

```
In[16]:= x = r[t] Cos[φ[t]];
y = r[t] Sin[φ[t]];
rp = μ r[t] (1 - r[t]^2);
xp = D[x, t] /. {r'[t] → rp, φ'[t] → 1} // Simplify
yp = D[y, t] /. {r'[t] → rp, φ'[t] → 1} // Simplify
```

```
Out[19]= r[t] (-μ Cos[φ[t]] (-1 + r[t]^2) - Sin[φ[t]])
```

```
Out[20]= r[t] (Cos[φ[t]] - μ (-1 + r[t]^2) Sin[φ[t]])
```

```
In[21]:= (* Igy neznek ki xx-yy KR.ben az egyenletek*)
xxp = xp /. {r[t] → √(xx^2 + yy^2), φ[t] → ArcTan[xx, yy]} // FullSimplify
yyp = yp /. {r[t] → √(xx^2 + yy^2), φ[t] → ArcTan[xx, yy]} // FullSimplify
Simplify[xxp /. {xx → Cos[t], yy → Sin[t]}]
Simplify[yyp /. {xx → Cos[t], yy → Sin[t]}]
```

```
Out[21]= -yy - xx (-1 + xx^2 + yy^2) μ
```

```
Out[22]= xx - yy (-1 + xx^2 + yy^2) μ
```

```
Out[23]= -Sin[t]
```

```
Out[24]= Cos[t]
```

```
In[48]:= Jac = FullSimplify[{{D[xxp, xx] D[xxp, yy]
D[yyp, xx] D[yyp, yy}}];
MatrixForm[Jac]
M = Exp[Jac t /. {xx → Cos[t], yy → Sin[t]} /. {t → 2 π}] // Simplify;
MatrixForm[M]
```

```
Out[49]//MatrixForm=
( - (-1 + 3 xx^2 + yy^2) μ      -1 - 2 xx yy μ
  1 - 2 xx yy μ      - (-1 + xx^2 + 3 yy^2) μ )
```

```
Out[51]//MatrixForm=
( e^(-4 π μ)  e^(-2 π)
  e^(2 π)     1 )
```

```
In[61]:= DSolve[{D[rr[t], t] == μ rr[t] (1 - rr[t]^2), rr[0] == r0}, rr[t], t]
```

... **Solve:** Inverse functions are being used by Solve, so some solutions may not be found; use Reduce for complete solution information.

... **Solve:** Inverse functions are being used by Solve, so some solutions may not be found; use Reduce for complete solution information.

```
Out[61]= {{rr[t] → - (e^(t μ) / √(-1 + e^(2 t μ) + 1/r0^2))}, {rr[t] → (e^(t μ) / √(-1 + e^(2 t μ) + 1/r0^2))}}
```

```
In[63]:= FullSimplify[D[(e^(t μ) / √(-1 + e^(2 t μ) + 1/r0^2)), r0] /. {r0 → 1} /. {t → 2 π},
Assumptions → {Im[μ] == 0}]
```

```
Out[63]= e^(-4 π μ)
```