

i)

a) $\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow |A| = 1 \neq 0$

therefore the given vectors are linearly independent basis of \mathbb{R}^3

b) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ the given vectors are linearly dependent

c) $\begin{bmatrix} 2 & 1 & -7 \\ -2 & -3 & 5 \\ 1 & 2 & 4 \end{bmatrix}$ linearly independent vectors that span \mathbb{R}^3

d) $\begin{bmatrix} 1 & -4 \\ 2 & -5 \\ -3 & 6 \end{bmatrix}$ linearly independent, not basis of \mathbb{R}^3

e) $\begin{bmatrix} 1 & 0 & 3 & 0 \\ -4 & 3 & -5 & 2 \\ 3 & -1 & 4 & -2 \end{bmatrix}$ vectors not a basis, is not a set of linearly independent vectors, but spans \mathbb{R}^3

2) B is row echelon form of A, we see that the first, third and fifth columns of A are its pivot columns.

Basis of COL A is

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} -5 \\ -5 \\ 0 \\ -5 \end{bmatrix}, \begin{bmatrix} -3 \\ 2 \\ 5 \\ -2 \end{bmatrix} \right\}$$

$x_1 = -2x_2 - 4x_4$, $x_3 = (7/5)x_4$, $x_5 = 0$ with x_2 and x_4 free.

$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = x_2 \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -4 \\ 0 \\ 7/5 \\ 1 \\ 0 \end{pmatrix}$$

basis for $N(A)$ is

$$\left\{ \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -4 \\ 0 \\ 7/5 \\ 1 \\ 0 \end{pmatrix} \right\}$$

$$3) \quad v_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} -2 \\ 1 \\ -1 \\ 1 \end{bmatrix}, v_3 = \begin{bmatrix} 6 \\ -1 \\ 2 \\ -1 \end{bmatrix}, v_4 = \begin{bmatrix} 5 \\ -3 \\ 3 \\ -4 \end{bmatrix}, v_5 = \begin{bmatrix} 0 \\ 3 \\ -1 \\ 1 \end{bmatrix}$$

$$\text{col } A, A = [v_1, v_2, v_3, v_4, v_5]$$

$$A = \begin{bmatrix} 1 & -2 & 6 & 5 & 0 \\ 0 & 1 & -1 & -3 & 3 \\ 0 & -1 & 2 & 3 & -1 \\ 1 & 1 & -1 & -4 & 1 \end{bmatrix}$$

$$\text{reduce matrix: } \begin{bmatrix} 1 & -2 & 6 & 5 & 0 \\ 0 & 1 & -1 & -3 & 3 \\ 0 & -1 & 2 & 3 & -1 \\ 1 & 1 & -1 & -4 & 1 \end{bmatrix} \xrightarrow{R_4 - R_1} \begin{bmatrix} 1 & -2 & 6 & 5 & 0 \\ 0 & 1 & -1 & -3 & 3 \\ 0 & -1 & 2 & 3 & -1 \\ 0 & 3 & -7 & -9 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & 6 & 5 & 0 \\ 0 & 1 & -1 & -3 & 3 \\ 0 & -1 & 2 & 3 & -1 \\ 0 & 3 & -7 & -9 & 1 \end{bmatrix} \xrightarrow{R_3 + R_2, R_4 - 3R_2} \begin{bmatrix} 1 & -2 & 6 & 5 & 0 \\ 0 & 1 & -1 & -3 & 3 \\ 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & -4 & 0 & -8 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & 6 & 5 & 0 \\ 0 & 1 & -1 & -3 & 3 \\ 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & -4 & 0 & -8 \end{bmatrix} \xrightarrow{R_4 + 4R_3} \begin{bmatrix} 1 & -2 & 6 & 5 & 0 \\ 0 & 1 & -1 & -3 & 3 \\ 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\text{Matrix } A \text{ is: } A = \begin{bmatrix} 1 & -2 & 6 & 5 & 0 \\ 0 & 1 & -1 & -3 & 3 \\ 0 & -1 & 2 & 3 & -1 \\ 1 & 1 & -1 & -4 & 1 \end{bmatrix} \approx \begin{bmatrix} 1 & -2 & 6 & 5 & 0 \\ 0 & 1 & -1 & -3 & 3 \\ 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$b = b_1, b_2, b_3, b_4, b_5 \quad \text{col}(A) = \left\{ v_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} -2 \\ 1 \\ -1 \\ 1 \end{bmatrix}, v_3 = \begin{bmatrix} 6 \\ -1 \\ 2 \\ -1 \end{bmatrix} \right\}$$

$$\text{vector} \{v_1, v_2, v_3\}$$

4)

a) For each b in \mathbb{R}^m , the equation has solution $Ax=b$ is equivalent to the columns of A span \mathbb{R}^m . The matrix A has pivot position in each row: each b in \mathbb{R}^m is a linear combo of column A .

b) $\{v_1, \dots, v_p\}$ in \mathbb{R}^n is linearly dependent if $p > n$.
the only difference is p instead of k .
therefore $\{v_1, \dots, v_k\}$ is linearly dependent,
and can't be a basis.

$$5) B = \begin{bmatrix} 4 \\ 5 \end{bmatrix}, \begin{bmatrix} 6 \\ 7 \end{bmatrix}$$

$$X \cdot B = \begin{bmatrix} 4 \\ 5 \end{bmatrix}$$

$$X = 8(b_1) + = 5(b_2)$$

$$\begin{aligned} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} &= 8 \begin{bmatrix} 4 \\ 5 \end{bmatrix} + -5 \begin{bmatrix} 6 \\ 7 \end{bmatrix} \\ &= \begin{bmatrix} 32 \\ 40 \end{bmatrix} + \begin{bmatrix} -30 \\ -35 \end{bmatrix} \\ &= \begin{bmatrix} 2 \\ 5 \end{bmatrix} \end{aligned}$$

$$5) B = \begin{bmatrix} 4 \\ 5 \end{bmatrix}, \begin{bmatrix} 6 \\ 7 \end{bmatrix}$$

1)

$$x \cdot B = \begin{bmatrix} 9 \\ 5 \end{bmatrix}$$

$$x = 8(b_1) + 5(b_2)$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 8 \begin{bmatrix} 4 \\ 5 \end{bmatrix} + 5 \begin{bmatrix} 6 \\ 7 \end{bmatrix} \\ = \begin{bmatrix} 32 \\ 40 \end{bmatrix} + \begin{bmatrix} 30 \\ 35 \end{bmatrix} \\ = \begin{bmatrix} 2 \\ 5 \end{bmatrix}$$

$$5) = B = \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ -5 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ -7 \\ 3 \end{bmatrix}, x_B = \begin{bmatrix} -4 \\ 8 \\ 7 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = (-4)b_1 + 8(b_2) + 7(b_3)$$

$$x = (-4) \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix} + 8 \begin{bmatrix} 3 \\ -5 \\ 2 \end{bmatrix} + 7 \begin{bmatrix} 4 \\ -7 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} 4 + 24 - 28 \\ -8 + (-40) + 49 \\ 0 + 16 - 21 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ -5 \end{bmatrix}$$

6)

a)

$$b) b = \left\{ \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 8 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} \right\}, x = \begin{bmatrix} 3 \\ -5 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 & 3 \\ 0 & 1 & -1 & -5 \\ 0 & 2 & -1 & -5 \end{bmatrix}$$

$$\begin{aligned} \text{So } x_1 + 2x_2 + x_3 &= 3 \\ x_2 - x_3 &= -5 \\ x_3 &= 5 \end{aligned}$$

$$\begin{bmatrix} 1 & 2 & 1 & 3 \\ 0 & 1 & -1 & -5 \\ 0 & 0 & 1 & 5 \end{bmatrix}$$

$$\text{So } x_2 = 0, x_1 = 8$$

Coordinate vector = $(8, 0, 5)$

7)

the change-of-coordinates matrix from B to the standard basis in \mathbb{R}^2 is $P_B = \begin{pmatrix} 4 & 6 \\ 5 & 7 \end{pmatrix}$.

$$x_B = \begin{pmatrix} 4 & 6 & -1 & 2 \\ 5 & 7 & 0 \end{pmatrix} = \begin{pmatrix} -3.5 & 3 & 2 \\ 2.5 & -2 & 0 \end{pmatrix} = \begin{pmatrix} -7 \\ -5 \end{pmatrix}$$

$$8) \quad x_1(1-t^2) + x_2(t-t^2) + x_3(2-2+t+t^2) = 3+t-6t^2$$

$$\hookrightarrow (x_1 + 2x_3) + (x_2 - 2x_3)t + (-x_1 - x_2 + x_3)t^2 = 3 + t - 6t^2$$

$$x_1 + 2x_3 = 3$$

$$x_2 - 2x_3 = 1$$

$$-x_1 - x_2 + x_3 = -6$$

$$\text{augmented matrix } \begin{bmatrix} 1 & 0 & 2 & 3 \\ 0 & 1 & -2 & 1 \\ -1 & -1 & 1 & -6 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 7 \\ 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & -2 \end{bmatrix}$$

$$x_1 = 7, x_2 = -3, x_3 = -2$$

$$7(1-t^2) + (-3)(t-t^2) + (-2)(2-2+t+t^2) = 3+t-6t^2$$

$$\{3+t-6t^2\}_B = \begin{bmatrix} 7 \\ -3 \\ -2 \end{bmatrix} \in \mathbb{R}^3$$

7)

$$\begin{array}{c|c|c} 1+0+2+2+3 & 0+1+0+2+2+3 & 1+2+2+0+3 \\ \hline & & \\ \hline v_1 = (1, 0, -2, -1) & v_2 = (0, 1, 0, 2) & v_3 = (1, 1, -2, 0) \end{array}$$

$$[v_1, v_2, v_3] = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ -2 & 0 & -2 \\ -1 & 2 & 0 \end{bmatrix}$$

$$R_3 \rightarrow R_3 + 2R_1, R_4 \rightarrow R_4 + R_1$$

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 2 & 2 \\ 0 & 2 & 1 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - 2R_2, R_4 \rightarrow R_4 - R_2$$

$$R_3 \rightarrow R_3 \rightarrow 2R_2$$

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow[-1]{R_3} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

v_1, v_2, v_3 are linearly independent

(0)

a) for any polynomial in P_2 is of the form $a_0 + a_1t + a_2t^2$
then the coordinate vectors are $(1, 0, 1), (2, -1, 3), (1, 2, -4)$

$$\begin{pmatrix} 1 & 2 & 1 \\ 0 & -1 & 2 \\ 1 & 3 & -4 \end{pmatrix} = -2 + 4 = 2 \neq 0$$

the polynomials $\{p_1(t), p_2(t), p_3(t)\}$ form a basis for P_2

b) $\{p_1(t), p_2(t), p_3(t)\}$

$$\begin{aligned} &= x(1+t) + y(2-t+3t^2) + z(1+2t-4t^2) \\ &= (x+2y+z) + (-y+2z)t + (x+3y-4z)t^2 \\ &= x+2y+z = a_0, -y+2z = a_1 \text{ and } x+3y-4z = a_2 \end{aligned}$$

$$\begin{aligned} x &= \frac{1}{3}(-2a_0 + 11a_1 + 5a_2), y = \frac{1}{3}(2a_0 - 5a_1 - 2a_2) \text{ and } z = \frac{1}{3}(a_0 - a_1 - a_2) \\ a_0 + a_1 + a_2 &= \frac{1}{3}(-2a_0 + 11a_1 + 5a_2)(1+t) + \frac{1}{3}(2a_0 - 5a_1 - 2a_2)(2-t+3t^2) \\ &\quad + \frac{1}{3}(a_0 - a_1 - a_2)(1+2t-4t^2) \end{aligned}$$

$$\text{coordinate vector } [q]_b = \begin{bmatrix} -3 \\ 1 \\ 2 \end{bmatrix}$$

$$\begin{aligned} \frac{1}{3}(-2a_0 + 11a_1 + 5a_2) &= -3, \frac{1}{3}(2a_0 - 5a_1 - 2a_2) = 1 \\ \frac{1}{3}(a_0 - a_1 - a_2) &= 2 \end{aligned}$$

$$a_0 = 1, a_1 = -3, a_2 = -8 \quad q = 1 + 3t - 8t^2$$