

上海交通大学 2022 年秋季学期

《复分析》课程教学说明

一、课程基本信息

1. 任课教师: 来米加 (laimijia@sjtu.edu.cn)
2. 时间地点: 下院 205 周一、四 10: 00-11:40
3. 参考书目: 复分析: 可视化方法 尼达姆著 齐民友译
4. 办公室: 理科六号楼 725
5. Office hour: 周四 3-5pm or by appointments, email, canvas
6. 助教: 张扬 zyy2233456@sjtu.edu.cn

二、课程考核方式及说明

总评成绩=35%平时和小测+65%期末考试 (酌情调整)

三、课程大纲

- Part1: 复数的几何、复值函数、莫比乌斯变换 (第一、二、三章)
Part2: 复函数的微分、柯西黎曼方程、环绕数与拓扑学 (第四、五、七章)
Part3: 复积分及其应用 (第八、九章)
Part4: 当复分析遇见几何、拓扑、偏微分方程.... (第十、十一、十二章)

上午8:50



群二维码名片

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复分析2022秋季



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Why complex numbers?

Is Mathematics Invented or Discovered?

$$\int_{-\infty}^{+\infty} \frac{dx}{(x+1)^z} = ?$$

$$\int_0^{\infty} \frac{dt}{1+a^2 - 2at \cos t} = ?$$

Riemann-Zeta function.

$$\zeta(s) = \sum_{n=1}^{\infty} \frac{1}{n^s} = \frac{1}{1^s} + \frac{1}{2^s} + \frac{1}{3^s} + \dots$$

if $\operatorname{Re}(s) > 1$, $\zeta(s)$ converges



Prime numbers.

1. 领略复变量函数别具一格的特点

2. 提升考察问题的视野

3. 联系拓扑学、微分几何、偏微分方程，开拓思维方式

Complex numbers

\mathbb{C}

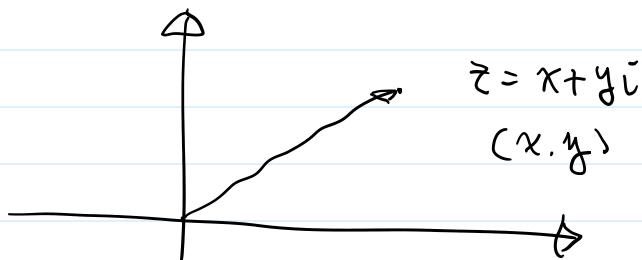
$$z = x + yi$$

$$i^2 = -1$$

$$(1+2i)(3+4i) = 3 + 6i + 4i + 8(-1) = -5 + 10i$$

$$\operatorname{Re}(z) = x$$

$$\operatorname{Im}(z) = y$$



$$x^3 = 3px + 2q$$

$$x = \sqrt[3]{\frac{q}{2} + \sqrt{\frac{q^2}{4} - p^3}} + \sqrt[3]{\frac{q}{2} - \sqrt{\frac{q^2}{4} - p^3}}$$

Q: what if

$$\frac{q^2}{4} - p^3 < 0 ?$$

$$\underline{p=5}, \underline{q=2}$$

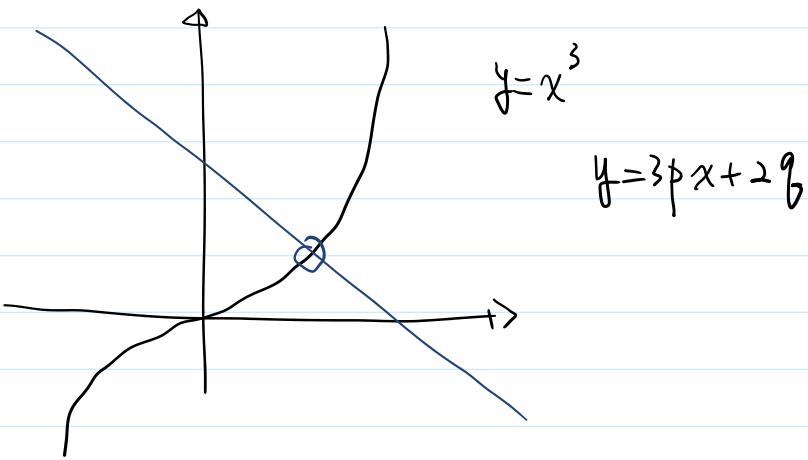
$$x = \sqrt[3]{2 + \sqrt{-121}} + \sqrt[3]{2 - \sqrt{-121}} = 2a$$

$$(a+bi)^3 = 2+11i$$

$$(a-bi)^3 = 2-11i$$

Geometric meaning of solution of

$$x^3 = 3px + 2q$$



欧拉公式

Euler formula :

$$\boxed{e^{i\theta} = \cos \theta + i \sin \theta} \quad \theta \in \mathbb{R}$$

$$\text{令 } \theta = \pi \quad e^{i\pi} = -1$$

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots \quad x \in \mathbb{R}$$

$$\text{令 } x = i\theta$$

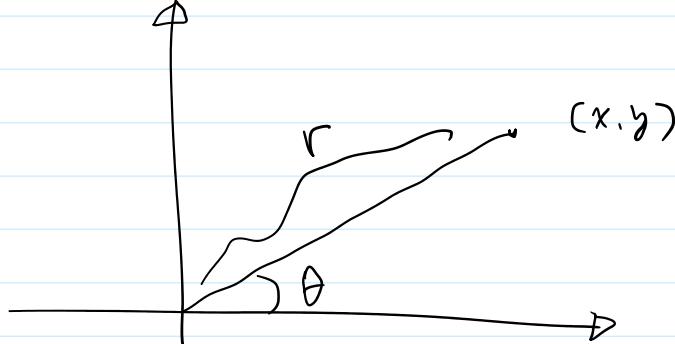
$$e^{i\theta} = 1 + i\theta + \frac{(i\theta)^2}{2!} + \frac{(i\theta)^3}{3!} + \dots$$

$$= \left(1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!} - \dots \right) + i \left(\theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} - \dots \right)$$

$$= \cos \theta + i \sin \theta$$

$$z = x + yi = r \cos \theta + r \sin \theta i = r(\cos \theta + i \sin \theta)$$

$$= r e^{i\theta}$$



$$r = |z| = \sqrt{x^2 + y^2}$$

$$\theta = \arg(z)$$

θ : Argument 角

$$\operatorname{Arg}(z)$$

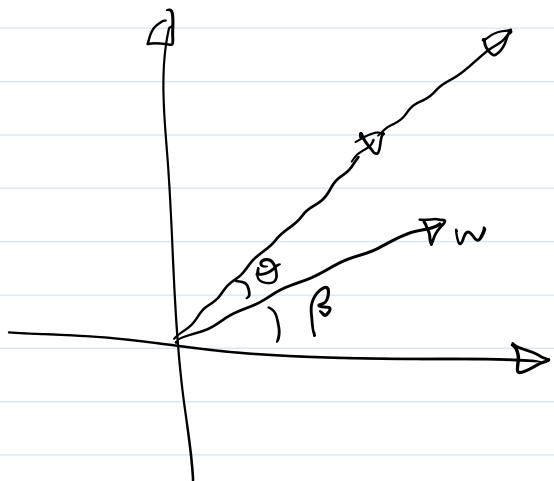
复数乘法的几何意义：

复数乘法的几何意义：

$$z \cdot w = r e^{i\theta} \cdot (s e^{i\beta})$$

$$= \underbrace{r s}_{\text{.}} e^{i(\theta+\beta)}$$

$z \cdot (\quad)$ \leftrightarrow 旋转+伸缩



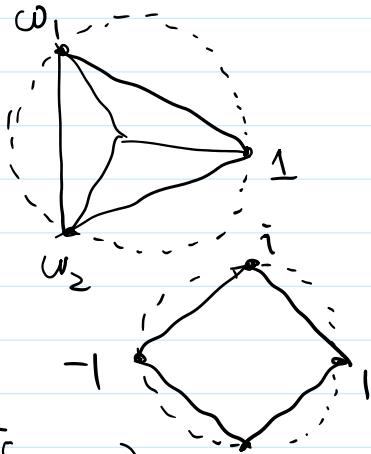
$$\int \frac{dx}{x^n - 1}$$

$$x^2 - 1 = (x-1)(x+1)$$



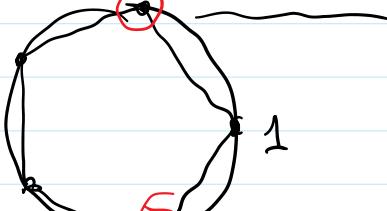
$$x^3 - 1 = (x-1)(\underbrace{x^2 + x + 1}_{\Delta}) = (x-1)(x-\omega_1)(x-\omega_2)$$

$$\omega_1 = e^{i\frac{2\pi}{3}}, \quad \omega_2 = e^{i\frac{4\pi}{3}}$$



$$x^4 - 1 = (\underbrace{x^2 - 1}_{\Delta})(x^2 + 1) = (x-1)(x+1)(x+i)(x-i)$$

$$x^5 - 1 = (x-1)(x^4 + x^3 + x^2 + x + 1) = (x-1)\left(x^2 + \frac{1+\sqrt{5}}{2}x + 1\right)\left(x^2 + \frac{1-\sqrt{5}}{2}x + 1\right)$$

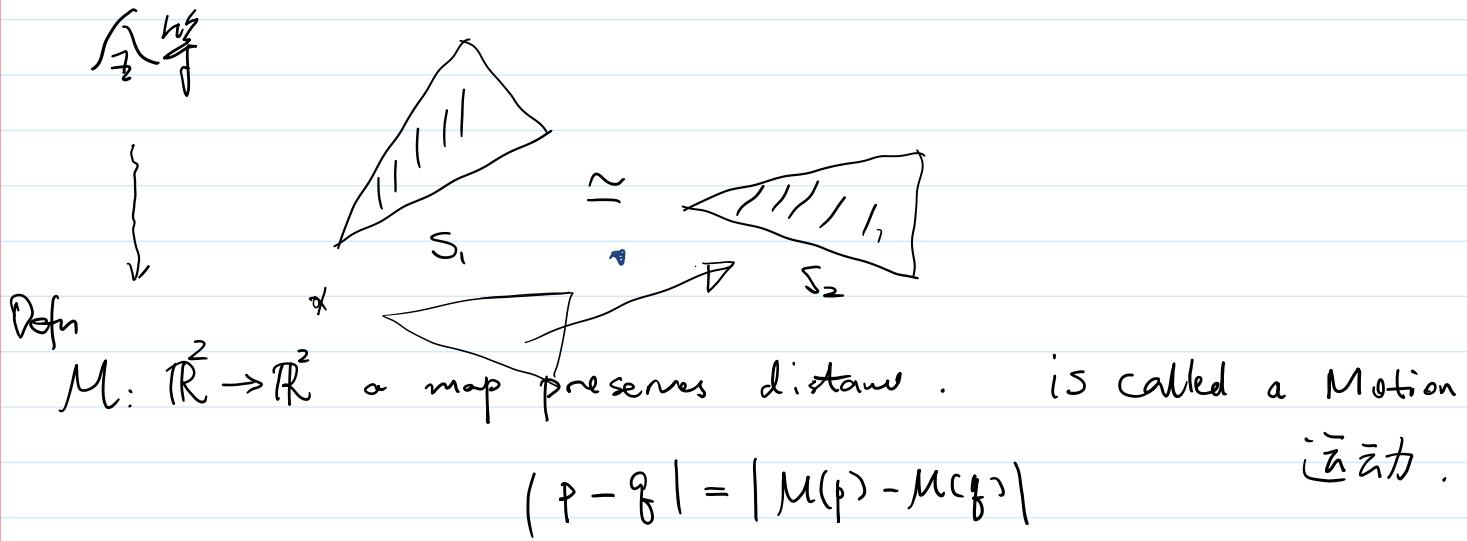


$$x^n - 1 = 0 \text{ 有 } n \text{ 个根. } \sum \omega = e^{i\frac{2\pi}{n}} \quad \omega^n = (e^{i\frac{2\pi}{n}})^n = e^{i\cdot 2\pi} = 1$$

$$x^n - 1 = (x-1)(\underbrace{x-\omega}_{\Delta})(x-\omega^2) \dots (\underbrace{x-\omega^{n-1}}_{\Delta})$$

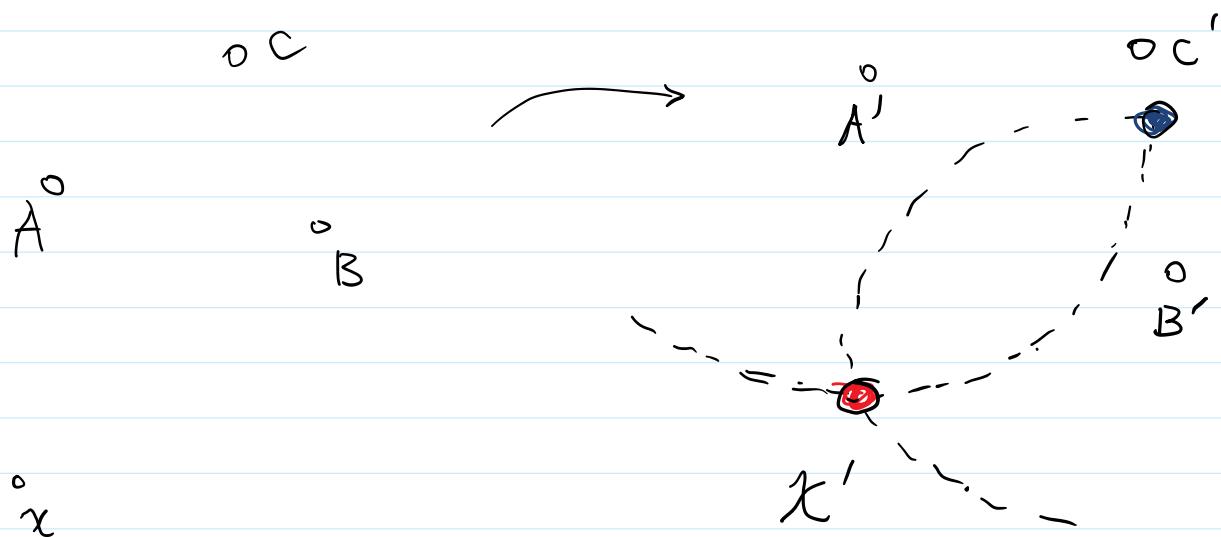
$$\begin{aligned} z &= x + yi \\ \bar{z} &= x - yi \end{aligned}$$

$$\begin{aligned} &(z - (a+bi))(z - (a-bi)) \\ &= z^2 - 2az + (a^2 - b^2) \end{aligned}$$



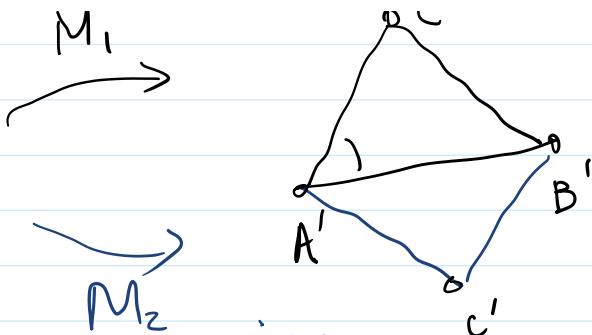
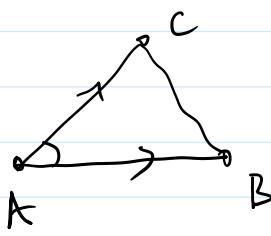
$S_1 \xrightarrow{\text{Motion}} S_2 \Leftrightarrow \exists M$ distance-preserving map s.t. $M(S_1) = S_2$.

Prop 1. A motion is uniquely determined by its action on three points not on a line.



Motion has two types:





保持方向运动

$\Rightarrow AB, AC$ 逆时针

反向运动.

$A'B' \rightarrow A'C'$
顺时针.

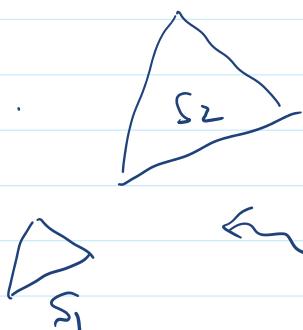
Prop 3. 保定向运动必为一旋转 或者为平移

Prop 4

$$M(z) = e^{i\theta} \cdot z + w$$

$$= e^{i\theta} \left(z + \underbrace{e^{-i\theta} w} \right)$$

本节



$\exists M: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ s.t.

$$\frac{|p-q|}{|M(p)-M(q)|} = \lambda \text{ fixed.}$$

s.t.

$$M(S_1) = S_2$$

such

M is called a 保向变换.

Prop. \forall 保向相似变换 M is of the form

$$M(z) = r \cdot e^{i\theta} z + v$$