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Image Basics



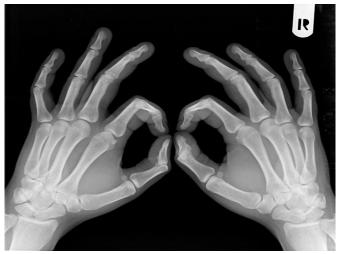




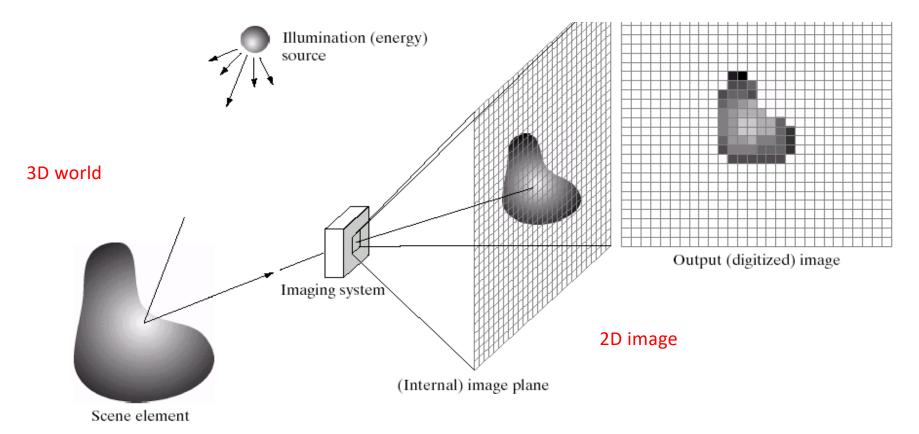


Image Basics

Topic in three points:

- 1. What is a digital image how can we represent it?
- 2. How is color represented in a digital image?
- 3. What do we mean by resolution for a digital image?

Imaging System





What are digital images?

- An image is a 2-d rectilinear array of *pixels*
- The word pixel is derived from "picture element".





Pixels as samples

• A pixel is a *sample* of a continuous function



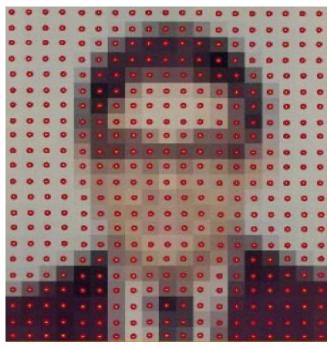
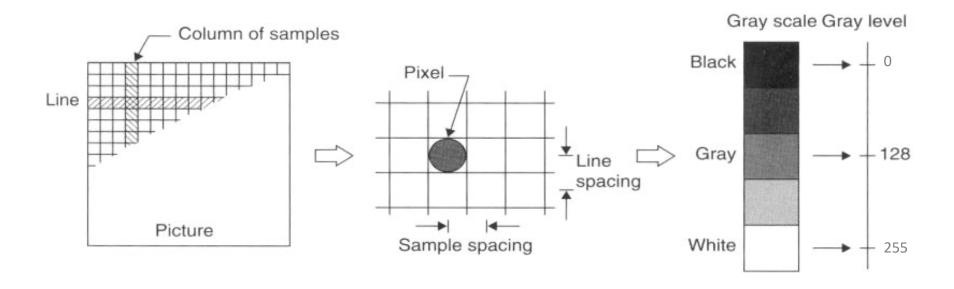
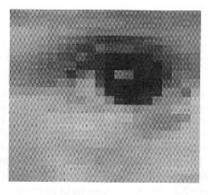


Image Digitization (sampling and quantization)



Sampling: measuring the value of an image position at a finite number of points. **Quantization:** representation of the measured value at the sampled point by a finite number of bits.

Representation in the computer



By a matrix of numbers Integers

8 bit words, unsigned integers 0, 1, 2, 255

Image representation – image as a function

- A digital image is represented as a 2D (light) intensity function f(x,y), (x,y) are spatial coordinates.
- f(x,y) has values proportional to the brightness at that point.
- f(x,y) can represent a gray scale image -> one scalar value for each (x,y)
- f(x,y) can represent a color image -> 3D vector with values for each (x,y), representing color. For example as RGB (red-green-blue)
- f(x,y) can represent a hyperspectral image -> vector of size P>3 for each (x,y).

Image representation

An image can be represented as an M×N numerical array.

For multispectral (color) images there are one for each color/spectral band). Image as a function with numbering as in the book:

$$f(x,y) = egin{pmatrix} f(0,0) & f(1,0) & \cdots & f(N-1,0) \ f(0,1) & f(1,1) & \cdots & f(N-1,1) \ dots & dots & \ddots & dots \ f(0,M-1) & f(1,M-1) & \cdots & f(N-1,M-1) \end{pmatrix}$$

Figure 1.5: Top: Image as a 2D array, showing the 1D index of each pixel. Bottom: Internal representation of image as a 1D array using row major order.

0

(0,0)

(1,0)

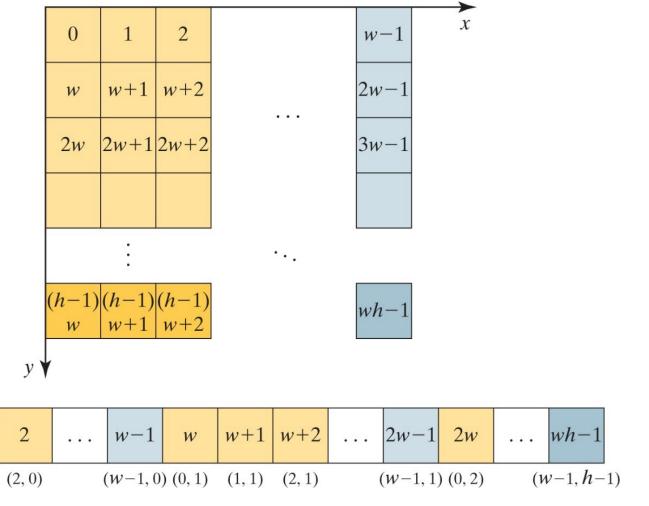


Image representation - image as a matrix

Image as a MxN matrix

$$f(row, column) = egin{pmatrix} f(1,1) & f(1,2) & \cdots & f(1,N) \ f(2,1) & f(2,2) & \cdots & f(2,N) \ dots & dots & \ddots & dots \ f(M,1) & f(M,2) & \cdots & f(M,N) \end{pmatrix}$$

Figure 1.6: Different ways to visualize an image: as a picture, as a height map, as an array of values, as a function, as a set, as a graph, and as a vector. The 5×4 array is a small portion of the image; the set contains the coordinates of all pixels in the array whose value is greater than 80; and the weights of the edges in the graph are the absolute differences between values in the array.

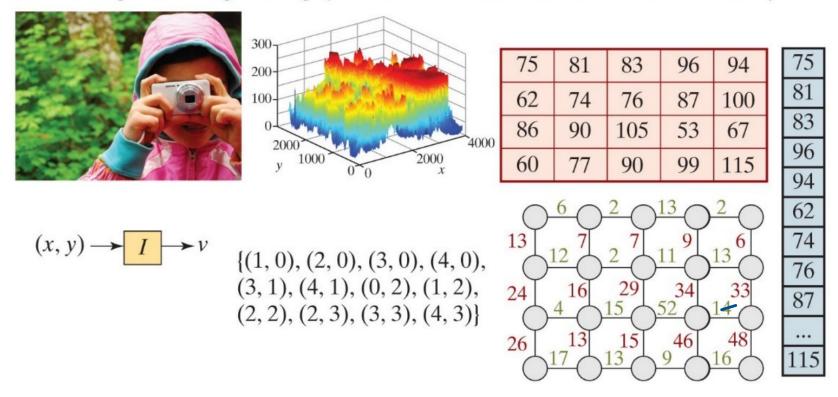


Image representation – remarks

- A digital image an be regaded as a function, as an array, as a matrix, graph etc. $f(x,y) = f_{x,y}$
- ullet The value of a specific point: $\ f(x_i,y_j)=v$
- Often for image of size NxM: $N=2^{n1}, M=2^{n2}$

$$0 \leq f(x,y) \leq (G-1)$$
 $G=2^m$ m bit pr. pixel

How many pixels (NxM)?

Reducing the number of pixels produces pixelated image (here printed as the same size for illustration)

original image



sampled by a factor of 4



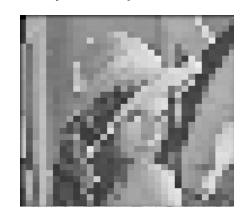


sampled by a factor of 2





sampled by a factor of 8





How many gray levels (number of bits pr pixel)?

Reducing the number of grey levels produces false contouring





8 gray levels (3 bits/pixel)



32 gray levels (5 bits/pixel)



4 gray levels (2 bits/pixel)



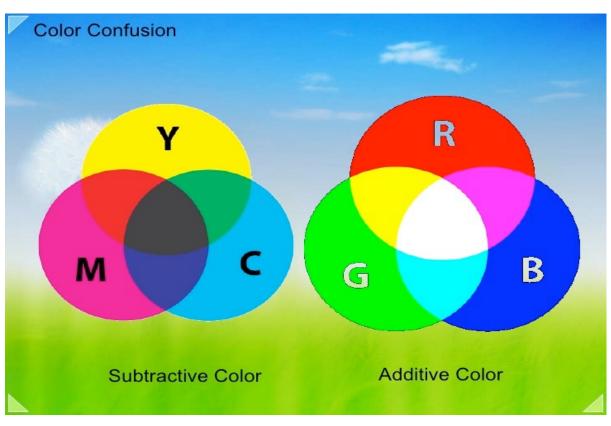
16 gray levels (4 bits/pixel)



2 gray levels (1 bit/pixel)

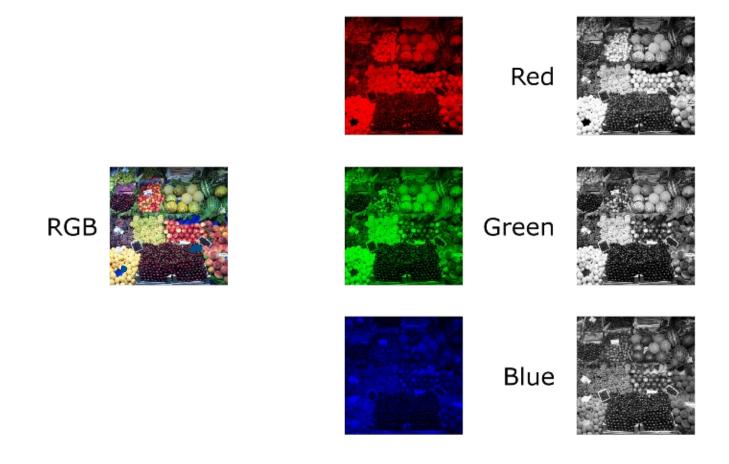


Color images



- RGB additive color mixing: it describes what kind of *light* that must be *emitted* to produce a given color.
- CMY(K) subtractive color mixing: it describes what kind of colored ink that has to be applied so the light reflected from the paper produces a given color.

Color image – 3D vector for each pixel



Back to color: representation in the computer

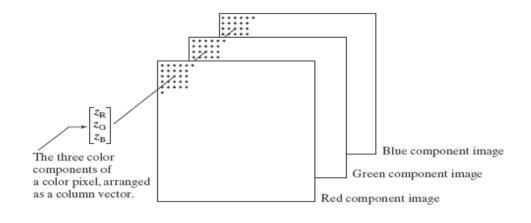
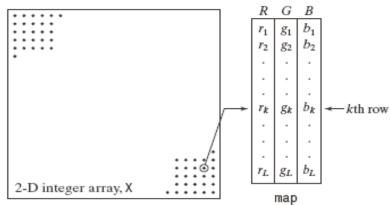


FIGURE 7.1 Schematic showing how pixels of an RGB color image are formed from the corresponding pixels of the three component images.



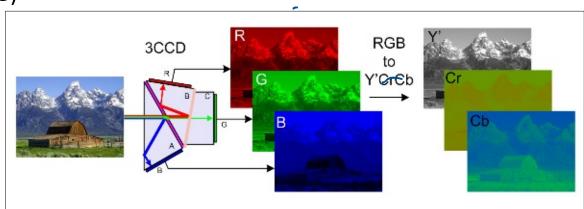
Value of circled element = k

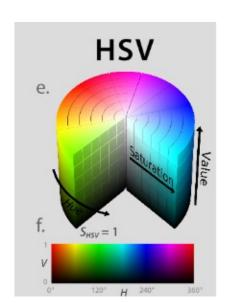
FIGURE 7.3

Elements of an indexed image. The value of an element of integer array X determines the row number in the color map. Each row contains an RGB triplet, and L is the total number of rows.

Color models, examples

- RGB (red green blue), captured by camera
- HSV Hue, saturation and Value(intensity). Close to how humans observe color
 - Hue describe pure color
 - Saturation degree of pure color diluted by white light
 - Value/Intensity gray-level intensity information
- YCbCr Used in television transmission, video/image coding etc. (MPEG, JPEG)
 - Y luminance (gray level)
 - Cb and Cr are the blue-difference and red-difference chrominance (color) components





Conversion expressions

RGB to **YCbCr**:

$$\begin{bmatrix} Y \\ Cb \\ Cr \end{bmatrix} = \begin{bmatrix} 16 \\ 128 \\ 128 \end{bmatrix} + \begin{bmatrix} 65.481 & 128.553 & 24.966 \\ -37.797 & -74.203 & 112.000 \\ 112.000 & -93.786 & -18.214 \end{bmatrix} \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$

RGB to **HSV** and **HSV** to **RGB**: the expressions are more complicated especially for the hue value. Conversion functions exist.

More information about color spaces can ex. be found at http://en.wikipedia.org/wiki/Color_space

Image Types

- **Grayscale image**: the value of each pixel is a scalar indicating the amount of light captured.
 - These values are quantized into a finite number of discrete levels called gray levels.
- In an 8-bit grayscale image, a pixel whose value is 0 represents black, whereas a pixel whose value is 255 represents white.
- RGB color image: the pixel values are triples containing the amount of light captured in the three color channels: red, green, and blue.
 - Interleaved: all three values for one pixel are stored before the three values of the next pixel
 - **Planar:** the red, green, and blue channels are stored as separate one-byte-per-pixel images
 - Alpha value or opacity: used for blending multiple images

Image Types (2)

- Binary image: The logical values can be stored using one bit per pixel, (0 for off or 1 for on), or they can be stored using one byte per pixel, where their values are usually 0 (hexadecimal 00) or 255 (hexadecimal FF).
- Real-valued image, or floating-point image: each pixel contains a real number.
 - The number is stored in the computer as a single- or double-precision floating point number
- Integer-valued image: the value of each pixel is an integer.

	grayscale	RGB color	binary	integer-valued	real-valued	complex-valued
channels	1	3	1	1	1	2
bit depth	8	24	1	32/64	32/64	64/128
value range	$\{0, \ldots, 255\}$	$\{0,\ldots,255\}^3$	$\{0, 1\}$	\mathbb{Z}	\mathbb{R}	\mathbb{R}^2

TABLE 1.3: Common image types, shown with the number of channels, the most commonly encountered bit depth (number of bits per pixel), and the set of possible values. In the final three columns this set is conceptual only, since the integers \mathbb{Z} and real numbers \mathbb{R} are infinite sets.

Image Basics - summary

We will go through three points:

- 1. What is a digital image how can we represent it?
 - ✓ Pixels in a matrix / array, function
- 2. What do we mean by resolution for a digital image?
 - ✓ Number of pixels AND bit-depth (nubmer of bits per pixel)
- 3. How is color represented in a digital image?
 - ✓ 3 x matrix / array. One for Red, Green and Blue channels.