

Unidad 4: Redes Convolucionales

Curso: Redes Neuronales Profundas

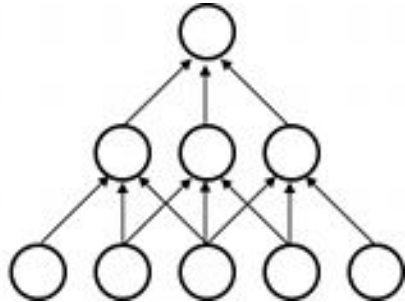
Convolutional Neural Networks

Sparse connectivity

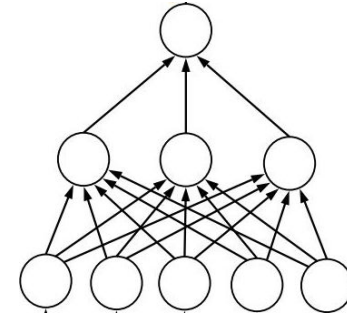
layer $m+1$

layer m

layer $m-1$



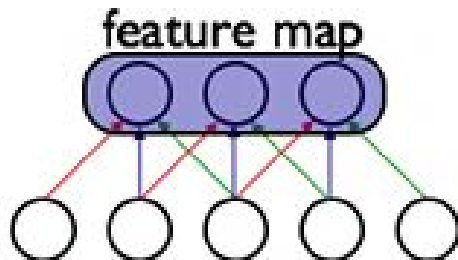
Dense connectivity



Shared weights

layer m

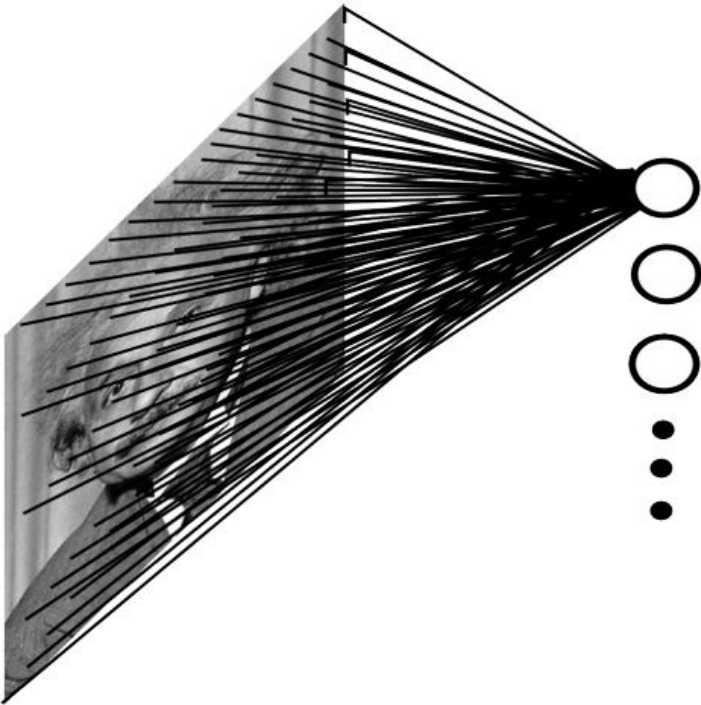
layer $m-1$



Convolutional Neural Networks

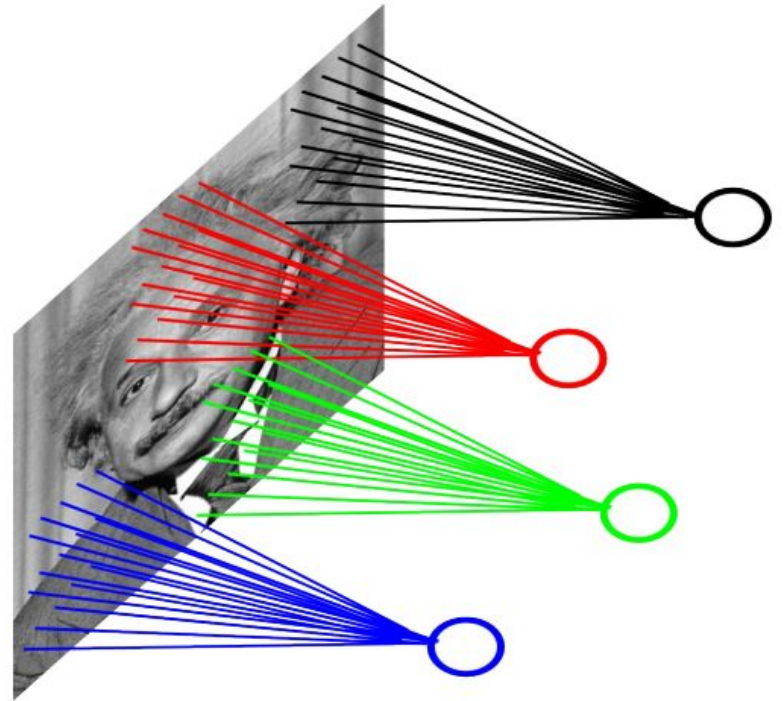
dot product + bias

$$h_k = \tanh(W_k^T x + b_k)$$



convolution + bias

$$h_{ij}^k = \tanh((W^k * x)_{ij} + b_k)$$

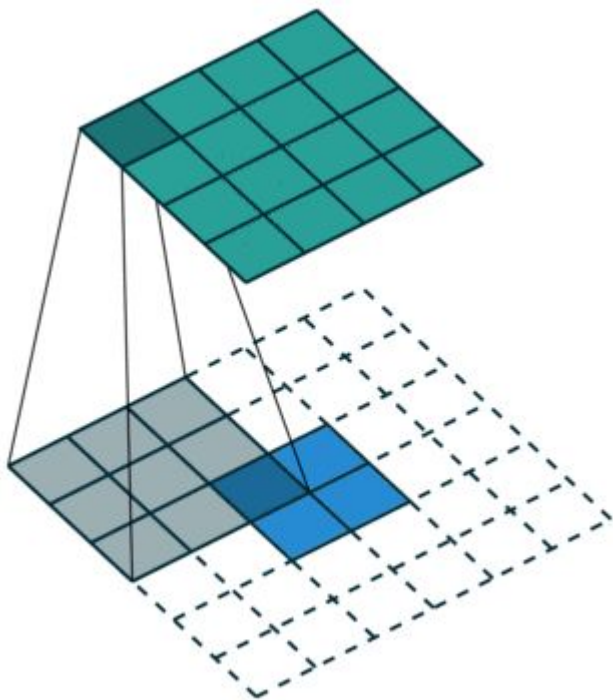


Convolución

$$s(t) = (x * w)(t) = \sum_{a=-\infty}^{\infty} x(a)w(t-a)$$

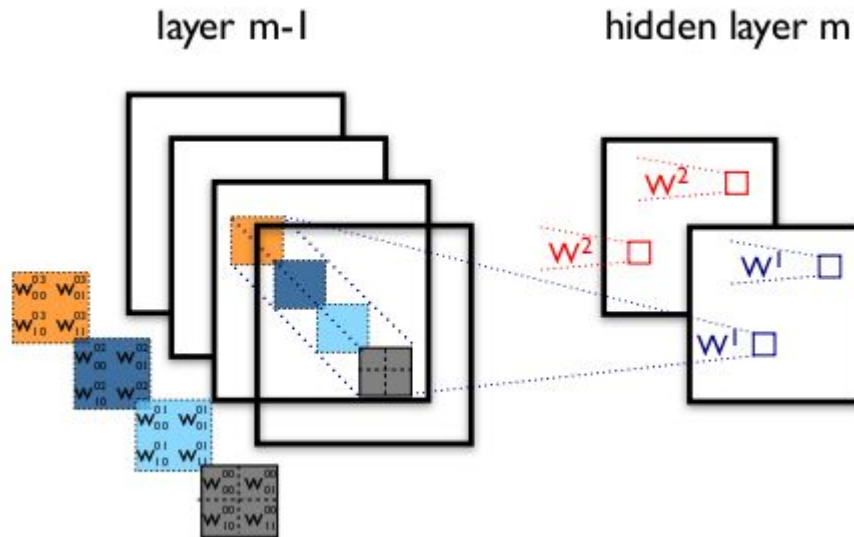
$$S(i, j) = (K * I)(i, j) = \sum_m \sum_n I(i-m, j-n)K(m, n)$$

$$S(i, j) = (I * K)(i, j) = \sum_m \sum_n I(i+m, j+n)K(m, n)$$



Equivalentes en
dos dimensiones

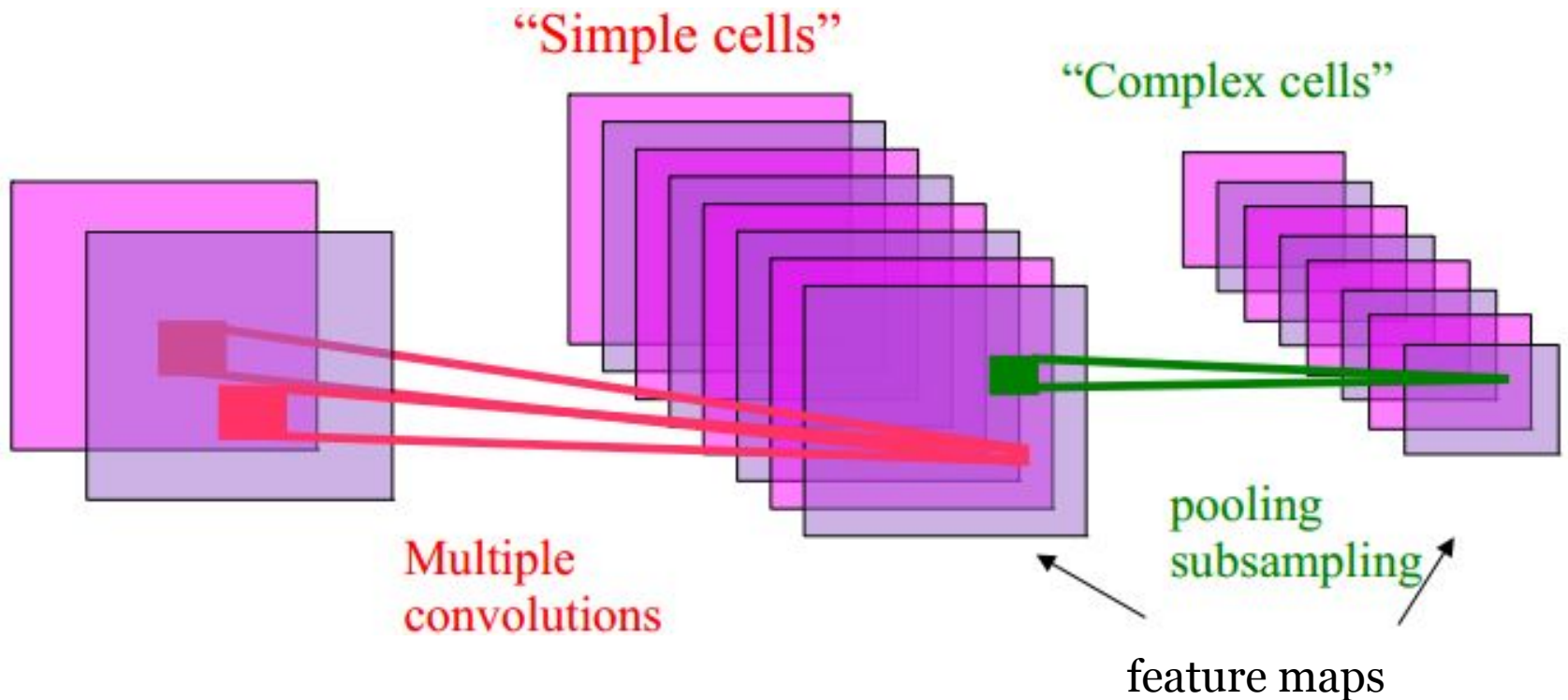
Convolutional Neural Networks



- Detects multiple motifs at each location
- The collection of units looking at the same patch is akin to a feature vector for that patch.
- The result is a 3D array, where each slice is a feature map.

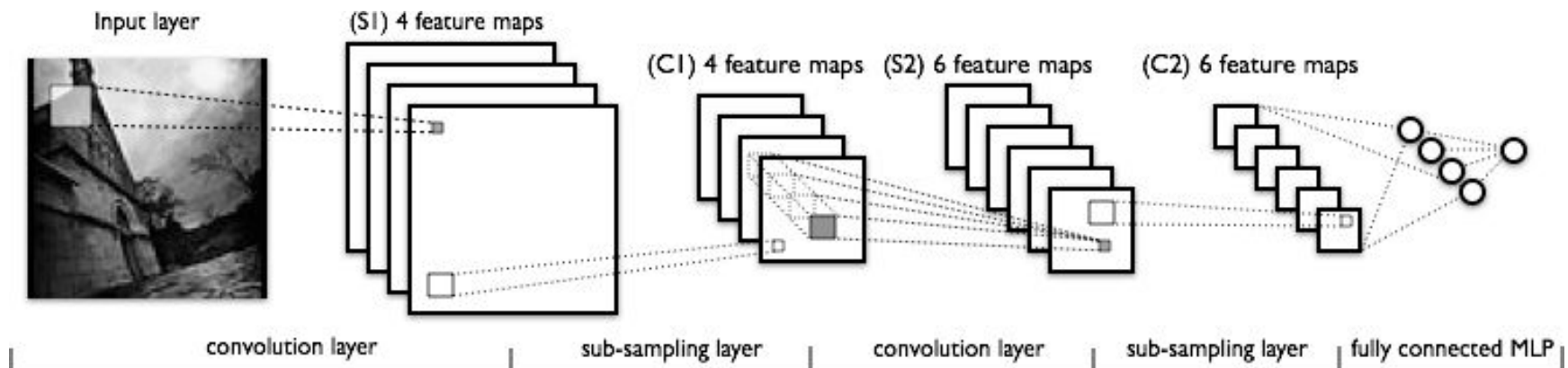
Convolutional Neural Networks

Pooling subsampling



Convolutional Neural Networks

- **Are deployed in many practical applications**
 - Image recognition, speech recognition, Google's and Baidu's photo taggers
- **Have won several competitions**
 - ImageNet, Kaggle Facial Expression, Kaggle Multimodal Learning, German Traffic Signs, Connectomics, Handwriting....
- **Are applicable to array data where nearby values are correlated**
 - Images, sound, time-frequency representations, video, volumetric images, RGB-Depth images,.....
- **One of the few deep models that can be trained purely supervised**

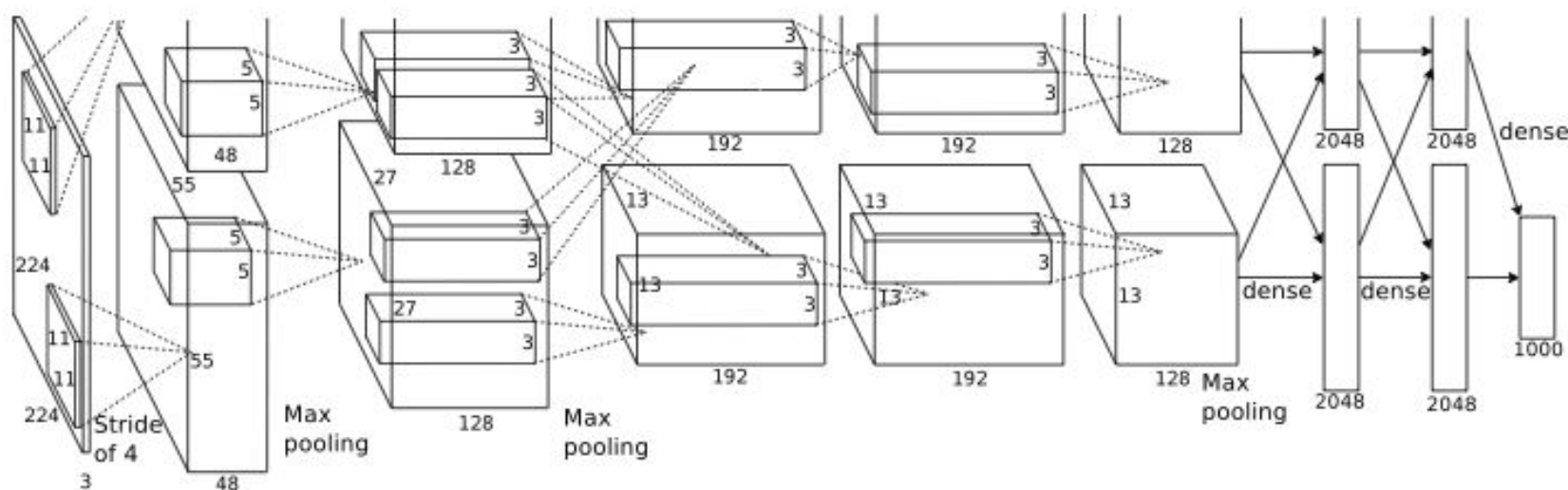


ImageNet Classification with Deep Convolutional Neural Networks

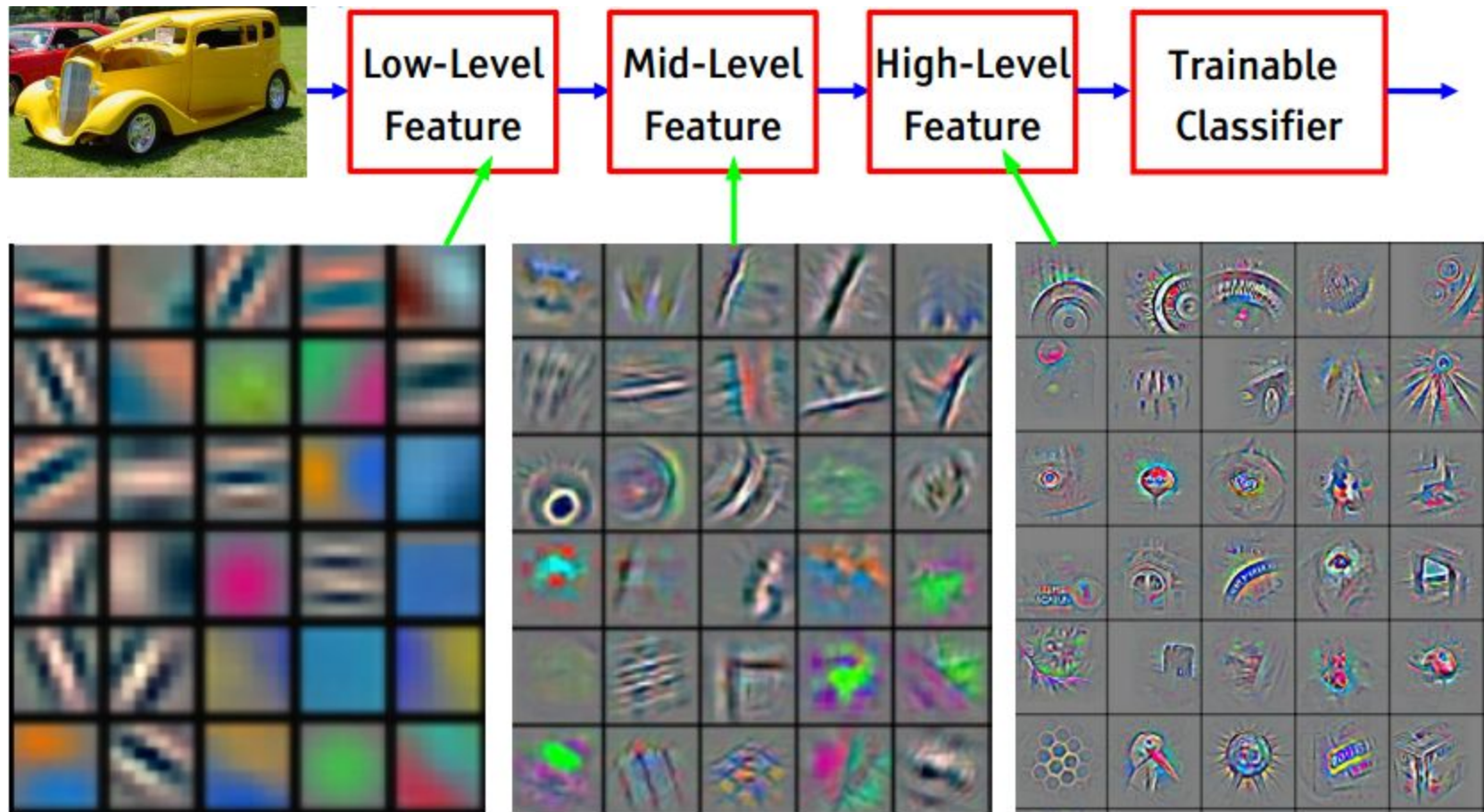
Alex Krizhevsky
University of Toronto
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University of Toronto
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University of Toronto
hinton@cs.utoronto.ca

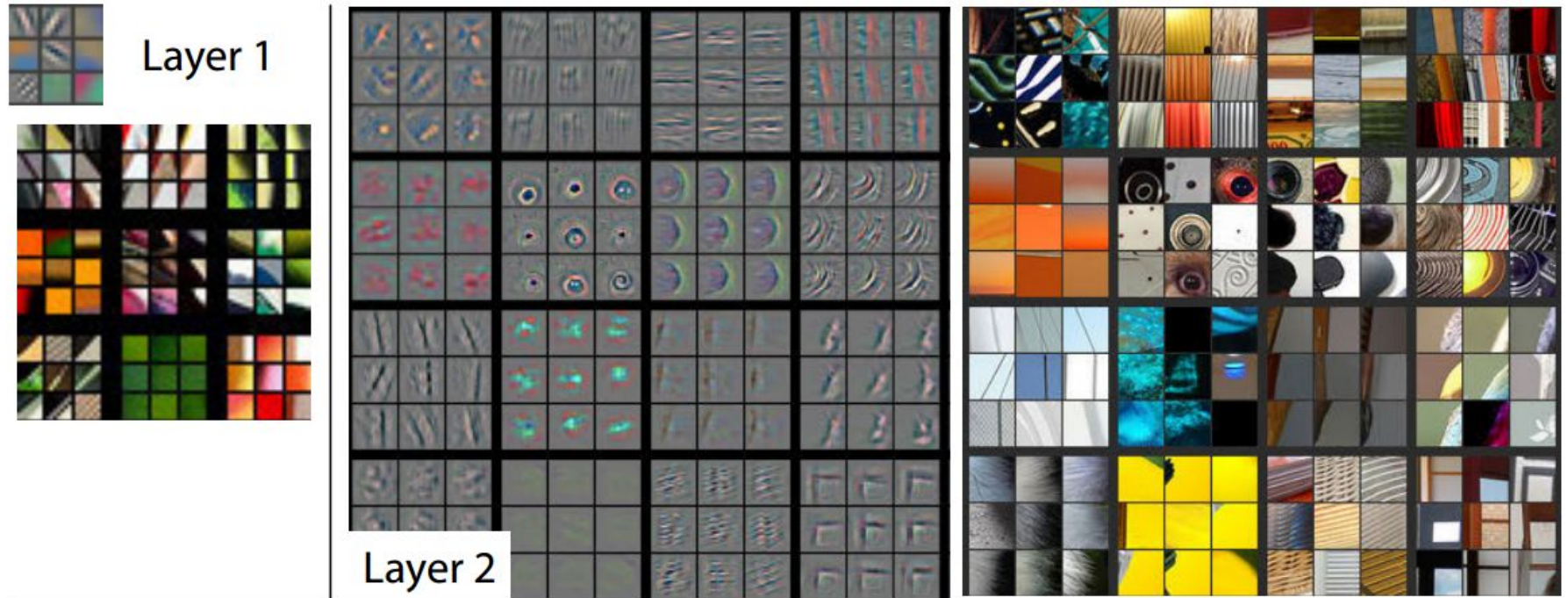


Krizhevsky, Alex, Ilya Sutskever, and Geoffrey E Hinton. "Imagenet classification with deep convolutional neural networks." *Advances in neural information processing systems* 2012: 1097-1105.



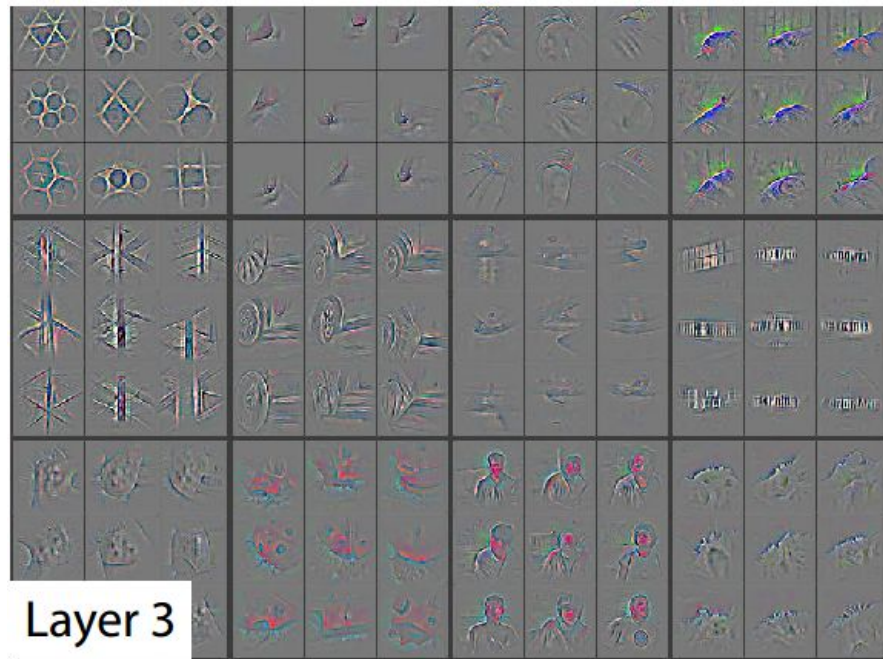
Zeiler, Matthew D, and Rob Fergus. "Visualizing and understanding convolutional neural networks." *arXiv preprint arXiv:1311.2901* (2013).

Visualizing and understanding convolutional neural networks



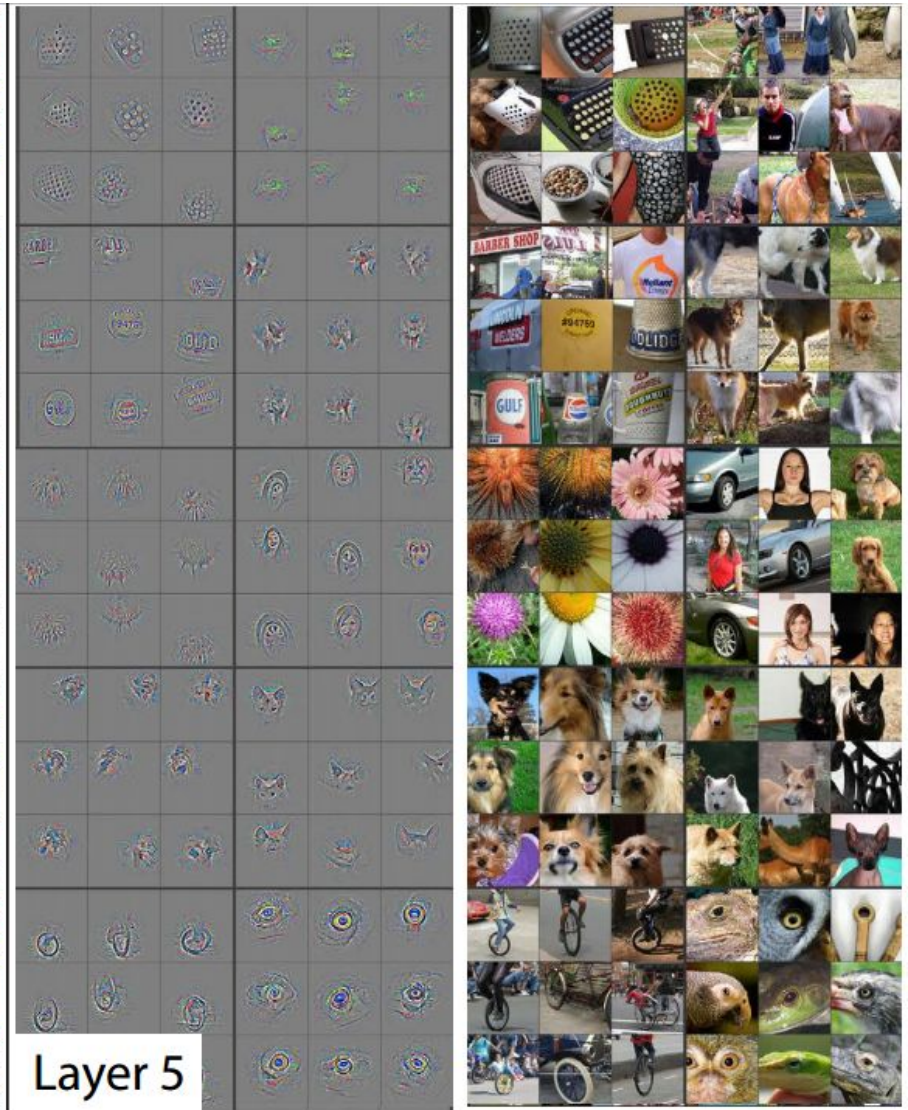
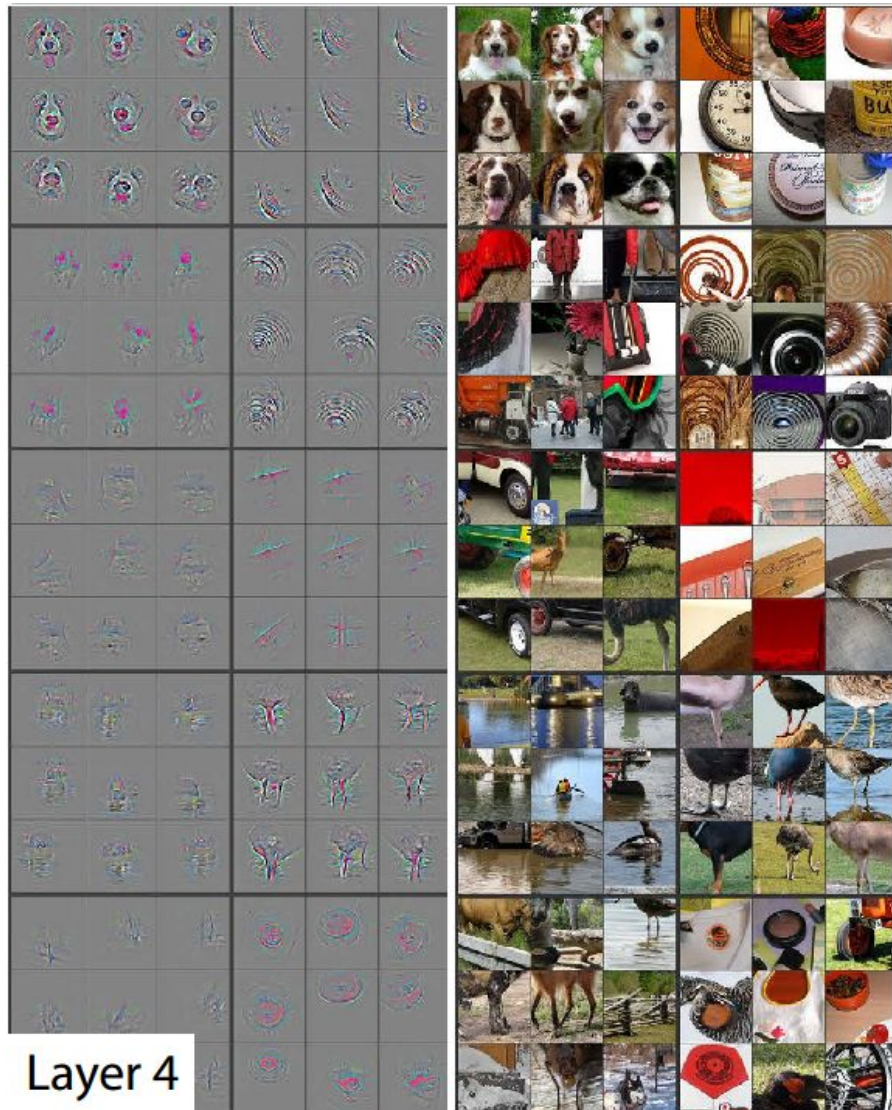
Zeiler, Matthew D, and Rob Fergus. "Visualizing and understanding convolutional neural networks." *arXiv preprint arXiv:1311.2901* (2013).

Visualizing and understanding convolutional neural networks

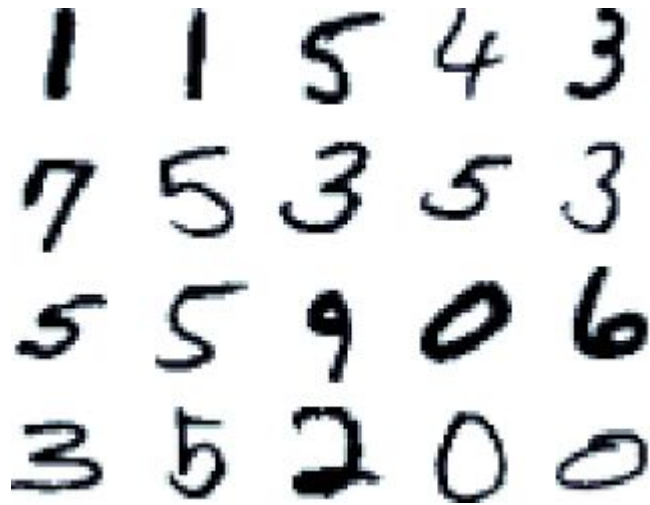


Zeiler, Matthew D, and Rob Fergus. "Visualizing and understanding convolutional neural networks." *arXiv preprint arXiv:1311.2901* (2013).

Visualizing and understanding convolutional neural networks



Tasks for Which Deep CNN are the Best



Handwriting
recognition MNIST

Arabic Handwriting Recognition

أولاد حفوز	أولاد حفوز	أولاد حفوز
أولاد حفوز	أولاد حفوز	أولاد حفوز
أولاد حفوز	أولاد حفوز	أولاد حفوز
أولاد حفوز	أولاد حفوز	أولاد حفوز

Margner, Volker, and Haikal El Abed. "Arabic handwriting recognition competition." *Document Analysis and Recognition, 2007. ICDAR 2007. Ninth International Conference on* 23 Sep. 2007: 1274-1278.

Tasks for Which Deep CNN are the Best

StreetView House Numbers [2011]



94.3 % accuracy

Netzer, Yuval et al. "Reading digits in natural images with unsupervised feature learning." *NIPS workshop on deep learning and unsupervised feature learning* 2011: 4.

Tasks for Which Deep CNN are the Best



Traffic Sign Contest, Silicon Valley,
2011(IDSIA)

0.56% ERROR

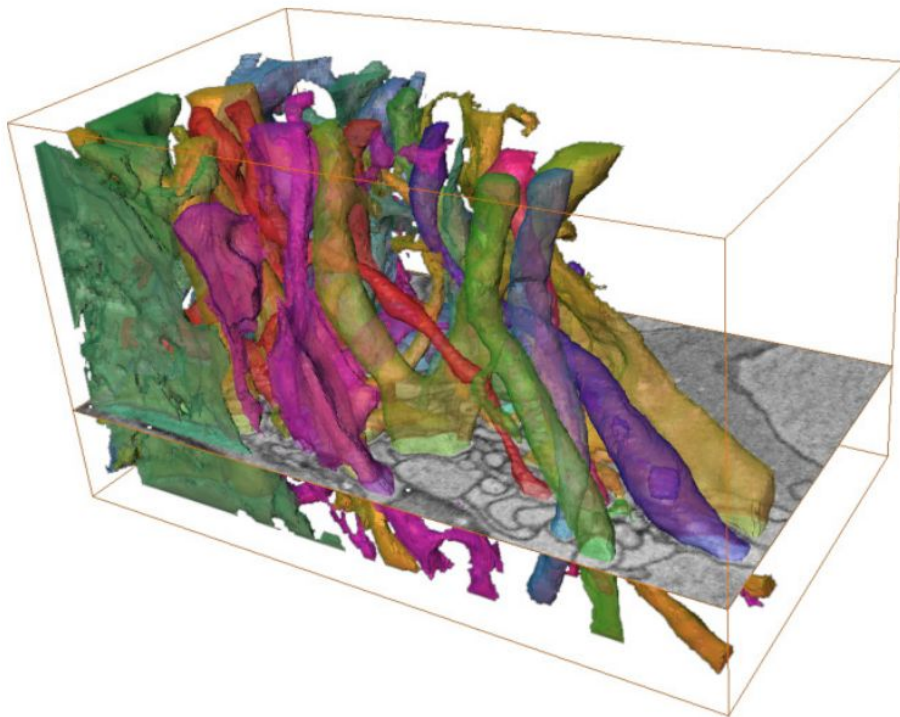
- first place
- twice better than humans
- three times better than the closest artificial competitor
- six times better than the best non-neural method



Pedestrian Detection
[2013]: INRIA
datasets and others
(NYU)

Tasks for Which Deep CNN are the Best

Volumetric brain image
segmentation [2009]
Connectomics (IDSIA, MIT)



Turaga, Srinivas C et al. "Convolutional networks can learn to generate affinity graphs for image segmentation." *Neural Computation* 22.2 (2010): 511-538.

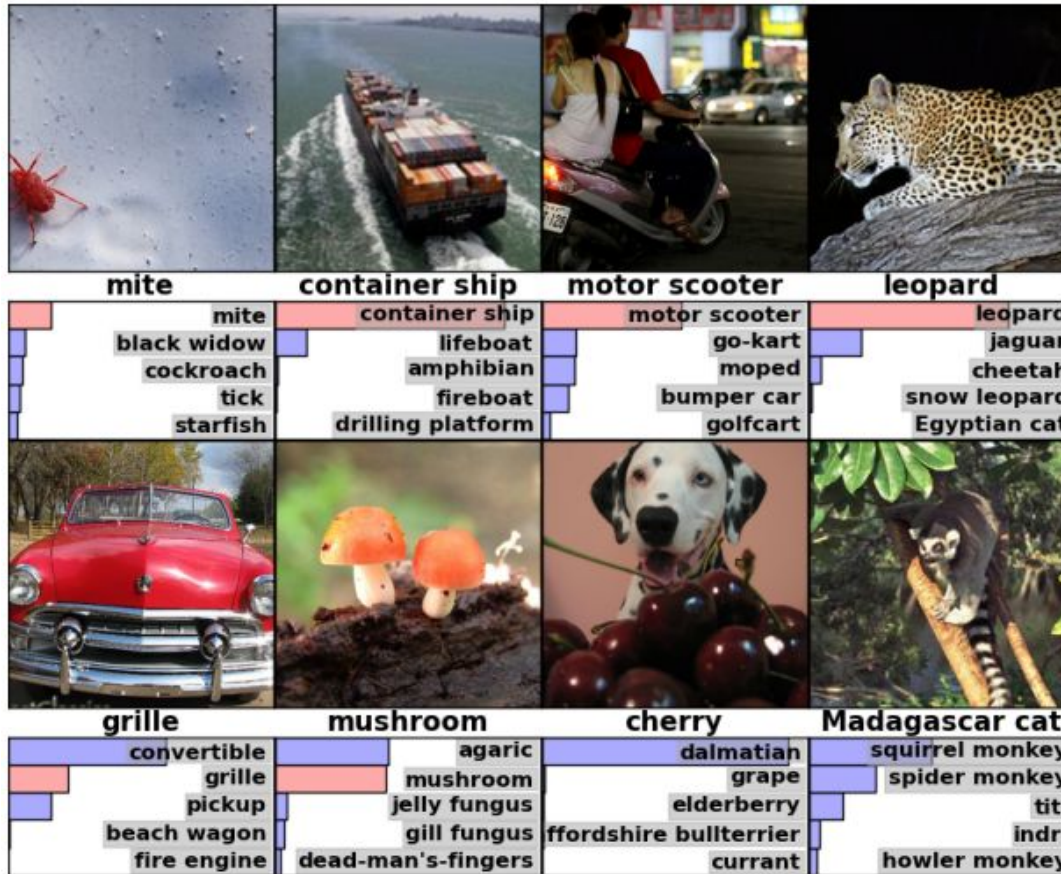
Human Action Recognition
[2011] Hollywood II dataset
(Stanford)



Le, Quoc V et al. "Learning hierarchical invariant spatio-temporal features for action recognition with independent subspace analysis." *Computer Vision and Pattern Recognition (CVPR), 2011 IEEE Conference on* 20 Jun. 2011: 3361-3368.

Tasks for Which Deep CNN are the Best

Object Recognition [2012] ImageNet competition



Error rate: 15% (whenever correct class isn't in top 5)
 Previous state of the art: 25% error

Krizhevsky, Alex, Ilya Sutskever, and Geoffrey E Hinton. "Imagenet classification with deep convolutional neural networks." *Advances in neural information processing systems* 2012: 1097-1105.

Tasks for Which Deep CNN are the Best

Scene Parsing [2012]



Farabet, Clément et al. "Scene parsing with multiscale feature learning, purity trees, and optimal covers." *arXiv preprint arXiv:1202.2160* (2012).

Google AI algorithm masters ancient game of Go

Deep-learning software defeats human professional for first time.



27 January 2016

A computer has beaten a human professional for the first time at Go — an ancient board game that has long been viewed as one of the greatest challenges for artificial intelligence (AI)

"We pass in the board position as a 19×19 image and use convolutional layers to construct a representation of the position."

Silver, D., Huang, A., Maddison, C. J., Guez, A., Sifre, L., van den Driessche, G., ... & Dieleman, S. (2016). Mastering the game of Go with deep neural networks and tree search. *Nature*, 529(7587), 484-489.

Style transfer



Gatys, Leon A., Alexander S. Ecker, and Matthias Bethge. "A neural algorithm of artistic style." *arXiv preprint arXiv:1508.06576* (2015).







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Se aproximan las JCC...

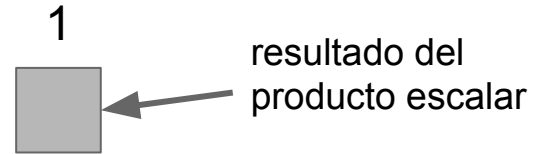
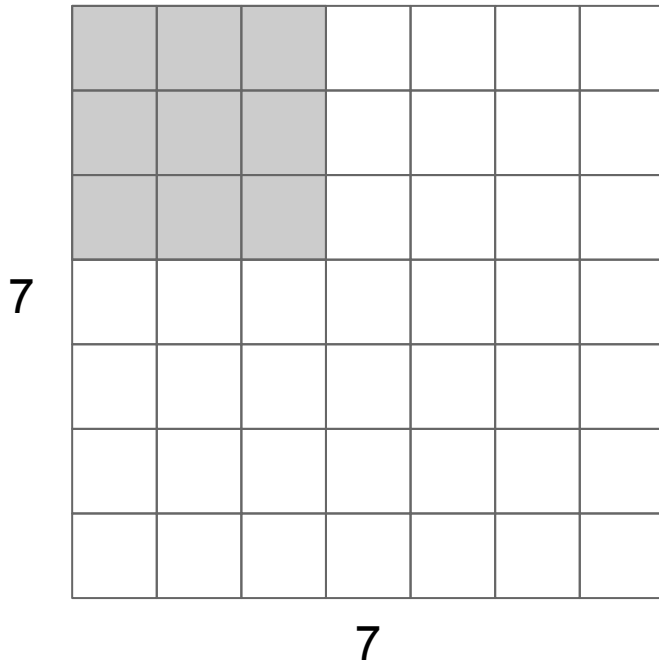
Charlas confirmadas

- [Andrés Rojas Paredes y Jheison López Restrepo \(UNGS\) - Teoría de la complejidad y Heurísticas: Problema de optimización combinatoria QAP](#)
- [Carlos Areces \(FaMAF UNC\) - Optimizando Dominios de Planning](#)
- [Daniel Fino \(FUESMEN\) - Desafíos computacionales en radiodiagnóstico por MR y MR/PET](#)
- [Ignacio Cassol \(Universidad Austral\) - Refactorización de modelos estructurados de alto nivel a OO](#)
- [Lucas Uzal \(CIFASIS\) - Deep Learning en Machine Vision](#)
- [Pablo Altamura \(NeuralSoft\) - La Inteligencia Artificial aplicada a la gestión de las organizaciones](#)
- [Carlos Luna \(UdelaR\) - Análisis formal de modelos de seguridad para sistemas críticos: plataformas de virtualización y dispositivos móviles.](#)
- [Uciel Pablo Chorostecki \(IBR\) - La bioinformática como disciplina científica](#)
- [Eugenia Simich \(FCEIA - UNR\) - Construyendo tipos de datos con containers](#)
- [Juan Edi \(Manas\) - Introducción a Crystal: creando programas eficientes sin resignar simplicidad](#)
- [Martín Ceresa \(DCC - FCEIA - UNR\) - Charla de difusión: Elige tu propia LCC](#)

Miércoles, jueves y viernes

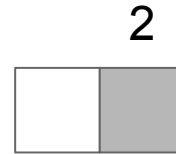
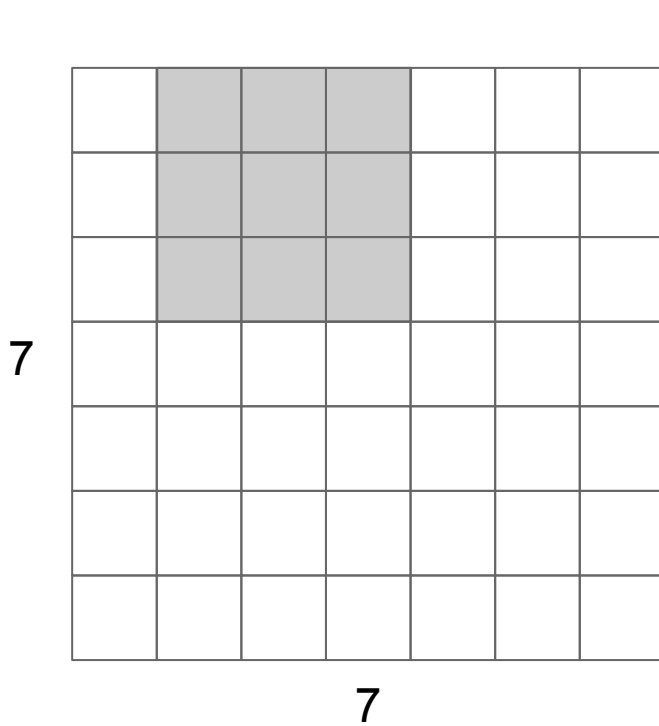
<http://fceia.unr.edu.ar/lcc/jcc/2016/>

Tamaño de la salida



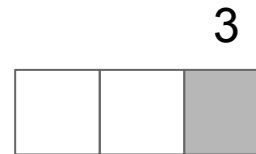
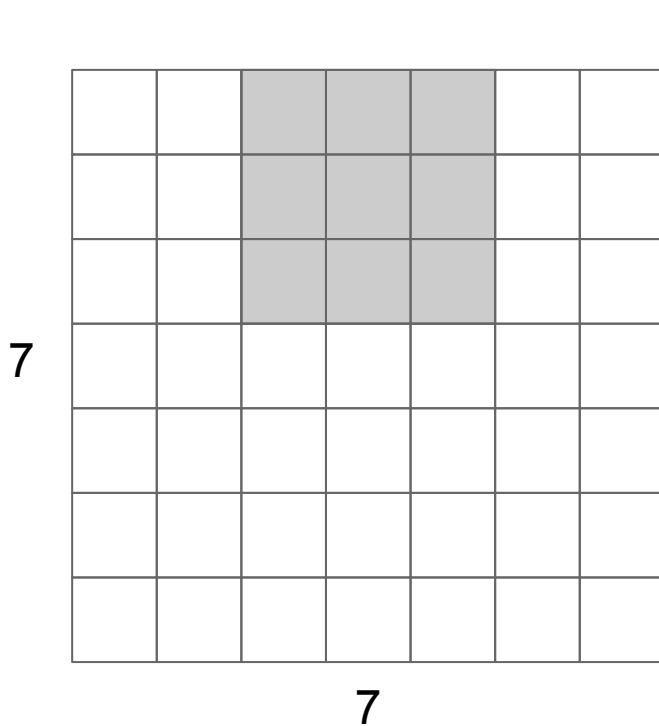
`input_size = 7x7`
`filter_size = 3x3`
`stride = 1`
`output_size = ?`

Tamaño de la salida



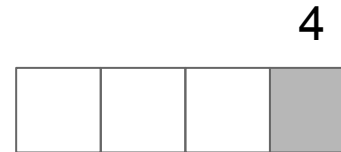
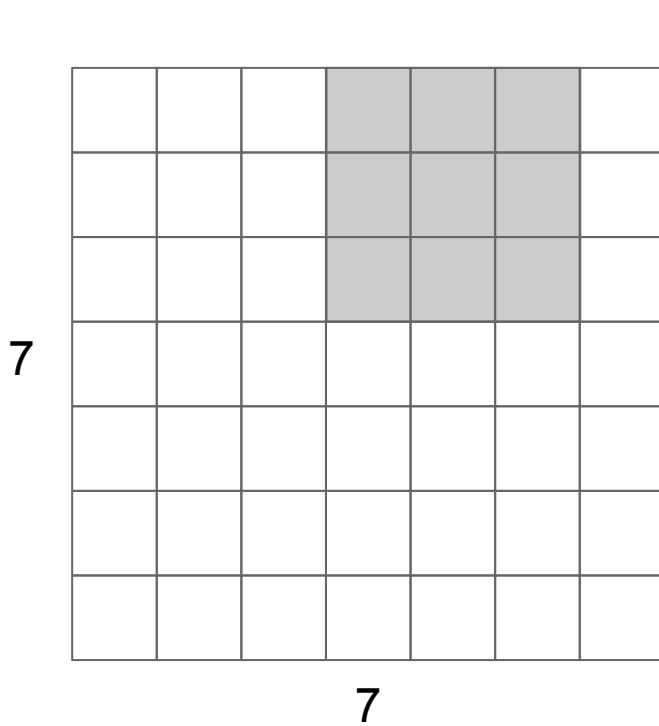
`input_size = 7x7`
`filter_size = 3x3`
`stride = 1`
`output_size = ?`

Tamaño de la salida



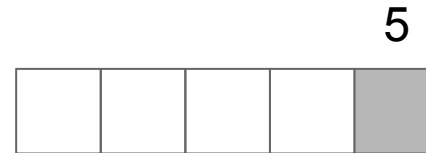
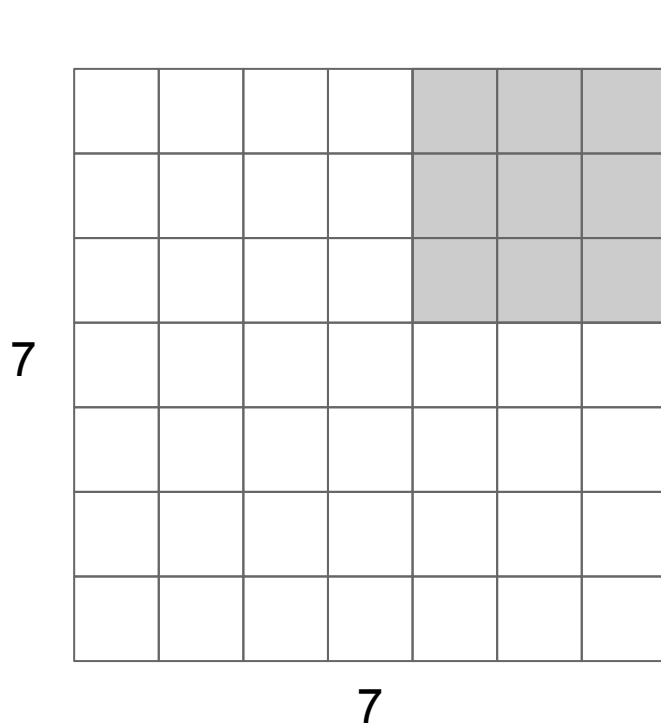
`input_size = 7x7`
`filter_size = 3x3`
`stride = 1`
`output_size = ?`

Tamaño de la salida



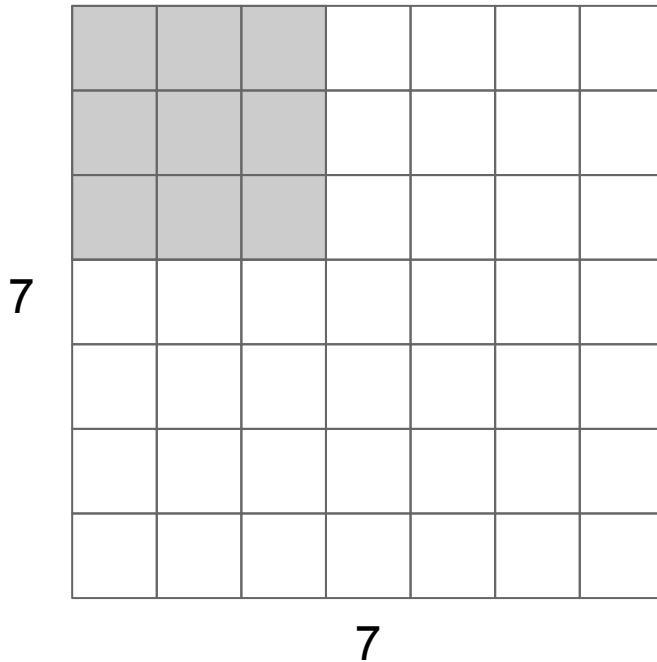
`input_size = 7x7`
`filter_size = 3x3`
`stride = 1`
`output_size = ?`

Tamaño de la salida



`input_size = 7x7`
`filter_size = 3x3`
`stride = 1`
`output_size = 5x5`

Tamaño de la salida

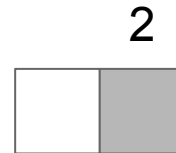
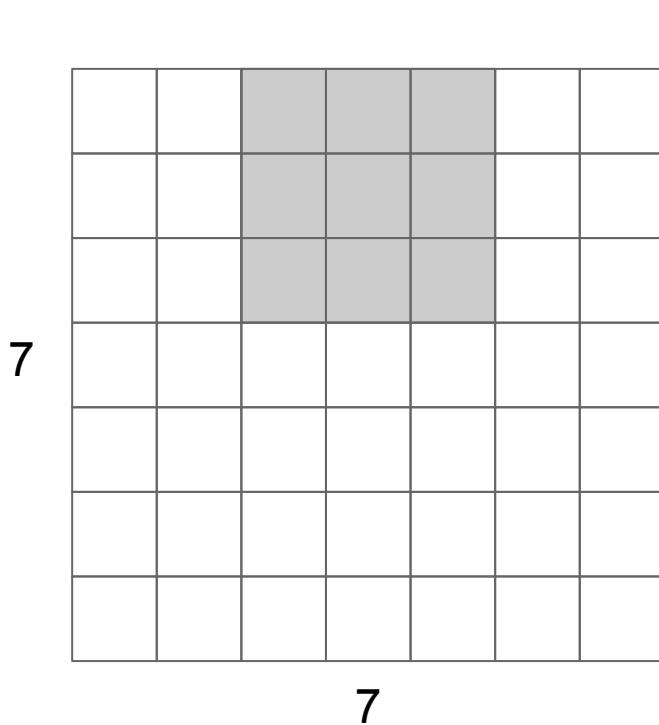


1



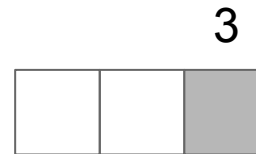
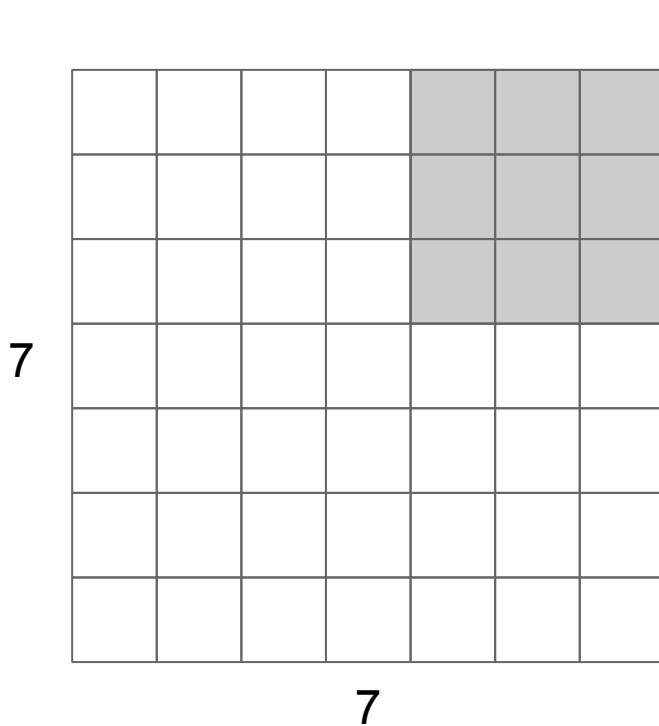
```
input_size = 7x7  
filter_size = 3x3  
stride = 2  
output_size = ?
```

Tamaño de la salida



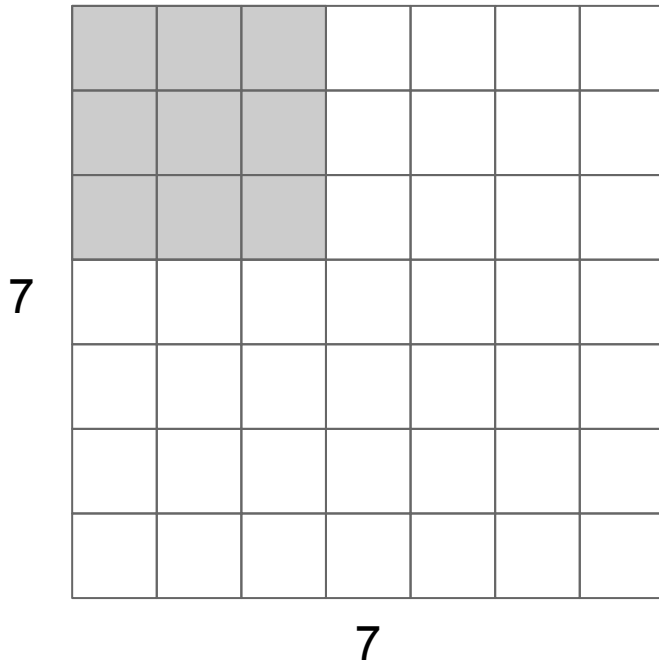
`input_size = 7x7`
`filter_size = 3x3`
`stride = 2`
`output_size = ?`

Tamaño de la salida



`input_size = 7x7`
`filter_size = 3x3`
`stride = 2`
`output_size = 3x3`

Tamaño de la salida

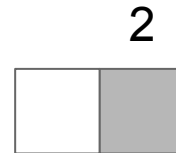
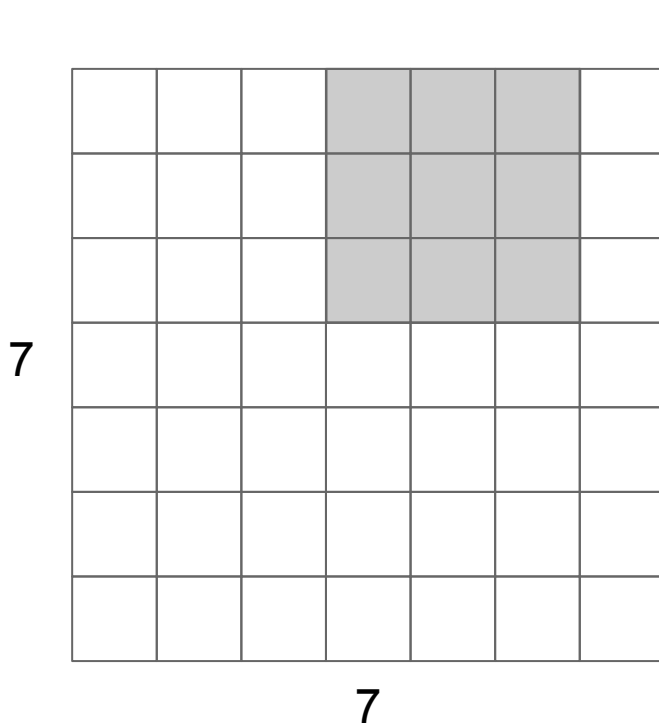


1



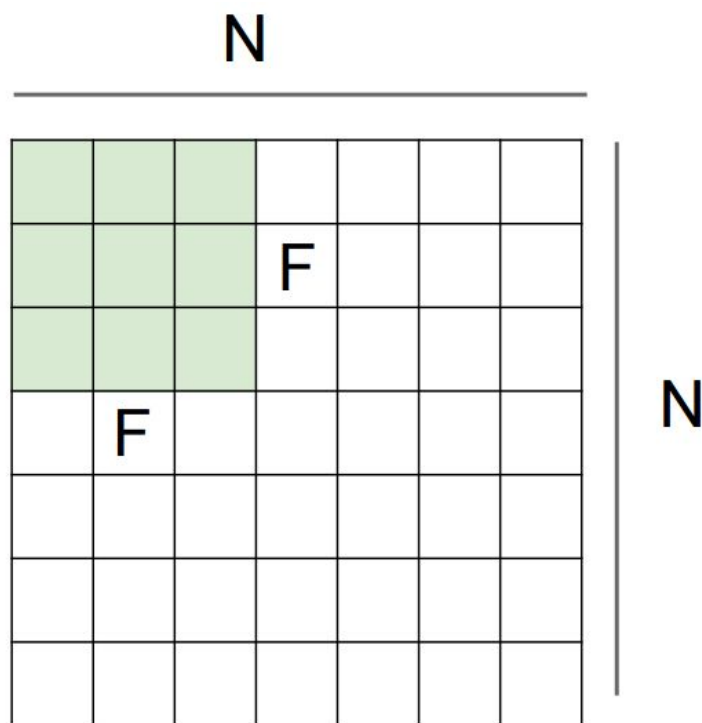
`input_size = 7x7`
`filter_size = 3x3`
`stride = 3`
`output_size = ?`

Tamaño de la salida



```
input_size = 7x7  
filter_size = 3x3  
stride = 3  
output_size = 2x2 (!)
```

Tamaño de la salida



Output size:
 $(N - F) / \text{stride} + 1$

e.g. $N = 7, F = 3$:

stride 1 $\Rightarrow (7 - 3) / 1 + 1 = 5$

stride 2 $\Rightarrow (7 - 3) / 2 + 1 = 3$

stride 3 $\Rightarrow (7 - 3) / 3 + 1 = 2.33$

Zero padding

9

0	0	0	0	0	0	0	0	0
0								0
0								0
0								0
0								0
0								0
0								0
0	0	0	0	0	0	0	0	0

9

`input_size = 7x7`
`filter_size = 3x3`
`stride = 1`
`padding = 1`
`output_size = 7x7`

`output_size = (input_size + 2*padding - filter_size) / stride + 1`

Zero padding

9

0	0	0	0	0	0	0	0	0
0								0
0								0
0								0
0								0
0								0
0								0
0								0
0	0	0	0	0	0	0	0	0

9

Algunos modos predefinidos

'valid':

padding = 0

'same':

padding = (filter_size - 1) / 2

'full':

padding = filter_size - 1

input_size = 7x7

filter_size = 3x3

stride = 1

padding = 1

output_size = 7x7

$$\text{output_size} = (\text{input_size} + 2 * \text{padding} - \text{filter_size}) / \text{stride} + 1$$

Razones para usar padding ('same')

9

0	0	0	0	0	0	0	0	0
0								0
0								0
0								0
0								0
0								0
0								0
0	0	0	0	0	0	0	0	0

9

- Controlar más fácilmente el tamaño de los mapas (independizarse de **filter_size**)
- Detectar patrones 'pegados a los bordes'

```
input_size = 7x7
filter_size = 3x3
stride = 1
padding = 1
output_size = 7x7
```

$$\text{output_size} = (\text{input_size} + 2 * \text{padding} - \text{filter_size}) / \text{stride} + 1$$

theano.tensor.nnet.conv2d(*input, filters, input_shape=None, filter_shape=None, border_mode='valid', subsample=(1, 1), filter_flip=True*)

input (*symbolic 4D tensor*) – Mini-batch of feature map stacks, of shape (batch size, input channels, input rows, input columns).

filters (*symbolic 4D tensor*) – Set of filters used in CNN layer of shape (output channels, input channels, filter rows, filter columns).

input_shape (*None, tuple/list of len 4 of int or Constant variable*) – The shape of the input parameter. Optional, possibly used to choose an optimal implementation. You can give **None** for any element of the list to specify that this element is not known at compile time.

filter_shape (*None, tuple/list of len 4 of int or Constant variable*) – The shape of the filters parameter. Optional, possibly used to choose an optimal implementation. You can give **None** for any element of the list to specify that this element is not known at compile time.

subsample (*tuple of len 2*) – Factor by which to subsample the output. Also called strides elsewhere.

border_mode (*str, int or tuple of two int*) – Either of the following:

'valid': apply filter wherever it completely overlaps with the input.

'full': apply filter wherever it partly overlaps with the input.

'half': pad input with a symmetric border of **filter rows / 2** rows and **filter columns / 2** columns.

int: pad input with a symmetric border of zeros of the given width

(int1, int2): pad input with a symmetric border of **int1** rows and **int2** columns.

filter_flip (*bool*) – If **True**, will flip the filter rows and columns before sliding them over the input. This operation is normally referred to as a convolution, and this is the default. If **False**, the filters are not flipped and the operation is referred to as a cross-correlation.


```
keras.layers.convolutional.Convolution2D(nb_filter, nb_row, nb_col,  
init='glorot_uniform', activation='linear', weights=None, border_mode='valid',  
subsample=(1, 1), dim_ordering='default', W_regularizer=None, b_regularizer=None,  
activity_regularizer=None, W_constraint=None, b_constraint=None, bias=True)
```

input_shape: When using this layer as the first layer in a model, provide this keyword argument, e.g. input_shape=(3, 128, 128) for 128x128 RGB pictures.

nb_filter: Number of convolution filters to use.

nb_row: Number of rows in the convolution kernel.

nb_col: Number of columns in the convolution kernel.

init: name of initialization function for the weights of the layer (see [initializations](#)), or alternatively, Theano function to use for weights initialization. This parameter is only relevant if you don't pass a **weights** argument.

activation: name of activation function to use (see [activations](#)), or alternatively, elementwise Theano function. If you don't specify anything, no activation is applied (ie. "linear" activation: $a(x) = x$).

weights: list of numpy arrays to set as initial weights.

border_mode: 'valid' or 'same'.

subsample: tuple of length 2. Factor by which to subsample output. Also called strides elsewhere.

W_regularizer: ...

b_regularizer: ...

activity_regularizer: ...

W_constraint: ...

b_constraint: ...

dim_ordering: 'th' or 'tf'. In 'th' mode, the channels dimension (the depth) is at index 1, in 'tf' mode is it at index 3. It defaults to the **image_dim_ordering** value found in your Keras config file at `~/.keras/keras.json`. If you never set it, then it will be "tf".

bias: whether to include a bias (i.e. make the layer affine rather than linear).

Configuraciones típicas

```
input_size = 2^N x 2^N
filter_size = 3x3
nb_filter = 2^M
stride = 1
padding = 1
    output_size = input_size
```

```
input_size = 2^N x 2^N
filter_size = 5x5
nb_filter = 2^M
stride = 2
padding = 'same'
    output_size = input_size/2
```

```
input_size = 2^N x 2^N
filter_size = 5x5
nb_filter = 2^M
stride = 1
padding = 2
    output_size = input_size
```

```
input_size = 2^N x 2^N
filter_size = 1x1
nb_filter = 2^M
stride = 1
padding = 0
    output_size = input_size
```

Pooling

1	1	2	4
5	6	7	8
3	2	1	0
1	2	3	4

max pool with 2x2 filters
and stride 2

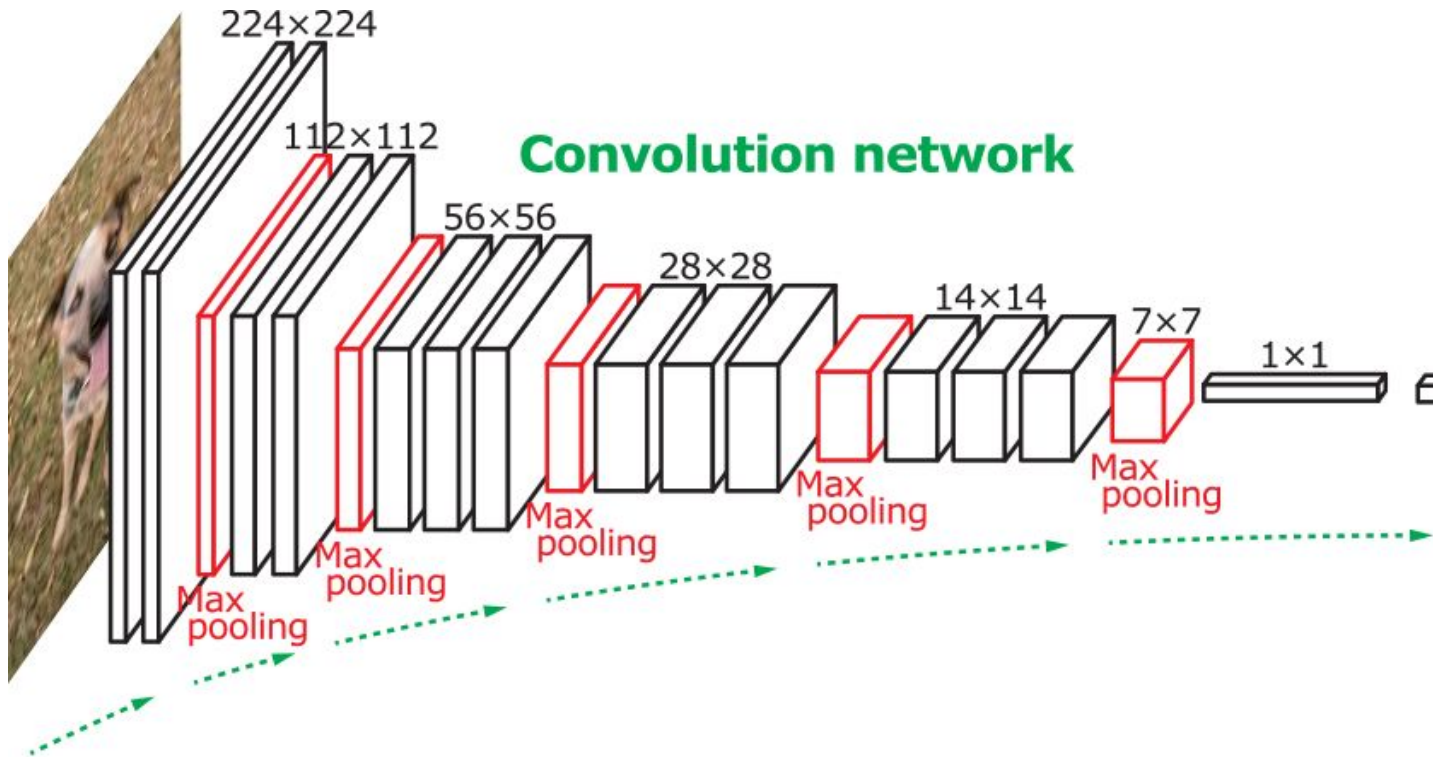


6	8
3	4

`output_size = (input_size - pool_size) / stride + 1`

Si `stride = pool_size`: `output_size = input_size / stride`

Ejemplo: VGG net ("versión D")



Input 224x224

conv3-64

conv3-64

maxpool

conv3-128

conv3-128

maxpool

conv3-256

conv3-256

conv3-256

maxpool

conv3-512

conv3-512

conv3-512

maxpool

conv3-512

conv3-512

conv3-512

maxpool

FC-4096

FC-4096

FC-1000

softmax

dataset: ImageNet (ILSVRC 2013)

Ejemplo: VGG net ("versión D")

INPUT:	[224x224x3]	memory: 224*224*3=150K	params: 0
CONV3-64:	[224x224x64]	memory: 224*224*64=3.2M	params: (3*3*3)*64 = 1,728
CONV3-64:	[224x224x64]	memory: 224*224*64=3.2M	params: (3*3*64)*64 = 36,864
POOL2:	[112x112x64]	memory: 112*112*64=800K	params: 0
CONV3-128:	[112x112x128]	memory: 112*112*128=1.6M	params: (3*3*64)*128 = 73,728
CONV3-128:	[112x112x128]	memory: 112*112*128=1.6M	params: (3*3*128)*128 = 147,456
POOL2:	[56x56x128]	memory: 56*56*128=400K	params: 0
CONV3-256:	[56x56x256]	memory: 56*56*256=800K	params: (3*3*128)*256 = 294,912
CONV3-256:	[56x56x256]	memory: 56*56*256=800K	params: (3*3*256)*256 = 589,824
CONV3-256:	[56x56x256]	memory: 56*56*256=800K	params: (3*3*256)*256 = 589,824
POOL2:	[28x28x256]	memory: 28*28*256=200K	params: 0
CONV3-512:	[28x28x512]	memory: 28*28*512=400K	params: (3*3*256)*512 = 1,179,648
CONV3-512:	[28x28x512]	memory: 28*28*512=400K	params: (3*3*512)*512 = 2,359,296
CONV3-512:	[28x28x512]	memory: 28*28*512=400K	params: (3*3*512)*512 = 2,359,296
POOL2:	[14x14x512]	memory: 14*14*512=100K	params: 0
CONV3-512:	[14x14x512]	memory: 14*14*512=100K	params: (3*3*512)*512 = 2,359,296
CONV3-512:	[14x14x512]	memory: 14*14*512=100K	params: (3*3*512)*512 = 2,359,296
CONV3-512:	[14x14x512]	memory: 14*14*512=100K	params: (3*3*512)*512 = 2,359,296
POOL2:	[7x7x512]	memory: 7*7*512=25K	params: 0
FC:	[1x1x4096]	memory: 4096	params: 7*7*512*4096 = 102,760,448
FC:	[1x1x4096]	memory: 4096	params: 4096*4096 = 16,777,216
FC:	[1x1x1000]	memory: 1000	params: 4096*1000 = 4,096,000

TOTAL memory: 24M * 4 bytes ~= 93MB / image (only forward! ~*2 for bwd)

TOTAL params: 138M parameters

Campo visual (VGG)



76x76



132x132



196x196

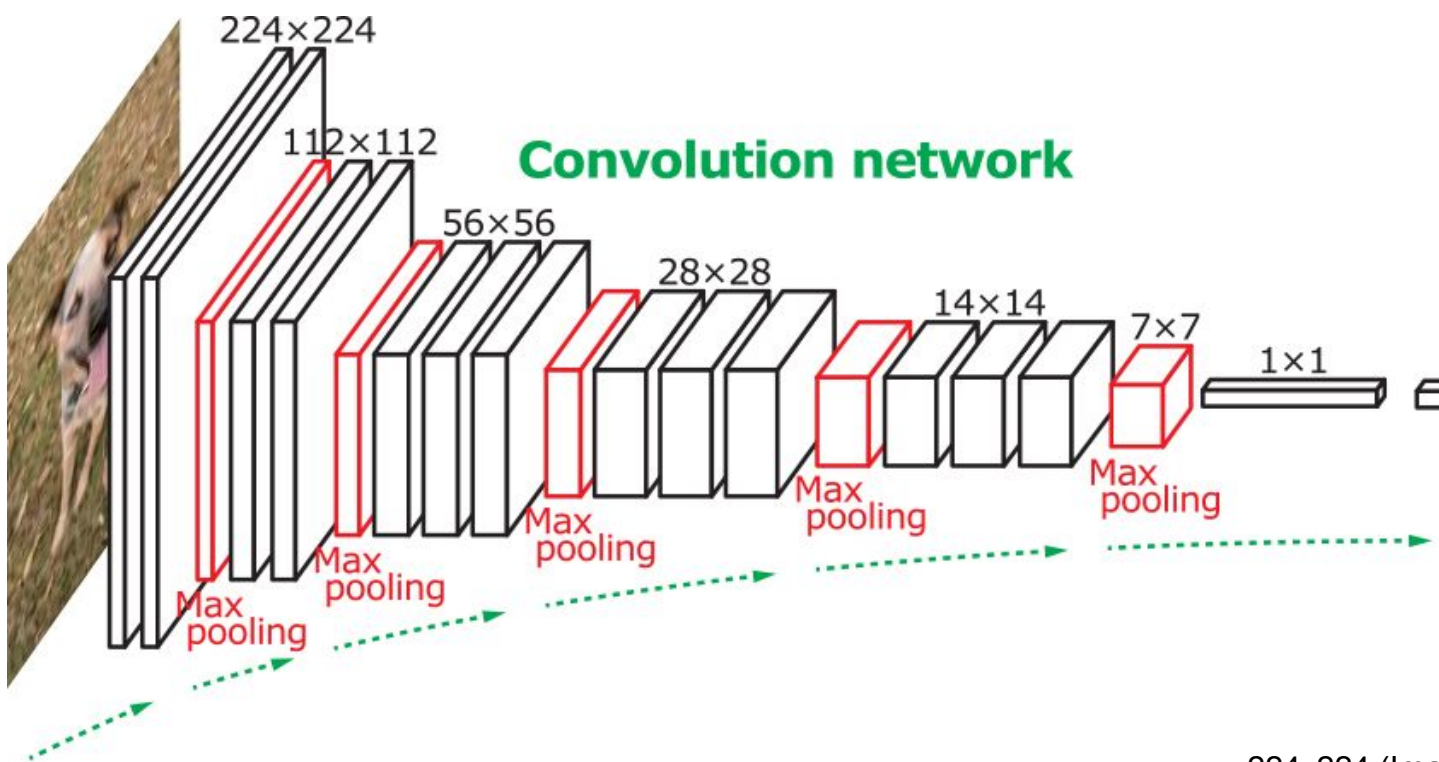


212x212



224x224 (Imagen Original)





196x196



212x212

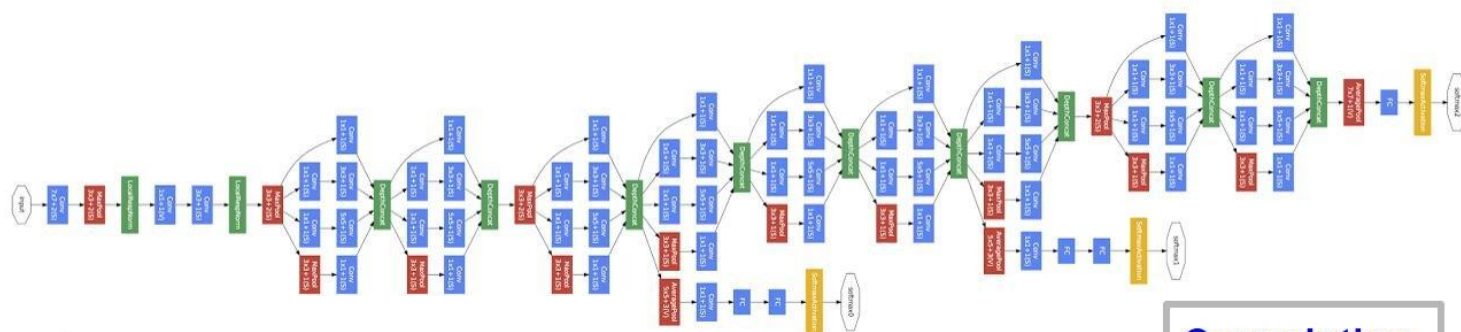


224x224 (Imagen Original)

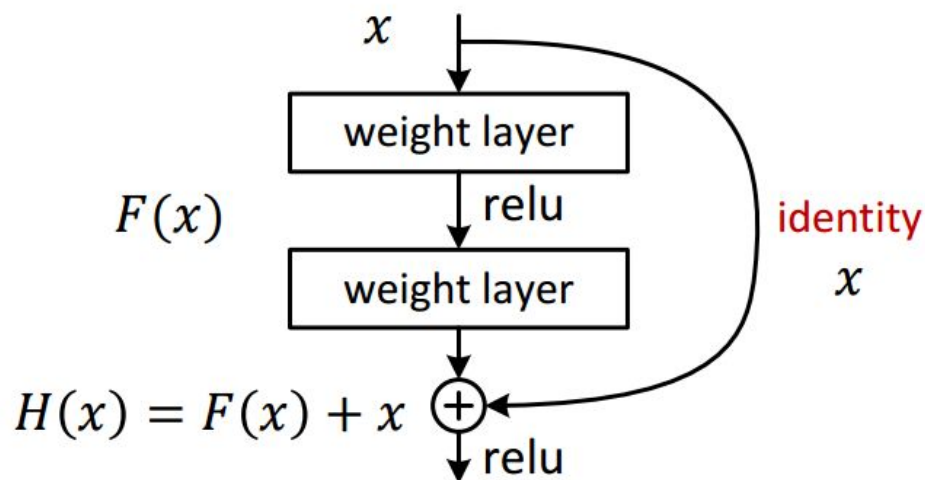


Combinaciones más complejas

GoogLeNet



- Residual net

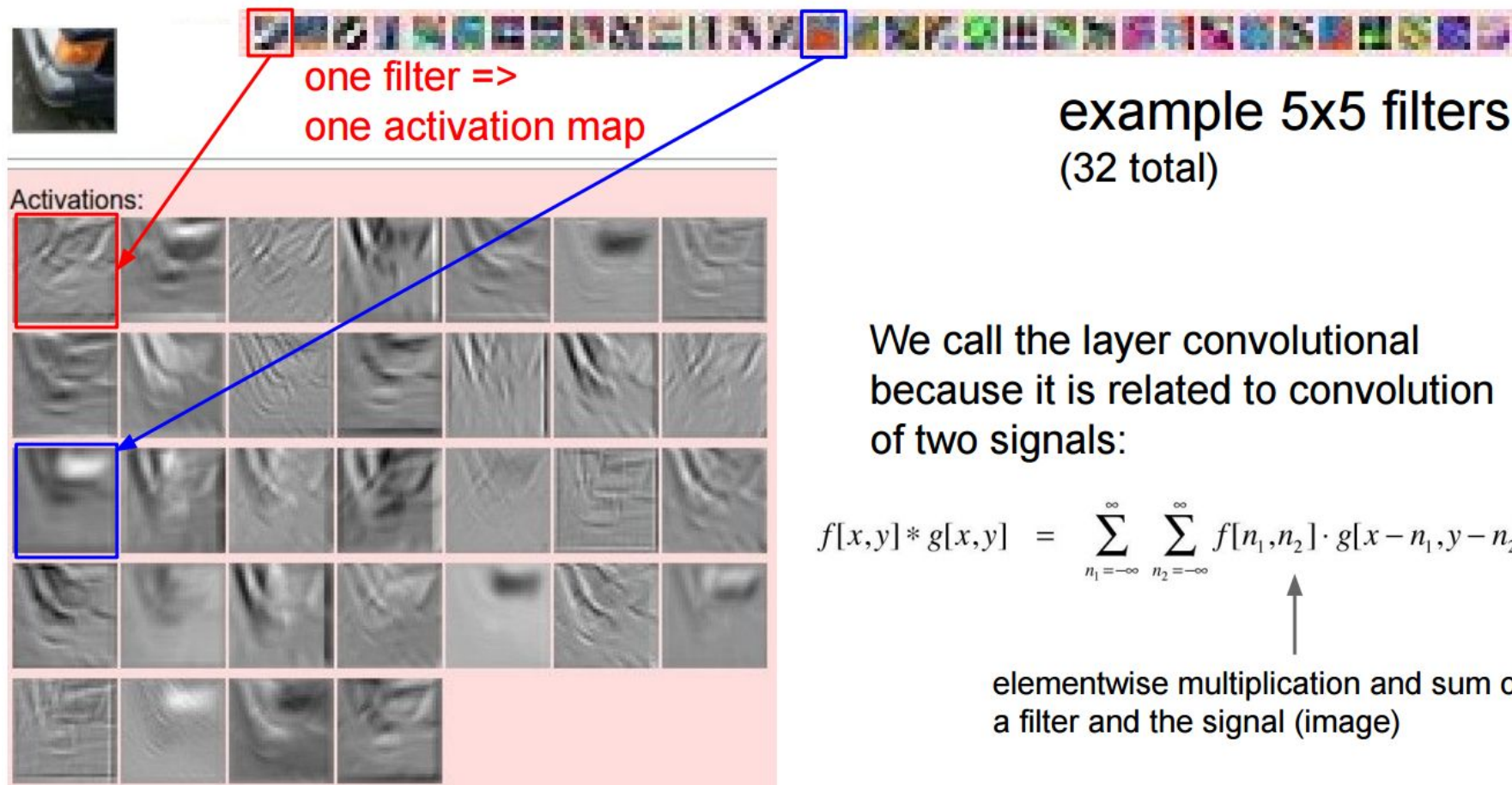


Convolution
Pooling
Softmax
Other
www.voidcn.com

Entendiendo el modelo

- Ver cómo son las activaciones
- Visualizar los pesos (sólo interpretable la primera capa)
- Visualizar los parches que maximizan la activación de una dada neurona
- Visualizar el espacio de representación
- Oclusiones y optimización sobre imágenes

Mapas de activación



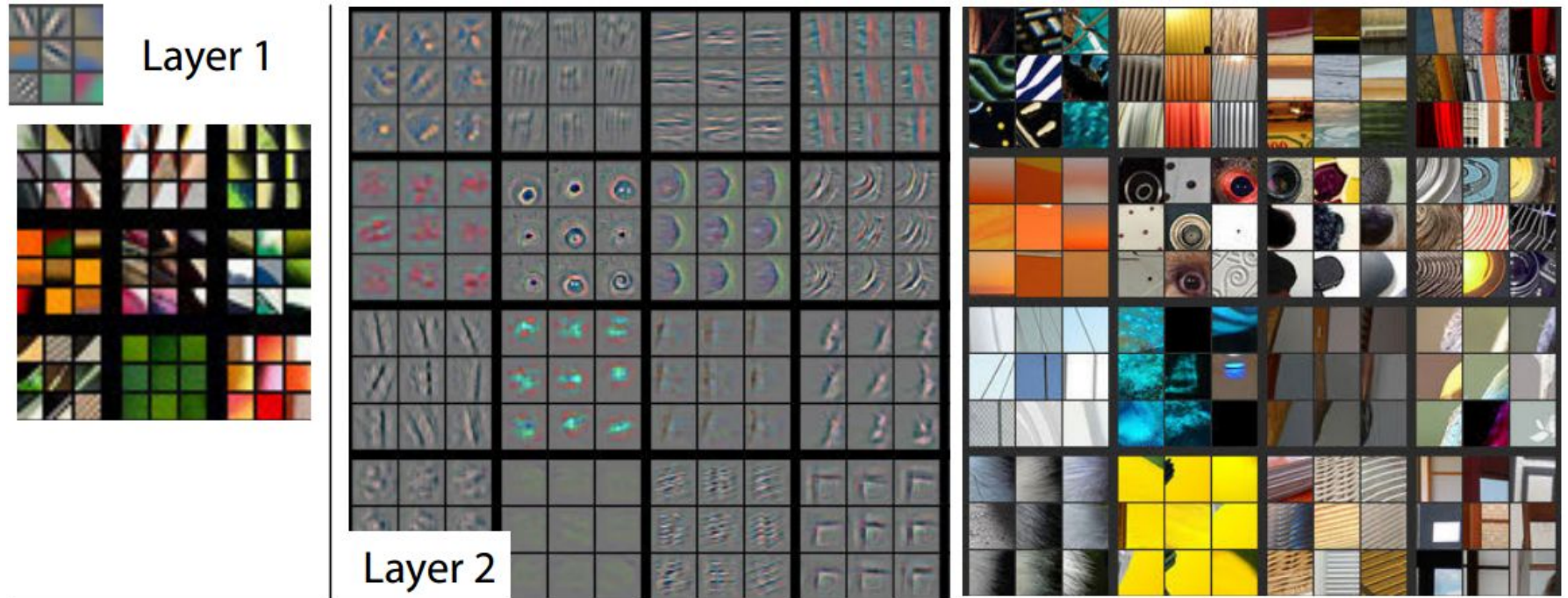
Visualizing and understanding convolutional neural networks



Viendo los filtros podemos detectar algunos problemas

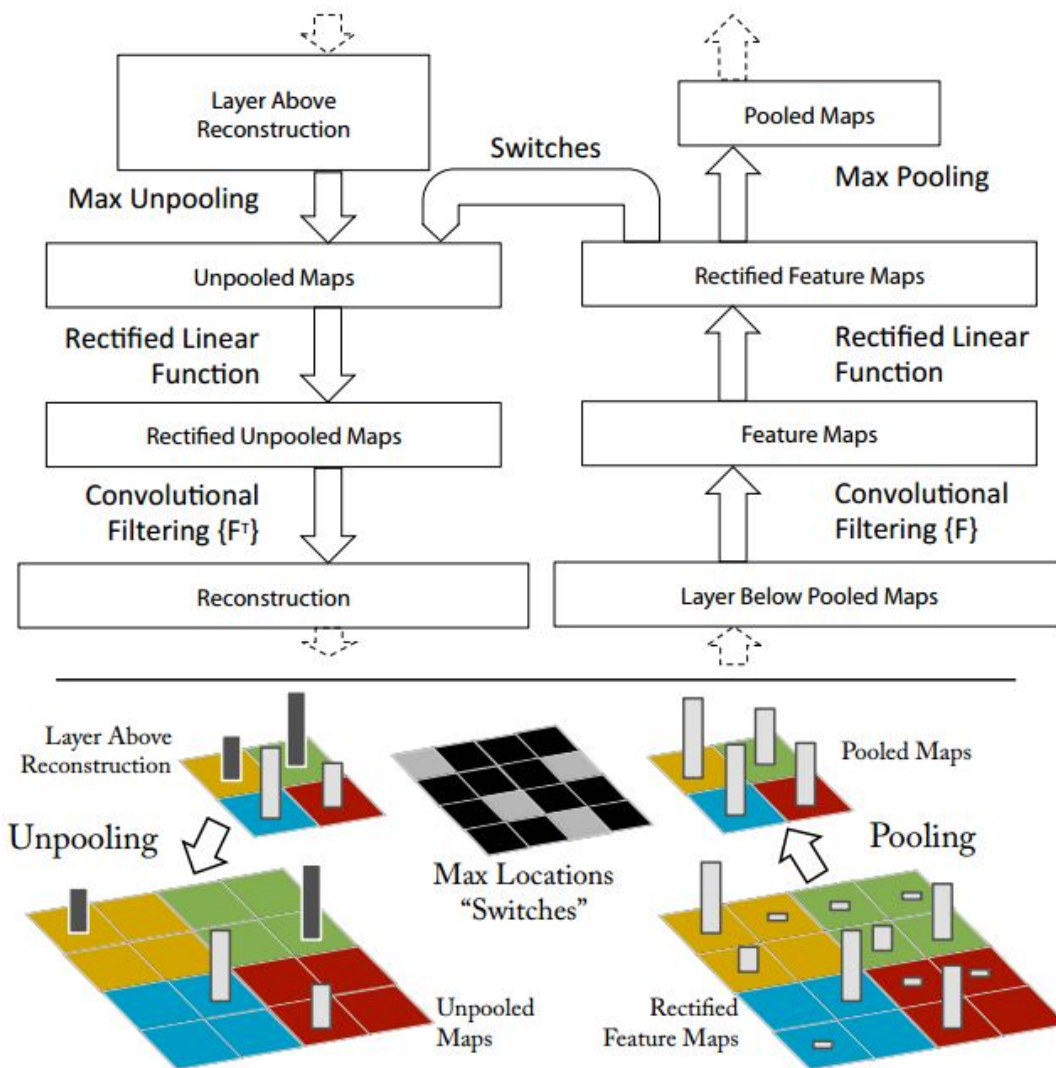
Zeiler, Matthew D, and Rob Fergus. "Visualizing and understanding convolutional neural networks." *arXiv preprint arXiv:1311.2901* (2013).

Visualizing and understanding convolutional neural networks



Zeiler, Matthew D, and Rob Fergus. "Visualizing and understanding convolutional neural networks." *arXiv preprint arXiv:1311.2901* (2013).

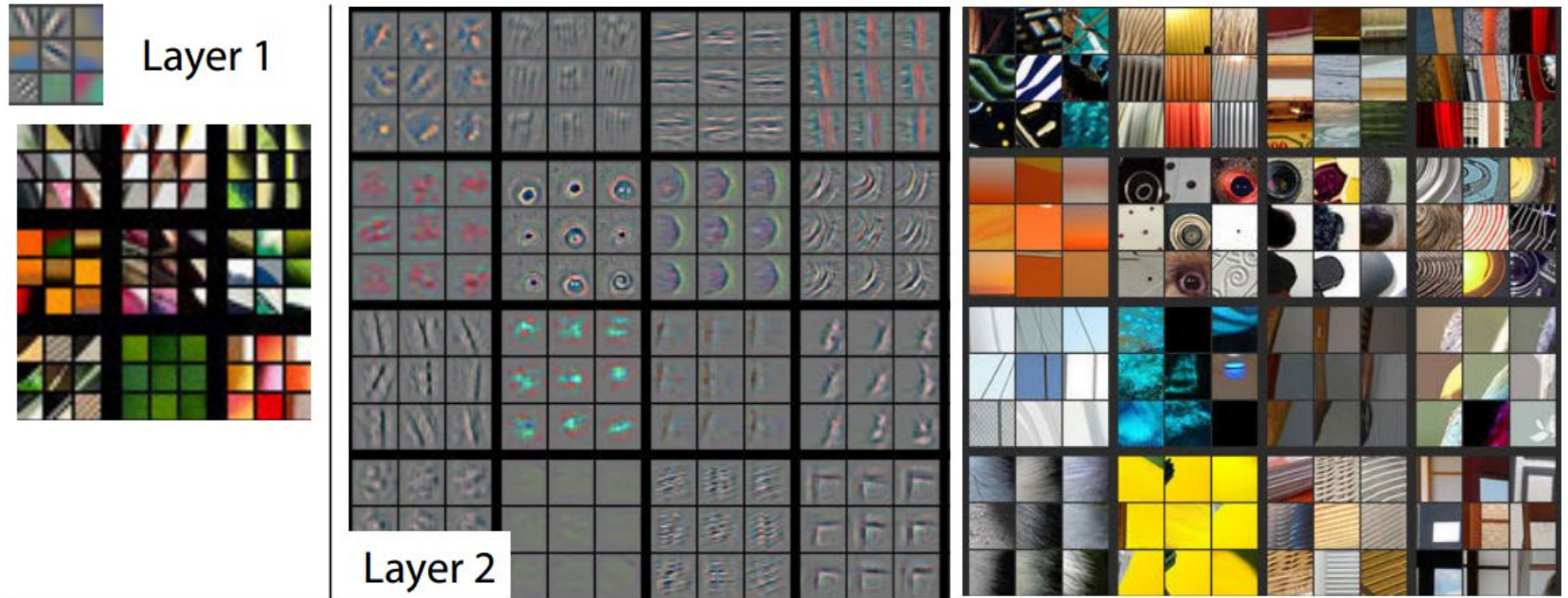
"Invertir" una red convolucional (Deconvolución)



"Invertir" una red convolucional (Deconvolución)

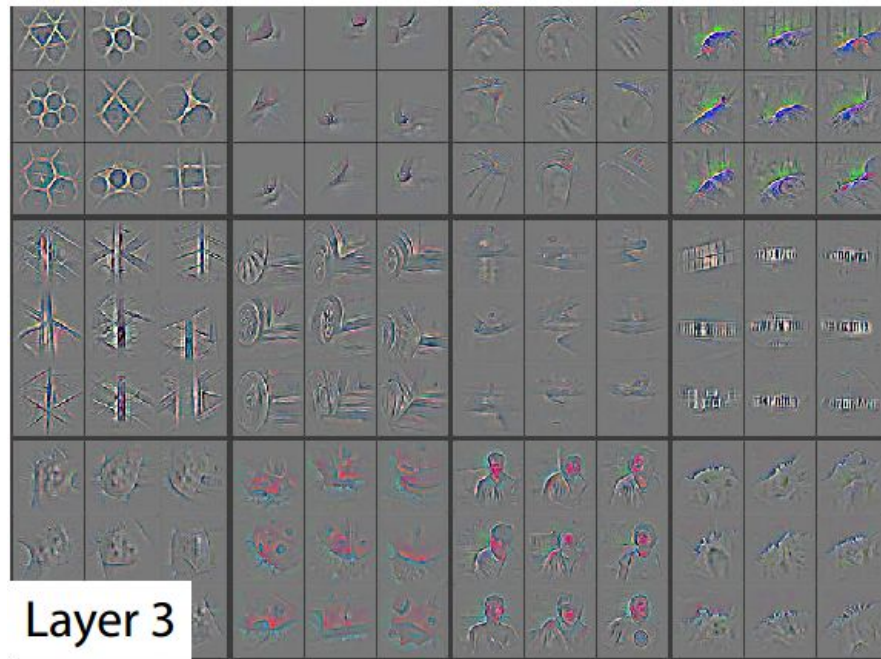
1. Presentar un ejemplo y computar las activaciones.
2. Para examinar una activación dada, poner en cero el resto de las activaciones de la capa.
3. Partiendo de ahí, aplicar sucesivamente unpool, rectify y deconv

Visualizing and understanding convolutional neural networks



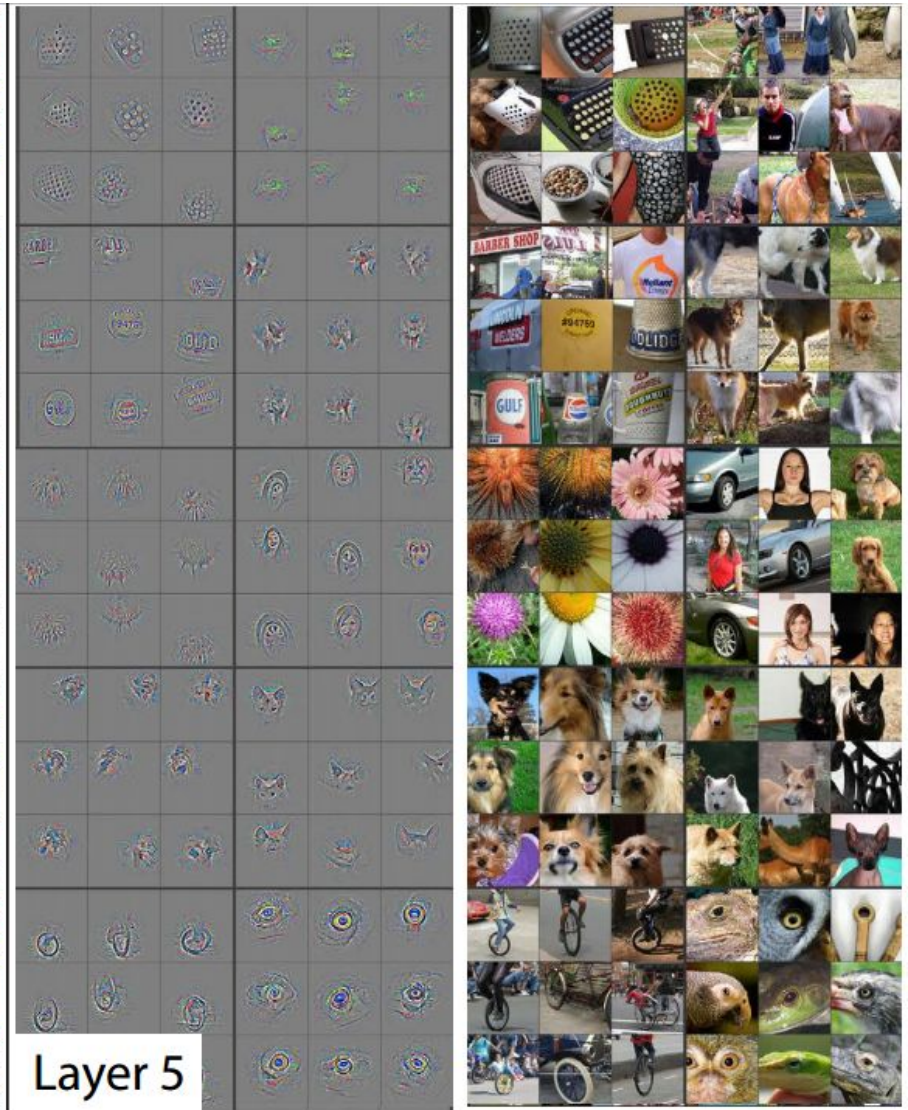
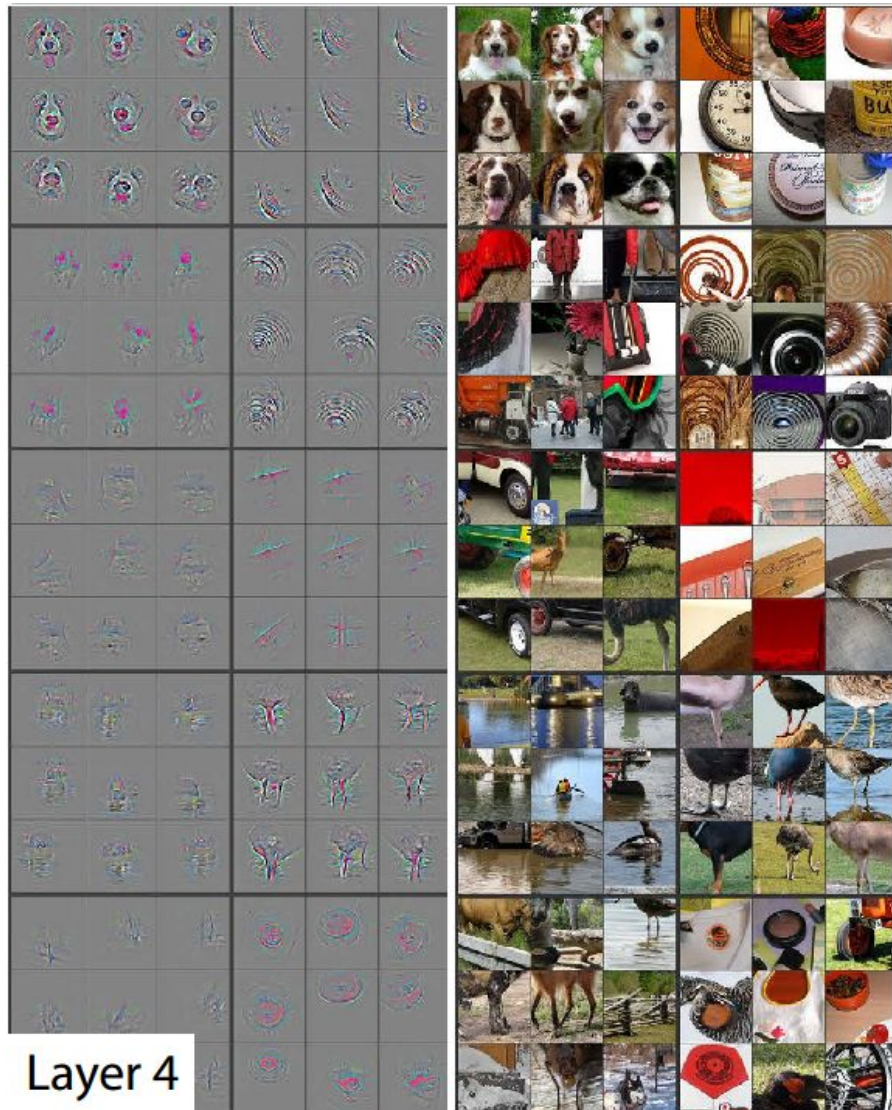
Zeiler, Matthew D, and Rob Fergus. "Visualizing and understanding convolutional neural networks." *arXiv preprint arXiv:1311.2901* (2013).

Visualizing and understanding convolutional neural networks

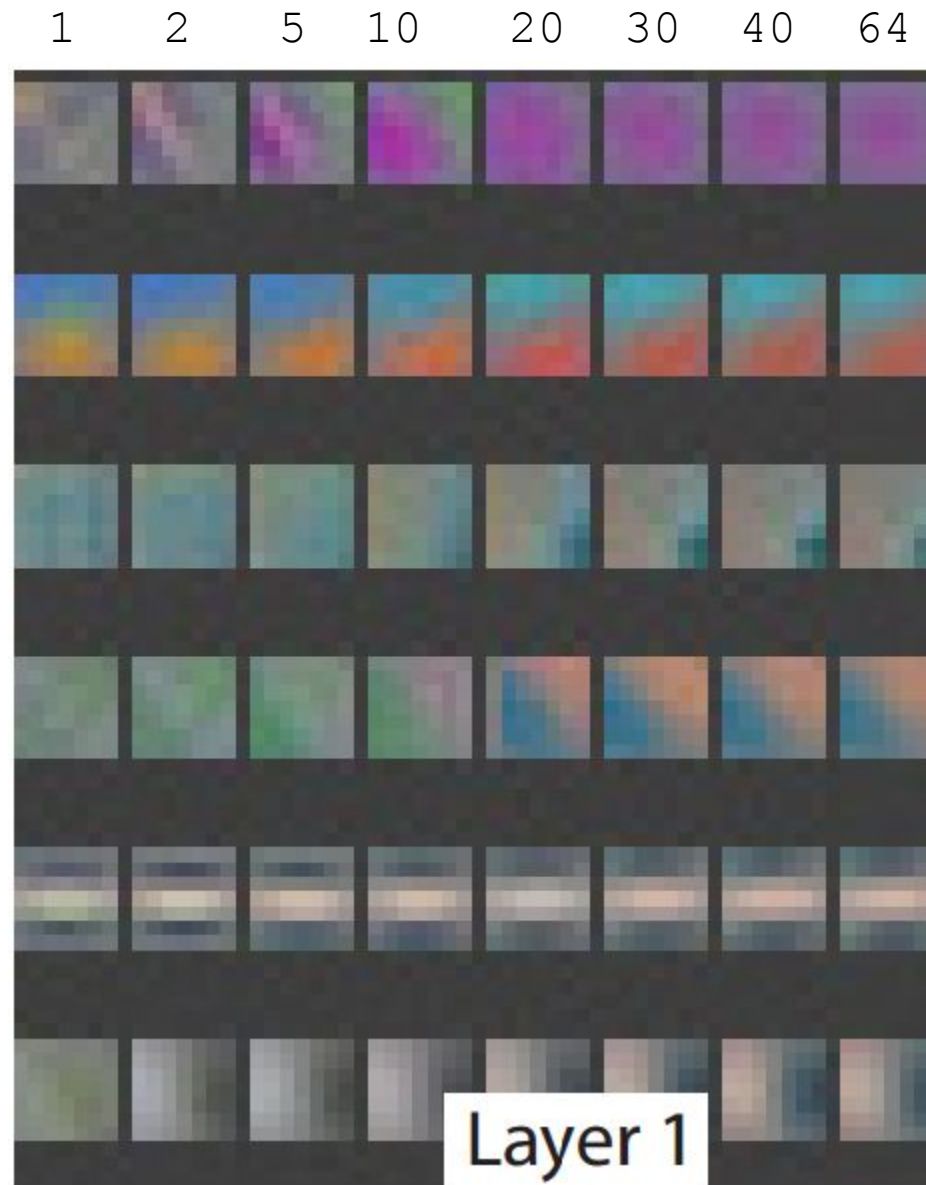


Zeiler, Matthew D, and Rob Fergus. "Visualizing and understanding convolutional neural networks." *arXiv preprint arXiv:1311.2901* (2013).

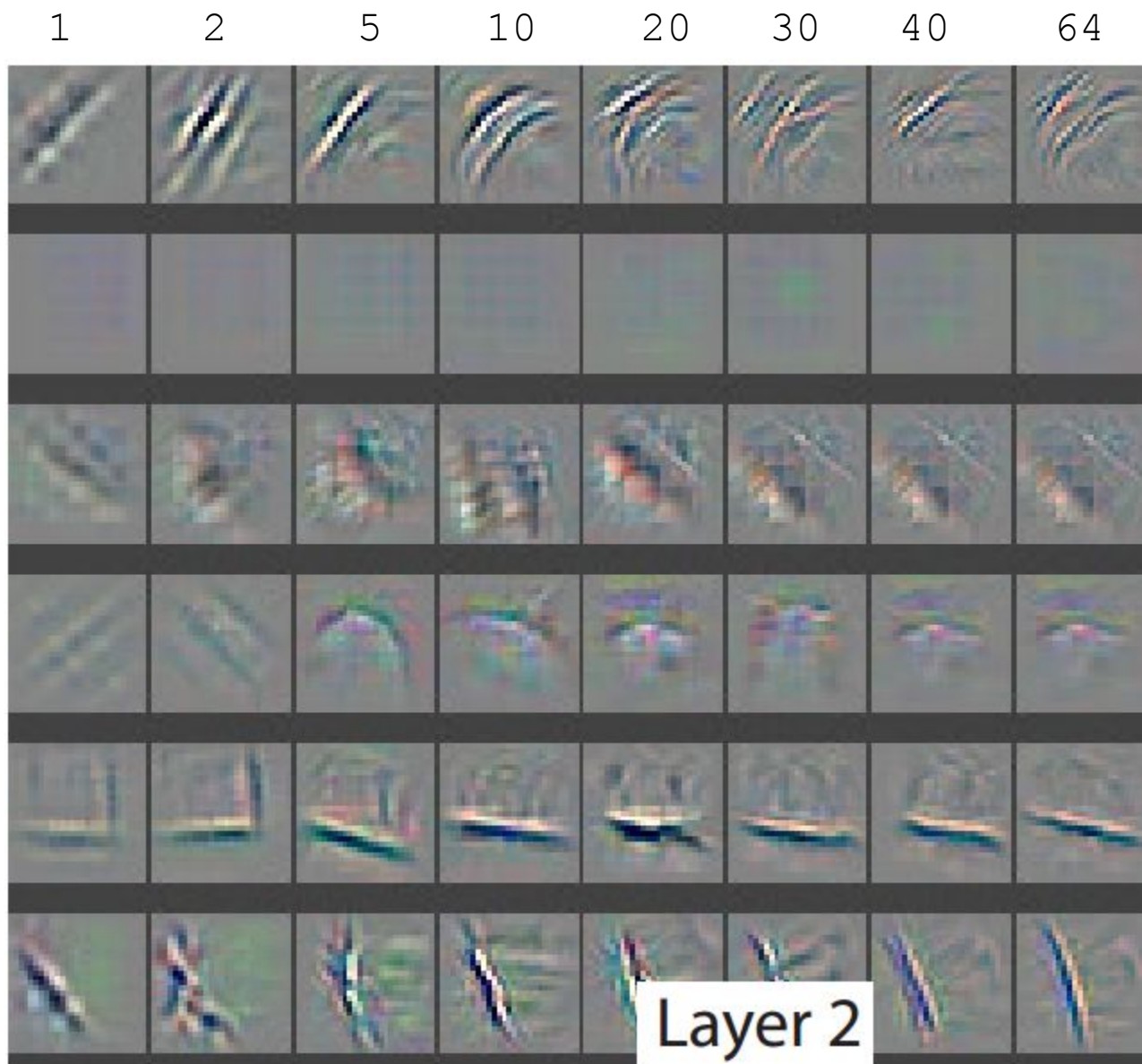
Visualizing and understanding convolutional neural networks



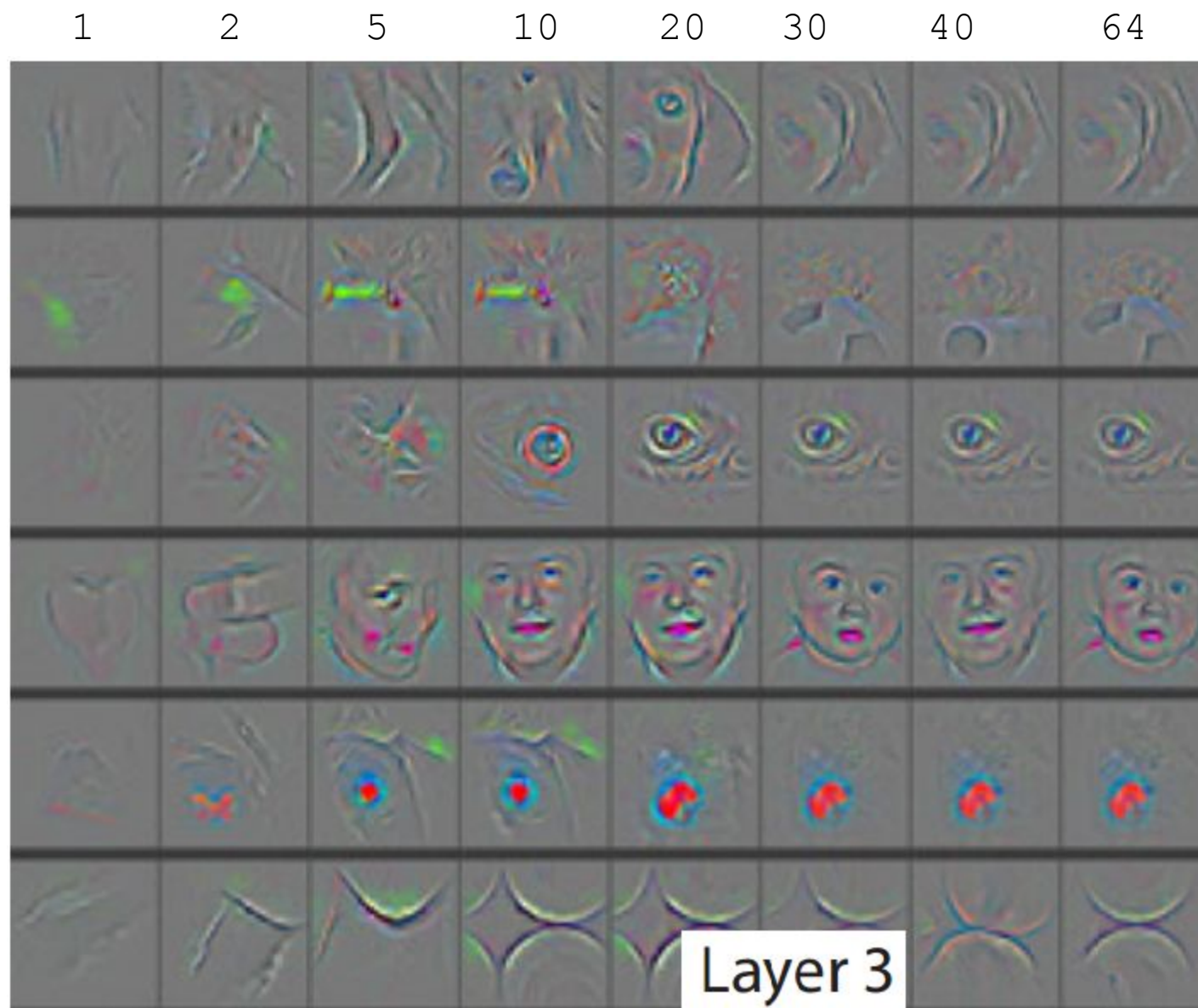
Evolución de la red con las épocas



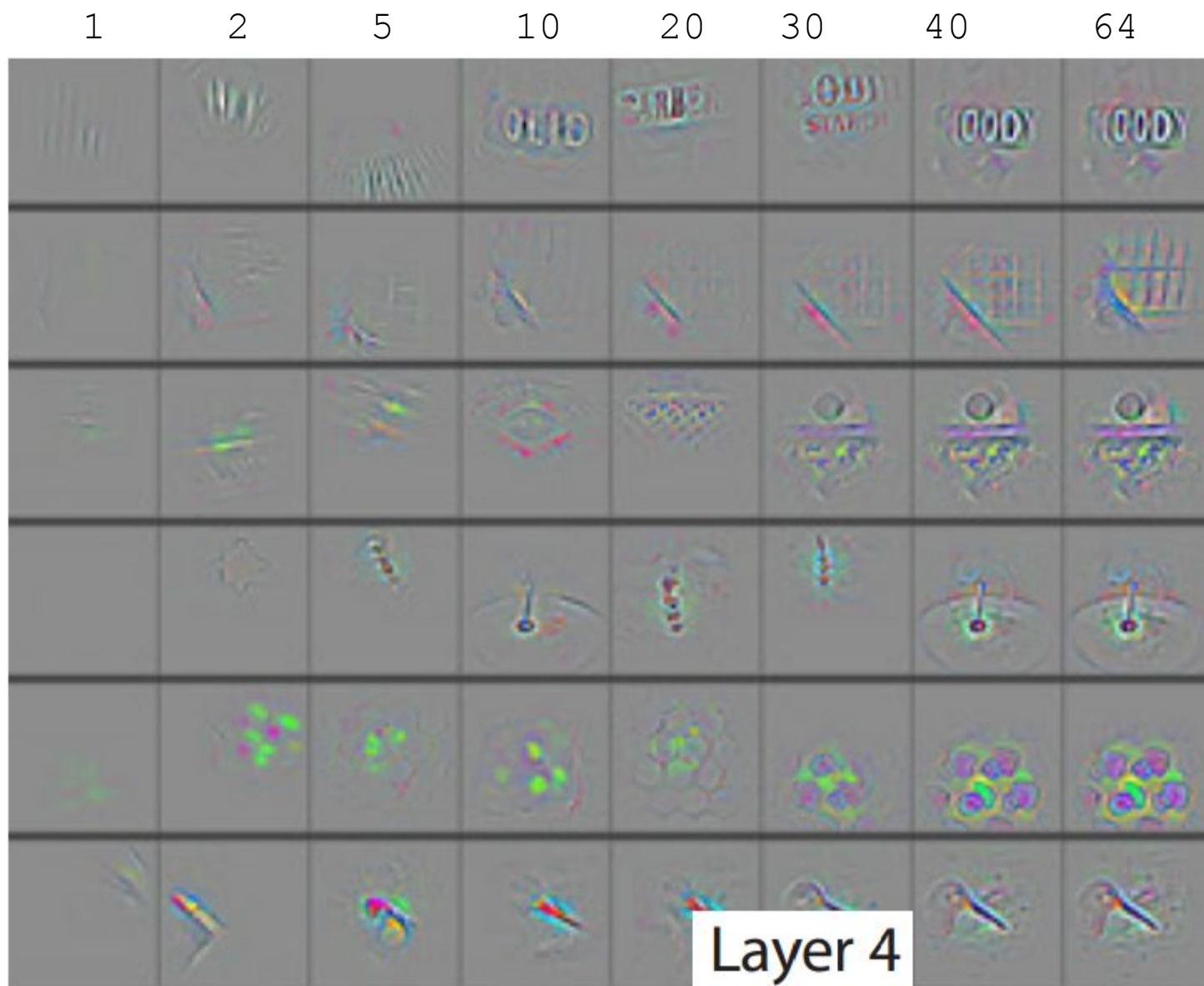
Evolución de la red con las épocas



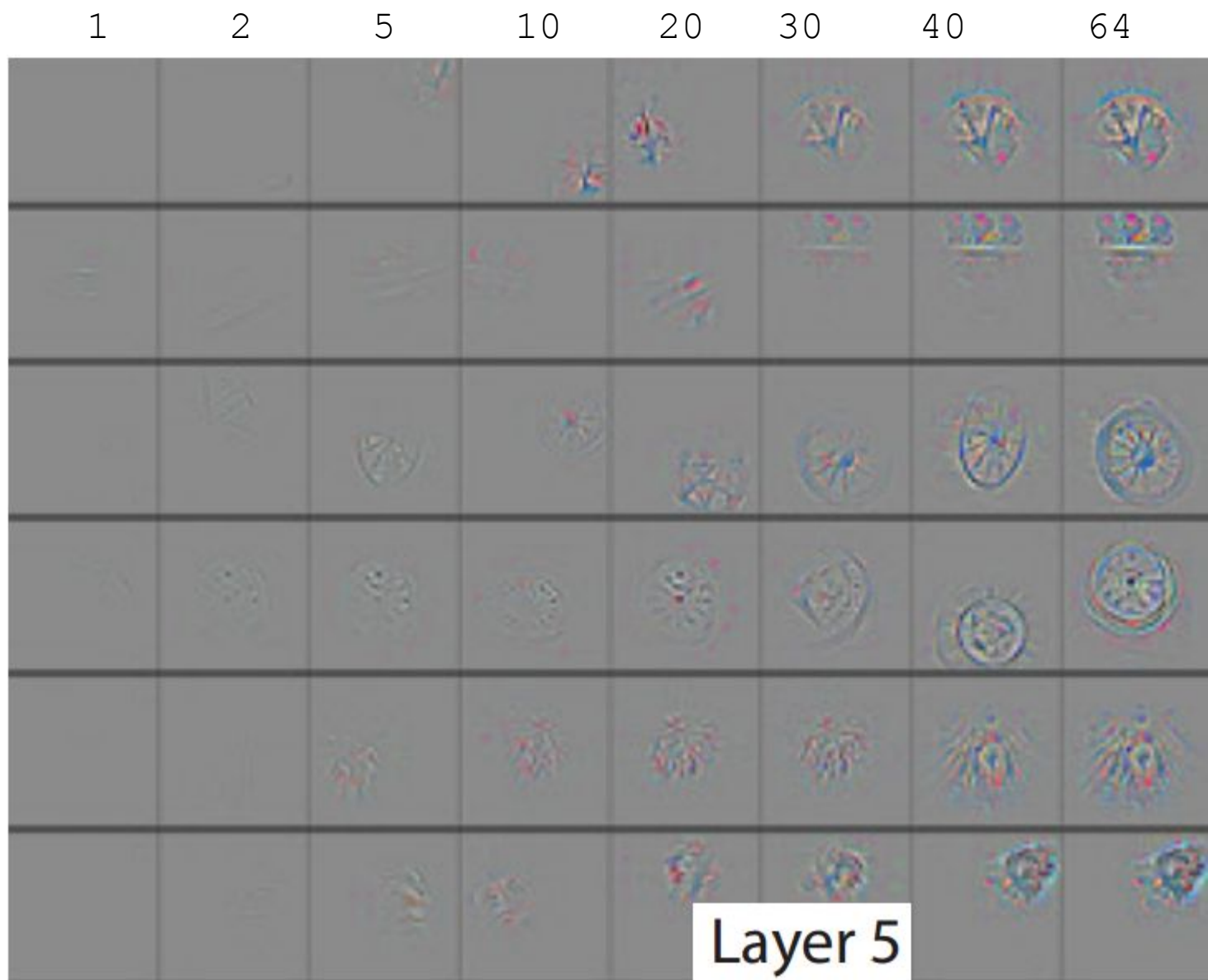
Evolución de la red con las épocas



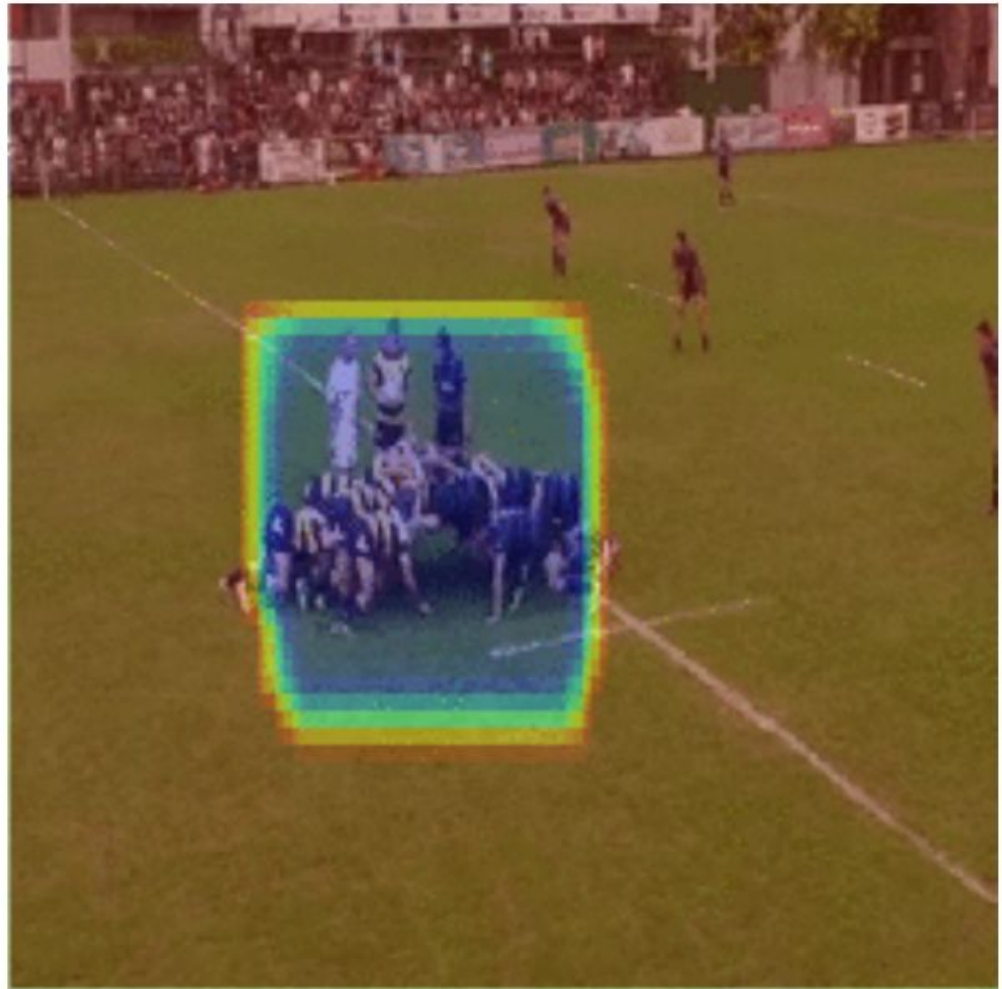
Evolución de la red con las épocas



Evolución de la red con las épocas

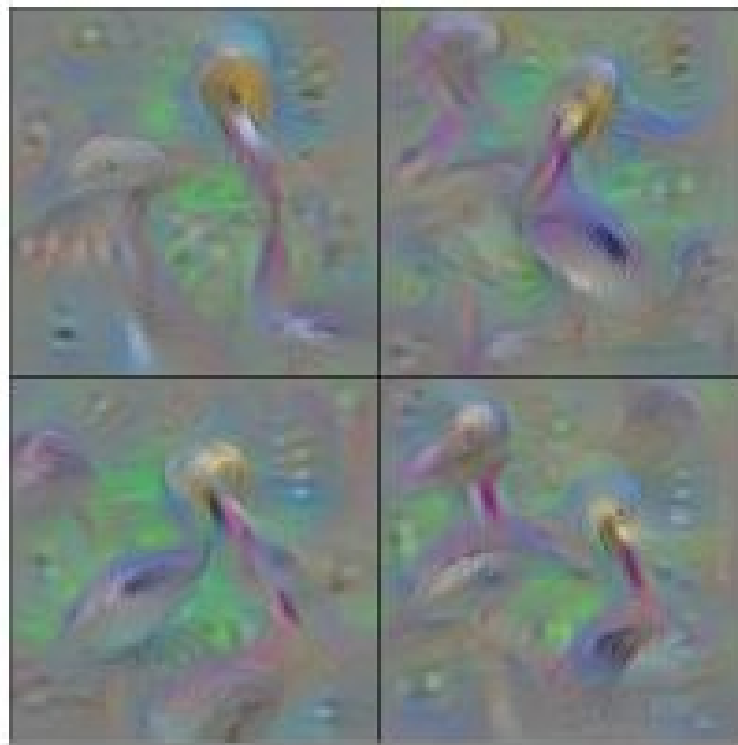


Visualización por oclusión



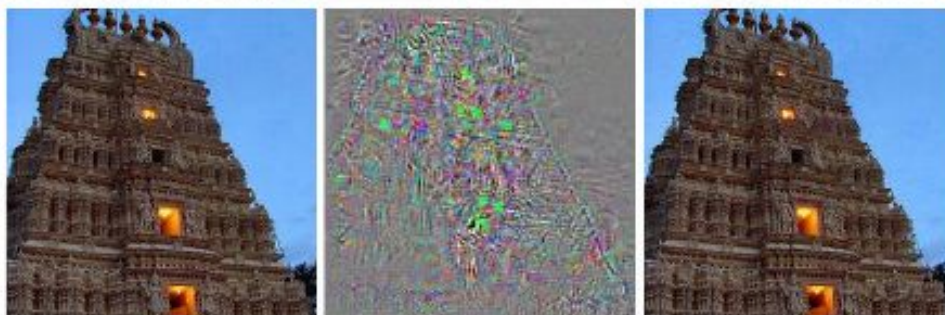
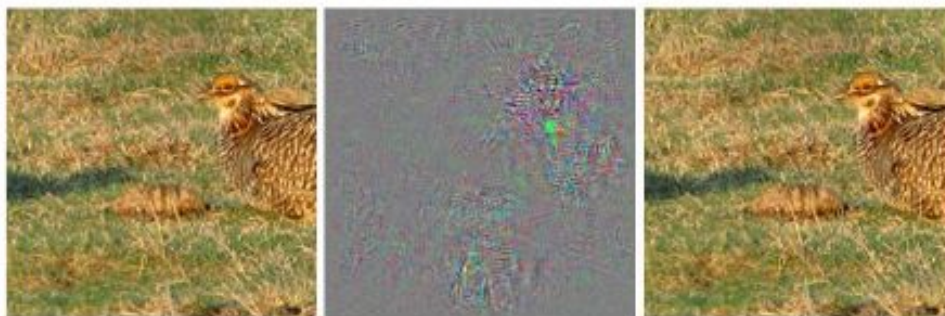
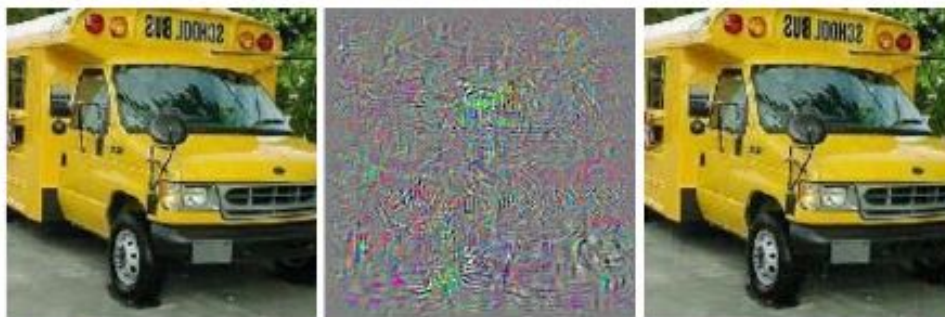
Optimización sobre imágenes

Partiendo de una imagen formada por ceros, maximizar la probabilidad de la clase “Pelicano”



Optimización sobre imágenes

Partiendo de una imagen bien clasificada, hacer que se clasifique como “Avestruz”



correct

+distort

ostrich

Trabajo Práctico 3

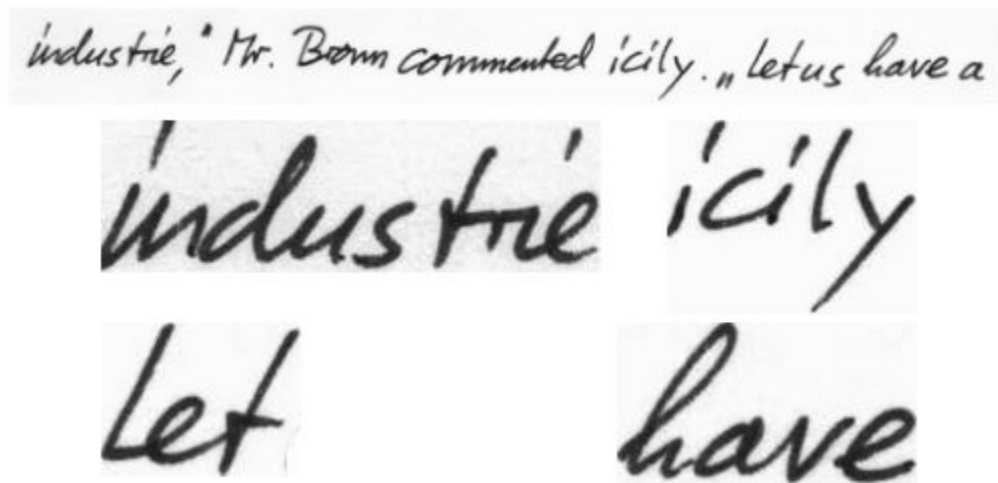
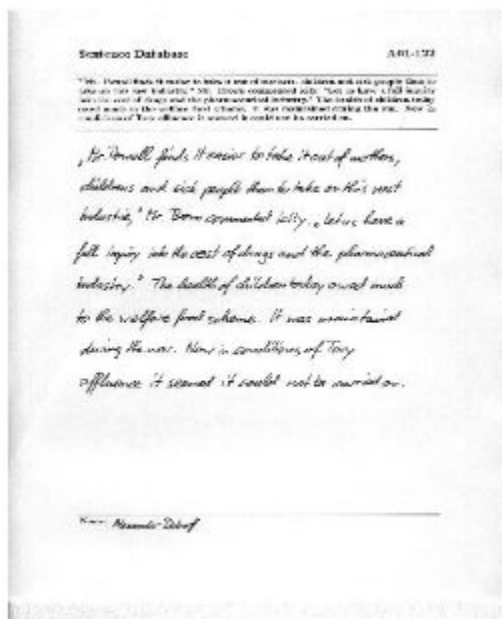
Observaciones sobre el dataset

IAM Handwriting Database

<http://www.fki.inf.unibe.ch/databases/iam-handwriting-database>

- forms of handwritten English text
- year 2002
- were scanned at a resolution of 300dpi
- PNG images with 256 gray levels.

The figure below provides samples of a complete form, a text line and some extracted words.



IAM Handwriting Database

- 657 writers contributed samples of their handwriting
- 1'539 pages of scanned text
- 5'685 isolated and labeled sentences
- 13'353 isolated and labeled text lines
- 115'320 isolated and labeled words

No presenta segmentación al nivel
de caracteres

Large Writer Independent Text Line Recognition Task

This task consists of a total number of 9'862 text lines. It provides one training, one testing, and two validation sets. The text lines of all data sets are mutually exclusive, thus each writer has contributed to one set only.

Train	6161	283
Validation 1	900	46
Validation 2	940	43
Test	1861	128

Informal talks at Lancaster House will resume today. PRESIDENT KENNEDY today defended the appointment of a Negro as his Housing Minister. It has aroused strong opposition from the anti-Negro senators of the Deep South. The negro is Mr. Robert Weaver of New York. One of his tasks will be to see there is no racial discrimination in Government and State housing projects.

¿Cómo armamos
nuestro dataset de
caracteres?

Informal talks at Lancaster House will
resume today. President Kennedy today
defended the appointment of a Negro as
his Housing Minister. It has aroused
strong opposition from the anti-Negro
senators of the Deep South. The negro

his Housing Minister. It has aroused
and State housing projects.

B. Kaufman

Name:

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Como cotas verticales se utilizó como referencia la desviación estándar vertical del renglón completo

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Para la posición horizontal, se partió de la segmentación de palabras. Se estimó la posición horizontal relativa de cada caracter tomando como referencia su posición en la versión digital de la palabra con una fuente cursiva.

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and State housing projects.

his Housing Minister. It has aroused

Muestras del dataset de caracteres obtenido

