## Exam Notes of Code and Math

Wednesday, December 6, 2023

5:43 PM

Amdahl's Law

S: % of series N: Number of processing cores

Banker's Algorithm

System Snapshot

Need = Max - Allocation

Allocation Max

ABCD

ABCD

ABCD Only | entry

Available

Need

ABCD

Safe State:

Follow Algorithm:

1) Check if need has each element less than or equal to available.

2) If satisfies, then add thread to safe state and add need to available

3) If does not satisfy, go to next one.

4) If no more threads, then safe state exists.

5) If after full cycle no more threads con be added but still some exist not in the safe state, then false.

e.g. (TO, T2, T3, T4, T1)

Request for Immediate Access

·Tn:Threads Rm:Resources

· Cycle occurs (directed cycle)

'If does not deadlock, then list

Traits of dead lock

order of threads

·Otherwise, list cycles

(Most of the time)

·If the elements in Available ≥ Request, access is granted IMMEDIATELY

e.g. Ti request for <1410> is granted immediately

CPU Scheduling

Given a time quantum, overhead from context switching, and tasks

calculate CPU utilization

Memory Management

Given N-bit address, p-bit physical address, and page size

1) Find # of entries in conventional single-level table

i) Determine # of bits in page size e.g. if page size = 8KB, then convert to 213 by tes, thus 13 bits

ii) Subtract # of bits found in i with n-bits to get q-bits

iii) 29-bits

2) Find # of enthes in an inverted page

i)Use # of bits in page size

ii) Subtract from # of bits in physical address to get q-bits

iii) 29-bits

3) Max amount of physical memory = 2 physical bits

Demand - Paged Memory

Variables: m: Memory Access Time rn: rate for a page fault event to happen Sn: time it takes for such event to 'complete

Calculate: P: Page-fault Rate

Effective Access Time = (1-P)m+P. Tri.si = (1-P)m+ rosoP+risiP...

Resource - Allocation Tables Virtual Memory

·Determine if something has deadlock Page Fault Algorithms:

LAU: Least recently used

FIFO: First in first out

Optimal Replacement: Replace the one that has the next value furthest away or does not exist in the rest of the lists

File Management

Given pointers, size of disk sectors, find max file size. (Size of int = 4)

Type of pointers: Direct, Single, Double, Iriple,...

How to calculate:

Degree of pointer size of disk sector · size of disk size size of int

Sum up all the pointers!

Parent/Child Functions

fork(): Creates duplicate function (1 child 1 parent) When called as follows: pidt pid; pid = fork();

If pid 40, fork failed pid ==0, child process pid>0, parent process

Parent & Child execute every line after fork! Each fork doubles # of processes

wait (NULL): Used on parent function to wait for children functions to terminate

If not used, one of 2 functions could occur: zombie Function:

· Process that has finished execution but still has entry in process table

· Child process done, but parent function is waiting (e.g. sleep (so): sleep for 50 seconds)

· Wastes System resources

· Child finishes first but waits while alive

Orphan:

Process where parent no longer exists I terminated or finished) without waiting for child to finish

·Orphan process stays and con not properly terminate

Functions to Remember exec functions execute functions

execup(args[o].args);

· Executes and creates new child function . Child process does not have to run same program as parent process

args [0] & args are pointers to char \* args[].

execup parameters are ALL pointers · First variable is a filename

execv (args[0], args);

· Same as execup BUT angs[0] is path to executable

Threads

Lightweight process

Sequential execution stream

· Process has at least 1 thread

Most apps today are multithreaded

· Displaying graphics · Keystrokes

· Spelling & grammar

· A efficiency, simplify code · Parallel coding

Thread Creation

0) Import pthread.h #include <pthread.h>

1) Declare thread ID pthread\_t thread\_id;

2) Create thread with pthread\_create(): pthread\_create(a,b,c,d);

a: pointer to thread ID (&thread-id) b. Attributes. Usually NULL or O for

default C: function

d: function variables

3) Use pthread\_join(); for threads (same as wait())

pthread\_join (a,b)

b: NULL

a: thread ID (&thread\_ia)

Thread Termination

17Use pthread-cancel (tid);

· Only indicates a request to terminate

· Actual termination depends on target

thread set up to handle request · Can set cancellation state a type using API

. Only occurs when pthread\_testcancel() invoked. then cleanup handler

Tree Hierarchy

·Start with PO(parent)

· First fork: P1 is created

·Second fork: P2 and P3 are created

Third fork: P4,P5, P6, and P7 are created

Continues for each fork

·# of processes = 2 number of forks

Gantt Chart

·Chart that displays time for each process ·Shows dependency relations

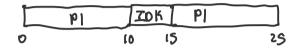
· Suppose T1=245, T2=55, T3=65



Turnaround Time: Time end - Arrival Time · Important for something like a round robin scheduler

Arrival Time + Start Time!

Wait Time: Sum of idle time not running the process when process has started



IDK is the wait time

Include Start Time - Arrival Time

Total Time - Total Wait CPU Utilization Rate: 100% Total Time

Exponential Average Formula

Tn+1= aT + (1-a) To

Given a and To

·If a = 0, then formula has consistent Solution (%)

·Ifa≠0, then in terms of T, which means most recent behaviour is much higher weight than past history.

Producer Consumer Program

·If program has voniables (a, b, c)

·Suppose a is an int, b & c are binary semaphones

a: Increments iff att or a -- or integer operations

b.c: Wait makes it go from 1-0, Signal makes it go from O →1

Critical Sections: Operations on a (a+t or a--)

a: Represents if consumer consumed. Depending on code and implementation, CAN BE NEGATIVE (but bad)