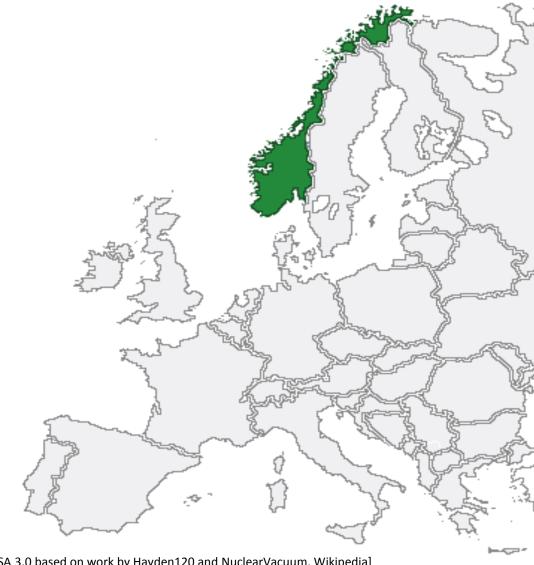
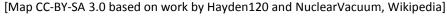




- Established 1950 by the Norwegian Institute of Technology.
- The largest independent research organisation in Scandinavia.
- A non-profit organisation.
- Motto: "Technology for a better society".
- Key Figures\*
  - 2100 Employees from 70 different countries.
  - 73% of employees are researchers.
  - 3 billion NOK in turnover (about 360 million EUR / 490 million USD).
  - 9000 projects for 3000 customers.
  - Offices in Norway, USA, Brazil, Chile, and Denmark.







### Talk outline

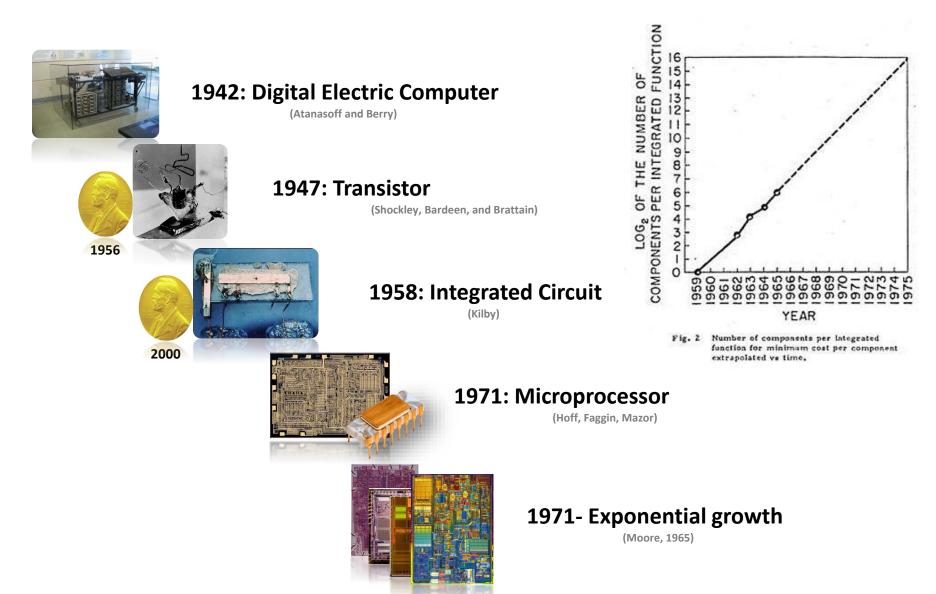
- Parallel computing on your desktop
- Motivation for parallelism
- Parallel algorithm design
- Lessons learned from working with multi- and many-core processors
  - Ca 2005: OpenGL
  - Ca 2007: CUDA
  - Ca 2014: Jupyter notebooks and pyopencl
- Summary



# Motivation for going parallel



### History lesson: development of the microprocessor 1/2





### History lesson: development of the microprocessor 2/2



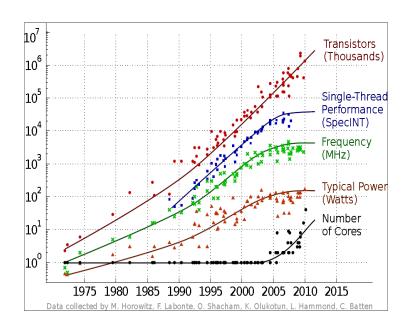
1971: 4004, 2300 trans, 740 KHz



1982: 80286, 134 thousand trans, 8 MHz

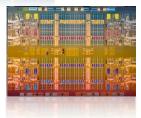


**1993: Pentium P5,** 1.18 mill. trans, 66 MHz





**2000: Pentium 4,** 42 mill. trans, 1.5 GHz

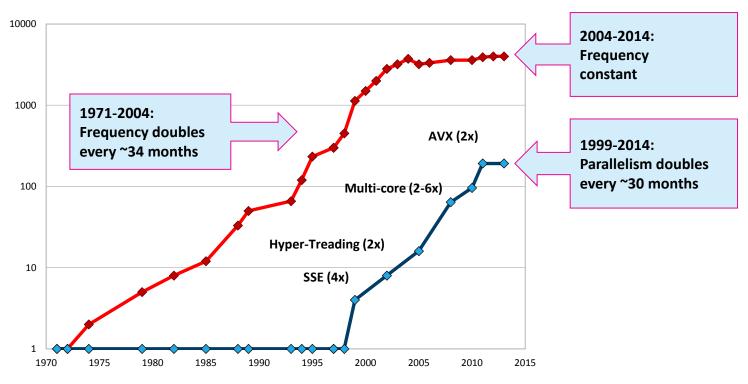


2010: Nehalem
2.3 bill. Trans, 8 cores, 2.66 GHz



# End of frequency scaling

#### **Desktop processor performance (SP)**

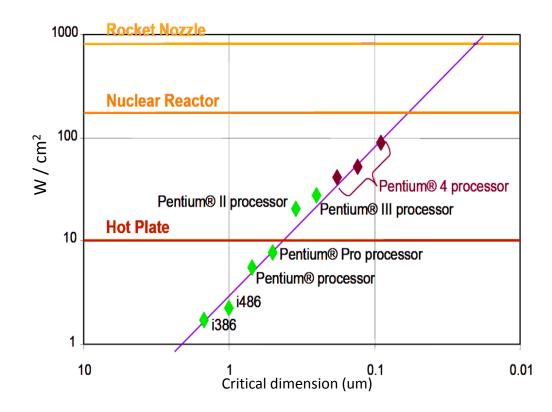


- 1970-2004: Frequency doubles every 34 months (Moore's law for performance)
- 1999-2014: Parallelism doubles every 30 months



## What happened in 2004?

- Heat density approaching that of nuclear reactor core: Power wall
  - Traditional cooling solutions (heat sink + fan)
     insufficient
- Industry solution: multi-core and parallelism!



Original graph by G. Taylor, "Energy Efficient Circuit Design and the Future of Power Delivery" EPEPS'09



## Why Parallelism?

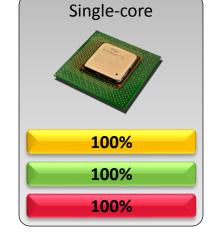
Frequency

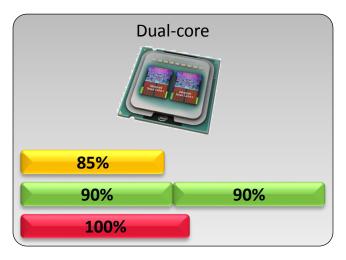
Power

Performance

The power density of microprocessors is proportional to the clock frequency cubed:<sup>1</sup>

$$P_d \propto f^3$$





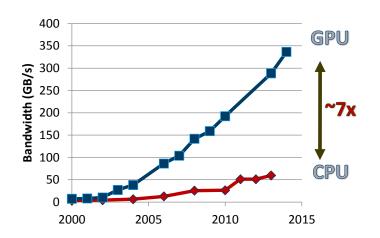
 $<sup>^{\</sup>rm 1}$  Brodtkorb et al. State-of-the-art in heterogeneous computing, 2010

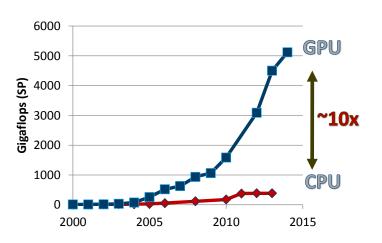


## Massive Parallelism: The Graphics Processing Unit

- Thousands of floating point operations in parallel!
- 5-10 times as power efficient as CPUs!

















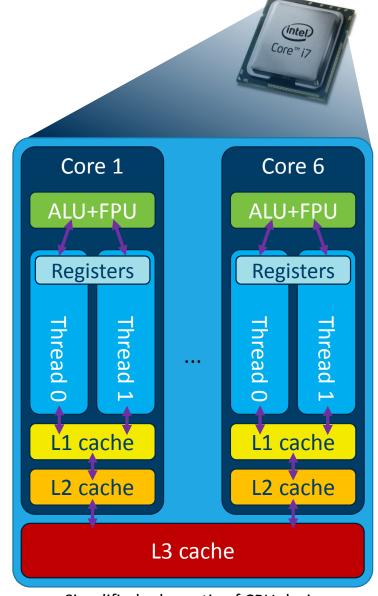
### Multi-core CPU architecture

### A single core

- L1 and L2 caches
- 8-wide SIMD units (AVX, single precision)
- 2-way Hyper-threading (<u>hardware</u> threads)
   When thread 0 is waiting for data,
   thread 1 is given access to SIMD units
- Most transistors used for cache and logic

### Optimal number of FLOPS per clock cycle:

- 8x: 8-way SIMD
- 6x: 6 cores
- 2x: Dual issue (fused mul-add / two ports)
- Sum: 96!

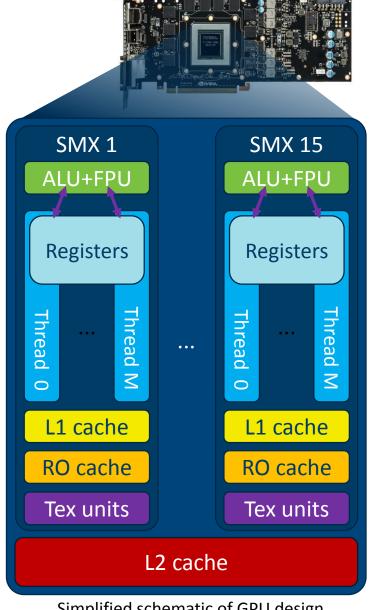


Simplified schematic of CPU design



## Many-core GPU architecture

- A single core (Called streaming multiprocessor, SMX)
  - L1 cache, Read only cache, texture units
  - <u>Six</u> 32-wide SIMD units (192 total, single precision)
  - Up-to 64 warps simultaneously (<u>hardware</u> warps) Like hyper-threading, but a warp is 32-wide SIMD
  - Most transistors used for floating point operations
- Optimal number of FLOPS per clock cycle:
  - 32x: 32-way SIMD
  - 2x: Fused multiply add
  - 6x: Six SIMD units per core
  - 15x: 15 cores
  - Sum: 5760!



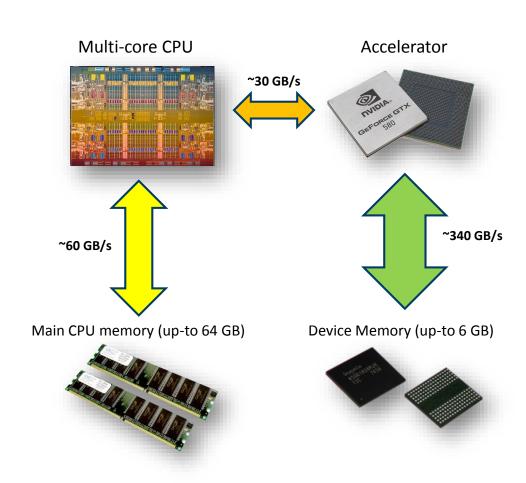
Simplified schematic of GPU design



### Memory transfers

- Accelerators are connected to the CPU via the PCI-express bus
  - Slow: 15.75 GB/s each direction

- Accelerator memory is limited but fast
  - Typically on the order of 10 GB
  - Up-to 340 GB/s!
  - Fixed size, and cannot be expanded with new dimm's (like CPUs)





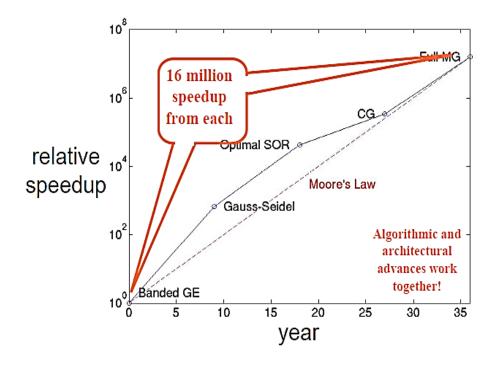
# Parallel algorithm design



## Why care about computer hardware?

 The key to performance, is to consider the full algorithm and architecture interaction.

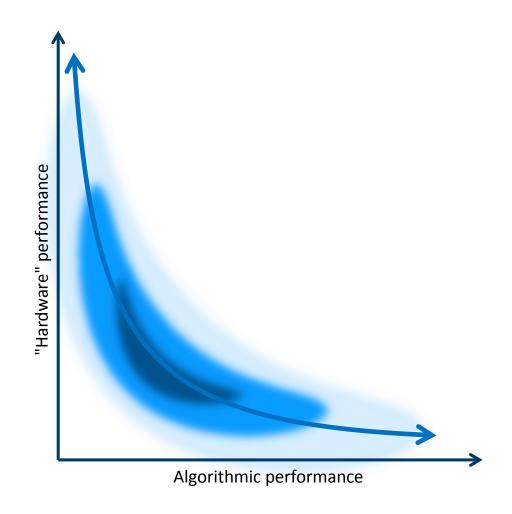
 A good knowledge of <u>both</u> the algorithm <u>and</u> the computer architecture is required.





### Algorithmic and numerical performance

- Total performance is the product of algorithmic and "hardware" performance
  - Your mileage may vary: algorithmic performance is highly problem dependent
- Many algorithms have low "hardware" performance
- Only able to utilize a fraction of the capabilities of processors, and often worse in parallel
- Need to consider both the algorithm and the architecture for maximum performance



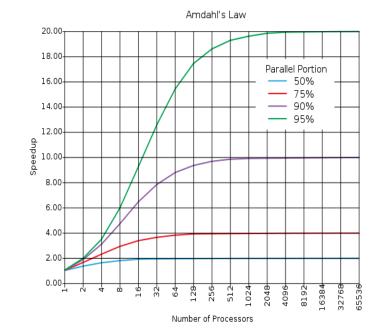


## Parallel considerations 1/4

- Most algorithms contains a mixture of work-loads:
  - Some serial parts
  - Some task and / or data parallel parts

### Amdahl's law:

- There is a limit to speedup offered by parallelism
- Serial parts become the bottleneck for a massively parallel architecture!
- Example: 5% of code is serial: maximum speedup is 20 times!



$$S(N) = \frac{1}{(1-P) + \frac{P}{N}}$$

S: Speedup

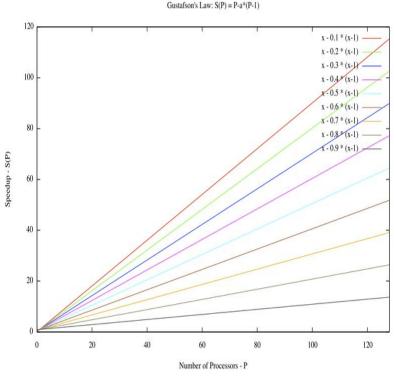
P: Parallel portion of code

N: Number of processors

## Parallel considerations 2/4

### Gustafson's law:

- If you cannot reduce serial parts of algorithm, make the parallel portion dominate the execution time
- Essentially: solve a bigger problem to get a bigger speedup!

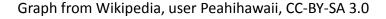


$$S(P) = P - \alpha \cdot (P - 1).$$

S: Speedup

P: Number of processors

 $\alpha$ : Serial portion of code

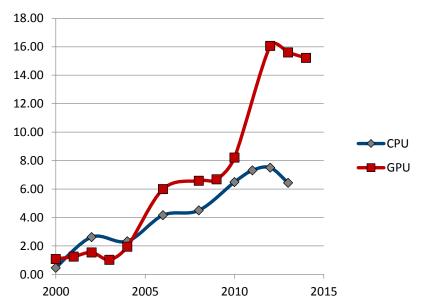




## Parallel considerations 3/4

- A single precision number is four bytes
  - You must perform over 60 operations for each float read on a GPU!
  - Over 25 operations on a CPU!
- This groups algorithms into two classes:
  - Memory bound
     Example: Low order finite volume
  - Compute bound
     Example: High order finite volume
- The third limiting factor is latencies
  - Waiting for data
  - Waiting for floating point units
  - Waiting for ...

#### **Optimal FLOPs per byte (SP)**





## Parallel considerations 4/4

- Moving data has become the major bottleneck in computing.
- Downloading 1GB from Japan to Switzerland consumes roughly the energy of 1 charcoal briquette<sup>1</sup>.



- A FLOP costs less than moving one byte<sup>2</sup>.
- Key insight: <u>flops are free</u>, <u>moving data is expensive</u>

<sup>1</sup> Energy content charcoal: 10 MJ / kg, kWh per GB: 0.2 (Coroama et al., 2013), Weight charcoal briquette: ~25 grams <sup>2</sup>Simon Horst, Why we need Exascale, and why we won't get there by 2020, 2014



Lessons learned from working with multi- and many-core processors



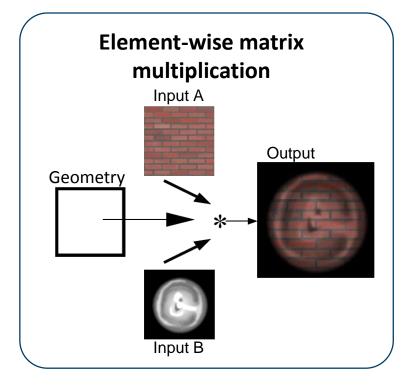
Ca 2005: GPUs with OpenGL: GPGPU



# **Early Programming of GPUs**

- GPUs were first programmed using OpenGL and other graphics languages
- Mathematics were written as operations on graphical primitives
- Extremely cumbersome and error prone



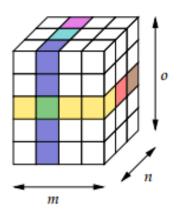


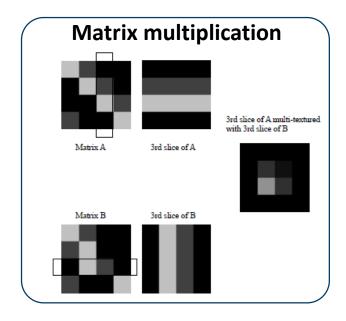


## Matrix-matrix multiplication with OpenGL

 Larsen & McAllister demonstrated that using GPUs through non-programmable OpenGL could be faster than using ATLAS [1]

- Their algorithm was "simple"
  - Matrix-matrix multiplication dots row i of matrix A with column j of matrix B to produce element (i, j)
  - We can formulate this product for a virtual cube of processors
    - Processor (m, n, 0) computes the product A[m, n]\*B[n, o]
    - By summing along the o dimension, the matrix product is complete.
  - L&M used textures and blending to implement the virtual cube of processors algorithm



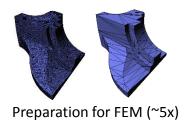


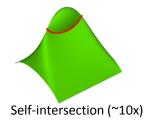
[1] Fast matrix multiplies using graphics hardware, Larsen and McAllister, 2001

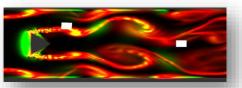


### Examples of Early GPU Research at SINTEF





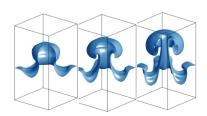




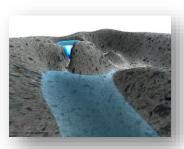
Fluid dynamics and FSI (Navier-Stokes)



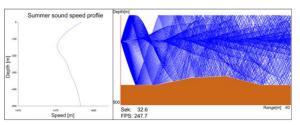
Inpainting (~400x matlab code)



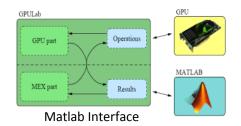
Euler Equations (~25x)



SW Equations (~25x)

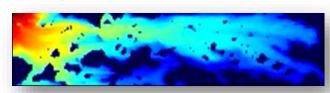


Marine aqoustics (~20x)





Linear algebra



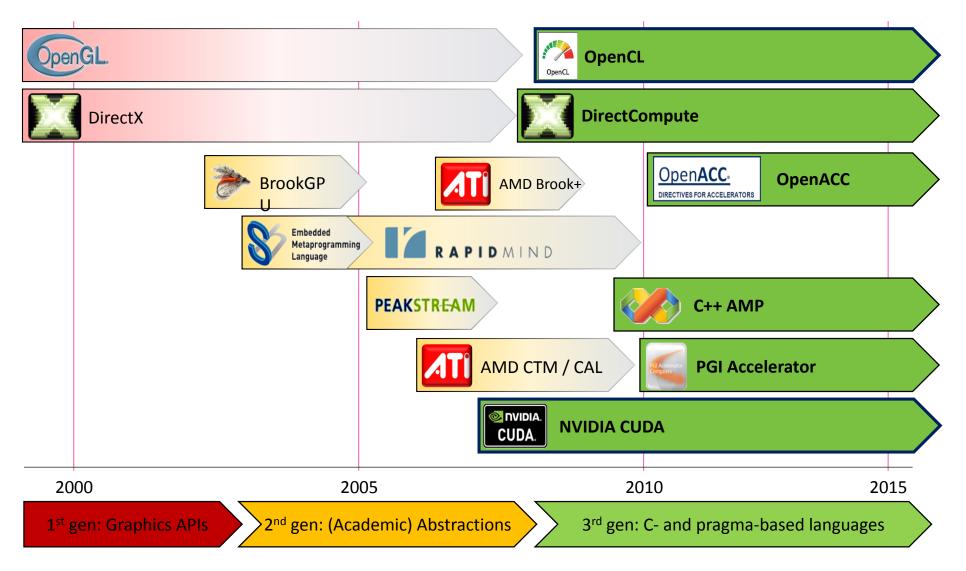
Water injection in a fluvial reservoir (20x)



Ca 2007: CUDA and mature programming languages



### **GPU Programming Languages**



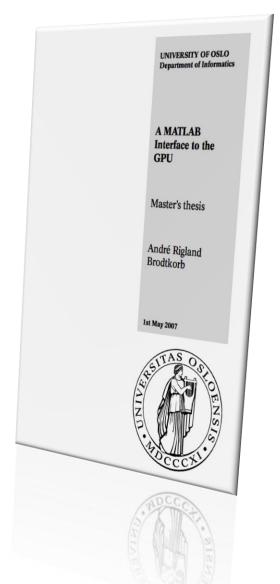


## My first encounter with CUDA

• May 1st 2007: I handed in my masters thesis.

• June 15th 2007: I hold the oral presentation and receive my grade.

June 23rd 2007: CUDA was released officially.
 Most of my thesis was officially obsolete.





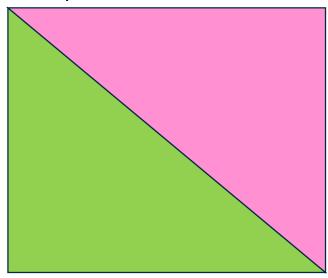
### **NVIDIA CUDA**

- CUDA solved the major problems with OpenGL
  - Unstable driver and different results on different hardware (it will only run on NVIDIA)
  - Uncomfortable implementation regime
- We could now program in a C-like language
- Rapid development of a whole range of new applications
- A huge interest for GPUs emerged
- The first versions, however, had the same amount of compiler bugs as OpenGL



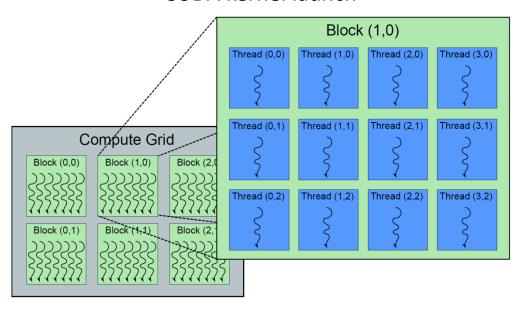
### The benefit of CUDA

OpenGL "Kernel launch"



- Render primitives that cover part of the screen that represents your computational domain
- The shader which colours the pixel performs the wanted calculation

#### **CUDA** kernel launch



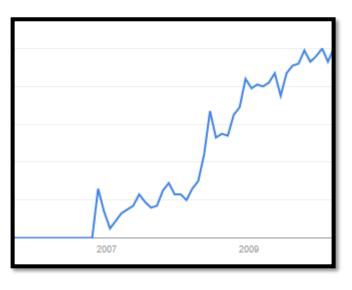
- "Pixels" are still the underlying primitive, but now we execute a grid of blocks.
- Each block runs independently, but threads within a block can collaborate



### **CUDA** fever

- CUDA became a superstar in the academic camp "over night".
- Within 2010, there were over 1000 demos, papers, and commercial applications using CUDA on the CUDA Showcase.
- AMD tried countering with Close-to-the-metal (assemly for AMD GPUs) and Brook+, but none recieved any noticeable attention.

#### Google search trends





## **Exploring CUDA**

- CUDA sparked a whole new range of research articles on GPUs
- Hardware exploration
- How was texture memory laid out?
- How large were the different caches?
- Would it be better to use more registers and less shared memory or not?
- Is more threads always better?

- Massive focus on memory movement
  - Coalesced reads and writes
  - Cached versus non-cached reads
- Texture reads versus cached reads
- Low-hanging fruit was rapidly picked
  - More and more articles solved real-world problems
  - Proof-of-concept slowly became less interesting



Ca 2014: High-level GPU with Jupyter and pyopencl



### OpenCL

- OpenCL is much like CUDA, but slightly more cumbersome to work with.
  - The benefit is that the same code can run on Intel CPUs, the Xeon Phi, NVIDIA GPUs, AMD GPUs, etc.

- The amount of code needed to do the exact same thing is larger in OpenCL
  - OpenCL is a C API
  - CUDA has C++ bindings, and supports templates







## Jupyter and Pyopencl

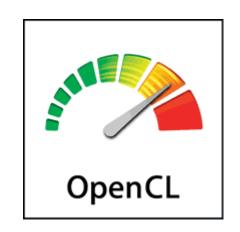
 OpenCL is a C API, which requires working in C, and possibly long compilation times



• Even the simplest OpenCL example requires a lot of boilerplate code

Pyopencl solves this, by enabling access to OpenCL through Python

• Jupyter (previously ipython) notebook gives us an interactive shell to try out OpenCL and prototype!



# Demo of iPython and Pyopencl

• If time permits



# Summary



### Summary

- We need to consider parallelism when designing and implementing algorithms
  - We cannot afford to waste most of the true potential
- GPU computing has never been easier
  - Getting good performance still requires knowledge of the architecture
- GPUs have been a success story in many fields
  - Its widespread availability, low cost, and "easy" programming model has made it a success, where other parallel architectures have failed
  - A 10 times performance improvement possible



## Thank you for your attention!

André R. Brodtkorb

Email: <u>Andre.Brodtkorb@sintef.no</u>

Homepage: <a href="http://babrodtk.at.ifi.uio.no/">http://babrodtk.at.ifi.uio.no/</a>

