

1. Review.

Key Fact: $T: (\mathbb{R}^2 \simeq \mathbb{C}) \mapsto (\mathbb{R}^2 \simeq \mathbb{C})$ a linear transformation of the form $T\begin{pmatrix} x \\ y \end{pmatrix} = A \cdot \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} u \\ v \end{pmatrix}$ can be written as a complex multiplication by z , $(x+yi) \cdot z = (u+vi)$, iff $A = \begin{pmatrix} a & -b \\ b & a \end{pmatrix}$, moreover $z = a+bi$.

$f: \Omega^{\text{open}} \subseteq \mathbb{C} \rightarrow \mathbb{C}$ is analytic, if $f'(z)$ exists!

$f: \Omega^{\text{open}} \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}^2$ \iff f is of the form $\begin{pmatrix} a & -b \\ b & a \end{pmatrix} = \begin{pmatrix} \partial_x u & \partial_y u \\ \partial_x v & \partial_y v \end{pmatrix}$

f is analytic $\Rightarrow f$ satisfies C-R equation.

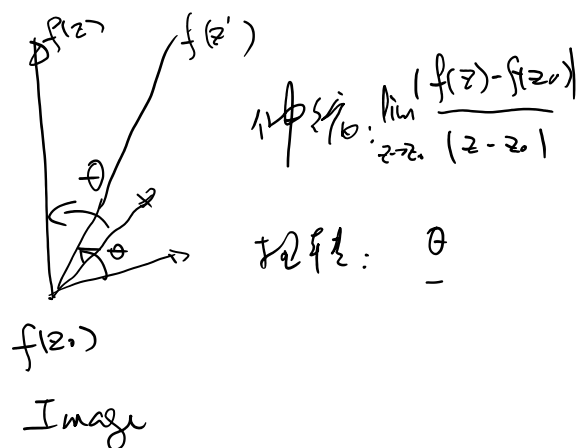
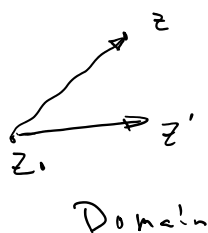
$$\boxed{\partial_x u = \partial_y v, \quad \partial_y u = -\partial_x v}$$

f is analytic $\Leftarrow f$ satisfies C-R equation + u, v continuously differentiable

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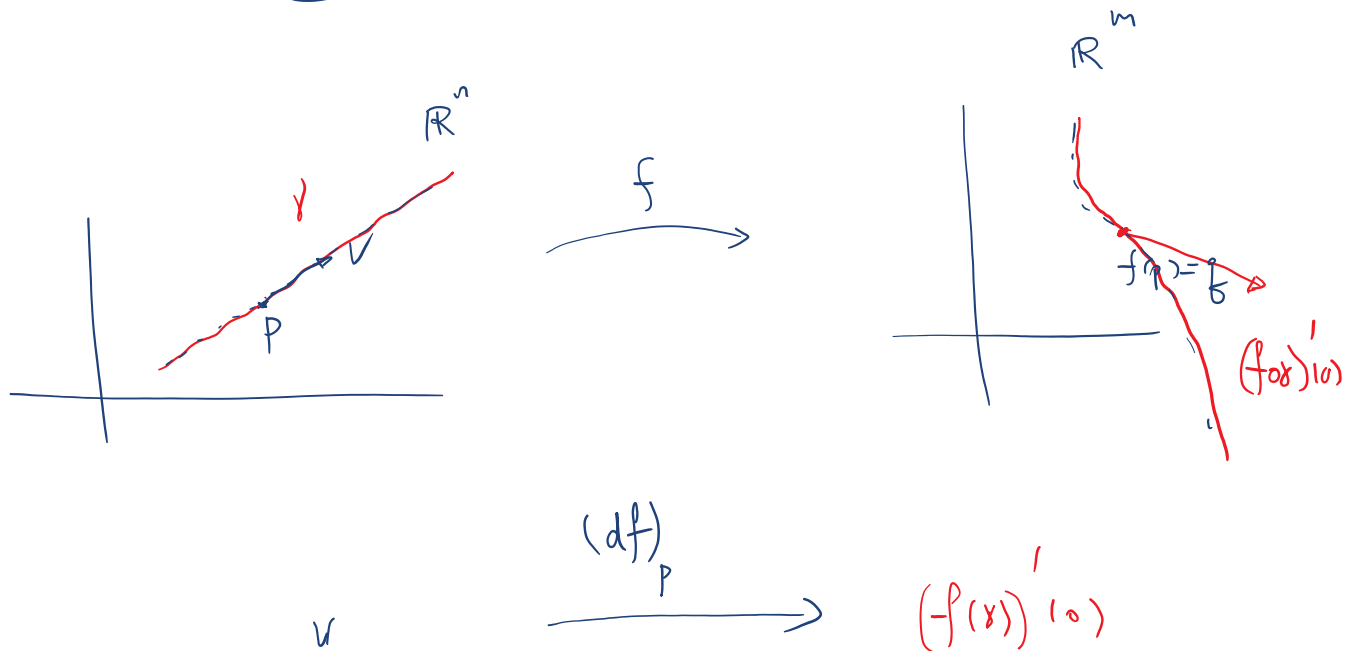
$$f(z) - f(z_0) \approx f'(z_0) \cdot (z - z_0)$$

(无'的... 无'的...)



Remark: In fact, $f'(z_0)$ can be interpreted as the differential of the map f :

$f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ smooth map.
 $(df)_p: T_p \mathbb{R}^n \rightarrow T_{f(p)} \mathbb{R}^m$ is a linear transformation
 given by $\begin{pmatrix} \nabla f \end{pmatrix}_p$.



choose γ s.t.

$$\gamma(t_0) = p, \gamma'(t_0) = v$$

Note: independent of choice of γ

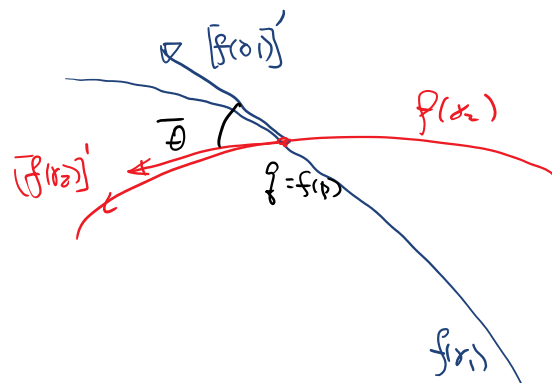
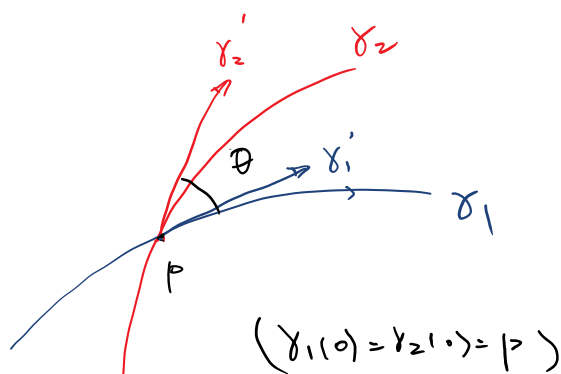
$(df)_p$ is matrix representation under canonical basis is $\begin{pmatrix} \nabla f \end{pmatrix}_p$.

2. Analytic and conformal

Prop 1. $\hookrightarrow f$ is analytic in Ω and $f'(z) \neq 0, \forall z \in \Omega$,
 then f is a conformal map.

then f is a conformal map.

[Preserves oriented angles.]



Since f is analytic \Rightarrow

$$\left. \begin{aligned} \gamma_1'(0) \cdot f'(p) &= (f \circ \gamma_1)'(0) \\ \gamma_2'(0) \cdot f'(p) &= (f \circ \gamma_2)'(0) \\ f'(p) &\neq 0 \end{aligned} \right\} \Rightarrow \theta = \bar{\theta}$$

Prop 2. If f is a conformal map: $\Omega^{\text{open}} \subseteq \mathbb{R}^2 \cong \mathbb{C} \rightarrow \mathbb{R}^2$ and differentiable, then f is analytic.

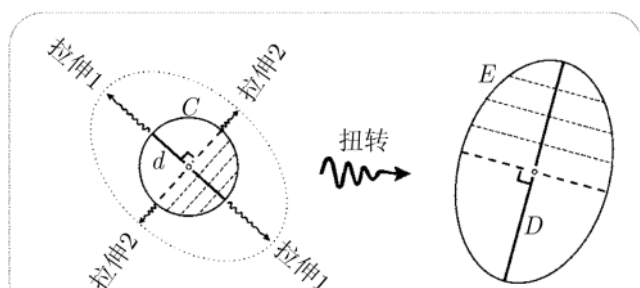
(Major conformal implies differentiable)

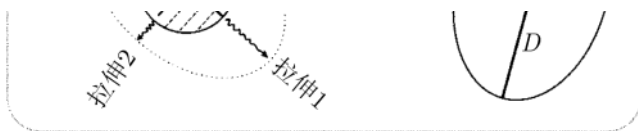
Proof: Goal: to show Jf is of the form $\begin{pmatrix} a & -b \\ b & a \end{pmatrix}$ at every point of Ω .

$$1 \text{ 保持 } \{ \hat{e}_1 \} \Rightarrow \begin{pmatrix} a & -b \\ b & a \end{pmatrix}$$

Exercise: T is a linear transformation $\mathbb{R}^2 \rightarrow \mathbb{R}^2$, and T preserves angles. i.e. $\angle v, w = \angle Tv, Tw \quad \forall v, w \in \mathbb{R}^2$.

then T must be of the form $\begin{pmatrix} a & -b \\ b & a \end{pmatrix}$.





局部线性变换

局部线性变换就是在 d 方向做一个拉伸, 在与它垂直的方向上做另一拉伸, 最后再做一个扭转. $\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \cdot \left(A \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} A^{-1} \right)$

Polar decomposition

From Wikipedia, the free encyclopedia

In mathematics, the **polar decomposition** of a square real or complex matrix A is a factorization of the form $A = UP$, where U is a unitary matrix and P is a positive semi-definite Hermitian matrix, both square and of the same size.^[1]

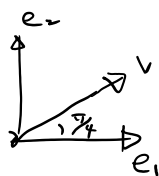
Intuitively, if a real $n \times n$ matrix A is interpreted as a linear transformation of n -dimensional space \mathbb{R}^n , the polar decomposition separates it into a rotation or reflection U of \mathbb{R}^n , and a scaling of the space along a set of n orthogonal axes.

$$A \cdot A^T = Id, \lambda_1, \lambda_2 \geq 0$$

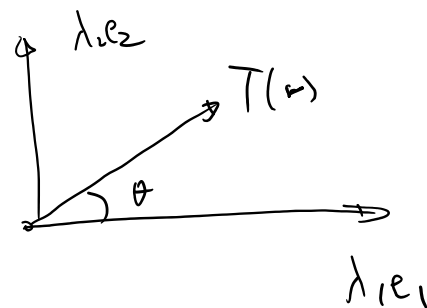
Since rotation preserves angles, we just need to show the following.
Claim: Suppose $\{e_1, e_2\}$ are orthonormal basis. $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ s.t.

$T(e_1) = \lambda_1 e_1, T(e_2) = \lambda_2 e_2$. and T preserves angles. then

$$\lambda_1 = \lambda_2$$



$$\text{let } v = \cos \frac{\pi}{4} e_1 + \sin \frac{\pi}{4} e_2$$

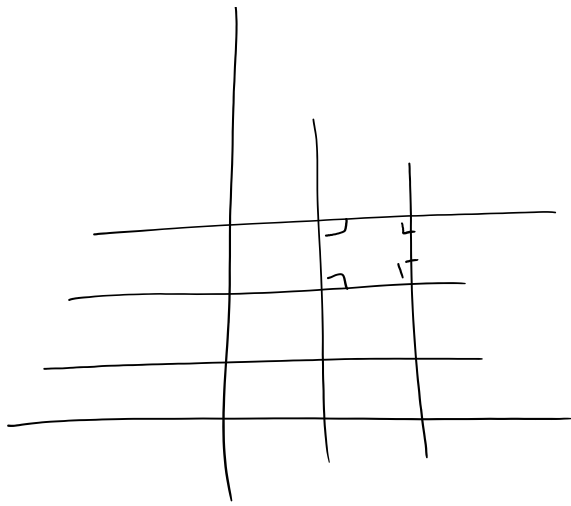


$$\text{then } T(v) = \cos \frac{\pi}{4} \lambda_1 e_1 + \sin \frac{\pi}{4} \lambda_2 e_2.$$

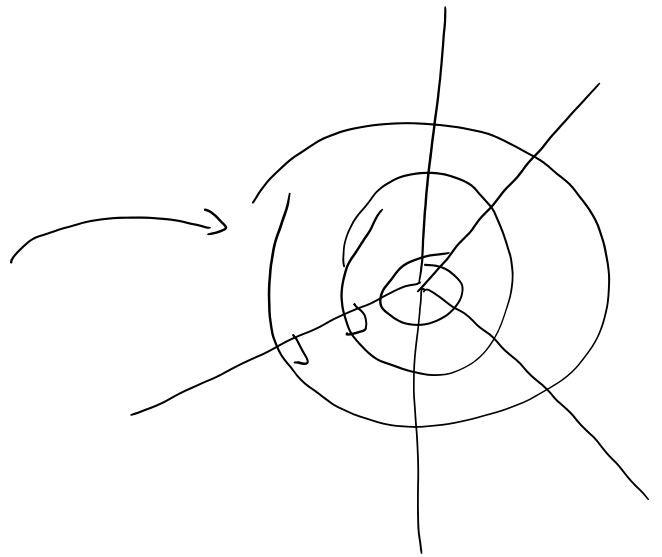
$$\text{if } \lambda_1 \neq \lambda_2 \Rightarrow \theta \neq \frac{\pi}{4} \text{ contradiction.}$$

$$\Rightarrow \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \cdot \begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix}$$

$$= \begin{pmatrix} \lambda \cos\theta & -\lambda \sin\theta \\ \lambda \sin\theta & \lambda \cos\theta \end{pmatrix} \text{ is of the form } \begin{pmatrix} a & -b \\ b & a \end{pmatrix}$$



Domain

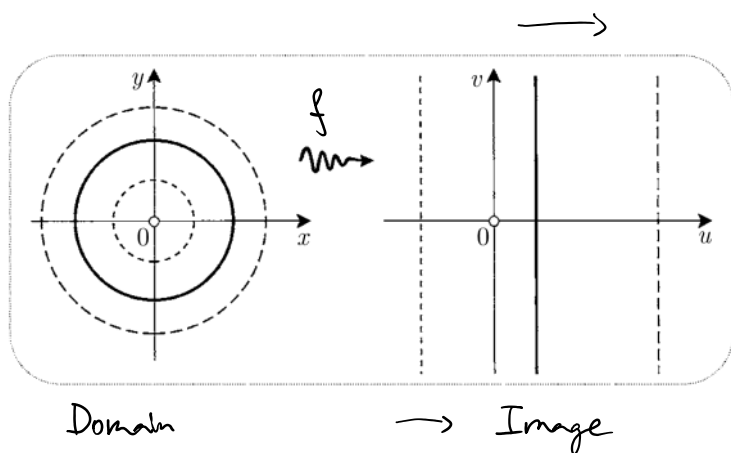


1. Rigidity coming from conformal map.

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$\mathbb{C} \rightarrow \mathbb{C}$

Suppose f is a conformal map, which maps circles centered at 0 to vertical lines, as radius of circles increases the vertical lines move to right.



\Downarrow
Can determine f !

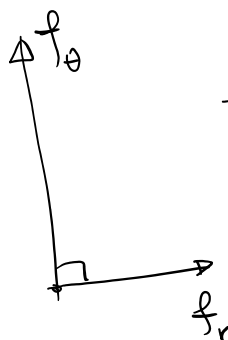
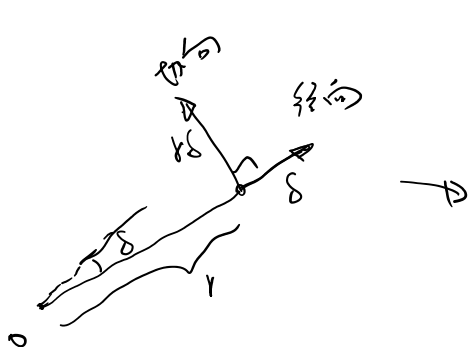
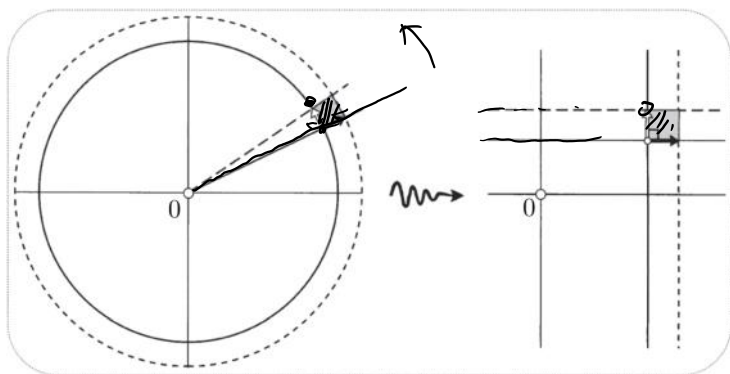
\Rightarrow radial lines mapped to horizontal lines.

• as radial lines rotates counterclockwise, horizontal lines move upward

• f conformal $\Rightarrow f$ is analytic.

\Rightarrow C-R equation. (Another version)

$$f(r, \theta) = U(r, \theta) + i V(r, \theta).$$



$$\left| f_\theta = f_r \cdot (i r) \right|$$

\Downarrow

$$(u_\theta + i v_\theta) = (u_r + i v_r)(i r)$$

$$\Rightarrow \left| u_\theta = -v_r \cdot r \right|$$

$$v_\theta = u_r \cdot r$$

• circles \rightarrow vertical lines

$\Rightarrow u_\theta = 0 \Rightarrow u$ depends on r only.

$$\begin{aligned}
 & \left. \begin{aligned} & \text{L.H.S is a function of } \theta \\ & \text{R.H.S is a function of } r. \end{aligned} \right\} \Rightarrow V_{\theta} = U_r \cdot r = C.
 \end{aligned}$$

$\Rightarrow \underline{U_{\theta} = 0} \Rightarrow U \text{ depends on } r \text{ only}$
 $\Rightarrow \text{radial lines} \rightarrow \text{Horizontal lines}$
 $\Rightarrow \underline{V_r = 0} \Rightarrow V \text{ depends on } \theta \text{ only}$

$$\Rightarrow V = c\theta + a, \quad U = c \log r + b.$$

$$\begin{aligned}
 \Rightarrow f(r, \theta) &= c \log r + b + i(c\theta + a) \\
 &= c (\log r + i\theta) + \underline{\underline{b + ai}} \\
 &= c \cdot \text{Log}(z) + c'
 \end{aligned}$$

2. Analytic continuation.

解析刚性的本质特性尽纳于以下结果中:

如果哪怕是任意小一段曲线被一解析映射挤压成为一点, 则其整个定义域也将坍缩于该点.

(2).

$$\begin{aligned}
 f(z) &= 1 + z + z^2 + z^3 + \dots + z^n + \dots \\
 &= \frac{1}{1-z}
 \end{aligned}$$

$R=1$



Domain of L.H.S. $|z| < 1$.

Domain of R.H.S. $z \neq 1$.

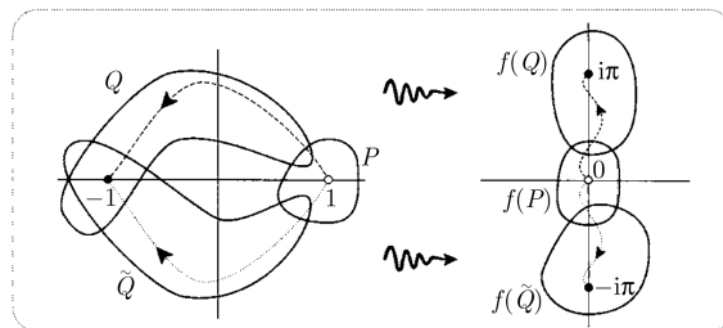
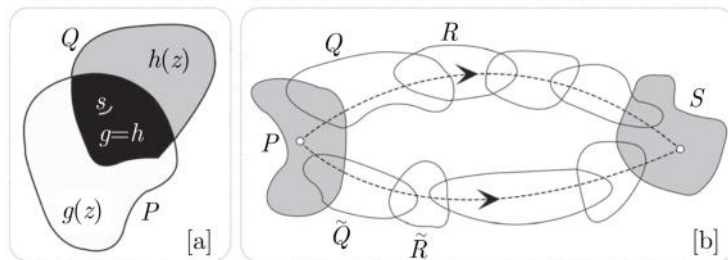
$\frac{1}{1-z}$ is an analytic extension of $(1 + z + \dots + z^n + \dots)$
 \parallel
 $f(z)$

< 1 and 1 and $|z| < 1$

let \tilde{f} be another analytic extension of f

$$\frac{1}{1-z} - \tilde{f} = 0 \quad \text{on } |z| < 1 \Rightarrow \frac{1}{1-z} - \tilde{f} \equiv 0$$

thus $\frac{1}{1-z}$ is called the analytic continuation of f .



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3. Schwartz reflection.

