to logic 0 |
| 4 to 2 | SAT[2:0] | stereo blend slow attack time; see Table 48 |
| 1 and 0 | SRT[1:0] | stereo blend slow recovery time 00 = 2 times attack time 01 = 4 times attack time 10 = 8 times attack time 11 = 16 times attack time |

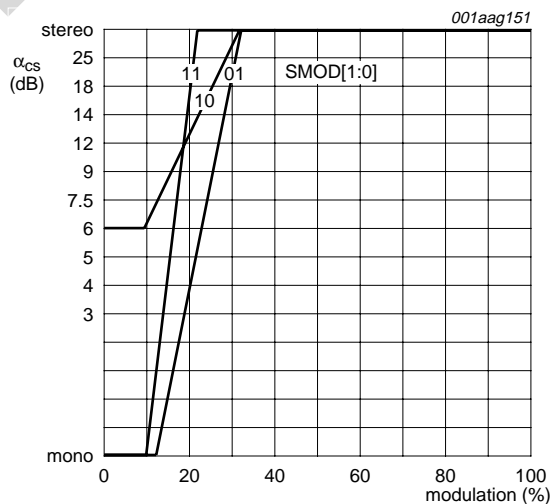


Fig 25. Stereo blend controlled by modulation

Table 48. Stereo blend attack time

| SAT2 | SAT1 | SAT0 | Stereo blend attack time |
|------|------|------|--------------------------|
| 0 | 0 | 0 | 60 ms |
| 0 | 0 | 1 | 125 ms |
| 0 | 1 | 0 | 250 ms |
| 0 | 1 | 1 | 0.5 s |
| 1 | 0 | 0 | 1 s |
| 1 | 0 | 1 | 2 s |
| 1 | 1 | 0 | 4 s |
| 1 | 1 | 1 | 8 s |

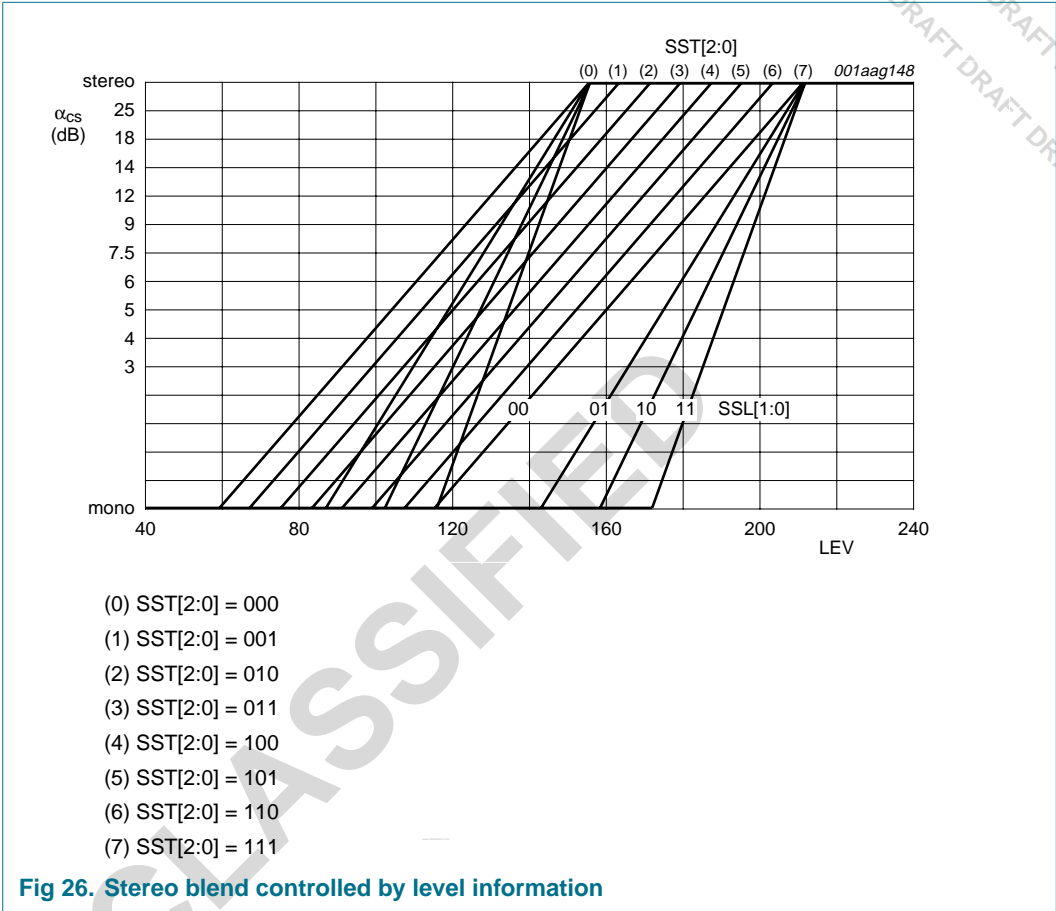
8.2.14 Write mode: data byte STEREO1

Table 49. STEREO1 - data byte Bh bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------|---|------|------|------|------|------|
| SFOL | SSOL | 0 | SST2 | SST1 | SST0 | SSL1 | SSL0 |
| 0 | 0 | | 0 | 0 | 0 | 0 | 0 |

Table 50. STEREO1 - data byte Bh bit description

| Bit | Symbol | Description |
|---------|----------|---|
| 7 | SFOL | stereo blend fast on level 0 = no fast control on level 1 = fast control on level active |
| 6 | SSOL | stereo blend slow on level 0 = no slow control on level 1 = slow control on level active |
| 5 | - | not used, must be set to logic 0 |
| 4 to 2 | SST[2:0] | stereo blend start on level 000 to 111 = high threshold to low threshold of weak signal stereo blend control; see Figure 26 |
| 1 and 0 | SSL[1:0] | stereo blend slope on level 00 to 11 = low steepness to high steepness of slope of weak signal stereo blend control; see Figure 26 |



8.2.15 Write mode: data byte STEREO2

Table 51. STEREO2 - data byte Ch bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------|------|------|------|------|------|------|
| SFON | SSON | SNS1 | SNS0 | SFOM | SSOM | SMS1 | SMS0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Table 52. STEREO2 - data byte Ch bit description

| Bit | Symbol | Description |
|---------|----------|--|
| 7 | SFON | stereo blend fast on noise (USN) 0 = no fast control on noise (USN) 1 = fast control on noise (USN) active |
| 6 | SSON | stereo blend slow on noise (USN) 0 = no slow control on noise (USN) 1 = slow control on noise (USN) active |
| 5 and 4 | SNS[1:0] | sensitivity of stereo blend on noise (USN) 00 to 11 = weak to strong stereo blend control by FM noise (USN); see Figure 27 |

Table 52. STEREO2 - data byte Ch bit description ...continued

| Bit | Symbol | Description |
|---------|----------|--|
| 3 | SFOM | stereo blend fast on multipath (WAM) 0 = no fast control on multipath (WAM) 1 = fast control on multipath (WAM) active |
| 2 | SSOM | stereo blend slow on multipath (WAM) 0 = no slow control on multipath (WAM) 1 = slow control on multipath (WAM) active |
| 1 and 0 | SMS[1:0] | sensitivity of stereo blend on multipath (WAM) 00 to 11 = weak to strong stereo blend control by FM multipath (WAM); see Figure 28 |

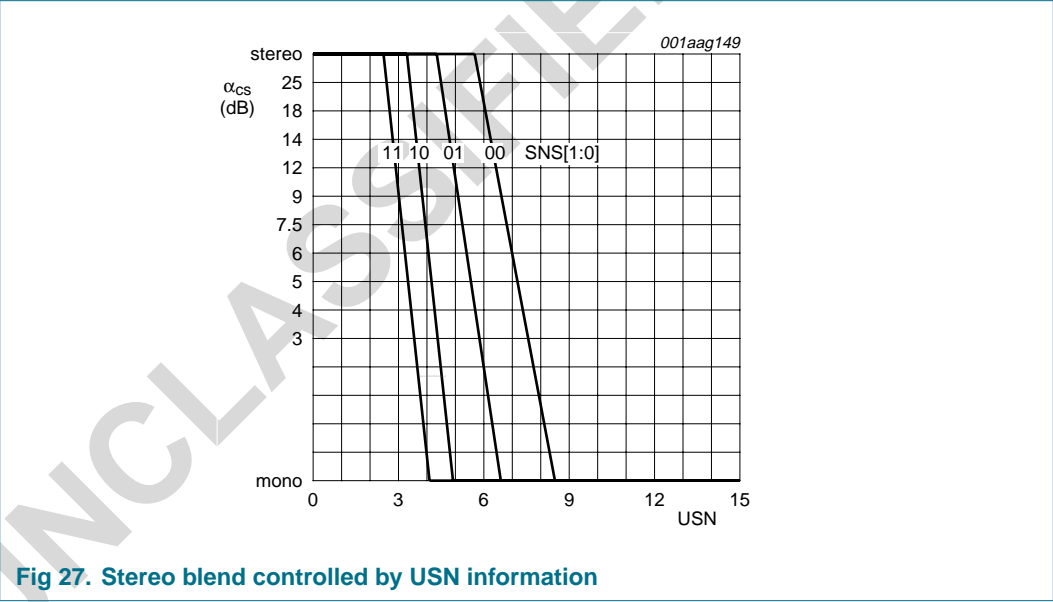


Fig 27. Stereo blend controlled by USN information

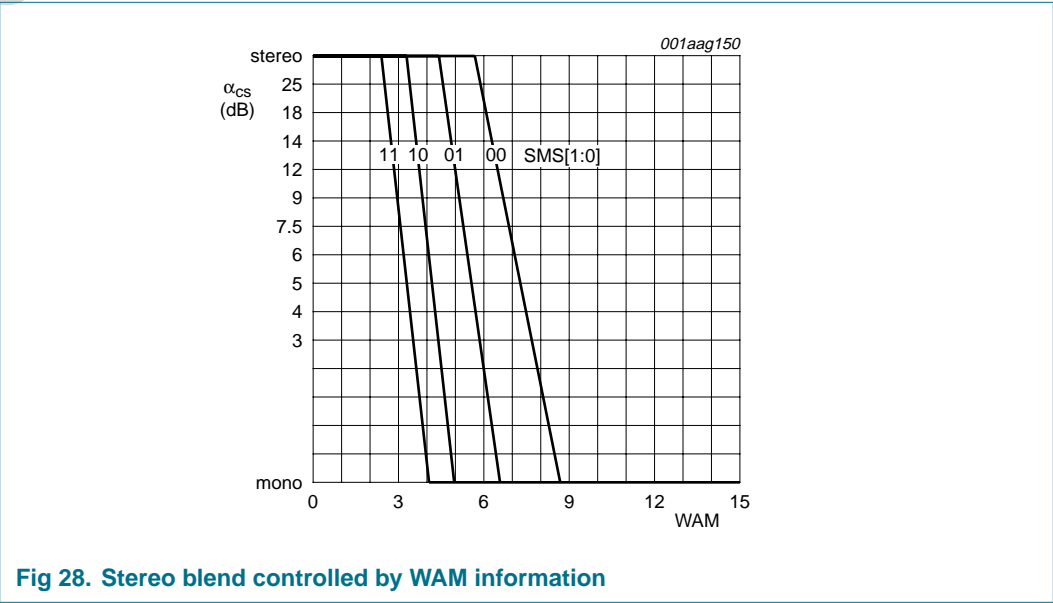


Fig 28. Stereo blend controlled by WAM information

8.2.16 Write mode: data byte CONTROL

Table 53. CONTROL - data byte Dh bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|-------|---|---|---|---|-------|-------|
| PORT | NBLIM | 0 | 1 | 0 | 1 | BWLEV | BWMOD |
| 0 | 0 | | | | | 0 | 0 |

Table 54. CONTROL - data byte Dh bit description

| Bit | Symbol | Description |
|-----|--------|---|
| 7 | PORT | switch output port 0 = pin TEST open-circuit 1 = pin TEST pull-down to ground |
| 6 | NBLIM | FM noise blanker pulse rate limiter 0 = pulse rate not limited 1 = pulse rate limited to 400 Hz |
| 5 | - | not used, must be set to logic 0 |
| 4 | - | not used, must be set to logic 1 |
| 3 | - | not used, must be set to logic 0 |
| 2 | - | not used, must be set to logic 1 |
| 1 | BWLEV | dynamic FM bandwidth control as a function of low level 0 = narrow bandwidth (reduced noise) 1 = wide bandwidth (modulation handling) |
| 0 | BWMOD | dynamic FM bandwidth control as a function of modulation 0 = adjacent channel suppression 1 = modulation handling |

8.2.17 Write mode: data byte LEVEL_OFFSET

Table 55. LEVEL_OFFSET - data byte Eh bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|-------|-------|-------|-------|-------|-------|-------|
| 0 | LEVO6 | LEVO5 | LEVO4 | LEVO3 | LEVO2 | LEVO1 | LEVO0 |
| | 1 | 0 | 0 | 0 | 0 | 0 | 0 |

Table 56. LEVEL_OFFSET - data byte Eh bit description

| Bit | Symbol | Description |
|--------|-----------|---|
| 7 | - | not used, must be set to logic 0 |
| 6 to 0 | LEVO[6:0] | level offset control ^[1] 0 to 127 = correction of the digital level information equivalent to a level voltage shift of -1 V to +1 V |

- [1] The level offset can be used to correct for active antenna gain and noise level. The level correction influences the weak signal processing and the LEVEL read data via I²C-bus. The level correction does not influence the analog voltage at pin RSSI.

8.2.18 Write mode: data byte AM_LNA

Table 57. AM_LNA - data byte Fh bit allocation with default setting

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|---|-------|-------|---|--------|--------|--------|
| 0 | 0 | AAITT | ALAMT | 0 | CHSEP2 | CHSEP1 | CHSEP0 |
| | | 0 | 1 | | 1 | 0 | 0 |

Table 58. AM_LNA - data byte Fh bit description

| Bit | Symbol | Description |
|---------|------------|---|
| 7 and 6 | - | not used, must be set to logic 0 |
| 5 | AAITT | AM auto-injection test time 0 = 4 ms AM mirror measurement time at auto-injection tuning 1 = 8 ms AM mirror measurement time at auto-injection tuning |
| 4 | ALAMT | AM LNA AGC mute time; audio mute and fast AGC settling at AM LNA AGC step 0 = 4 ms 1 = 7 ms |
| 3 | - | not used, must be set to logic 0 |
| 2 to 0 | CHSEP[2:0] | stereo channel separation alignment 100 = default setting (no alignment) 000 to 111 = optional channel separation |

9. Limiting values

Table 59. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|------------------|--|--------------------------------------|------|------------|------|
| V_{CC} | supply voltage | on pins V_{CC1} and V_{CC2} | -0.3 | +10 | V |
| ΔV_{CCn} | voltage difference between any supply pins | between pins V_{CC1} and V_{CC2} | -0.3 | +0.3 | V |
| V_{SCL} | voltage on pin SCL | | -0.3 | +6 | V |
| V_{SDA} | voltage on pin SDA | | -0.3 | +6 | V |
| $V_{AMRFDEC}$ | voltage on pin AMRFDEC | | -0.3 | +6 | V |
| V_{AMRFIN} | voltage on pin AMRFIN | | -0.3 | +6 | V |
| $V_{AMRFAGC}$ | voltage on pin AMRFAGC | | -0.3 | +6 | V |
| $V_{AMIFAGC2}$ | voltage on pin AMIFAGC2 | | -0.3 | +6 | V |
| V_{RSSI} | RSSI voltage | | -0.3 | +6 | V |
| V_{VCODEC} | voltage on pin VCODEC | | -0.3 | +6 | V |
| V_{PLL} | voltage on pin PLL | | -0.3 | +6 | V |
| V_{PLLREF} | voltage on pin PLLREF | | -0.3 | +6 | V |
| V_{TEST} | voltage on pin TEST | | -0.3 | +6 | V |
| $V_{AMIFAGC1}$ | voltage on pin AMIFAGC1 | | -0.3 | +6 | V |
| V_{VREF} | voltage on pin VREF | | -0.3 | +6 | V |
| V_n | voltage on any other pin | | -0.3 | + V_{CC} | V |
| T_{stg} | storage temperature | | -40 | +150 | °C |

Table 59. Limiting values ...continued

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|--------------|---------------------------------|------------------|-----------|-------|------|
| T_{amb} | ambient temperature | | [1] -40 | +85 | °C |
| $T_{j(max)}$ | maximum junction temperature | | - | 150 | °C |
| V_{esd} | electrostatic discharge voltage | human body model | [2] -2000 | +2000 | V |
| | | machine model | [3] -200 | +200 | V |

[1] For use of full operating supply voltage range and operating temperature range, the thermal resistance $R_{th(j-a)}$ should be less than 54 K/W.

[2] Class 2 according to JESD22-A114D.

[3] Class B according to EIA/JESD22-A115-A.

10. Thermal characteristics

Table 60. Thermal characteristics

| Symbol | Parameter | Conditions | Typ | Unit |
|---------------|---|-------------|--------|------|
| $R_{th(j-a)}$ | thermal resistance from junction to ambient | in free air | [1] 45 | K/W |

[1] Single layer board 70 mm by 100 mm with a copper thickness of 35 μ m and a copper area coverage of 20 %.

11. Static characteristics

Table 61. Static characteristics $V_{CC} = 8.5$ V; $T_{amb} = 25$ °C; unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------|------------------------------|--|------|-----|-----|------|
| V_{CC} | supply voltage | on pins V_{CC1} and V_{CC2} | 8 | 8.5 | 9 | V |
| I_{CC} | supply current | into pins V_{CC1} , V_{CC2} and V_{REGSUP} | | | | |
| | | FM | 90 | 120 | 140 | mA |
| | | AM | 100 | 134 | 150 | mA |
| $V_{VREGSUP}$ | voltage on pin $V_{VREGSUP}$ | $T_{amb} = -40$ °C to $+85$ °C | 6.35 | - | - | V |

Power-on reset

| | | | | | | |
|----------------|-----------------------------------|--|-----|------|-----|----|
| $V_{P(POR)}$ | power-on reset supply voltage | reset at power-on | 6.5 | 6.75 | 7.0 | V |
| $V_{hys(POR)}$ | power-on reset hysteresis voltage | | - | 0.2 | - | V |
| t_{start} | start time | series resistance of crystal $R_s = 150$ Ω | - | 10 | 100 | ms |

Logic pins SDA and SCL (voltage referenced to pin GNDD)

| | | | | | |
|----------|--------------------------|----------|---|-------|---|
| V_{IH} | HIGH-level input voltage | [1] 1.58 | - | 5.5 | V |
| V_{IL} | LOW-level input voltage | [1] -0.5 | - | +1.04 | V |

[1] SDA and SCL HIGH and LOW internal thresholds are specified according to an I²C-bus voltage of 2.5 V ± 10 % or 3.3 V ± 5 %. The I²C-bus interface tolerates also SDA and SCL signals from a 5 V I²C-bus, but does not fulfill the 5 V I²C-bus specification completely. The TEF6606 complies with the fast-mode I²C-bus protocol. The maximum I²C-bus communication speed is 400 kbit/s.

12. Dynamic characteristics

Table 62. Dynamic characteristics

$V_{CC} = 8.5 \text{ V}$; $T_{amb} = 25^\circ\text{C}$; unless otherwise specified.

FM condition: all RF voltages refer to an unterminated RMS voltage with a source impedance 75Ω ; $f_{mod} = 1 \text{ kHz}$,

$\Delta f = 22.5 \text{ kHz}$, de-emphasis = $50 \mu\text{s}$, $f_{RF} = 97.1 \text{ MHz}$; unless otherwise specified.

AM condition: all RF voltages are RMS values measured at the input of a 15 pF / 60 pF dummy aerial; $f_{mod} = 400 \text{ Hz}$, $m = 30 \%$, $f_{RF} = 990 \text{ kHz}$; unless otherwise specified.

All values measured in a test circuit according to [Figure 30](#); default settings; audio signals measured at LOUT and ROUT with IEC tuner filter (200 Hz to 15 kHz; IEC 60315-4); unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--|-----------------------------|---|-------|-----|--------|---------|
| Crystal oscillator; pins XTAL1 and XTAL2 | | | | | | |
| f _{xtal} | crystal frequency | fundamental frequency | - | 4 | - | MHz |
| Δf _{xtal} | inaccuracy caused by device | | -45 | -0 | 45 | ppm |
| C _i | input capacitance | input capacitance from XTAL1 and XTAL2 to ground | 1 | 3 | 4 | pF |
| R _i | input resistance | | - | - | −750 | Ω |
| Tuning system | | | | | | |
| C/N | LO carrier-to-noise ratio | f _{LO} = 100 MHz; Δf = 10 kHz | - | 98 | - | dBc/√Hz |
| t _{tune} | tuning time | FM (Europe/USA/Japan) f _{RF} = 87.5 MHz to 108 MHz | - | 1.8 | 2 | ms |
| | | FM (OIRT) f _{RF} = 65 MHz to 74 MHz | - | 6.8 | 7 | ms |
| | | AM (MW) f _{RF} = 0.53 MHz to 1.7 MHz | - | 9 | 9.2 | ms |
| | | AM (LW) f _{RF} = 0.144 MHz to 0.288 MHz | - | 3.5 | 3.7 | ms |
| | | AM (SW) f _{RF} = 2.94 MHz to 18.135 MHz | - | 3.5 | 3.7 | ms |
| | | | | | | |
| f _{RF} | RF frequency | FM tuning range | 65 | - | 108 | MHz |
| | | AM (LW) tuning range | 144 | - | 288 | kHz |
| | | AM (MW) tuning range | 522 | - | 1710 | kHz |
| | | AM (SW) tuning range | 2.94 | - | 18.135 | MHz |
| f _{tune(step)} | step of tuning frequency | FM (Europe/USA/Japan) | - | 50 | - | kHz |
| | | FM (OIRT) | - | 10 | - | kHz |
| | | AM (LW and MW) | - | 1 | - | kHz |
| | | AM (SW) | - | 5 | - | kHz |
| FM path | | | | | | |
| V _{i(sens)} | input sensitivity voltage | (S+N)/N = 26 dB; without weak signal handling | - | 5.5 | - | dBμV |
| | | (S+N)/N = 26 dB; including weak signal handling | - | 5 | - | dBμV |
| | | (S+N)/N = 46 dB; including weak signal handling | - | 16 | - | dBμV |
| NF | noise figure | | - | 6 | 9 | dB |
| V _{L(LO)} | LO leakage voltage | LO residue at antenna input; R _{source(ant)} = 75 Ω | [1] - | −6 | - | dBμV |

Table 62. Dynamic characteristics ...continued

$V_{CC} = 8.5\text{ V}$; $T_{amb} = 25\text{ }^{\circ}\text{C}$; unless otherwise specified.

FM condition: all RF voltages refer to an unterminated RMS voltage with a source impedance $75\text{ }\Omega$; $f_{mod} = 1\text{ kHz}$, $\Delta f = 22.5\text{ kHz}$, de-emphasis = $50\text{ }\mu\text{s}$, $f_{RF} = 97.1\text{ MHz}$; unless otherwise specified.

AM condition: all RF voltages are RMS values measured at the input of a $15\text{ pF} / 60\text{ pF}$ dummy aerial; $f_{mod} = 400\text{ Hz}$, $m = 30\%$, $f_{RF} = 990\text{ kHz}$; unless otherwise specified.

$m = 30\%$, $f_{RF} = 990\text{ kHz}$; unless otherwise specified.

All values measured in a test circuit according to [Figure 30](#); default settings; audio signals measured at LOUT and ROUT with IEC tuner filter (200 Hz to 15 kHz; IEC 60315-4); unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------------|----------------------------------|---|-----|-----|-----|------------------------|
| $V_{sp(VCO)}$ | VCO spurious voltage | VCO residue at antenna input; $R_{source(ant)} = 75\text{ }\Omega$ | - | 46 | 60 | $\text{dB}\mu\text{V}$ |
| (S+N)/N | signal plus noise-to-noise ratio | $V_{i(RF)} = 1\text{ mV}$; $\Delta f = 22.5\text{ kHz}$ | 55 | 60 | - | dB |
| α_{ripple} | ripple rejection | V_{ripple} / V_{audio} ; $V_{ripple} = 100\text{ mV}$; $f_{ripple} = 100\text{ Hz}$ | 34 | 44 | - | dB |
| f_{IF} | IF frequency | | - | 150 | - | kHz |
| α_{image} | image rejection | $f_{RF(image)} = f_{RF(wanted)} \pm 2 \times f_{IF}$ | 50 | 60 | - | dB |
| IP3 | third-order intercept point | $f_{RF(unw)1} = 97.5\text{ MHz}$; $f_{RF(unw)2} = 97.9\text{ MHz}$; $V_{i(RF)} = 80\text{ dB}\mu\text{V}$ | 106 | 113 | - | $\text{dB}\mu\text{V}$ |
| S_{dyn} | dynamic selectivity | $V_{i(RF)} = 10\text{ }\mu\text{V}$; $\Delta f_{RF(unw)} = 22.5\text{ kHz}$; (S+N)/N = 26 dB; mono; $f_{AF} = 1\text{ kHz}$ | | | | |
| | | $\Delta f_{RF} = 100\text{ kHz}$; PACS disabled | - | 3 | - | dB |
| | | $\Delta f_{RF} = 200\text{ kHz}$; PACS disabled | - | 55 | - | dB |
| | | $\Delta f_{RF} = 100\text{ kHz}$; PACS enabled | - | 24 | - | dB |
| | | $\Delta f_{RF} = 200\text{ kHz}$; PACS enabled | - | 64 | - | dB |
| S_{stat} | static selectivity | maximum IF bandwidth; $f_{i(RF)} \pm 100\text{ kHz}$ | 10 | 14 | 25 | dB |
| | | maximum IF bandwidth; $f_{i(RF)} \pm 200\text{ kHz}$ | 54 | 64 | 74 | dB |
| | | maximum IF bandwidth; $f_{i(RF)} \pm 300\text{ kHz}$ (excluding image) | 65 | 75 | 90 | dB |
| | | minimum IF bandwidth; $f_{i(RF)} \pm 100\text{ kHz}$ | 30 | 38 | - | dB |
| | | minimum IF bandwidth; $f_{i(RF)} \pm 200\text{ kHz}$ | 63 | 73 | - | dB |
| $\alpha_{sup(AM)}$ | AM suppression | AM: $f_{AF} = 1\text{ kHz}$; $m = 30\%$ | | | | |
| | | $V_{i(RF)} = 0.05\text{ mV}$ to 20 mV | 45 | 55 | - | dB |
| | | $V_{i(RF)} = 20\text{ mV}$ to 500 mV | 40 | 50 | - | dB |
| $V_{start(desens)}$ | desensitization start voltage | unwanted signal voltage for 6 dB desensitization; $ f_{RF(unw)} - f_{RF(wanted)} > 400\text{ kHz}$; $V_{i(RF)wanted} = 30\text{ dB}\mu\text{V}$; data byte 2h bits RFAGC[1:0] = 00 | - | 90 | - | $\text{dB}\mu\text{V}$ |
| V_{sp} | spurious voltage | at antenna input; $R_{source(ant)} = 75\text{ }\Omega$ | | | | |
| | | $30\text{ MHz} < f < 1\text{ GHz}$ | - | - | 50 | $\text{dB}\mu\text{V}$ |
| | | $1\text{ GHz} < f < 12.75\text{ GHz}$ | - | - | 60 | $\text{dB}\mu\text{V}$ |

Table 62. Dynamic characteristics ...continued

$V_{CC} = 8.5 \text{ V}$; $T_{amb} = 25 \text{ }^{\circ}\text{C}$; unless otherwise specified.

FM condition: all RF voltages refer to an unterminated RMS voltage with a source impedance $75 \text{ } \Omega$; $f_{mod} = 1 \text{ kHz}$,

$\Delta f = 22.5 \text{ kHz}$, de-emphasis = $50 \text{ } \mu\text{s}$, $f_{RF} = 97.1 \text{ MHz}$; unless otherwise specified.

AM condition: all RF voltages are RMS values measured at the input of a $15 \text{ pF} / 60 \text{ pF}$ dummy aerial; $f_{mod} = 400 \text{ Hz}$,

$m = 30 \%$, $f_{RF} = 990 \text{ kHz}$; unless otherwise specified.

All values measured in a test circuit according to [Figure 30](#); default settings; audio signals measured at LOUT and ROUT with IEC tuner filter (200 Hz to 15 kHz; IEC 60315-4); unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---|--|--|------|-----|------|------------------|
| FM front-end; pins FMIN1 and FMIN2 | | | | | | |
| $R_{i(dif)}$ | differential input resistance | $f_{RF} = 97.1 \text{ MHz}$; maximum gain | 200 | 300 | 400 | Ω |
| $C_{i(dif)}$ | differential input capacitance | $f_{RF} = 97.1 \text{ MHz}$ | - | 4 | 7 | pF |
| FM RF AGC | | | | | | |
| $V_{start(AGC)}$ | AGC start voltage | RF input voltage for first AGC step; $V_{i(RF)}$ value, at which the RF gain decreases by 6 dB with increasing $V_{i(RF)}$; data byte 2h | | | | |
| | | bits RFAGC[1:0] = 00 | 77 | 80 | 83 | dB μV |
| | | bits RFAGC[1:0] = 01 | 79 | 82 | 85 | dB μV |
| | | bits RFAGC[1:0] = 10 | 81 | 84 | 87 | dB μV |
| | | bits RFAGC[1:0] = 11 | 83 | 86 | 89 | dB μV |
| $V_{i(RF)AGC(hys)}$ | hysteresis of AGC RF input voltage | hysteresis of AGC start | 1 | - | 5 | dB |
| FM IF AGC | | | | | | |
| $V_{i(RF)AGC}$ | AGC RF input voltage | $V_{i(RF)}$ value, at which the IF gain decreases by 6 dB with increasing $V_{i(RF)}$; start of AGC; first step | 71 | 76 | 81 | dB μV |
| $V_{i(RF)AGC(hys)}$ | hysteresis of AGC RF input voltage | hysteresis of AGC start | 1 | - | 6 | dB |
| FM RSSI; pin RSSI | | | | | | |
| V_{RSSI} | RSSI voltage | $V_{i(RF)} = -20 \text{ dB}\mu\text{V}$ | 0.65 | 0.8 | 0.95 | V |
| | | $V_{i(RF)} = 20 \text{ dB}\mu\text{V}$ | 1.8 | 2.0 | 2.2 | V |
| | | $V_{i(RF)} = 40 \text{ dB}\mu\text{V}$ | 2.75 | 3.0 | 3.25 | V |
| | | $V_{i(RF)} = 60 \text{ dB}\mu\text{V}$ | 3.6 | 3.9 | 4.2 | V |
| $\Delta V_{RSSI} / \Delta L_{i(RF)}$ | RSSI voltage difference to RF input level difference ratio | between $V_{i(RF)} = 20 \text{ dB}\mu\text{V}$ and $V_{i(RF)} = 40 \text{ dB}\mu\text{V}$ | 45 | 50 | 55 | mV/dB |
| $f_{-3dB(RSSI)}$ | RSSI cut-off frequency | $V_{i(RF)} = 500 \text{ } \mu\text{V}$; $m = 30 \%$ | 100 | - | - | kHz |
| FM IF counter | | | | | | |
| $V_{i(sens)}$ | input sensitivity voltage | $V_{i(RF)}$ at which IF counter starts; $\Delta f = 0 \text{ Hz}$ | - | 2 | 5 | μV |
| $f_{IFc(res)}$ | IF counter frequency resolution | | - | 5 | - | kHz |
| FM demodulator; pin MPXOUT | | | | | | |
| R_o | output resistance | | - | - | 100 | Ω |
| R_L | load resistance | | 5 | - | - | k Ω |
| C_L | load capacitance | | - | - | 20 | pF |
| Δf_{max} | maximum frequency deviation | THD = 3 %; $V_{i(RF)} = 10 \text{ mV}$ | 115 | 140 | - | kHz |
| V_o | output voltage | $\Delta f = 22.5 \text{ kHz}$; $f_{AF} = 1 \text{ kHz}$ | 180 | 230 | 300 | mV |

Table 62. Dynamic characteristics ...continued

$V_{CC} = 8.5$ V; $T_{amb} = 25$ °C; unless otherwise specified.

FM condition: all RF voltages refer to an unterminated RMS voltage with a source impedance 75 Ω ; $f_{mod} = 1$ kHz,

$\Delta f = 22.5$ kHz, de-emphasis = 50 μ s, $f_{RF} = 97.1$ MHz; unless otherwise specified.

AM condition: all RF voltages are RMS values measured at the input of a 15 pF / 60 pF dummy aerial; $f_{mod} = 400$ Hz,

$m = 30$ %, $f_{RF} = 990$ kHz; unless otherwise specified.

All values measured in a test circuit according to [Figure 30](#); default settings; audio signals measured at LOUT and ROUT with IEC tuner filter (200 Hz to 15 kHz; IEC 60315-4); unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---|----------------------------------|---|------|------|------|-----------------|
| Audio part; pin MPXIN | | | | | | |
| R_i | input resistance | data byte 3h bit LOCUT = 0 (FM or AM) | - | 220 | - | k Ω |
| | | data byte 3h bit LOCUT = 1 (AM) | - | 16 | - | k Ω |
| $\alpha_{bal(ch)}$ | channel balance | balance between R and L channel | -1 | - | +1 | dB |
| $\alpha_{sup(pilot)}$ | pilot suppression | 9 % pilot; $f_{pilot} = 19$ kHz; referenced to 91 % FM modulation | 30 | 40 | - | dB |
| m_{pilot} | modulation degree of pilot tone | threshold for pilot detection | | | | |
| | | stereo on | 2 | 3.9 | 5.8 | % |
| | | stereo off | 1.2 | 3.1 | 5 | % |
| $\alpha_{hys(pilot)}$ | pilot hysteresis | | 0.7 | 0.8 | 1.6 | % |
| $t_{det(pilot)}$ | pilot detection time | | - | 30 | 100 | ms |
| Audio output; pins LOUT and ROUT | | | | | | |
| V_o | output voltage | $\Delta f = 22.5$ kHz; $f_{AF} = 1$ kHz | | | | |
| | | data byte 3h bit OUTA = 1 | 200 | 290 | 410 | mV |
| | | data byte 3h bit OUTA = 0 | 80 | 120 | 175 | mV |
| α_{AF} | AF attenuation | mono; pre-emphasis = 50 μ s; referenced to $f_{AF} = 1$ kHz | | | | |
| | | $f_{AF} = 50$ Hz | -0.6 | -0.1 | +0.4 | dB |
| | | $f_{AF} = 15$ kHz | -1.5 | 0 | +1.5 | dB |
| α_{cs} | channel separation | $V_{i(RF)} = 1$ mV; data byte Fh bits CHSEP[2:0] = 100 | 26 | 40 | - | dB |
| THD | total harmonic distortion | mono; $\Delta f = 75$ kHz; $V_{i(RF)} = 1$ mV | - | 0.4 | 0.8 | % |
| | | stereo; $\Delta f = 67.5$ kHz; L or R | - | - | 1 | % |
| R_L | load resistance | | 10 | - | - | k Ω |
| C_L | load capacitance | | - | - | 20 | pF |
| FM noise blanker | | | | | | |
| (S+N)/N | signal plus noise-to-noise ratio | noise pulses at RF input signal $t_p = 5$ ns; $t_r < 1$ ns; $t_f < 1$ ns; $f_p = 100$ Hz; $V_p = 500$ mV; $V_{i(RF)} = 40$ dB μ V; quasi peak; audio filter according "ITU-R BS.468-4" | - | 30 | - | dB |
| AM path | | | | | | |
| $V_{i(sens)}$ | input sensitivity voltage | S/N = 26 dB; data byte 3h bits DEMP[1:0] = 10; MW | - | 34 | - | dB μ V |
| $V_{n(i)(eq)}$ | equivalent input noise voltage | $C_{source} = 100$ pF | - | 1 | - | nV/ \sqrt{Hz} |
| (S+N)/N | signal plus noise-to-noise ratio | $V_{i(RF)} = 10$ mV | 50 | 56 | - | dB |

Table 62. Dynamic characteristics ...continued

$V_{CC} = 8.5\text{ V}$; $T_{amb} = 25\text{ }^{\circ}\text{C}$; unless otherwise specified.

FM condition: all RF voltages refer to an unterminated RMS voltage with a source impedance $75\text{ }\Omega$; $f_{mod} = 1\text{ kHz}$,

$\Delta f = 22.5\text{ kHz}$, de-emphasis = $50\text{ }\mu\text{s}$, $f_{RF} = 97.1\text{ MHz}$; unless otherwise specified.

AM condition: all RF voltages are RMS values measured at the input of a $15\text{ pF} / 60\text{ pF}$ dummy aerial; $f_{mod} = 400\text{ Hz}$,

$m = 30\%$, $f_{RF} = 990\text{ kHz}$; unless otherwise specified.

All values measured in a test circuit according to [Figure 30](#); default settings; audio signals measured at LOUT and ROUT with IEC tuner filter (200 Hz to 15 kHz; IEC 60315-4); unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--|------------------------------------|---|---|-----|-----|------------------------|
| f_{IF} | IF frequency | | - | 25 | - | kHz |
| α_{image} | image rejection | $f_{RF(\text{image})} = f_{RF(\text{wanted})} \pm 2 \times f_{IF}$ | 45 | 55 | - | dB |
| $\alpha_{\text{sup(H)LO}}$ | LO harmonics suppression | $f_{RF(\text{unw})} = N \times (f_{RF(\text{wanted})} \pm f_{IF}) \pm f_{IF}$; MW | | | | |
| | | $N = 2, 3, 4, 5, 6$ | - | 90 | - | dB |
| | | $N \geq 7$ | - | 50 | - | dB |
| $V_{L(\text{LO})}$ | LO leakage voltage | LO residue at antenna input; load capacitance at antenna input; $C_{\text{ant}} = 60\text{ pF}$ | - | -6 | - | $\text{dB}\mu\text{V}$ |
| $B_{\text{ftr(IF)}}$ | IF filter bandwidth | -3 dB bandwidth | 5 | 6.5 | 8 | kHz |
| S_{stat} | static selectivity | $f_{\text{tune}} \pm 10\text{ kHz}$ | 40 | 48 | - | dB |
| | | $f_{\text{tune}} \pm 20\text{ kHz}$ | 65 | 78 | - | dB |
| $V_{i(\text{RF})(\text{max})}$ | maximum RF input voltage | THD = 10 %; $m = 80\%$; active antenna $50\text{ }\Omega$ | 120 | 135 | - | $\text{dB}\mu\text{V}$ |
| IP2 | second-order intercept point | | 150 | 170 | - | $\text{dB}\mu\text{V}$ |
| IP3 | third-order intercept point | $\Delta f = 40\text{ kHz}$ | 116 | 127 | - | $\text{dB}\mu\text{V}$ |
| AM LNA and AM RF AGC; input pins AMRFIN and AMRFDEC | | | | | | |
| R_i | input resistance | $f_{RF} = 990\text{ kHz}$ | - | 20 | - | Ω |
| C_i | input capacitance | AGC maximum gain | [2] [3] | 530 | - | pF |
| MW band with passive antenna (measured with dummy aerial 15 pF / 60 pF) | | | | | | |
| $V_{i(\text{RF})\text{AGC}}$ | AGC RF input voltage | switched LNA AGC: $V_{i(\text{RF})}$ value, at which the LNA gain decreases with increasing $V_{i(\text{RF})}$; $m = 0\%$; start of AGC; first step | 110 | 113 | 116 | $\text{dB}\mu\text{V}$ |
| $V_{i(\text{RF})\text{AGC}(\text{hys})}$ | hysteresis of AGC RF input voltage | hysteresis of AGC start | 1 | 3 | 6 | dB |
| MW band with active antenna (measured with dummy aerial 50 Ω) | | | | | | |
| $V_{i(\text{RF})\text{AGC}}$ | AGC RF input voltage | switched LNA AGC: $V_{i(\text{RF})}$ value, at which the LNA gain decreases with increasing $V_{i(\text{RF})}$; $m = 0\%$; start of AGC; first step | 78 | 81 | 84 | $\text{dB}\mu\text{V}$ |
| $V_{i(\text{RF})\text{AGC}(\text{hys})}$ | hysteresis of AGC RF input voltage | hysteresis of AGC start | 1 | 3 | 6 | dB |
| LW band with passive antenna (measured with dummy aerial 15 pF / 60 pF) | | | | | | |
| $V_{i(\text{RF})\text{AGC}}$ | AGC RF input voltage | switched LNA AGC: $V_{i(\text{RF})}$ value, at which the LNA gain decreases with increasing $V_{i(\text{RF})}$; $f_{RF} = 207\text{ kHz}$; $m = 0\%$; start of AGC; first step | - | 104 | - | $\text{dB}\mu\text{V}$ |

Table 62. Dynamic characteristics ...continued

$V_{CC} = 8.5\text{ V}$; $T_{amb} = 25\text{ }^{\circ}\text{C}$; unless otherwise specified.

FM condition: all RF voltages refer to an unterminated RMS voltage with a source impedance $75\text{ }\Omega$; $f_{mod} = 1\text{ kHz}$,

$\Delta f = 22.5\text{ kHz}$, de-emphasis = $50\text{ }\mu\text{s}$, $f_{RF} = 97.1\text{ MHz}$; unless otherwise specified.

AM condition: all RF voltages are RMS values measured at the input of a $15\text{ pF} / 60\text{ pF}$ dummy aerial; $f_{mod} = 400\text{ Hz}$,

$m = 30\%$, $f_{RF} = 990\text{ kHz}$; unless otherwise specified.

All values measured in a test circuit according to [Figure 30](#); default settings; audio signals measured at LOUT and ROUT with IEC tuner filter (200 Hz to 15 kHz; IEC 60315-4); unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--|------------------------------------|---|-----|-----|-----|------------------|
| $V_{i(RF)AGC(hys)}$ | hysteresis of AGC RF input voltage | hysteresis of AGC start | 1 | 3 | 6 | dB |
| <i>LW band with active antenna (measured with dummy aerial $50\text{ }\Omega$)</i> | | | | | | |
| $V_{i(RF)AGC}$ | AGC RF input voltage | switched LNA AGC: $V_{i(RF)}$ value, at which the LNA gain decreases with increasing $V_{i(RF)}$; $f_{RF} = 207\text{ kHz}$; $m = 0\%$; start of AGC; first step | - | 72 | - | dB μV |
| $V_{i(RF)AGC(hys)}$ | hysteresis of AGC RF input voltage | hysteresis of AGC start | 1 | 3 | 6 | dB |
| <i>SW bands with passive antenna (measured with dummy aerial $15\text{ pF} / 60\text{ pF}$)</i> | | | | | | |
| $V_{i(RF)AGC}$ | AGC RF input voltage | switched LNA AGC: $V_{i(RF)}$ value, at which the LNA gain decreases with increasing $V_{i(RF)}$; $f_{RF} = 6.1\text{ MHz}$; $m = 0\%$; start of AGC; first step | - | 101 | - | dB μV |
| $V_{i(RF)AGC(hys)}$ | hysteresis of AGC RF input voltage | hysteresis of AGC start | 1 | 3 | 6 | dB |
| <i>SW bands with active antenna (measured with dummy aerial $50\text{ }\Omega$)</i> | | | | | | |
| $V_{i(RF)AGC}$ | AGC RF input voltage | switched LNA AGC: $V_{i(RF)}$ value, at which the LNA gain decreases with increasing $V_{i(RF)}$; $f_{RF} = 6.1\text{ MHz}$; $m = 0\%$; start of AGC; first step | - | 80 | - | dB μV |
| $V_{i(RF)AGC(hys)}$ | hysteresis of AGC RF input voltage | hysteresis of AGC start | 1 | 3 | 6 | dB |
| Continuous AM RF AGC | | | | | | |
| $V_{i(RF)AGC}$ | AGC RF input voltage | linear RF AGC: $V_{i(RF)}$ at which AGC starts; $m = 0\%$ | | | | |
| | | data byte 2h bits RFAGC[1:0] = 00 | 87 | 90 | 93 | dB μV |
| | | data byte 2h bits RFAGC[1:0] = 01 | 85 | 88 | 91 | dB μV |
| | | data byte 2h bits RFAGC[1:0] = 10 | 83 | 86 | 89 | dB μV |
| | | data byte 2h bits RFAGC[1:0] = 11 | 81 | 84 | 87 | dB μV |
| t_s | settling time | $V_{i(RF)} = 10\text{ mV to }600\text{ mV}$ | - | 64 | - | ms |
| | | $V_{i(RF)} = 600\text{ mV to }10\text{ mV}$ | - | 3.2 | - | s |

Table 62. Dynamic characteristics ...continued

$V_{CC} = 8.5\text{ V}$; $T_{amb} = 25\text{ }^{\circ}\text{C}$; unless otherwise specified.

FM condition: all RF voltages refer to an unterminated RMS voltage with a source impedance $75\text{ }\Omega$; $f_{mod} = 1\text{ kHz}$, $\Delta f = 22.5\text{ kHz}$, de-emphasis = $50\text{ }\mu\text{s}$, $f_{RF} = 97.1\text{ MHz}$; unless otherwise specified.

AM condition: all RF voltages are RMS values measured at the input of a $15\text{ pF} / 60\text{ pF}$ dummy aerial; $f_{mod} = 400\text{ Hz}$, $m = 30\%$, $f_{RF} = 990\text{ kHz}$; unless otherwise specified.

All values measured in a test circuit according to [Figure 30](#); default settings; audio signals measured at LOUT and ROUT with IEC tuner filter (200 Hz to 15 kHz; IEC 60315-4); unless otherwise specified.

| $m = 30\%$, $f_{RF} = 990\text{ kHz}$; unless otherwise specified. All values measured in a test circuit according to Figure 30 ; default settings; audio signals measured at LOUT and ROUT with IEC tuner filter (200 Hz to 15 kHz; IEC 60315-4); unless otherwise specified. | | | | | | |
|---|----------------------|---|-------|------|------|------------------------|
| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
| $I_{source(AGC)}$ | AGC source current | AGC attack; $V_{i(RF)M} = 105\text{ dB}\mu\text{V}$ (peak); normal mode | 25 | 35 | 50 | μA |
| | | AGC attack; fast mode after tuning and AGC switching | 0.7 | 1 | 1.4 | mA |
| $I_{sink(AGC)}$ | AGC sink current | AGC release; normal mode | 0.7 | 1 | 1.4 | μA |
| | | AGC release; fast mode after tuning and AGC switching | 17.5 | 25 | 35 | μA |
| Continuous IF AGC 1 | | | | | | |
| $V_{i(RF)AGC}$ | AGC RF input voltage | linear IF AGC 1: $V_{i(RF)}$ at which AGC starts; $m = 0\%$ | 59 | 62 | 65 | $\text{dB}\mu\text{V}$ |
| $I_{source(AGC)}$ | AGC source current | AGC attack; $V_{i(RF)M} = 80\text{ dB}\mu\text{V}$ (peak); normal mode | 35 | 50 | 70 | μA |
| | | AGC attack; fast mode after tuning and AGC switching | 0.875 | 1.25 | 1.75 | mA |
| $I_{sink(AGC)}$ | AGC sink current | AGC release; normal mode | 0.7 | 1 | 1.4 | μA |
| | | AGC release; fast mode after tuning and AGC switching | 17.5 | 25 | 35 | μA |
| Continuous IF AGC 2 | | | | | | |
| $V_{i(RF)AGC}$ | AGC RF input voltage | linear IF AGC 2: $V_{i(RF)}$ at which AGC starts; $m = 0\%$ | 19 | 22 | 25 | $\text{dB}\mu\text{V}$ |
| $I_{source(AGC)}$ | AGC source current | AGC attack; $V_{i(RF)M} = 50\text{ dB}\mu\text{V}$ (peak); normal mode | 4 | 6 | 8 | μA |
| | | AGC attack; fast mode after tuning and AGC switching | 100 | 150 | 200 | μA |
| $I_{sink(AGC)}$ | AGC sink current | AGC release; normal mode | 0.7 | 1 | 1.4 | μA |
| | | AGC release; fast mode after tuning and AGC switching | 17.5 | 25 | 35 | μA |
| AM demodulator; pin MPXOUT | | | | | | |
| V_o | output voltage | $m = 30\%$ | 175 | 210 | 250 | mV |
| Audio output; pins LOUT and ROUT | | | | | | |
| V_o | output voltage | $m = 30\%$; $f_{AF} = 400\text{ Hz}$; data byte 3h bits DEMP[1:0] = 10 | | | | |
| | | data byte 3h bit OUTA = 1 | 200 | 270 | 355 | mV |
| | | data byte 3h bit OUTA = 0 | 85 | 115 | 150 | mV |

Table 62. Dynamic characteristics ...continued

$V_{CC} = 8.5\text{ V}$; $T_{amb} = 25\text{ }^{\circ}\text{C}$; unless otherwise specified.

FM condition: all RF voltages refer to an unterminated RMS voltage with a source impedance $75\text{ }\Omega$; $f_{mod} = 1\text{ kHz}$,

$\Delta f = 22.5\text{ kHz}$, de-emphasis = $50\text{ }\mu\text{s}$, $f_{RF} = 97.1\text{ MHz}$; unless otherwise specified.

AM condition: all RF voltages are RMS values measured at the input of a $15\text{ pF} / 60\text{ pF}$ dummy aerial; $f_{mod} = 400\text{ Hz}$,

$m = 30\%$, $f_{RF} = 990\text{ kHz}$; unless otherwise specified.

All values measured in a test circuit according to [Figure 30](#); default settings; audio signals measured at LOUT and ROUT with IEC tuner filter (200 Hz to 15 kHz; IEC 60315-4); unless otherwise specified.

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--------------------------------------|--|---|------|-----|------|------------------|
| α_{AF} | AF attenuation | referenced to $f_{AF} = 400\text{ Hz}$ | | | | |
| | | $f_{AF} = 100\text{ Hz}$; data byte 3h bit LOCUT = 1 | -4.5 | -3 | -1.5 | dB |
| | | $f_{AF} = 1.5\text{ kHz}$; data byte 3h bits DEMP[1:0] = 10 | -4 | -3 | -2 | dB |
| THD | total harmonic distortion | $V_{i(RF)} = 1\text{ mV}$; $m = 80\%$ | - | 0.7 | 1 | % |
| α_{ripple} | ripple rejection | V_{ripple} / V_{audio} ; $V_{ripple} = 100\text{ mV}$; $f_{ripple} = 100\text{ Hz}$ | 24 | 31 | - | dB |
| AM noise blanker | | | | | | |
| SINAD | signal-to-noise-and-distortion ratio | $m = 30\%$; $f_{AF} = 1\text{ kHz}$; noise pulses at RF input signal $t_p = 100\text{ ns}$; $t_r < 1\text{ ns}$; $t_f < 1\text{ ns}$; $f_p = 100\text{ Hz}$; $V_p = 500\text{ mV}$; $V_{i(RF)} = 40\text{ dB}\mu\text{V}$ | - | 12 | - | dB |
| AM RSSI; pin RSSI | | | | | | |
| V_{RSSI} | RSSI voltage | $V_{i(RF)} = -20\text{ dB}\mu\text{V}$ at dummy aerial input | 1.05 | 1.2 | 1.35 | V |
| | | $V_{i(RF)} = 14\text{ dB}\mu\text{V}$ at dummy aerial input | 1.7 | 1.9 | 2.1 | V |
| | | $V_{i(RF)} = 34\text{ dB}\mu\text{V}$ at dummy aerial input | 2.65 | 2.9 | 3.15 | V |
| | | $V_{i(RF)} = 54\text{ dB}\mu\text{V}$ at dummy aerial input | 3.5 | 3.8 | 4.1 | V |
| $\Delta V_{RSSI} / \Delta L_{i(RF)}$ | RSSI voltage difference to RF input level difference ratio | $5\text{ }\mu\text{V} < V_{i(RF)} < 50\text{ }\mu\text{V}$ | 45 | 50 | 55 | mV/dB |
| AM IF counter | | | | | | |
| $V_{i(sens)}$ | input sensitivity voltage | $V_{i(RF)}$ at which IF counter starts; $m = 0\%$ | - | 14 | 20 | dB μV |
| $f_{IFc(res)}$ | IF counter frequency resolution | | - | 500 | - | Hz |

[1] $f_{LO} = f_{RF} + f_{IF}$ for high injection and $f_{LO} = f_{RF} - f_{IF}$ for low injection.

[2] The switched input capacitance is part of the switched RF AGC function.

[3] The input impedance of the AM LNA depends on the AGC state.

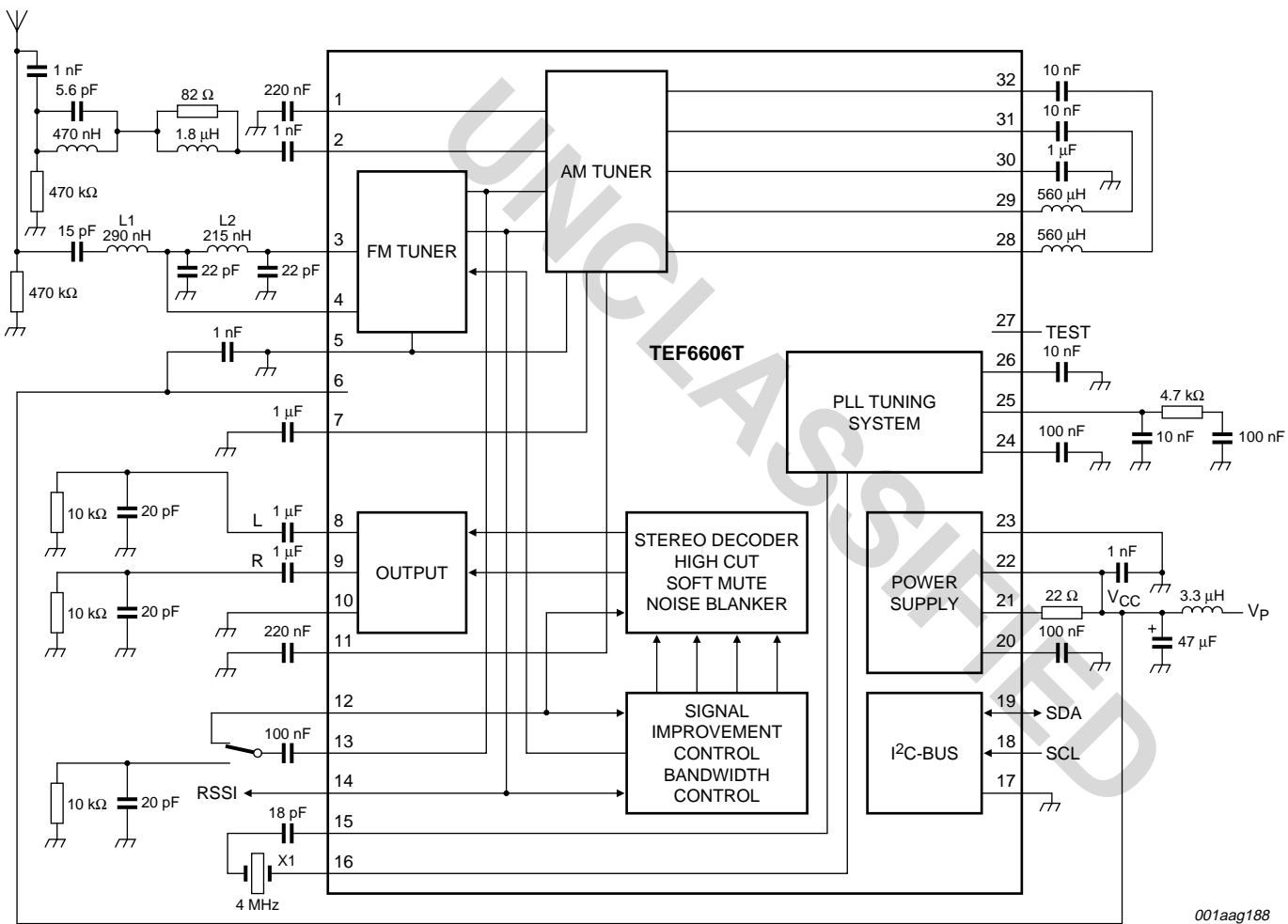


Fig 29. Application diagram of TEF6606T

Table 63. 4MHz crystal specification for [Figure 29](#) and [Figure 30](#)

| Parameter | Symbol | Value | Unit |
|-----------------------------|--------------|-------------|----------|
| Nominal frequency | F_n | 4.000 | MHz |
| Oscillation mode | | fundamental | |
| Load capacitance | C_L | 18 | pF |
| Shunt capacitance | C_O | 7 max. | pF |
| Motional capacitance | C_1 | 10 typ. | fF |
| Series resistance | R_R | 150 max. | Ω |
| Accuracy at 25 °C | ΔF_N | +/-25 | ppm |
| Ageing | ΔF_N | +/-5 | ppm |
| Temperature stability | ΔF_N | +/-30 | ppm |
| Operating temperature range | T | -40 /+85 | °C |

14. Test information



001aag188

For list of components see [Table 64](#).

Fig 30. Test circuit of TEF6606T

Table 64. List of components for Figure 29 and Figure 30

| Symbol | Component | Type | Manufacturer |
|--------|---------------|------------------------|--------------|
| L1 | FM RF input 1 | 290 nH; LQH31HNR29K03L | muRata |
| L2 | FM RF input 2 | 215 nH; LQH31HNR21K01L | muRata |
| X1 | crystal 4 MHz | LN-G102-1413 | NDK |

Table 65. DC operating points

$V_{i(RF)} = 0 \mu V$; audio output gain low; unless otherwise specified.

| Symbol | Pin | Unloaded DC voltage (V) | | | | | |
|------------------|-----|---------------------------------------|------|-----------------|---------------------------------------|------|-----------------|
| | | AM mode | | | FM mode | | |
| | | Min | Typ | Max | Min | Typ | Max |
| AMRFDEC | 1 | - | 4.1 | - | floating | | |
| AMRFIN | 2 | - | 2.85 | - | - | - | - |
| FMIN2 | 3 | - | - | - | - | 3.1 | - |
| FMIN1 | 4 | - | - | - | - | 3.1 | - |
| GNDRF | 5 | external GND | | | external GND | | |
| V _{CC2} | 6 | external 8.5 | | | external 8.5 | | |
| AMRFAGC | 7 | floating | | | - | - | - |
| LOUT | 8 | - | 3.8 | - | - | 3.8 | - |
| ROUT | 9 | - | 3.8 | - | - | 3.8 | - |
| GNDAUD | 10 | external GND | | | external GND | | |
| AMIFAGC2 | 11 | - | - | - | - | - | - |
| MPXIN | 12 | - | 3.7 | - | - | 3.7 | - |
| MPXOUT | 13 | - | 4 | - | - | 4 | - |
| RSSI | 14 | - | 1.3 | - | - | 1.3 | - |
| XTAL2 | 15 | - | 6.5 | - | - | 6.5 | - |
| XTAL1 | 16 | - | 6.5 | - | - | 6.5 | - |
| GNDD | 17 | external GND | | | external GND | | |
| SCL | 18 | external I ² C-bus voltage | | | external I ² C-bus voltage | | |
| SDA | 19 | external I ² C-bus voltage | | | external I ² C-bus voltage | | |
| VREF | 20 | 3.9 | 4.0 | 4.1 | 3.9 | 4.0 | 4.1 |
| VREGSUP | 21 | 5.6 | 6.5 | 7 | 5.6 | 6.5 | 7 |
| V _{CC1} | 22 | external 8.5 | | | external 8.5 | | |
| GND | 23 | external GND | | | external GND | | |
| VCODEC | 24 | - | 5.7 | - | - | 5.7 | - |
| PLL | 25 | 1.2 | - | 5.5 | 1.2 | - | 5.5 |
| PLLREF | 26 | - | 2.25 | - | - | 2.25 | - |
| TEST | 27 | - | - | - | - | - | - |
| AMSELIN1 | 28 | 7 | - | V _{CC} | 7 | - | V _{CC} |
| AMSELIN2 | 29 | 7 | - | V _{CC} | 7 | - | V _{CC} |
| AMIFAGC1 | 30 | - | 5.5 | - | - | - | - |
| AMSELOUT1 | 31 | 7 | - | V _{CC} | 7 | - | V _{CC} |
| AMSELOUT2 | 32 | 7 | - | V _{CC} | 7 | - | V _{CC} |

14.1 Quality information

This product has been qualified in accordance with the Automotive Electronics Council (AEC) standard Q100 (Stress qualification for integrated circuits) and is suitable for use in automotive critical applications.

UNCLASSIFIED

15. Package outline

SO32: plastic small outline package; 32 leads; body width 7.5 mm

SOT287-1

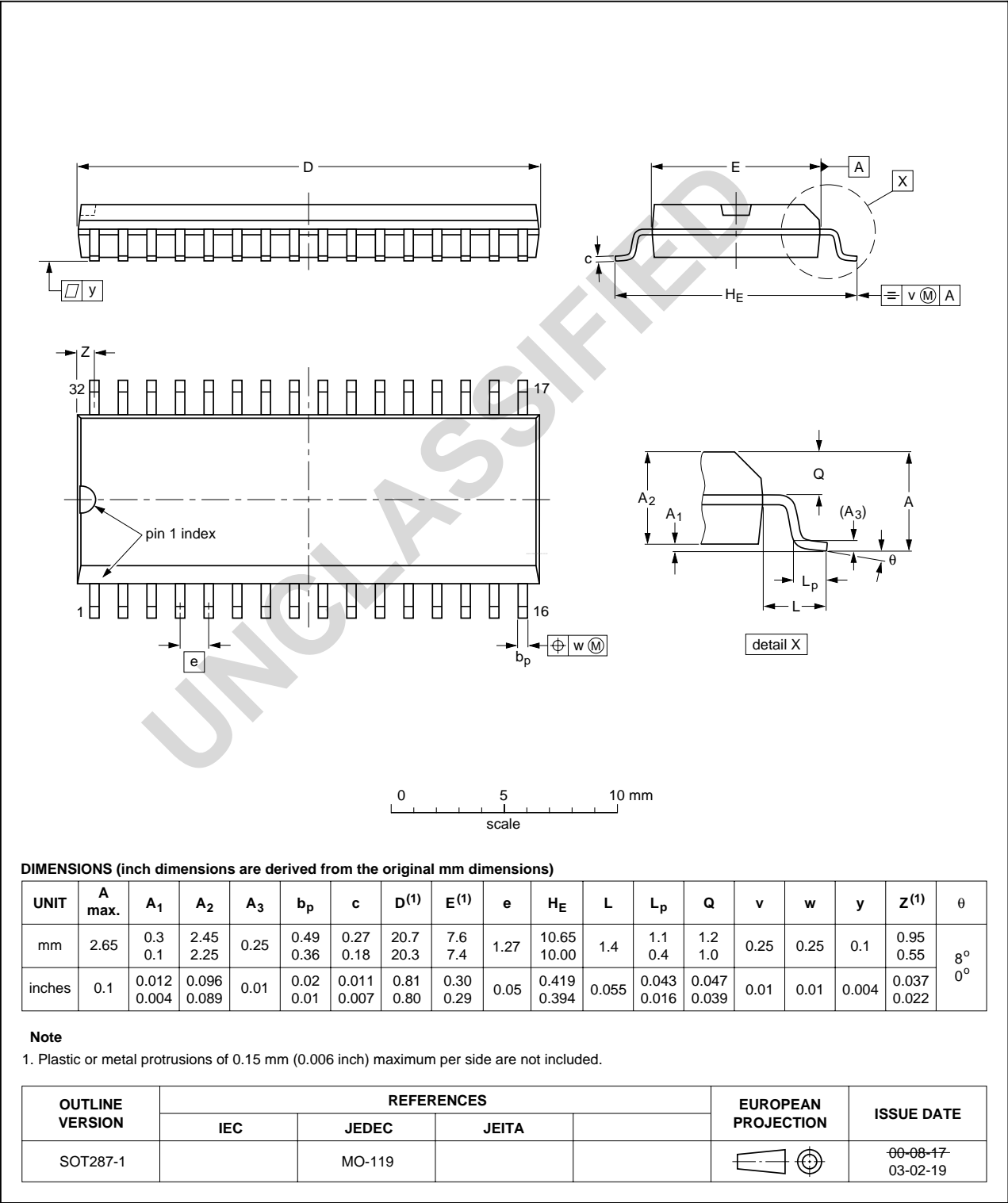


Fig 31. Package outline SOT287-1 (SO32)

16. Soldering

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note AN10365 "Surface mount reflow soldering description".

16.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

16.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus PbSn soldering

16.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

16.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see [Figure 32](#)) than a PbSn process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with [Table 66](#) and [67](#)

Table 66. SnPb eutectic process (from J-STD-020C)

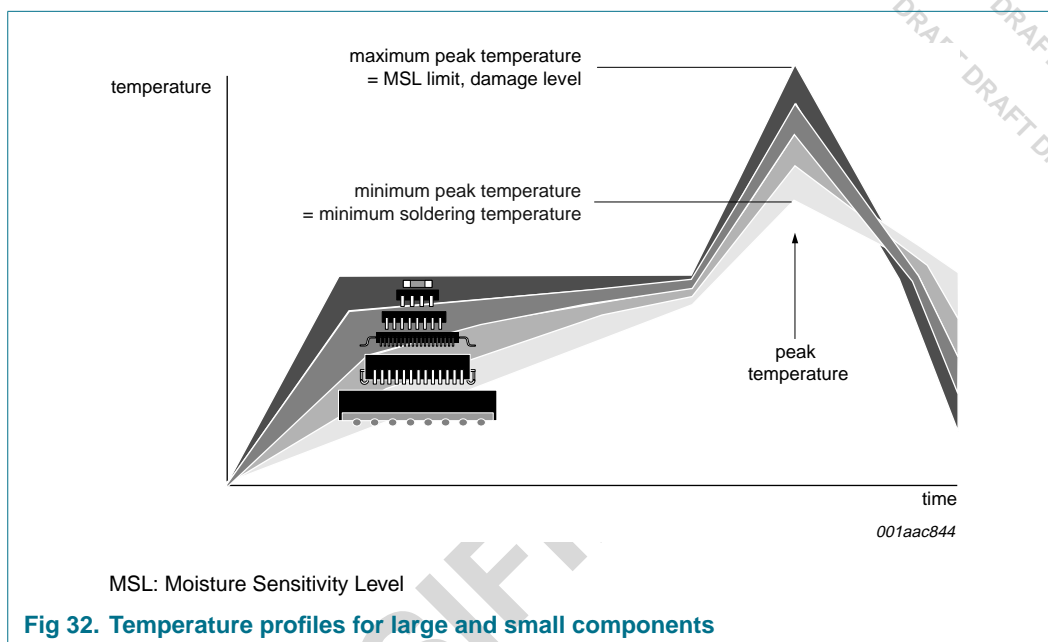
| Package thickness (mm) | Package reflow temperature (°C) | |
|------------------------|---------------------------------|-------|
| | Volume (mm ³) | |
| | < 350 | ≥ 350 |
| < 2.5 | 235 | 220 |
| ≥ 2.5 | 220 | 220 |

Table 67. Lead-free process (from J-STD-020C)

| Package thickness (mm) | Package reflow temperature (°C) | | |
|------------------------|---------------------------------|-------------|--------|
| | Volume (mm ³) | | |
| | < 350 | 350 to 2000 | > 2000 |
| < 1.6 | 260 | 260 | 260 |
| 1.6 to 2.5 | 260 | 250 | 245 |
| > 2.5 | 250 | 245 | 245 |

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see [Figure 32](#).



For further information on temperature profiles, refer to Application Note AN10365 "Surface mount reflow soldering description".

17. Abbreviations

Table 68. Abbreviations

| Acronym | Description |
|---------|--|
| AGC | Automatic Gain Control |
| HCC | High-Cut Control |
| IF | Intermediate Frequency |
| LO | Local Oscillator |
| LW | Long Wave |
| MPX | Multiplex |
| MW | Medium Wave |
| PACS | Precision Adjacent Channel Suppression |
| PLL | Phase-Locked Loop |
| RF | Radio Frequency |
| RSSI | Received Signal Strength Indication |
| SW | Short Wave |
| USN | UltraSonic Noise |
| VCO | Voltage-Controlled Oscillator |
| WAM | Wideband AM |

18. Revision history

Table 69. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|---|--------------|----------------------|---------------|------------|
| TEF6606_1 | yyymmdd | Objective data sheet | - | - |
| Modifications: | | | | |
| <ul style="list-style-type: none">Updated Figure 5 to Figure 15, Figure 29 and Figure 30Changed device type identification in Section 8.1.5Changed text inset in Section 14.1 | | | | |

19. Legal information

19.1 Data sheet status

| Document status ^{[1][2]} | Product status ^[3] | Definition |
|-----------------------------------|-------------------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

19.2 Definitions

Draft — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

Short data sheet — A short data sheet is an extract from a full data sheet with the same product type number(s) and title. A short data sheet is intended for quick reference only and should not be relied upon to contain detailed and full information. For detailed and full information see the relevant full data sheet, which is available on request via the local NXP Semiconductors sales office. In case of any inconsistency or conflict with the short data sheet, the full data sheet shall prevail.

19.3 Disclaimers

General — Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information.

Right to make changes — NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

Suitability for use — NXP Semiconductors products are not designed, authorized or warranted to be suitable for use in medical, military, aircraft, space or life support equipment, nor in applications where failure or malfunction of a NXP Semiconductors product can reasonably be expected to

result in personal injury, death or severe property or environmental damage. NXP Semiconductors accepts no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

Applications — Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Limiting values — Stress above one or more limiting values (as defined in the Absolute Maximum Ratings System of IEC 60134) may cause permanent damage to the device. Limiting values are stress ratings only and operation of the device at these or any other conditions above those given in the Characteristics sections of this document is not implied. Exposure to limiting values for extended periods may affect device reliability.

Terms and conditions of sale — NXP Semiconductors products are sold subject to the general terms and conditions of commercial sale, as published at <http://www.nxp.com/profile/terms>, including those pertaining to warranty, intellectual property rights infringement and limitation of liability, unless explicitly otherwise agreed to in writing by NXP Semiconductors. In case of any inconsistency or conflict between information in this document and such terms and conditions, the latter will prevail.

No offer to sell or license — Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights.

19.4 Trademarks

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

I²C-bus — logo is a trademark of NXP B.V.

20. Contact information

For additional information, please visit: <http://www.nxp.com>

For sales office addresses, send an email to: salesaddresses@nxp.com

Please be aware that important notices concerning this document and the product(s) described herein, have been included in section 'Legal information'.

© NXP B.V. 2007.

All rights reserved.

For more information, please visit: <http://www.nxp.com>

For sales office addresses, please send an email to: salesaddresses@nxp.com

Date of release: 12 June 2007

Document identifier: TEF6606_1

founded by

PHILIPS

21. Contents

| | | |
|-----------|---|-----------|
| 1 | General description | 1 |
| 2 | Features | 1 |
| 3 | Quick reference data | 2 |
| 4 | Ordering information | 2 |
| 5 | Block diagram | 3 |
| 6 | Pinning information | 4 |
| 6.1 | Pinning | 4 |
| 6.2 | Pin description | 4 |
| 7 | Functional description | 5 |
| 7.1 | FM tuner | 5 |
| 7.2 | AM tuner | 5 |
| 7.3 | PLL tuning system | 5 |
| 7.4 | Signal dependent FM IF bandwidth control ... | 5 |
| 7.5 | FM stereo decoder | 5 |
| 7.6 | Weak signal processing and noise blanker. ... | 5 |
| 7.7 | I ² C-bus transceiver | 6 |
| 8 | I²C-bus protocol | 6 |
| 8.1 | Read mode | 6 |
| 8.1.1 | Read mode: data byte STATUS | 7 |
| 8.1.2 | Read mode: data byte LEVEL | 7 |
| 8.1.3 | Read mode: data byte USN_WAM | 8 |
| 8.1.4 | Read mode: data byte IFCOUNTER | 8 |
| 8.1.5 | Read mode: data byte ID | 9 |
| 8.2 | Write mode | 9 |
| 8.2.1 | Mode and subaddress byte for write. | 10 |
| 8.2.2 | Write mode: data byte TUNER0 | 22 |
| 8.2.3 | Write mode: data byte TUNER1 | 22 |
| 8.2.4 | Write mode: data byte TUNER2 | 23 |
| 8.2.5 | Write mode: data byte RADIO | 24 |
| 8.2.6 | Write mode: data byte SOFTMUTE0 | 24 |
| 8.2.7 | Write mode: data byte SOFTMUTE1 | 25 |
| 8.2.8 | Write mode: data byte SOFTMUTE2_FM. ... | 27 |
| 8.2.9 | Write mode: data byte SOFTMUTE2_AM ... | 29 |
| 8.2.10 | Write mode: data byte HIGHCUT0 | 29 |
| 8.2.11 | Write mode: data byte HIGHCUT1 | 30 |
| 8.2.12 | Write mode: data byte HIGHCUT2 | 32 |
| 8.2.13 | Write mode: data byte STEREO0 | 34 |
| 8.2.14 | Write mode: data byte STEREO1 | 35 |
| 8.2.15 | Write mode: data byte STEREO2 | 36 |
| 8.2.16 | Write mode: data byte CONTROL | 38 |
| 8.2.17 | Write mode: data byte LEVEL_OFFSET ... | 38 |
| 8.2.18 | Write mode: data byte AM_LNA | 39 |
| 9 | Limiting values | 39 |
| 10 | Thermal characteristics | 40 |
| 11 | Static characteristics | 40 |
| 12 | Dynamic characteristics | 41 |
| 13 | Application information | 49 |
| 14 | Test information | 50 |
| 14.1 | Quality information | 52 |
| 15 | Package outline | 53 |
| 16 | Soldering | 54 |
| 16.1 | Introduction to soldering | 54 |
| 16.2 | Wave and reflow soldering | 54 |

| | | |
|-----------|--------------------------------------|-----------|
| 16.3 | Wave soldering | 54 |
| 16.4 | Reflow soldering | 55 |
| 17 | Abbreviations | 56 |
| 18 | Revision history | 57 |
| 19 | Legal information | 58 |
| 19.1 | Data sheet status | 58 |
| 19.2 | Definitions | 58 |
| 19.3 | Disclaimers | 58 |
| 19.4 | Trademarks | 58 |
| 20 | Contact information | 58 |
| 21 | Contents | 59 |