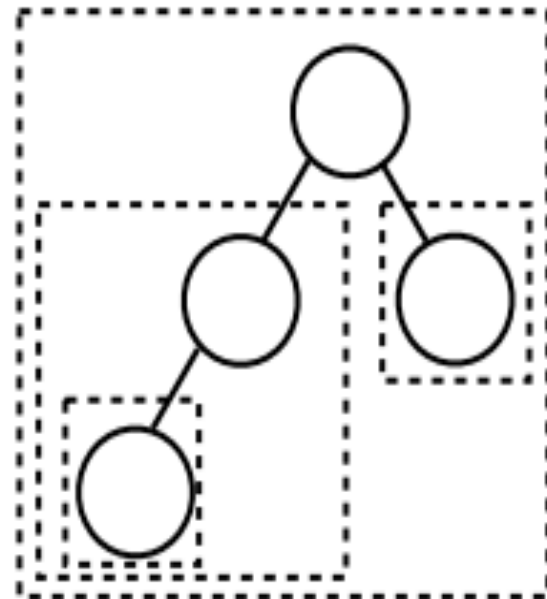


# Lecture 18-19

# Sub-trees

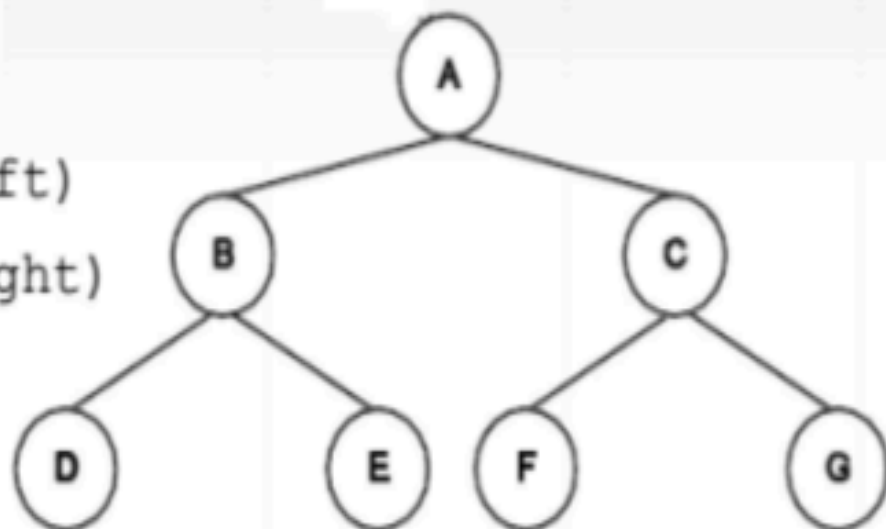
- Each node in a tree is the *root* of its own *sub-tree*.
- The gray boxes below show all possible sub-trees.



# BINARY TREE TRAVERSALS

# Pre-order traversal

```
preorder(node) {  
  if (node != null){  
    visit this node  
    preorder(node.left)  
    preorder(node.right)  
  }  
}
```



A. DBEAFCG

B. ABDECFCG

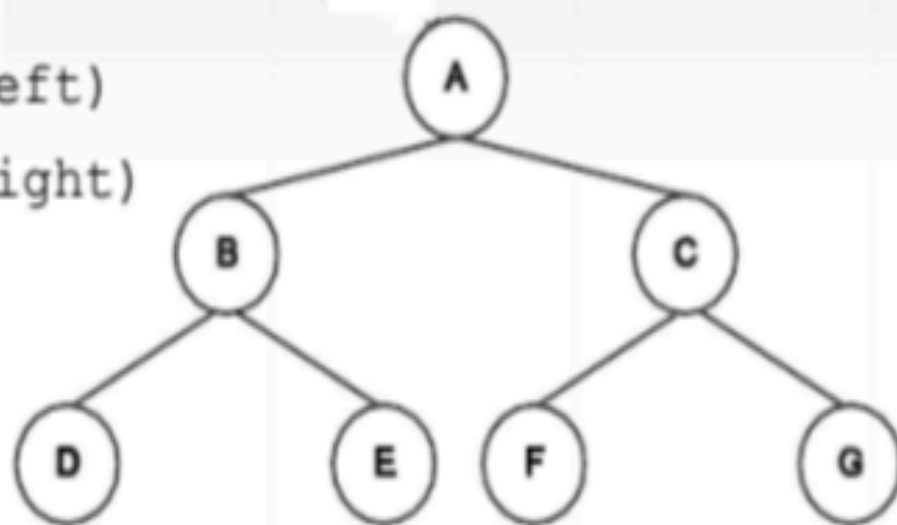
C. ABCDEFG

D. DEBFGCA

E. Other/none/more

# Post-order traversal

```
postorder(node) {  
  if (node != null) {  
    postorder(node.left)  
    postorder(node.right)  
    visit this node  
  }  
}
```



A. DBEAFCG

B. ABDECFCG

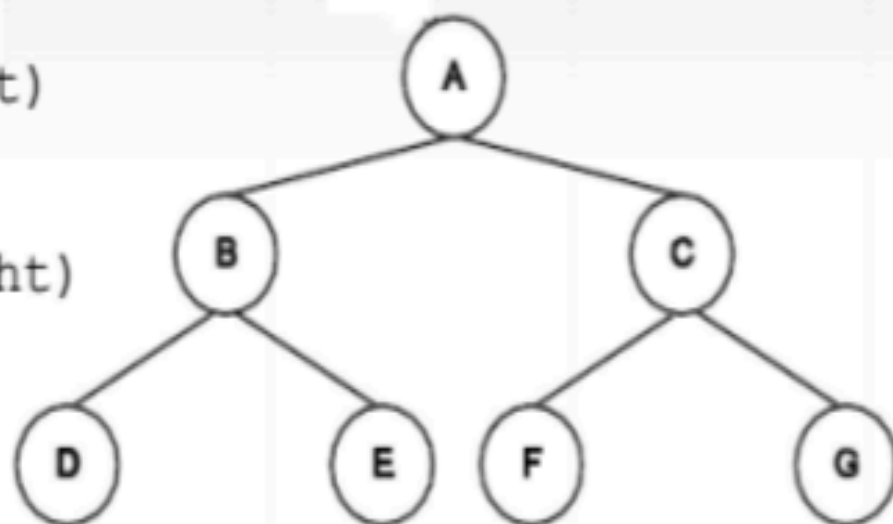
C. ABCDEFG

D. DEBFGCA

E. Other/none/more

# In-order traversal

```
inorder(node) {  
  if (node != null){  
    inorder(node.left)  
    visit this node  
    inorder(node.right)  
  }  
}
```



A. DBEAFCG

B. ABDECFCG

C. ABCDEFG

D. DEBFGCA

E. Other/none/more

# Could you do it?

- Give a tree with at least 3 nodes (all nodes must have different keys) such that both its in-order read and its pre-order read are the same, or prove that there is no such tree.
- Give a tree with at least 3 nodes (all nodes must have different keys) such that both its pre-order read and its post-order read are the same, or prove that there is no such tree.

# BINARY SEARCH TREES



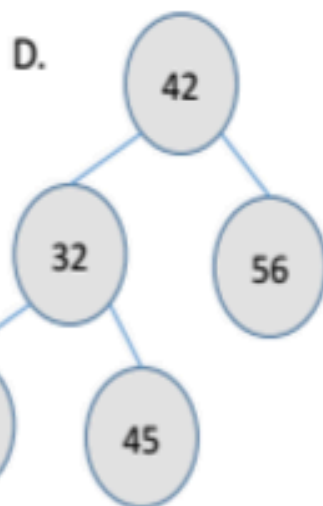
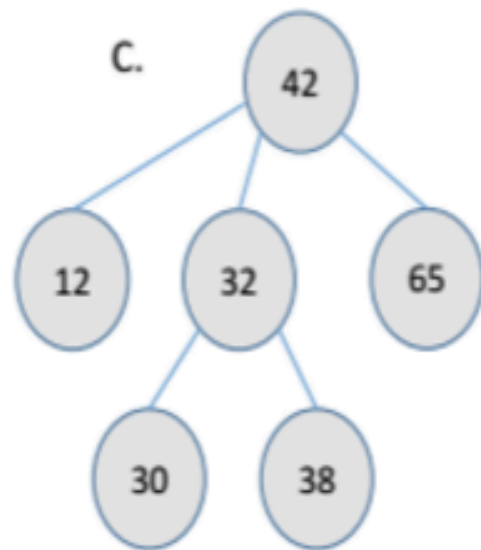
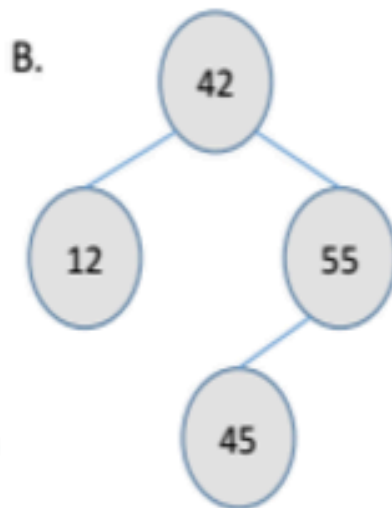
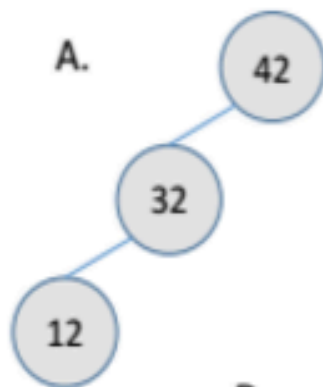
# Heaps are not enough!

- Heaps offer fast access to the largest element in a collection.
  - This is most useful in a priority queue.
- However, finding an arbitrary element is still slow --  $O(n)$  time.
- We may want to sacrifice efficiency of getting the largest element in exchange for increased efficiency to access any *arbitrary* element.

# Binary SEARCH tree

- A binary search tree (BST) is a binary-tree based data structure that offers  $O(\log n)$  **average-case** time costs for:
  - Add (element)
  - Find (element)
  - Remove (element)
  - findLargest/removeLargest (element)

# Which of the following is/are a binary search tree?



E. More than one of these

# Binary SEARCH tree (BST)

- BST property? For **each** node  $n$ 
  - A: all nodes in left subtree of  $n$  are “less than” node  $n$ , and all nodes in the right subtree of  $n$  are “greater than node  $n$ .”
  - B: It must be complete
  - C: all nodes in left subtree of  $n$  are “greater than” node  $n$ , and all nodes in the right subtree of  $n$  are “less than node  $n$ .”
  - D: answer A + tree must be complete.
  - E: answer C + tree must be complete

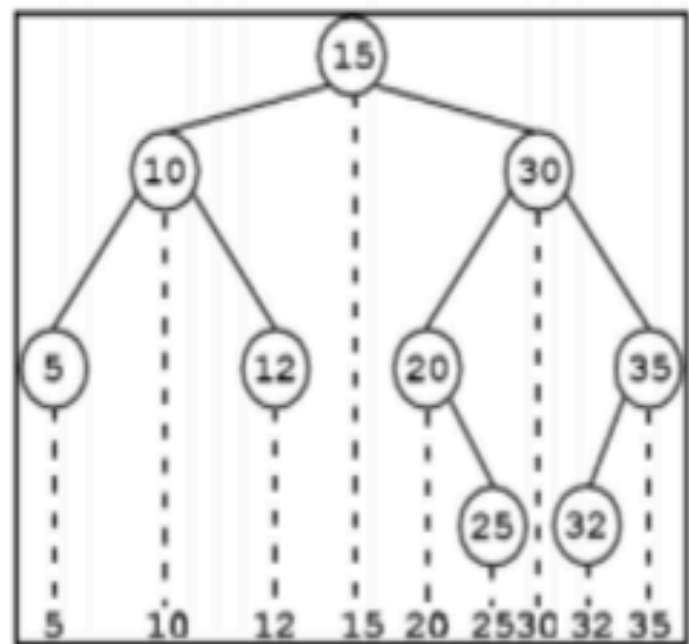
# Binary Search Tree (BST)

FACT:

- The “in-order” traversal method, when applied to a BST, gives sorted order

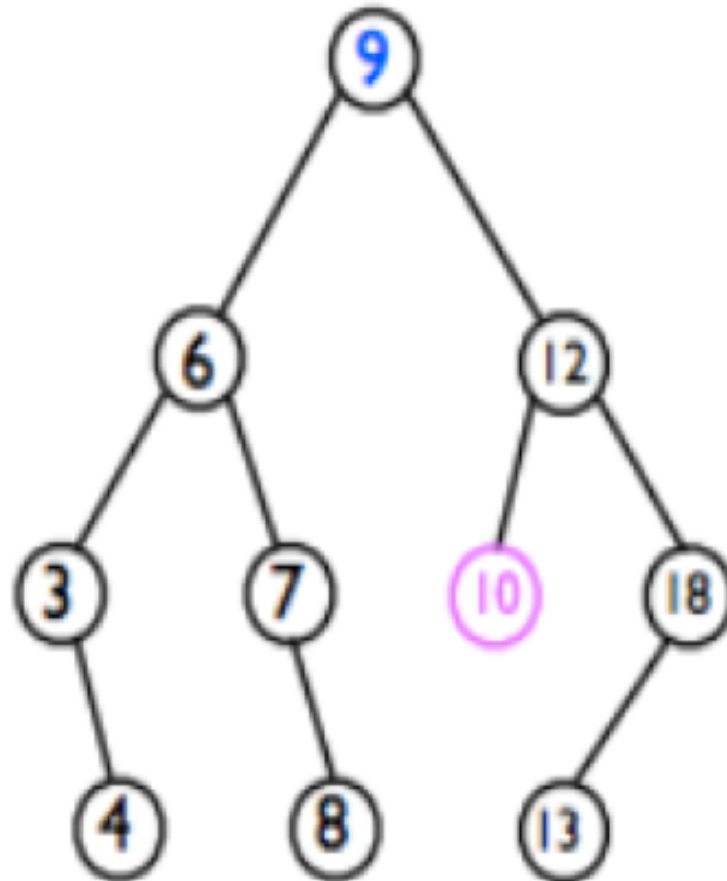
FACT:

- Easy to find things: just recursively check if you should go left or right based on  $>$  or  $<$



# Where to find a min element?

- In a given a binary tree?

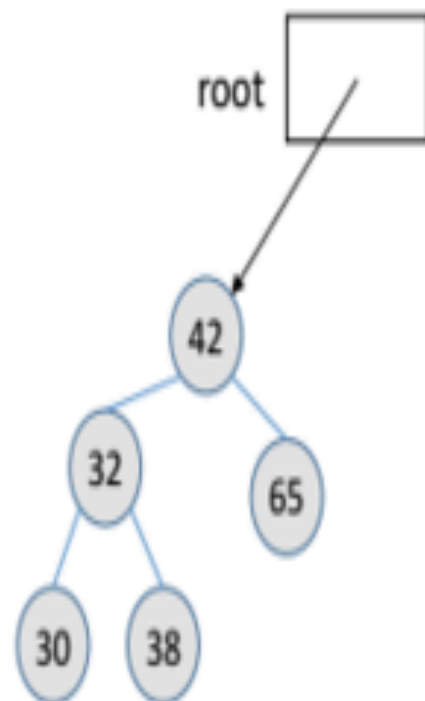


# BST IMPLEMENTATION

# The BST and BSTNode Classes

```
public class BST<E extends Comparable<? super E>>
{
    /** Inner class for the BSTNode */
    private class BSTNode {
        protected BSTNode leftChild;
        protected BSTNode rightChild;
        protected E element;

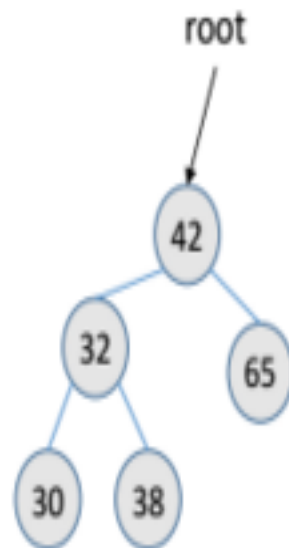
        public BSTNode(E elem)
        {
            element = elem;
        }
    }
    protected BSTNode root;
```





# BST Contains: Let's write it!

```
// Return true if toFind is in the BST  
public boolean contains(E toFind) {
```

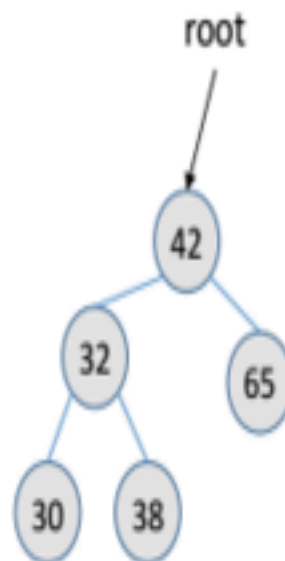


contains(32)?

# BST Contains: Let's write it!

```
// Return true if toFind is in the BST
public boolean contains(E toFind) {
    //RECURSION!
    return containsHelper(root, toFind);
}

// This recursive method returns true if toFind is in the
// tree rooted at currRoot, and false otherwise
private boolean containsHelper(BSTNode currRoot, E toFind)
{
    // To write!
}
```



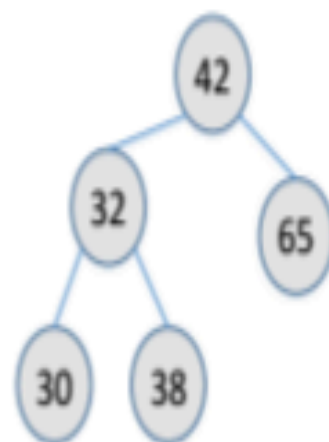
contains(32)?

# BST Contains: Let's write it!

```
// Return true if toFind is in the BST rooted at currRoot,  
// false otherwise  
boolean contains(BSTNode currRoot, E toFind) {
```

Base case(s): When do we know we are done?

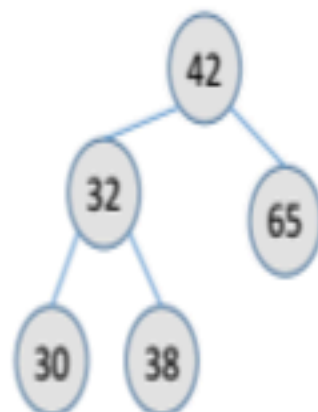
- A. toFind is less than currRoot's element
- B. toFind is greater than currRoot's element
- C. toFind is equal to currRoot's element
- D. currRoot is null
- E. More than one of these



# BST Contains: Let's write it!

```
// Return true if toFind is in the BST rooted at currRoot,  
// false otherwise  
boolean contains(BSTNode currRoot, E toFind) {
```

Base case 1: (sub)tree is empty, so we know currRoot is not in it



# BST Contains: Let's write it!

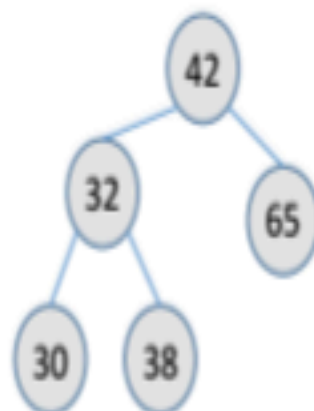
```
// Return true if toFind is in the BST rooted at currRoot,  
// false otherwise
```

```
boolean contains(BSTNode currRoot, E toFind) {  
    if (currRoot == null) return false;
```

Base case 2: Element is found

We will roll this in with our recursive step

So what is our recursive step...?



contains(32)?

contains(65)?

contains(42)?

contains(40)?

# BST Contains: Let's write it!

```
// Return true if toFind is in the BST rooted at currRoot,  
// false otherwise
```

```
boolean contains(BSTNode currRoot, E toFind) {  
    if (currRoot == null) return false;
```

Base case 2: Element is found

We will roll this in with our recursive step

So what is our recursive step...?



contains(32)?

contains(65)?

contains(42)?

contains(40)?

# BST Contains: Let's write it!

```
// Return true if toFind is in the BST rooted at currRoot,  
// false otherwise
```

```
boolean contains(BSTNode currRoot, E toFind) {  
    if (currRoot == null) return false;  
    if ( _____ )  
        return contains( _____, toFind );  
    else if ( _____ )  
        return contains( _____, toFind );  
    else  
        return _____;
```

Recursive step and base case 2: How do you know which way to go? Fill in the blanks above. Hint: use compareTo. If you need another hint, check out the next slide.



contains(32)?  
contains(65)?  
contains(42)?  
contains(40)?

```
// Return true if toFind is in the BST rooted at root,  
// false otherwise  
boolean contains(BSTNode currRoot, E toFind) {  
    if ( currRoot == null ) return false;  
    if ( toFind.compareTo(currRoot.getElement()) < 0 )  
        return _____1_____  
    else if ( toFind.compareTo(currRoot.getElement()) > 0 )  
        return _____2_____  
    else  
        return _____3_____;
```



contains(32)?  
contains(65)?  
contains(42)?  
contains(40)?



```
// Return true if toFind is in the BST rooted at root,  
// false otherwise  
boolean contains(BSTNode currRoot, E toFind) {  
    if ( currRoot == null ) return false;  
    if ( toFind.compareTo(currRoot.getElement()) < 0 )  
        return contains(currRoot.getLeft(), toFind);  
    else if (toFind.compareTo(currRoot.getElement()) > 0 )  
        return contains(currRoot.getRight(), toFind);  
    else  
        return true;  
}
```



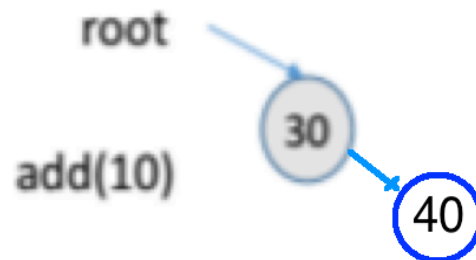
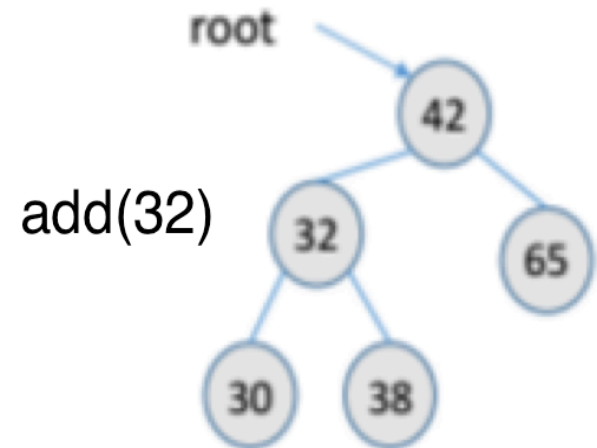
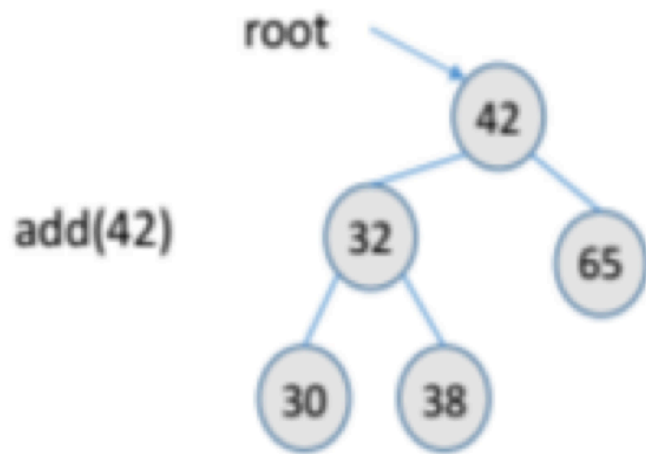
contains(32)?  
contains(65)?  
contains(42)?  
contains(40)?

# Plan

- Insert
- Delete
- Running time

# BST Add: With recursion!

Consider the following:

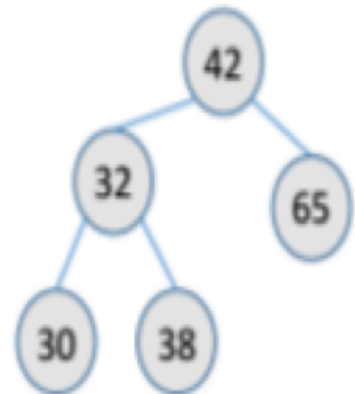


# BST Add: Recursively

```
boolean add( E toAdd ) {  
    if (root == null) {  
        root = new BSTNode(toAdd);  
        return true;  
    }  
    return addHelper( root, toAdd );  
}  
  
boolean addHelper( BSTNode currRoot, E toAdd )  
{  
    ...  
}
```

Which of these is/are a base case for addHelper?

- A. currRoot is null
- B. currRoot's element is equal to toAdd
- C. Both A & B
- D. Neither of these

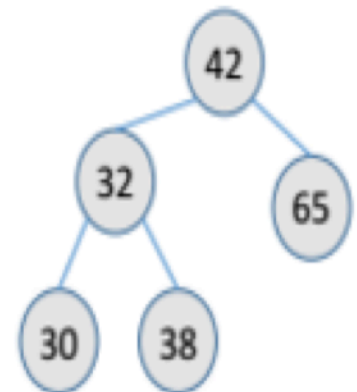


# BST Add: Recursively

```
boolean add( E toAdd ) {  
    if (root == null) {  
        root = new BSTNode(toAdd);  
        return true;  
    }  
    return addHelper( root, toAdd );  
}
```

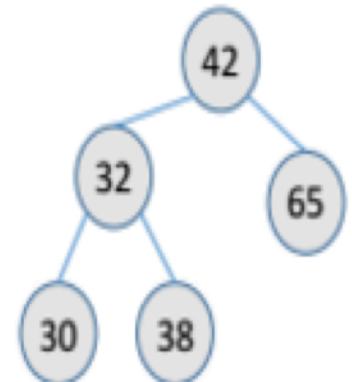
```
boolean addHelper( BSTNode currRoot, E toAdd )  
{  
    int compare = toAdd.compareTo(currRoot.getElement());  
    if (compare == 0) {  
        return ;  
    }  
}
```

Which of these is/are a base case for addHelper?  
currRoot's element is equal to toAdd



# BST Add: Recursively

```
boolean add( E toAdd ) {  
    if (root == null) {  
        root = new BSTNode(toAdd);  
        return true;  
    }  
    return addHelper( root, toAdd );  
}  
  
boolean addHelper( BSTNode currRoot, E toAdd )  
{  
    int compare = toAdd.compareTo(currRoot.getElement());  
    if (compare == 0) {  
        return false;  
    }  
    // Finish the code...  
}
```



Which of these is/are a base case for addHelper?  
currRoot's element is equal to toAdd

# BST Add: Recursively

```
void addHelper( BSTNode currRoot, E toAdd )
{
    int value = toAdd.compareTo( currRoot.getElement() );
    if (value == 0) return false;
    if ( value < 0 ) {
        if ( currRoot.getLeftChild() == null ) {
            currRoot.setLeftChild(new BSTNode( toAdd ));
        }
        else {
            addHelper( currRoot.getLeftChild(), toAdd );
        }
    }
    else { // ( value > 0 )
        // Repeat for other side
    }
    return true;
}
```

# Remove a node

- Real deletion (blackboard)
- **Lazy** deletion.



# Duplicate keys

- Allow them and be consistent with the rule
- Node is a linked list. All duplicates are linked.

COMPLEXITY

What is the BEST CASE cost for doing find() in BST (tightest Big-O, on this and future questions)?

- A.  $O(1)$
- B.  $O(\log n)$
- C.  $O(n)$
- D.  $O(n \log n)$
- E.  $O(n^2)$

What is the WORST CASE cost for doing find()  
in a BST?

- A.  $O(1)$
- B.  $O(\log n)$
- C.  $O(n)$
- D.  $O(n \log n)$
- E.  $O(n^2)$

# Balance

- The #1 issue to remember with BSTs is that they are great when balanced ( $O(\log n)$  operations), and horrible when unbalanced ( $O(n)$  operations)
- Balance depends on order of insert/delete of elements
- Over the years, people have devised many ways of making sure BSTs stay balanced no matter what order the elements are inserted.
- We won't talk about these ways here, but stay tuned for CSE 100...

# Fun Questions

- Find k-th minimum element in a BST.
- Given a binary tree, check whether it's a binary search tree or not.