

# Computer Organization

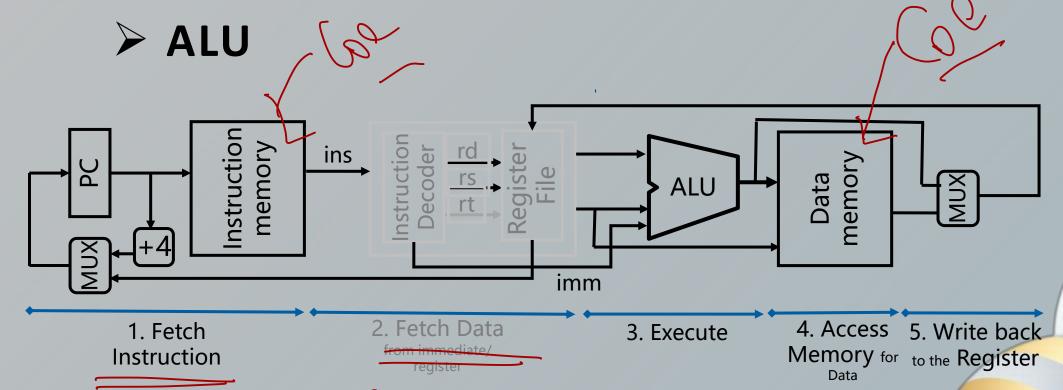
Lab10 CPU Design(2)

Data Path(2) IFetch, Dmemory, ALU



## Topic

- CPU(2) -DataPath (2)
  - > Data-Memory
  - > IFetch





### Von Neumann structure vs Harvard structure

	Dxffffffff	memory map limit address
	Dxffffffff	kernel space high address
	0xffff0000	MMIO base address
	Dxfffeffff	kernel data segment limit address
	0x90000000	.kdata base address
	0x8ffffffc	kernel text limit address
	0x80000180	exception handler address
	0x80000000	kernel space base address
Configuration —	0x80000000	.ktext base address
Default	Dx7fffffff	user space high address
Compact, Data at Address 0	Dx7fffffff	data segment limit address
Compact, Text at Address 0	Dx7ffffffc	stack base address stack pointer \$sp
	Dx7fffeffc	
	0x10040000	stack limit address
	0x10040000	heap base address
	0x10010000	.data base address
	0x10008000	global pointer \$gp
	0x10000000	data segment base address
	Dx10000000	.extern base address
	DxOffffffc	text limit address
	0x00400000	.text base address

Von Neumann architecture: data and instruction share the same memory.

The **Von Neumann architecture**, also known as the **Princeton** architecture, is centered around the fact that data and instructions are mixed and addressed together, meaning that their data and instructions are stored at different addresses in the same memory, and their widths must be the same. When transmitting instructions and data, both **share the** same program bus and data bus, so instructions and data cannot be operated simultaneously, and they can only be executed **sequentially**.

The data and instruction memory implemented in Mars (a simulator of MIPS32) is **Von Neumann architecture** (data and instruction share the same memory)

The characteristic of the **Harvard architecture** is that data and instructions are stored separately in two different memories: data memory and program memory.

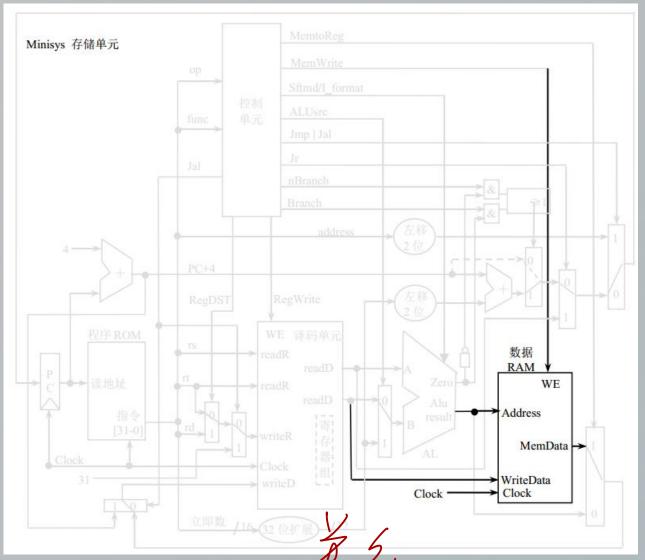
The buses of the two are used separately, and the buses are divided into data bus and address bus of program memory, as well as data bus and address bus of data memory. And the width of instructions and data can be different, while instructions and data can work in **parallel**.

In the next few pages of the courseware, we will introduce the implementation of the **Harvard architecture**.

TIPS: Harvard architecture here is just a refernece, not requirement!



### **Data-Memory**



module **dmemory32**(readData,address, writedata,memWrite,clock);

input clock; //'Clock' signal

/\* used to determine to write the memory unit or not, in the left screenshot its name is 'WE' \*/

input **memWrite**;

// the 'Address' of memory unit which is tobe read/writen

input[31:0] address;

// data tobe wirten to the memory unit

input[31:0] writeData;

 $^{\prime *}$ data to be read from the memory unit, in the left

screenshot its name is 'MemData' \*/

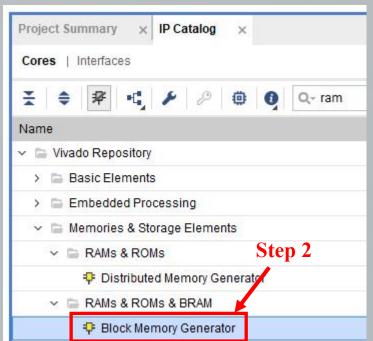
output[31:0] readData;



### Using IP core: Block Memory

**Using** the **IP core** 'Block Memory' of Xilinx to implement the Data-memory.





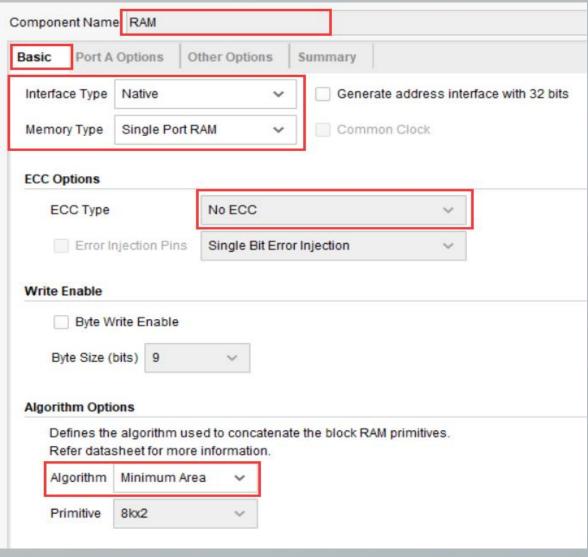
**Import** the **IP core** in vivado project

1) in "PROJECT MANAGER" window click "IP Catalog"

- 2) in "IP Catalog" window
  - > Vivado Repository
    - > Memories & Storage Elements
      - > RAMs & ROMs & BRAM
        - > Block Memory Generator



### **Customize Memory IP core**

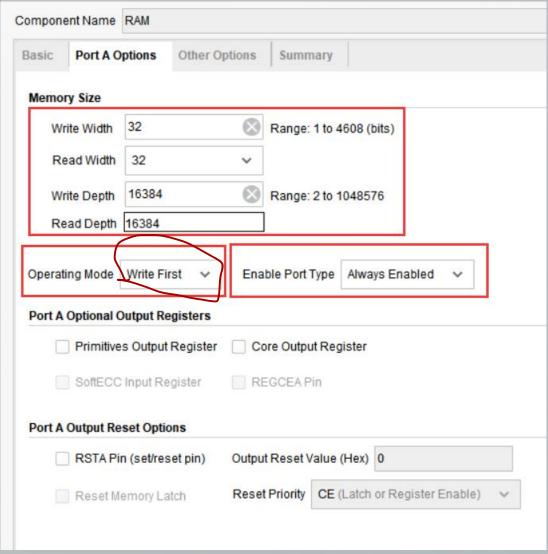


#### **Customize memory IP core**

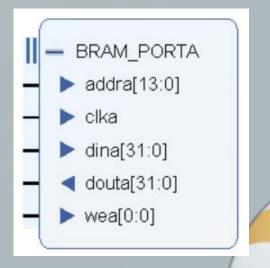
- **▶1)** Component Name: RAM
- **▶2)** Basic settings:
  - ➤ Interface Type: Native
  - ➤ Memory Type: Single-port RAM
  - ➤ ECC options: no ECC check
  - ➤ Algorithm options: Minimum area



### Customize Memory IP core continued

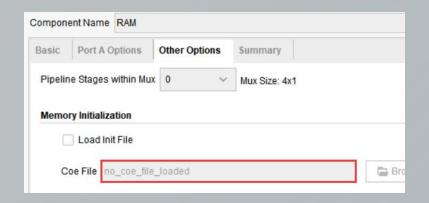


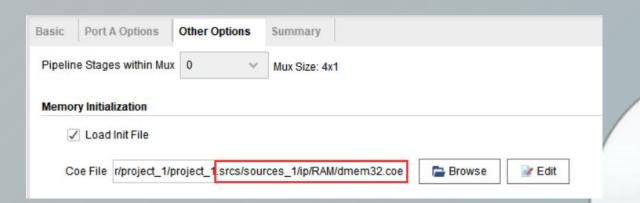
- 3) PortA Options settings:
  - > Data read and write bit width:
    - 32 bits (4Byte)
  - Write/Read Depth: 16384 (64KB)
  - ➤ Operating Mode: Write First
  - > Enable Port Type: Always Enabled
  - ➤ PortA Optional Output Registers: **NOT SET**



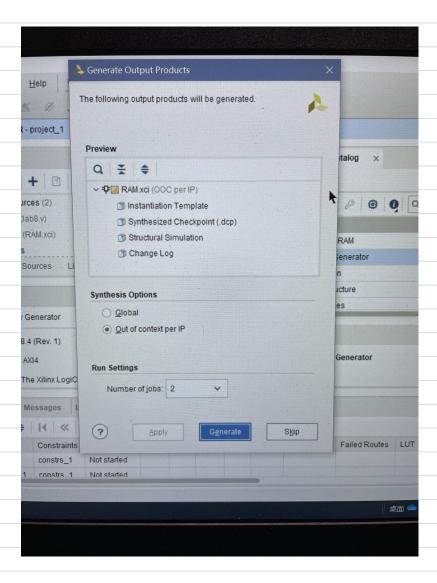
### Customize Memory IP core continued

- 4) Other Options settings:
  - > 1. When specifying the initialization file for customize the RAM on the 1st time, the IP core RAM just customized WITHOUT initial file and corresponding path, so set it to no initial file when creating RAM.
  - > 2. After the RAM IP core created The information of previous setting?
    - > 2-1. COPY the initialization file dmem32.coe to projectName.srcs/sources\_1/ip/ComponentName. ("projectName.srcs" is under the project folder, "componentName" here is 'RAM')
    - > 2-2. Double-click the newly created RAM IP core, RESET it with the initialization file, select the dmem32.coe file that has been in the directory of projectName.srcs/sources\_1/ip/RAM.





Tips: "dmem32.coe" file could be found in the directory "labs/lab10" of course blackboard site





## Design Module With Memory IP Instanced

```
BRAM PORTA
RAM ram (
                                                                                   addra[13:0]
                      Use the ip core in other wire clka
   clka (clk),
                                                                                   clka
    .wea(memWrite),module?
                                                                                   dina[34:0]
    .addra(address[15:2]),
                                                                                   douta[31:0]
    .dina(writeData),
                                                                                   wea[0:0]
    .douta(readData)
);
/*The 'clock' is from CPU-TOP, sup
                                 its one edge has been used at the upstream module of data memory, su
Why Data-Memroy DO NQT use the same edge as the module? */
assign clk > !clock;
```

**Q**: In the five stages of instruction processing, what operations must be arranged on the edge of the clock? What's your design for a one-cycle CPU?



### **Function Verification by simulation**

```
module ramTb(
reg clock = 1'b0;
reg memWrite Tb0;
reg [31:0] addr = 32'h0000 0010;
reg [31:0] writeData = 32'ha000 0000
wire [31:0] readData;
dmemory32 uram.
            (clock, memWrite, addr, writeData, readData);
always #50 clock = ~clock;
initial fork
        memWrite = 1'b1;
  #200
     writeData = 32'h0000 00f5;
  #400
    memWrite = 1'b0;
join
endmodule
```

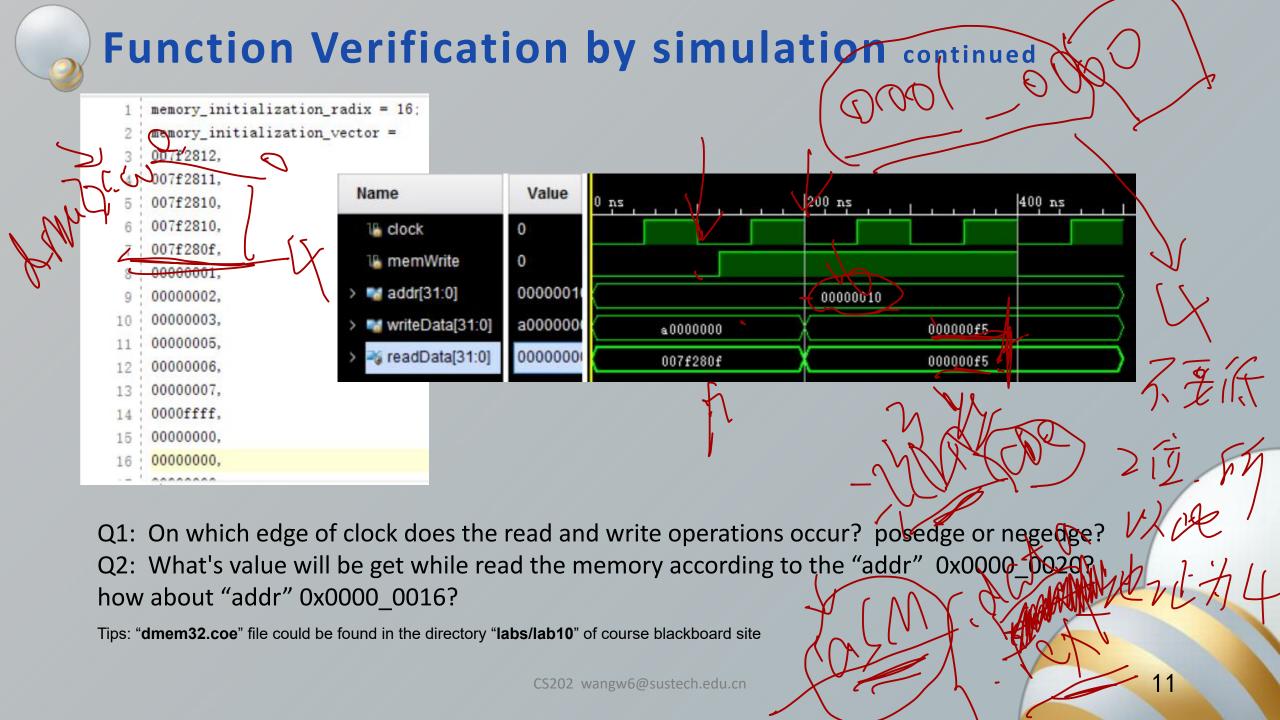
**NOTE:** 

Using bind port with name is Suggested!!

- 1) Set "memWrite" to 1'b0 means to read the data from the RAM unit identified by "addr".
- 2) Set "memWrite" to 1'b1 and "writeData" to 0x0000\_00f5 which means to write data 0xa000\_00f5 to the RAM unit identified by "addr".
- Q1. While instance the module on page 4(module dmemory32/readData address writedata memWrit

testbench on the left hand, What will hanppen?

**Q2.** While the data has been written to the RAM unit, would it be recorded to the initial data file(dmem32.coe)?





- 1. Build the data memory module.
- 2. Verify its function by simulation

(NOTE: The testbench on page 9 is JUST a reference)

- > Read the values one by one from memory unit where are specified in the red box of the screenshot on the right hand.
- ➤ Write a word(value is 0x1000\_0000) to the memory unit where is specified in the blue box of the screeshot on the right hand, then read it out.
- 3. List all the signals which are needed for data-memory module

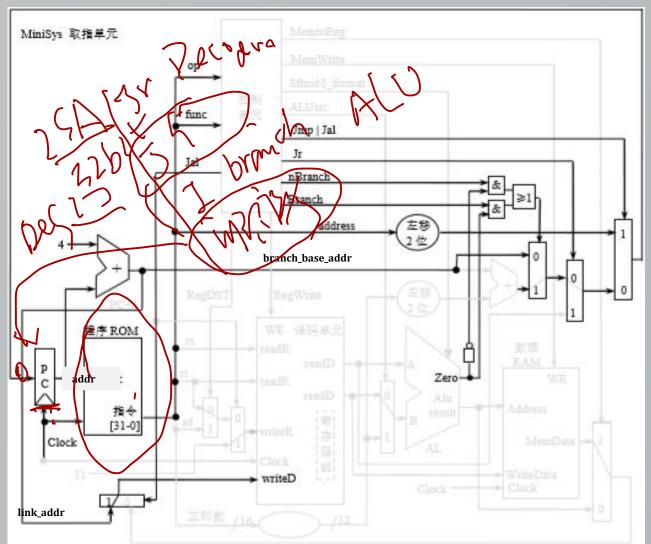
1 2 3 4 5 6 7 8 9 10 11 12 13	memory_initialization_radix = 16; memory_initialization_vector = 007f2812, 007f2811, 007f2810, 007f280f, 00000001, read these initial value  value
14 15 16 17 18 19 20 21	0000ffff, 00000000, 00000000, 00000000, 00000000

name	from	to	bits	function
clock	CPU-TOP	Data Memory	1	data memory write is sensitive with its negedge
rdata	Data Memory	Decoder	32	the word read from the data memory and send to decoder
memoryWrite	Controller	Data Memory	1	1'b1 means to write the memory unit, else means not to write
address	ALU	Data Memory	32	the address which is used to identify the memory unit tobe read or written

Tips: "dmem32.coe" file could be found in the directory "labs/lab10" of course blackboard site



### **Instruction Fetch**



The function of Instruction Fetch module

- 1. Store the instructions(machine-code)
- 2. **Update** the value of the PC register
  - Reset
  - PC+4
  - Update the value of the PC register according to the jump instructions
    - branch(beq,bne) [I-type]
    - jal, j [J-type]
    - jr [R-type]
- 3. Fetch the instructions according to the value of the PC register



### **Using IP core As Instruction Memory**

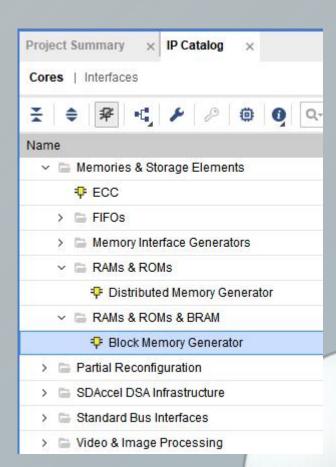
Step1: Find the IP core(Block Memory Generator) in IP Catalog

Step2: Customize the IP core

- set name(component name), type(ROM)
- set features of the ROM(width and depth), operation mode and register output
- set initial file

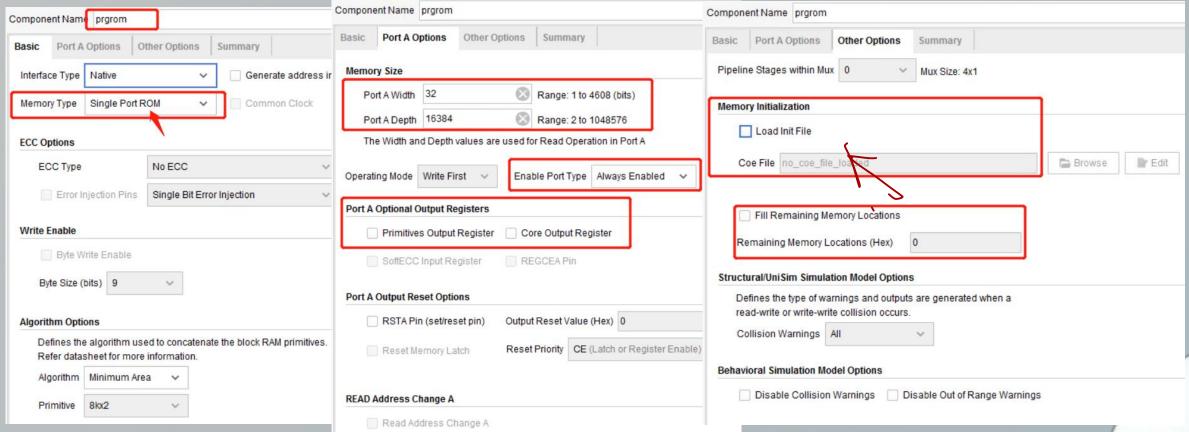
**Step3: Generate** the IP core, then it will be added to vivado project automatically

Tips: The setting steps of ROM IP core are almost same as which of the RAM IP core in Data-memory except the type is





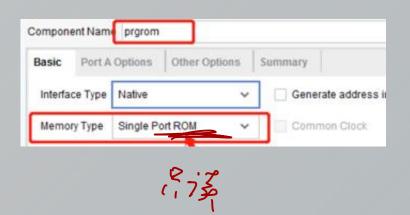
### Customize the IP core



**NOTE**: set the init file of prgrom after this IP core has been added into vivado project. Same steps as the RAM IP core used in Data-memory.



### Instance the IP core





```
prgrom instmem(
.clka(clock),
.addra(PC[15:2]),
.douta(Instruction)
);
```

In One Cycle CPU, the process of **geting instrcution** should **happen** on the **posedge** of the clock. At this moment, IFetch module gets the instruction which is store at "**addra**" from the instruction memory "Instmem"

Q: Why using PC[15:2] instead of PC[13:0] to bind with port "addra"?

TIPS: The same reason as the address bus used in Data-memory

?

clock = 1'b0;

repeat(5) **begin** 

#10 PC = PC+4:

#10 \$finish;

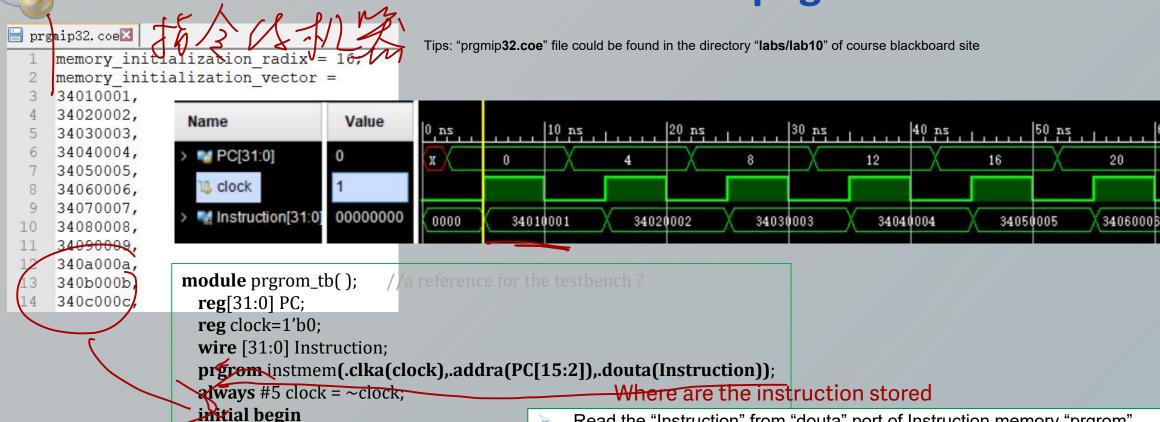
end

endmodule

end

#2 PC = 32'h0000 0000;

## The Function Verification of "prgrom"



- Read the "Instruction" from "douta" port of Instruction memory "prgrom" on every posedge of the "clock".
- In this tescase, the value of 'PC' is added with 4 each time.
- Q: How many instructions would be fetched in this testbench?

20



### **IFetch Module**

```
module IFetc32(Instruction, branch_base_addr, link_addr,
clock, reset.
Addr_result, Read_data_1, Branch, nBranch, Jmp, Jal, Jr, Zero);
  output[31:0] Instruction;
                                      // the instruction fetched from this module to Decoder and Controller
  output[31:0] branch_base_addr; // (pc+4) to ALU which is used by branch type instruction
  output[31:0] link_addr;
                                     // (pc+4) to Decoder which is used by jal instruction
//from CPU TOP
               clock, reset:
                                          // Clock and reset
 input
// from ALU
 input[31:0] Addr_result;
                                    // the calculated address from ALU
 input
              Zero;
                                    // while Zero is 1, it means the ALUresult is zero
// from Decoder
                                    // the address of instruction used by jr instruction
 input[31:0] Read_data_1;
// from Controller
                                    // while Branch is 1,it means current instruction is beq
           Branch:
 input
                                    // while nBranch is 1,it means current instruction is bnq
 input
           nBranch;
 input
                                    // while Jmp 1, it means current instruction is jump
           Jmp;
           Jal;
                                    // while Jal is 1, it means current instruction is jal
 input
                                    // while Ir is 1, it means current instruction is ir
 input
           Jr;
```



### Update the Value of the PC register

```
Q1: Complete the code to update 'Next PC'
                                Q2: Could be 'PC' ready while read the 'prgrom'? Determine when to update the value of the PC register.
reg[31:0] PC, Next_PC;
                                Q3: Is this Minisys ISA a Harvard structure or Von Neumann structure(take a look at the initial value of PC)
always @* begin
    if(((Branch == 1) && (Zero == 1)) || ((nBranch == 1) && (Zero == 0)))
      Next_PC = ... // the calculated new value for PC
                                                                                          Next PC
    else if(Jr == 1)
      Next_PC = ... // the value of $31 register
    else Next_PC = ... // PC+4
                                                                                                    Clock .
  end
 always @(... clock) begin
  if(reset == 1)
      PC <= 32'h0000_0000;
  else begin
                                                                                     Address
                                                                                                           Memory
   if((Jmp == 1) || (Jal == 1)) begin
PC <= ...;
                                                                                                            Word
   end
  else PC <= ...;
end
                                                             NOTES: The code here is JUST refence, NOT request.
```

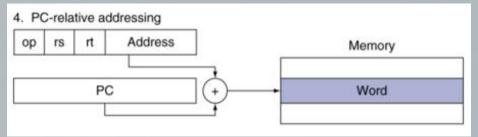


### **Outputs of IFetch: Prepare for Decoder and ALU**

```
output[31:0] branch_base_addr; // (pc+4) to ALU which is used by branch type instruction output[31:0] link_addr; // (pc+4) to Decoder which is used by 'jal' instruction
```

Here for "pc+4", the value of 'pc' is the address of current processing instruction.





#### **NOTES:**

Don't forget to instance instruction memory, complete the port binding.

TIPS: The design here is for reference ONLY, NOT request.



### Practice 2

- 1. Make a Minisys source file with j, jal, jr, beg, bne and other NON-jumping instructions included.
- 2. Using the Minisys1AssemblerV2.2 to assembler the source file on step 1, get the coe files.
- 3. Using the "prgmip32.coe" generated on step 2 as the initial file for the ROM in IFetch submodule to verify the its funciton:
- 3-1) What's the value of register PC while the reset is valid.
- 3-2) While reset is invalid, on which edge of clock would the value of register PC be updated?
- 3-3) What's the updated value to register PC while the current instruction is j, jal, jr, beq,bne and other NON-jumping instructions.
- 3-4) On which edge of clock would the instruction be fetched out?
- 3-5) Is there any difference between the two output ports ("branch\_base\_addr" and "link\_addr")

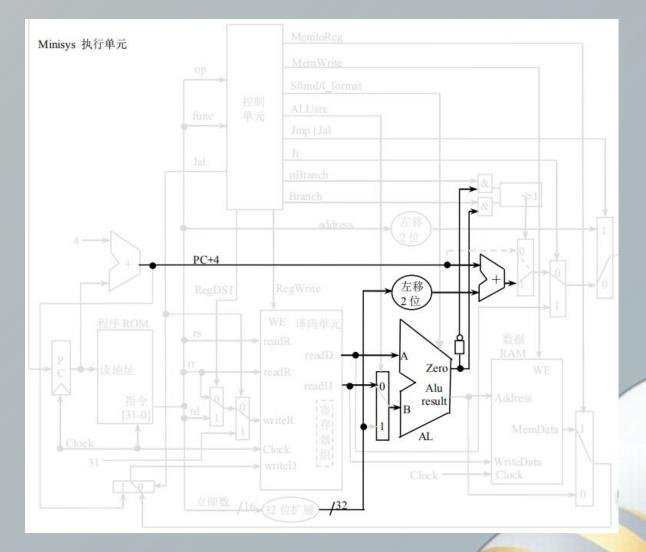
Tips:1) There are j, jal, jr, beg, bne and other NON-jumping instructions in cputest.asm(which is in the Minisys1AssemblerV2.2.rar), you can modify it as an alternative to the 1st step.

2) "Minisys1AssemblerV2.2.rar" could be found in the directory "labs" of course blackboard site



- Determine the function and the inputs and outputs of ALU
  - > A MUX for operand selection
  - 'ALU\_control'
  - ➤ Operation
    - Arithmetic and Logic calculation
    - > Shift calculation
    - > Special calculation (slt,lui)
    - > Address calculation

### Q: Is the ALU a commbinatorial logic and sequential logic?



Tips: follow design is a reference ONLY, not required.



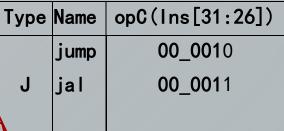
## Minisys - A subset of MIP\$32

Туре	Name	funC(ins[5:0])
R	sII	00_0000
	srl	00_0010
	sllv	<b>00_0</b> 100
	srlv	00_0110
	sra	<b>00_0</b> 011
	srav	00_0111
$\  \langle \rangle$	jr	00_1000
	add	<b>10_000</b> 0
	addu	10_0001
	sub	<b>10_001</b> 0
	subu	10_0011
	and	<b>10_01</b> 00
	or	<b>10_01</b> 01
\	xor	<b>10_01</b> 10 /
	nor	10_0111
	slt	<b>10_1</b> 010
	sltu	<b>10_1</b> 011

Type	Name	opC(Ins[31:26])
TI	beq	<b>00</b> _0100
R	brie	<b>00</b> _0101
	Iw M	10_0011
	SW	10 1011
		ms All

SIW M	10 0011
	_
SW	10_1011
0	12)
> CALT	
- KAN	
addi	00_1000
addiu	<b>1</b> 001
addiu	
slti	<b>00_1</b> 010
sItiu	<b>00 1</b> 011
	<b>00 1</b> 100
andi	_
ori	<b>00_1</b> 101

Type	Name	opC(Ins[31:26])
	jump	<b>00_001</b> 0
J	jal	00_0011





Minisys is a subset of MIPS32.

The opC of R-Type instruction is 6 b00\_0000

#### **BASIC INSTRUCTION FORMATS**

	opcode	rs		rt	rd	shamt	funct
31	1 20	5 25	21 20	10	6 15 1	1 10	5 5 (
	opcode	rs		rt		immediat	e
31	1 20	5 25	21 20	10	6 15		(
	opcode				address		
31	1 20	5 25					(

**00\_1**110

00\_1111

xori



### Inputs Of ALU

```
module Executs32 ();
// from Decoder
  input[31:0] Read_data_1;
                                      //the source of Ainput
  input[31:0] Read_data_2;
                                       //one of the sources of Binput
  input[31:0] Sign_extend;
                                      //one of the sources of Binput
// from IFetch
  input[5:0] Opcode;
                                       //instruction[31:26]
  input[5:0] Function_opcode;
                                       //instructions[5:0]
                                       //instruction[10:6], the amount of shift bits
  input[4:0] Shamt;
  input[31:0] PC plus 4;
                                       //pc+4
// from Controller
  input[1:0] ALUOp;
                             //{ (R format || I format), (Branch || nBranch) }
             ALUSrc;
                             // 1 means the 2nd operand is an immediate (except beg,bne)
  input
                             // 1 means I-Type instruction except beq, bne, LW, SW
  input
             I format;
                             // 1 means this is a shift instruction
             Sftmd;
  input
```



### **Outputs And Variable of ALU**

Q1: Who needs the calculation result of ALU?

```
output[31:0] reg ALU_Result; // the ALU calculation result
output Zero; // 1 means the ALU_reslut is zero, 0 otherwise
output[31:0] Addr_Result; // the calculated instruction address
```

Q2: How to determine the data type of following variable?

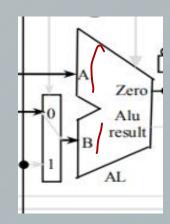
```
wire[31:0]
             Ainput, Binput;
                                          // two operands for calculation
wire[5:0]
              Exe code; // use to generate ALU_ctrl. (I_format==0) ? Function_opcode : { 3'b000 , Opcode[2:0] };
                         // the control signals which affact operation in ALU directely
             ALU ctl;
wire[2:0]
wire[2:0]
             Sftm;
             Shift Result;
                                     // the result of shift operation
reg[31:0]
reg[31:0]
             ALU output mux;
                                      // the result of arithmetic or logic calculation
                                // the calculated address of the instruction, Addr Result is Branch Addr[31:0]
wire[32:0]
             Branch Addr;
```



### The Selection On Operand2

Two operands of ALU: Ainput and Binput.

- Ainput is from the output port "Read\_data\_1" of Decoder
- **Binput** is the output of 2-1 MUX:
  - "Sign\_extend" and "Read\_data\_2" are from Decoder.
  - The output of the MUX is determined by "ALUSrc" which comes from Controller.



```
input[31:0] Read_data_1; // from Decoder
input[31:0] Read_data_2; // from Decoder
input[31:0] Sign_extend; // from Decoder
// from Controller, 1 means the Binput is an extended immediate, otherwise the Binput is Read
input ALUSrc;

assign Ainput = Read_data_1;
assign Binput = (ALUSrc == 0) ? Read_data_2 : Sign_extend[31:0];
```



### **ALU\_ctrl** generation

- ➤ Design:
  - > lots of operations need to be processed in ALU
  - ➤ To reduce the burden of the Controller, the Controller and ALU produce control signals which affect the ALU operation together

    I format

Opcode

**Function code** 

Exe code

**ALUOp** 

**ALU** ctrl

- > Implements(1):
  - ALUOp(1st level control signal):

generated by Controller (the basic relationship between instruction and operation)

- > bit1 to identify if the instruction is R\_format/ I\_format, otherwise means neither
- > bit0 to identify if the instruction is beg/bne, otherwise means neither
- ALUOp = { (R\_format || I\_format) , (Branch || nBranch) }

```
// R_format = (0pcode = = 6'b000000)? 1'b1:1'b0;
```

// "I\_format" is used to identify if the instruction is I\_type(except for beq, bne, lw and sw).



### ALU\_ctrl generation continued

- Implements(2):
  - Exe\_code(2nd level control signal): according to the instruction type( I-format or not):

#### Tips

- I\_format is 1 means this is the I-type instruction
   except beq,bne,lw and sw.
- 2) Opcode is instruction[31:26]
- 3) function\_opcode is instruction[5:0]
- **Q.** Could the 'Exe\_code' be generated by Controller or by ALU? What's your choice?

Type	Name	funC(ins[5:0])
R	sll	00_0000
	srl	<b>00_0</b> 010
	sllv	00_0100
	srlv	<b>00_0</b> 110
	sra	<b>00_0</b> 011
	srav	00_0111
	jr	00_1000
	add	<b>10_000</b> 0
	addu	10_0001
	sub	10_0010
	subu	10_0011
	and	10_0100
	or	<b>10_01</b> 01
	xor	<b>10_01</b> 10
	nor	10_0111
	slt	<b>10_1</b> 010
	sltu	<b>10_1</b> 011

ype	Name	opC(Ins[31:26])		
1	beq	<b>00</b> _0100		
	bne	<b>00</b> _0101		
	lw	<b>10</b> _0011		
	sw	<b>10</b> _1011		
		I-Format		
		1		
	addi	<b>00_1</b> 000		
- 1	addiu	<b>00_1</b> 001		
	slti	<b>00_1</b> 010		
- 1	sltiu	<b>00_1</b> 011		
	andi	<b>00_1</b> 100		
	ori	<b>00_1</b> 101		
- 1	xor i	<b>00_1</b> 110		
- 1	lui	00 1111		



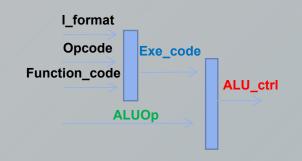
### ALU\_ctrl generation continued

Exe_code[30]	ALUOp[10]	ALU_ctl[20]	指令助记符
0100	10	000	and,andi
0101	10	001	or,ori
0000	10	010	add,addi
xxxx	00	010	lw, sw
0001	10	011	addu, addiu
0110	10	100	xor,xori
0111	10	101	nor,lui
0010	10	110	sub, slti
xxxx	01	110	beq, bne
0011	10	111	subu, sltiu
1010	10	111	slt
1011	10	111	sltu

```
Implements(3)
ALU_ctrl : based on ALUOp and Exe_code,
specify most of the operation details in ALU

ALUOp =
{ (R_format || I_format) , (Branch || nBranch) }

Exe_code = (I_format==0) ?
```



```
assign ALU_ctl[0] = (Exe_code[0] | Exe_code[3]) & ALUOp[1];

assign ALU_ctl[1] = ((!Exe_code[2]) | (!ALUOp[1]));

assign ALU_ctl[2] = (Exe_code[1] & ALUOp[1]) | ALUOp[0];
```

Function\_opcode:

{ 3'b000, Opcode[2:0] };



### **ALU\_ctrl** usage

> Type1: The same operation in ALU with different operand source sometimes the instructions share the same calculation operation but with different operand source, such as "and" and "andi", "addu" and "addui".

## The same operation but different operand source: **ALU\_ctrl** is same

- add vs addi
- addu vs addiu
- and vs andi
- or vs ori
- xor vs xori
- slt vs sltu vs sltiu

Exe_code[30]	ALUOp[10]	ALU_ctl[20]	指令助记符
0100	10	000	and,andi
0101	10	001	or,ori
0000	10	010	add,addi
XXXX	00	010	lw, sw
0001	10	011	addu, addiu
0110	10	100	xor,xori
0111	10	101	nor,lui
0010	10	110	sub, slti
XXXX	01	110	beq, bne
0011	10	111	subu, sltiu
1010	10	111	slt
1011	10	111	sltu



### ALU\_ctrl usage continued

> Type2: The same operation in ALU with different destination

The ALU\_ctrl code is same(3'b010) for both "Iw", "sw", "add" and "andi":

the operation of "Iw" and "sw" in ALU
is calcuation the address based on
the base address and offset which is
same as in "add" operation.

Exe_code[30]	ALUOp[10]	ALU_ctl[20]	指令助记符		
0100	10	000	and,andi		
0101	10	001	or,ori		
0000	10	010	add,addi		
XXXX	00	010	lw, sw		
0001	10	011	addu, addiu		
0110	10	100	xor,xori		
0111	10	101	nor,lui		
0010	10	110	sub, slti		
XXXX	01	110	beq, bne		
0011	10	111	subu, sltiu		
1010	10	111	slt		
1011	10	111	sltu		



### ALU\_ctrl usage continued

- > Type2 continued: The same operation in ALU with different destination
  - "beq", "bne" vs "sub" (destionation ):
    - "beq" and "bne": Addr\_reslut
    - "sub": "ALU reslut"
  - "subu" vs "slt", "sltu" (destionation)
    - "slti" and "sltiu": Zero.

I\_format is used here to distinguish these two types

• "sub" vs "slti", "subu" vs "sltiu":

same as upper instructions,
Function\_opcode(3)=1 of slt and sltu
could be used as distinguishment

Exe_code[30]	ALUOp[10]	ALU_ctl[20]	指令助记符	
0100	10	000	and,andi	
0101	10	001	or,ori	
0000	10	010	add,addi	
XXXX	00	010	lw, sw	
0001	10	011	addu, addiu	
0110	10	100	xor,xori	
0111	10	101	nor,lui	
0010	10	110	sub, slti	
xxxx	01	110	beq, bne	
0011	10	111	subu, sltiu	
1010	10	111	slt	
1011	10	111	sltu	



### ALU\_ctrl usage continued

> Type3: Some instructions' ALU\_ctrl code is the same as others, but with different operation in ALU.

For these instructions, make sure they can be identified to avoid wrong operations:

- shift instructions: could be identified by the input port "sftmd"
- lui: whose ALU\_ctrl code is the same as "nor", but could be identified by "I\_format"
- jr: could be identified by the input port "jr", not excute in ALU
- j : could be identified by the input port "jmp", not excute in ALU
- jal: could be identified by the input port "jal", not excute in ALU



### Practice3-1: Arithmatic and Logic calculation

Complete the following code according to the table on the right hand

```
reg[31:0] ALU output mux;
always @ (ALU ctl or Ainput or Binput)
begin
case (ALU ctl)
    3'b000:ALU output mux =? ? ?
    3'b001:ALU output mux =? ? ?
    3'b010:ALU output mux =? ? ?
    3'b011:ALU output mux =? ? ?
    3'b100:ALU output mux =? ? ?
    3'b101:ALU output mux =? ? ?
    3'b110:ALU output mux =? ? ?
    3'b111:ALU output mux =? ? ?
    default:ALU output mux = 32'h00000000;
endcase
end
```

Exe_code[30]	ALUOp[10]	ALU_ctl[20]	指令助记符
0100	10	000	and,andi
0101	10	001	or,ori
0000	10	010	add,addi
xxxx	00	010	lw, sw
0001	10	011	addu, addiu
0110	10	100	xor,xori
0111	10	101	nor,lui
0010	10	110	sub, slti
xxxx	01	110	beq, bne
0011	10	111	subu, sltiu
1010	10	111	slt
1011	10	111	sltu

**Tips**: While ALU\_ctrl is 3'b101, One of the implements is to execute only 'nor', make other procedure do the 'lui'



### **Shift Operation**

Туре	Name	funC(ins[5:0])
R	sII	00_0000
- 11	srl	<b>00_0</b> 010
	sllv	<b>00_0</b> 100
	srlv	<b>00_0</b> 110
	sra	00_0011
	srav	00_0111

There are 6 shift instructions, listed in the table on the left hand.

Ainput, Binput/shamt are the operand of shift operation

R	opc	ode	rs	rt		rd	shamt	funct
	31	26 25	21	20	16	15 11	10 6	5 0

```
      sftm[2:0] process

      3'b000
      sll rd, rt, shamt

      3'b010
      srl rd, rt, shamt

      3'b100
      sllv rd, rt, rs

      3'b110
      srlv rd, rt, rs

      3'b011
      sra rd, rt, shamt

      3'b111
      srav rd, rt, rs

      other
      not shift
```



### **Practice3-2: Shift Operation**

Complete the following code, taking the table on the left hand as reference

sftm[2:0]	process
3'b000	sll rd, rt, shamt
3'b010	srl rd, rt, shamt
3'b100	sllv rd, rt, rs
3'b110	srlv rd, rt, rs
3'b011	sra rd, rt, shamt
3'b111	srav rd, rt, rs
other	not shift

```
always @* begin
   if(Sftmd)
         case(Sftm[2:0])
           3'b000:Shift_Result = Binput << Shamt;
           3'b010:Shift_Result = ???;
           3'b100:Shift_Result = Binput << Ainput;
           3'b110:Shift_Result = ???;
           3'b011:Shift Result = ???;
           3'b111:Shift_Result = ???;
           default:Shift_Result = Binput;
         endcase
   else
         Shift_Result = Binput;
  end
```



### Get the Output of ALU

#### The operations of ALU include:

- 1) execute the **setting** type instructions ( **slt, sltu, slti** and **sltiu** )
  - > get ALU\_output\_mux, and set the value of the output port "ALU\_result"
- 2) execute the lui operation
  - get result of "lui" execution, and set the value to the output port "ALU\_result"
- 3) execute the **shift** operation
  - > get "Shift\_Result", set its value to the output port "ALU\_result"
- 4) do the basic arithmetic and logic calculation
  - > get ALU\_output\_mux, set its value to the output port "ALU\_result"

Tips: Exe\_code[3..0], ALUOp[1..0] and ALU\_ctl[2..0] are used to identify the types of operation



### Practice 3-3: the output "ALU\_Result"

Complete the following code according to the code annotation

```
always @* begin
    //set type operation (slt, slti, sltu, sltiu)
    if( ((ALU_ctl==3'b111) && (Exe_code[3]==1)) || /*to be completed*/ )
              ALU_Result = (Ainput-Binput<0)?1:0;
   //lui operation
   else if((ALU_ctl==3'b101) && (I_format==1))
              ALU_Result[31:0] = /*to be completed*/;
   //shift operation
   else if(Sftmd==1)
              ALU_Result = Shift_Result ;
    //other types of operation in ALU (arithmatic or logic calculation)
    else
              ALU_Result = ALU_output_mux[31:0];
 end
```

Exe_code[30]	ALUOp[10]	ALU_ctl[20]	指令助记符	
0100	10	000	and,andi	
0101	10	001	or,ori	
0000	10	010	add,addi	
XXXX	00	010	lw, sw	
0001	10	011	addu, addiu	
0110	10	100	xor,xori	
0111	10	101	nor,lui	
0010	10	110	sub, slti	
xxxx	01	110	beq, bne	
0011	10	111	subu, sltiu	
1010	10	111	slt	
1011	1011 10		sltu	



### Practice 3-4: the output "Addr\_result" and "Zero"

The values of "Addr\_result" and "Zero" are still not determined.

```
output[31:0] reg ALU Result; // the ALU calculation result
output Zero; // 1 means the ALU_reslut is zero, 0 otherwise
output[31:0] Addr_Result; // the calculated instruction address
```

> "Zero" is a signal used by "IFetch" to determine whether to use the value of "Addr\_reslut" to update PC register or not.

TIPS: Minisys only support "beq" and "bne" in the conditional jump instruction.

> "Addr\_result" is calculated by ALU when the instruction is "beq" or "bne".

TIPS: Addr\_reslut should be the sum of pc+4(could be get from PC\_plus\_4) and the immediate in the instruction.



### **Practice 3-5: Function Verification on ALU**

Build a testbench to verify the function of ALU.

Take the testcases described in bellow table as reference, More testcases are suggested for function verification.

Time (ns)	Instruction	A input	B input	Results(includes 'Zero')	
0	add	0x5	0x6	ALU_Result = 0x0000_000b, Zero=1'b0	
200	addi	0xffff_ff40	0x3	ALU_Result = 0xffff_ff43, Zero=1'b0	
400	and	0x0000_00ff	0x0000_0ff0	ALU_Result = 0x0000_00f0, Zero=1'b0	
600	sll	0x0000_0002	0x3	ALU_Result = 0x0000_0010, Zero=1'b0	
800	lui	0x0000_0040	0x10 (16)	ALU_Result = 0x0040_0000, Zero=1'b0	
1000	beq	The value of Ainput is same with that of Binput. Zero = 1'b1 Depends on your design Addr_Result: should be the sum of pc+4(could be get from PC_plus_4) and the immediate in the instruction			