

Connectomics: Null Hypotheses

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Hypothesis Testing

There are key components to take full advantage of th

- Likelihood
- Statistical Hypothesis
- Hypothesis Test
- Likelihood Ratio
- Asymptotic Properties of the Normal Distribution
- p -values

Likelihood

If we have X_1, \dots, X_n independent and identically distributed (iid) random variables with a common probability (mass/density) function $f(x; \theta)$ where the parameter θ is unknown ($\theta \in \Omega$). The likelihood of a sample $\vec{x} = (x_1, \dots, x_n)$ is

$$L(\theta, \vec{x}) = \prod_{i=1}^n f(x_i, \theta)$$

Example: If we have $X_i \sim N(\theta, \sigma^2)$ with $\sigma^2 > 0$ known but θ unknown. Then

$$L(\theta, \vec{x}) = \left(\frac{1}{2\pi\sigma^2} \right)^{n/2} \exp \left(-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \bar{x})^2 \right) \exp \left(-\frac{1}{2\sigma^2} n(\bar{x} - \theta)^2 \right)$$

Statistical Hypothesis

A Statistical Hypothesis is a conjecture about the probability distribution of a population.

Example: We suppose that in an experiment we have a random sample from $N(\theta, 10)$.

H_0 : The population is $N(5, 10)$ -distributed

H_1 : The population is $N(1, 10)$ -distributed

Hypothesis Test

A Hypothesis Test is a tuple $(X_1, \dots, X_n; H_0, H_1, G)$, where

- ① (x_1, \dots, x_n) is a sample of (X_1, \dots, X_n) random variables iid.
- ② H_0 and H_1 are hypothesis concerning the probability distribution of the population.
- ③ $G \subset \mathbb{R}^n$ is Borel set (countable unions of open sets).

The **level of significance** is defined as

$$\alpha = P_{X_1, \dots, X_n}^{H_0}(G)$$

We will consider hypothesis such as

$$H_0: \theta = \theta_0 \text{ (or } \theta \in \Theta_0 \text{)} \quad H_1: \theta \neq \theta_0 \text{ (or } \theta \in \Theta = \Theta_1 \cup \Theta_0 \text{)}$$

Maximum Likelihood Test

The **likelihood ratio** function

$$\Lambda(x_1, \dots, x_n) = \frac{\sup_{\theta \in \Theta_0} L_{\theta}(x_1, \dots, x_n)}{\sup_{\theta \in \Theta} L_{\theta}(x_1, \dots, x_n)}$$

Let $\hat{\theta}$ be the maximum likelihood estimate of θ .

If θ_0 is the true value of θ , then $L(\theta_0)$ is the maximum value of $L(\theta)$. Since $\Lambda \leq 1$, then if H_0 is true Λ should be close to 1, whereas if H_1 is true then Λ should be smaller.

We have the decision rule

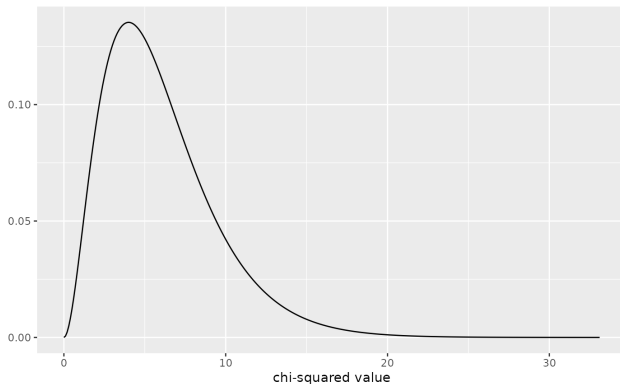
Reject H_0 in favor of H_1 if $\Lambda \leq c$,

where $\alpha = P^{\theta_0}(\Lambda \leq c)$.

Asymptotic Properties

Under some (regularity) conditions we have the following result:
If the null hypothesis $H_0: \theta = \theta_0$.

$$-2 \log \Lambda(X_1, \dots, X_n) \rightarrow \chi^2(1)$$



Asymptotics for the Normal distribution

When μ and σ are unknown and testing the hypothesis

$$H_0: \mu = \mu_0 \quad H_1: \mu \neq \mu_0$$

The likelihood ratio is given by

$$\Lambda(x_1, \dots, x_n) = \left\{ 1 + \frac{1}{n-1} \left(\frac{\bar{x} - \mu_0}{s/\sqrt{n}} \right)^2 \right\}^{-n/2}$$

where $s^2 = \frac{1}{n-1} \sum_i (x_i - \bar{x})^2$. The critical regions are of the form

$$G = \{(x_1, \dots, x_n) \in \mathbb{R}^n : \left| \frac{\bar{x} - \mu_0}{s/\sqrt{n}} \right| \geq c\}$$

p -values

The test statistic $\frac{\bar{x} - \mu_0}{s/\sqrt{n}}$ is critical to reject H_0 or not. The decision procedure is as follows

if $\left| \frac{\bar{x} - \mu_0}{s/\sqrt{n}} \right| \geq c$ then we assume H_1

if $\left| \frac{\bar{x} - \mu_0}{s/\sqrt{n}} \right| < c$ then we assume H_0

Furthermore, we have the following equivalence

$$P\left(\left|\frac{\bar{x} - \mu_0}{s/\sqrt{n}}\right| \geq u\right) \leq \alpha \iff u \geq c$$

The p -value associated with the outcome u of the test statistic $\frac{\bar{x} - \mu_0}{s/\sqrt{n}}$

$$P\left(\left|\frac{\bar{x} - \mu_0}{s/\sqrt{n}}\right| \geq |u|\right)$$

p -values (cont)

Thus if an outcome u of $\frac{\bar{x}-\mu_0}{s/\sqrt{n}}$ satisfies

$$P\left(\left|\frac{\bar{x}-\mu_0}{s/\sqrt{n}}\right| \geq |u|\right) \leq \alpha \text{ we accept } H_1$$

Today's paper



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Computational Neuroscience

Extracting spatial–temporal coherent patterns in large-scale neural recordings using dynamic mode decomposition

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Background

What are eigenvalues and eigenvectors?

Let A be a $n \times n$ matrix (real), a number $\lambda \in \mathbb{C}$ is an **eigenvalue** if there is a nonzero vector $x \in \mathbb{C}^n$ for which $Ax = \lambda x$. We call such a vector an **eigenvector** of A associated with λ .

The collection of all eigenvalues of A is called the **spectrum** of A .

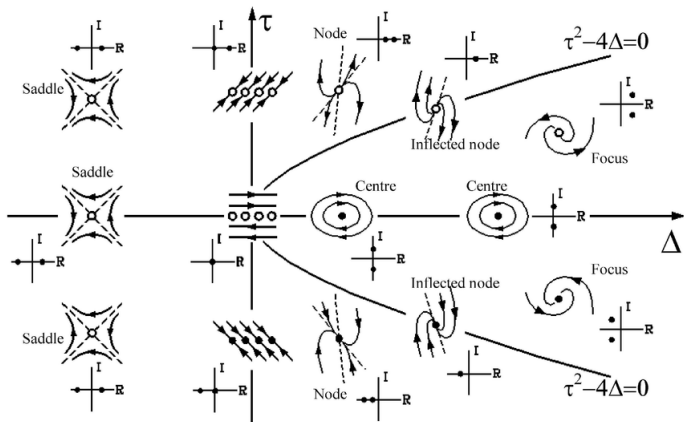
The fundamental theorem for linear systems: If A is a $n \times n$ matrix. For any $x_0 \in \mathbb{R}^n$, the initial value problem

$$\dot{x} = Ax \quad x(0) = x_0$$

has a unique solution

$$x(t) = \exp(A^t)x_0$$

Eigenvalues in Dynamical Systems



<https://www.researchgate.net/profile/Marco-Altosole/publication/245387409/figure/fig1/AS:392836487892996@1470670925920/Types-of-phase-portrait.png>

Singular Value Decomposition

If $A \in M_{m,n}$ has rank k , then it may be written in the form

$$A = V\Sigma W^*$$

where $V \in M_m$ and $W \in M_n$ are unitary ($W^*W = I_n$). The matrix $\Sigma = \text{diag}\{\sigma_1, \dots, \sigma_q\}$ are the non-negative square roots of the eigenvalues of AA^* . The columns of V are eigenvectors of AA^* , and the columns of W are eigenvectors of A^*A . If $m \leq n$ and if AA^* has distinct eigenvalues, then V is determined up to a right diagonal factor $D = \text{diag}(\exp(i\theta_1), \dots, \exp(i\theta_n))$ where $\theta_j \in \mathbb{R}$.

Main Premise

The DMD algorithm seeks a best-fit linear matrix A that approximately advances the state of a system $x \in \mathbb{R}^n$ forward in time according to the linear system

$$x_{k+1} = Ax_k$$

where $x_k = x(k\Delta t)$ and Δt denotes a fixed time step that is small enough to resolve the highest frequencies in the dynamics.

DMD setup

$$(3.2a) \quad \mathbf{X} = \begin{bmatrix} \mathbf{x}(t_1) & \mathbf{x}(t_2) & \cdots & \mathbf{x}(t_m) \end{bmatrix},$$

$$(3.2b) \quad \mathbf{X}' = \begin{bmatrix} \mathbf{x}(t'_1) & \mathbf{x}(t'_2) & \cdots & \mathbf{x}(t'_m) \end{bmatrix}.$$

Equation (3.1) may be written in terms of these data matrices as

$$(3.3) \quad \mathbf{X}' \approx \mathbf{A}\mathbf{X}.$$

DMD trick

computing $\tilde{\mathbf{A}}$ in (3.4), we may project \mathbf{A} onto the first r SVD modes in \mathbf{U}_r and approximate the pseudoinverse using the rank- r SVD approximation $\mathbf{X} \approx \mathbf{U}_r \Sigma_r \mathbf{V}_r^*$:

$$(3.6a) \quad \tilde{\mathbf{A}} = \mathbf{U}_r^* \mathbf{A} \mathbf{U}_r$$

$$(3.6b) \quad = \mathbf{U}_r^* \mathbf{X}' \mathbf{X}^\dagger \mathbf{U}_r$$

$$(3.6c) \quad = \mathbf{U}_r^* \mathbf{X}' \mathbf{V}_r \Sigma_r^{-1} \mathbf{U}_r^* \mathbf{U}_r$$

$$(3.6d) \quad = \mathbf{U}_r^* \mathbf{X}' \mathbf{V}_r \Sigma_r^{-1}.$$

The leading spectral decomposition of \mathbf{A} may be approximated from the spectral decomposition of the much smaller $\tilde{\mathbf{A}}$:

$$(3.7) \quad \tilde{\mathbf{A}} \mathbf{W} = \mathbf{W} \Lambda.$$

The diagonal matrix Λ contains the *DMD eigenvalues*, which correspond to eigenvalues of the high-dimensional matrix \mathbf{A} . The columns of \mathbf{W} are eigenvectors of $\tilde{\mathbf{A}}$ and provide a coordinate transformation that diagonalizes the matrix. These columns may be thought of as linear combinations of POD mode amplitudes that behave linearly with a single temporal pattern given by the corresponding eigenvalue λ .

The eigenvectors of \mathbf{A} are the *DMD modes* Φ , and they are reconstructed using the eigenvectors \mathbf{W} of the reduced system and the time-shifted data matrix \mathbf{X}' :

$$(3.8) \quad \Phi = \mathbf{X}' \tilde{\mathbf{V}} \tilde{\Sigma}^{-1} \mathbf{W}.$$

DMD expansion

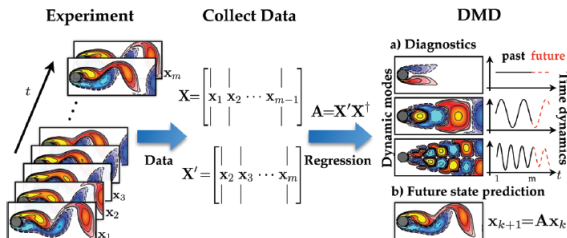


Fig. 3.1 Overview of DMD illustrated on the fluid flow past a circular cylinder at Reynolds number 100. Reproduced with permission from Kutz et al. [225].

3.1.1. Spectral Decomposition and the DMD Expansion. Once the DMD modes and eigenvalues are computed, it is possible to represent the system state in terms of the DMD expansion

$$(3.9) \quad x_k = \sum_{j=1}^r \phi_j \lambda_j^{k-1} b_j = \Phi \Lambda^{k-1} \mathbf{b},$$

where ϕ_j are eigenvectors of A (DMD modes), λ_j are eigenvalues of A (DMD eigenvalues), and b_j are the mode amplitudes. The DMD expansion (3.9) is directly analo-

DMD expansion (cont)

The spectral expansion in (3.9) may be converted to continuous time by introducing the continuous eigenvalues $\omega = \log(\lambda)/\Delta t$:

$$(3.14) \quad \mathbf{x}(t) = \sum_{j=1}^r \phi_j e^{\omega_j t} b_j = \Phi \exp(\Omega t) \mathbf{b},$$

where Ω is a diagonal matrix containing the continuous-time eigenvalues ω_j . Thus, the data matrix \mathbf{X} may be represented as

$$(3.15) \quad \mathbf{X} \approx \begin{bmatrix} | & & | \\ \phi_1 & \cdots & \phi_r \\ | & & | \end{bmatrix} \begin{bmatrix} b_1 & & \\ & \ddots & \\ & & b_r \end{bmatrix} \begin{bmatrix} e^{\omega_1 t_1} & \cdots & e^{\omega_1 t_m} \\ \vdots & \ddots & \vdots \\ e^{\omega_r t_1} & \cdots & e^{\omega_r t_m} \end{bmatrix} = \Phi \text{diag}(\mathbf{b}) \mathbf{T}(\omega).$$

Colophon

