

Rule Learning from Knowledge Graphs | TILDIL max planck institut | Guided by Embedding Models



Vinh Thinh Ho¹, Daria Stepanova¹, Mohamed Gad-Elrab¹, Evgeny Kharlamov², Gerhard Weikum¹

hvthinh@mpi-inf.mpg.de, dstepano@mpi-inf.mpg.de, gadelrab@mpi-inf.mpg.de, evgeny.kharlamov@cs.ox.ac.uk, weikum@mpi-inf.mpg.de

¹Max Planck Institute for Informatics, Saarbrücken, Germany ²University of Oxford, Oxford, United Kingdom

1. Motivation

- ► Knowledge Graphs: huge collections of positive unary and binary facts treated under Open World Assumption (e.g. isMarriedTo(alice, bob), researcher(mat))
- ► Automatically constructed, thus incomplete ⇒ Knowledge Graph Completion

Rule-based approach

 $livesIn(X,Z) \leftarrow spouse(X,Y), livesIn(Y,Z)$

- + Interpretable
- + Limited training data
- Local patterns
- Not extendable

Embedding-based approach

score(< Jack, livesIn, Chicago >) = 0.8

- Hard to interpret
- A lot of training data
- + Global patterns
- + Extendable (e.g., text)

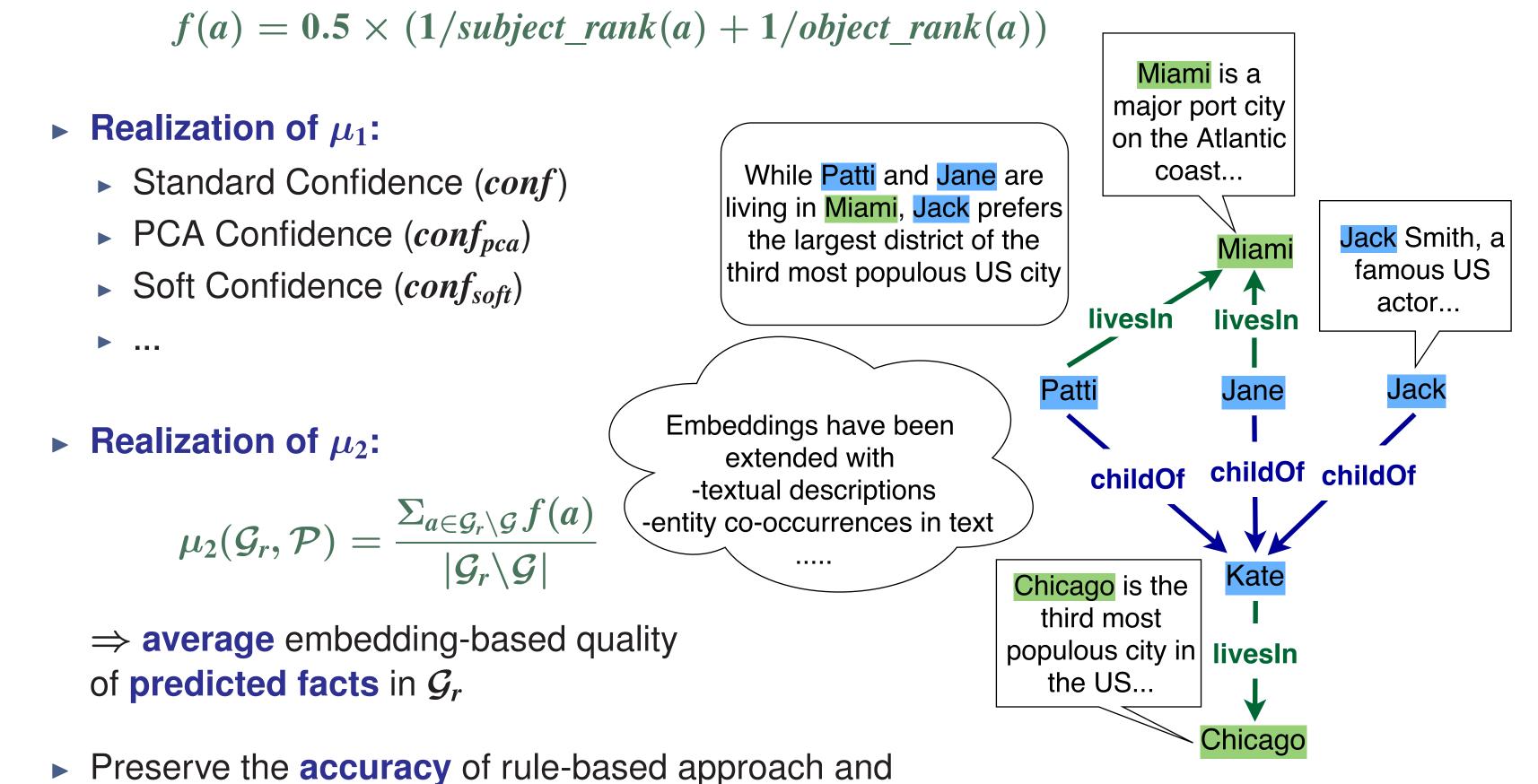
Our approach:

Mine rules with support from KG embeddings

- ► Challenges: OWA, Huge size of KGs, how to combine the 2 approaches
- **▶** Contributions:
 - Framework for rule learning guided by external sources
 - Concrete framework instantiation utilizing feedback from embedding models
 - Interactive non-monotonic rules mining mechanism
 - Experiments on real-world Knowledge Graphs

3. Embedding-based Rule Evaluation

► Realization of f using embeddings [with additional textual data]:



Enhance the **predicting power** of embedding-based approach

2. Rule Learning Guided by External Sources

Given:

- ▶ Knowledge Graph G
- External Source
 - Probability function f reflecting trustfulness of \mathcal{G} 's missing facts

Find:

► A ordered rule list extracted from *G* with respect to the support from the quality function f

Our solution: Introduce the novel Hybrid Rule Quality Function μ as follows:

▶ Measure the **descriptive quality** μ_1 of rule r over \mathcal{G} :

$$\mu_1:(r,\mathcal{G})\mapsto lpha\in[0,1]$$

- \Rightarrow any classical quality measure which describes \mathcal{G} properly
- ▶ Measure the **predictive quality** μ_2 of \mathcal{G}_r relying on $\mathcal{P} = (\mathcal{G}, f)$:

$$\mu_2:(\mathcal{G}_r,\mathcal{P})\mapsto lpha\in[0,1]$$

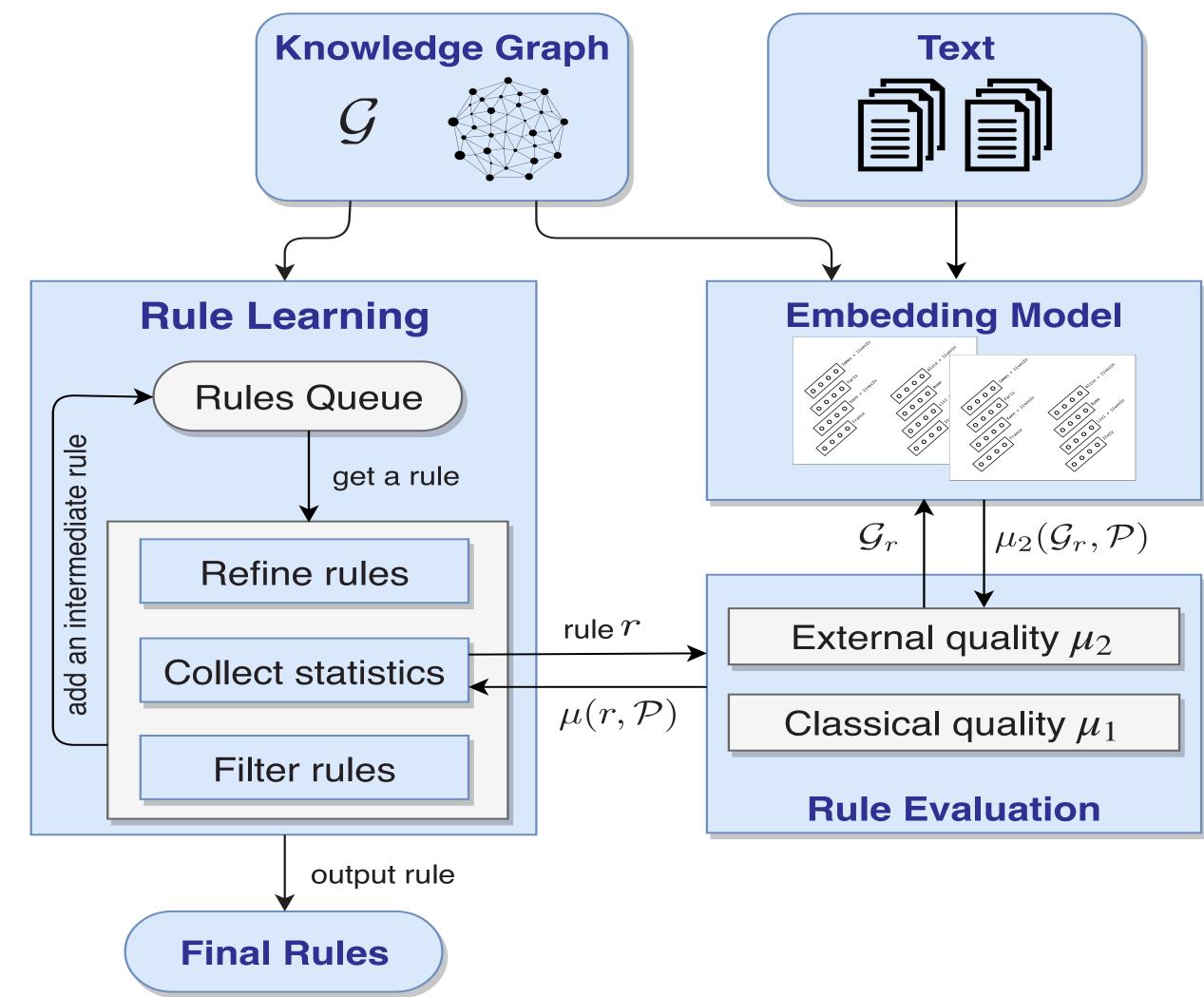
where \mathcal{G}_r is a extension of \mathcal{G} by applying r

- \Rightarrow capture **information about missing facts** in \mathcal{G} that are relevant for r
- Combine the result as the weighted sum:

$$\mu(r,\mathcal{P}) = (1-\lambda) imes \mu_1(r,\mathcal{G}) + \lambda imes \mu_2(\mathcal{G}_r,\mathcal{P})$$

weighting factor $\lambda \in [0,1]$ control the distribution of μ_1 and μ_2

4. Non-monotonic Rule Mining with Embedding Support



5. Rule Refinement and Filters

add dangling atom

livesIn(X, Y) ← ੍

livesln(X, Y) \leftarrow actedln(X,Z) livesln(X, Y) \leftarrow marriedTo(X,Z),

livesIn(Z,Y)

livesln(X, Y) \leftarrow marriedTo(X,Z), livesln(Z,Y),

not researcher(X)

add negated atom

Refinement Operators add:

- dangling atom
- instantiated atom
- closing atom
- negated instantiated atom
- negated closing atom add closing atom
- Filtering rules on:
- rule form support (supp)
- head coverage (hc)
- confidence (conf)
- the hybrid measure (μ) guides the dynamic rules construction

livesln(X, Y) \leftarrow actedln(X,Z),

exception confidence:

$$e ext{-}conf(r,\mathcal{G})=conf(r',\mathcal{G})$$

where $r':body^-(r) \leftarrow body^+(r), not\ head(r) \Rightarrow$ ensure the quality of exceptions

References

producedIn(Z,Y)

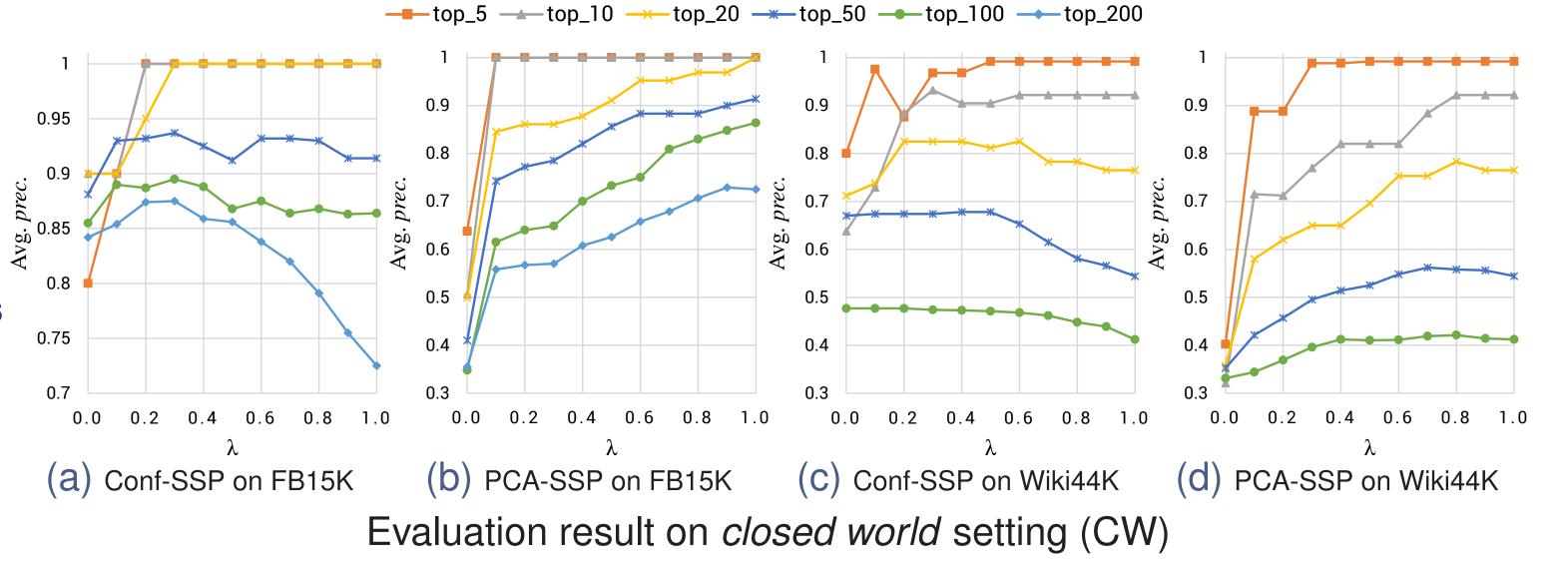
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- ▶ D. H. Tran., D. Stepanova, M. Gad-Elrab, Francesca A. Lisi, G. Weikum. Towards Nonmonotonic Rule Learning from Knowledge Graphs. *Inductive Logic Programming*, 2016.
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6. Experiments

- Data sets: FB15K, Wiki44K
- Approximated ideal KG: original
 Available KG: random 80% of ► Available KG: random 80% of original KG, preserving the distribution of facts over predicates.



- ► Embedding Models: 2 settings
 - Without additional textual data: TransE model, HolE model
 - With entities description text: SSP model
- ▶ 2 Evaluation settings: closed world setting (CW) and open world setting (OW)



- Examples of mined rules:
 - r_1 : nationality $(X,Y) \leftarrow graduated_from(X,Z), in_country(Z,Y), not research_uni(Z)$ r_2 : $scriptwriter_of(X, Y) \leftarrow preceded_by(X, Z), <math>scriptwriter_of(Z, Y), not\ tv_series(Z)$