

## (1)SC\_Halt:

## Machine::Run()

```
void Machine::Run() {
    Instruction *instr = new Instruction; // storage for decoded instruction
    if (debug->IsEnabled('m')) {         //debug.cc 如果m有在Debug message裡
        cout << "Starting program in thread: " << kernel->currentThread->getName();
        cout << ", at time: " << kernel->stats->totalTicks << "\n";
    }
    kernel->interrupt->setStatus(UserMode); //user program執行 使用usermode interrupt.h IdleMode, SystemMode, UserMode
    for (;;) {
        DEBUG(dbgTraCode, "In Machine::Run(), into OneInstruction "           //debug.h  dbgTraCode = 'c' 如果這個flag enable時候 就印出後面的訊息
            << "==" Tick " << kernel->stats->totalTicks << " ==");
        OneInstruction(instr);                                                 //執行解碼完的instruction
        DEBUG(dbgTraCode, "In Machine::Run(), return from OneInstruction "
            << "==" Tick " << kernel->stats->totalTicks << " ==");

        DEBUG(dbgTraCode, "In Machine::Run(), into OneTick "                 //debug.h  dbgTraCode = 'c' 如果這個flag enable時候 就印出後面的訊息
            << "==" Tick " << kernel->stats->totalTicks << " ==");
        kernel->interrupt->OneTick();                                           //執行OneTick
        DEBUG(dbgTraCode, "In Machine::Run(), return from OneTick "
            << "==" Tick " << kernel->stats->totalTicks << " ==");
        if (singleStep && (runUntilTime <= kernel->stats->totalTicks))
            Debugger();
    }
}
```

把解碼後的 instruction 如 ADD, BEQ 丟進 OneInstruction(instr)

## 做運算

## Machine::OneInstruction()

模擬 CPU 執行各個指令, 其中還有 Exception 的 opcode, 遇到異常會

## 丟出 RaiseException 訊息

## Machine:RaiseException()

```
void
Machine::RaiseException(ExceptionType which, int badVAddr)
{
    DEBUG(dbgMach, "Exception: " << exceptionNames[which]);
    registers[BadVAddrReg] = badVAddr;
    DelayedLoad(0, 0);           // finish anything in progress
    kernel->interrupt->setStatus(SystemMode); //轉成kernel mode
    ExceptionHandler(which);     // interrupts are enabled at this point
    kernel->interrupt->setStatus(UserMode); //轉回user mode
}
```

當發生 Exception, 印出訊息, 進入 Kernel Mode, 解決完之後跳回 User Mode

## ExceptionHandler()

```
int type = kernel->machine->ReadRegister(2);
int status, exit, threadID, programID, fileID, numChar;
DEBUG(dbgSys, "Received Exception " << which << " type: " << type << "\n");
DEBUG(dbgTraCode, "In ExceptionHandler(), Received Exception " << which << " type: " <<
switch (which) {
    case SyscallException: //看是哪個System call
        switch (type) {
            case SC_Halt:
                DEBUG(dbgSys, "Shutdown, initiated by user program.\n");
                SysHalt();
                cout << "in exception\n";
                ASSERTNOTREACHED();
                break;
        }
}
```

System call 的值在 Reg2, 以 type 儲存起來, 接著根據這個 type 值看是哪種 system call, 此處是 SC\_Halt.

## SysHalt()

進入到 **ksyscall.h**, 系統的 **system call** 都寫在這了

```

>machine->ReadRegister(2);
threadID, programID, fileID, numChar;
Received Exception " << which << " type: " << type << "
"In ExceptionHandler(), Received Exception " << whic

void SysHalt()
{
    kernel->interrupt->Halt();
}

```

此實作的 **system call** 寫在 **interrupt.cc** 的 **Halt()**裡了

## Halt()

```

void Interrupt::Halt() {
    cout << "Machine halting!\n\n";
    cout << "This is halt\n";
    kernel->stats->Print();
    delete kernel; // Never returns.
}

```

系統 **print** 出訊息後,把整個 **kernel** 結束掉,程式就停止了

## (2)SC\_Create

### ExceptionHandler()

```

case SC_Create:
    val = kernel->machine->ReadRegister(4);
    {
        char *filename = &(kernel->machine->mainMemory[val]);
        // cout << filename << endl;
        status = SysCreate(filename);
        kernel->machine->WriteRegister(2, (int)status);
    }
    kernel->machine->WriteRegister(PrevPCReg, kernel->machine->ReadRegister(PCReg));
    kernel->machine->WriteRegister(PCReg, kernel->machine->ReadRegister(PCReg) + 4);
    kernel->machine->WriteRegister(NextPCReg, kernel->machine->ReadRegister(PCReg) + 4);
    return;
    ASSERTNOTREACHED();
    break;

```

把要創立的 **file** 名字放入到 **val** 變數(原先儲存在 **Reg4**),**SysCreate** 詳細在 **ksyscall.h**,並且把 **status** 更新到 **Reg2**(system call 的值),最後更新 **program counter** 的值.

## SysCreate()

```

int SysCreate(char *filename)
{
    // return value
    // 1: success
    // 0: failed
    return kernel->fileSystem->Create(filename);
}

```

此 **function** 在 **ksyscall.h**,System call 的實作在 **fileSYS.h**

## FileSystem::Create()

```

bool Create(char *name) {
    int fileDescriptor = OpenForWrite(name); //在lib的sysdep.cc

    if (fileDescriptor == -1) return FALSE;
    Close(fileDescriptor);
    return TRUE;
}

```

再往下追蹤 **OpenForWrite** 可發現在 **lib** 的 **sysdep.cc**,可以看到會呼叫 **Unix** 系統的 **open()** system call,也就是 **stub** 檔案的來由.最後 **Create()**,根據回傳的 **fileDescriptor** 建立檔案,成功為 **1**,失敗為 **-1**

### (3)SC\_PrintInt

**ExceptionHandler():**

```

case SC_PrintInt:
    DEBUG(dbgSys, "Print Int\n");
    val = kernel->machine->ReadRegister(4);
    DEBUG(dbgTraCode, "In ExceptionHandler(), into SysPrintInt, " << kernel->stats->totalTicks);
    SysPrintInt(val);
    DEBUG(dbgTraCode, "In ExceptionHandler(), return from SysPrintInt, " << kernel->stats->totalTicks);
    // Set Program Counter
    kernel->machine->WriteRegister(PrevPCReg, kernel->machine->ReadRegister(PCReg));
    kernel->machine->WriteRegister(PCReg, kernel->machine->ReadRegister(PCReg) + 4);
    kernel->machine->WriteRegister(NextPCReg, kernel->machine->ReadRegister(PCReg) + 4);
    return;
    ASSERTNOTREACHED();
    break;

```

一樣會判斷是甚麼樣的 system call 類型,此處是 **PrintInt**,讀出傳入的參數進入 **SysPrintInt()**

**SysPrintInt():**

進到 **ksyscall.h** 看到必須進入 **synchConsoleOut.cc**

```
void SysPrintInt(int val)
{
    DEBUG(dbgTraCode, "In ksyscall.h:SysPrintInt, into synchConsoleOut->PutInt, " << kernel->stats->totalTicks);
    kernel->synchConsoleOut->PutInt(val);
    DEBUG(dbgTraCode, "In ksyscall.h:SysPrintInt, return from synchConsoleOut->PutInt, " << kernel->stats->totalTicks);
}
```

**SynchConsoleOutput::PutInt() &&**

**SynchConsoleOutput::PutChar()**

```
void
SynchConsoleOutput::PutInt(int value)
{
    char str[15];
    int idx=0;
    //sprintf(str, "%d\n", value); the true one
    sprintf(str, "%d\n", value); //simply for trace code
    lock->Acquire();
    do{
        DEBUG(dbgTraCode, "In SynchConsoleOutput::PutChar, into consoleOutput->PutChar, " << kernel->stats->totalTicks);
        consoleOutput->PutChar(str[idx]);
        DEBUG(dbgTraCode, "In SynchConsoleOutput::PutChar, return from consoleOutput->PutChar, " << kernel->stats->totalTicks);
        idx++;

        DEBUG(dbgTraCode, "In SynchConsoleOutput::PutChar, into waitFor->P(), " << kernel->stats->totalTicks);
        waitFor->P();
        DEBUG(dbgTraCode, "In SynchConsoleOutput::PutChar, return from waitFor->P(), " << kernel->stats->totalTicks);
    } while (str[idx] != '\0');
    lock->Release();
}
```

```
void
SynchConsoleOutput::PutChar(char ch)
{
    lock->Acquire();
    consoleOutput->PutChar(ch); //hardware display
    waitFor->P();
    lock->Release();
}
```

使用 **lock**, 只有獲得鎖的 **process** 可以進入同步區, 其他 **process** 必須等待,

將輸入的整數轉成 **string** 並在最後加入換行以及終止字元,

**consoleOutput->PutChar()** 主要是控制硬體輸出在螢幕上,

**waitFor->P()** 讓後面還沒做完的字元先等待

**ConsoleOutput::PutChar():**

```
void  
ConsoleOutput::PutChar(char ch)  
{  
    ASSERT(putBusy == FALSE);  
    WriteFile(writeFileNo, &ch, sizeof(char));  
    putBusy = TRUE;  
    kernel->interrupt->Schedule(this, ConsoleTime, ConsoleWriteInt);  
}
```

寫入 **file**, 當寫入時候 **flag** 為 **True**, 此時不能處理其他事情.

**Interrupt::Schedule()**

```

//
void Interrupt::Schedule(CallBackObj *toCall, int fromNow, IntType type) {
    int when = kernel->stats->totalTicks + fromNow;
    // arg1 is the object to call when the interrupt occurs
    // arg2 is when (in simulated time) the interrupt is to occur
    // arg3 is the hardware device that generated the interrupt
    PendingInterrupt *toOccur = new PendingInterrupt(toCall, when, type);
    //Initialize a hardware device interrupt that is to be scheduled
    // to occur in the near future.
    DEBUG(dbgInt, "Scheduling interrupt handler the " << intTypeNames[type] << " at time =
    ASSERT(fromNow > 0);

    pending->Insert(toOccur);
}

```

在 **Interrupt.cc** 底下, **toCall** 是 **interrupt** 執行的對象, **when** 是指 **interrupt** 發生的時間, **type** 是指產生 **interrupt** 的硬體設備, 最後把此 **interrupt** 放入 **pending queue** 裡。

## Machine::Run()

**OneInstrucion** 會把解碼好的 **instruction** 放入 **MIP** 模擬 **CPU** 執行指令

## Interrupt::OneTick()



```

void Interrupt::OneTick() {
    MachineStatus oldStatus = status;
    Statistics *stats = kernel->stats;

    // advance simulated time
    if (status == SystemMode) {
        stats->totalTicks += SystemTick;
        stats->systemTicks += SystemTick;
    } else {
        stats->totalTicks += UserTick;
        stats->userTicks += UserTick;
    }
    DEBUG(dbgInt, "== Tick " << stats->totalTicks << " ==");

    // check any pending interrupts are now ready to fire
    ChangeLevel(IntOn, IntOff); // first, turn off interrupts
                                // (interrupt handlers run with
                                // interrupts disabled)
    CheckIfDue(FALSE);          // check for pending interrupts
    ChangeLevel(IntOff, IntOn); // re-enable interrupts
    if (yieldOnReturn) {        // if the timer device handler asked
                                // for a context switch, ok to do it now
        yieldOnReturn = FALSE;
        status = SystemMode; // yield is a kernel routine
        kernel->currentThread->Yield(); // Relinquish the CPU if any
                                // other thread is runnable
        status = oldStatus;
    }
}

```

目的是要模擬系統往前一個時刻

檢查是否有等待中斷：程式碼會關閉中斷（**turn off interrupts**），然後檢查是否有等待的中斷需要處理。如果有，就會開啟中斷（**re-enable interrupts**）以處理中斷。

如果當前的 **Thread** 用完了 **time slice**,kernel 會釋放現在的 **Thread** 並調度新的 **Thread**

**Interrupt::CheckIfDue()**

檢查所有 **pending queue** 裡的 **interrupt** 是否全部解決了,解決完 **return True**.

**ConsoleOutput::CallBack()**

當下一個字元可以輸出到 **Monitor** 上了時候使用這個 **function**

**SynchConsoleOutput::CallBack()**

如果可以安全的發送下一個字元(**semaphore on**),調用 **interrupt**,並送到 **monitor**

**PartII:**

**Syscall.h:**

- 先到 **syscall.h** 把 **#define SC\_Open 6** 等等的註解拿掉

**start.S**

**user program call Open()**的 **API** 時會發出 **system call** 給 **kernel(SC\_Open)**

重複做 **4** 次



```

case SC_Open:
    DEBUG(dbgSys, "File Open.\n");
    val = kernel->machine->ReadRegister(4); //arg1
    {
        char *filename = &(kernel->machine->mainMemory[val]);
        DEBUG(dbgSys, "File name : "<<filename<<"\n");
        // cout << filename << endl;
        status = SysOpen(filename);
        kernel->machine->WriteRegister(2, (int)status);
    }
    kernel->machine->WriteRegister(PrevPCReg, kernel->machine->ReadRegister(PCReg));
    kernel->machine->WriteRegister(PCReg, kernel->machine->ReadRegister(PCReg) + 4);
    kernel->machine->WriteRegister(NextPCReg, kernel->machine->ReadRegister(PCReg) + 4);
    return;
    ASSERTNOTREACHED();
    break;
case SC_Write:
    DEBUG(dbgSys, "File Writing...\n");
    val = kernel->machine->ReadRegister(4); //arg1
    numChar = kernel->machine->ReadRegister(5); //arg2
    .
    fileID = kernel->machine->ReadRegister(6); //arg3
    DEBUG(dbgSys, "file ID:"<<fileID<<"\n");
    {
        char *buffer = &(kernel->machine->mainMemory[val]);
        DEBUG(dbgSys, "Buffer:"<<buffer<<"\n");
        // cout << filename << endl;
        //numChar,fileID在函數先定義好了
        status = SysWrite(buffer,numChar,fileID);
        kernel->machine->WriteRegister(2, (int)status);
    }
    kernel->machine->WriteRegister(PrevPCReg, kernel->machine->ReadRegister(PCReg));
    kernel->machine->WriteRegister(PCReg, kernel->machine->ReadRegister(PCReg) + 4);
    kernel->machine->WriteRegister(NextPCReg, kernel->machine->ReadRegister(PCReg) + 4);
    return;
    ASSERTNOTREACHED();
    break;

```

```

case SC_Read:
    DEBUG(dbgSys, "File Reading...\n");
    val = kernel->machine->ReadRegister(4); //arg1
    numChar = kernel->machine->ReadRegister(5); //arg2

    fileID = kernel->machine->ReadRegister(6); //arg3
    DEBUG(dbgSys, "file ID:"<<fileID<<"\n");
    {
        char *buffer = &(kernel->machine->mainMemory[val]);
        DEBUG(dbgSys, "Buffer:"<<buffer<<"\n");
        // cout << filename << endl;
        //numChar,fileID在函數先定義好了
        status = SysRead(buffer,numChar,fileID);
        kernel->machine->WriteRegister(2, (int)status);
    }
    kernel->machine->WriteRegister(PrevPCReg, kernel->machine->ReadRegister(PCReg));
    kernel->machine->WriteRegister(PCReg, kernel->machine->ReadRegister(PCReg) + 4);
    kernel->machine->WriteRegister(NextPCReg, kernel->machine->ReadRegister(PCReg) + 4);
    return;
    ASSERTNOTREACHED();
    break;
case SC_Close:
    DEBUG(dbgSys, "File Closing...\n");
    fileID = kernel->machine->ReadRegister(4); //arg1
    DEBUG(dbgSys, "file ID:"<<fileID<<"\n");

    status = SysClose(fileID);
    DEBUG(dbgSys, "status:"<<status<<"\n");
    kernel->machine->WriteRegister(2, (int)status);
    kernel->machine->WriteRegister(PrevPCReg, kernel->machine->ReadRegister(PCReg));
    kernel->machine->WriteRegister(PCReg, kernel->machine->ReadRegister(PCReg) + 4);
    kernel->machine->WriteRegister(NextPCReg, kernel->machine->ReadRegister(PCReg) + 4);
    return;
    ASSERTNOTREACHED();
    break;

```

我們根據 **function** 傳入的參數, **arg1,arg2,arg3**, 去接收對應的值, 如 **fileID,numChar**.

```

像是 val = kernel->machine->ReadRegister(4);

char *buffer = &(kernel->machine->mainMemory[val]);

```

這兩行會去 **memory** 把 **buffer** 的起始位置抓出來

## ksyscall.h

負責 **system call**, 在本次作業主要針對檔案做操作, 實作細節在

fileSYS.h.

## fileSYS.h

```
int ReadFile(char *buffer, int size, OpenFileId id) {
    if(size<=0) return -1;
    Read(id,buffer,size);
    return size;
}

"File Closing...\n");
l->machine->ReadRegister(4); //arg1
"file ID:<<fileID<<"\n");
```

大部分跟上圖的 ReadFile 一樣撰寫邏輯

其中 Read()在 sysdep.c 檔裡.

進去檔案可看到是 Unix 的 read() system call.

## 成果

```
在 Received Exception 1 type: 100
(t
>| Message received.

| Passed! ^_^
i| Machine halting!

Re This is halt
re Ticks: total 815, idle 0, system 120, user 695
| Disk I/O: reads 0, writes 0
| Console I/O: reads 0, writes 0
| Paging: faults 0
e | Network I/O: packets received 0, sent 0
ac [os23s71@localhost test]$
```

What difficulties did you encounter when implementing this assignment?

蠻開心可以看到以前學過的作業系統以及計算機組織,在實際的程式裡出現,過程有一些函式觀念還是比較模糊,相信之後的學習可以幫助我釐清觀念.