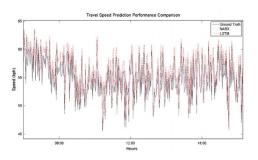
# Unidad 6: Redes Recurrentes

Curso: Redes Neuronales Profundas

#### **Datos Secuenciales**

na mirada panteísta donde un solo hombre inmortal es todos imbres y a su vez ninguno. Y a partir de esta idea también pue irmarse, como luego veremos, que un solo texto también dos los textos. Según Borges este relato vendría a ser osquejo de una ética para inmortales" y su tema "el efecto q inmortalidad causaría en los hombres". Este efecto lo descri orges a través del autor implícito del relato, el anticuario Jose artaphilus, quien narra la vida del tribuno romano Mar aminio Rufo. Así podremos presenciar en este relato la voz 1 hombre que fue todos y a la vez fue nadie, ya que fueron "labras de otros [...] la pobre limosna que le dejaron las hora s siglos". El texto presente nos servirá para hacer una reflexi

#### time series



#### handwriting

speech

```
Reque de Mondeur D. Monney red

la somme de pour cents francs, pour un

hemeste de senson abmentaire pour

le mineur Marie formetres.

Le Get Hemes the commètée le fet fair

urant et finisant le 31 faillet procham

Legianty Paris le 12 fair 1890

a Norme de Mondeur D. Monney red

a Norme de Mondeur D. Monney red

a Norme de Mondeur D. Monney red

a nome de Mondeur D. Monney rour

le mineur De la senson abmentaire pour

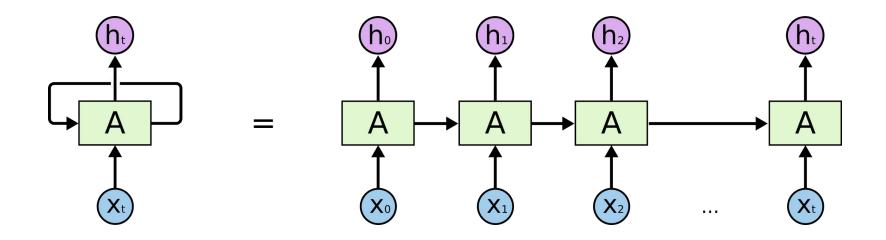
le mineur Marie formet red.
```

code

stock market

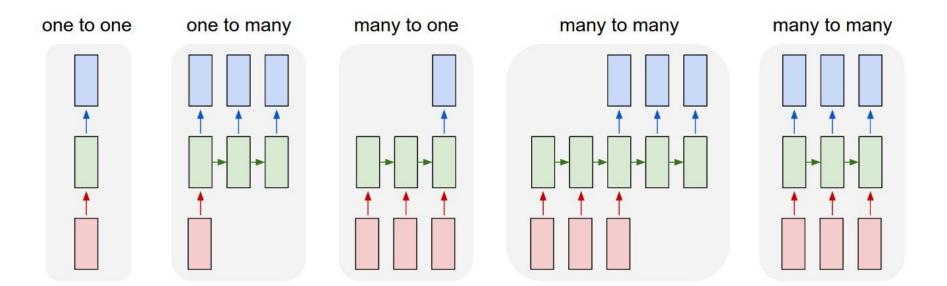


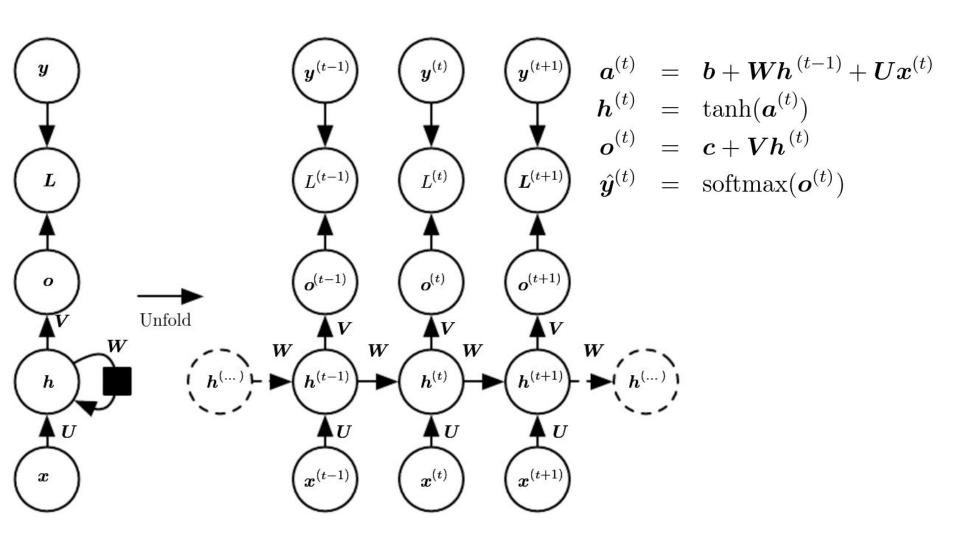
from colah's blog http://colah.github.io/posts/2015-08-Understanding-LSTMs/



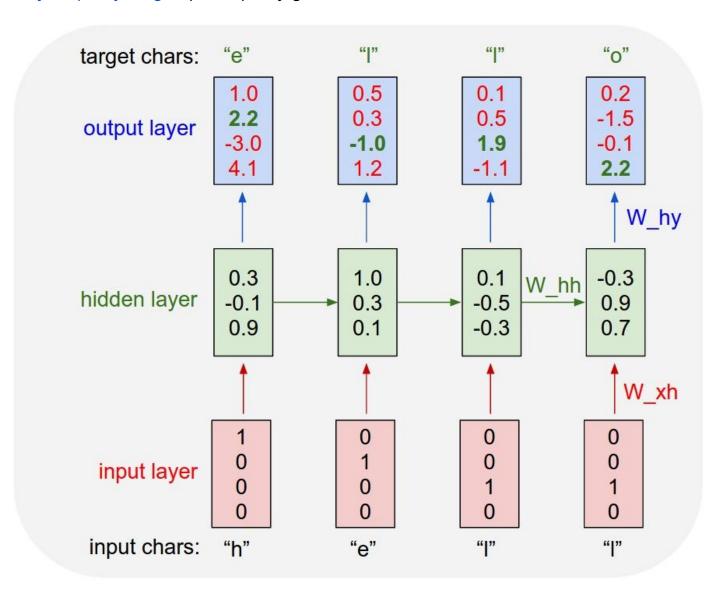
Neural Network with a loop

**Unfolded Computational Graph** 





from Andrej Karpathy blog http://karpathy.github.io/2015/05/21/rnn-effectiveness/



#### **RNN: Problems**

Ejemplo artificial: Reconocer secuencias de la forma

 $A^nB^n$ 

AAAAAABBBBBB AABB AAAAAAAAABBBBBBBB

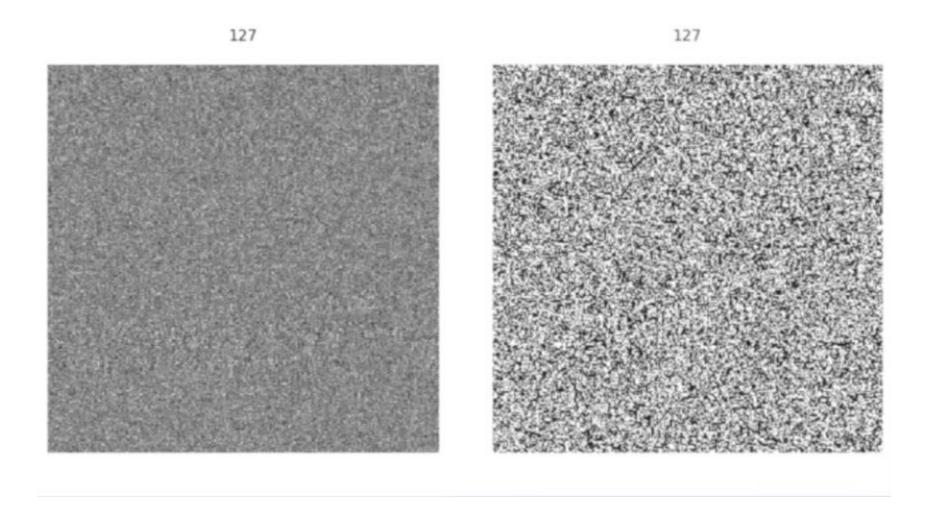
Train: n hasta 11. Test: n hasta 18.

Resultado: Calamitoso, 20% accuracy

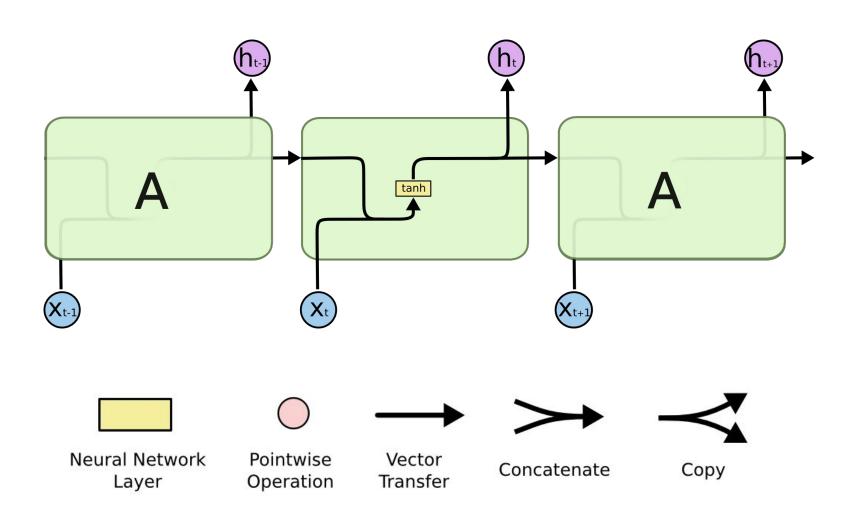


Veremos un modelo que logra 100% accuracy con n = 1000

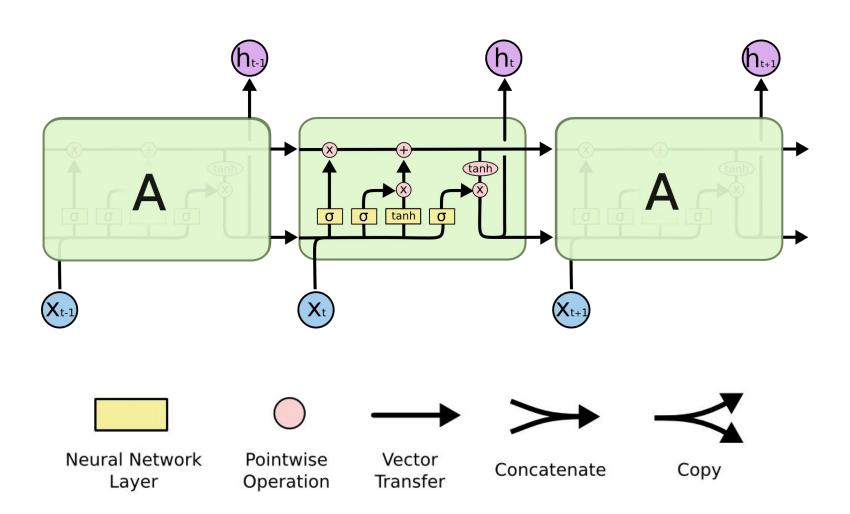
## **RNN: Vanishing Gradient Problem**



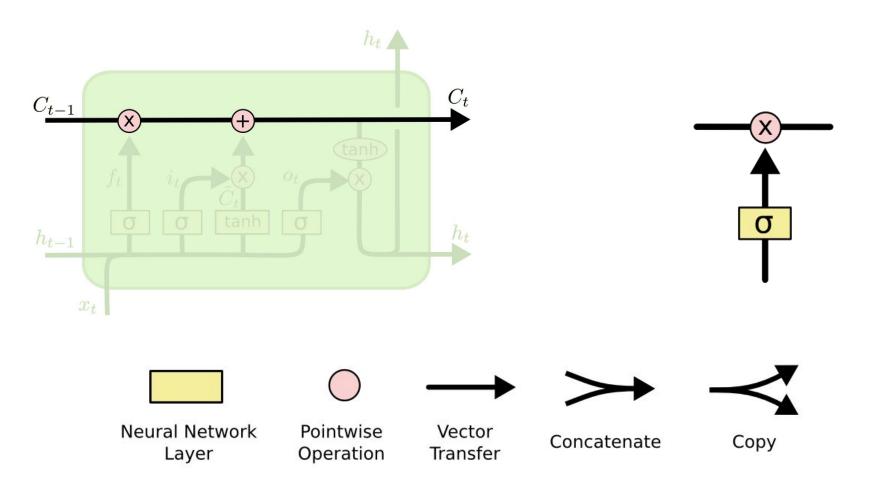
from colah's blog http://colah.github.io/posts/2015-08-Understanding-LSTMs/



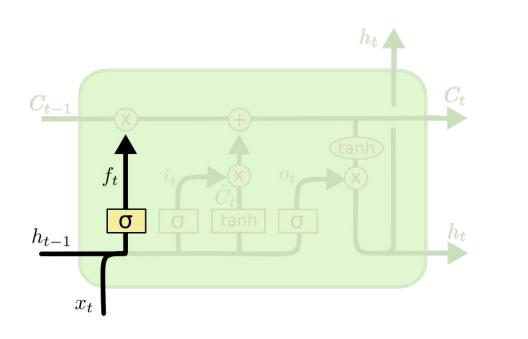
from colah's blog http://colah.github.io/posts/2015-08-Understanding-LSTMs/



from colah's blog http://colah.github.io/posts/2015-08-Understanding-LSTMs/



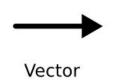
from colah's blog http://colah.github.io/posts/2015-08-Understanding-LSTMs/



$$f_t = \sigma\left(W_f \cdot [h_{t-1}, x_t] + b_f\right)$$







Transfer

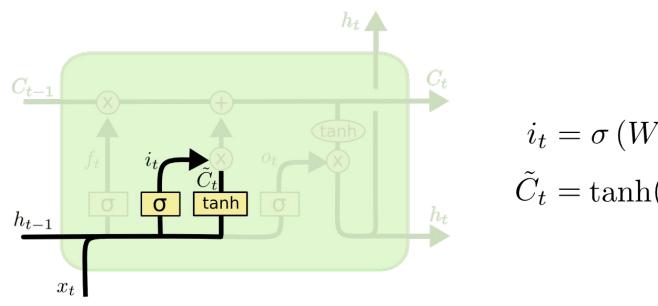




Concatenate

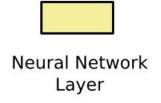
Copy

from colah's blog http://colah.github.io/posts/2015-08-Understanding-LSTMs/



$$i_t = \sigma\left(W_i \cdot [h_{t-1}, x_t] + b_i\right)$$

$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$





Pointwise Operation



Vector Transfer

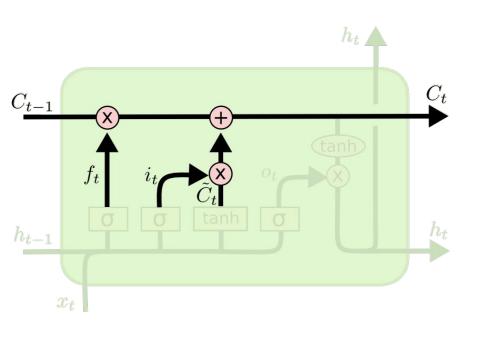


Concatenate

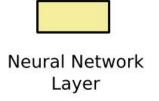


Copy

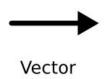
from colah's blog http://colah.github.io/posts/2015-08-Understanding-LSTMs/



$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$







Transfer

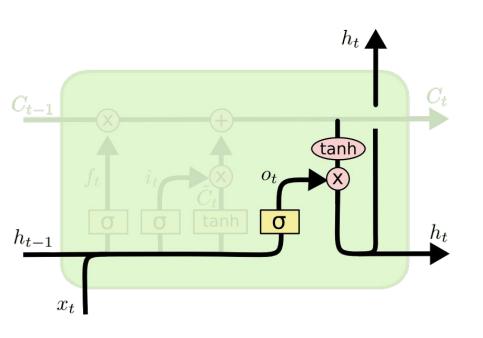




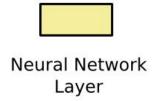


Copy

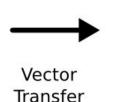
from colah's blog http://colah.github.io/posts/2015-08-Understanding-LSTMs/



$$o_t = \sigma (W_o [h_{t-1}, x_t] + b_o)$$
$$h_t = o_t * \tanh (C_t)$$











Concatenate

Copy

## LSTM: Sampled Wikipedia articles

from Andrej Karpathy blog http://karpathy.github.io/2015/05/21/rnn-effectiveness/

Naturalism and decision for the majority of Arab countries' capitalide was grounded by the Irish language by [[John Clair]], [[An Imperial Japanese Revolt]], associated with Guangzham's sovereignty. His generals were the powerful ruler of the Portugal in the [Protestant Immineners]], which could be said to be directly in Cantonese Communication, which followed a ceremony and set inspired prison, training. The emperor travelled back to [[Antioch, Perth, October 25|21]] to note, the Kingdom of Costa Rica, unsuccessful fashioned the [[Thrales]], [[Cynth's Dajoard]], known in western [[Scotland]], near Italy to the conquest of India with the conflict.

#### LSTM: Sampled Linux source code

from Andrej Karpathy blog http://karpathy.github.io/2015/05/21/rnn-effectiveness/

```
* Increment the size file of the new incorrect UI FILTER group information
* of the size generatively.
static int indicate policy(void)
                                                      segaddr = in SB(in.addr);
 int error;
                                                      selector = seq / 16;
 if (fd == MARN EPT) {
                                                      setup works = true;
    * The kernel blank will coeld it to userspace.
                                                      for (i = 0; i < blocks; i++) {</pre>
                                                        seq = buf[i++];
   if (ss->segment < mem total)</pre>
     unblock graph and set blocked();
                                                        bpf = bd->bd.next + i * search;
   else
                                                        if (fd) {
     ret = 1;
   goto bail;
                                                           current = blocked;
 segaddr = in SB(in.addr);
 selector = seq / 16;
 setup works = true;
 for (i = 0; i < blocks; i++) {</pre>
   seq = buf[i++];
   bpf = bd->bd.next + i * search;
   if (fd) {
     current = blocked;
 rw->name = "Getjbbregs";
 bprm self clearl &iv->version);
 regs->new = blocks[(BPF STATS << info->historidac)] | PFMR CLOBATHINC SECONDS << 12;
 return seqtable;
```

# Unidad 6: Redes Recurrentes

Curso: Redes Neuronales Profundas

- Recurrent Neural Network (RNN)
- Long Short Term Memory (LSTM)
- Sentiment analysis on movie reviews
- <u>Large Movie Review Dataset</u> (IMDB dataset)
- Task: given a movie review, predict whether it is positive or negative.

```
import numpy as np
from keras.preprocessing import sequence
from keras.models import Sequential
from keras.layers import Embedding, Dense, LSTM
from keras.datasets import imdb
```

```
max_features = 20000
max_length = 80
embedding_dim = 256
```

```
Camera SeaWorld porpoise dolphin
```

```
max features = 20000
max length = 80
embedding dim = 256
model = Sequential()
model.add(Embedding(max features, embedding dim,
                    input length=max length,
                    dropout=0.2))
model.add(LSTM(output dim=embedding dim,
               dropout W=0.2,
               dropout U=0.2,
               consume less='gpu', unroll=False))
```

```
model = Sequential()
model.add(Embedding(max features, embedding dim,
                    input length=max length,
                    dropout=0.2))
model.add(LSTM(output dim=embedding dim, dropout W=0.2,
               dropout U=0.2, consume less=mode))
model.add(Dense(1, activation='sigmoid'))
model.compile(loss='binary_crossentropy',
              optimizer='adam',
              metrics=['accuracy'])
```

## Testing mode = 'cpu'

Train on 25000 samples, validate on 25000 samples

```
Epoch 1/10 - 35s - loss: 0.5445 - acc: 0.7162 - val_loss: 0.3777 - val_acc: 0.8338

Epoch 2/10 - 35s - loss: 0.3812 - acc: 0.8404 - val_loss: 0.3804 - val_acc: 0.8330

Epoch 3/10 - 35s - loss: 0.3176 - acc: 0.8677 - val_loss: 0.3713 - val_acc: 0.8410

Epoch 4/10 - 35s - loss: 0.2674 - acc: 0.8898 - val_loss: 0.4061 - val_acc: 0.8317

Epoch 5/10 - 35s - loss: 0.2286 - acc: 0.9102 - val_loss: 0.4070 - val_acc: 0.8305

Epoch 6/10 - 35s - loss: 0.1903 - acc: 0.9277 - val_loss: 0.4435 - val_acc: 0.8266

Epoch 7/10 - 35s - loss: 0.1622 - acc: 0.9375 - val_loss: 0.5855 - val_acc: 0.8156

Epoch 8/10 - 35s - loss: 0.1412 - acc: 0.9468 - val_loss: 0.5214 - val_acc: 0.8233

Epoch 9/10 - 35s - loss: 0.1300 - acc: 0.9502 - val_loss: 0.5882 - val_acc: 0.7984

Epoch 10/10 - 35s - loss: 0.1170 - acc: 0.9549 - val_loss: 0.5502 - val_acc: 0.8191
```

mode = 'cpu' preprocesses input to the LSTM which typically results in faster computations at the expense of increased peak memory usage as the preprocessed input must be kept in memory.

## Testing mode = 'mem'

Train on 25000 samples, validate on 25000 samples

```
Epoch 1/10 - 34s - loss: 0.5531 - acc: 0.7056 - val_loss: 0.4007 - val_acc: 0.8204
Epoch 2/10 - 34s - loss: 0.3868 - acc: 0.8360 - val_loss: 0.3890 - val_acc: 0.8268
Epoch 3/10 - 34s - loss: 0.3237 - acc: 0.8625 - val_loss: 0.4675 - val_acc: 0.8200
Epoch 4/10 - 34s - loss: 0.2717 - acc: 0.8910 - val_loss: 0.3785 - val_acc: 0.8323
Epoch 5/10 - 34s - loss: 0.2288 - acc: 0.9105 - val_loss: 0.4086 - val_acc: 0.8367
Epoch 6/10 - 34s - loss: 0.1956 - acc: 0.9249 - val_loss: 0.4562 - val_acc: 0.8263
Epoch 7/10 - 34s - loss: 0.1615 - acc: 0.9382 - val_loss: 0.4849 - val_acc: 0.8222
Epoch 8/10 - 34s - loss: 0.1377 - acc: 0.9480 - val_loss: 0.4977 - val_acc: 0.8213
Epoch 9/10 - 34s - loss: 0.1241 - acc: 0.9537 - val_loss: 0.5055 - val_acc: 0.8166
Epoch 10/10- 34s - loss: 0.1118 - acc: 0.9574 - val_loss: 0.5692 - val_acc: 0.8201
```

mode = 'mem' does away with the preprocessing, meaning that it might take a little longer, but should require less peak memory.

## Testing mode = 'gpu'

Train on 25000 samples, validate on 25000 samples

```
Epoch 1/10 - 20s - loss: 0.4951 - acc: 0.7595 - val_loss: 0.4459 - val_acc: 0.8022
Epoch 2/10 - 20s - loss: 0.3549 - acc: 0.8503 - val_loss: 0.3978 - val_acc: 0.8324
Epoch 3/10 - 20s - loss: 0.2939 - acc: 0.8785 - val_loss: 0.3868 - val_acc: 0.8299
Epoch 4/10 - 20s - loss: 0.2479 - acc: 0.9032 - val_loss: 0.3935 - val_acc: 0.8301
Epoch 5/10 - 20s - loss: 0.2161 - acc: 0.9142 - val_loss: 0.4458 - val_acc: 0.8222
Epoch 6/10 - 20s - loss: 0.1896 - acc: 0.9252 - val_loss: 0.4551 - val_acc: 0.8246
Epoch 7/10 - 20s - loss: 0.1699 - acc: 0.9371 - val_loss: 0.4537 - val_acc: 0.8138
Epoch 8/10 - 20s - loss: 0.1446 - acc: 0.9453 - val_loss: 0.5767 - val_acc: 0.8053
Epoch 9/10 - 20s - loss: 0.1327 - acc: 0.9498 - val_loss: 0.4977 - val_acc: 0.8118
Epoch 10/10- 20s - loss: 0.1164 - acc: 0.9566 - val_loss: 0.5607 - val_acc: 0.8128
```

mode = 'gpu' concatenates the input, output and forget gate's weights into one, large matrix, resulting in faster computation time as the GPU can utilize more cores, at the expense of reduced regularization because the same dropout is shared across the gates.

## Image Captioning

Curso: Redes Neuronales Profundas

a man riding a bike on a dirt path through a forest. bicyclist raises his fist as he rides on desert dirt trail. this dirt bike rider is smiling and raising his fist in triumph. a man riding a bicycle while pumping his fist in the air. a mountain biker pumps his fist in celebration.



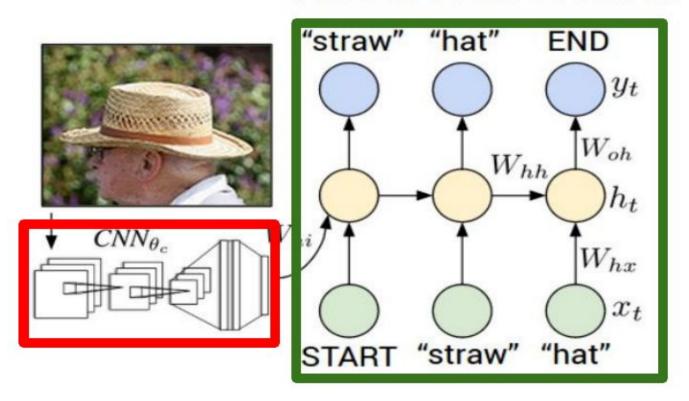
a man riding a bike on a dirt path through a forest. bicyclist raises his fist as he rides on desert dirt trail. this dirt bike rider is smiling and raising his fist in triumph. a man riding a bicycle while pumping his fist in the air. a mountain biker pumps his fist in celebration.

#### MS COCO - mscoco.org Alrededor de 300K imágenes



#### Estructura general

#### **Recurrent Neural Network**

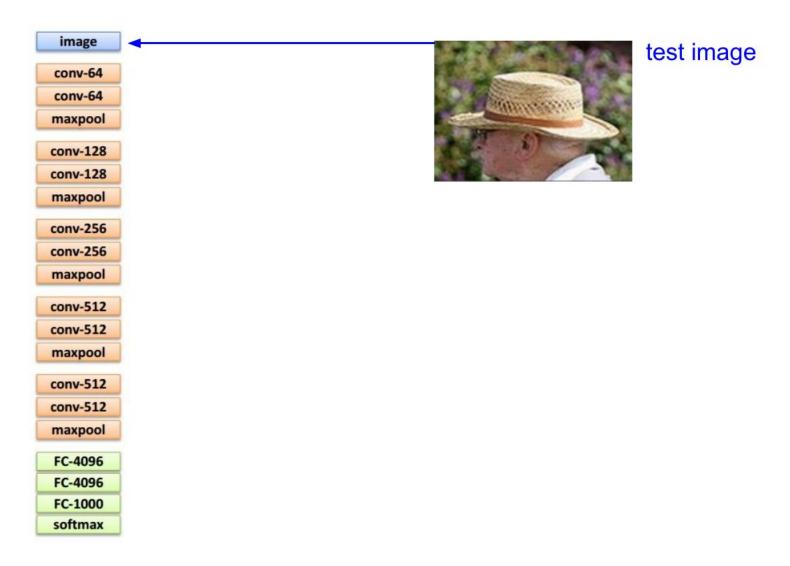


#### **Convolutional Neural Network**

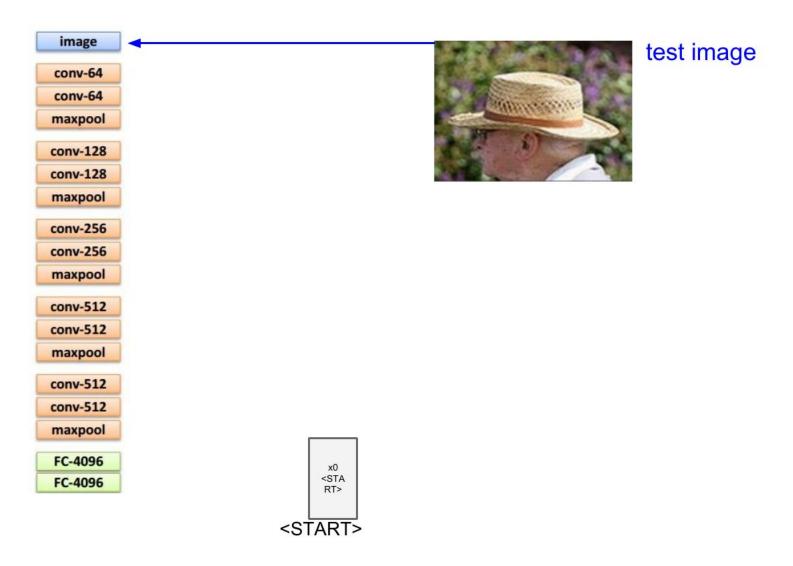
del curso de Fei-Fei, Karpathy y Johnson http://cs231n.stanford.edu

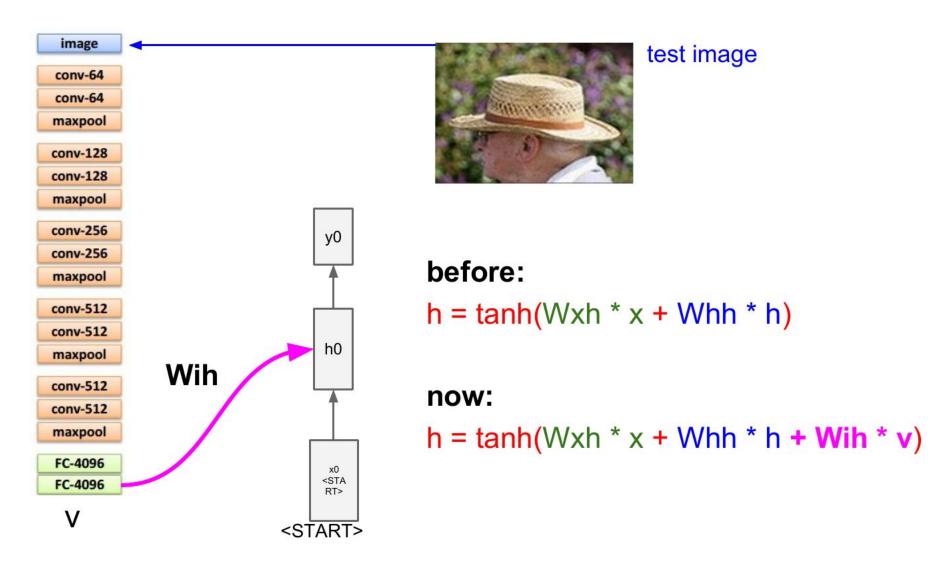


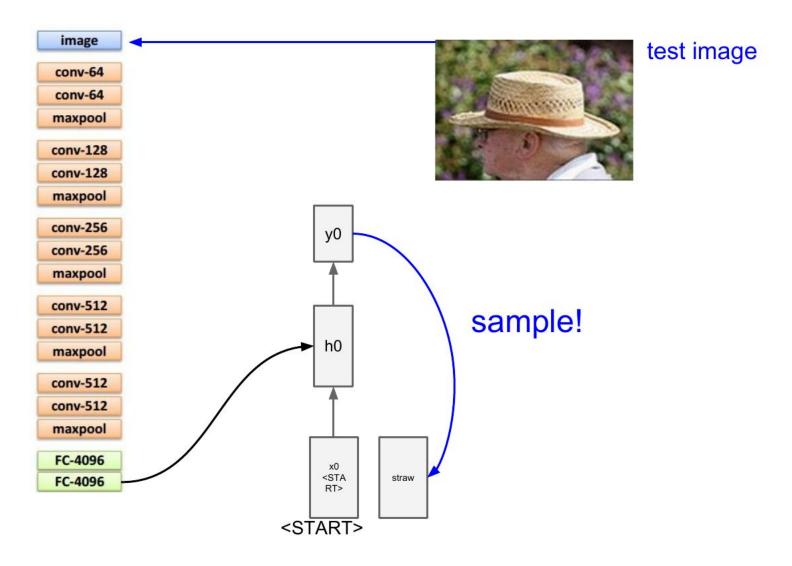
test image

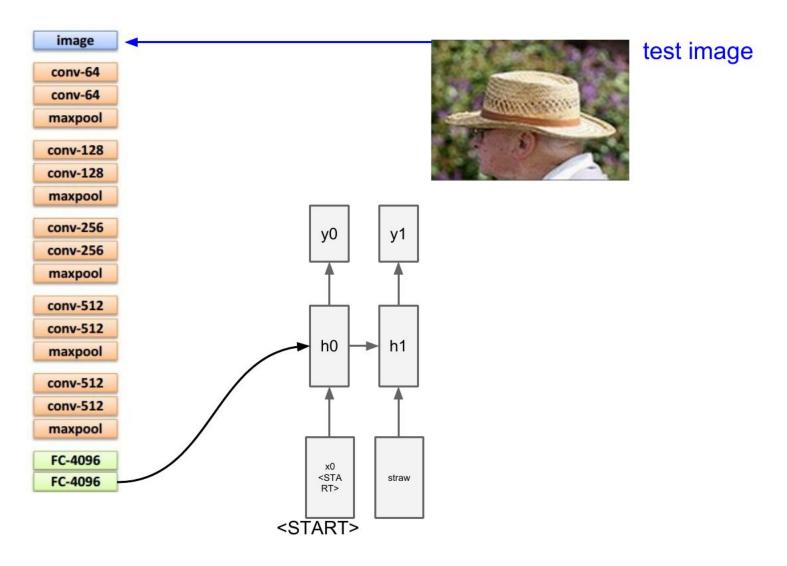


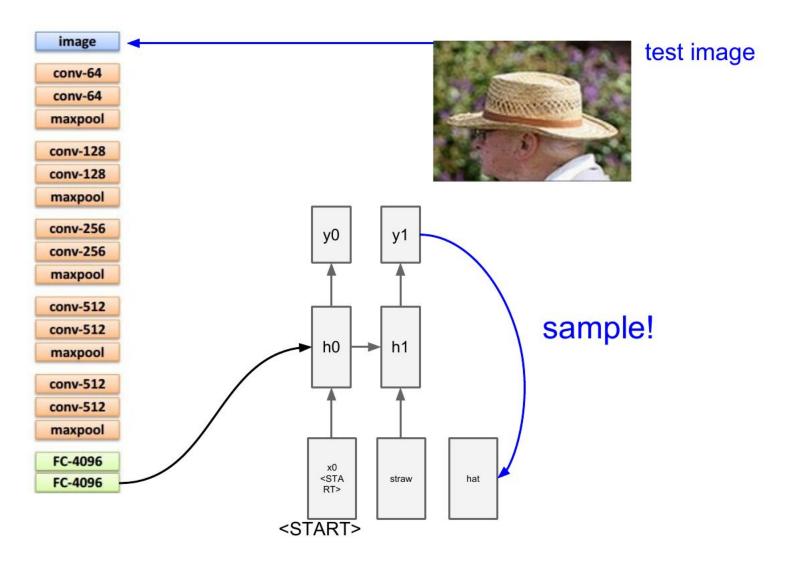


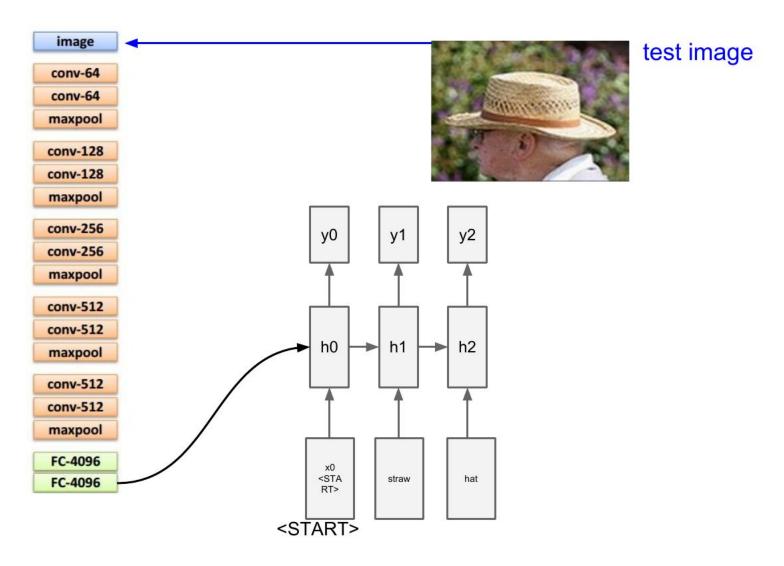


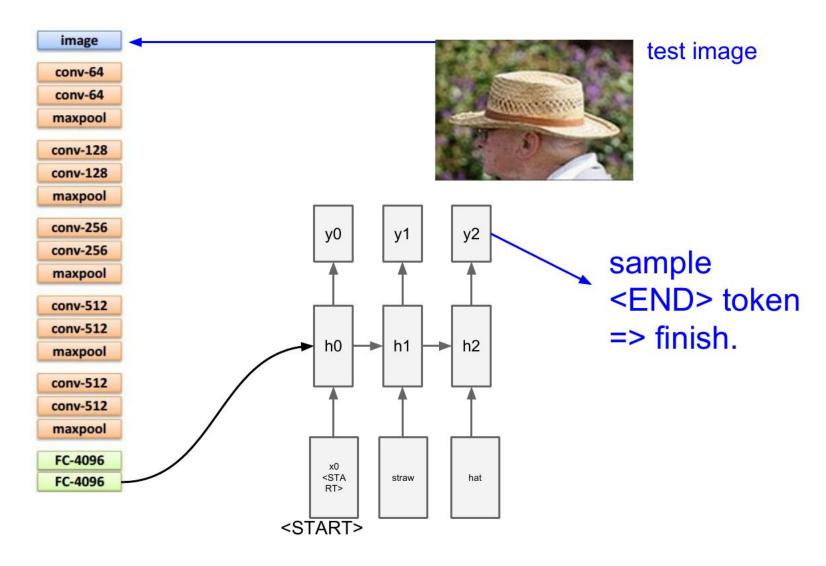












## Algunos Resultados

A person riding a motorcycle on a dirt road.



A group of young people



A herd of elephants walking across a dry grass field.



Two dogs play in the grass.



Two hockey players are



A close up of a cat laying on a couch.



A skateboarder does a trick



A little girl in a pink hat is



A red motorcycle parked on the



A dog is jumping to catch a



A refrigerator filled with lots of food and drinks.



A yellow school bus parked



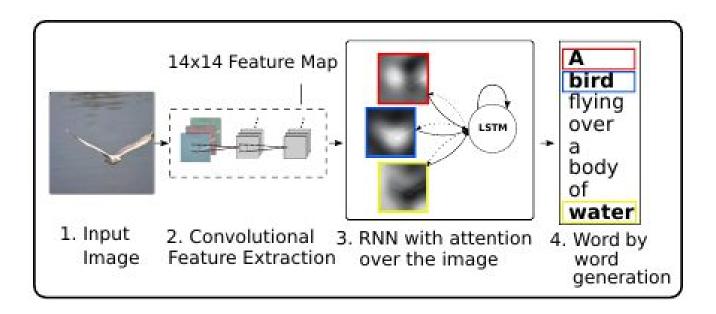
**Describes without errors** 

Describes with minor errors

Somewhat related to the image

Unrelated to the image

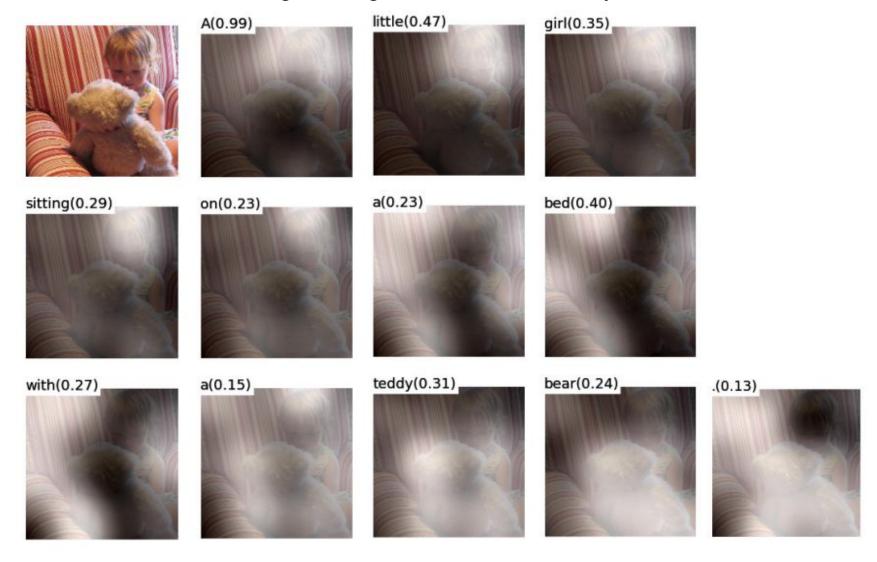
## Modelos más complejos



Agregado de un mecanismo de "atención": una máscara que multiplica al resultado de la CNN, que se actualiza en cada paso

Xu, K., Ba, J., Kiros, R., Cho, K., Courville, A., Salakhutdinov, R., ... & Bengio, Y. (2015). Show, attend and tell: Neural image caption generation with visual attention. *arXiv* preprint arXiv:1502.03044, 2(3), 5.

#### A little girl sitting on a bed with a teddy bear.



## Modelos más complejos



A woman is throwing a frisbee in a park.



A dog is standing on a hardwood floor.



A stop sign is on a road with a mountain in the background.



A little girl sitting on a bed with a teddy bear.



A group of <u>people</u> sitting on a boat in the water.



A giraffe standing in a forest with trees in the background.

Xu, K., Ba, J., Kiros, R., Cho, K., Courville, A., Salakhutdinov, R., ... & Bengio, Y. (2015). Show, attend and tell: Neural image caption generation with visual attention. *arXiv preprint arXiv:1502.03044*, *2*(3), 5.

## ¿Cómo medir performance?



Candidate: the the the the the.

Reference 1: The cat is on the mat.

Reference 2: There is a cat on the mat.



Candidate 1: I always invariably perpetu-

ally do.

Candidate 2: I always do.

Reference 1: I always do.

Reference 2: I invariably do.

Reference 3: I perpetually do.

# ¿Cómo medir performance?

Métricas: BLEU-1, ..., BLEU-4

Papineni, Kishore, et al. "BLEU: a method for automatic evaluation of machine translation." *Proceedings of the 40th annual meeting on association for computational linguistics*. Association for Computational Linguistics, 2002.

#### METEOR

Denkowski, Michael, and Alon Lavie. "Meteor universal: Language specific translation evaluation for any target language." In Proceedings of the Ninth Workshop on Statistical Machine Translation. 2014.