

N1 Manual

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# Revision History

Date	Change	
March 21, 2019	Initial release	
March 22, 2019	Changed encoding of ALU operands (see Table 2-1 and Table 4-1)	
April 17, 2019	Fixed some copy & paste errors	
April 26, 2019	Fixes and a description of the branch condition in	
April 20, 2019	Section 2.4 "Conditional Branches"	
May 6, 2019	Added input pbus_rty_i	
Way 0, 2019	Corrected and specified reference point for relative addresses	
May 7, 2019	Changed definition of reference point for relative addresses	
October 14 2019	Added Section 3 "Instruction Set Extensions"	
October 14 2019	Updated Section 7.1 "Integratation Parameters"	
November 11, 2022	Fixed typos	
November 11, 2022	Started chapter Section 8 "Architecture Description"	
January 4, 2024	Modified "Status and Control Instructions" in Figure 2-1 and	
January 4, 2024	Section 2.9 "Function Register Access"	
	Extended sections Section 2.7 "Stack Instructions" and	
February 5, 2024	Section 3.1 "ROT Extension", including a description of the stack underflow	
	detection	

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## 1 Overview

The N1 is a 16-bit stack machine, targeted for low-end FPGA applications. Its instruction set and architecture are designed for efficient execution of Forth code. Here is a summary of the N1's characteristics:

#### Memory connection:

- 16-bit Von-Neumann-Architecture
- Separate address space for stack content
- Wishbone interfaces to main and stack memory
- Up to 128KB (main) memory space
- Memory addressable in 16-bit entities only

#### Stacks:

- Two hardware stacks (parameter and return stack)
- Each stack consists of three segments:

#### Upper stack:

- Shift registers with selectable shift direction for each individual cell
- Fixed size
  - \* Upper parameter stack: 4 cells
  - \* Upper return stack: 1 cell

#### Intermediate stack:

- Buffer with lazy data transfers to and from the lower stack
- Configurable size

#### Lower stack:

- RAM space shared by both stacks
- Stacks grow towards each other
- Up to 128KB in size

#### Instruction set:

- Fixed instruction size of 16-bit
- Jumps and calls
  - Indirect addressing
  - Direct addressing within a 32KB window
  - Two bus cycle execution time
  - Return from calls performed concurrently with last instruction
- Conditional branches
  - Direct relative addressing within a 16KB range
  - Two bus cycles of execution time if branch is taken, one cycle if not
- Literals
  - Immediate encoding of literals between -2048 and 2047
  - Literals out of this range requre one additional instruction
- Arithmetic and logic operations
  - Single cycle ALU operations include:

- \* Sum and Difference
- \* Comparisons
- \* Signed and unsigned products
- \* Bitwise logic operations
- \* Milti-bit shifts
- Optional immediate encoding of one operand, using 5-bit encoding
- Stack operations
  - All 1024 stack transitions of the upper stack encodable
- Memory I/O
  - Indirect addressing
  - Direct addressing within a 511B window
  - Two bus cycle execution time if branch is taken, one cycle if not

#### **Exceptions:**

- Exception handler invoked by five error conditions:
  - Parameter stack overflow
  - Parameter stack underflow
  - Return stack overflow
  - Return stack underflow
  - Access violations in the (main) address space

## Interrupts:

- $\bullet$  Optional interrupt support through external interrupt controller
- Automatic interrupt acknowledge (flag clearing) supported

## 2 Instruction Set

The intent of the N1's instruction set is to map most of the essential Forth words to single cycle instructions. Figure 2-1 illustrates the instruction format.

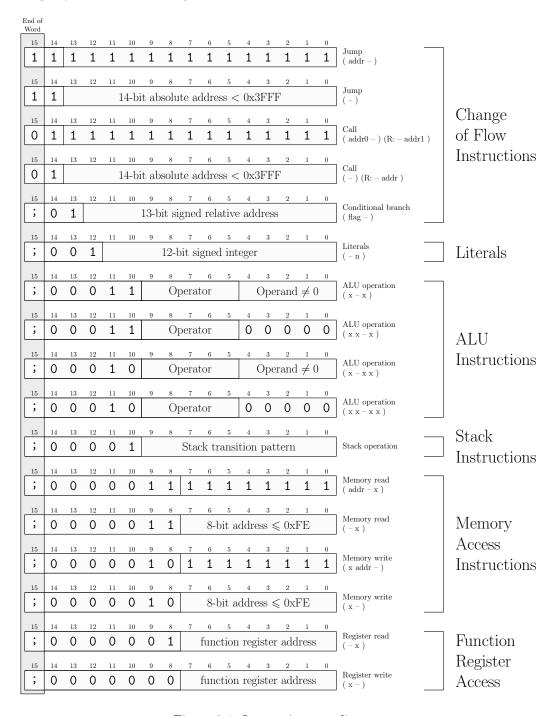


Figure 2-1: Instruction encoding

## 2.1 Return from a Call (;)

Rather than providing a dedicated instruction to end the execution of word in Forth and to return the caller's program flow, the N1 allows to perform this operation in parallel to the execution of any of its instructions. Each opcode contains a bit (bit 15) to indicate, that the current instruction is the last operation of the current word. If this bit is set, the program flow will resume at the calling word as soon as the operationis performed.

As shown in Figure 2-1, bit 15 is also distinction between the encoding of jump and of call instructions. Considering that the last call in a word definition can be optimized to a jump, bit 15 can be regarded as the termination bit for call instructions as well. For a Forth compiler, this means that the semi-colon (;) always translates to setting bit 15 of the last instruction.

## 2.2 Jump Instructions

Jump instructions transfer the program flow to any address location within the supported 128KB program space. Jump instructions consume an absolute destination address which can either be placed on the top of the parameter stack or encoded into the opcode of the instruction (only for destination addresses < 0x3FFF).

#### 2.3 Call Instructions

Call instructions temporarily transfer the program flow to any address location within the supported 128KB program space, while pushing a return address onto the return stack. Call instructions consume an absolute destination address which can either be placed on the top of the Parameter stack or encoded into the opcode of the instruction (only for destination addresses < 0x3FFF).

#### 2.4 Conditional Branches

Conditional branches invoke a change of program flow depending on the argument at the top of the parameter stack. If it is zero, then the branch is taken. The branch destination is a relative address, encoded into the opcode of the instruction in the range of  $\pm$  8KB. A relative address of value zero points to the istruction following the conditional branches.

#### 2.5 Literals

Signed integer literals of 12-bit length can be pushed onto the parameter stack within a single instruction. For larger integers a supplemental ALU instruction is required. (see encoding 11100 in Table 2-1)

#### 2.6 ALU Instructions

ALU instructions perform an operation on two cell values, resulting in a new double cell value. The result can either be placed entirely onto the parameter stack, or truncated, discarding the most significant cell. The first operand is always taken from the parameter stack. The second operand can either be taken from the parameter stack or encoded into the opcode of the instruction. In the latter case, the interpretation of the embedded 5-bit value depends on the operation. The immediate value

is interpreted as either an unsigned (uimm), a sign extended (simm), or an offsetted (oimm) integer value:

$$\begin{aligned} &uimm = \operatorname{opcode}[4:0]\\ &simm = \begin{cases} \operatorname{opcode}[4:0], & \text{if } \operatorname{opcode}[4:0] < 16\\ \operatorname{opcode}[4:0] - 32, & \text{if } \operatorname{opcode}[4:0] \ge 16\\ &oimm = \operatorname{opcode}[4:0] - 16 \end{aligned}$$

Table 2-1 lists the supported ALU operations.

Table 2-1: ALU operations

Encoding	Operation	( x1 - d )	( x1 x2 - d )
00000	Sum	x1 + uimm	x2 + x1
00001	Absolute value	oimm + ABS(x1)	x1 + ABS(x2)
00010	Difference	x1 - uimm	$x^{2} - x^{1}$
00011	Difference	oimm - x1	x1 - x2
00100	Unsigned minimum value	UMIN(x1, uimm)	UMIN(x2, x1)
00101	Signed maximum value	MAX(oimm, x1)	MAX(x1, x2)
00110	Unsigned maximum value	UMAX(x1, uimm)	UMAX(x2, x1)
00111	Signed minimum value	MIN(oimm, x1	MIN(x1 > x2)
01000	Equals comparison	x1 = uimm?	x2 = x1?
01001	Equals comparison	oimm = x1?	x1 = x2?
01010	Not-equals comparison	$x1 \neq uimm?$	$x2 \neq x1$ ?
01011	Not-equals comparison	$oimm \neq x1?$	$x1 \neq x2$ ?
01100	Unsigned lower-than comparison	x1 < uimm?	x2 < x1?
01101	Signed lower-than comparison	oimm < x1?	x1 < x2?
01110	Unsigned greater-than comparison	x1 > uimm?	x2 > x1?
01111	Signed greater-than	oimm > x1?	x1 > x2?
10000	Unsigned product	x1 * uimm	x2 * x1
10001	Unsigned product	x1 * simm	x2 * x1
10010	Signed product	x1 * uimm	x2 * x1
10011	Signed product	x1 * simm	x2 * x1
10100	Logic AND	$x1 \wedge simm$	x2 ∧ x1
10101	Logic XOR	$x1 \oplus simm$	$x2 \oplus x1$
10110	Logic OR	$x1 \lor uimm$	x2 ∨ x1
10111	Reserved		
11000	Logic right shift	$x1 \gg uimm$	$x2 \gg x1$
11001	Logic left shift	$x1 \ll uimm$	$x2 \ll x1$
11010	Arithmetic right shift	$x1 \gg uimm$	$x2 \gg x1$
11011		served	
11100	Set upper bits of a literal value	simm, x1[11:0]	simm, x2[11:0]
11101	Res	served	
11110	Reserved		
11111	Reserved		

#### 2.7 Stack Instructions

The N1's stack instruction aims at efficiently implementing common stack operations of the Forth language, while only implementing the essential data paths, which are needed for plain push and pull operations.

The opcode of the stack instruction contains a 10-bit field to specify a transition pattern of the upper cells of the parameter stack and the return stack. The structure transition pattern is shown in Figure 2-2.

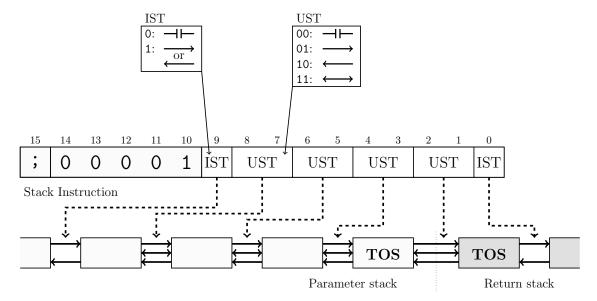


Figure 2-2: Transition encoding of stack instructions

The stack instruction contains four UST fields which control the data movement within the upper four cells of the parameter stack and the top cell of the return stack. Each UST field determines the direction of data transfer between two neighboring stack cells. Four options are selectable:

- No data transfer
- Data transfer upwards (or towards the return stack)
- Data transfer downwards (or towards the parameter stack)
- Data exchange between two stack cells

It is possible to put the UST fields into a combination which would trigger a data transfer of two source cells to a single desination cell. These combinations are reserved for instruction set extensions (see Section 3 "Instruction Set Extensions"). If no related instruction set extension is implemented, the outcome of these stack operations is undefined. In practice, the resulting data in the desination cell is then a logic OR of all sources.

The two remaining IST fields in the stack instruction control the data movement of the lower stacks. Two options are selectable:

- No data transfer
- Data shift throughout the entire intermediate stack. The direction is determined by the data movement of the lowest cell of the upper stack (see Figure 2-3).

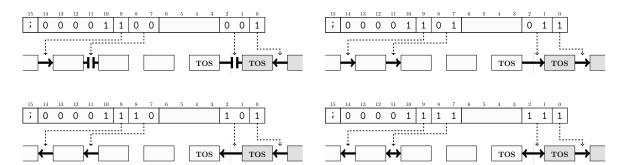


Figure 2-3: Transitions to and from the intermediate stack

#### 2.7.1 Common Stack Operations

Table 2-2 shows how common stack operations in Forth are mapped N1 instructions.

Word Opcode Description Transitions DROP 0x06A8 (x-)→ TOS TOS DUP (x-xx)TOS 0x0750 TOS (x1 x2 - x2 x1)SWAP ↔ Tos TOS 0x0418 OVER (x1 x2 - x1 x2 x1)0x0758 ↔ Tos TOS (x1 x2 - x2)NIP 0x06A0 TOS TOS ← TOS TOS 0x0750 TUCK (x1 x2 - x2 x1 x2) $\leftrightarrow$ TOS TOS 0x0460 TOS TOS0x0460 ROT (x1 x2 x3 - x2 x3 x1)↔ Tos TOS 0x0418 ↔ Tos TOS 0x0418 -ROT (x1 x2 x3 - x3 x1 x2)TOS TOS 0x0460 RDROP (R: x -)TOS TOS **←** 0x0401 TOS ← → TOS 0x0407 (R: x - xx)RDUP 0x0406 TOS 🗲 (x-) → TOS 0x06AB >R → TOS (R:-x)(-x)TOS 🗲 TOS R@ 0x0754(R: x - x)(-x)R> Tos **←** TOS 0x0755 (R:x-)→ TOS TOS 0x06A8 2DROP (x1 x2 - )→ TOS TOS 0x06A8

Table 2-2: Common stack operations

...continued

Table 2-2: Common stack operations

Word	Description	Transitions	Opcode
ODIID	( 1 0 1 0 1 0)	← ← tos Tos	0x0758
2DUP	( x1 x2 - x1 x2 x1 x2 )	Tos	0x0758
		→ Tos Tos	
2SWAP	( x1 x2 x3 x4 - x3 x4 x1 x2 )	↔ Tos Tos	0x0460
	,	Tos Tos	0x0598 0x0460
		Tos Tos	0110100
		Tos Tos	0x0780
20VER	$\left( \ x1\ x2\ x3\ x4-x1\ x2\ x3\ x4\ x1\ x2\ \right)$		0x0760 0x0460
		← ← Tos Tos	0x0798
		Tos Tos	0x0460
2NIP	( x1 x2 x3 x4 - x3 x4 )	Tos Tos	0x06A0
21111		TOS	0x06A0
		$\longrightarrow \text{Tos} \longrightarrow \text{Tos} \longrightarrow$	
		Tos tos	
	( 1 2 2 4 2 2 4 2 2 4 )	→ TOS TOS	0x046B 0x0587
2TUCK	( x1 x2 x3 x4 - x3 x4 x1 x2 x3 x4 )	TOS TOS	0x0307 0x0418
		← ← TOS ← TOS ←	0x0460
		← ← TOS ← TOS ←	0x0755 0x0755
			0110100
		Tos Tos	
		Tos Tos	
		↔ Tos Tos	0x06AB
2ROT	( x1 x2 x3 x4 x5 x6 - x3 x4 x5 x6 x1 x2 )		0x0580 0x06AB
ZNUI			0x0598
		→ Tos Tos	0x0755
			0x0598
		→ Tos Tos	0x0755 0x0598
		TOS TOS	0x0460

...continued

Word Description Transitions Opcode TOS TOS ↔ Tos TOS → TOS TOS 0x0460 ↔ Tos TOS 0x0598 -2ROT ( x1 x2 x3 x4 x5 x6 - x5 x6 x1 x2 x3 x4 ) 0x06AB  $\rightarrow$  TOS TOS 0x0598 ↔ Tos TOS 0x06AB **←** TOS **←** TOS 0x0598 0x0755↔ Tos TOS 0x0418 **←** TOS **←** TOS 0x0755 TOS TOS0x0401 (R: x1 x2 -) 2RDROP TOS TOS 🗲 0x0401 TOS 🗲 TOS Tos 🗲 → TOS 0x0755 2RDUP (R: x1 x2 - x1 x2 x1 x2)0x0757 → TOS TOS 0x06AB TOS → TOS 0x06AB → TOS TOS (x1 x2 - )0x06AB 2>R (R: -x1 x2) $\rightarrow$  Tos 0x06AB Tos **←** (-x1 x2)0x0755 2R@ (R: x1 x2 - x1 x2)TOS 0x0757 TOS TOS (-x1 x2)0x0755 2R> TOS 🗲 TOS 🗲 (R: x1 x2 - )0x0755

Table 2-2: Common stack operations

## 2.7.2 Stack Underflow Detection

The required number of arguments for a stack instruction is determined by the transition pattern (UST and IST fields). The rules listed in Table 3-2 are applied. subsubsectionCommon Stack Operations Table 2-2 shows how common stack operations in Forth are mapped N1 instructions.

Table 2-3: Rules of Stack Underflow Detection

Rule	Transitions	Description
"DROP" Rule		A cell that will be dropped (overwritten, without passing on it's content) from either direction must hold content, otherwise a stack underflow exception will be triggered.
"DUP" Rule	_ <del>-</del>	A cell that will be duplicated in either direction must hold content, otherwise a stack underflow exception will be triggered.
"SWAP" Rule	↔	Two neighboring cells that will be swapped must both hold content, otherwise a stack underflow exception will be triggered.
"Shift" Rule		Cells that will be shifted in either direction, will not be checked for content
"Cross" Rule	<b>→ → → → → → → → → →</b>	Any cell that is shifted, swapped or duplicated across the parameter stack/return stack boundary must hold content, otherwise a stack underflow exception will be triggered.

## 2.8 Memory Access Instructions

Memory access instruction perform read or write acesses to the system's 64K word (128KB) address space. Data is solely accessed in 16-bit entities. Accesses to a 255 word (510B) window in the main address space, can be done through an immediate addressing. This offers faster access to frequently used system variables.

## 2.9 Function Register Access

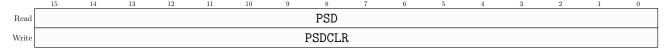
The N1 processor provides a set function registers, which provide access to a number of processor features (see Table 2-4). These function registers are read and written through special opcodes.

Table 2-4: Function registers

Address	Mnemonic	Name
0x00	PSD	Parameter Stack Depth Register
0x01	RSD	Return Stack Depth Register
0x02	EIM	Exception and Interrupt Mask Register

## 2.9.1 Parameter Stack Depth Register (PSD)

Offset: 0x00



The current depth of the parameter stack is captured in the parameter stack depth register.

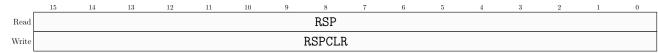
Writing 0x0000 to this register will clear the parameter stack.

Table 2-5: Parameter Stack Depth Register Bit Description

Bit	Postion	Description
PSD	150	Parameter Stack Depth Read:
		Current parameter stack depth
		Clear Parameter Stack
PSDCLR	150	Write: Writing the value 0x0000 will clrear the parameter stack. All other write accesses have no effect.

## 2.9.2 Return Stack Depth Register (RSD

Offset: 0x01



The current depth of the return stack is captured in the parameter stack depth register.

Writing 0x0000 to this register will clear the return stack.

Table 2-6: Return Stack Depth Register Bit Description

Bit	Postion	Description
RSD	150	Return Stack Depth Read: Current return stack depth.

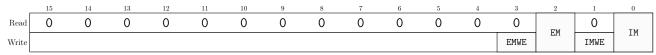
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Table 2-6: Return Stack Depth Register Bit Description

Bit	Postion	Description
		Return Stack Depth
RSDCLR	150	Write:
		Writing the value 0x0000 will clrear the return stack.
		All other write accesses have no effect.

#### 2.9.3 Exception and Interrupt Mask Register (EIM)

Offset: 0x02



Interrupt and exception handling can be disabled through two control register bits: IM (interrupt mask) and EM (exception mask). This is to avoid return stack overflows, caused by nested execution of exceptions and interrupt sevice routines.

The IM bit is automatically set when an interrupt service routine is started. The eM bit is automatically set when an exception handler is executed. Both flags mut be set manually as soon as new interrupts or exceptions can be processed. Each one of these bits is protected by a write enable bit to atomic bit manipulations.

Table 2-7: Exception and Interrupt Mask Register Bit Description

Bit	Postion	Description		
EMWE	3	Exception Mask Write Enable		
		Write: Writing a 1 allows modification of the EM bit in the same access.		
			Exception Mask	
		Read:		
EM	2	0:	Exceptions are enabled.	
		1:	Exceptions are disbled.	
		Write:		
		0:	Disable exceptions. Only possible while instantly writing a 1 to EMWE.	
		1:	Disable exceptions. Only possible while instantly writing a 1 to EMWE.	

 $\dots$ continued

Table 2-7: Exception and Interrupt Mask Register Bit Description

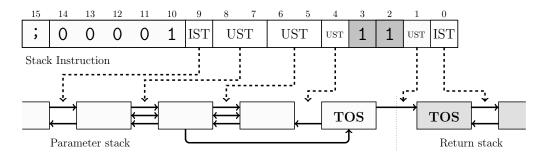
Bit	Postion	Description	
IMWE	1	Interrupt Mask Write Enable	
THWE	1	Write:	
		Writing a 1 allows modification of the IM bit in the same access.	
			Interrupt Mask
		Read:	
IEN	0	0:	Interrupts are enabled.
		1:	Interrupts are disabled.
		Write:	
		0:	Disable interrupts. Only possible while instantly writing a 1 to IMWE.
		1:	Disable interrupts. Only possible while instantly writing a 1 to IMWE.

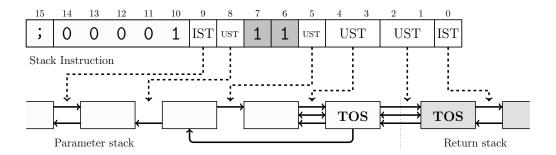
## 3 Instruction Set Extensions

The instruction set of the N1 processor (see Section 2 "Instruction Set") reserves a number of undefined opcodes for functional extensions. These extensions imply a trade-off between hardware complexity and functional improvements. They can be selected individually for each system integrating the N1 processor (see Section 7 "Integration Guide").

## 3.1 ROT Extension

The ROT extension adds two data paths to the upper stack, allowing direct data transfers between the top and the third element of the parameter stack. These new stack transitions are performed by the regular stack instructions (see Section 2.7 "Stack Instructions"), using some of the reserved stack transition patterns. Figure 3-1 illustrates the usage of the ROT extension.





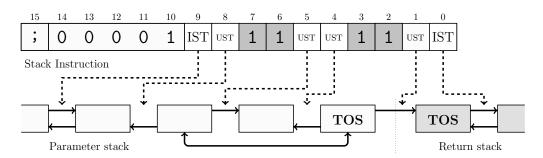


Figure 3-1: Stack transitions of the ROT extension

#### 3.1.1 Accellerated Stack Operations

The ROT extension improves the execution time and code density of the three common stack operations TUCK, ROT, and -ROT (see Table 3-1). This means that all common single-cell parameter stack operations shown in Table 2-2 can be executed in one cycle if the ROT extension is enabled.

Word Description **Transitions** Opcode TOS TOS TUCK (x1 x2 - x2 x1 x2)0x07C0 TOS TOS ROT (x1 x2 x3 - x2 x3 x1)0x041C TOS TOS -ROT (x1 x2 x3 - x3 x1 x2)0x04E0

Table 3-1: Improved stack operations

N1 processors with ROT extension are backward compatible to the ones without. All stack operations can still be executed as listed in Table 2-2, even if the ROT extension is enabled.

#### 3.1.2 Stack Underflow Detection

Rule

The ROT extension introduces three new stack underflow detection rules. These rules are listed in Table 3-2.

Rule

Transitions

Description

If the downward ROT extension path is used and the target cell is shifted further downward, then the parameter stack must hold at least two values prior to the stack operation.

For all other stack operations, which use any of the ROT extension paths and for the rest of the stack operation paths and for the rest of the r

values prior to the stack operation.

which the "TUCK" rule does not apply, the parameter stack must hold at least three

Table 3-2: Rules of Stack Underflow Detection

## 4 ANS Forth Words

The N1 processor aims at executing Forth code in an efficient way. Table 4-1 provides a list of standard ANS Forth[1] words which can be directly mapped to N1 instructions.

Table 4-1: ANS Forth words

Word	Stack	Description	Opcode
!	( x addr – )	Store x at addr	0x02FF
*	( n1 u1 n2 u2 - n3 u3 )	Multiply n1 u1 by n2 u2	0x0E00
+	( n1 u1 n2 u2 - n3 u3 )	Add n1 u1 to n2 u2	0x0C00
			0x0403
+!	( n1 u1 a-adr - )	Add n1 u1 to the cell at addr	0x03FF
			0x0C00
			0x0755
			0x02FF
_	( n1 u1 n2 u2 - n3 u3 )	Subtract n2 u2 from n1 u1	0x0C40
0<	(n-flag)	Test if n is negative	0x0DF0
0<>	(x - flag)	Test if x is not zero	0x0D70
0>	( n – flag )	Test if n is greater than zero	0x0DB0
0=	( x - flag )	Test if x is not zero	0x0D30
1+	( n1 u1 - n2 u2 )	Increment n1 u1	0x0C01
1-	( n1 u1 - n2 u2 )	Decrement n1 u1	0x0C1F
			0x0750
2!	(x1 x2 addr -)	Store x2 at addr and x1 at addr+1	0x0460
			0x02FF
			0x0C01
			0x02FF
2*	(x1 - x2)	Shift x1 one bit towards the MSB	0x0F41
2/	(x1 - x2)	Shift x1 one bit towards the LSB,	0x0F41
	,	while the MSB remains unchanged	
			0x0750
20	( addr - x1 x2 )	Fetch x2 from addr and x1 at	0x0C01
		addr+1	0x03FF
			0x0418
			0x03FF
2DROP	( x1 x2 - )	Drop cell pair x1 x2	0x06A8
			0x06A8
2DUP	( x1 x2 - x1 x2 x1 x2 )	Duplicate cell pair x1 x2	0x0758
			0x0758
20VER	( x1 x2 x3 x4 - x1 x2 x1 x2 x3 x4 x1 x2 )	Copy cell pair x1 x2 to the TOS	0x0750
ZU V ĽIL	( 11 12 10 14 11 12 11 12 10 14 11 12 )	copy cen pan XI X2 to the 105	0x0460
			0x0789
			0x0460
2>R	(x1 x2 -) (R: -x1 x2)	Shift cell pair x1 x2 to the	0x06AB
		return stack	0x06AB
2R>	$(-x1 \ x2) \ (R: x1 \ x2 -)$	Shift cell pair x1 x2 to the	0x0755
		parameter stack	0x0755

...continued

Table 4-1: ANS Forth words

Word	Stack	Description	Opcode
2R@	(-x1 x2) (R: x1 x2 - x1 x2)	Copy cell pair x1 x2 to the	0x0755
210	( X1 X2 ) (10. X1 X2 X1 X2 )	parameter stack	0x0757
			0x06AB
			0x0580
2ROT	( x1 x2 x3 x4 x4 x5 x6 - x3 x4 x5 x6 x1 x2 )	Rotate three cell pairs	0x06AB
			0x0598
			0x0755
			0x0598
			0x0755
			0x0598
			0x0460
2SWAP	( x1  x2  x3  x4  - x3  x4  x1  x2 )	Swap two cell pairs	0x0460
	( )	T	0x0598
	( ) (D 11 )		0x0460
;	( - ) (R: addr - )	Return to the calling word	0x8400
<	( n1 n2 – flag )	Test if n1 is lower than n2	0x0DA0
<b>&lt;&gt;</b>	(x1 x2 - flag)	Test if x1 is different than x2	0x0D40
=	(x1 x2 - flag)	Test if x1 equals x2	0x0D00
>	(n1 n2 - flag)	Test if n1 is greater than n2	0x0DE0
>R	(x-)(R:-x)	Shift x on to the return stack	0x06AB
?DUP	(x-0 x x)	Duplicate x if it is not zero	0x0750
: DOI	$(X \cup X )$	Duplicate X II it is not zero	0x0D30
			0x2001
@	( addr – x )	Fetch x from addr	0x06A8
ABS	( addi – x ) ( n – u )	Absolute vale of n	0x03FF 0x0C30
AND	$(x1 \ x2 - x3)$	Bitwise logic AND of x1 and x2	0x0E80
BL	$(x_1 x_2 - x_3)$ $(-\operatorname{char})$	Space character	0x0E80
CELL+	$\left(\begin{array}{c} - \operatorname{char} \right)$ $\left(\operatorname{addr} 1 - \operatorname{addr} 2\right)$	Increment addr1	0x1020
		+n is the number of cells on the	
DEPTH	( - +n )	parameter stack without +n	0x00FF
DROP	(x-)	Drop x from the /glsps	0x06A8
DUP	(x - x x)	Duplicate x	0x0750
EXECUTE	(i*x xt - j*x)	Execute xt	0x7FFF
FALSE	( - false )	FALSE flag	0x1000
		Copy the innermost loop index	
I	(-n u ) (R:n u-n u )	n u onto the parameter stack	0x0754
INVERT	(x1 - x2)	Bitwise inverse of x1	0x0EBF
J	(-n u) (R: x n u - x n u)	Copy the next-outer loop index	0x0755
J	$(-\Pi   \mathbf{u}) (\Pi \cdot \mathbf{x} \Pi   \mathbf{u} - \mathbf{x} \Pi   \mathbf{u})$	n u onto the parameter stack	0x0407
LSHIFT	( x1 u - x2 )	Shift x1 u bits towards the MSB	0x0F20
M*	( n1 n2 - d )	Multiply n1 by n2	0x0A40
M+	( n1 n2 - d )	Add n1 to n2	0x0800
MAX	(n1 n2 - n3)	n3 is the greater of n1 and n2	0x0CA0
MIN	( n1 n2 – n3 )	n3 is the lesser of n1 and n2	0x0CE0
NEGATE	( n1 - n2 )	n2 is the two's complement of n1	0x0C70

...continued

Table 4-1: ANS Forth words

Word	Stack	Description	Opcode
NIP	( x1 x2 - x2 )	Drop x1	0x06A0
OR	( x1 x2 - x3 )	Bitwise logic OR of x1 and x2	0x0EC0
OVER	( x1 x2 - x1 x2 x1 )	Copy x1 to the TOS	0x0758
R>	(-x)(R:x-)	Shift x to the parameter stack	0x0755
R@	(-x)(R:x-x)	Copy x to the parameter stack	0x0754
RSHIFT	(x1 u - x2)	Shift x1 u bits towards the LSB	0x0F00
рот	(19991 )	Detete the three terror et celle	0x0460
ROT	(x1 x2 x3 - x2 x3 x1)	Rotate the three topmost cells	0x0418
			or
			0x041C <sup>1</sup>
S>D	(n-d)	Sign-extend n	0x0A41
SWAP	(x1 x2 - x2 x1)	Swap x1 and x2	0x0418
TRUE	(-true)	TRUE flag	0x1FFF
	( 1 2 2 1 2)	G 41.1	0x0750
TUCK	$( \ x1 \ x2 - x2 \ x1 \ x2 \ )$	Copy x1 below x2	0x0460
			or
			0x07C0 <sup>1</sup>
U<	( u1 u2 – flag)	Test if u1 is lower than u2	0x0DC0
U>	( u1 u2 – flag)	Test if u1 is greater than u2	0x0D80
UM*	( u1 u2 – d )	Multiply u1 by u2	0x0A00
XOR	( x1 x2 - x3 )	Bitwise logic XOR of x1 and x2	0x0EA0

 $<sup>^1\</sup>mathrm{Requires}$  the ROT extension

## 5 Stacks

The N1 operates with two stacks: the parameter stack to perform data transactions and the return stack to manage the program flow. As illustrated in Figure 5-1, each of these stacks consists of three segments: the upper stack, the intermediate stack, and the lower stack.

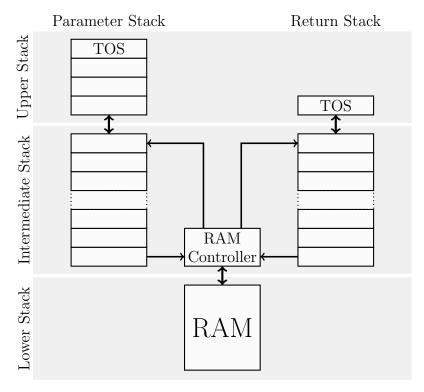


Figure 5-1: Stack Architecture

#### 5.1 Parameter Stack

The upper parameter stack holds the four topmost data entries. Its purpose is to perform stack and ALU operations (see Section 2.7 "Stack Instructions" and Section 2.6 "ALU Instructions"). When the capacity of the upper stack is exceeded, older data entries are shifted to the intermediate stack.

The intermediate stack serves as a buffer between the upper stack and the lower stack, which resides in RAM. The purpose of the intermediate stack is to minimize RAM traffic to and from the lower stack. Push operations to the intermediate stack are only propagated to the lower stack when the buffer capacity is exceeded. Pull operations are only propagated when the intermediate stack is empty. Stack fluctuations within the intermediate stack's capacity are not visible to the lower stack.

The lower stack is a region of the RAM, which is managed by a memory controller that is shared by the parameter stack and the return stack. Within the RAM, both stacks will grow towards each other. Moving cell content from one stack to the other (>R or R>) will never lead to a stack overflow.

## 5.2 Return Stack Stack

The upper stack of the return stack has the capacity of one cell. The intermediate stack and lower stack are identical to the ones of the parameter stack.

## 6 Reset, Exceptions, and Interrupts

There are three hardware mechanisms in the N1 processor, which can stop the ongoing program flow in order to react to an urgent hardware condition: Reset, Exceptions and Interrupts.

#### 6.1 Reset

A reset puts the entire sequential logic of the N1 into a defined initial state. The return stack becomes completely cleared and the parameter stack is initialized to hold exactly one cell, containing the reset indicator 0x0000 (see Table 6-1). After every reset, program execution will begin at address 0x0000. Any context of the previous program flow is lost. Resets are generated by the system's hardware and occur at least once during power-up.

#### 6.2 Exceptions

Exceptions are triggered by error conditions and allow the software to restore the functionality of the system. There are five error conditions, which can be detected by the N1 hardware:

#### Parameter stack overflow

A parameter stack overflow occurs when the capacity of the lower stack's RAM is exceeded (excluding a little margin, which is required for the error handling).

#### Return stack stack underflow

A parameter stack underflow occurs when an instruction requires more arguments than available on the stack and when a stack instruction would result in non-continuous filling of the stack.

#### Return stack overflow

A return stack overflow occurs when the capacity of the lower stack's RAM is exceeded (excluding a little margin, which is required for the error handling).

#### Return stack underflow

A return stack underflow occurs when an instruction requires more arguments than available on the return stack.

#### Address out of range

This error condition indicates a memory access to a restricted address. This can either be caused by an instruction fetch or a data access

In any of these cases, the N1 processor will push a throw code (see Table 6-1) onto the parameter stack and proceed with code execution at address 0x0000. The return stack and the lower content of the parameter stack remain untouched. The context of the previous program execution is not reserved. To avoid reoccurance of error conditions during the execution of the handler routine, excepions are temorarily disabled after detection. Exceptions must then be reenabled by a control instruction (see Table ??) when the error is resolved. The throw codes listed in Table 6-1 comply with the exception word set of the ANS Forth standard [1].

Table 6-1: Throw codes

Throw Code	Condition
0x0000 (0)	Reset
OxFFFD (-3)	Parameter stack overflow
0xFFFC (-4)	Parameter stack underflow
OxFFFB (-5)	Parameter stack overflow
OxFFFA (-6)	Parameter stack underflow
0xFFF7 (-9)	Invalid memory address

The five hardware exceptions can be easily complemented by user defined software exceptions. Software exceptions can be thrown by pushing a unique throw code onto the parameter stack and performing a jump to address 0x0000. Hardware and software exceptions can then be handled by a common exception handler routine.

## 6.3 Interrupts

Interrupts are service requests which are generated by the peripheral hardware. They cause a temporary interruption of the ongoing program flow. When an iterrupt occurs, the program counter is saved to the return stack and an interrupt service routine is executed. The location of the interrupt service routine is determined by the system's interrupt controller hardware. Further interrupts are automatically disabled during the execution of the interrupt service routine and must be manually reenabled by a control instruction (see Table ??) before resuming the interrupted program flow.

## 7 Integration Guide

This section outlines the interfaces and configurations of the N1 processor for system integration.

## 7.1 Integratation Parameters

The N1 processor supports six Verilog integration parameters to configure the design for application specific needs:

#### SP\_WIDTH

Stack pointer width.

This parameter determines the address width of the lower stack. Values in the range of 5 to 16 are valid. The default value is 12.

#### IPS\_DEPTH

Depth of the intermediate parameter stack.

This parameter determines the number of cells in the intermediate stack of the parameter stack. Any value larger than 2 is valid. The default value is 8. The purpose of the intermediate stack is to conceal fluctuations in stack usage to the lower stack. The optimal value should be derived from the application use case.

#### IPS\_BYPASS

Bypass the intermediate parameter stack.

This parameter provides the option of bypassing the intermediate parameter stack. If set to a non-zero value, the lower stack will be directly connected to the upper stack. The default value is 0.

#### IRS\_DEPTH

Depth of the intermediate return stack.

This parameter determines the number of cells in the intermediate stack of the return stack. Any value larger than 2 is valid. The default value is 8. The purpose of the intermediate stack is to conceal fluctuations in stack usage to the lower stack. The optimal value should be derived from the application use case.

#### IRS\_BYPASS

Bypass the intermediate return stack.

This parameter provides the option of bypassing the intermediate return stack. If set to a non-zero value, the lower stack will be directly connected to the upper stack. The default value is 0.

#### PBUS\_AADR\_OFFSET

Offset for direct jump or call addressing.

This parameter determines the location of the 32KB window for jumps and calls with direct addressing. The default value is 0x0000.

#### PBUS\_MADR\_OFFSET

Offset for direct data accesses.

This parameter determines the location of the 511B window for memory I/O with direct addressing. This window should cover commonly used Forth variables. The default value is 0xFFFF.

#### EXT\_ROT

Enable the ROT extension.

Recovering from an exception requires some free stack space. This parameter enables the ROT extension if set to a non-zero value. It is disabled by default.

#### 7.2 Interfaces

The N1 processor provides four interfaces which must be connected at system level. A fifth one (see Section 7.2.5 "Probe Signals") is only to be used for verification and debug purposes.

#### 7.2.1 Clock and Resets

This interface provides clocks and resets for all sequential logic in the N1 design.

#### clk\_i

Single clock input.

This clock is used for all interfaces as well as all internal sequential logic.

#### async\_rst\_i

Asynchronous reset input.

This active high reset input may assert asynchronously, but must deassert synchronously. This signal is not required if a synchronous reset (sync\_rst\_i) is implemented. If unused, this input must be tied to 0.

#### sync\_rst\_i

Synchronous reset input.

This active high reset input must assert and deassert synchronously. This signal is not required if an asynchronous reset (async\_rst\_i) is implemented. If unused, this input must be tied to 0.

## 7.2.2 Program Bus

This interface connects the N1 to the main memory. All signals comply to the Wishbone protocoll [2].

## pbus\_cyc\_o

Cycle indicator output.

This output signal corresponds to signal CYC\_O of the Wishbone specification [2].

## pbus\_stb\_o

Strobe output.

This output signal corresponds to signal STB\_O of the Wishbone specification [2].

#### pbus\_we\_o

Write enable output.

This output signal corresponds to signal WE\_O of the Wishbone specification [2].

#### pbus\_adr\_o

Address bus

These output signals correspond to bus ADR\_O of the Wishbone specification [2].

#### pbus\_dat\_o

Write data bus.

These output signals correspond to bus DAT\_O of the Wishbone specification [2].

#### pbus\_tga\_cof\_jmp\_o

Change of flow indicator.

This output signal corresponds to bus TGA\_O of the Wishbone specification [2]. It indicates, that the current bus access was caused by a jump instruction. This information may be used to trace the program flow.

#### pbus\_tga\_cof\_cal\_o

Change of flow indicator.

This output signal corresponds to bus TGA\_O of the Wishbone specification [2]. It indicates, that the current bus access was caused by either a call instruction or an interrupt service request. This information may be used to trace the program flow.

#### pbus\_tga\_cof\_bra\_o

Change of flow indicator.

This output signal corresponds to bus TGA\_O of the Wishbone specification [2]. It indicates, that the current bus access was caused by a conditional branch instruction. This information may be used to trace the program flow.

#### pbus\_tga\_cof\_eow\_o

Change of flow indicator.

This output signal corresponds to bus TGA\_O of the Wishbone specification [2]. It indicates ,that the current bus access was caused by a return from a call. This information may be used to trace the program flow.

#### pbus\_ack\_i

Acknowlede input.

This input signal corresponds to signal ACK\_I of the Wishbone specification [2]. If unused, this input must be tied to 1.

#### pbus\_err\_i

Error indicator input.

This input signal corresponds to signal ERR\_I of the Wishbone specification [2]. It informs the N1 processor, that the current address exceeds the valid range of the connected memory system. If unused, this input must be tied to 0.

#### pbus\_rty\_i

Retry input.

This input signal corresponds to signal RTY\_I of the Wishbone specification [2]. It terminates the bus cycle, indicating that the target is not ready to accept or provide new data. In contrast to asserting pbus\_stall\_i or delaying pbus\_ack\_i, the bus cycle termination via pbus\_rty\_i does not block the processor from handing interrupts. If unused, this input must be tied to 0.

#### pbus\_stall\_i

Pipeline stall input.

This input signal corresponds to signal STALL\_I of the Wishbone specification [2]. If unused, this input must be tied to 0.

#### pbus\_dat\_i

Read data bus.

These input signals correspond to bus DAT\_I of the Wishbone specification [2].

#### 7.2.3 Stack Bus

This interface connects the N1 to the stack memory. It is expected that the SP\_WIDTH parameter (see Section 7.1 "Integratation Parameters") matches the implemented memory size. Therefore no ERR\_I input is needed in this interface. All signals comply to the Wishbone protocoll [2].

#### sbus\_cyc\_o

Cycle indicator output.

This output signal corresponds to signal CYC\_O of the Wishbone specification [2].

#### sbus\_stb\_o

Strobe output.

This output signal corresponds to signal STB\_0 of the Wishbone specification [2].

#### sbus\_we\_o

Write enable output.

This output signal corresponds to signal WE\_O of the Wishbone specification [2].

#### sbus\_adr\_o

Address bus.

These output signals correspond to bus ADR\_O of the Wishbone specification [2].

#### sbus\_dat\_o

Write data bus.

These output signals correspond to bus DAT\_O of the Wishbone specification [2].

#### sbus\_tga\_ps\_o

Parameter stack access indicator.

These output signals correspond to bus TGA\_O of the Wishbone specification [2]. It indicates, that the current bus access is associated with the parameter stack.

#### sbus\_tga\_rs\_o

Return stack access indicator.

These output signals correspond to bus TGA\_O of the Wishbone specification [2]. It indicates, that the current bus access is associated with the return stack.

#### sbus\_ack\_i

Acknowlede input.

This input signal corresponds to signal ACK\_I of the Wishbone specification [2]. If unused, this input must be tied to 1.

#### sbus\_stall\_i

Pipeline stall input.

This input signal corresponds to signal STALL\_I of the Wishbone specification [2]. If unused, this input must be tied to 0.

#### sbus\_dat\_i

Read data bus.

These input signals correspond to bus DAT\_I of the Wishbone specification [2].

## 7.2.4 Interrupt Interface

This interface connects an optional interrupt controller to the N1 processor.

#### irq\_ack\_o

Interrupt acknowledge.

This output signal asserts for one clock cycle, whenever the current interrupt is serviced. It may be used for automatic flag clearing.

#### irq\_req\_i

Interrupt request.

Any non-zero value driven to this bus interface is interpreted as interrupt request. The value determines the start address of the interrupt service routine that is to be executed by the N1 processor. This bus must be tied to 0x0000 if no interrupt controller is connected.

#### 7.2.5 Probe Signals

This interface propagates all internal states of the N1 processor to the outside. It is solely intended for verification and debug purposes and should be left unconnected for system integration. The signals in this interface are specific to the internal implementation of the N1 processor and may change with every revision.

## 7.3 Target Specific Design Files

All adder and multiplier logic of the N1 design ls located in a single Verilog module called N1\_dsp. A synthesizable implementation of this module, can be found in the file rtl/verolog/N1\_dsp\_synth.v. If desired, this file can be replaced by one containing a alternative implementation of the N1\_dsp module. An example is given in in the file rtl/verolog/N1\_dsp\_iCE40UP5K.v. It contains a custom implementation for Lattice iCE40 FPGAs, utilizing four hard instantiated SB\_MAC16 macro cells.

## 8 Architecture Description

The following sections provide some descriptions of the internal N1 design.

## 8.1 Design Principles

The RTL implementation of the N1 follows a number of design principles which are captured in following sections.

#### 8.1.1 Naming Convention of Interface Signals

For all signals, which do not implement a common standard (e.g. Wishbone), the following signal naming rules are used throughout the design:

• All interface signals of a point-to-point connection, contain a mnemonic of the sending and the receiving block in its prefix. The format of the prefix is: <sender mnemonic>2<receiver mnemonic>....

Example: fc2ir\_capture

- Control signals which represent a request, end with a verb in imperative form. Example: fc2ir\_expend
- Status signals represening a busy indicator, have the postfix ...\_bsy Example: prs2fc\_bsy
- If a signal is connected to the interface of a module, a further postfix is added to indicate the signal direction:
  - Input signals: ...i
  - Output signals: ... ₋o

Example: prs2fc\_bsy\_o

• Names of signals which are only used within one design block are kept short and don't follow a particular naming convention.

#### 8.1.2 Handshaking

A high signal level of a contol signal is interpreted a request by the receiving design block. The request is expected to be immediately accepted by the receiver and processed in the next clock cycle, unless the receiver provides a busy indicator (...bsy). In this case the request in only accepted if the busy indicator was deasserted in the previous cycle.

#### 8.1.3 Instruction Boundaries

The instruction register always contains the instruction which is currently in execution. Before the execution of an instruction can ce concluded and the next one can begin, the fillowing conditions must be fulfilled:

- The program bus must be available TBD
- The parameter and the return stack must be available TBD

## 8.2 Instruction Execution Cycle

The execution cycle of the N1 processor characterized by the following design components:

#### **Program Counter**

A 16-bit register, which contains the memory location on the next instruction to be executed. It is implemented within the DSP Block.

#### Address Bus

The address output of the Program Bus (pbus\_adr\_o).

#### Read Data Bus

The read data input of the Program Bus (pbus\_dat\_i)

#### Instruction Register

A 16-bit register holding the opcode of the instruction, which is currently executed (see Section 8.3.2 "Instruction Register (ir)").

#### Instruction Stash Register

A 16-bit register to temoprarily store an upcoming opcode. (see Section 8.3.2 "Instruction Register (ir)").

The following sections show the timing relation of these design components in different execution scenarios.

#### 8.2.1 Plain Linear Execution

Most of the N1 instructuins are executed in a single clock cycle. Figure 8-1 the typical linear execution flow of single cycle instructions.

The opcode stored in the instruction register determines which instruction is currently being executed. The program counter points to the address of the next instruction. The address bus is unregistered and always runs one clock cycle ahead of the program counter. The resulting data on the read data bus is captured by the instruction register in the next clock cycle.

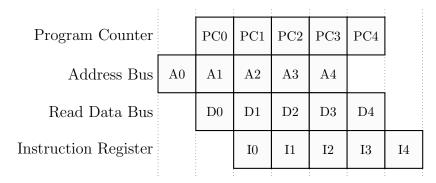


Figure 8-1: Plain Linear Execution

#### 8.2.2 Execution of Extended Instructions

In some cases the execution of an instruction can span multiple cycles (i.e. non-concurrent control instructions or any instruction waiting for a blocked stack access). Figure 8-2 illustrates the timing in these scenarios.

Whenever an opcode needs to be captured from the read data bus, but the instruction register is blocked by an instruction spaning multiple cycles, The incoming opcode needs to be temourarely stashed away in a separate register. When the execution of the ongoing instruction is finished, the stashed opcode is moved into the instruction register.

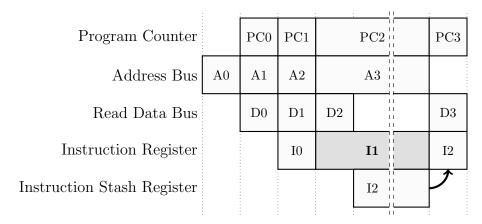


Figure 8-2: Execution of an Extended Instruction

#### 8.2.3 Execution of Memory Access Instructions

A special case of multi-cycle instructions are memory access instructions. These instructions perform their memory accesses on the program bus. Figure 8-3 illustrates how opcode fetches and data accesses are interleaved.

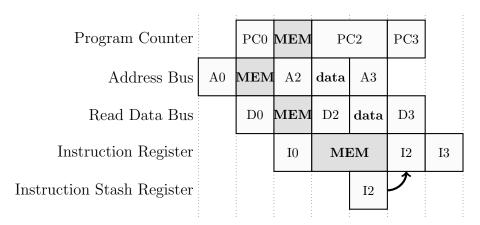


Figure 8-3: Execution of a Memory Access Instruction

#### 8.2.4 Change of Flow Instructions

TBD

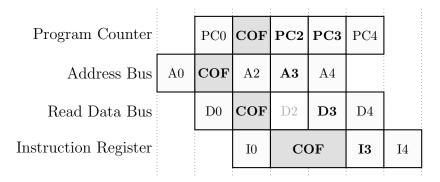


Figure 8-4: Execution of a Change of Flow Instruction

## 8.2.5 Exceptions and Interrupts

TBD

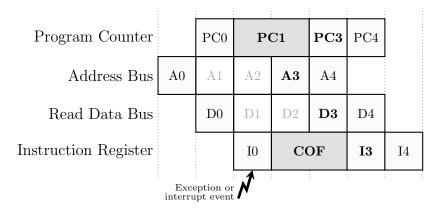


Figure 8-5: Program flow interruted by an exception - TBD

## 8.3 Design Components

The N1 architecture is divided in 11 subblocks as shown in Figure 8-6.

#### TBD

Figure 8-6: Block Diagram

#### 8.3.1 Flow Control Block (fc)

The flow control block is implemented in the Verilog module N1\_fc (N1\_fc.v). It manages the instruction cycles of the N1 core. It handles the control and resonse

signals of the program bus's Wishbone interface and it communicates with the other N1 componenents by sending requests and receiving status information. No actual data passes through the N1\_fc module. The interfaces to the N1 compunents, which are under the control of the flow control block, are explained in the following sections.

#### 8.3.1.1 Control and Status Interface to the Instruction Register

The flow control block is able to request has the following request signals to the instruction register:

#### fc2ir\_capture

Capture the program bus's read data (pbus\_dat\_i) in the instruction register at the next clock edge.

#### fc2ir\_stash

Capture the program bus's read data (pbus\_dat\_i) in the stash register at the next clock edge.

#### fc2ir\_expend

The read data input of the Program Bus (pbus\_dat\_i)

#### fc2ir\_expend

Copy the stash regiesr's content into the instruction register at the next clock cycle.

The following status signala are coming from the instruction register:

```
8.3.2 Instruction Register (ir)
8.3.3 Arithmetic Logic Unit (alu)
TBD
8.3.4 DSP Block (dsp)
TBD
8.3.5 Exception Handler (excpt)
TBD
8.3.6 Upper Stack (us)
TBD
```

8.3.7 Intermediate Parameter Stack (ips)

TBD

8.3.8 Intermediate Return Stack (irs)

TBD

8.3.9 Lower Stack (ls)

TBD

## 9 Verification Status

The implementation of the N1 design is currently still ongoing. Verification has not yet begun.

# 10 Tool Summary

One of the main goals of the N1 project is to use a design and verification flow, based on open source EDA tools. Table 10-1 summarizes the tools, used for this project.

Table 10-1: Tool Summary

Tool	Version	Usage
Verrilator[4]	3.874	Linting
Icarus Verilog[6]	0.9.7	Linting
Yosys[8]	0.7 + 627	Linting, Formal Verification
SymbiYosys[7]	Sep. 12, 2018	Formal Verification
GTKWave[3]	3.3.95	Waveform Viewer
Verilog-Perl[5]	3.418-1	Gerneration of design data for GTKWave[3]

## 11 Glossary

;

End of a word definition in Forth.

#### ALU

Arithmetic Logic Unit.

#### call

A change of the program flow, where a return address is kept on the return stack (see Section 2.3 "Call Instructions").

#### cell

A data entity within a stack.

#### conditional branch

A change of the program flow without return option, only if a certain (non-zero) argument value is given (see Section 2.4 "Conditional Branches").

#### direct addressing

Addressmode, where the address is encoded into the opcode of an instruction

#### Forth

Forth is an extensible stack-based programming language.

#### function register

A processor internal register, that provides access to a hardware feature.

#### immediate data

A data value, which is encoded into the opcode of an instruction

#### indirect addressing

Address mode, where the address ist stored on the parameter stack.

#### intermediate stack

The section of the stack that serves as a buffer between the lower stack and the upper stack. See Section 5 "Stacks".

#### IST

A bit field in the stack instruction which contols data movement on the intermediate parameter stack or return stack. The mnemonic stands for "Intermediate Stack Transition".

#### jump

A change of the program flow without return option (see Section 2.2 "Jump Instructions").

#### literal

A fixed numerical value within the program code (see Section 2.5 "Literals").

Glossary

#### lower stack

The section of the stack which is stored in RAM. See Section 5 "Stacks".

#### LSB

The least significant bit.

#### **MSB**

The most significant bit.

#### opcode

Encoding of a machine instruction. Short for "operation code".

#### parameter stack

A LIFO storage mainly for keeping call parameters and return values.

#### RAM

Random access memory.

#### relative addressing

Addressmode, where the address is given relative to the current position in the execution flow

#### return stack

A LIFO storage mainly for maintaining return addresses of calls.

## ROT extension

An optional extension of the N1 instruction set, described in Section 3.1 "ROT Extension"

#### stack

A LIFO storage.

#### throw code

A unique identifier for each type of exception.

### TOS

The top cell of a stack.

## upper stack

The section of the stack that contains the TOS. It supports reordering of its storage cell. See Section 5 "Stacks".

#### UST

A bit field in the stack instruction which contols data movement between two neighboring cells in the upper parameter stack or return stack. The mnemonic stands for "Upper Stack Transition".

Glossary

## Verilog

The harware description language used for the N1 implementation.

## Von-Neumann-Architecture

A computer architecture where intruction fetches and data  ${\rm I/O}$  occur over the same memory interface.

## Wishbone

An open bus prototocoll. see [2]

## 12 References

- [1] American National Standard for Information Systems, 1994.
- [2] Wishbone b4. http://cdn.opencores.org/downloads/wbspec\_b4.pdf, 2010.
- [3] BSI. Gtkwave. http://gtkwave.sourceforge.net.
- [4] Wilson Snyder. Verilator. http://www.veripool.org/verilator.
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- [6] Stephen Williams. Icarus verilog. http://iverilog.icarus.com.
- [7] Clifford Wolf. Symbiyosys. https://github.com/cliffordwolf/SymbiYosys.
- [8] Clifford Wolf. Yosys open synthesis suite. http://www.clifford.at/yosys.