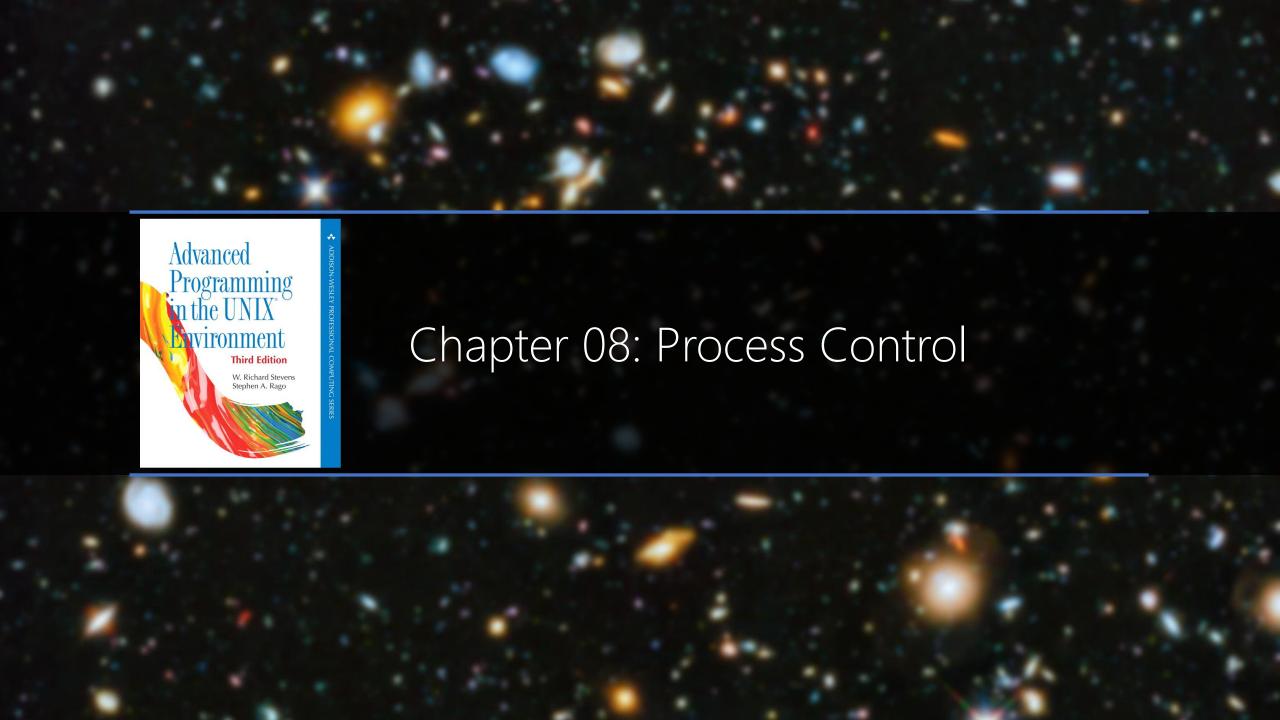
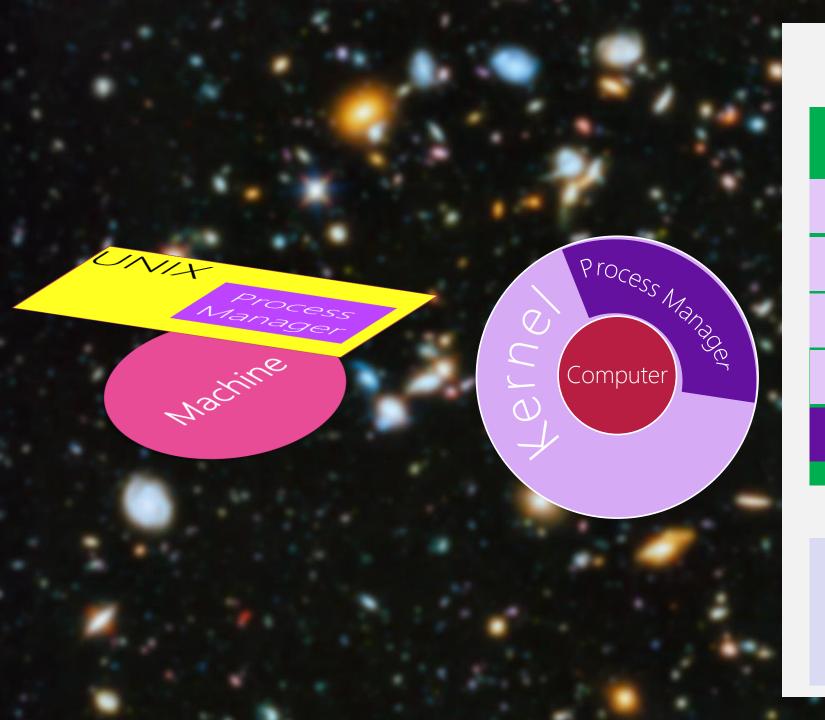


Lab09 and Lec09 is out!

Marks and Keys for Lab06 and Lec06 is out! Keys for Lab04 and Lec04 is out!





Computer

Memory

Kernel: Device Manager

Kernel: Memory Manager

Kernel: File Manager

Kernel: Network Manager

Kernel: Process Manager

Bus

Processor



Multiprocessing aka multiprogramming

Single Processor Multiprocessor

Whether Busy Waiting or HALT Waste of Processor

Waste of Processor

Share it with another process

Processor Sharing → Time Sharing/Slicing

Single Processor Multiprocessor

It's not that simple, tho! Process Context Switch



Magnus Carlsen







Hikaru Nakamura







Creating a New Process

Creating a New Process System Calls: fork() in unistd.h

```
#include <unistd.h>
pid t fork(void);
```

Returns: 0 in child, PID of child in parent, -1 on error

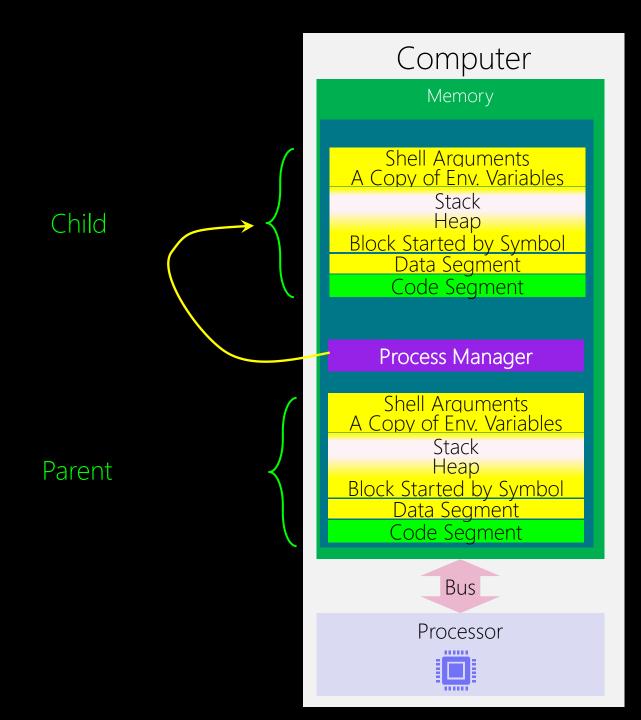
Parent vs. Child Process

System Calls: fork() in unistd.h

Only an existing process can create a new process. Because somebody should do the system call!

Computer Memory Process Manager Shell Arguments A Copy of Env. Variables Stack Heap Block Started by Symbol Data Segment int child_pid = fork(); Code Segment Bus Processor

Exact copy at fork()



Any change by the child is in the child copy

Any change by the parent is in the parent copy

Parent

Computer

Memory

Code Segment

Process Manager

Code Segment

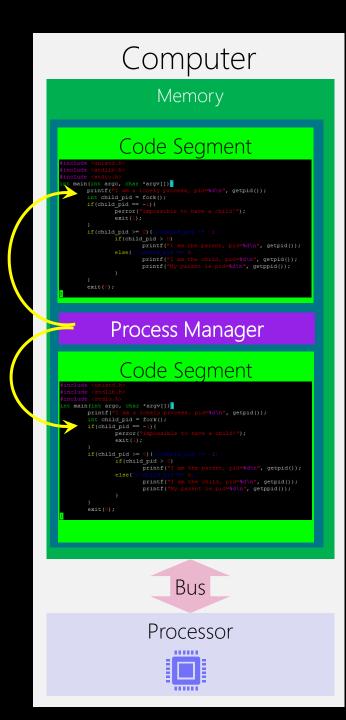
Bus

Processor



If we zoom in to the code segment, which line is the current line in child and parent?

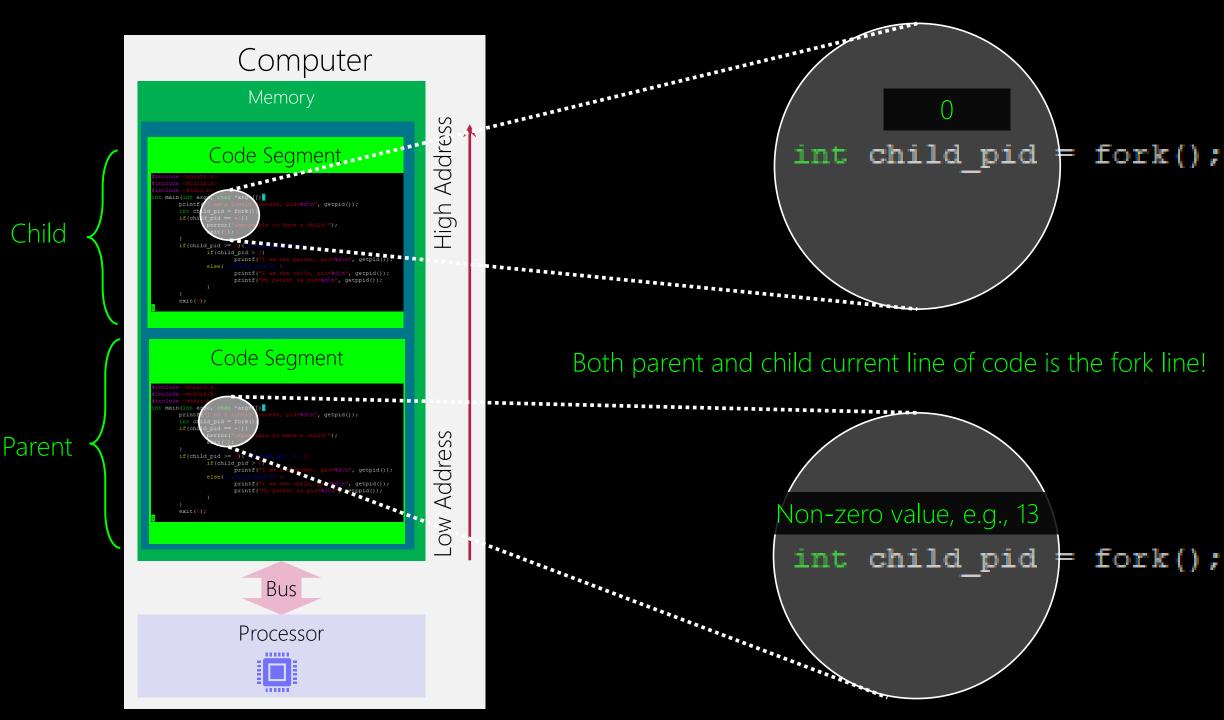
Parent



O at fork () for child

This system call is amazing as it returns two values to two different processes!

child_pid at fork() for parent



fork();

Parent Child

int child pid = fork();

13 int child_pid = fork();

> Let's be fair Give 1 time slice to each

```
int child_pid = fork();
if(child_pid == -1){
```

```
int child_pid = fork();
if(child_pid == -1){
```

Parent 13 int child_pid = fork(); if(child_pid == -1) { perror("impossible to have a child!"); exit(1); } if(child_pid >= 0) {//(child_pid != -1)}

```
int child_pid = fork();
if(child_pid == -1) {
    perror("impossible to have a child!");
    exit(1);
}
if(child_pid >= 0) {//(child_pid != -1)}
```

Parent 13 int child_pid = fork(); if(child_pid == -1) { perror("impossible to have a child!"); exit(1); } if(child_pid >= 0) {//(child_pid != -1) if(child_pid > 0)

```
int child_pid = fork();
if(child_pid == -1) {
        perror("impossible to have a child!");
        exit(1);
}
if(child_pid >= 0) {//(child_pid != -1)
        if(child_pid > 0)
```

```
Parent
int child pid = fork();
if(child pid == -1){
if (child pid >= 0) {// (child pid != -1)
        if (child pid > 0)
                printf("I am the parent, pid=%d\n", getpid());
exit(0);
```

Orphan

No Parent → Kernel Adopts the Child Child' PPID → ? What's Kernel PID?

```
int child_pid = fork();
if(child_pid == -1){
if(child_pid >= 0) {//(child_pid != -1)
       if(child_pid > 0)
        else{//(child pid == 0)
               printf("I am the child, pid=%d\n", getpid());
                printf("My parent is pid=%d\n", getppid());
exit(0);
```



Generative Model for New Process I

- A) Parent process carries the task of 1) Itself and 2) The Child
- B) Parent does the fork() to pass the child's task to the child

```
int child pid = fork();
if(child_pid == -1) {
       perror("impossible to have a child!");
       exit(1);
if(child_pid >= 0) {//(child_pid != -1)
       if (child pid > 0)
               printf("I am t
                                            =d\n", qetpid());
                            Parent's Tasks
       else{//(child pid ==
                             Child's Tasks getppid());
               printf(
exit(0);
```

Processor/Time Share/Slice

As programmer, we don't know. We should not assume anything. E.g., parent gets 20 slices/minutes, child gets 1 slice/1 minute E.g., parent gets 1 slice/minute, child gets 100 slices/10 minutes

Parent Child

int child pid = fork();

```
int child_pid = fork();
```

If parent gets higher priority ...

```
Child
```

```
int child_pid = fork();
```

```
int child_pid = fork();
if(child_pid == -1) {
    perror("impossible to have a child!");
    exit(1);
}
if(child_pid >= 0) {//(child_pid != -1)
    if(child_pid > 0)
        printf("I am the parent, pid=%d\n", getpid());
    else{//(child_pid == 0)
        printf("I am the child, pid=%d\n", getpid());
        printf("My parent is pid=%d\n", getppid());
    }
}
exit(0);
```

Orphan Child

Best Pattern/Practice

```
int child pid = fork();
if(child pid == -1){
        perror("impossible to have a child!");
        exit(1);
if (child pid >= 0) {//(child pid != -1)
        if (child pid > 0)
                printf("I am the parent, pid=%d\n", getpid());
        else{//(child pid == 0)
               printf(
                              Child's Tasks getppid());
                printf(
                exit(0);
       Parent's Tasks
exit(0); \leftarrow
```

Still there is a chance for having orphaned child. Why?

```
int child pid = fork();
if(child pid == -1){
        perror("impossible to have a child!");
        exit(1);
if (child pid >= 0) {//(child pid != -1)
        if (child pid > 0)
                printf("I am the parent, pid=%d\n", getpid());
        else{//(child pid == 0)
               printf("
                                                    getpid());
                              Child's Tasks getppid());
                printf("
                exit(0); <
```

Parent's Tasks

Wait for the child

```
exit(0); ←
```



Wait for Child Process be over

System Calls: wait() in sys/wait.h

Like HLT (HALT) to processor, kernel can also halt a process:

- Not give any processor time/slices
- It is called blocking for processes instead of halting.

Wait for Child Process be over

System Calls: wait() in sys/wait.h

```
#include <sys/wait.h>
pid_t wait(int *statloc);
```

Return Child's PID if OK, or -1 on error

Parent Child

int child pid = fork();

```
int child pid = fork();
if(child\ pid == -1){
if (child pid >= 0) {// (child pid != -1)
        if (child pid > 0)
                printf("I am the parent, pid=%d\n", getpid());
int *child exit;
wait(child exit);
```

Parent blocks

No processor share or time slice will be given

```
Parent
int child pid = fork();
                                                                 int child pid = fork();
if(child\ pid == -1){
                                                                 if(child pid == -1){
if (child pid >= 0) {// (child pid != -1)
                                                                 if (child pid >= 0) {// (child pid != -1)
        if (child pid > 0)
                printf("I am the parent, pid=%d\n", getpid());
int *child exit;
wait(child exit); 4
```

```
Child to Kernel: I am done!
Kernel to Parent: Wake up! Send a SIGCHLD + Child's Exit Status
```

Child

printf("I am the child, pid=%d\n", getpid());
printf("My parent is pid=%d\n", getppid());

if (child pid > 0)

else{//(child pid == 0)

exit(0);

```
Parent
int child pid = fork();
if(child\ pid == -1){
if (child pid >= 0) {// (child pid != -1)
       if (child pid > 0)
               printf("I am the parent, pid=%d\n", getpid());
int *child exit;
wait(child exit);
exit(0);
```

Parent become unblocked. Receive Some Share of Processor

Parent Child

int child pid = fork();

int child_pid = fork();

What if child gets higher priority?

```
Child
                            Parent
int child pid = fork();
                                                                  int child pid = fork();
                                                                  if(child\ pid == -1){
                                                                                     possible to have a child!");
                                                                          perror ("i
                                                                          exit(1);
                                                                  if (child pid >= 0) {//(child pid != -1)
                                                                          if (child pid > 0)
                                                                          else{//(child pid == 0)
                                                                                  printf("I am the child, pid=dn", getpid());
                                                                                                 rent is pid=%d\n", getppid());
                                                                                  printf("My
                                                                                  exit(0);
```

Child to Kernel: I am done! Kernel to ???, I have no sleeping parent to wakeup!

```
Child
                            Parent
int child pid = fork();
                                                                  int child pid = fork();
                                                                  if(child pid == -1){
                                                                                      possible to have a child!");
                                                                          perror("i
                                                                           exit(1);
                                                                  if (child pid >= 0) {// (child pid != -1)
                                                                          if (child pid > 0)
                                                                           else{//(child pid == 0)
                                                                                   printf("I am the child, pid=%d\n", getpid());
                                                                                                 ent is pid=%d\n", getppid());
                                                                                   printf("My par
                                                                                   exit(0);
```

Zombie

Child finishes before parent's wait ()

Child is waiting for the parent to receive the exit status.

Parent MUST have a wait(), otherwise Zombie never exits!

```
Child
                              Parent
int child pid = fork();
                                                                      int child pid = fork();
if(child\ pid == -1){
                                                                      if(child pid == -1){
                                                                                           possible to have a child!");
                                                                               perror ("i
                                                                               exit(1);
if (child pid >= 0) {// (child pid != -1)
                                                                      if (child pid >= 0) {//(child pid != -1)
        if (child pid > 0)
                                                                               if (child pid > 0)
                 printf("I am the parent, pid=%d\n", getpid());
                                                                                       printf("I am the parent, pid=%d\n", getpid());
                                                                               else{//(child pid == 0)
                                                                                       printf("I am the child, pid=%d\n", getpid());
printf("My parent is pid=%d\n", getppid());
                                                                                       exit(0);
//Assign parent tasks here
int *child exit;
wait(child exit);
```

No blocking!

Wait for nothing. The child was already done. Returns immediately with exit status of the child

```
Parent
int child pid = fork();
if(child\ pid == -1){
if(child_pid >= 0) {// (child_pid != -1)
       if (child pid > 0)
               printf("I am the parent, pid=%d\n", getpid());
int *child exit;
wait(child exit);
exit(0);
```



Example I

We want to ADD and SUB two numbers

- A) The parent does the ADD
- B) The child does the SUB

```
hfani@bravo:~$ vi fork model I.c
include <unistd.h
include <stdlib.h
#include
#include
int main(int argc, char *argv[]){
       int a = 0;
       int b = 0;
       a = atoi(argv[1]);
       b = atoi(argv[2]);
       printf("I am a lonely process, pid=%d\n", getpid());
       int child pid = fork();
       if(child pid == -1){
               perror("impossible to have a child!\n");
               exit(1);
       if (child pid >= 0) {//(child pid != -1)
               if (child pid > 0)
                       printf("I am the parent, pid=%d\n", getpid());
               else{//(child pid == 0)
                       printf("I am the child, pid=%d\n", getpid());
                       printf("child: d = d = dn, a, b, a - b);
                       exit(0);
       printf("parent: d + d = dn, a, b, a + b);
       int *child exit;
       wait(child exit);
       exit(0);
```

Generative Model for New Process II

- A) Parent process carries the task of 1) Itself and 2) A path to the task of child
- B) Parent does the fork() to create the child and pass the path to the tasks
- C) Child does the exec() to fetch the tasks (Lab08)

```
int child pid = fork();
if(child pid == -1){
       perror("impossible to have a child!");
       exit(1);
if (child pid >= 0) {//(child pid != -1)
       if(child pid > 0)
               printf("I am the parent, pid=%d\n", getpid());
       else{//(child pid == 0)
                        Path to Child's Tasks: exec (path)
               exit(0);
      Parent's Tasks
```

Wait for the child

```
exit(0);
```

Example II

We want to ADD and GCD of two numbers

- A) The parent does the ADD
- B) The child does the GCD (Great Common Devisor)

Example II

Child: Not fair! You do a simple task, but I do the task that I have no idea about. Parent: Don't worry. Hossein already have the program. Simply exec () it.

```
hfani@bravo:~$ vi gcd.c
//from https://www.javatpoint.com/gcd-of-two-numbers-in-c <
#include <stdio.h>
                                   Even Hossein may not know how to calculate GCD!
#include <stdlib.h>
#include <unistd.h>
int main(int argc, char *argv[])
    int nl = atoi(argv[1]);
    int n2 = atoi(argv[2]);
    int i, gcd;
    for( i = 1; i <= n1 && i <= n2; ++i)
        if (nl % i ==0 && n2 % i == 0)
            qcd = i; /* if nl and n2 is completely divisible by i, the divisible number will be the
    printf ("PID: %d => gcd of %d and %d is %d\n", getpid(), nl, n2, gcd);
    return 0;
hfani@bravo:~$ ./gcd 105 200
PID: 3359754 => gcd of 105 and 200 is 5
```

```
hfani@bravo:~$ vi fork model II exec.c
#include
#include
#include
#include
int main(int argc, char *argv[]) {
       printf("I
                                 ess, pid=%d\n", getpid());
       int child pid = fork();
       if(child pid == -1){
               perror("impossible to have a child!\n");
               exit(1);
       if (child pid >= 0) {// (child pid != -1)
               if (child pid > 0)
                       printf("I am the parent, pid=%d\n", getpid());
               else{//(child pid == 0)
                       printf("I am the child, pid=%d\n", getpid());
                       int fd = open("./gcd", O_RDONLY);
                       printf("fd of gcd: %d\n", fd);
                       char *newargv[] = {"./gcd", argv[1], argv[2], NULL};
                       char *newenviron[] = {NULL};
                       int res = fexecve(fd, newargv, newenviron);
                       printf("%d\n", res);
                       exit(0);
       int a = 0;
       int b = 0;
       a = atoi(argv[1]);
       b = atoi(argv[2]);
       printf("parent: d + d = d\n", a, b, a + b);
       int *child exit;
       wait(child exit);
       exit(0);
```

```
else{//(child pid == 0)
           printf("I am the child, pid=%d\n", getpid());
           int fd = open("./gcd", O RDONLY);
           printf("fd of gcd: %d\n", fd);
           char *newargv[] = {"./gcd", argv[1], argv[2], NULL}
           char *newenviron[] = {NULL};
           int res = fexecve(fd, newargv, newenviron);
           printf("%d\n", res);
           exit(0);
                                                                                 ranigoravo: vi fork model II exec.c
                                                                                    t child_pid = fork();
                                                                                        char *newargv[] = {"./god", argv[1], argv[1], MULL);
char *newenviron[] = {WULL};
                                                                                        nt res = fexecve(fd, newardy, newenviron)
   Look at Lab08 ...
```

```
hfani@bravo:~$ ./fork_model_II_exec_105_200
I am a lonely process, pid=3370346
I am the parent, pid=3370346
parent: 105 + 200 = 305
I am the child, pid=3370347
fd of gcd: 3
PID: 3370347 => gcd of 105 and 200 is 5
```

```
hfani@bravo:~$ ./fork model II exec 105 200

I am a lonely process, pid=3370346

I am the parent, pid=3370346

parent: 105 + 200 = 305

I am the child, pid=3370347

fd of gcd: 3

PID: 3370347 => gcd of 105 and 200 is 5
```

The child embed the program file inside itself Not as a separate process, but as itself!

Computer Memory Shell Arguments A Copy of Env. Variables Stack Child Heap Block Started by Symbol Data Segment Code Segment Process Manager Shell Arguments A Copy of Env. Variables Stack Heap Parent Block Started by Symbol Data Segment Code Segment

Bus

Processor



Child

Parent

Computer

Memory

Code Segment

Process Manager

Shell Arguments A Copy of Env. Variables Stack Heap Block Started by Symbol Data Segment

Bus

Code Segment

Processor



Child does exec (path)

Computer Memory Process Manager Shell Arguments A Copy of Env. Variables Stack Heap Block Started by Symbol Data Segment Code Segment Bus Processor

Child

Parent

Child does exec (path)

Kernel empty the child space

Child

Parent

Computer

Memory

A Copy of Env. Variables
Stack
Heap
Block Started by Symbol
Data Segment
Code Segment

Process Manager

Shell Arguments
A Copy of Env. Variables
Stack
Heap
Block Started by Symbol
Data Segment
Code Segment

Bus

Processor



Child does exec (path)

Kernel empty the child space Kernel fills it with the program file in path.

> No new process! No new PID!



Process Life Cycle Process States