High-level Reference Generation

Human Data → Hand-Object Particles → **Particle-Based World Model** → Collision / Trajectory Proposal / Model-Based Search
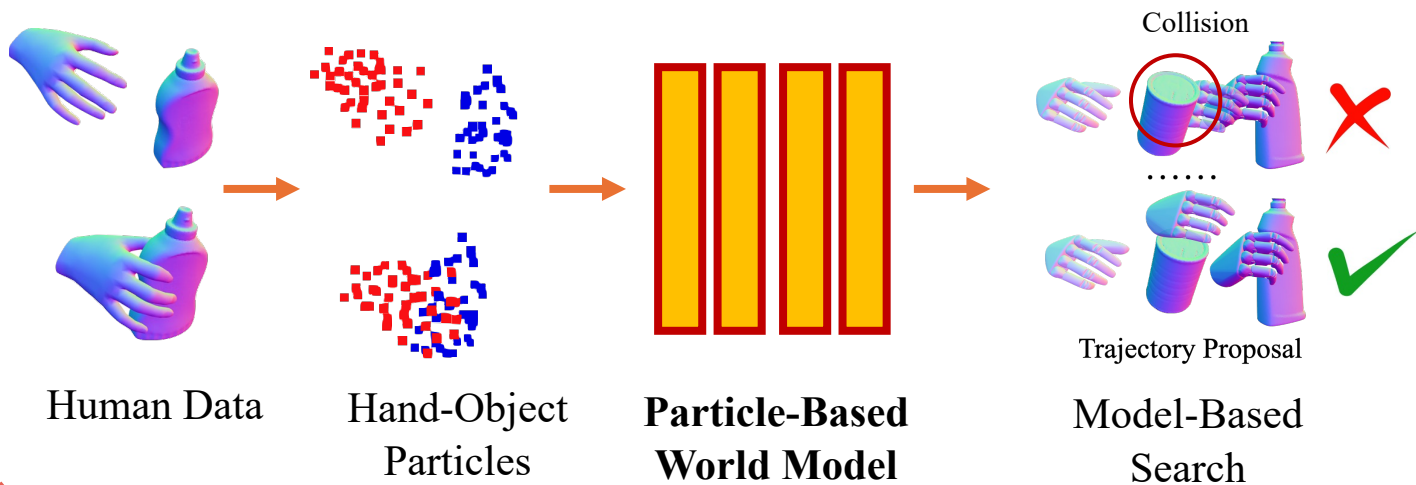
Low-level Control Refinement

Zero-Shot Transfer ← RL Policies ← Robot References