

**CZ4042 CE/CZ4042: Neural Networks and Deep Learning**

*Assignment 1*

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# 1. Part A: Classification Problem

## 1.1 Introduction

Part A aims at building a feed-forward which 3 to 4 hidden layers neural networks to classify the Cardiotocography dataset containing measurements of fetal heart rate (FHR) and uterine contraction (UC) features on 2126 cardiotocograms classified by expert obstetricians and plot the model training result in regard of classification accuracy. Each record contains a feature space of 21 and 2 class labels. We will only use the NSP label for the scope of the assignment

The cardiotocograms were classified by three expert obstetricians and a consensus classification label with respect to a morphologic pattern and to a fetal state (N denotes Normal, S denotes Suspect and P denotes Pathologic) was assigned to each of the,. The aim is to predict the N, S and P class labels in the test dataset after training the neural network on the training dataset.

## 1.2. Methods

### 1.2.1. Normalization of Inputs



By observing the sample data set, we can note that there are relatively huge variations between features that might affect the training result of the model. For example: the mode, mean and median fields can reach over 100 while fields like AC and UC are in the range of [0, 1e-3].



To eliminate the variations between fields to prevent a few features from having a dominant effect on training, we adopted min-max normalization technique such that all the input features lies in [0,1].

### 1.2.2. Split Training and Testing Data

We utilized the built in function ‘train\_test\_split’ from sklearn to randomly split the entire sample into training set and testing set with size ratio of 70:30. The function ‘train\_test\_split’ will split the data randomly by specifying the ‘random\_state’ parameter. The split of the same sample with the same ‘random\_state’ will always result in the same split, thus ensuring the consistency of the training result.



The split result in a training set with size 1488 and testing set with size 638.

## 1.3. Experiments and Results

### 1.3.1. Question 1.

For this question, we will need to build a model that fulfils the following requirements:

1. The network is a feed-forward neural network with an input layer, one hidden layer of 10 neurons with ReLU activation function and one softmax layer.
2. The learning rate α = 0.01
3. L2 regularization with wight decay parameter = 1e-7
4. Batch gradient descent with batch size = 32
5. Scaling of features (as we mentioned above)

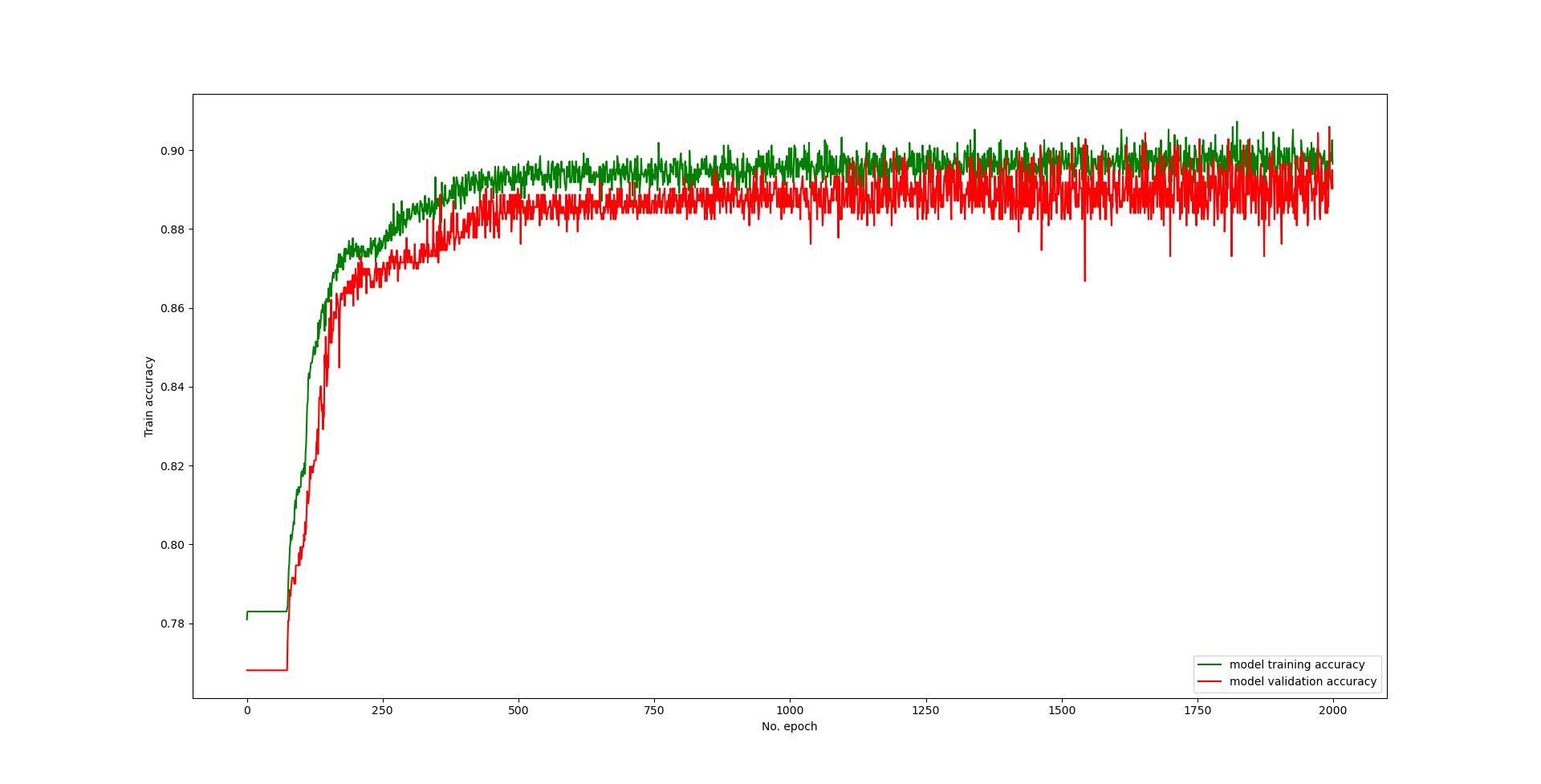
We implemented the following method to build the required model:



The model is composed of 2 layers, the first layer consists of 10 neurons with ReLU activation function and L2 regularization with weight decay parameter 𝛽 = 10−6. The second layer and also the output layer has softmax activation function. The optimizer adopts the built-in SGD optimizer with learning rate equal to 0.01.

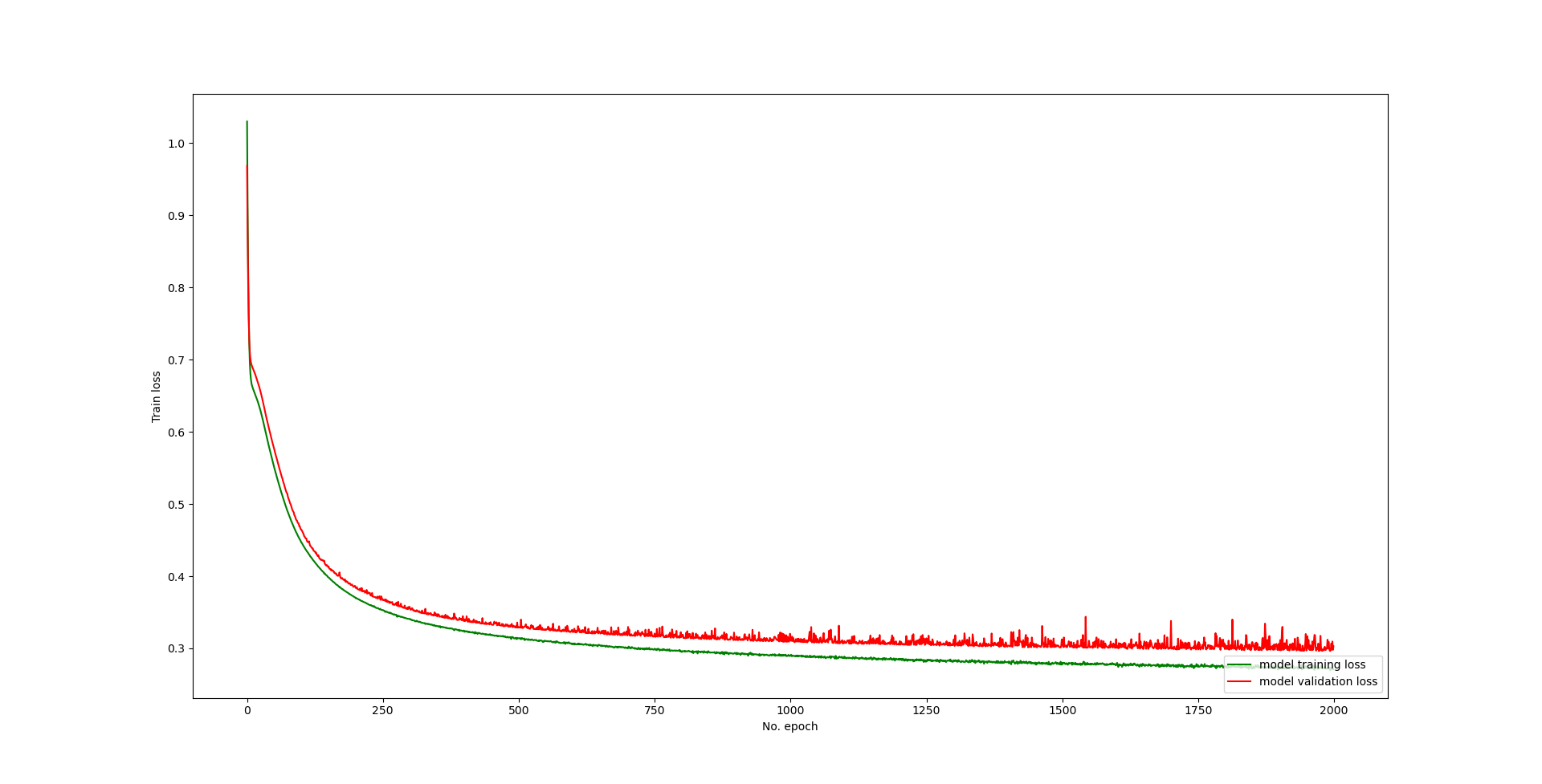
a) Use the training dataset to train the model and plot accuracies on training and testing data against training epochs

The training accuracies on training and testing set of the model is given by:



b) State the approximate number of epochs where the test error begins to converge.

The errors of the training set and testing set are given by:



We have implemented callback functions in the training session to log the loss of the testing set as follows:

|  |  |
| --- | --- |
| Epoch | Testing Loss |
| 0 | 0.97 |
| 100 | 0.46 |
| 200 | 0.35 |
| 300 | 0.34 |
| 400 | 0.33 |
| 500 | 0.32 |
| 600 | 0.32 |
| 700 | 0.32 |
| 800 | 0.32 |
| 900 | 0.31 |
| 1000 | 0.32 |
| 1100 | 0.31 |
| 1200 | 0.31 |
| 1300 | 0.31 |
| 1400 | 0.30 |
| 1500 | 0.31 |
| 1600 | 0.34 |
| 1700 | 0.30 |
| 1800 | 0.30 |
| 1900 | 0.30 |
| 2000 | 0.30 |

We can observe the testing loss reduced to 0.30 and converges around the 1500th epoch.

### 1.3.2. Question 2

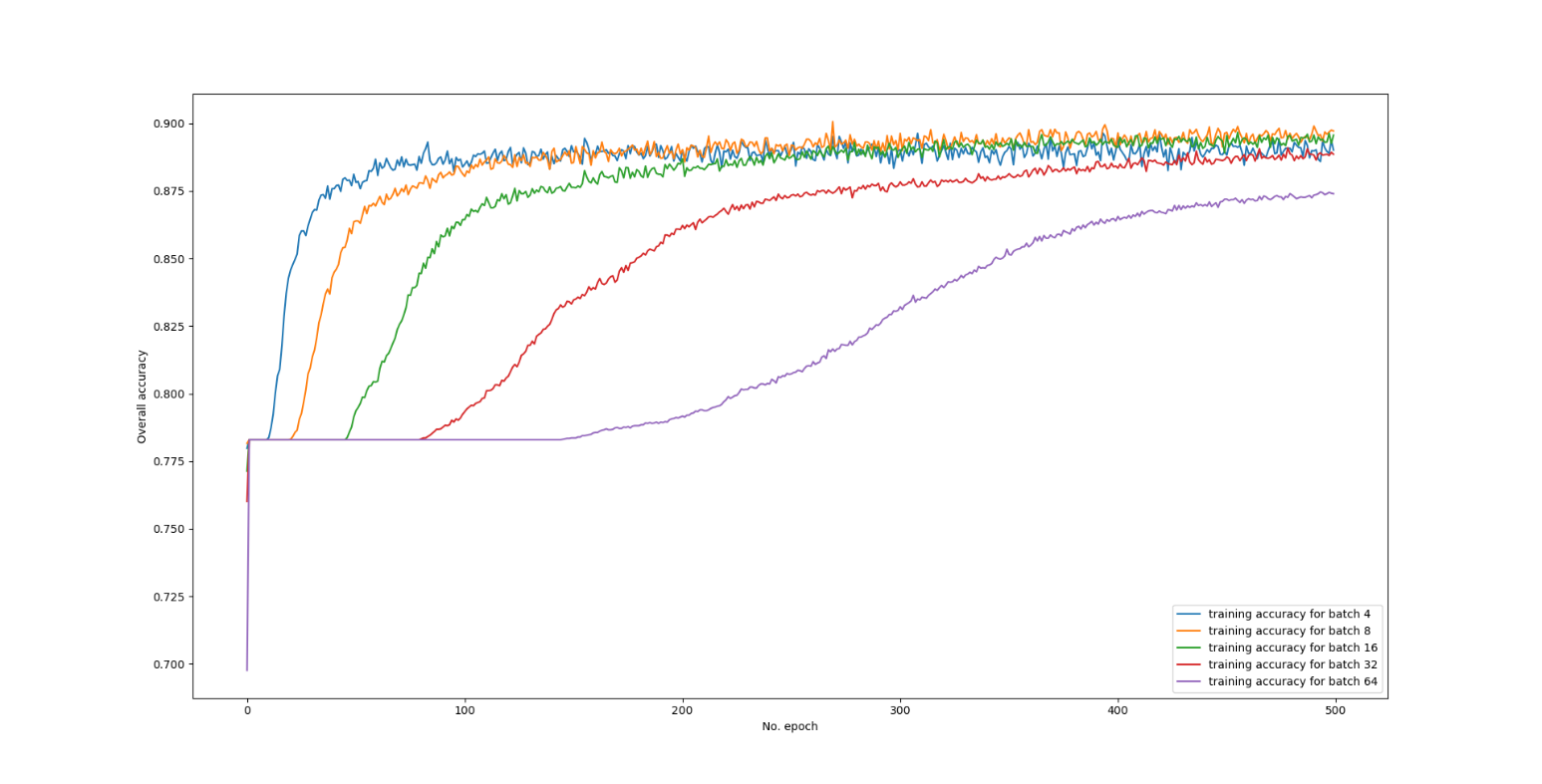
a) Plot cross-validation accuracies against the number of epochs for different batch sizes. Limit search space to batch sizes {4,8,16,32,64}. Plot the time taken to train the network for one epoch against different batch sizes.

We implemented the built-in method of sklearn to split the training set into five folds for cross validation:



|  |  |  |
| --- | --- | --- |
| Batch Size | Accuracy for each fold | Overall accuracy (Mean of all the folds) |
| 4 | A picture containing chart  Description automatically generated | Chart  Description automatically generated |
| 8 | Chart  Description automatically generated | Chart  Description automatically generated |
| 16 | Chart, histogram  Description automatically generated | Chart, line chart  Description automatically generated |
| 32 | Chart  Description automatically generated | Chart, line chart  Description automatically generated |
| 64 | Chart, line chart  Description automatically generated | Chart, line chart  Description automatically generated |

To compare the cross-validation accuracy between different batch sizes, we plotted the following graph:



We implemented the following code to record the average training time for one epoch of each batch size:



The average training time for each epoch is calculated as below:

|  |  |
| --- | --- |
| Batch Size | Average Time for each epoch |
| 4 | 3.072826560020447 |
| 8 | 1.531836547374725 |
| 16 | 0.9100194253921509 |
| 32 | 0.4580783643722534 |
| 64 | 0.26774400424957273 |

b) Select the optimal batch size and state reasons for your selection.

From the cross-validation result in section a) we can observe that the batch size 4, 8, and 16 have the highest training accuracies with batch size 8 being the highest. Comparably batch size 32 and 64 have the poorest training result after convergence. We can also observe that the speed of the increase of training accuracy is inversely proportional to the batch size, with batch size 4 increases the fastest.

From the average training time for each epoch we can observe that with the increase of batch size, the average time for each epoch reduces.

We select the optimal batch size to be 8 since it has the highest training accuracy and relatively acceptable average time for training each epoch.

c) Plot the train and test accuracies against epochs for the optimal batch size.

We chose the optimal batch size to be 8 and plot the train and test accuracies against epochs as following:

Chart, shape

Description automatically generated

### 1.3.3. Question 3

a) Plot the cross-validation accuracies against the number of epochs for different number of hidden-layer neurons. Limit the search space of number of neurons to {5,10,15,20,25}.

|  |  |  |
| --- | --- | --- |
| Number of Neurons | Accuracy for each fold | Overall accuracy (Mean of all the folds) |
| 5 | Chart, histogram  Description automatically generated | Chart, line chart  Description automatically generated |
| 10 | Chart, histogram  Description automatically generated | Chart, line chart  Description automatically generated |
| 15 | Chart, histogram  Description automatically generated | Chart  Description automatically generated |
| 20 | Chart  Description automatically generated | Chart, line chart  Description automatically generated |
| 25 | Chart  Description automatically generated | Chart, line chart  Description automatically generated |

To compare the cross-validation accuracy between different number of neurons in the hidden layer, we plotted the following graph:Chart, line chart

Description automatically generated

b) Select the optimal number of neurons for the hidden layer. State the rationale for your selection.

From the cross-validation comparison result above we can observe that the training accuracy for 25-neuron hidden layer has the highest training accuracy among other neuron sizes after convergence. Thus, the optimal number of neurons that we select is 25.

c) Plot the train and test accuracies against epochs with the optimal number of

neurons.

We chose the optimal number of neurons to be 25 and plot the train and test accuracies against epochs as following:

Chart, shape

Description automatically generated

### 1.3.4. Question 4

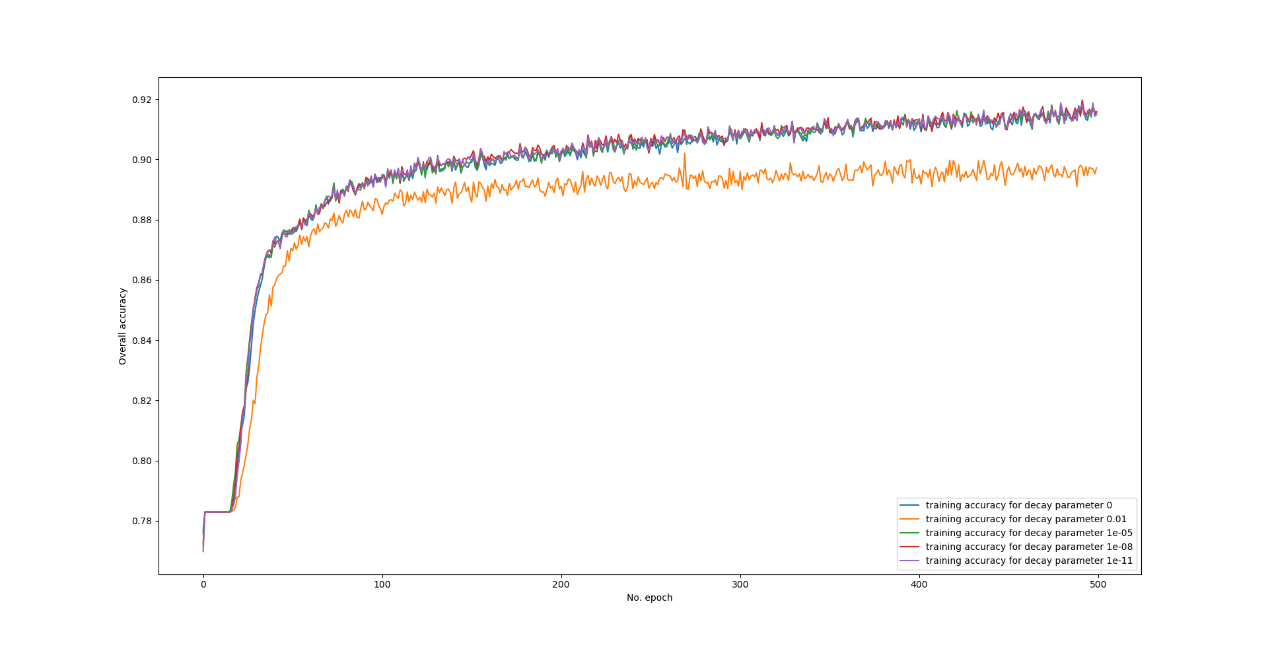
a) Plot cross-validation accuracies against the number of epochs for the 3-layer

network for different values of decay parameters. Limit the search space of decay

parameters to {0, 10e−3, 10e−6, 10e−9, 10e−12}.

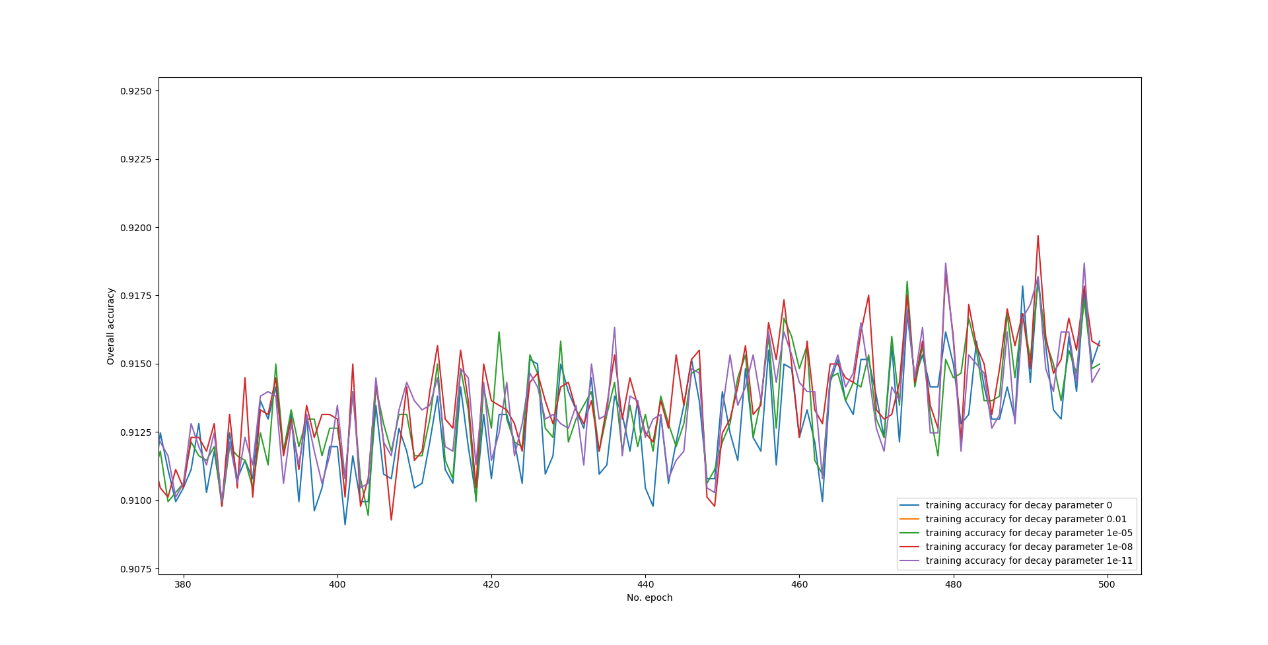
|  |  |  |
| --- | --- | --- |
| Decay Parameter | Accuracy for each fold | Overall accuracy (Mean of all the folds) |
| 0 |  |  |
| 10e−3 |  |  |
| 10e−6 |  |  |
| 10e−9 |  |  |
| 10e−12 |  |  |

To compare the cross-validation accuracy between different decay parameters in the hidden layer, we plotted the following graph:



b) Select the optimal decay parameter. State the rationale for your selection.

If we zoom in the comparison in section a) between training epoch 400 and training epoch 500, we can have the following pattern. From the following pattern we can observe that the training accuracy of decay parameter 1e-08 stands out of the other options for most of the time. Thus we choose decay parameter 1e-08 to be the optimal decay parameter for the model.



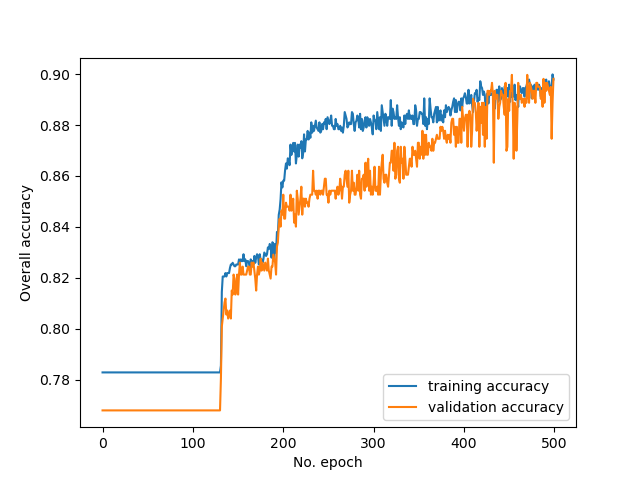
### 1.3.5. Question 5

a) Plot the train and test accuracy of the 4-layer network.

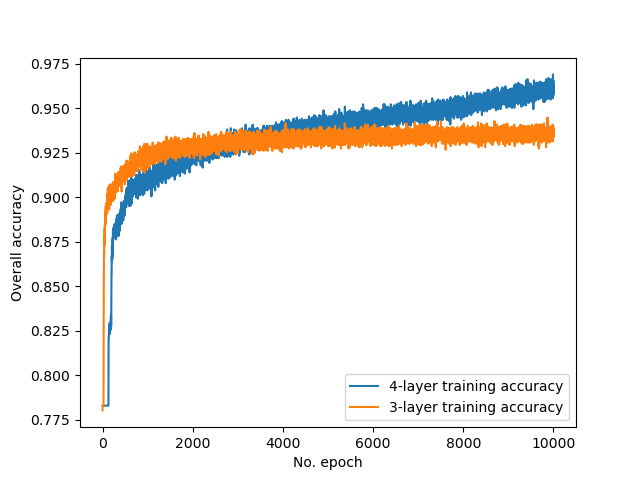
We created and trained the 4-layer model with the following requirements:

1. Having two hidden layers, each consisting 10 neurons
2. Training batch size if 32 and the decay parameter is 10e-6

We acquired the following graph for the training and testing accuracies against training epochs:



b) Compare and comment on the performances of the optimal 3-layer and 4-layer

networks. 

From the graph in section a) we can observe that the optimal 3-layer training model have a higher accuracy than 4-layer training model initially before the 4000th epoch. However, the training accuracy of the 4-layer model surpasses 3-layer model after the 4000th epoch and continues to increase while the accuracy of 3-layer model converges.

One possible reasoning for this behaviour is that with the increase in the number of hidden layers, the network becomes less volatile but more accurate to reflect the input data, and with more hidden layers the network becomes more capable to classify data with non-linear distribution which might explain why the 4-layer model can surpass the bottleneck experienced by the 3-layer model. The 4-layer network also has more parameters to train, so we could expect a higher accuracy with the increase of data size, for the current data size is only 1488 which is relatively small and not ideal for the network to learn complex mapping.

# 2. Part B: Regression Problem

## 2.1 Introduction

Part B aims to use the data from the Graduate Admission Prediction which contains several parameters like GRE score, TOEFL score, University Rating and strength of Statement of Purpose and Letter of Recommendation, undergraduate GPA, research experience, that are considered to be important during the application for Master Programs. The assignment attempts to predict the chance of getting an admit ranging from 0 to 1.

## 2.2. Methods

### 2.2.1. Normalization of Inputs



By observing the sample data set, we can note that there are relatively huge variations between features that might affect the training result of the model. For example: the GRE scores can reach over 300 and TOEFL score over 100, while other features are only single-digits



To eliminate the variations between fields to prevent a few features from having a dominant effect on training, we Normalize the input to have standard normal distributions N(0,1).

### 2.2.2. Split Training and Testing Data

We utilized the built-in function ‘train\_test\_split’ from sklearn to randomly split the entire sample into training set and testing set with size ratio of 70:30. This is similar to what we have implemented in PartA.



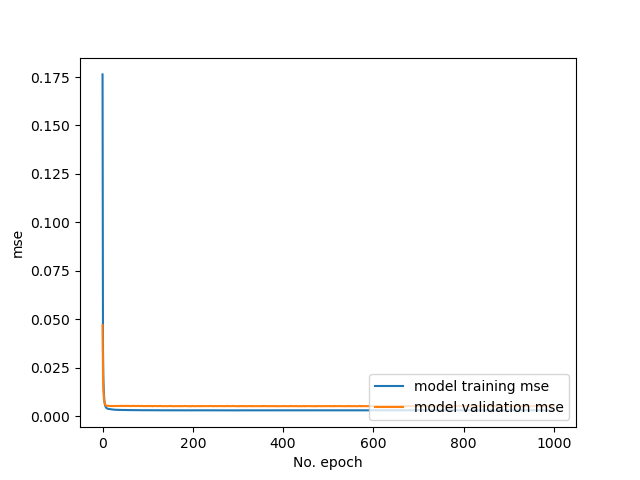
The split result in a training set with size 280 and testing set with size 120.

## 2.3. Experiments and Results

### 2.3.1. Question 1

a) Use the train dataset to train the model and plot both the train and test errors against epochs

We have built the model using the following implementation and trained it. We acquired the training mse and validation mse against the training epoch:

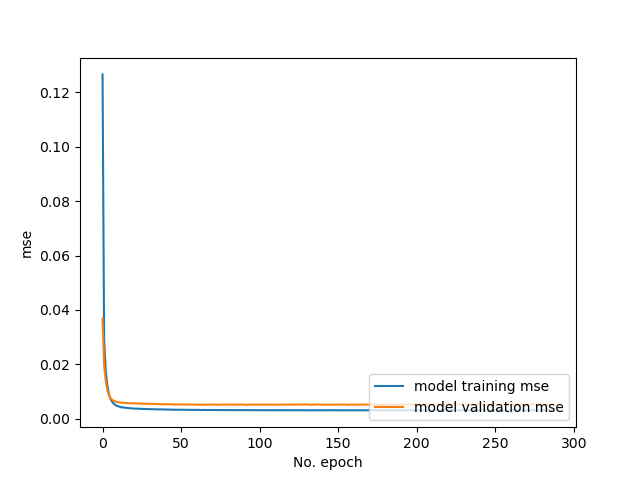


b) State the approximate number of epochs where the test error is minimum and use it to stop training.

We implemented the in-built EarlyStopping callback from Keras to record the minimum test error:



We set the patience to be 10, which means the training will stop if the error has not improved in 10 consecutive epochs. We then acquired the following graph for training with early stopping implemented:



The log of the training with early stopping enabled is as below:

*Epoch 288/1000*

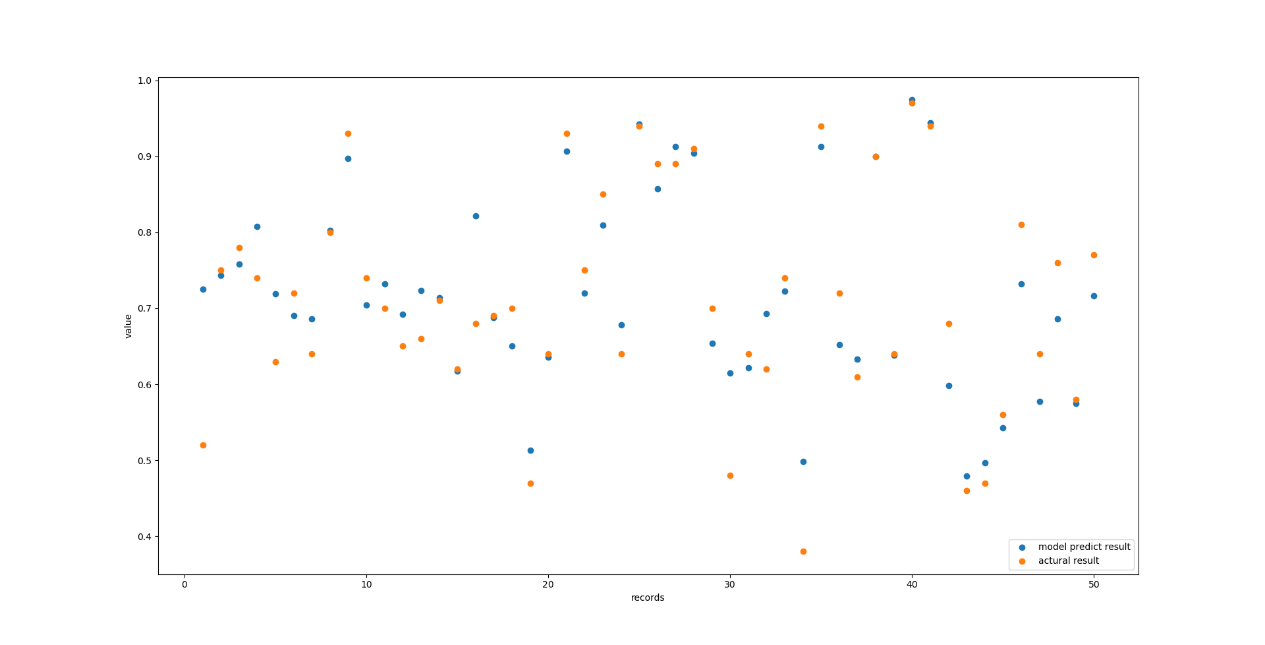
*35/35 - 0s - loss: 0.0035 - mse: 0.0030 - val\_loss: 0.0056 - val\_mse: 0.0051*

We can observe that the training stopped at epoch 288.

c) Plot the predicted values and target values for any 50 test samples.

# Split the data randomly into 1:7, we will use predict\_x to evaluate the model accuracy  
rest\_X, predict\_X, rest\_Y, predict\_Y = train\_test\_split(trainX, trainY, test\_size = 0.125, random\_state=2)  
result = model.predict(predict\_X)

We split the data into 50:350 randomly, use the 50-sized sample to predict the values and compare the result with the actual values:



### 2.3.2. Question 2