

FULL WAVEFORM INVERSION

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Introduction

This is an explanation of Full Waveform Inversion program in Madagascar (<https://github.com/ahay/src>) to help us understand the details of seismic inversion workflow. The author of code is Pengliang Yang and the theory can be found on http://www.reproducibility.org/RSF/book/xjtu/primer/paper_html/. What's more, Karol Koziol published the \LaTeX template on ShareLatex <https://www.sharelatex.com/>.

Main points:

1. Sub the source when recovery forward wavefield, see [line 309 in main\(\)](#).
2. Calculate one time forward exploration for a better CG step, see [line 370-413 in main\(\)](#)

main()

main() in [\\$\(RSFROOT\)/src/user/pyang/Mfwi2d.c](#).

Listing 1: main()

```
1
2  /* Time domain full waveform inversion
3     Note: This serial FWI is merely designed to help the understanding of
4     beginners. Enquist absorbing boundary condition (A2) is applied!
5  */
6  /*
7     Copyright (C) 2014  Xi'an Jiaotong University, UT Austin (Pengliang Yang)
8
9     This program is free software; you can redistribute it and/or modify
10    it under the terms of the GNU General Public License as published by
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21    Foundation, Inc., 59 Temple Place, Suite 330, Boston, MA 02111-1307  USA
```

```

22
23 Important references:
24 [1] Clayton, Robert, and Bjaqrn Engquist. "Absorbing boundary
25     conditions for acoustic and elastic wave equations." Bulletin
26     of the Seismological Society of America 67.6 (1977): 1529-1540.
27 [2] Tarantola, Albert. "Inversion of seismic reflection data in the
28     acoustic approximation." Geophysics 49.8 (1984): 1259-1266.
29 [3] Pica, A., J. P. Diet, and A. Tarantola. "Nonlinear inversion
30     of seismic reflection data in a laterally invariant medium."
31     Geophysics 55.3 (1990): 284-292.
32 [4] Dussaud, E., Symes, W. W., Williamson, P., Lemaistre, L.,
33     Singer, P., Denel, B., & Cherrett, A. (2008). Computational
34     strategies for reverse-time migration. In SEG Technical Program
35     Expanded Abstracts 2008 (pp. 2267-2271).
36 [5] Hager, William W., and Hongchao Zhang. "A survey of nonlinear
37     conjugate gradient methods." Pacific journal of Optimization
38     2.1 (2006): 35-58.
39 */
40
41 int main(int argc, char *argv[]) {
42
43     /*! variables on host
44     bool verb, precon, csdgather;
45     int is, it, iter, niter, distx, distz, csd, rbell;
46     int nz, nx, nt, ns, ng;
47
48     /*! parameters of acquisition geometry
49     int sxbeg, szbeg, gxbeg, gzbeg, jsx, jsz, jgx, jgz;
50     float dx, dz, fm, dt, dtx, dtz, tmp, amp, obj1, obj, beta, epsil, alpha;
51     float *dobs, *dcal, *derr, *wlt, *bndr, *trans, *objval;
52     int *sxz, *gxz;
53     float **vv, **illum, **lap, **vtmp, **sp0, **sp1, **sp2, **gp0, **gp1, **gp2, **g0, **g1, **cg, *alpha1, *alpha2, **ptr=NULL;
54
55     /*! time
56     clock_t start, stop;
57
58     /*! I/O files
59     sf_file vinit, shots, vupdates, grads, objs, illums;
60
61     /*! initialize Madagascar
62     sf_init(argc,argv);
63
64     /*! set up I/O files
65     vinit=sf_input ("in");
66     /* initial velocity model, unit=m/s */
67     shots=sf_input("shots");

```

```

68  /* recorded shots from exact velocity model */
69  vupdates=sf_output("out");
70  /* updated velocity in iterations */
71  grads=sf_output("grads");
72  /* gradient in iterations */
73  illums=sf_output("illums");
74  /* source illumination in iterations */
75  objs=sf_output("objs");
76  /* values of objective function in iterations */
77
78  ///! get parameters from velocity model and recorded shots
79  if (!sf_getbool("verb",&verb))      verb=true;
80  /* verbosity */
81  if (!sf_histint(vinit,"n1",&nz))    sf_error("no n1");
82  /* nz */
83  if (!sf_histint(vinit,"n2",&nx))    sf_error("no n2");
84  /* nx */
85  if (!sf_histfloat(vinit,"d1",&dz))  sf_error("no d1");
86  /* dz */
87  if (!sf_histfloat(vinit,"d2",&dx))  sf_error("no d2");
88  /* dx */
89  if (!sf_getbool("precon",&precon))  precon=false;
90  /* precondition or not */
91  if (!sf_getint("niter",&niter))    niter=100;
92  /* number of iterations */
93  if (!sf_getint("rbell",&rbell))    rbell=2;
94  /* radius of bell smooth */
95
96  if (!sf_histint(shots,"n1",&nt))    sf_error("no nt");
97  /* total modeling time steps */
98  if (!sf_histint(shots,"n2",&ng))    sf_error("no ng");
99  /* total receivers in each shot */
100 if (!sf_histint(shots,"n3",&ns))    sf_error("no ns");
101 /* number of shots */
102 if (!sf_histfloat(shots,"d1",&dt))  sf_error("no dt");
103 /* time sampling interval */
104 if (!sf_histfloat(shots,"amp",&amp))sf_error("no amp");
105 /* maximum amplitude of ricker */
106 if (!sf_histfloat(shots,"fm",&fm))  sf_error("no fm");
107 /* dominant freq of ricker */
108 if (!sf_histint(shots,"sxbeg",&sxbeg)) sf_error("no sxbeg");
109 /* x-begining index of sources, starting from 0 */
110 if (!sf_histint(shots,"szbeg",&szbeg)) sf_error("no szbeg");
111 /* x-begining index of sources, starting from 0 */
112 if (!sf_histint(shots,"gxbeg",&gxbeg)) sf_error("no gxbeg");
113 /* z-begining index of receivers, starting from 0 */
114 if (!sf_histint(shots,"gzbeg",&gzbeg)) sf_error("no gzbeg");

```

```

115  /* x-begining index of receivers, starting from 0 */
116  if (!sf_histint(shots,"jsx",&jsx)) sf_error("no jsx");
117  /* source x-axis jump interval */
118  if (!sf_histint(shots,"jsz",&jsz)) sf_error("no jsz");
119  /* source z-axis jump interval */
120  if (!sf_histint(shots,"jgx",&jgx)) sf_error("no jgx");
121  /* receiver x-axis jump interval */
122  if (!sf_histint(shots,"jgz",&jgz)) sf_error("no jgz");
123  /* receiver z-axis jump interval */
124  if (!sf_histint(shots,"csdgather",&csd))
125  sf_error("csdgather or not required");
126  /* default, common shot-gather; if n, record at every point */
127
128  /*! set up I/O parameters
129  sf_putint(vupdates,"n1",nz);
130  sf_putint(vupdates,"n2",nx);
131  sf_putint(vupdates,"n3",niter);
132  sf_putfloat(vupdates,"d1",dz);
133  sf_putfloat(vupdates,"d2",dx);
134  sf_putint(vupdates,"d3",1);
135  sf_putint(vupdates,"o3",1);
136  sf_putstr(vupdates,"label1","Depth");
137  sf_putstr(vupdates,"label2","Distance");
138  sf_putstr(vupdates,"label3","Iteration");
139  /* updated velocity in iterations */
140  sf_putint(grads,"n1",nz);
141  sf_putint(grads,"n2",nx);
142  sf_putint(grads,"n3",niter);
143  sf_putfloat(grads,"d1",dz);
144  sf_putfloat(grads,"d2",dx);
145  sf_putint(grads,"d3",1);
146  sf_putint(grads,"o3",1);
147  sf_putstr(grads,"label1","Depth");
148  sf_putstr(grads,"label2","Distance");
149  sf_putstr(grads,"label3","Iteration");
150  /* gradient in iterations */
151  sf_putint(illums,"n1",nz);
152  sf_putint(illums,"n2",nx);
153  sf_putint(illums,"n3",niter);
154  sf_putfloat(illums,"d1",dz);
155  sf_putfloat(illums,"d2",dx);
156  sf_putint(illums,"d3",1);
157  sf_putint(illums,"o3",1);
158  /* source illumination in iterations */
159  sf_putint(objs,"n1",niter);
160  sf_putint(objs,"n2",1);
161  sf_putfloat(objs,"d1",1);

```

```

162     sf_putfloat(objs,"o1",1);
163     /* values of objective function in iterations */
164     dtx=dt/dx;
165     dtz=dt/dz;
166     csdgather=(csd>0)?true:false;
167
168     /*!! allocate memory
169     vv=sf_floatalloc2(nz, nx);
170     /* updated velocity */
171     vtmp=sf_floatalloc2(nz, nx);
172     /* temporary velocity computed with epsil */
173     sp0=sf_floatalloc2(nz, nx);
174     /* source wavefield p0 */
175     sp1=sf_floatalloc2(nz, nx);
176     /* source wavefield p1 */
177     sp2=sf_floatalloc2(nz, nx);
178     /* source wavefield p2 */
179     gp0=sf_floatalloc2(nz, nx);
180     /* geophone/receiver wavefield p0 */
181     gp1=sf_floatalloc2(nz, nx);
182     /* geophone/receiver wavefield p1 */
183     gp2=sf_floatalloc2(nz, nx);
184     /* geophone/receiver wavefield p2 */
185     g0=sf_floatalloc2(nz, nx);
186     /* gradient at previous step */
187     g1=sf_floatalloc2(nz, nx);
188     /* gradient at curret step */
189     cg=sf_floatalloc2(nz, nx);
190     /* conjugate gradient */
191     lap=sf_floatalloc2(nz, nx);
192     /* laplace of the source wavefield */
193     illum=sf_floatalloc2(nz, nx);
194     /* illumination of the source wavefield */
195     objval=(float*)malloc(niter*sizeof(float));
196     /* objective/misfit function */
197     wlt=(float*)malloc(nt*sizeof(float));
198     /* ricker wavelet */
199     sxz=(int*)malloc(ns*sizeof(int));
200     /* source positions */
201     gxz=(int*)malloc(ng*sizeof(int));
202     /* geophone positions */
203     bndr=(float*)malloc(nt*(2*nz+nx)*sizeof(float));
204     /* boundaries for wavefield reconstruction */
205     trans=(float*)malloc(ng*nt*sizeof(float));
206     /* transposed one shot */
207     dobs=(float*)malloc(ng*nt*sizeof(float));
208     /* observed seismic data */

```

```

209     dcal=(float*)malloc(ng*sizeof(float));
210     /* calculated/synthetic seismic data */
211     derr=(float*)malloc(ns*ng*nt*sizeof(float));
212     /* residual/error between synthetic and observation */
213     alpha1=(float*)malloc(ng*sizeof(float));
214     /* numerator of alpha, length=ng */
215     alpha2=(float*)malloc(ng*sizeof(float));
216     /* denominator of alpha, length=ng */
217
218     /*! initialize variables
219     sf_floatread(vv[0], nz*nx, vinit);
220     memset(sp0[0], 0, nz*nx*sizeof(float));
221     memset(sp1[0], 0, nz*nx*sizeof(float));
222     memset(sp2[0], 0, nz*nx*sizeof(float));
223     memset(gp0[0], 0, nz*nx*sizeof(float));
224     memset(gp1[0], 0, nz*nx*sizeof(float));
225     memset(gp2[0], 0, nz*nx*sizeof(float));
226     memset(g0[0], 0, nz*nx*sizeof(float));
227     memset(g1[0], 0, nz*nx*sizeof(float));
228     memset(cg[0], 0, nz*nx*sizeof(float));
229     memset(lap[0], 0, nz*nx*sizeof(float));
230     memset(vtmp[0], 0, nz*nx*sizeof(float));
231     memset(illum[0], 0, nz*nx*sizeof(float));
232     /* set up zero for each array */
233
234     for(it=0;it<nt;it++){
235         tmp=SF_PI*fm*(it*dt-1.0/fm);
236         tmp*=tmp;
237         wlt[it]=(1.0-2.0*tmp)*expf(-tmp);
238     }
239     /* calculate source wavelet */
240
241     if (!(sxbeg>=0 && szbeg>=0 &&
242         sxbeg+(ns-1)*jsx<nx && szbeg+(ns-1)*jsz<nz)) {
243         sf_warning("sources exceeds the computing zone!\n");
244         exit(1);
245     }
246     /* check source position */
247     sg_init(sxz, szbeg, sxbeg, jsz, jsx, ns, nz); ! GOTO sg_init( )
248     /* shot position initialize */
249
250     distx=sxbeg-gxbeg;
251     distz=szbeg-gzbeg;
252     if (csdgather){
253         if(!(gxbeg>=0 && gzbeg>=0 &&
254             gxbeg+(ng-1)*jgx<nx && gzbeg+(ng-1)*jgz<nz &&
255             (sxbeg+(ns-1)*jsx)+(ng-1)*jgx-distx <nx &&

```

```

256         (szbeg+(ns-1)*jsz)+(ng-1)*jgz-distz <nz)){
257             sf_warning("geophones exceeds the computing zone!\n");
258             exit(1);
259         }
260     } else{
261         if(!(gxbeg>=0 && gzbeg>=0 &&
262             gxbeg+(ng-1)*jgx<nx && gzbeg+(ng-1)*jgz<nz)){
263             sf_warning("geophones exceeds the computing zone!\n");
264             exit(1);
265         }
266     }
267     /* check receivers position */
268     sg_init(gxz, gzbeg, gxbeg, jgz, jgx, ng, nz); ! GOTO sg_init( )
269     /*
270     * receiver position initialize
271     * this code is available when csdgather==false
272     */
273
274     memset(bndr, 0, nt*(2*nz+nx)*sizeof(float));
275     memset(dobs, 0, ng*nt*sizeof(float));
276     memset(dcal, 0, ng*sizeof(float));
277     memset(derr, 0, ns*ng*nt*sizeof(float));
278     memset(alpha1, 0, ng*sizeof(float));
279     memset(alpha2, 0, ng*sizeof(float));
280     memset(dobs, 0, ng*nt*sizeof(float));
281     memset(objval, 0, niter*sizeof(float));
282     /* set up zero for each array */
283
284     for(iter=0; iter<niter; iter++){
285         if(verb){
286             start=clock();/* record starting time */
287             sf_warning("iter=%d",iter);
288         }
289         sf_seek(shots, 0L, SEEK_SET);
290         memcpy(g0[0], g1[0], nz*nx*sizeof(float));
291         memset(g1[0], 0, nz*nx*sizeof(float));
292         memset(illum[0], 0, nz*nx*sizeof(float));
293         for(is=0;is<ns;is++){
294             sf_floatread(trans, ng*nt, shots);
295             /* read shot gather */
296             matrix_transpose(trans, dobs, nt, ng); ! GOTO matrix_transpose( )
297             /* transpose the matrix to get dobs */
298             if(csdgather){
299                 gxbeg=sxbeg+is*jsx-distx;
300                 sg_init(gxz, gzbeg, gxbeg, jgz, jgx, ng, nz); ! GOTO sg_init( )
301             }
302             /* receiver position initialize */

```

```

303
304     memset(sp0[0], 0, nz*nx*sizeof(float));
305     memset(sp1[0], 0, nz*nx*sizeof(float));
306     for(it=0; it<nt; it++){
307         add_source(sp1, &wlt[it], &sxz[is], 1, nz, true);
308         ! GOTO add_source( )
309         /* add source */
310
311         step_forward(sp0, sp1, sp2, vv, dtz, dtx, nz, nx);
312         ! GOTO step_forward( )
313         /* forward exploration */
314
315         ptr=sp0; sp0=sp1; sp1=sp2; sp2=ptr;
316         /* update wavefield */
317
318         rw_bndr(&bndr[it*(2*nz+nx)], sp0, nz, nx, true);
319         ! GOTO rw_bndr( )
320         /* save boundary value for saving memory */
321
322         record_seis(dcal, gxz, sp0, ng, nz);
323         ! GOTO record_seis( )
324         /* save seismic record at receiver position */
325
326         cal_residuals(dcal,&dobs[it*ng],&derr[is*ng*nt+it*ng],ng);
327         ! GOTO cal_residuals( )
328         /* calculate record residual at receiver position */
329     }
330     /* forward exploration complete */
331
332     ptr=sp0; sp0=sp1; sp1=ptr;
333     memset(gp0[0], 0, nz*nx*sizeof(float));
334     memset(gp1[0], 0, nz*nx*sizeof(float));
335     for(it=nt-1; it>-1; it--){
336         rw_bndr(&bndr[it*(2*nz+nx)], sp1, nz, nx, false);
337         ! GOTO rw_bndr( )
338         /* read boundary value for saving memory */
339
340         step_backward(illum,lap,sp0,sp1,sp2,vv,dtz,dtx,nz,nx);
341         ! GOTO step_backward( )
342         /*
343          * this step is to recovery forward wavefield
344          * via backward exploration and boundary condition
345          * illum is the source compensate
346          * lap is the laplace operator * velocity^2
347          */
348
349         add_source(sp1, &wlt[it], &sxz[is], 1, nz, false);

```



```

350         ! GOTO add_source( )
351         /* sub source to eliminate source in backward scattering */
352
353         add_source(gp1, &derr[is*ng*nt+it*ng], gxz, ng, nz, true);
354         ! GOTO add_source( )
355         /* stack residual as backward scattering source */
356
357         step_forward(gp0, gp1, gp2, vv, dtz, dtx, nz, nx);
358         ! GOTO step_forward( )
359         /* backward scattering residual wavefield */
360
361         cal_gradient(g1, lap, gp1, nz, nx);
362         ! GOTO cal_gradient( )
363         /* calculate gradient via correlation */
364
365         ptr=sp0; sp0=sp1; sp1=sp2; sp2=ptr;
366         ptr=gp0; gp0=gp1; gp1=gp2; gp2=ptr;
367         /* update wavefield */
368     }
369 }
370 /* simulating complete */
371
372 obj=cal_objective(derr, ng*nt*ns);
373 ! GOTO cal_objective( )
374 /* obj = norm2(derr) */
375
376 scale_gradient(g1, vv, illum, nz, nx, precon);
377 ! GOTO scale_gradient( )
378 /*
379  * g1 = 2.0*g1/velocity^2
380  * IF precon == true DO source compensate
381  */
382 sf_floatwrite(illum[0], nz*nx, illums);
383 /* output illum */
384 bell_smoothz(g1, illum, rbell, nz, nx);
385 ! GOTO bell_smoothz( )
386 bell_smoothx(illum, g1, rbell, nz, nx);
387 ! GOTO bell_smoothx( )
388 /* smooth g1 while use illum as temp store */
389 sf_floatwrite(g1[0], nz*nx, grads);
390 /* output gradient */
391 /* calculating gradient complete */
392
393 if (iter>0)
394     beta=cal_beta(g0, g1, cg, nz, nx);
395 else
396     beta=0.0;

```

```

397         ! GOTO cal_beta( )
398     /* calculate beta */
399     cal_conjgrad(g1, cg, beta, nz, nx);
400     ! GOTO cal_conjgrad( )
401     /* calculate cg direction */
402     epsil=cal_epsilon(vv, cg, nz, nx);
403     ! GOTO cal_epsilon( )
404     /* calculate cg step size */
405     /* calculating CG direction complete */
406
407     sf_seek(shots, 0L, SEEK_SET);
408     memset(alpha1, 0, ng*sizeof(float));
409     memset(alpha2, 0, ng*sizeof(float));
410     cal_vtmp(vtmp, vv, cg, epsil, nz, nx);
411     ! GOTO cal_vtmp( )
412     /* update the velocity */
413     for(is=0;is<ns;is++){
414         sf_floatread(trans, ng*nt, shots);
415         /* read shot gather */
416         matrix_transpose(trans, dobs, nt, ng);
417         ! GOTO matrix_transpose( )
418         /* transpose the matrix to get dobs */
419         if(csdgather){
420             gxbeg=sxbeg+is*jsx-distx;
421             sg_init(gxz, gzbeg, gxbeg, jgz, jgx, ng, nz);
422             ! GOTO sg_init( )
423         }
424         /* receiver position initialize */
425         memset(sp0[0], 0, nz*nx*sizeof(float));
426         memset(sp1[0], 0, nz*nx*sizeof(float));
427         for(it=0; it<nt; it++){
428             add_source(sp1, &wlt[it], &sxz[is], 1, nz, true);
429             ! GOTO add_source( )
430             /* add source */
431
432             step_forward(sp0, sp1, sp2, vv, dtz, dtx, nz, nx);
433             ! GOTO step_forward( )
434             /* forward exploration */
435
436             ptr=sp0; sp0=sp1; sp1=sp2; sp2=ptr;
437             /* update wavefield */
438
439             record_seis(dcal, gxz, sp0, ng, nz);
440             ! GOTO record_seis( )
441             /* save seismic record at receiver position */
442
443             sum_alpha12(alpha1, alpha2, dcal, &dobs[it*ng], &derr[is*ng*nt←

```

```

        +it*ng], ng);
444         ! GOTO sum_alpha12( )
445         /* calculate alpha12 */
446     }
447 }
448
449 alpha=cal_alpha(alpha1, alpha2, epsil, ng);
450 ! GOTO cal_alpha( )
451 /* calculate alpha */
452
453 update_vel(vv, cg, alpha, nz, nx);
454 ! GOTO update_vel( )
455 /* update velocity */
456 sf_floatwrite(vv[0], nz*nx, vupdates);
457 /* output velcotiy */
458 /* updating velocity complete */
459
460 if(iter==0) {
461     obj1=obj;
462     objval[iter]=1.0;
463 } else{
464     objval[iter]=obj/obj1;
465 }
466 /* calcuate obj */
467
468 if(verb) {
469     sf_warning("obj=%f beta=%f epsil=%f alpha=%f", obj, beta, epsil↵
        , alpha);
470     /* output important information at each FWI iteration */
471     stop=clock();
472     /* record ending time */
473     sf_warning("iteration %d finished: %f (s)",iter+1, ((float)(stop-↵
        start))/CLOCKS_PER_SEC);
474 }
475 }
476 sf_floatwrite(objval, niter, objs);
477 /* output obj */
478
479 free(*vv); free(vv);
480 free(*vtmp); free(vtmp);
481 free(*sp0); free(sp0);
482 free(*sp1); free(sp1);
483 free(*sp2); free(sp2);
484 free(*gp0); free(gp0);
485 free(*gp1); free(gp1);
486 free(*gp2); free(gp2);
487 free(*g0); free(g0);

```

```

488     free(*g1); free(g1);
489     free(*cg); free(cg);
490     free(*lap); free(lap);
491     free(*illum); free(illum);
492     free(objval);
493     free(wlt);
494     free(sxz);
495     free(gxz);
496     free(bndr);
497     free(trans);
498     free(dobs);
499     free(dcal);
500     free(derr);
501     free(alpha1);
502     free(alpha2);
503
504     exit(0);
505 }

```

sg_init()

sg_init() in \$(RSFROOT)/src/user/pyang/Mfwi2d.c.

Listing 2: sg_init()

```

1     void sg_init(int *sxz, int szbeg, int sxbeg,
2                 int jsz, int jsx, int ns, int nz)
3     /*< shot/geophone position initialize >*/
4     {
5         int is, sz, sx;
6         for(is=0; is<ns; is++) {
7             sz=szbeg+is*jsz;
8             sx=sxbeg+is*jsx;
9             sxz[is]=sz+nz*sx;
10        }
11    }
12    /*! RETURN main( )

```

matrix_transpose()

matrix_transpose() in \$(RSFROOT)/src/user/pyang/Mfwi2d.c.

Listing 3: matrix_transpose()

```

1 void matrix_transpose(float *matrix, float *trans, int n1, int n2)
2 /*< matrix transpose: matrix transposed to be trans >*/
3 {
4     int i1, i2;
5
6     for(i2=0; i2<n2; i2++)
7         for(i1=0; i1<n1; i1++)
8             trans[i2+n2*i1]=matrix[i1+n1*i2];
9 }
10 ///! RETURN main( )

```

add_source()

add_source() in [\\$\(RSFROOT\)/src/user/pyang/Mfwi2d.c](#).

Listing 4: add_source()

```

1 void add_source(float **p, float *source, int *sxz, int ns, int nz, bool add)
2 /*< add/subtract seismic sources >*/
3 {
4     int is, sx, sz;
5     if(add){
6         for(is=0;is<ns; is++){
7             sx=sxz[is]/nz;
8             sz=sxz[is]%nz;
9             p[sx][sz]+=source[is];
10        }
11    }else{
12        for(is=0;is<ns; is++){
13            sx=sxz[is]/nz;
14            sz=sxz[is]%nz;
15            p[sx][sz]-=source[is];
16        }
17    }
18 }
19 ///! RETURN main( )

```

step_forward()

step_forward() in [\\$\(RSFROOT\)/src/user/pyang/Mfwi2d.c](#).

Listing 5: step_forward()

```

1 void step_forward(float **p0, float **p1, float **p2, float **vv, float dtz, ↵
    float dtx, int nz, int nx)
2 /*< forward modeling step, Clayton-Enquist ABC incorporated >*/
3 {
4     int ix,iz;
5     float v1,v2,diff1,diff2;
6
7     for(ix=0; ix < nx; ix++){
8         for(iz=0; iz < nz; iz++){
9             v1=vv[ix][iz]*dtz; v1=v1*v1;
10            v2=vv[ix][iz]*dtx; v2=v2*v2;
11            diff1=diff2=-2.0*p1[ix][iz];
12            diff1+=(iz-1>=0)?p1[ix][iz-1]:0.0;
13            diff1+=(iz+1<nz)?p1[ix][iz+1]:0.0;
14            diff2+=(ix-1>=0)?p1[ix-1][iz]:0.0;
15            diff2+=(ix+1<nx)?p1[ix+1][iz]:0.0;
16            diff1*=v1;
17            diff2*=v2;
18            p2[ix][iz]=2.0*p1[ix][iz]-p0[ix][iz]+diff1+diff2;
19        }
20    }
21    for (ix=1; ix < nx-1; ix++) {
22        /* top boundary */
23        /*
24        iz=0;
25        diff1= (p1[ix][iz+1]-p1[ix][iz])-
26        (p0[ix][iz+1]-p0[ix][iz]);
27        diff2= c21*(p1[ix-1][iz]+p1[ix+1][iz]) +
28        c22*(p1[ix-2][iz]+p1[ix+2][iz]) +
29        c20*p1[ix][iz];
30        diff1*=sqrtf(vv[ix][iz])/dz;
31        diff2*=vv[ix][iz]/(2.0*dx*dx);
32        p2[ix][iz]=2*p1[ix][iz]-p0[ix][iz]+diff1+diff2;
33        */
34        /* bottom boundary */
35        iz=nz-1;
36        v1=vv[ix][iz]*dtz;
37        v2=vv[ix][iz]*dtx;
38        diff1=-(p1[ix][iz]-p1[ix][iz-1])+(p0[ix][iz]-p0[ix][iz-1]);
39        diff2=p1[ix-1][iz]-2.0*p1[ix][iz]+p1[ix+1][iz];
40        diff1*=v1;
41        diff2*=0.5*v2*v2;
42        p2[ix][iz]=2.0*p1[ix][iz]-p0[ix][iz]+diff1+diff2;
43    }
44
45    for (iz=1; iz < nz-1; iz++){

```

```

46      /* left boundary */
47      ix=0;
48      v1=vv[ix][iz]*dtz;
49      v2=vv[ix][iz]*dtx;
50      diff1=p1[ix][iz-1]-2.0*p1[ix][iz]+p1[ix][iz+1];
51      diff2=(p1[ix+1][iz]-p1[ix][iz])-(p0[ix+1][iz]-p0[ix][iz]);
52      diff1*=0.5*v1*v1;
53      diff2*=v2;
54      p2[ix][iz]=2.0*p1[ix][iz]-p0[ix][iz]+diff1+diff2;
55      /* right boundary */
56      ix=nx-1;
57      v1=vv[ix][iz]*dtz;
58      v2=vv[ix][iz]*dtx;
59      diff1=p1[ix][iz-1]-2.0*p1[ix][iz]+p1[ix][iz+1];
60      diff2=-(p1[ix][iz]-p1[ix-1][iz])+(p0[ix][iz]-p0[ix-1][iz]);
61      diff1*=0.5*v1*v1;
62      diff2*=v2;
63      p2[ix][iz]=2.0*p1[ix][iz]-p0[ix][iz]+diff1+diff2;
64  }
65 }
66 //! RETURN main( )

```

rw_bndr()

rw_bndr() in \$(RSFROOT)/src/user/pyang/Mfwi2d.c.

Listing 6: rw_bndr()

```

1 void rw_bndr(float *bndr, float **p, int nz, int nx, bool write)
2     /*< if write==true, write/save boundaries out of variables;
3     else read boundaries into variables (for 2nd order FD) >*/
4 {
5     int i;
6     if(write){
7         for(i=0; i<nz; i++){
8             bndr[i]=p[0][i];
9             bndr[i+nz]=p[nx-1][i];
10        }
11        for(i=0; i<nx; i++)
12            bndr[i+2*nz]=p[i][nz-1];
13    }else{
14        for(i=0; i<nz; i++){
15            p[0][i]=bndr[i];
16            p[nx-1][i]=bndr[i+nz];
17        }

```

```

18         for(i=0; i<nx; i++)
19             p[i][nz-1]=bndr[i+2*nz];
20     }
21 }
22 ///! RETURN main( )

```

record_seis()

record_seis() in **\$(RSFROOT)/src/user/pyang/Mfwi2d.c**.

Listing 7: record_seis()

```

1 void record_seis(float *seis_it, int *gxz, float **p, int ng, int nz)
2 /*< record seismogram at time it into a vector length of ng >*/
3 {
4     int ig, gx, gz;
5     for(ig=0;ig<ng; ig++){
6         gx=gxz[ig]/nz;
7         gz=gxz[ig]%nz;
8         seis_it[ig]=p[gx][gz];
9     }
10 }
11 ///! RETURN main( )

```

cal_residuals()

cal_residuals() in **\$(RSFROOT)/src/user/pyang/Mfwi2d.c**.

Listing 8: cal_residuals()

```

1 void cal_residuals(float *dcal, float *dobs, float *dres, int ng)
2 /*< calculate residual >*/
3 {
4     int ig;
5     for(ig=0; ig<ng; ig++){
6         dres[ig]=dcal[ig]-dobs[ig];
7     }
8 }
9 ///! RETURN main( )

```

step_backward()

step_backward() in \$(RSFROOT)/src/user/pyang/Mfwi2d.c.

Listing 9: step_backward()

```
1 void step_backward(float **illum, float **lap, float **p0, float **p1, float ←
   **p2, float **vv, float dtz, float dtx, int nz, int nx)
2 /*< step backward >*/
3 {
4     int ix,iz;
5     float v1,v2,diff1,diff2;
6
7     for(ix=0; ix < nx; ix++){
8         for (iz=0; iz < nz; iz++){
9             v1=vv[ix][iz]*dtz; v1=v1*v1;
10            v2=vv[ix][iz]*dtx; v2=v2*v2;
11            diff1=diff2=-2.0*p1[ix][iz];
12            diff1+=(iz-1>=0)?p1[ix][iz-1]:0.0;
13            diff1+=(iz+1<nz)?p1[ix][iz+1]:0.0;
14            diff2+=(ix-1>=0)?p1[ix-1][iz]:0.0;
15            diff2+=(ix+1<nx)?p1[ix+1][iz]:0.0;
16            lap[ix][iz]=diff1+diff2;
17            diff1*=v1;
18            diff2*=v2;
19            p2[ix][iz]=2.0*p1[ix][iz]-p0[ix][iz]+diff1+diff2;
20            illum[ix][iz]+=p1[ix][iz]*p1[ix][iz];
21        }
22    }
23 }
24 //! RETURN main( )
```

cal_gradient()

cal_gradient() in \$(RSFROOT)/src/user/pyang/Mfwi2d.c.

Listing 10: cal_gradient()

```
1 void cal_gradient(float **grad, float **lap, float **gp, int nz, int nx)
2 /*< calculate gradient >*/
3 {
4     int ix, iz;
5     for(ix=0; ix<nx; ix++){
6         for(iz=0; iz<nz; iz++){
7             grad[ix][iz]+=lap[ix][iz]*gp[ix][iz];
8         }
9     }
```

```

9         }
10    }
11    ///! RETURN main( )

```

cal_objective()

cal_objective() in \$(RSFROOT)/src/user/pyang/Mfwi2d.c.

Listing 11: cal_objective()

```

1  float cal_objective(float *dres, int ng)
2  /*< calculate the value of objective function >*/
3  {
4      int i;
5      float a, obj=0;
6
7      for(i=0; i<ng; i++){
8          a=dres[i];
9          obj+=a*a;
10     }
11     return obj;
12 }
13 ///! RETURN main( )

```

scale_gradient()

scale_gradient() in \$(RSFROOT)/src/user/pyang/Mfwi2d.c.

Listing 12: scale_gradient()

```

1  void scale_gradient(float **grad, float **vv, float **illum, int nz, int nx, ↵
    bool precon)
2  /*< scale gradient >*/
3  {
4      int ix, iz;
5      float a;
6      for(ix=1; ix<nx-1; ix++){
7          for(iz=1; iz<nz-1; iz++){
8              a=vv[ix][iz];
9              if (precon)
10                 a=sqrtf(illum[ix][iz]+SF_EPS);
11                 /*precondition with residual wavefield illumination*/
12                 grad[ix][iz]*=2.0/a;

```

```

13     }
14 }
15 for(ix=0; ix<nx; ix++){
16     grad[ix][0]=grad[ix][1];
17     grad[ix][nz-1]=grad[ix][nz-2];
18 }
19
20 for(iz=0; iz<nz; iz++){
21     grad[0][iz]=grad[1][iz];
22     grad[nx-1][iz]=grad[nx-2][iz];
23 }
24 }
25 ///! RETURN main( )

```

bell_smoothz()

bell_smoothz() in [\\$\(RSFROOT\)/src/user/pyang/Mfwi2d.c](#).

Listing 13: bell_smoothz()

```

1 void bell_smoothz(float **g, float **smg, int rbell, int nz, int nx)
2 /*< gaussian bell smoothing for z-axis >*/
3 {
4     int ix, iz, i;
5     float s;
6
7     for(ix=0; ix<nx; ix++){
8         for(iz=0; iz<nz; iz++){
9             s=0.0;
10            for(i=-rbell; i<=rbell; i++)
11                if(iz+i>=0 && iz+i<nz)
12                    s+=expf(-(2.0*i*i)/rbell)*g[ix][iz+i];
13            smg[ix][iz]=s;
14        }
15    }
16 }
17 ///! RETURN main( )

```

bell_smoothx()

bell_smoothx() in [\\$\(RSFROOT\)/src/user/pyang/Mfwi2d.c](#).

Listing 14: bell_smoothx()

```

1 void bell_smoothx(float **g, float **smg, int rbell, int nz, int nx)
2 /*< gaussian bell smoothing for x-axis >*/
3 {
4     int ix, iz, i;
5     float s;
6
7     for(ix=0; ix<nx; ix++) {
8         for(iz=0; iz<nz; iz++){
9             s=0.0;
10            for(i=-rbell; i<=rbell; i++)
11                if(ix+i>=0 && ix+i<nx)
12                    s+=expf(-(2.0*i*i)/rbell)*g[ix+i][iz];
13            smg[ix][iz]=s;
14        }
15    }
16 }
17 //! RETURN main( )

```

cal_beta()

cal_beta() in [\\$\(RFSROOT\)/src/user/pyang/Mfwid.c](#).

Listing 15: cal_beta()

```

1 float cal_beta(float **g0, float **g1, float **cg, int nz, int nx)
2 /*< calculate beta >*/
3 {
4     int ix, iz;
5     float a,b,c;
6
7     a=b=c=0;
8     for(ix=0; ix<nx; ix++){
9         for(iz=0; iz<nz; iz++){
10            a += g1[ix][iz]*(g1[ix][iz]-g0[ix][iz]); // numerator of HS
11            b += cg[ix][iz]*(g1[ix][iz]-g0[ix][iz]); // denominator of HS,DY
12            c += g1[ix][iz]*g1[ix][iz]; // numerator of DY
13        }
14    }
15
16    float beta_HS=(fabsf(b)>0)?(a/b):0.0;
17    float beta_DY=(fabsf(b)>0)?(c/b):0.0;
18    return SF_MAX(0.0, SF_MIN(beta_HS, beta_DY));
19 }
20 //! RETURN main( )

```

cal_conjgrad()

cal_conjgrad() in `$(RSFROOT)/src/user/pyang/Mfwi2d.c`.

Listing 16: cal_conjgrad()

```
1 void cal_conjgrad(float **g1, float **cg, float beta, int nz, int nx)
2 /*< calculate conjugate gradient >*/
3 {
4     int ix, iz;
5
6     for(ix=0; ix<nx; ix++){
7         for(iz=0; iz<nz; iz++){
8             cg[ix][iz]=-g1[ix][iz]+beta*cg[ix][iz];
9         }
10    }
11 }
12 //! RETURN main( )
```

cal_epsilon()

cal_epsilon() in `$(RSFROOT)/src/user/pyang/Mfwi2d.c`.

Listing 17: cal_epsilon()

```
1 float cal_epsilon(float **vv, float **cg, int nz, int nx)
2 /*< calculate epsilon >*/
3 {
4     int ix, iz;
5     float vvmax, cgmax;
6     vvmax=cgmax=0.0;
7
8     for(ix=0; ix<nx; ix++){
9         for(iz=0; iz<nz; iz++){
10             vvmax=SF_MAX(vvmax, fabsf(vv[ix][iz]));
11             cgmax=SF_MAX(cgmax, fabsf(cg[ix][iz]));
12         }
13     }
14
15     return 0.01*vvmax/(cgmax+SF_EPS);
16 }
17 //! RETURN main( )
```

cal_vtmp()

cal_vtmp() in \$(RSFROOT)/src/user/pyang/Mfwi2d.c.

Listing 18: cal_vtmp()

```
1 void cal_vtmp(float **vtmp, float **vv, float **cg, float epsil, int nz, int ←
    nx)
2 /*< calculate temporary velocity >*/
3 {
4     int ix, iz;
5
6     for(ix=0; ix<nx; ix++){
7         for(iz=0; iz<nz; iz++){
8             vtmp[ix][iz]=vv[ix][iz]+epsil*cg[ix][iz];
9         }
10    }
11 }
12 //! RETURN main( )
```

sum_alpha12()

sum_alpha12() in \$(RSFROOT)/src/user/pyang/Mfwi2d.c.

Listing 19: sum_alpha12()

```
1 void sum_alpha12(float *alpha1, float *alpha2, float *dcaltmp, float *dobs, ←
    float *derr, int ng)
2 /*< calculate numerator and denominator of alpha >*/
3 {
4     int ig;
5     float a, b, c;
6     for(ig=0; ig<ng; ig++){
7         c=derr[ig];
8         a=dobs[ig]+c;
9         /*
10          * since f(mk)-dobs[id]=derr[id],
11          * thus f(mk)=b+c;
12          */
13         b=dcaltmp[ig]-a;
14         /* f(mk+epsil*cg)-f(mk) */
15         alpha1[ig]-=b*c;
16         alpha2[ig]+=b*b;
17    }
18 }
19 //! RETURN main( )
```

cal_alpha()

cal_alpha() in [\\$\(RSFR00T\)/src/user/pyang/Mfwi2d.c](#).

Listing 20: cal_alpha()

```
1 float cal_alpha(float *alpha1, float *alpha2, float epsil, int ng)
2 /*< calculate alpha >*/
3 {
4     int ig;
5     float a,b;
6
7     a=b=0;
8     for(ig=0; ig<ng; ig++){
9         a+=alpha1[ig];
10        b+=alpha2[ig];
11    }
12
13    return (a*epsil/(b+SF_EPS));
14 }
15 ///! RETURN main( )
```

update_vel()

update_vel() in [\\$\(RSFR00T\)/src/user/pyang/Mfwi2d.c](#).

Listing 21: update_vel()

```
1 void update_vel(float **vv, float **cg, float alpha, int nz, int nx)
2 /*< update velcity >*/
3 {
4     int ix, iz;
5
6     for(ix=0; ix<nx; ix++){
7         for(iz=0; iz<nz; iz++){
8             vv[ix][iz]+=alpha*cg[ix][iz];
9         }
10    }
11 }
12 ///! RETURN main( )
```
