

Recursive Partitioning

Practical Machine Learning (with R)

UC Berkeley Fall 2015

Topics

Review and Expectations

Project Work and Questions

New Topics

REVIEW AND EXPECTATIONS

REVIEW AND EXPECTATION

- Use resampling techniques to calculate error rates (-or- any statistics)
 - Evaluating model performance is not the same thing as training. They are separate processes
 - Differences between repeated splitting, kfold cross-validation and bootstrap

Create, edit Rmarkdown documents using Rstudio and knitr

REVIEW AND EXPECTATION

Use model formula to specify interaction effects and more complex relationships between predictors and response variables

Nearest neighbor methods (briefly)

• Understand Bias Variance Trade-off

REVIEW AND EXPECTATION

Definitions for all the binomial performance measurements: accuracy, error rate, TP, FP, TN, FN, Type I Error, Sensitivity, Specificity, Recall, True Error

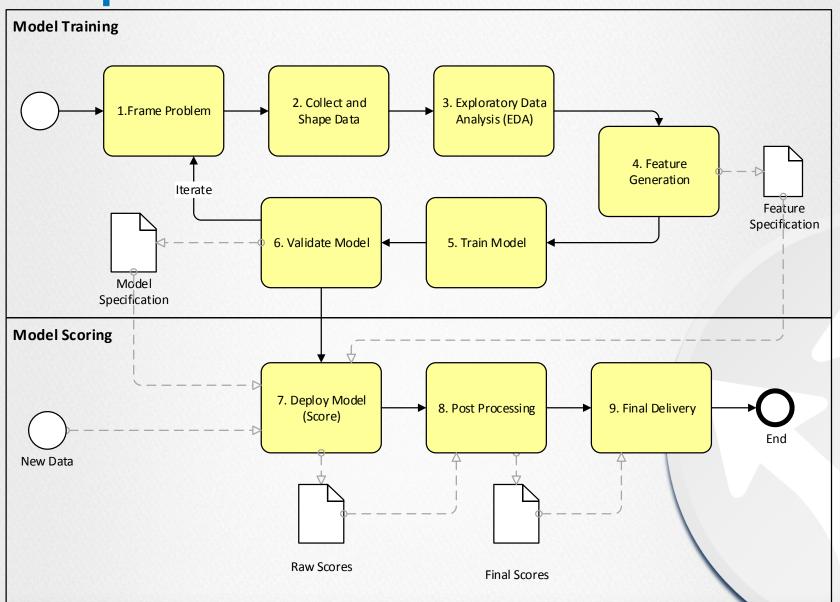


QUESTIONS

QUIZ



Comprehensive ML Process



ASSIGNMENT FROM LAST LECTURE: RESAMPLING

NEW TOPICS



MULTI-CLASS PERFORMANCE

TERMS

- SKappa Statistic,
- S-Statistics, F-Statistic

DECISION TREES / RECURSIVE PARTITIONING

LINEAR METHODS: LIMITATIONS

Advantages

- €...
- €...

Disadvantages

- ∍...
- Э.,
- €...

LINEAR METHODS: LIMITATIONS

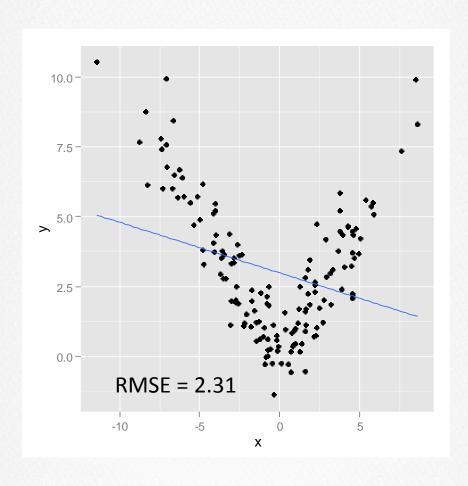
Advantages

- Interpretable
- Easy to train

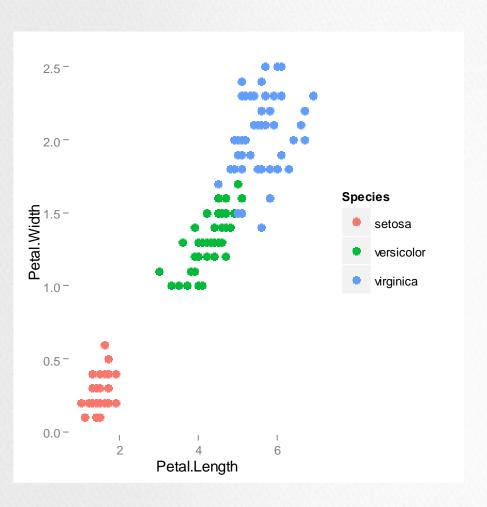
Disadvantages

- Logistic regression: multiclass problems
- Highly sensitive to inputs
- ⇒ Linear functions → do not model real data well

Linear Models: abs



A Simple Example

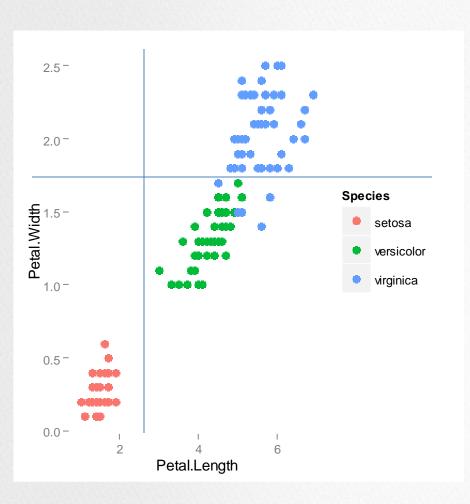


Partitioning Requirements

- Restricted Class of Functions
 - First order propositional logic (for partitions)
 - Aggregation (for outcomes)
- Error Methods
 - Normal error calculations

- Search Methods
 - Recursion

A Simple Example

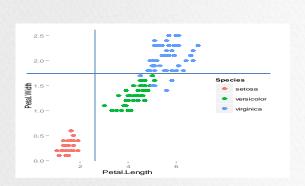


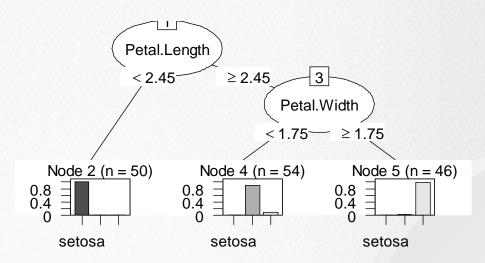
Partitioning Requirements

- Restricted Class of Functions
 - First Order Propositional Logic (for partitions)
 - Aggregation (for outcomes)
- Error Methods
 - Standard Error Methods
 - Regression: SSE, etc.
 - Class.: Misclassification Rate, etc
- Search Methods
 - Recursion and Exhaustive

SOME NOTES

Splitting by planes is the same as a tree





Partitions define a rule*

Rules can be associated with outcomes → aggregation method

Trees always partition "all of of space"

Partition Goal:

PARTITION INPUT SO THAT THE RESULTING SMALLER GROUPS ARE MORE HOMOGENEOUS

Splitting on Categorical Variable

- Select "metric"
- For each categorical variable
 - Find $argmin_{s \in S}(\sum_{S_i} err_i)$, i = 1...2
- Calculate:
 - $\sum_{S_i} err_i$

- Metric (e.g.)
 - misclassification rate etc.
 - Gini index

SPLITTING ON CONTINUOUS VARIABLE

- Determine Metric
- Order data
 - If metric is a "cumulative" function calculate as cumulative function:

e.g.
$$FPR = cumsum(FP)/cumsum(TN + FP)$$

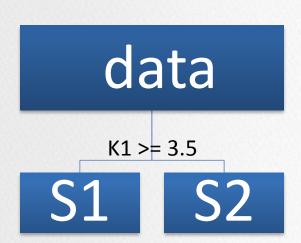
 Otherwise calculate at all possible split points or subset of split points

$$argmin_{x=n}(\sum_{i=1...2}err_i)$$

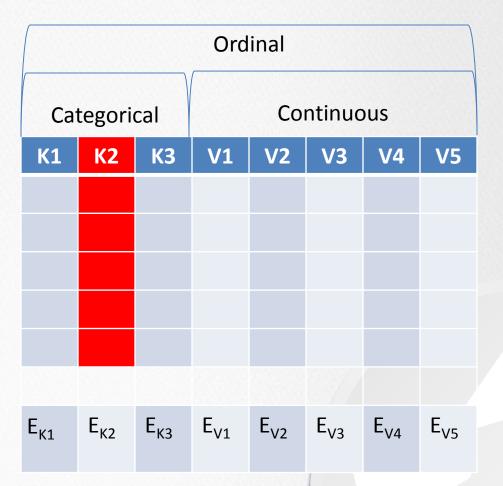
data

Choose the split that minimizes the error $argmin_S(Error)$

| | Ordinal | | | | | | | | | | | |
|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|----------|-----------------|--|--|--|--|--|
| Categorical | | | Continuous | | | | | | | | | |
| K1 | . K2 K3 | | V1 | V2 | V3 | V4 | V5 | | | | | |
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| | | | | | | | | | | | | |
| E _{K1} | E _{K2} | E _{K3} | E _{V1} | E _{V2} | E _{V3} | E_{V4} | E _{V5} | | | | | |



Choose the split that minimizes the error $argmin_S(Error)$



REPEAT WITH S1 AND S2

* Very often predictor will be used again.

Tree Method Advantages I

- Highly interpretable
- Easy to implement (even in SQL)
- Handle many predictors (sparse, skewed, continuous, categorical) --> little need to pre-process them
- Non-parametric: do not require specification of predictor-response relationship

Tree Method Advantages I

- Inherent method for handling missing data
- Trees insensitive to monotonic (orderpreserving) transformation of inputs
 - 2*x
 - No use in scaling and centering
- Intrinsic feature selection
- Computational simple and quick

TREE DISADVANTAGES

- Model instability (sensitive to data)
 - Derives from each subsequent split is dependent on prior splits
- Less than optimal predictive performance
 - Rectangular regions
- Limited number of outcome values
- Selection bias toward predictors with higher number of distinct values
- Tuning parameter

RPART EXAMPLE

CARET



Caret

- "Misc functions for training and plotting classification and regression models."
- Really:
 - Wraps 100's of modeling functions
 - Automates tediousness of model building
 - Manages a process

- Competitors:
 - mlr (machine learning with R): task focused
 - Rattle: Graham Williams et al. / Togaware.com
 - R Commander: Statistical workbench

Caret Goals

Does a couple things:

- evaluate, using resampling, the effect of model tuning parameters on performance
- choose the "optimal" model across these parameters
- estimate model performance from a training set
- Variable Importance
- Aids feature selection

Process

LOTS OF CONFIGURATIONS

- Easy if you know what you are doing
- which method?

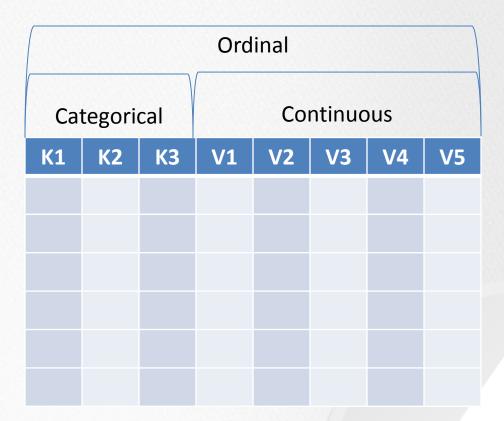
Caret Model List*

- Controlled mostly through
 - train
 - trainControl

APPENDIX



data



EXAMPLE OF ML ALGORITHM(S)

- Spam Filter
- handwriting recognition (svm)
- Traffic engineering (lights)
- Weather prediction
- Sentiment analysis (social media)
- Netflix Recommender
- Fraud detection (Visa)
- Imaging processing
- (network) Intrution detection
- Self-driving cars

COMPARISON OF MODELS (CHART)

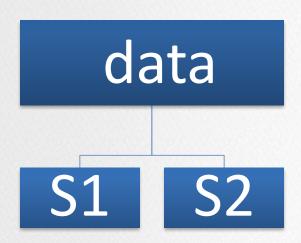


TRANSFORMATIONS

- Centering and Scaling: scale*
- Resolve skewness: log, sqrt, inv
- Resolve outliers: spatial sign, PCA

Some algorithms require scaling Some are insensitive Time consuming Somewhat of an art

Genetic algorithms (GA)



| N1 | N2 | N3 | V1 | V2 | V3 | V4 | V5 |
|----|----|----|----|----|----|----|----|
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