

Tipos Habitados

Sean σ, τ, ρ tipos cualquiera.

a) $\sigma \rightarrow \tau \rightarrow \sigma$

$M = \lambda x:\sigma. \lambda y:\tau. x$ const

$$\frac{\frac{\frac{}{x:\sigma, y:\tau \vdash x:\sigma} ax_v}{x:\sigma \vdash \lambda y:\tau. x:\tau \rightarrow \sigma} \rightarrow_i}{\vdash \lambda x:\sigma. \lambda y:\tau. x:\sigma \rightarrow \tau \rightarrow \sigma} \rightarrow_i$$

b) $\Delta = (\sigma \rightarrow \tau \rightarrow \rho) \rightarrow (\sigma \rightarrow \tau) \rightarrow \sigma \rightarrow \rho$

$M = \lambda F:(\sigma \rightarrow \tau \rightarrow \rho). \lambda g:(\sigma \rightarrow \tau). \lambda x:\sigma. (fx)(gx)$ Combinador S

$$\frac{\frac{\frac{\frac{\Gamma \vdash F:\sigma \rightarrow \tau \rightarrow \rho}{\Gamma \vdash Fx:\tau \rightarrow \rho} ax_v}{\Gamma \vdash Fx:\tau \rightarrow \rho} \rightarrow_e}{\Gamma \vdash Fx:\tau \rightarrow \rho} \rightarrow_e}{\frac{\frac{\frac{\frac{\Gamma \vdash g:\sigma \rightarrow \tau}{\Gamma \vdash gx:\tau} ax_v}{\Gamma \vdash gx:\tau} \rightarrow_e}{\Gamma \vdash Fx:\tau \rightarrow \rho, gx:\sigma \vdash (fx)(gx):\rho} \rightarrow_i}{F:\sigma \rightarrow \tau \rightarrow \rho, g:\sigma \rightarrow \tau \vdash \lambda x:\sigma. (fx)(gx):\sigma \rightarrow \rho} \rightarrow_i}{F:\sigma \rightarrow \tau \rightarrow \rho \vdash \lambda g:(\sigma \rightarrow \tau). \lambda x:\sigma. (fx)(gx):(\sigma \rightarrow \tau) \rightarrow \sigma \rightarrow \rho} \rightarrow_i}{\vdash \lambda F:(\sigma \rightarrow \tau \rightarrow \rho). \lambda g:(\sigma \rightarrow \tau). \lambda x:\sigma. (fx)(gx):\Delta} \rightarrow_i$$

$$c) (\sigma \rightarrow \tau \rightarrow \rho) \rightarrow \tau \rightarrow \sigma \rightarrow \rho$$

$$M = \lambda f: (\sigma \rightarrow \tau \rightarrow \rho). \lambda \gamma: \tau. \lambda x: \sigma. f x \gamma \quad \text{flip}$$

$$\begin{array}{c}
 \frac{\frac{\frac{}{\Gamma \vdash f: \sigma \rightarrow \tau \rightarrow \rho} \text{ax}_f \quad \frac{}{\Gamma \vdash x: \sigma} \text{ax}_x}{\Gamma \vdash f x: \tau \rightarrow \rho} \rightarrow_e \quad \frac{}{\Gamma \vdash y: \tau} \text{ax}_y}{\Gamma = f: \sigma \rightarrow \tau \rightarrow \rho, y: \tau, x: \sigma \vdash f x y: \rho} \rightarrow_e \\
 \frac{}{f: \sigma \rightarrow \tau \rightarrow \rho, y: \tau \vdash \lambda x: \sigma. f x y: \sigma \rightarrow \rho} \rightarrow_i \\
 \frac{}{f: \sigma \rightarrow \tau \rightarrow \rho \vdash \lambda y: \tau. \lambda x: \sigma. f x y: \tau \rightarrow \sigma \rightarrow \rho} \rightarrow_i \\
 \frac{}{\vdash \lambda f: (\sigma \rightarrow \tau \rightarrow \rho). \lambda y: \tau. \lambda x: \sigma. f x y: (\sigma \rightarrow \tau \rightarrow \rho) \rightarrow \tau \rightarrow \sigma \rightarrow \rho} \rightarrow_i
 \end{array}$$

$$d) (\tau \rightarrow \rho) \rightarrow (\sigma \rightarrow \tau) \rightarrow \sigma \rightarrow \rho$$

$$M = \lambda f: (\tau \rightarrow \rho). \lambda g: (\sigma \rightarrow \tau). \lambda x: \sigma. f (g x) \quad (.) \text{ composición}$$

$$\begin{array}{c}
 \frac{\frac{\frac{}{\Gamma \vdash g: \sigma \rightarrow \tau} \text{ax}_g \quad \frac{}{\Gamma \vdash x: \sigma} \text{ax}_x}{\Gamma \vdash g x: \tau} \rightarrow_e \quad \frac{}{\Gamma \vdash f: \tau \rightarrow \rho} \text{ax}_f}{\Gamma = f: \tau \rightarrow \rho, g: \sigma \rightarrow \tau, x: \sigma \vdash f (g x): \rho} \rightarrow_e \\
 \frac{}{f: \tau \rightarrow \rho, g: \sigma \rightarrow \tau \vdash \lambda x: \sigma. f (g x): \sigma \rightarrow \rho} \rightarrow_i \\
 \frac{}{f: \tau \rightarrow \rho \vdash \lambda g: (\sigma \rightarrow \tau). \lambda x: \sigma. f (g x): (\sigma \rightarrow \tau) \rightarrow \sigma \rightarrow \rho} \rightarrow_i \\
 \frac{}{\vdash \lambda f: (\tau \rightarrow \rho). \lambda g: (\sigma \rightarrow \tau). \lambda x: \sigma. f (g x): (\tau \rightarrow \rho) \rightarrow (\sigma \rightarrow \tau) \rightarrow \sigma \rightarrow \rho} \rightarrow_i
 \end{array}$$