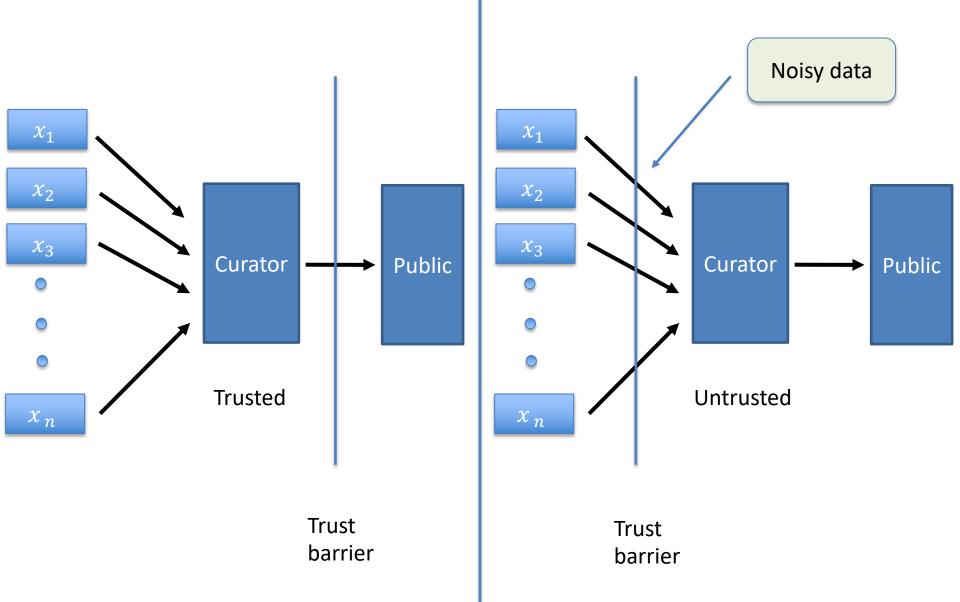


CS208: Applied Privacy for Data Science The Local Model: Foundations

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Central Model vs Local Model



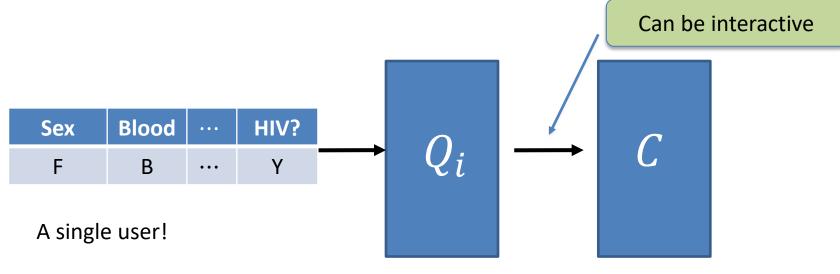
Central Model vs Local Model

DP definition:

An algorithm $M: T^n \to R$ is (ϵ, δ) -differentially private if \forall neighboring $x, x' \in T^n$ and $\forall S \subseteq R$, $P[M(x) \in S] \leq e^{\epsilon} P[M(x') \in S] + \delta$

- Only distinction: when the privacy perturbation needs to be applied!
- Leads to differences in what is meant by ``neighboring databases''

Local Differential Privacy



local randomizer

Local Randomizer $Q: X \to Y$ is (ϵ, δ) — locally differentially private (LDP) if for all $x, x' \in X$, $S \in Y$ $\Pr[Q(x) \in S] \le e^{\varepsilon} \cdot \Pr[Q(x') \in S] + \delta$

A protocol is ε -local DP if each party's local randomizer Q_i is an ε -DP mechanism for 1-row databases.

Randomized Response [Warner'65]

• x_i : bits (binary)

•
$$y_i = \begin{cases} x_i & w.p. \frac{e^{\epsilon}}{1+e^{\epsilon}} \\ 1-x_i & w.p. \frac{1}{1+e^{\epsilon}} \end{cases}$$

Theorem: Each user's disclosure is ϵ -DP.

Mean Estimation by RR

•
$$\hat{\mu} = \frac{1}{n} \sum_{i} \left(\frac{e^{\epsilon} + 1}{e^{\epsilon} - 1} y_i - \frac{1}{e^{\epsilon} - 1} \right)$$

Unbiased estimator

• Accuracy $O\left(\frac{1}{\varepsilon\sqrt{n}}\right)$ (Chebyshev's inequality)

Randomized Response

ε -locally DP protocol that

- Estimates "statistical queries" (means/avgs) to $\pm O\left(\frac{1}{\varepsilon\sqrt{n}}\right)$.
 - Q: how to use RR for fractional-valued functions?
- Estimates count/sum of a bounded function to $\pm O\left(\frac{\sqrt{n}}{\varepsilon}\right)$.
 - -- Q: proof idea?

- Worse than centralized DP, but still useful.
- This is best possible for ε -local DP.

Laplace Mechanism

Histograms

• $x_1, \dots, x_n \in [D]$ (D bins)

 $y_i =$

1 -1 1 ... 1 -1 ... 1

$$x_{i} = 0, y_{i} = \begin{cases} 1 & wp \frac{1}{2} \\ -1 & wp \frac{1}{2} \end{cases} x_{i} = 1, y_{i} = \begin{cases} 1 & wp \frac{1+\epsilon}{2} \\ -1 & wp \frac{1-\epsilon}{2} \end{cases}$$

$$\hat{f}(w) = (\sum w)^{1}$$

$$\hat{f}(x) = (\sum_{i} y_i) \frac{1}{\epsilon}$$

Histograms

- Expected error on each bin is $\pm O\left(\frac{\sqrt{n}}{\varepsilon}\right)$.
- Expected max error over all D bins is $\pm O\left(\frac{\sqrt{n \cdot \log D}}{\varepsilon}\right)$.
- We need to communicate $\Omega(D)$ bits. There exists some sophisticated algorithmic ideas to get computational complexity sublinear in D.

Local vs. Centralized DP

Central Model

- Central curator collects the data from all users, then performs privatization
- Requires the users to trust the curator with their private data
- Most differentially private algorithms are in this model

Local Model

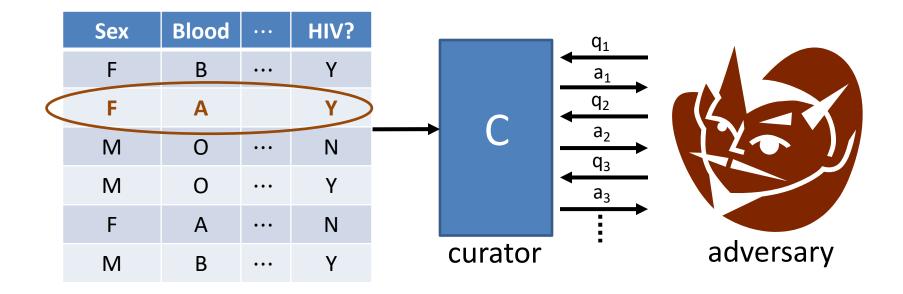
- Each user privatizes their own data then sends it to a central curator
- Require less trust from users
- Worse accuracy

Defining Privacy

• Def: a protocol is ε -local DP if each party's local randomizer Q_i is an ε -DP interactive mechanism for 1-row databases.

Q: What does it mean for an interactive mechanism to be DP?

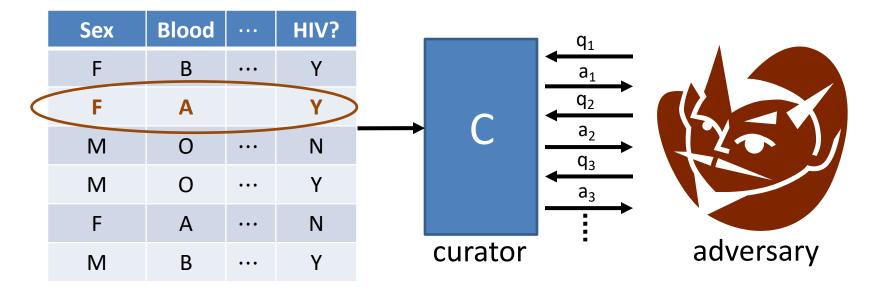
DP for Interactive Mechanisms



1st **Attempt:** for all D, D' differing on one row, all $q_1,...,q_t$, all T

$$\Pr[C(D,q_1,\ldots,q_t)\in T]\leq e^{\varepsilon}\cdot\Pr[C(D',q_1,\ldots,q_t)\in T]+\delta$$
 vectors of answers a_1,\ldots,a_t

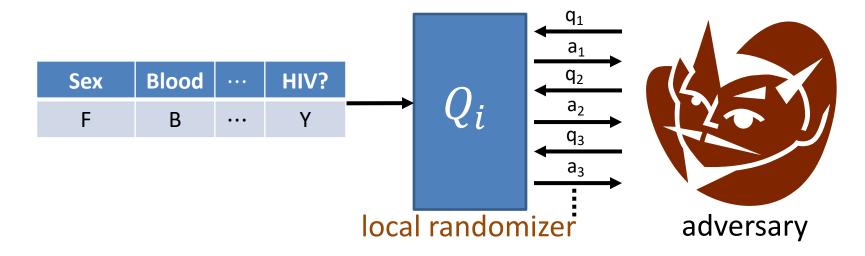
DP for Interactive Mechanisms



Better: for all D, D' differing on one row, all adversarial strategies A $\Pr[A \text{ outputs YES after interacting } w/C(D)] \le e^{\varepsilon} \cdot \Pr[A \text{ outputs YES after interacting } w/C(D')] + \delta$

Fact: composition thms for DP yield interactive DP in this sense. (advanced/optimal comp. requires privacy params to be non-adaptive [Rogers et al. `16].)

Local DP



Require: for all i, x_i, x_i' differing on one row, all strategies A $\Pr[A \text{ outputs YES after interacting } w/Q_i(x_i)] \le e^{\varepsilon} \cdot \Pr[A \text{ outputs YES after interacting } w/Q_i(x_i')] + \delta$

Local vs. Centralized DP

- Local DP protocols provably have lower accuracy for counts/averages than centralized DP protocols.
 - $-\Theta(1/\varepsilon\sqrt{n})$ error vs. $\Theta(1/\varepsilon n)$.
 - Successful deployments have very large n (Google, Apple).

 Gap can be closed by relaxing adversarial model (e.g. anonymous participants, computationally bounded adversaries) and using crypto/infrastructure (secure MPC, mix-nets).