Supplementary Material for "An ADMM-based Battery Dispatch Optimization Approach for Electric Vehicle Aggregators with Customized Local Differential Privacy Budgets"

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I. Proof of Theorem 1

There exists an optimal battery dispatch optimization (BDO) solution \boldsymbol{x}_i^{t*} with the minimum objective function value \boldsymbol{F}^* for the non-private BDO model (1a)-(1e). We incorporate $\boldsymbol{p}_{sig,i}^{t*} \in \mathbb{R}$ such that $\sum_{i=1}^{N_E} \boldsymbol{p}_{sig,i}^{t*} = \boldsymbol{p}_{ref}^t$. Then, $\left\| \sum_{i=1}^{N_E} \boldsymbol{c}^T \boldsymbol{x}_i^{t*} - \boldsymbol{p}_{ref}^t \right\|_2 = \left\| \sum_{i=1}^{N_E} (\boldsymbol{c}^T \boldsymbol{x}_i^{t*} - \boldsymbol{p}_{sig,i}^{t*}) \right\|_2 \text{ can hold. Clearly,}$ $\sum_{t=1}^{N_T} \left\| \sum_{i=1}^{N_E} (\boldsymbol{c}^T \boldsymbol{x}_i^{t*} - \boldsymbol{p}_{ref}^t) \right\|_2 = \boldsymbol{F}^* \text{ can be achieved. This proves that } (\boldsymbol{x}_i^{t*}, \boldsymbol{p}_{sig,i}^{t*}) \in \mathcal{X} \text{ can be the optimal BDO solution with the minimum objective function value } \boldsymbol{F}^*.$

Due to the triangle inequality of norms, i.e., $|a+b| \leq |a| + |b|$ for any real-valued numbers a and b, we obtain that $F^* \leq F \leq G$ naturally holds. This suggests that F^* can be the lower bound of G over \mathcal{X} . In other words, $(x_i^{t*}, p_{sig,i}^{t*}) \in \mathcal{X}$ can be the optimal solution iff the minimum function value $G^* = F^*$ is achieved, which demonstrates $(x_i^{t*}, p_{sig,i}^{t*})$ can be also the optimal BDO solution for minimizing the objective function G over the feasibility space \mathcal{X} . This proves Theorem 1.

II. PROOF OF THEOREM 2

First, we prove that the optimal charge-discharge solution $\boldsymbol{x}_i^{t\dagger} = \boldsymbol{x}_i^{t*}$ holds for the i-th EV. It is clear that $\boldsymbol{d}_i^{t*} = \boldsymbol{c}^T \boldsymbol{x}_i^{t*} - \boldsymbol{p}_{sig,i}^{t*} + \boldsymbol{\alpha}_i^{t\dagger} \boldsymbol{\xi}_i^t - \boldsymbol{\alpha}_i^{t\dagger} \boldsymbol{\xi}_i^t$ stands. We denote $\tilde{\boldsymbol{p}}_{sig,i}^{t\dagger} = \boldsymbol{p}_{sig,i}^{t*} + \boldsymbol{\alpha}_i^{t\dagger} \boldsymbol{\xi}_i^t$. Then, we have $\boldsymbol{d}_i^{t*} = \boldsymbol{c}^T \boldsymbol{x}_i^{t*} - \tilde{\boldsymbol{p}}_{sig,i}^{t\dagger} + \boldsymbol{\alpha}_i^{t\dagger} \boldsymbol{\xi}_i^t$. As $\boldsymbol{d}_i^{t\dagger} \geqslant \boldsymbol{d}_i^{t*}$ and $\boldsymbol{y}_i^{t\dagger} = \boldsymbol{d}_i^{t\dagger}$ achieved at optimality, minimizing the objective function \boldsymbol{g}_i ensures $\boldsymbol{d}_i^{t\dagger} = \boldsymbol{d}_i^{t\dagger}$, where other two terms in \boldsymbol{g}_i can be held, i.e., $\boldsymbol{\mu}^t(\tilde{\boldsymbol{p}}_{sig,i}^{t\dagger} - \boldsymbol{\alpha}_i^t \boldsymbol{\xi}_i^t) =$

$$\mu^t \boldsymbol{p}_{sig,i}^{t*} \text{ and } \frac{\boldsymbol{\rho}}{2} || \sum_{j=1,j\neq i}^{N_E} \widetilde{\boldsymbol{p}}_{sig,j}^{t\dagger} + \widetilde{\boldsymbol{p}}_{sig,i}^{t\dagger} - \boldsymbol{p}_{ref}^t ||_2^2 = \frac{\boldsymbol{\rho}}{2} || \sum_{j=1,j\neq i}^{N_E} \boldsymbol{p}_{sig,j}^{t*} + \boldsymbol{p}_{sig,i}^{t*} - \boldsymbol{p}_{ref}^t ||_2^2 \approx 0 \text{ at convergence. Thus, we rewrite } \boldsymbol{d}_i^{t\dagger} = \boldsymbol{c}^T \boldsymbol{x}_i^{t*} - \widetilde{\boldsymbol{p}}_{sig,i}^{t\dagger} + \boldsymbol{\alpha}_i^{t\dagger} \boldsymbol{\xi}_i^t. \text{ This suggests that } \boldsymbol{x}_i^{t\dagger} = \boldsymbol{x}_i^{t*} \text{ holds with obfuscated } \widetilde{\boldsymbol{p}}_{sig,i}^{t\dagger} = \boldsymbol{p}_{sig,i}^{t*} + \boldsymbol{\alpha}_i^{t\dagger} \boldsymbol{\xi}_i^t \text{ for the proposed privacy-preserving BDO model.}$$

Second, we prove that \mathcal{M} is $r_{\varepsilon,i}$ -input-discriminative differentially locally private (ID-LDP) with respect to the local dataset of subproblem i during all iterations. Let the query output answer for the sub-problem i be $\mathcal{O}_i^t = \widetilde{p}_{sig,i}^t$, and we alternatively rewrite (A-1) in the definition of ε_i -LDP for the sub-problem i [1]:

$$\mathbb{P}_{\varepsilon}[\mathcal{M}_{i} = \mathcal{O}_{i}^{t} | \boldsymbol{x}_{i}^{t}] \leqslant \mathbb{P}_{\varepsilon}[\mathcal{M}_{i} = \mathcal{O}_{i}^{t} | \boldsymbol{x}_{i}^{t'}] e^{r_{\varepsilon, i}}, \tag{A-1}$$

for two $r_{\varepsilon,i}$ -indistinguishable charge-discharge solutions \boldsymbol{x}_i^t and $\boldsymbol{x}_i^{t'}$. For convenience, the query output \mathcal{O}_i^t of i-th EV for $\forall t \in \mathcal{T}$ with a random noise $\boldsymbol{\xi}_i^t$ can be written as $\mathcal{O}_i^t = \widetilde{\boldsymbol{p}}_{sig,i}^t = \boldsymbol{p}_{sig,i}^t + \boldsymbol{\alpha}_i^t \boldsymbol{\xi}_i^t$ where $\forall t \in \mathcal{T}$.

Therefore, the ratio of probabilities on two ε_i -indistinguishable charge-discharge solutions \boldsymbol{x}_i^t and $\boldsymbol{x}_i^{t'}$ can be bounded by

$$\begin{split} &\frac{\mathbb{P}_{\boldsymbol{\xi}}[\mathcal{M}_{i} = \mathcal{O}_{i}^{t}|\boldsymbol{x}_{i}^{t}]}{\mathbb{P}_{\boldsymbol{\xi}}[\mathcal{M}_{i} = \mathcal{O}_{i}^{t}|\boldsymbol{x}_{i}^{t}]} = \frac{\mathbb{P}_{\boldsymbol{\xi}}\left[\boldsymbol{p}_{sig,i}^{t} + \boldsymbol{\alpha}_{i}^{t}\boldsymbol{\xi}_{i}^{t} = \mathcal{O}_{i}^{t}|\boldsymbol{x}_{i}^{t}\right]}{\mathbb{P}_{\boldsymbol{\xi}}\left[\boldsymbol{p}_{sig,i}^{t} + \boldsymbol{\alpha}_{i}^{t}\boldsymbol{\xi}_{i}^{t} = \mathcal{O}_{i}^{t}|\boldsymbol{x}_{i}^{t'}\right]} \\ &= \frac{\mathbb{P}_{\boldsymbol{\xi}}\left[\boldsymbol{\alpha}_{i}^{t}\boldsymbol{\xi}_{i}^{t} = \mathcal{O}_{i}^{t} - \boldsymbol{p}_{sig,i}^{t}|\boldsymbol{x}_{i}^{t}\right]}{\mathbb{P}_{\boldsymbol{\xi}}\left[\boldsymbol{\alpha}_{i}^{t}\boldsymbol{\xi}_{i}^{t} = \mathcal{O}_{i}^{t} - \boldsymbol{p}_{sig,i}^{t}|\boldsymbol{x}_{i}^{t'}\right]} \stackrel{(i)}{=} \frac{\boldsymbol{\alpha}_{i}^{t}\exp\left\{\frac{r_{\varepsilon,i}\|\mathcal{O}_{i}^{t} - \boldsymbol{p}_{sig,i}^{t}\|_{1}}{\Delta_{\rho,i}}\right\}}{\boldsymbol{\alpha}_{i}^{t}\exp\left\{\frac{r_{\varepsilon,i}\|\mathcal{O}_{i}^{t} - \boldsymbol{p}_{sig,i}^{t}\|_{1}}{\Delta_{\rho,i}}\right\}} \\ &= \exp\left(\frac{r_{\varepsilon,i}\|\mathcal{O}_{i}^{t} - \boldsymbol{p}_{sig,i}^{t}\|_{1} - r_{\varepsilon,i}\|\mathcal{O}_{i}^{t} - \boldsymbol{p}_{sig,i}^{t}\|_{1}}{\Delta_{\rho,i}}\right) \end{split}$$

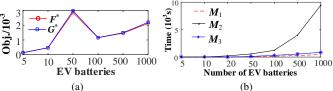


Fig. 1. (a) Optimal objective function values; (b) CPU time.

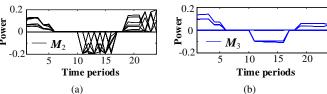


Fig. 2. Optimal charge-discharge power solution: (a) M_2 ; (b) M_3 .

$$\stackrel{(ii)}{\leqslant} \exp\left(\frac{r_{\varepsilon,i} \|\boldsymbol{p}_{sig,i}^{t} - \boldsymbol{p}_{sig,i}^{t'}\|_{1}}{\Delta_{\rho,i}}\right) \stackrel{(iii)}{\leqslant} \exp\left(\frac{r_{\varepsilon,i} \Delta_{\rho,i}}{\Delta_{\rho,i}}\right) = e^{r_{\varepsilon,i}},$$
(A-

where (i) comes from the definition of the probability density function of the Gaussian distribution. In (ii) step, it is followed by the inequality of norms, i.e., $|a|-|b|\leqslant |a-b|$ for any real-valued numbers a and b. For the (iii) step, $\|\boldsymbol{p}_{sig,i}^t-\boldsymbol{p}_{sig,i}^{t'}\|_1$ denotes the ℓ_1 -sensitivity on ρ -indistinguishable output datasets $\boldsymbol{p}_{sig,i}^t$ and $\boldsymbol{p}_{sig,i}^{t'}$ subject to $\|\boldsymbol{p}_{sig,i}^t-\boldsymbol{p}_{sig,i}^{t'}\|_1 \leqslant \Delta_{\rho,i}$.

Accordingly, it is clear that (A-1) holds based on (A-2), which proves this Theorem.

III. ADDITIONAL CASE STUDY FOR THEOREM 1

The computational performance of this proposed ADMM-based BDO approach by **Theorem 1** can be verified in this section. For brevity, three methods are compared: the LP-based approach in [2] (M_1) , and the MIQP-based BDO model solved using commercial solver MOSEK (M_2) for comparison with the proposed ADMMbased BDO method (M_3) . In Fig. 1(a), we plot the minimum objective function value F^st obtained from the benchmark M_2 and compare it to G^* obtained from the proposed M_3 for the case with the different numbers of EVs, i.e, 5, 20, 20, 50, 100, 500 and 1000. We observe that, indeed, $G^* \approx F^*$ in all cases. Moreover, Fig. 1(b) reports the computation time with respect to the numbers of EV batteries. M_1 incurs the least computational time because M_1 is free of binary variables, but it can result in infeasible solutions featuring simultaneous charging and discharging. And M_3 is superior to both M_2 with respect to computational time. In fact, for the case with $N_E = 1000$ EVs, M_3 converges to the optimal solution in 12.67% of the time taken by M_2 . To further demonstrate the numbers of charging/discharging switches in M_2 and M_3 , Figs. 2(a) and 2(b) present the specific optimal charge-discharge power solutions for the case with $N_E=10$ EVs. In Fig. 2(a), M_2 incurs many charging and discharging actions over 24 hours, while M_3 imposes few charging and discharging actions, as shown in Fig. 2(b). This is highly beneficial as charging/discharging switches degrade the remaining useful life of EV batteries. This case study showcases that an ADMM-based BDO approach established by Theorem 1 outperforms existing methods for solving BDO problems in terms of computational time and switching times.

REFERENCES

[1] C. Dwork, A. Roth *et al.*, "The algorithmic foundations of differential privacy," *Foundations and Trends in Theoretical Computer Science*, vol. 9, no. 3–4, pp. 211–407, 2014.