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```
NUMBER THEORY:
SIEVE:
         #define M 1000000
         bool marked[M];
         vector < int > primes;
     3
     4.
        void sieve(int n) {
             primes.push_back(2);
             for (int i = 3; i * i <= n; i += 2) {</pre>
                 if (marked[i] == 0) {
     8.
                     primes.push_back(i);
                     for (int j = i * i; j <= n; j += i + i) {
                        marked[j] = 1;
     11.
     12
     13.
     14. }
NUMBER OF DIVISOR:
         int NOD(int n) {
         int sqrtn = sqrt(n);
             int res = 1:
     3
        for (int i = 0; i < primes.size() && primes[i] <= sqrtn;</pre>
                 if (n \% primes[i] == 0) {
                     int p = 0; /*Counter for power of prime*/
     6
                     while (n \% primes[i] == 0) {
     8.
                         n /= primes[i];
                         p++;
     10
     11.
                     sartn = sart(n);
                     p++; /*Increase it by one at end*/
     13
                     res *= p; /*Multiply with answer*/
     14
     15
           if (n != 1) {
                res *= 2; /*Remaining prime has power p^1. So multipl
         v with 2*/
     18. }
     19.
             return res;
     20 }
ALL DIVISOR:
         vector < II > mainfactor;
       vector < int > countfactor;
         vector < || > allfactor;
       void alldivisor(int idx, II num) {
              if (idx == mainfactor.size()) {
     6
              allfactor.push back(num);
                 return
     8
             alldivisor(idx + 1, num);
           // alldivisor(idx+1, mainfactor[idx]);
     10.
             for (int i = countfactor[idx]; i; i--) {
     11.
            alldivisor(idx + 1, num * mainfactor[idx]);
     13.
                 num *= mainfactor[idx];
     14.
     15. }
BIG MOD: (Iterative)
         int bigmod(int b, int p, int m) {
         int res = 1 \% m, x = b \% m;
              while (p) {
              if (p & 1) res = (res * x) % m;
                 x = (x * x) % m;
     6.
                p >>= 1:
     8.
            return res;
BITWISE SIEVE:
         #define M 100000000
     2. int marked[M / 64 + 2];
     3
         void sieve(int n) {
     4.
          for (int i = 3; i * i < n; i += 2) {
                 if (!bitCheck(i)) {
                     for (int j = i * i; j \le n; j += i + i) {
     6.
                         bitOn(j);
```

```
10.
     11.
         }
     12. bool isPrime(int num) {
     13.
              return num > 1 && (num == 2 || ((num & 1) && !on(num)));
    14. }
MODULAR INVERSE + EXTENDED EUCLID:
         pii extendedEuclid(int a, int b) {
             if (b == 0)
                   \textbf{return} \ \texttt{pii} \ (1, \ \ 0) \ ; \\
              else {
                  pii d = extendedEuclid(b, a % b);
     6.
                  return pii (d. ss, d. ff - d. ss * (a / b));
     7.
     8. }
        int modularInverse(int a, int n) { // returns a er modular In
          verse; n dara mod kore
         pii ret = extendedEuclid(a, n);
     11.
              return ((ret. ff % n) + n) % n;
     12. }
FACTORIAL:
     1. ///Digits of N! in Different Base
         int factorialDigitExtended(int n. int base) {
                  double x = 0;
                  for (int i = 1; i <= n; i++) {
                      x += log10(i) / log10(base); ///Base Conversion
     6.
                  int res = ((int) x) + 1;
                  return res;
     10. ///Prime Factorization of Factorial
     11.
          void factFactorize(int n) {
                  for (int i = 0; i < primes.size() && primes[i] <= n;</pre>
          j++) {
     13.
                      int x = n;
     14.
                      int frea = 0;
     15
                      while (x / primes[i]) {
     16
                       freq += x / primes[i];
     17
                          x = x / primes[i];
     18.
     19
                      printf("%d^%d\u00e4n", primes[i], freq);
     20
     21
     22. ///leading digits in factorial
     23. ///Find the first K digits of N!
     24. ///k=first k digits
          int leadingDigitFact(int n, int k) {
     26.
               double fact = 0;
     27
                  ///Find log(N!)
     28.
                  for (int i = 1; i <= n; i++) {
                      fact += log10(i);
     30.
     31
                  ///Find the value of q
     32.
                  double q = fact - floor(fact + EPS);
     33.
                  double B = pow(10, q);
     34.
                  ///Shift decimal point k-1 times
     35
                  for (int i = 0; i < k - 1; i++) {
     36.
                   B *= 10:
     38.
                 ///Don't forget to floor it
     39
                  return floor (B + eps);
     40.
          ///last digit of factorial
     41.
     42.
         int last_digit_factorial(int N) {
     43
              int i, j, ans = 1, a2 = 0, a5 = 0, a;
     44.
     45
              for (i = 1; i \le N; i++) {
     46.
                j = i;
     47
                  //divide i by 2 and 5
     48.
                  while (j \% 2 == 0) {
     49.
                      j /= 2;
     50
                      a2++:
```

```
51.
          52.
                                    while (j % 5 == 0) {
          53.
                                           j /= 5;
          54.
                                           a5++;
          55.
                                    ans = (ans * (j % 10)) % 10;
          56.
          57.
          58.
                            a = a2 - a5;
                            for (i = 1; i <= a; i++)
          59
          60.
                             ans = (ans * 2) \% 10;
          61.
          62.
          63
LEADING DIGIT OF POWER: (N^M)
                 ///leading digits of n^k
                  II leadingdigit(II n, II k, II dig) {
                            ///\log 10(x) = y
          3.
          4
                           double y = (double) k * log10(n);
                            ///if y=123.456 we are setting y=0.456
                         y = y - floor(y);
          6
          7
                            ///we are getting 10°v for reverse processing
          8
                         y = pow(10, y);
          9
                           ///now we are getting the digits by shifting the decimal
                   to right
                   rep(i, dig - 1) y *= 10;
          10
          11.
                            return (II) floor(y);
          12. }
LINEAR DIOPHANTINE EQN + EXTENDED EUCLID (ITERATIVE):
                   int ext_gcd(int A, int B, int * X, int * Y) {
          2
                  int x2, y2, x1, y1, x, y, r2, r1, q, r;
          3
                            x2 = 1; y2 = 0;
                           x1 = 0; y1 = 1;
          4.
                           for (r2 = A, r1 = B; r1 != 0; r2 = r1, r1 = r, x2 = x1, y
                   2 = y1, x1 = x, y1 = y) {
                           q = r2 / r1;
          6
          7
                                   r = r2 \% r1;
                                 x = x2 - (q * x1);
                                    y = y2 - (q * y1);
                          * X = x2; * Y = y2;
          10
          11.
                            return r2:
          12.
                  bool linearDiophantine(int A, int B, int C, int *x, int *y)
          13.
          14
                            int g = gcd(A, B);
                            if (C % g != 0) return false; //No Solution
          16
                           int a = A / g, b = B / g, c = C / g;
          17
                            ext_gcd(a, b, x, y); //Solve ax + by = 1
           18
                            if (g < 0) \{ //Make Sure gcd(a, b) = 1 \}
          19.
                                    a *= -1;
                               b *= -1;
          20.
                                  c *= -1;
          21.
                           * x *= c; * y *= c; //ax + by = c
          23.
                            return true: //Solution Exists
          24. }
          25
                   int main() {
                   int x, y, A = 2, B = 3, C = 5;
          26.
          27.
                            bool res = linearDiophantine(A, B, C, & x, & y);
                      if (res == false) printf("No Solution\u00e4n");
          28
          29.
                            else {
                            printf("One Possible Solution (%d %d) ¥n", x, y);
          30.
          31.
                                   int g = gcd(A, B);
                                  int k = 1; //Use different value of k to get differen
          32
                   t solutions
                                  printf("Another Possible Solution (%d %d)\footnote{Another Possible 
                    (B / g), y - k * (A / g));
          34. }
          35. }
Simple Hyperbolic Diophantine Equation:
                   bool isValidSolution(int a, int b, int c, int p, int div) {
          2.
                    if (((div - c) \% a) != 0) return false; //x = (div - c) /
          3.
                            if (((p - b * div) % (a * div)) != 0) return false; // y
```

= (p-b*div) / (a*div)

```
5.
         }
     6.
         int hyperbolicDiophantine(int a, int b, int c, int d) {
              int p = a * d + b * c;
              if (p == 0) \{ //ad + bc = 0 \}
                  if (-c % a == 0) return -1; //Infinite solutions (-
     9.
          c/a. k)
     10.
                  else if (-b % a == 0) return -
          1; //Infinite solutions (k, -b/a)
                  else return 0; //No solution
     11.
     12.
             } else {
     13.
                  int res = 0;
     14
                  //For each divisor of p
                  int sqrtn = sqrt(p), div;
     15
                  for (int i = 1; i <= sqrtn; i++) {</pre>
     17.
                       if (p \% i == 0) \{ //i \text{ is a divisor } 
     18
     19
                          //Check if divisors i -i p/i -
          p/i produces valid solutions
                         if (isValidSolution(a, b, c, p, i)) res++;
     20.
                            \textbf{if} \ ( isValidSolution(a, b, c, p, -i) ) \ res++; \\
     21
     22
                          if (p / i != i) { //Check whether p/i is diff
          erent divisor than i
     23
                               if (isValidSolution(a, b, c, p, p / i)) r
          6844.
                              if (isValidSolution(a, b, c, p, -
     24
          p / i)) res++;
     25
     26
     27.
                  }
     28.
                  return res;
     29
     30. }
EULER PHI/TOTIENT:
     1. int phi(int n) // Oyler er Tochient Function
     3
                  int ret = n;
                  for (int i = 2; i * i <= n; i++) {
     4
     5
                      if (n \% i == 0) {
                          while (n % i == 0) {
     7
                              n /= i;
     8
                           ret -= ret / i;
     10
     11
                  1
     12.
                  if (n > 1) ret = ret - (ret / n):
     13
                  return ret:
     14.
     15
              ///another if this method needs to be called several time
     16. #define M 1000005
     17. int phi[M];
     18. void calculatePhi() {
     19.
              for (int i = 1; i < M; i++) {</pre>
     20.
                  phi[i] = i;
     21.
     22
              for (int p = 2; p < M; p++) {
     23.
                  if (phi[p] == p) { // p is a prime}
                   for (int k = p; k < M; k += p) {
     25.
                          phi[k] -= phi[k] / p;
     26
     27.
     28.
     29. }
GCD(I, N) \leftarrow M:
     1.
          int main() {
              calculatePhi();
              sieve (M - 1):
     3
     4.
              int t;
              getI(t):
              rep(cs, t) {
                      II n. m:
```

return true

```
8.
                      int a:
                      CLR (cum):
     9.
     10.
                      getL(n);
                      getI(q);
     11.
     12
                      ///getting the prime factor of n
                      divisor (n):
     13.
     14.
                      ///getting all the factor of n
     15.
                      alldivisor(0, 1);
                      sort(ALL(allfactor));
     16.
     17.
                      ///generating phi value for all the factor
     18.
                      repI(i, allfactor.size()) {
     19.
                          ans.push_back(make_pair(allfactor[i], eulerPh
          i(n / allfactor[i])));
     20
                    }
                      printf("Case %d\u00e4n", cs);
     21.
                      int sz = ans.size();
     22.
     23
                      ///generating cumalitive sum of phi value
     24
                      repl(i sz) {
                          if (i) cum[i] = cum[i - 1] + ans[i].ss;
     25
     26.
                          else cum[i] = ans[i].ss;
     27
     28
                      rep(i, q) {
                          getL(m);
     29
     30.
                          ///binary searching the answer based on the g
          cd see khata for explaination
                          int low = 0. high = sz - 1. flag = -1;
     31
     32
                          while (low <= high) {
     33.
                              int mid = (low + high) / 2;
                              if (ans[mid].ff <= m) {
     34
                                  flag = mid;
     35.
                                  low = mid + 1;
     36
     37.
                              } else high = mid - 1;
     38
     39.
                          ///flag==-1 means m is negative or zero
                          printf("%||d\fomation", flag == -
     40.
          1 ? 0 : cum[flag]);
     41
     42.
                  ///GCD(i, n) <=m
     44
                 ///koita i ase jader n er sathe gcd m er cheya choto
         or equal
     45.
                  ///a = auerv
    46.
SEGMENTED SIEVE:
         #define SIZE 1000005
       int arr[SIZE];
         int segmentedSieve(int a, int b) {
     3
         if (a == 1) a++;
     4
              int sqrtn = sqrt(b);
     5
     6.
             CLR(arr);
             for (int i = 0; i < primes.size() && primes[i] <= sqrtn;</pre>
        int p = primes[i];
     8.
                  int j = p * p;
     9.
     10
                 ///If j is smaller than a, then shift it inside of se
          gment [a, b]
                  if (j < a) j = ((a + p - 1) / p) * p;
     11.
     12.
                  for (; j <= b; j += p) {
                     arr[j - a] = 1; ///mark them as not prime
     13
     14.
     16.
         int res = 0;
     17
              for (int i = a; i \le b; i++) {
     18.
             ///If it is not marked, then it is a prime
                  if (arr[i - a] == 0) res++;
     19.
     20.
     21
              return res;
    22. }
Sum of Divisor (SOD):
     1. int SOD(int n) {
          int res = 1;
                  int sqrtn = sqrt(n);
```

```
for (int i = 0; i < primes.size() && primes[i] <= sqr</pre>
          tn; i++) {
                      if (n % primes[i] == 0) {
                          int tempSum = 1; //Contains value of (p^0+p^1
          +...p^a)
                          int p = 1:
     8.
                          while (n % primes[i] == 0) {
                              n /= primes[i];
     10
                              p *= primes[i];
     11.
                              tempSum += p:
     12.
     13.
                          sartn = sart(n);
     14
                          res *= tempSum;
     15
                      }
     16.
     17.
                  if (n != 1) {
     18
                  res *= (n + 1); //Need to multiply (p^0+p^1)
     19
                  }
     20.
                  return res;
     21.
     22
              ///SOD(N) = (p01+p11+p21...pa11) \times (p02+p12+p22...pa22) \times ...
          (p0k+p1k+p2k...pakk)
SUM OF NUMBER OF DIVISOR (SNOD):

    int SNOD(int n) {

         int res = 0;
              int u = sqrt(n);
              for (int i = 1; i <= u; i++) {
                  res += (n / i) - i; //Step 1
     6.
              res *= 2; //Step 2
     8.
            res += u; //Step 3
    9
              return res;
     10. }
SUM OF SUM OF DIIVISOR (SSOD):
          | | ssod(|| n) {
          II ans = 0;
              for (|| i = 2; i * i <= n; i++) {
              || j = n / i;
                  ans += (i + j) * (j - i + 1) / 2;
     6.
                  ans += i * (j - i);
    8.
              return ans;
    9
XOR 1 TO N:
         | If f(long long a) {
             long long res[] = \{a, 1, a + 1, 0\};
    2
     3.
              return res[a % 4];
     4.
         II getXor(long long a, long long b) {
    5
             return f(b) \hat{f}(a-1);
     6.
LCM SUM:
     1. /*Given n, calculate the sum LCM(1, n) + LCM(2, n) + .. + LCM(n
         II res[1000010];
          II phi[1000010];
     4.
          void precal(int n) {
              ///Calculate phi from 1 to n using sieve
              FOR(i, 1, n) phi[i] = i;
              FOR (i, 2, n) \ \{
     7
     8.
                      if (phi[i] == i) {
                          for (int j = i; j \le n; j += i) {
     10
                              phi[j] /= i;
     11
                              phi[j] *= i - 1;
     12.
     13
     14.
     15
                  ///Calculate partial result using sieve
     16.
                  ///For each divisor d of n, add phi(d)*d to result ar
          ray
     17
              FOR(i, 1, n) \ \{
                  for (int j = i; j <= n; j += i) {
     18.
     19.
                      res[j] += (i * phi[i]);
```

```
21.
     22. }
     23.
          int main() {
               precal (1000000);
     24.
     25.
               int kase;
              scanf("%d", & kase);
     26.
     27.
               while (kase--) {
     28.
               II n;
     29
                   getL(n);
     30.
                   ///We already have partial result in res[n]
     31.
                   II ans = res[n] + 1;
     32.
                   ans *= n;
     33
                   ans /= 2:
                   printf("%||d\u00e4n", ans);
     34
     35.
     36. }
MATRIX EXPONENTIAL:
          struct matrix {
     1
          int v[5][5];
     3
               int row, col; // number of row and column
     4 }:
     5
          int mod = 10000;
        // multiplies two matrices and returns the result
          matrix multiply(matrix a, matrix b) {
          assert(a.col == b.row);
     8
     9.
                   matrix r;
     10.
                  r.row = a.row;
                   r.col = b.col;
     11
                   for (int i = 0; i < r.row; i++) {
     12.
     13.
                       for (int j = 0; j < r.col; j++) {
     14.
                           int sum = 0;
     15
                           for (int k = 0; k < a. col; k++) {
     16.
                                sum += a.v[i][k] * b.v[k][j];
     17.
                                sum %= mod;
     18.
                           r.v[i][j] = sum;
     19
     20.
     21.
     22
                   return r;
     23
     24.
              // returns mat^p
     25.
          matrix power(matrix mat, int p) {
     26.
               assert(p \geq= 1);
               if (p == 1) return mat;
     27
     28
               if (p \% 2 = 1)
                   return multiply(mat, power(mat, p - 1));
     29
     30
               matrix ret = power (mat, p / 2);
               ret = multiply(ret, ret);
     31
     32.
               return ret:
     33.
          }
          int main() {
     34.
     35.
               int tcase;
     36.
               int a, b, n, m;
     37.
               cin >> tcase;
               while (tcase--) {
     38
     39.
                   // input routine
     40.
                   cin \gg a \gg b \gg n \gg m;
     41.
                   // preparing the matrix
     42
                   matrix mat;
     43.
                   mat.row = mat.col = 2;
     44
                   mat. v[0][0] = mat. v[0][1] = mat. v[1][0] = 1;
     45
                   mat. v[1][1] = 0;
     46
                   // preparing mod value
     47.
                   mod = 1;
     48.
                   for (int i = 0; i < m; i++) mod *= 10;</pre>
     49
                   a \%= mod, b \%= mod;
     50
                   if (n < 3) {
     51.
                       if (n == 0) cout \langle\langle a \langle\langle endl \rangle\rangle
                       if (n == 1) cout << b << endl;</pre>
     52.
     53
                       if (n == 2) cout ((a + b) \% \mod (\end I)
     54
                   } else {
     55
                       mat = power(mat, n - 1);
     56.
                       int ans = b * mat. v[0][0] + a * mat. v[0][1];
```

```
57.
                      ans %= mod:
     58.
                     cout << ans << endl;
     59.
     60.
    61. }
NCR:
          ncr[0][0] = 1;
    int limncr = 10;
         FOR(i, 1, limncr)
     4. FOR(j, 0, limner) {
                  if (j > i) ncr[i][j] = 0;
                  else if (j == i || j == 0) ncr[i][j] = 1;
                  else nor[i][j] = nor[i - 1][j - 1] + nor[i - 1][j];
     7.
NEGATIVE BASE:
          string negaBase(int n, int b) {
          int i, tmp;
              string a;
              for (i = 0; n; i++) {
                 tmp = n \% b:
                 n = n / b;
                  if (tmp < 0) {
     8
                  tmp += (-b), n++;
     9.
                 }
     10.
                 a += '0' + tmp;
     11.
     12
             for (n = 0; n < (i / 2); n++) swap(a[n], a[i - n - 1]);
              if (i) return a;
     13.
              return "0";
    15. }
CONSTRUCT N FROM SOD:
         // powi64(a, b) computes a^b, rememver that prime upto i-
          1 are used
     2. i64 table[NN + 1][NN + 1]; // if there is an overflow, table[
      i][j] = inf;
          void preprocessTable() {
     4. for (int i = 0; i <= NN; i++) table[0][i] = 1;
              for (int i = 1; i \le NN; i++) {
             table[i][0] = 1;
     6
                 for (int j = 1; j < NN; j++) table[i][j] = table[i][j
          -1] + powi64(pr[i - 1], j);
         }
     8
         }
     9
     10. vector < i64 > calculateXFromSumOfDivisors(int sum) {
     11
              vector < i64 > res;
     12
              i64 \text{ val} = 1, \text{ prevD} = 1;
     13.
              for (int i = NN;; i--) {
     14.
                  if (sum == 1) {
     15
                     res.push_back(val); // Here the value is saved
     16.
                     sum *= prevD, val = 1;
     17.
     18.
                 if (i <= 0 || sum == 1) break;
                  for (int j = NN - 1; j \ge 0; j--) {
     19
     20.
                     if (table[i][j] > 1 && (sum % table[i][j] == 0))
     21
                          val *= powi64(pr[i - 1], j);
     22.
                         sum /= table[i][j], prevD = table[i][j];
     23.
                          break:
     24.
     25
     26.
     27.
              return res;
    28.
DERANGEMENT:
     1. /*d(n) = (n-1)*(d(n-1)+d(n-2))d(n) = (n-1)*(d(n-1)+d(n-2))
          বেস কেস: d(1)=0, d(2)=1*/
STRING MULTIPLY:
          string multiply(string a. int b) {
             // a contains the biginteger in reversed form
              int carry = 0;
              for (int i = 0; i < a. size(); i++) {</pre>
                  carry += (a[i] - 48) * b;
                  a[i] = (carry \% 10 + 48);
                  carry /= 10;
```

```
9.
         while (carry) {
10.
         a += (carry % 10 + 48);
11.
             carry /= 10;
12.
13.
         return a:
14. }
```

WILSON THEOREM:

Wilson's theorem states that a natural number n>1 is a prime number if and only if $(n-1)! \equiv -1 \pmod{n}$

This asserts that (n-1)! is exactly 1 less than a multiple of n when n

If N is a composite number (except for 1 and 4), then $(N-1)! \equiv 0 \pmod{N}$

CATALAN NUMBER:

```
C_{n+1} = \frac{2(2n+1)}{n+2} C_n
          2n!
C_n = \frac{2 \cdot n!}{n!(n+1)!}
                                        n+2
```

GRAPH THEORY:

DIRECTION ARRAY:

```
1. // 4 direction
2. int dx[]={-1, 1, 0, 0};
    int dy[]={0,0,-1,1};
3
    // 8 direction
     int dx[]=\{-1, 1, 0, 0, -1, -1, 1, 1\};
6. int dy[]={0, 0, -1, 1, -1, 1, 1, -1};
8. int dx[] = \{-2, -2, 2, 2, -1, -1, 1, 1\};
```

```
int dy[] = \{1, -1, -1, 1, 2, -2, -2, 2\};
     Q
ARTICULATION BRIDGE:
          #define BRIDGENODE 10010
         class BridgeFinding {
     2
              int disc[BRIDGENODE];
     3.
              int low[BRIDGENODE];
              int col[BRIDGENODE];
     6.
              int cnt; ///Timer
              int cc: ///Color
     7
     8.
              void tarjan(int s, int parentEdge) {
     9
                  disc[s] = low[s] = cnt++;
     10
                 col[s] = cc + 1;
                  for (int i = 0; i < adj[s].size(); ++i) {</pre>
     11.
                    int t = adj[s][i].ff;
     13.
                      int edgeNumber = adj[s][i].ss;
     14
                      if (edgeNumber == parentEdge) continue;
     15.
                      if (col[t] \le cc) { ///New node. Discovery.
                          tarjan(t, edgeNumber);
     16.
     17.
                          low[s] = min(low[s], low[t]); ///Update back
          edge extension for S
     18.
                          if (low[t] > disc[s]) { ///Back edge of T did
     19
                              ///This edge is Bridge
     20
                         }
     21.
                      } else if (col[t] = cc + 1) { ///Back Edge}
                       low[s] = min(low[s], disc[t]);
     22.
     23.
     24
     25.
     26
     27.
                  vector < pair < int, int > > adj[BRIDGENODE]; ///Ente
          r target and edge number as pair
     28.
              void clear(int n) {
     29.
                  cc += 3; ///cc is now 0. cc+1 is 1
                  for (int i = 0; i <= n; i++) {
     30
     31.
                   adj[i].clear();
     32.
     33.
     34
              void findBridge(int n, int start = 0) {
                  for (int i = start; i <= n; i++) {
     35.
     36.
                      if (col[i] <= cc) {</pre>
     37.
                         tarjan(i, -1);
     38
     39.
     40.
     41. }bridge;
```

```
ARTICULATION POINT:
         #define ARTNODE 10010
         class ArticulationPoint {
              int disc[ARTNODE], low[ARTNODE], col[ARTNODE];
             int cnt: ///Timer
              int cc: ///Color
             int root; ///Root of tree
              void tarjan(int s, int p) {
                 disc[s] = low[s] = cnt++;
     8.
     9
                 col[s] = cc + 1;
     10.
                 int child = 0; ///Needed for root only
     11.
                 int art = 0;
                 for (int i = 0; i < adj[s].size(); ++i) {</pre>
     12.
     13.
                      int t = adj[s][i];
     14.
                      if (t == p) continue; ///Don't go to parent
     15
                      if (col[t] \le cc) { ///New node. Discovery.
     16.
                        child++:
     17
                         tarjan(t, s);
     18.
                         low[s] = min(low[s], low[t]); ///Update back
          edge extension for S
     19
             if (low[t] >= disc[s]) { ///Back edge of T di
          d not go above S
     20
             art++; ///S is articulation point for T
     21
                     } else if (col[t] == cc + 1) { ///Back Edge
     22
     23.
                         low[s] = min(low[s], disc[t]);
     24.
     25
                 }
                 if ((s == root \&\& child > 1) || (s != root \&\& art)) {
     26.
     27
                     ///Edit in this block
     28
                     printf("This is a articulation point: %d\u00e4n", s);
     30.
     31
             public
     32
                 vector < int > adj[ARTNODE];
     33.
              void clear (int n) {
     34
                 cc += 3; ///cc is now 0. cc+1 is 1
                 for (int i = 0; i <= n; i++) {
     35
     36.
                     adj[i].clear();
     37.
     38
              void findArt(int n, int start = 0) {
     39
     40
                 for (int i = start; i <= n; i++) {
                      if (col[i] <= cc) {</pre>
     42
                       root = i;
     43.
                         tarian(i -1):
     44
     45
     46.
             }
     47. } art;
     48. ///remaining component after removing x
     49. int compo = 0;
     50. if ((s == root && child > 1) || (s != root && art)) {
     51. if (s == root) compo = child;
             else compo = art + 1;
     53. } else { ///s is not articulation point
     54.
            if (p != -
          1 || adj[s].size()) compo = 1; ///It is not singleton
    55. }
Strongly Connected Component (SCC) :
        //Cycle contains which scc node belongs too.
         struct SCC {
              int num[NODE], low[NODE], col[NODE], cycle[NODE], st[NODE
         1:

 int tail, cnt, cc;

             vi adj[NODE];
             SCC(): tail(0), cnt(0), cc(0) {
             void clear() {
     8.
                 cc += 3;
                 FOR(i, 0, NODE - 1) adj[i].clear();
                 tail = 0:
```

```
11.
     12.
              void tarjan(int s) {
     13.
                   num[s] = low[s] = cnt++;
                   col[s] = cc + 1;
     14.
     15.
                   st[tail++] = s;
                   FOR(i, 0, SZ(adj[s]) - 1) {
     16.
     17.
                       int t = adj[s][i];
     18.
                       \textbf{if} \ (\texttt{col}[\texttt{t}] \ \Leftarrow \ \texttt{cc}) \ \{
     19.
                           tarjan(t);
     20.
                           low[s] = MIN(low[s], low[t]);
     21.
     22.
                       /*Back edge*/
     23
                       else if (col[t] == cc + 1)
                       low[s] = MIN(low[s], low[t]);
     24
     25
     26.
                   if (low[s] == num[s]) {
     27
                       while (1) {
     28
                           int temp = st[tail - 1];
     29
                           tail--;
     30.
                           col[temp] = cc + 2;
     31
                           cycle[temp] = s;
                           if (s == temp) break;
     32
     33
     34.
     35
              void shrink(int n) {
     36
     37
                   FOR(i, 0, n) {
     38.
                   FOR(j, 0, SZ(adj[i]) - 1) {
                          adj[i][j] = cycle[adj[i][j]]; ///Careful. Thi
     39
          s will create self-loop. Just ignore i-
          >i edges when processing.
     40.
           }
     41
                   }
     42.
                   FOR(i, 0, n) {
                       if (cycle[i] == i) continue;
     43.
     44.
                       int u = cycle[i];
     45
                       FOR(j, 0, SZ(adj[i]) - 1) {
     46.
                        int v = adj[i][j];
     47.
                           adj[u].pb(v);
     48.
     49
                       adj[i].clear();
     50.
     51.
                   FOR(i, 0, n) { ///Not always necessary
     52
                      sort(ALL(adj[i]));
                       UNIQUE(adj[i]);
     53
     54.
     55.
     56
               void findSCC(int n) {
     57
                   FOR(i 0 n) {
                       if (col[i] <= cc) {</pre>
     58.
     59.
                           tarjan(i);
     60
     61.
     62.
     63. };
SHRINK: (mamun4122)
          bool shrink(int node) {
          repl(i, node) {
                   repI(j, adj[i].size()) {
     4.
                   if (cycle[i] != cycle[adj[i][j]]) {
                           scc[cycle[i]].push_back(cycle[adj[i][j]]);
     6.
     8.
     9.
               ///this inserts same edge multiple times
    10. }
Lowest Common Ancesstor (LCA):
     1. #define mx 100002
     2. int depth[mx]; //লেভেল
          int parent[mx][22]; //স্পার্স টেবিল
     4.
          int T[mx]; //প্যারেন্ট
          vector \langle int \rangle g[mx];
          void dfs(int from, int u, int dep) {
```

```
T[u] = from:
              depth[u] = dep;
              for (int i = 0; i < (int) g[u].size(); i++) {</pre>
     10.
                  int v = g[u][i];
     11.
                  if (v == from) continue;
     12.
                  dfs(u, v, dep + 1);
     13.
     14. }
     15. int lca_query(int N, int p, int q)//N=নোড সংখ্যা
    16. {
     17.
                  int tmp, log, i;
     18.
                  if (depth[p] < depth[q])</pre>
     19.
                    tmp = p, p = q, q = tmp;
    20
                  log = 1;
    21.
                  while (1) {
                     int next = log + 1;
    22.
    23
                  if ((1 \ll next) > depth[p]) break:
    24
                  log++;
     25.
    26.
                 for (i = log; i >= 0; i--)
    27
                if (depth[p] - (1 \ll i) >= depth[q])
    28
                   p = parent[p][i];
    29
                  if (p == q)
    30.
                     return p;
    31
                  for (i = log; i >= 0; i--)
    32.
                  if (parent[p][i] != -
          1 && parent[p][i] != parent[q][i])
    33.
                         p = parent[p][i], q = parent[q][i];
    34.
                  return T[p];
    35.
    36. void lca_init(int N) {
    37.
              memset(parent, 1, sizeof(parent)); //শুরুতে সবগুলো ঘরে
          –১ থাকবে
    38. int i, j;
     39.
              for (i = 0; i < N; i++)
     40.
                  parent[i][0] = T[i];
    41
              //can be modified here by looping only to depth from dfs
              for (j = 1; 1 << j < N; j++)
    43.
                  for (i = 0; i < N; i++)
    44.
                  if (parent[i][j - 1] != -1)
    45.
                          parent[i][j] = parent[parent[i][j - 1]][j - 1
    46. }
    47
         int main(void) {
    48.
              g[0].pb(1);g[0].pb(2);g[2].pb(3);g[2].pb(4);
              dfs(0, 0, 0);
    50
              lca_init(5);
    51
              printf("%d¥n", lca\_query(5, 3, 4));\\
    52
              return 0;
    53 }
LCA + MST :
         #define MAXN 200005
         struct edge {
             int u, v, pos;
    4.
             II w;
              bool operator < (const edge & p) const {</pre>
              return w < p.w;
    7
    8. };
         int pr[MAXN];
     10. vector < edge > e;
         int find(int r) {
     11
     12.
          if (pr[r] == r) return r;
     13.
              return pr[r] = find(pr[r]);
     14. }
     15. vector \langle pair \langle int, | 11 \rangle \rangle g[MAXN];
     16. | I ans[MAXN];
     17. ///LCA HERE
     18. int depth[MAXN];
     19
         int parent[MAXN][30];
     20.
         int T[MAXN];
         II dist[MAXN][30];
```

```
22. void dfs(int from, int u, int dep) {
23.
         T[u] = from:
24.
         depth[u] = dep;
25.
         for (int i = 0; i < (int) g[u].size(); i++) {</pre>
26.
             int v = g[u][i].ff;
27.
             if (v == from) continue;
28.
             dist[v][0] = g[u][i].ss;
29.
             dfs(u, v, dep + 1);
30.
31. }
32.
    void lca_init(int N) {
33.
         memset(parent, -1, sizeof(parent));
34.
        int i, j;
         for (i = 1: i \le N: i++)
35
36.
         parent[i][0] = T[i];
37.
         //can be modified here by looping only to depth from dfs
      for (j = 1; 1 << j < N; j++)
38
39.
             for (i = 1; i \le N; i++)
40.
              if (parent[i][j - 1] != -1) {
                     dist[i][j] = max(dist[i][j-1], \ dist[parent[
41.
     i][j - 1]][j - 1]);
42
                     parent[i][j] = parent[parent[i][j - 1]][j - 1
43
44
45
     II lca_query(int N, int p, int q) //N=???? ??????
46.
47
             int tmp, log, i;
             if (depth[p] < depth[q]) swap(p, q);</pre>
48.
49.
             II tmpans = 0;
50
             log = 1;
51
             while (1) {
52.
                int next = log + 1;
53.
                 if ((1 \ll next) > depth[p]) break;
54.
                 log++;
55
56.
             for (i = log; i >= 0; i--)
                 if (depth[p] - (1 \ll i) >= depth[q]) {
57.
58
                   tmpans = max(tmpans, dist[p][i]);
59
                     p = parent[p][i];
60.
61.
             if (p == q)
62
                return tmpans;
             for (i = log; i \ge 0; i--)
63
64.
               if (parent[p][i] != -
     1 && parent[p][i] != parent[q][i]) {
65
                     tmpans = max(tmpans, dist[p][i]);
66
                     tmpans = max(tmpans, dist[q][i]);
67
                     p = parent[p][i];
68.
                     q = parent[q][i];
69
             tmpans = max(tmpans, dist[p][0]);
70.
             tmpans = max(tmpans, dist[q][0]);
72.
             return tmpans;
73
74.
        ///LCA END
75.
     int main() {
76.
     int n, m;
77
         getII(n, m);
78.
         edge get;
         rep(i, m) {
80.
         getII(get.u, get.v);
81
             getL(get.w);
82.
            get.pos = i;
83.
             e. push_back (get);
84.
85
         CIR (ans):
         ///mst here
86
         II mst = 0;
87.
88
         sort(e.begin(), e.end());
         for (int i = 1; i <= n; i++) pr[i] = i;</pre>
89
         int count = 0;
```

```
for (int i = 0; i < (int) e.size(); i++) {</pre>
    91.
     92.
                 int u = find(e[i].u);
     93.
                  int v = find(e[i].v);
     94.
                 if (u != v) {
     95
                     pr[u] = v;
     96.
                     count++:
                     mst += e[i].w;
     98.
                     ans[e[i].pos] = 1;
     99
                     g[e[i].u].push_back(make_pair(e[i].v, e[i].w));
     100.
                     g[e[i].v].push_back(make_pair(e[i].u, e[i].w));
                     if (count == n - 1) break;
     102.
     103
     104
             dfs(-1, 1, 1);
             lca_init(n);
     106.
             repI(i. m) {
     107
                 if (ans[e[i].pos]) ans[e[i].pos] = mst;
     108.
                 else {
     109.
                     ans[e[i].pos] = mst - lca_query(n, e[i].u, e[i].v
     110.
             ans[e[i].pos] += e[i].w;
     111
     113.
             rep(i, m) printf("%||d\fomath{\text{vn''}}, ans[i]);
     114
STABLE MARRIAGE:
     1. /* A person has an integer preference for each of the persons
         of the opposite
        * sex, produces a matching of each man to some woman. The ma
       tching will follow:
     3.
                     - Each man is assigned to a different woman (n mu
          st be at least m)

    No two couples M1W1 and M2W2 will be unstable.

     4
         * Two couples are unstable if (M1 prefers W2 over W1 and W1
          prefers M2 over M1)
       st INPUT: m - number of man, n - number of woman (must be at
      least as large as m)
        * - L[i][]: the list of women in order of decreasin
          g preference of man i
        * - R[j][i]: the attractiveness of i to j.
     9
        * OUTPUTS: - L2R[]: the mate of man i (always between 0 and
                  - R2L[]: the mate of woman j (or -
     10
       1 if single) */
     11. /*While there is a free man m: let w be the most-
         preferred woman to whom he has not yet proposed, and propose
         m to w. If w is free, or is engaged to someone whom she prefe
          rs less than m match m with w else deny proposal */
     12. int m, n, L[MAXM][MAXW], R[MAXW][MAXM], L2R[MAXM], R2L[MAXW],
         p[MAXM];
     13. void stableMarriage() {
     14.
             memset(R2L, -1, sizeof(R2L));
             memset(p, 0, sizeof(p));
     16.
             for (int i = 0; i < m; i++) { // Each man proposes...
     17
                 int man = i;
     18.
                 while (man \ge 0) {
     19.
                     int wom:
     20.
                     while (1) {
     21
                         wom = L[man][p[man]++];
     22.
                         if (R2L[wom] < 0 || R[wom][man] > R[wom][R2L[
          wom]]) break;
     23
     24
                     int hubby = R2L[wom];
     25
                     R2L[L2R[man] = wom] = man;
     26.
                     man = hubby;
     27
     28
    29
         }
MINIMUM VERTEX COVER:
         #define MAXN 100002
         int dp[MAXN][5];
          int par[MAXN]:
         vectoredges[MAXN];
```

```
int f(int u, int isGuard) {
        if (edges[u].size() == 0)
     6.
                  return 0:
              if (dp[u][isGuard] != -1)
                  return dp[u][isGuard];
            int sum = 0:
     10.
     11.
              for (int i = 0; i < (int) edges[u].size(); i++) {</pre>
             int v = edges[u][i];
     13.
                  if (v != par[u]) {
     14.
                  par[v] = u;
     15.
                     if (isGuard == 0)
                       sum += f(v, 1);
     17
                      else
     18
                      sum += \min(f(v, 1), f(v, 0));
                  }
     20.
     21
              return dp[u][isGuard] = sum + isGuard;
     22.
     23.
          int main() {
     24.
         memset(dp, -1, sizeof(dp));
     25
              int n:
     26
              scanf("%d", & n);
     27
              for (int i = 1; i < n; i++) {</pre>
     28.
             int u, v;
                  scanf("%d%d", & u, & v);
     29
     30.
                  edges[u] push back(v):
     31
                  edges[v].push_back(u);
     32.
     33
              int ans = 0;
             ans = min(f(1, 1), f(1, 0));
     34.
              printf("%d\fomatsn";, ans);
     36.
              return 0;
     37 }
KTH BEST SHORTEST PATH:
     1.
         int m, n, deg[MM], source, sink, K, val[MM][12];
     2
        struct edge {
     3.
              int v, w;
         adj[MM][500];
     5.
     6. struct info {
              int v, w, k;
     8.
              bool operator < (const info & b) const {</pre>
     Q
                 return w > b.w;
     10
     11. };
     12. priority_queue < info, vector < info > > Q;
     13. void kthBestShortestPath() {
     14
         int i, j;
              info u. v;
     15
     16.
             for (i = 0; i < n; i++)
               for (j = 0; j < K; j++) val[i][j] = inf;</pre>
     17
     18.
             u.v = source;
              u.k = 0;
     20.
             u. w = 0;
              Q. push (u);
     21
     22.
             while (!Q. empty()) {
                 u = Q. top();
     23.
     24.
                Q. pop();
                  for (i = 0; i < deg[u, v]; i++) {
     25
     26.
                  v. v = adj[u. v][i]. v;
     27.
                      int cost = adj[u, v][i].w + u.w;
     28
                      for (v.k = u.k; v.k < K; v.k++) {
     29
                          if (cost == inf) break;
     30.
                          if (val[v.v][v.k] > cost) {
     31.
                              swap(cost, val[v.v][v.k]);
     32
                             v.w = val[v.v][v.k];
     33
                              Q nush (v):
     34
                             break
     35.
     36
                      for (v. k++; v. k < K; v. k++) {
     37
     38
                      if (cost == inf) break;
```

```
if (val[v.v][v.k] > cost) swap(cost, val[v.v]
          [v.k]);
     40.
     41.
     42.
     43. }
DIJKSTRA:
     1. #define mx 100005

 vector < int > adj[mx], cost[mx];

          struct node {
          int u, w;
              node(int a, int b) { u = a; w = b;}
              bool operator < (const node & p) const {</pre>
                  return w > p.w;
     8.
        };
     10. int dist[mx], par[mx];
     11
          int dijkstra(int dest) {
     12.
              MEM(dist, 63);
     13
              SFT (par):
     14
              priority_queue < node > q;
     15
              q. push (node (1, 0));
     16.
              dist[1] = 0;
     17
              \textbf{while} \ (!q. \, empty()) \ \{
     18.
              node top = q.top();
     19.
                   q. pop();
     20.
                  int u = top.u;
     21
                   if (u == dest) return dist[dest];
     22.
                   repI(i, adj[u].size()) {
                       int v = adj[u][i];
     24.
                      if (dist[u] + cost[u][i] < dist[v]) {</pre>
     25
                           dist[v] = dist[u] + cost[u][i];
     26.
                          par[v] = u;
                           q. push (node (v, dist[v]));
     28.
     29
     30.
     31.
              return -1;
     32
    MAN FORD:
          #define MAXE 10005
          #define MAXN 105
          int dist[MAXN], edge_u[MAXE], edge_v[MAXE], edge_cost[MAXE];
     4. int main() {
              int n, m;
              getII(n, m);
              MFM (dist 63):
              dist[1] = 0;
               rep(i, m) getIII(edge_u[i], edge_v[i], edge_cost[i]);
     10
              int neg cycle = false;
     11.
              rep(step. n) {
               int updated = false;
     13.
                   rep(i, m) {
     14
                   int u = edge_u[i], v = edge_v[i];
     15.
                        \textbf{if} \ (\texttt{dist[u]} \ + \ \texttt{edge\_cost[i]} \ < \ \texttt{dist[v]}) \ \ \{ \\
                       updated = true;
     16.
     17.
                           if (step == n) neg_cycle = true;
                           dist[v] = dist[u] + edge_cost[i];
     18
     19.
     21.
                   if (updated == false) break;
     22
     23.
               if (neg_cycle == false) {
                   rep(i, n) cout << dist[i] << endl;</pre>
     24.
     25.
              } else puts ("Negative Cycle");
     26. }
FLOYD WARSHALL:
          int d[100][100]; // d[i][j] = distance from i to j
     2. int midMan[100][100] //first set -1
          rep(k, n) rep(i, n) rep(j, n)
         if (d[i][j] > d[i][k] + d[k][j]) {
              d[i][j] = d[i][k] + d[k][j];
              next[i][j] = next[i][k];
```

```
8. // at 1st in all position = INF
    // After floyd if diagonal has <INF -> cycle
10. // After floyd if diagonal has \langle 0 - \rangle Neg cycle
11. void print(int a, int b) {
    int k = midMan[a][b];
12.
13.
         if (k == -1) v. PB(b);
         else {
15.
             print(k, b);
16.
             print(a, k);
17.
18. }
```

Tree Diameter:

- 1. // From any node 1st find the farthest node(f1) from that nod
- 2. // Then from F1 the farthest node(f2)
- // Tree diameter = dist[f1][f2];

Farthest node from a Given Node:

- /* First find the tree diameter (f1, f2)
 - Then from given node dist[a][f1] & dist[a][f2] which one is m aximum */

Topological Sort:

1. /* In degree 0 gula k queue te rakhbo then oi gula 1 ta kore queue theke ber kore tader adjancent node er indegree 1 minus korbo. If any in degree decreases to 0 then push the node in queue. jodi n ta node na hoi then topological sort nei */

Prufer Code to Tree:

```
vector < int > prufer;
2
    void pruferCodeToTree() {
3
         /*Stores number count of nodes in the prufer code*/
        map < int. int > mp;
5
         /* Set of integer absent in prufer code*/
        set < int > st:
6
7
         int len = prufer.size();
         int n = len + 2;
8.
9
         /*Count frequency of nodes*/
         for (int i = 0; i < len; i++) {</pre>
10
11
             int t = prufer[i];
12.
             mp[t]++;
13
       /*Find the absent nodes*/
14
15
         for (int i = 1; i <= n; i++) {
16
             if (mp.find(i) == mp.end()) st.insert(i);
17
       /*Connect Edges*/
18
19.
         for (int i = 0; i < len; i++) {
20.
             int a = prufer[i]; // First node
21
             /*Find the smallest number which is not present in pr
     ufer code now*/
22.
             int b = * st.begin(); // Second node
             printf("d d d n", a, b); // Edge of the tree
23
             st.erase(b); // Remove absent list
24
25.
             mp[a]--: // Remove from prufer code
             if (mp[a] == 0) st. insert(a); // If a becomes absent
26.
27
28.
       /*The final edge*/
         printf("%d %d\u00e4n", * st. begin(), * st. rbegin());
30. }
31. // If the tree has n node then we can make n^{n-1}
```

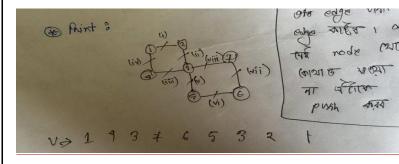
2) numbers of tree Tree to Prufer Code:

/* Among all the leaves which one is minimum we will push tha t in the queue. And cut the edge from the tree. It will be co ntinue until the length of prufer code is (n-2) */

Euler Circuit:

- /* Euler Circuit: If we can visit every edge ONCE and can com e back to the first node then this path is called Euler Circu Condition (Undirected):
- 3.
- (i) All degree even
- 4. (ii) graph connected
- Condition (Directed): 6. (i) for each node InDegree = OutDegree

- (ii) SCC
- Print: Proti edge visit kore edge katbo(mark kore rakhbo). P ore jei node theke kothaou jawa jabena take v te push korbo.



Euler Path:

```
1.
   /* Euler Path: If we can visit every edge ONCE and can go to
    the another node then this path is called Euler Path
```

- Condition (Undirected):
- (i) Except 2 every node has even degree
- (ii) graph connected
- (iii) Source & Destination have odd degree
- Condition(Directed):
- (i) for source (out in) = +1
- 8. (ii) for destination (out in) = -1
- (iii) for others (out in) = 0
- 10. (iv) after adding an edge from Destination to Source the grap h will be SCC
- 11. Print: For undirected, graph traversal will be started from a ny odd degree node like euler circuit.
- 12. For directed, graph traversal will be strated from that node which has (out-in) = +1 like euler circuit*/

MST (KRUS<u>kal)</u> :

```
#define MAXN 100005
     struct edge {
2.
         int u. v. w
         bool operator < (const edge & p) const {</pre>
5
             return w < p.w;
6.
8. int par[MAXN];
9
     vector < edge > e;
10
    int find(int r) {
11.
         if (par[r] == r) return r;
         return par[r] = find(par[r]);
12
    }
13
14. int mst(int n) {
15
         sort(e.begin(), e.end());
16
         for (int i = 1; i <= n; i++) par[i] = i;
17
         int count = 0, s = 0;
18
         for (int i = 0; i < (int) e.size(); i++) {</pre>
19
             int u = find(e[i].u);
20
             int v = find(e[i].v);
             if (u != v) {
21
               par[u] = v;
23.
                 count++;
24
                 s += e[i].w;
25.
                 if (count == n - 1) break;
26.
27.
28
         ///check if a mst exist or not by count
29.
         return s:
30. }
```

MST (PRIMS):

```
typedef vector < vector < pii > > Graph;
long long prim(Graph & g, vector < int > & pred) {
    int n = g. size();
   pred. assign (n, -1);
   vector < bool > vis(n);
   vector < int > prio(n, INT_MAX);
   prio[0] = 0;
```

```
8.
              priority_queue < pii, vector < pii > , greater < pii > >
          a:
     9.
              q. push (make pair (0, 0));
     10.
              long long res = 0;
     11.
              while (!q. empty()) {
                  int d = q. top().first;
     12.
     13.
                  int u = q. top(). second;
                  q. pop();
     14.
     15.
                  if (vis[u])
     16.
                      continue
     17.
                  vis[u] = true;
     18.
                  res += d;
     19
                  for (int i = 0; i < (int) g[u].size(); i++) {</pre>
                    int v = g[u][i].first;
     20
     21.
                      if (vis[v])
     22.
                          continue:
                      int nprio = g[u][i].second;
     23
     24
                      if (prio[v] > nprio) {
     25
                          prio[v] = nprio;
     26.
                          pred[v] = u;
     27
                          q. push (make_pair (nprio, v));
     28
     29
     30.
     31
              return rest
     32 }
     33
          int main() {
     34.
              Graph g(3);
     35
              g[0]. push_back(make_pair(1, 10));
              vector < int > prio;
     36.
     37.
              long long res = prim(g, prio);
     38.
              cout << res << endl;
     39 }
MAXIMUM BIPARTITE MATCHING:
         /* যদি কোন গ্রাফ এর N টা নোড থাকে , এমন এই N টা নোডকে U
          , V দুইটা Independent set এ বিভক্ত করা যাবে যাতে U Set এর
          প্রত্যেকটা নোড এর সাথে V set এর কোন না কোন নোড এর সাথে
          connect থাকবে । এই গ্রাফ এ কোন odd cycle থাকবে না। যেহেতু U
          , V দুইটা মাত্ৰই set এ নোড গুলো বিভক্ত odd cycle থাকা possible
          ও না। আর Independent set U, V এর নিজেদের মধ্যে কোন কানেক
          শন থাকবে না। মানে U set এর কোন নোড নিজেদের মধ্যে connect
          ed থাকবে না।
     2.
         */
          int adj[MAX][MAX], deg[MAX], Left[MAX], Right[MAX], m, n;
     3
     4
         bool visited[MAX];
     5.
          bool bpm(int u) {
     6.
         for (int i = 0, v; i < deg[u]; i++) {</pre>
                  v = adi[u][i]:
     7
     8
                 if (visited[v]) continue;
     9
                  visited[v] = true;
                  if (Right[v] = -1 \mid | bpm(Right[v])) {
     10.
                      Right[v] = u, Left[u] = v;
     11.
                     return true
     13.
                  }
     14
     15.
              return false:
     16.
     17.
          int bipartiteMatching() { // Returns Maximum Matching
         memset(Left, -1, sizeof(Left));
     18.
     19.
              memset(Right, -1, sizeof(Right));
     20.
              int i, cnt = 0;
     21.
              for (i = 0; i < m; i++) {
                 memset(visited, 0, sizeof(visited));
     22
     23.
                  if (bpm(i)) cnt++;
     24.
     25
              return cnt;
     26. }
2-SAT:
          /* 1. The nodes need to be split. So change convert() accordi
         ng Iv.
          2. Using clauses, populate scc edges.
         3. Call possible, to find if a valid solution is possible or
```

```
4. Dont forget to keep space for !A variables */
     5.
          struct SAT2 {
     6.
              SCC scc; /// This is from SCC Class
              SAT2(): bfscc(1) {}
     8.
              void clear() {
     9.
                  scc. clear();
     10.
              int convert(int n) { ///Change here. Depends on how input
          is provided
     12.
          int x = ABS(n);
     13.
                  χ--;
     14.
                  x = 2;
     15.
                  if (n < 0) x = 1;
     16
                  return x;
     17.
     18.
              void mustTrue(int a) { ///A is True
     19
                  scc. adj[a ^1]. pb(a);
     20.
     21.
              void orClause(int a, int b) { /// A || B clause
     22.
                      //!a->b !b->a
                      scc. adj[a ^ 1]. pb(b);
     23
                      scc. adj[b ^ 1]. pb(a);
     24
     25
     26
                  /\!/\!/ Out of all possible option, only one is true
     27
              void atMostOneClause(int a[], int n, int flag) {
     28.
                      if (flag == 0) \{ /// \text{ At most one can be false } \}
     29
                          FOR(i, 0, n) {
     30.
                            a[i] = a[i] ^ 1;
     31
     32.
                      FOR(i, 0, n) {
     34.
                      FOR(j, i + 1, n) {
                              orClause(a[i] ^ 1, a[j] ^ 1); /// !a || !
     35
          b both being true not allowed
     36.
     37.
     38
     39.
                  ///Send n, total number of nodes, after expansion
     40.
              bool possible(int n) {
     41
                      scc.findSCC(n);
     42
     43.
                      FOR(i, 0, n) {
     44.
                              int a = i, b = i ^ 1;
     45
                               ///Falls on same cycle a and !a.
     46
                               if (scc.cycle[a] == scc.cycle[b]) return
          false
     47
                          ///Valid solution exists
     48
     49.
                      return true:
     50
     51.
                  ///To determine if A can be true. It cannot be true,
          if a path exists from A to !A.
     52.
          int vis[SAT2NODE], qqq[SAT2NODE], bfscc;
              void bfs(int s) {
     54.
                  bfscc++;
     55
                  int qs = 0, qt = 0;
     56.
                  vis[s] = bfscc;
     57.
                  qqq[qt++] = s;
     58.
                  while (qs < qt) {
     59
                      s = qqq[qs++];
     60.
                      FOR(i. 0. SZ(scc.adi[s]) - 1)  {
                           int t = scc.adj[s][i];
     62.
                           if (vis[t] != bfscc) {
     63
                              vis[t] = bfscc;
     64
                              qqq[qt++] = t;
     65.
     66
     67
     68.
     69.
     70. }
     71 sat2:
ERDOS AND GALLAI THEOREM:
```

```
// Given the degrees of the vertices of a graph, is it possib
     le to construct such graph Input - the deg[] array
    int deg[MM], n, degSum[MM], ind[MM], minVal[MM];
    bool ErdosGallai() { // 1 indexed
4.
        bool poss = true;
         int i, sum = 0, j, r;
5.
         for (i = 1; i <= n; i++) {
6.
            if (deg[i] >= n) poss = false;
8.
            sum += deg[i];
9
10.
        //Summation of degrees has to be ODD and all degrees has
    to be < n - 1
       if (!poss || (sum & 1) || (n == 1 && deg[1] > 0)) return
11.
     false
12.
    sort(deg + 1, deg + n + 1, greater < int > ());
         degSum[0] = 0;
14
      j = n;
        for (i = 1; i <= n; i++) {
15
16.
            degSum[i] = degSum[i - 1] + deg[i]; //CONSTRUCTING: d
    egSum
            for (; j \ge 1 \&\& deg[j] < i; j--
17
    ); //CONSTRUCTING: ind
18
    ind[i] = j + 1;
19
      //CONSTRUCTING : minVal
20
         for (r = 1; r < n; r++)
21
22
         j = ind[r];
23.
            if (j == n + 1) minVal[r] = (n - r) * r;
           else if (j <= r) minVal[r] = degSum[n] - degSum[r];</pre>
24
25
            else {
               minVal[r] = degSum[n] - degSum[j - 1];
27.
                minVal[r] += (j - r - 1) * r;
28
29.
       //Checking : Erdos & Gallai Theorem
30.
31.
         for (r = 1; r < n; r++)
32
            if (degSum[r] > (r * (r - 1) + minVal[r])) return fal
    se:
33.
34
```

BICONNECTED COMPONENT:



```
1. /*In above graph, following are the biconnected components:
```

- 2. 4-2 3-4 3-1 2-3 1-2
- 3. 8-9
- 4. 8-5 7-8 5-7
- 5. 6-0 5-6 1-5 0-1
- 6. 10-11
- An undirected graph is called Biconnected if there are two ve rtex-disjoint paths between any two vertices.
- 3. Idea is to store visited edges in a stack while DFS on a grap h and keep looking for Articulation Points (highlighted in ab ove figure). As soon as an Articulation Point u is found, all edges visited while DFS from node u onwards will form one bic onnected component. When DFS completes for one connected component, all edges present in stack will form a biconnected component.
- If there is no Articulation Point in graph, then graph is bic onnected and so there will be one biconnected component which is the graph itself.
 */

DYNAMIC PROGRAMMING:

LIS NlogK:

```
1. ///input must be 0 indexed
2. vector < int > Sequence, I, L;
3. int LisNlogK() {
4. int i;
5. I.clear();
6. L.clear();
```

```
I push back (-INF);
              for (i = 1; i <= n; i++) I.push_back(INF);
              int LisLength = 0;
     10.
              for (i = 0; i < n; i++) {
     11.
                  int low, high, mid;
     12.
                  low = 0:
     13.
                  high = LisLength;
     14.
                  while (low <= high) {</pre>
     15
                      mid = (low + high) / 2;
     16.
                      if (I[mid] < Sequence[i])</pre>
     17.
                          low = mid + 1:
     18.
     19
                          high = mid - 1;
     20
     21.
                  I[low] = Sequence[i];
     22.
                  if (LisLength < low)</pre>
     23
                      LisLength = low:
     24.
                  L. push_back(low);
     25.
     26.
              return LisLength;
     27
          }
     28. void findSequence(int length) {
     29
     30
              for (int j = L. size() - 1; j >= 0; j--) {
                  if (L[j] == length) {
     31
     32.
                     ind = i;
     33
                      break:
     34.
     35
              stack < int > st;
     36.
              int mx = length - 1;
     38.
              st.push(Sequence[ind]);
              for (int i = ind - 1; i >= 0; i--) {
     39
     40.
                  if (L[i] == mx && Sequence[ind] > Sequence[i]) {
                      st.push(Sequence[i]);
     41.
     42.
                      ind = i;
     43
                      mx--:
     44
     46.
              while (!st.empty()) {
     47
                  cout << st. top() << endI;
     48.
                  st.pop();
     49.
     50.
     51 }
2D LIS (N log N):

    typedef pair < int, int > pii;

     2. pii p[100005];
          set < pii > s[100005];
     4. set < pii > ::iterator it, it1;
          int main() {
     6. int n, i, lo, hi, mid, lb, k, t, cs = 1;
              scanf("%d", & n);
          for (i = 0; i < n; i++) scanf("%d %d", & p[i].first, & p[
          i]. second);
     9.
              s[0].insert(p[0]);
     10.
              k = 0;
     11.
              for (i = 1; i < n; i++) {
     12
              lo = 0;
     13.
                  hi = k, lb = -1;
                  while (lo <= hi) {
     15
                      mid = (lo + hi) / 2;
     16
                      it = s[mid].lower_bound(p[i]);
     17
                      if (it != s[mid].begin()) {
     18.
                          it1 = it, it1--;
     19
                           if (( * it1).first == p[i].first) it--;
     20
     21
                      if (it != s[mid].begin() && ( * (--
          it)). second < p[i]. second)
     22
                        lo = mid + 1, lb = max(lb, mid);
     23
                      else hi = mid - 1;
     24
```

lb++;

```
26.
                  k = max(k, lb);
     27.
                  it = s[lb].lower_bound(pii(p[i].first, -inf));
     28.
                  if (it == s[lb].end() || (( * it).first > p[i].first
          || ( * it).second > p[i].second))
     29
                      s[lb].insert(p[i]);
                  it = s[lb].upper_bound(p[i]);
     30.
     31.
                  while (it != s[lb].end()) {
                      if (( * it).first >= p[i].first && ( * it).second
     32.
          >= p[i]. second) {
     33.
                          it1 = it, it1++;
     34.
                          s[lb].erase(it);
     35.
                          it = it1;
     36.
                      l else break:
     37
                  }
     38.
     39.
              printf("%dYn", k + 1);
     40
LCS 1D:
          Outline: O(nm) algorithm foR the LCS With O(n) spAce
         int m[2][1000]; // instead of [1000][1000]
          for (i = M; i \ge 0; i--) {
     3
         ii = i & 1;
              for (j = N; j \ge 0; j--) {
              if (i == M || j == N) {
     6
                      m[ii][i] = 0;
     8.
                      continue
                  if (s1[i] == s2[j]) m[ii][j] = 1 + m[1 - ii][j + 1];
     10
                  else m[ii][j] = max(m[ii][j + 1], m[1 - ii][j]);
     12.
     13. }
     14. cout \langle\langle m[0][0]; // \text{ if you want } m[x][y], \text{ write } m[x\&1][y]
Matrix Chain Multiplication (MCM) 0(MAX * MAX):
         #define MAX 100
     int row[MAX], col[MAX];
         int dp[MAX][MAX];
     bool visited[MAX][MAX];
         int f(int beg, int end) {
        if (beg >= end) return 0;
     6.
              if (visited[beg][end]) return dp[beg][end];
            int ans = 1 << 30; //২^৩০ কে ইনফিনিটি ধরছি
     8.
              for (int mid = beg; mid < end; mid++) //দুইভাগে ভাগ করছি
     9
     10.
     11
                  int opr_left = f(beg, mid); //opr = multiplication op
          eration
     12
                int opr_right = f(mid + 1, end);
                  int opr_to_multiply_left_and_right = row[beg] * col[m
     13.
          idl * col[end];
     14.
                 int total = opr_left + opr_right + opr_to_multiply_le
          ft_and_right;
     15.
                  ans = min(ans, total);
     16.
     17.
              visited[beg][end] = 1;
     18.
              dp[beg][end] = ans;
              return dp[beg][end];
     19.
     20. }
     21.
         int main() {
         int n; cin >> n;
     23
              FOR(i, 0, n-1) cin \gg row[i] \gg col[i];
              cout \ll f(0, n - 1) \ll endI;
     24
     25.
         }
HISTOGRAM:
          #define SIZE 120
         int arr[SIZE][SIZE];
          int cum[SIZE][SIZE];
         int histogram(int row, int col) {
              stack < pii > st;
     6.
              st.push(pii(-INF, 0));
              int Ift[SIZE], rght[SIZE];
     8.
              rep(i, col) {
                  while (st. top(). ff \ge cum[row][i]) st. pop();
    9.
```

```
Ift[i] = st. top().ss;
     11.
                  st.push(pii(cum[row][i], i));
     12.
     13.
              while (!st. empty()) st. pop();
     14.
              st.push(pii(-INF, col + 1));
     15.
              ROF(i, col. 1) {
     16.
     17.
                  while (st. top().ff >= cum[row][i]) st.pop();
     18.
                  rght[i] = st.top().ss;
     19.
                  st.push(pii(cum[row][i], i));
     20.
     21.
              int res = -INF;
     22.
              rep(i, col) {
     23
                  res = max(res, cum[row][i] * (rght[i] - Ift[i] - 1));
     24.
        }
     25.
              return res;
    26
LONGEST PALINDROME (MANACHER ALGORITHM):
         // Transform S into T.
        // For example, S = "abba", T = "^#a#b#b#a#$".
     3. // ^ and $ signs are sentinels appended to each end to avoid
          bounds checking
     4. string preProcess(string s) {
              int n = s length();
              if (n == 0) return "^$";
              string ret = "^";
              for (int i = 0; i < n; i++)
     8.
                 ret += "#" + s.substr(i, 1);
     9
     10.
     11.
              ret += "#$";
     12
          return ret;
     13. }
     14. string longestPalindrome(string s) {
     15.
              string T = preProcess(s);
     16
              int n = T. length();
     17.
              int * P = new int[n];
              int C = 0, R = 0;
     19
              for (int i = 1; i < n - 1; i++) {
     20
                 int i_mirror = 2 * C - i; // equals to i' = C - (i - i)
          C)
     21.
     22
                  P[i] = (R > i) ? min(R - i, P[i\_mirror]) : 0;
     23
     24
                  // Attempt to expand palindrome centered at i
     25
                  while (T[i + 1 + P[i]] == T[i - 1 - P[i]])
     26
                  P[i]++;
     27.
     28
                  // If palindrome centered at i expand past R,
     29
                  // adjust center based on expanded palindrome.
     30
                  if (i + P[i] > R) {
     31.
                     C = i;
                    R = i + P[i];
     33.
     34
     35.
              // Find the maximum element in P.
     36.
              int maxLen = 0;
     37.
              int centerIndex = 0;
              for (int i = 1; i < n - 1; i++) {
     38
     39.
                  if (P[i] > maxLen) {
                   maxLen = P[i];
     41
                      centerIndex = i;
     42
     43
              }
     44.
              delete[] P;
              return s. substr((centerIndex - 1 - maxLen) / 2, maxLen);
    46. }
2d MAX SUM: (dipta007)
          struct kadane //Structure for 1D-Kadane Algorithm
    1
     2. {
              int u. d:
             ll sum, area;
```

```
kadane() {
     6.
                 u = -1, d = -1, sum = 0, area = 0;
     7.
     8. };
     9.
          II a[104][104], jaBerHoilo;
     10. pii twoPoint(|| kad[104], int n, || k) {
     11.
              int low = 0, maxL = -1, maxR = -1, maxLen = 0;
              II \max Sum = 0, sum = 0;
              FOR(high, 0, n-1) {
     13.
     14.
                  sum += kad[high];
     15.
                  while (sum > k) {
     16.
                      sum -= kad[low];
     17
                      low++:
     18
     19
                  int len = high - low + 1;
     20.
                  if (len > maxLen) {
     21
                      maxSum = sum; maxLen = len;
     22
                      maxL = low; maxR = high;
     23.
                  } else if (len == maxLen && sum < maxSum) {
     24.
                      maxSum = sum; maxLen = len;
                      maxL = low; maxR = high;
     25
     26
     27
     28.
              jaBerHoilo = maxSum;
     29
              return pii(maxL. maxR);
     30.
         }
     31
          int main() {
     32.
          int t:
              getI(t);
     33
              FOR(ci, 1, t) {
     34.
     35.
                  int n. m. k;
     36
                  getIII(n, m, k);
                  FOR(i, 0, n-1)
     37
     38.
                     FOR(j, 0, m-1)
     39.
                          getL(a[i][j]);
     40.
                  int r = n, c = m, maxL, maxR, maxU, maxD;
     41
                  II maxSum = 0, maxArea = 0, kad[r];
     42.
                  for (int left = 0; left < c; left++) {</pre>
     43.
     44
                      for (int right = left; right < c; right++) {</pre>
                          for (int i = 0; i < r; i++) {
     45
     46.
                              kad[i] = kad[i] + a[i][right];
     47.
     48
                          pii res = twoPoint(kad, r, k);
                           if (res. ff = -1 \mid \mid res. ss == -1) continue;
     49
     50
                          kadane maxv;
     51.
                          maxy.sum = jaBerHoilo;
     52
                          maxy.u = res.ff; maxy.d = res.ss;
     53
                          maxy. area = (II) abs (maxy. d - maxy. u + 1) * (
          II) abs(right - left + 1);
     54.
                          if (maxy.area > maxArea) {
     55
                              maxArea = maxv. area;
     56.
                              maxSum = maxv.sum;
     57.
                              maxL = left; maxR = right;
     58.
                              maxU = maxy.u; maxD = maxy.d;
     59
                          } else if (maxy. area == maxArea && maxy. sum <
          maxSum) {
     60.
                              maxArea = maxy.area;
     61.
                              maxSum = maxy.sum;
     62
                              maxL = left; maxR = right;
                              maxU = maxy.u; maxD = maxy.d;
     63.
     64.
     65
     66
                  } ///end of 2d kadane
     67.
                  printf("Case #%d: %IId %IId\u00e4n", ci, maxArea, maxSum);
     68.
     69
2d MAX SUM: (mamun4122)
     1. #define SIZE 105
     2. int arr[SIZE][SIZE], vertical[SIZE][SIZE], cum[SIZE][SIZE];
          int tmp[SI7F];
     4. int twopointer (int frst, int scnd) {
     5
              CLR(tmp);
```

```
rep(i, m) tmp[i]=vertical[scnd][i]-vertical[frst-1][i];
              int Ift = 1, rght = 1, res = -INF, sum = 0;
     8.
              while (rght <= m) {</pre>
     9.
                   if (sum + tmp[rght] >= tmp[rght]) sum += tmp[rght];
     10.
                  else {
                      while(Ift< rght && sum + tmp[rght] < tmp[rght]) {</pre>
     11.
     12
                          sum -= tmp[lft];
     13.
                          Ift++;
     14.
     15.
                       sum += tmp[rght];
     16.
     17.
                  res = max(res, sum);
     18.
                  rght++;
     19
     20.
              res = max(res, sum);
     21.
              return res;
     22. }
     23
          int findmaximumsum(int r, int c) {
     24.
              int n = r, m = c;
     25
              CLR(vertical);
     26
              CLR (cum):
     27
              ///first find the vertical cum sum of every row
     28
              for (int i = 1; i <= n; i++) {
     29
                  for (int j = 1; j \le m; j++)
     30
                      vertical[i][j] = vertical[i - 1][j] + arr[i][j];
     31
     32.
              int ans = -INT_MAX;
              for (int first = 1; first <= n; first++) {</pre>
     33
                  for (int scnd = first; scnd <= n; scnd++) {</pre>
     34.
                      ans = max(ans, twopointer(first, scnd));
     36
     37
     38.
              return ans;
     39.
COIN CHANGE (II):
     1. /*In a strange shop there are n types of coins of value A1. A
          2\,\ldots\, An. You have to find the number of ways you can make M
          using the coins. You can use any coin at most M times.*/
     int t. n. m. val[105];
          int dp[105][10005];
          #define mod 100000007
          int main() {
         getI(t);
     6
              rep(cs, t) {
     8
                  getII(n, m);
     Q
                  int x:
     10.
                  rep(i, n) getI(val[i]);
     11
                  rep(i, n) dp[i][0] = 1;
     12
                  rep(i, m) dp[0][i] = 0;
     13
                  rep(i, n) {
     14.
                   rep(i, m) {
                          if (j < val[i]) dp[i][j] = dp[i - 1][j] % mod
                          else dp[i][j] = ((dp[i - 1][j] \% mod + dp[i][
     16
          j - val[i]] % mod) % mod);
                      }
     18.
     19
                  printf("Case %d: %d\u00e4n", cs, dp[n][m]);
     20.
     21. }
COIN CHANGE (III):
          /*In a strange shop there are n types of coins of value A1. A
          2 \ldots An. C1, C2, \ldots Cn denote the number of coins of value
          A1, A2 ... An respectively. You have to find the number of di
          fferent values (from 1 to m), which can be produced using the
          se coins. */
     int t, n, m;
          int arr[105], val[105];
          int dp[100005], need[100005];
          int main() {
              getI(t);
              rep(cs, t) {
```

```
CLR (dp):
                 getII(n, m);
    9.
     10.
                 rep(i, n) getI(val[i]);
     11.
                 rep(i, n) getI(arr[i]);
    12.
                 dp[0] = 1;
                 int ans = 0:
    13.
    14.
                 rep(i, n) {
    15.
                     CLR (need);
                     for (int j = val[i]; j <= m; j++) {</pre>
    16.
    17.
                      if (!dp[j] && dp[j - val[i]] && need[j - val[
          i]] + 1 <= arr[i]) {
     18.
    19.
                             dp[j] = 1;
    20
                             need[j] = need[j - val[i]] + 1;
    21.
    22.
    23
                 printf("Case %d: %d\u00e4n", cs, ans);
    24
    25.
    26. }
DIGIT DP (dipta007) :
    1. const int NX = 70;
    2. II dp[2][2][NX][NX];
       int vis[2][2][NX][NX];
    4. int lim, tt;
         vector < int > inp;
    6. II DP(int pos, int isSmall, int isStart, int value) {
            if (pos == lim) return value;
           II & ret = dp[isSmall][isStart][pos][value];
    8.
             int & v = vis[isSmall][isStart][pos][value];
           if (v == tt) return ret;
    11
            v = tt:
         int ses = isSmall ? 9 : inp[pos];
     12.
             int i:
     13.
           ret = 0;
     14.
             if (!isStart) {
    15
            for (i = 0; i <= ses; i++) {
     16.
                 ret += DP(pos + 1, isSmall | i \leq inp[pos], 0, (i
         == 0) + value);
         }
     18
     19.
             } else {
         for (i = 1; i <= ses; i++) {
    20.
    21.
                 ret += DP(pos + 1, isSmall | i < inp[pos], 0, (i
         == 0) + value):
    22. }
                 ret += DP(pos + 1, 1, 1, 0);
    24
    25
             return ret:
    26. }
    27
         II Cal(II x) {
         if (x < 0) return 0;
    28.
             if (x \le 9) return 1;
    29.
    30.
           inp.clear();
    31.
             while (x) {
            inp. pb (x % 10);
    32
    33.
                 x /= 10;
    34.
    35.
             reverse(inp.begin(), inp.end());
           lim = inp.size();
    36
    37.
             return DP(0, 0, 1, 0) + 1; //for '0' case (+1)
    39.
        }
    40. int main() {
    41.
             int cs, t;
    42.
             getI(t);
    43.
             for (cs = 1; cs <= t; cs++) {
             II n, m;
    44
    45.
                 getLL(n, m);
                II ans = Cal(m) - Cal(n - 1);
                 printf("Case %d: %IId\u00e4n", cs, ans);
     47
    48.
    49
        }
DIGIT DP (mamun4122) :
```

```
int tot:
         vector < int > dig;
         II dp[20][2][200][2];
         Il call(int pos, int flag, int sum, int strt) {
             if (pos == tot) return sum;
           II & ret = dp[pos][flag][sum][strt];
             if (ret != -1) return ret;
           II ans = 0;
             if (pos == 0) {
     10.
            repI(i, dig[pos] + 1) {
     11.
                  ans += call(pos + 1, i == dig[pos], sum + (i == 0
         && strt), (strt || i != 0));
     12.
         }
             } else {
    13
    14. if (flag) {
                    for (int i = 0; i <= dig[pos]; i++) {</pre>
    16.
                      ans += call(pos + 1, i == dig[pos], sum + (i
        == 0 && strt), (strt || i != 0));
                    }
     18.
                } else {
                    repI(i, 10)
    19
    20
                    ans += call(pos + 1, 0, sum + (i == 0 && strt), (
         strt || i != 0));
    21.
    22
             }
    23.
             return ret = ans:
    24 }
    25.
         void calc(|| num) {
    26. dig. clear();
             while (num) {
    27.
             dig.push_back(num % 10);
    29
                 num /= 10;
    30
    31.
             reverse(ALL(dig));
             tot = dig.size();
    32.
    33. }
    34. int main() {
    35.
             int t, n, m;
             getI(t);
    37.
             rep(cs, t) {
    38
                SFT (dp):
    39.
                 II a, b;
     40.
                 getLL(a, b);
    41
                 a--;
    42
                 II ansa, ansb;
                 if (a < 0) ansa = 0;
    44
                 else if (a < 10) ansa = 1;
     45
                 else {
    46.
                 calc(a);
     47
                    ansa = call(0, 0, 0, 0) + 1;
    48
    49
                 SFT (dp):
    50.
                 calc(b);
                 ansb = call(0, 0, 0, 0) + 1;
    52.
                 printf("Case %d: %IId\u00e4n", cs, ansb - ansa);
    53
    54.
         }
EDIT DISTANCE:
    1 int MOD = 1000000007:
    int dp[4000][4000];
    3. int main() {

 4. int t;

             getI(t);
            getchar();
    6.
             for (int ci = 1; ci <= t; ci++) {
             string a, b;
    9
                 cin \gg a \gg b;
     10.
                 int la = a.size();
     11.
                 int lb = b. size();
     12
                 for (int i = 0; i <= la; i++)
     13
                   dp[0][i] = i:
     14.
                 for (int i = 0; i <= lb; i++)
                    dp[i][0] = i;
```

```
for (int i = 1; i <= lb; i++) {</pre>
                                                                                    15.
     17.
                      for (int j = 1; j \le la; j++) {
                                                                                    16.
                          if (a[j-1] == b[i-1]) {
     18.
                                                                                    17.
     19.
                               dp[i][j] = dp[i - 1][j - 1];
     20.
                           } else {
                                                                                    19.
     21.
                                                                                    20.
                              dp[i][j] = min(dp[i-1][j], min(dp[i-1]
          [j-1], dp[i][j-1])) + 1;
                                                                                    21.
     22.
                                                                                    22.
                                                                                    23.
     23.
                      }
     24.
                                                                                    24.
                  printf("%d\fomation", dp[lb][la]);
     26.
     27.
GAME THEORY:
NIM:
          /*নিম-
                                                                                    4
          গেম এ দুইজন খেলোয়ার আর কিছু পাথরের স্তুপ(pile) থাকে। প্রতি
                                                                                    5
          চালে একজন খেলোয়াড় যেকোনো একটা স্তুপ থেকে এক বা একাধিক
          পাথর তুলে নিতে পারে। কেও চাল দিতে ব্যার্থ হলে হেরে যাবে। অর্থাৎ
                                                                                    7
          শেষ পাথরটা যে তুলে নিয়েছে সে গেমে জিতবে।
                                                                                    8
         */
     3
          if (xorsum > 0) first win
                                                                                    10.
     4
          else second win
                                                                                    11
Spurge Grundy:
                                                                                    12.
          int grundy[600][600];
                                                                                     13.
         int dirx[]=\{-2, -3, -2, -1, -1, 1\};
     2
                                                                                    14.
          int diry[]=\{1, -1, -1, -2, -3, -2\};
     3.
                                                                                    15
        int calc(int x, int y) {
                                                                                    16.
     5.
              if (grundy[x][y] != -1)
                                                                                    17.
     6
                  return grundy[x][y];
                                                                                    18.
              set < int > st;
     7.
                                                                                    19
     8.
              for (int i = 0; i < 6; i++) {
                                                                                    20.
     9
                  int posx = x + dirx[i];
                                                                                    21.
                  int posy = y + diry[i];
     10
                                                                                    22
     11.
                  if (posx >= 0 \&\& posy >= 0)
                                                                                    23
                  st.insert(calc(posx, posy));
                                                                                    24
     13
                                                                                    25.
     14
              int ans = 0:
                                                                                    26
     15
              while (st. contains (ans)) ans++;
                                                                                    27
     16.
              return grundy[x][y] = ans;
                                                                                    28
     17.
                                                                                    29
         int main() {
     18
                                                                                    30
     19
              int i, j, t, cs, n;
                                                                                    31
     20.
              getI(t);
                                                                                    32
     21
              SFT (grundy):
                                                                                    33
              rep(cs. t) {
     22
                                                                                    34
     23.
                  int ans = 0;
                                                                                    35.
                  printf("Case %d: ", cs);
     24.
                                                                                    36
     25
                  getI(n);
                                                                                    37.
     26.
                  rep(i, n) {
                                                                                    38.
     27.
                      int x, y;
                                                                                    39.
     28.
                      getII(x, y);
     29
                      ans \hat{} = calc(x, y);
     30.
     31.
                  if (ans) puts("Alice");
     32.
                  else puts("Bob");
     33.
                                                                                    4.
     34.
                                                                                    5
MINMAX:
          const int MAXN = 100005;
          int dp[MAXN];
     2.
          bool vis[MAXN];
     4.
          int moves[]={1, 3, 5};
     5
          bool valid_move(int x) {
         return x >= 0;
     6.
                                                                                    6.
        bool MINMAX(int x) {
     8.
              if (x == 0) return false; ///LOSE
     10.
              if (vis[x]) return dp[x];
                                                                                    10.
              vis[x] = 1;
     11.
                                                                                    11.
     12.
             FOR(i, 0, 2) {
                if (valid_move(x - moves[i]) && !MINMAX(x - moves[i])
     13.
            return dp[x] = true;
```

```
return dp[x] = false;
         }
     18. int main() {
             int n:
             getI(n):
             CLR(vis);
             if (MINMAX(n)) printf("First");
             else printf("Second");
DATA STRUCTURE:
UNION FIND/DISJOINT SET:
     1. class UnionFind { // 00P style
             private:
                 vi p, rank, setSize; // remember: vi is vector<int>
             int numSets:
             public.
                 UnionFind(int N) {
                     setSize.assign(N. 1);
                     numSets = N:
                     rank.assign(N, 0);
                     p. assign (N, 0);
                     for (int i = 0; i < N; i++) p[i] = i;
              int findSet(int i) {
                 return (p[i] == i) ? i : (p[i] = findSet(p[i]));
             bool isSameSet(int i, int j) {
                 return findSet(i) == findSet(j);
              void unionSet(int i, int j) {
                 if (!isSameSet(i, j)) {
                     int x = findSet(i), y = findSet(j);
                     // rank is used to keep the tree short
                      if (rank[x] > rank[y]) {
                         x = [v]q
                         setSize[x] += setSize[y];
                     } else {
                         p[x] = y;
                         setSize[y] += setSize[x];
                         if (rank[x] == rank[y]) rank[y]++;
             int numDisjointSets() {
                 return numSets;
              int sizeOfSet(int i) {
                 return setSize[findSet(i)];
    40. };
UNION FIND (MAMUN4122) :
        int find_representative(int r) {
          if (par[r] == r) return r;
             else {
               return par[r] = find_representative(par[r]);
        }
SEGMENT TREE:
         #define mx 100001
         int arr[mx];
          int tree[mx * 3]:
         void init(int node, int b, int e) {
              \textbf{if} \ (b == e) \ \{ \\
                 tree[node] = arr[b];
              init(Left, b, mid);
             init(Right, mid + 1, e);
              tree[node] = tree[Left] + tree[Right];
     12.
     13. int query(int node, int b, int e, int i, int j) {
     14. if (i > e \mid j < b) return 0;
              if (b >= i && e <= j) return tree[node];</pre>
```

```
int p1 = query(Left, b, mid, i, j);
     17.
              int p2 = query(Right, mid + 1, e, i, j);
     18.
             return p1 + p2;
     19.
         }
        void update(int node, int b, int e, int i, int newvalue) {
     20.
     21.
             if (i > e \mid | i < b) return:
     22.
              if (b >= i && e <= i) {
                  tree[node] = newvalue;
     23
     24.
                  return
     25.
     26.
            update(Left, b, mid, i, newvalue);
     27.
              update(Right, mid + 1, e, i, newvalue);
     28.
             tree[node] = tree[Left] + tree[Right];
     29 }
     30. ///lazy with propagation
         void Propagate(int at, int L, int R) {
     31.
     32.
             int mid = (L + R) / 2;
     33
              int left_at = at * 2, left_L = L, left_R = mid;
     34.
              int right_at = at * 2 + 1, right_L = mid + 1, right_R = R
     35
              toggle[at] = 0;
             toggle[left at] ^= 1;
     36
              toggle[right_at] ^= 1;
     37
              on[left_at] = left_R - left_L + 1 - on[left_at];
     38.
     30
              on[right_at] = right_R - right_L + 1 - on[right_at];
     40. }
     41
         void update(int at, int L, int R, int I, int r) {
     42.
         if (r < L || R < I) return;</pre>
              if (I <= L && R <= r) {</pre>
     43.
             toggle[at] ^= 1;
     44.
                  on[at] = R - L + 1 - on;
     45.
     46.
                return;
     47
     48.
         if (toggle[at]) Propagate(at, L, R);
              int mid = (L + R) / 2;
     49.
     50.
             update(at * 2, L, mid, I, r);
     51
             update(at * 2 + 1, mid + 1, R, I, r);
     52.
             on[at] = on[at * 2] + on[at * 2 + 1];
     54. int query(int at, int L, int R, int I, int r) {
              if (r < L \mid \mid R < I) return;
     55
     56.
              if (I <= L && R <= r) return on[at];</pre>
              if (toggle[at]) Propagate(at, L, R);
     58
             int mid = (L + R) / 2;
     59
              int x = querv(at * 2. L. mid. l. r);
     60
           int y = query(at * 2 + 1, mid + 1, R, I, r);
     61.
             return x + v;
     62
Binary Indexed Tree (BIT):
         int query(int idx) {
        int sum = 0;
     2
             while (idx > 0) {
     3.
             sum += tree[idx];
                  idx = idx & (-idx);
     6.
             return sum;
     8. }
         void update(int idx, int x, int n)
     10. //n is the size of the array, x is the number to add
     11. {
             while (idx <= n) {
     13
                  tree[idx] += x;
                 idx += idx & (-idx);
     14
     15.
             }
     16. }
Range Minimum Query (RMQ) :
     1. const int inf = (1 \ll 28);
       template < typename t > t MIN3(t a, t b, t c) {
             return min(a, min(b, c));
     4. }
     5.
         const int sz = 100005;
         int BLOCK[400];
         int arr[sz]:
```

```
int getId(int indx, int blockSZ) {
     9.
              return indx / blockSZ;
     10.
         void init(int sz) {
     11.
             for (int i = 0; i <= sz; i++) BLOCK[i] = inf;</pre>
     12.
     13. }
     14. void update(int val, int indx, int blockSZ) {
     15.
              int id = getId(indx, blockSZ);
     16.
             BLOCK[id] = min(BLOCK[id], val);
     17.
     18. int query(int L, int R, int blockSZ) {
              int lid = getId(L, blockSZ);
     20.
             int rid = getId(R, blockSZ);
             if (lid == rid) {
     21
             int ret = inf;
     23.
                 for (int i = L; i <= R; i++) ret = min(ret, arr[i]);</pre>
     24
                 return ret:
     26.
             int m1 = inf, m2 = inf, m3 = inf;
             for (int i = L: i < (lid + 1) * blockSZ: i++) m1 = min(m1)
          , arr[i]):
             for (int i = lid + 1; i < rid; i++) m2 = min(m2, BLOCK[i]</pre>
     29
             for (int i = rid * blockSZ; i \le R; i++) m3 = min(m3. arr
         [i]);
     30
          return MIN3 (m1, m2, m3);
     31.
     32. int main() {
     33.
             int N. Q;
             scanf ("%d %d", & N, & Q);
     35
             int blockSZ = sqrt(N);
     36
             init(blockSZ);
     37
             for (int i = 0; i < N; i++) {
     38.
             int x;
     39
                 scanf("%d", & x);
     40
                arr[i] = x;
     41.
                 update(x. i. blockSZ);
     43.
              while (Q--) {
     44
             int x, y;
     45
                 scanf ("%d %d", & x, & y);
     46.
                 printf("%dYn", query(x, y, blockSZ));
     47
     48. }
     49 //
     50. //getId ফাংশনের কাজ হল কোন index কত নাম্বার block এ তা বে
         র করে দেয়া।
     51 //init ফাংশন সবংগলা block কে infinity ভ্যাল নিয়ে initialize
          করে নিচ্ছে
     52. //update ফাংশন দিয়ে কোন একটা নির্দিষ্ট index এর ভ্যালু আপডেট
          করে দেয়া হচ্ছে।
     53. //query ফাংশন দিয়ে x to y রেঞ্জের result calculation করা হচ্ছ
     54. //Line 25 এ যদি রেঞ্জ পুরোটা কোন একটা নির্দিষ্ট block এর sub p
          art হয়ে থাকে, তাহলে main Array থেকে result calculation করে
         দিবে।
     55. //Line 32, যদি রেঞ্জ এর Iower bound এর কিছু অংশ নির্দিষ্ট একটা
          block এর sub part হয়ে থাকে তাহলে শুধু সেইটুক sub part এর re
          sult main Array থেকে calculate করে দিবে।
     56. //Line 34, যদি রেঞ্জ এর upper bound এর কিছু অংশ নির্দিষ্ট একটা
          block এর sub part হয়ে থাকে তাহলে শুধু সেইটুক sub part এর re
          sult main Array থেকে নিবে।
PREFIX TRIE:
         #define mx 26
         struct node {
             bool endmark:
     3
             node * next[mx + 1];
             node() {
            endmark = 0;
                 for (int i = 0; i < mx; i++)
     7
     8.
                 next[i] = NULL;
```

```
10. } * root;
         void insert(char * str, int len) {
          node * curr = root;
     12.
     13.
              for (int i = 0; i < len; i++) {</pre>
             int id = str[i] - 'a';
     14.
                 if (curr - > next[id] == NULL)
     15.
                 curr - > next[id] = new node();
     16.
     17.
                  curr = curr - > next[id];
     18.
     19.
              curr - > endmark = 1:
     20.
         }
     21.
         bool search (char * str, int len) {
     22.
         node * curr = root;
              for (int i = 0; i < len; i++) {</pre>
     23
     24.
              int id = str[i] - 'a';
                  if (curr - > next[id] == NULL) return false;
                 curr = curr - > next[id];
     26
     27
     28.
             return curr - > endmark; /// returns 1 or 0
     29.
         }
          void del(node * cur) /// send root here
     30.
     31
                 for (int i = 0; i < mx; i++)
     32
     33.
                     if (cur - > next[i])
                        del(cur - > next[i]);
     34
     35
                  delete(cur):
     36
     37.
         int main() {
         root = new node();
     38.
              int num_word;
     39.
            cin >> num_word;
     41.
              for (int i = 1; i <= num_word; i++) {</pre>
     42
              char str[50];
     43.
                  scanf("%s", str);
                 insert(str, strlen(str));
     44.
     45.
           int query;
     46
     47.
              cin >> query;
              for (int i = 1; i <= query; i++) {</pre>
     49
                 char str[50];
                 scanf("%s", str);
     50
     51.
                  if (search(str, strlen(str))) puts("FOUND");
     52.
                  else puts("NOT FOUND");
     53
     54
             del(root);
     55 }
STRING ALGORITHMS:
          void computeLPSArray(char * pat, int M, int * lps);
         void KMPSearch(char * pat, char * txt) {
     3.
              int M = strlen(pat);
              int N = strlen(txt);
     4
              int * lps = (int * ) malloc(sizeof(int) * M);
     5.
     6.
              int j = 0;
              computeLPSArray(pat, M, lps);
              int i = 0; // index for txt[]
     8.
              while (i < N) {
     9.
              if (pat[j] == txt[i]) {
     11.
                      j++;
     12
                     j++;
     13.
                  }
     14.
                 if (j = M) {
     15
                      printf("Found pattern at index %d n", i - j);
     16
                     j = lps[j - 1];
     17.
                  } else if (pat[j] != txt[i]) {
                     if (j != 0)
     18.
     19
                         j = lps[j - 1];
     20
                      else
     21
                          i = i + 1;
     22.
     23
     24
              free(lps);
     25. }
```

```
26. void computeLPSArray(char * pat, int M, int * lps) {
     27.
              int len = 0:
     28.
              int i:
     29.
              lps[0] = 0;
     30.
              i = 1:
     31.
              // the loop calculates lps[i] for i = 1 to M-1
     32.
              while (i < M) {
     33.
                  if (pat[i] == pat[len]) {
     34
                  len++:
     35.
                      lps[i] = len:
     36.
                     j++;
     37.
                  } else // (pat[i] != pat[len])
     38.
                      if (len != 0) {
     39
                         // This is tricky. Consider the example AAACA
          AAA and i = 7.
     41
                          len = lps[len - 1];
     42
                     } else {
                          lps[i] = 0;
     44
                          j++;
     45
     46
     47
     48. }
     49. int main() {
     50. char * txt = "ABABDABACDABABCABAB";
     51
              char * pat = "ABABCABAB";
    52.
              KMPSearch(pat, txt);
    53. }
Z ALGORITHM:
         const int NX = 1e5 + 10; // string size
    char text[NX];
        int Z[NX];
     4. void Z_Algorithm() {
                  int position, starting_point, ending_point;
                 int sz = strlen(text);
     6
                  Z[0] = sz; // always;
                 for (position = 1, starting_point = 0, ending_point =
          0; position < sz; position++) {
                    if (position <= ending_point) Z[position] = min(e</pre>
     9
          nding_point - position + 1, Z[position - starting_point]);
     10.
                    while (position + Z[position] < sz && text[Z[posi</pre>
          tion]] == text[position + Z[position]]) ++Z[position];
     11
                     if (position + Z[position] - 1 > ending_point) //
          need to update
                          starting_point = position, ending_point = pos
          ition + Z[position] - 1;
     13.
     15.
              /*****prefix==suffix*********/
     16. for (i = sz - 1; i \ge 0; i--) {
              if (Z[i] == sz - i) // suffix matches
     17.
     18. }
     19.
          /******************/
     20. bool zAlgorithm(string pattern, string target) {
     21
              string s = pattern + '$' + target;
     22.
             int n = s. length();
     23
              vector \langle int \rangle z(n, 0);
     24.
     25.
              int goal = pattern.length();
              int r = 0, l = 0, i;
     26.
     27.
              for (int k = 1; k < n; k++) {
     28.
                  if (k > r) {
                     for (i = k; i < n \&\& s[i] == s[i - k]; i++);
     29.
                      if (i > k) {
     30.
     31.
                         z[k] = i - k;
                         | = k;
     32
     33.
                          r = i - 1:
     34.
     35.
                  } else {
    36.
                 int kt = k - 1, b = r - k + 1;
```

```
37.
                      if (z[kt] > b) {
                          for (i = r + 1; i < n \&\& s[i] == s[i - k]; i+
     38.
          +);
     39
                          z[k] = i - k;
     40
                          I = k;
     41.
                          r = i - 1:
     42.
     43
     44
                  if (z[k] == goal)
     45.
                      return true:
     46.
     47.
              return false:
     48
AHO-CORASICK:
          #define MX 100 //small string length
         int m, n, res;
     3.
          typedef pair < int, int > Point:
     4
         struct NODF {
     5.
              int cnt:
              hool vis:
     6
              NODE * next[27];
     7
     8
             vector < NODE * > out;
              NODE () {
     9
            for (int i = 0; i < 27; i++) {
     10
                     next[i] = NULL;
     11
     12.
     13.
                  out.clear();
                vis = false:
     14
                 cnt = 0;
     15.
             } ~NODE () {
     16.
     17.
                  for (int i = 1; i < 27; i++)
                  if (next[i] != NULL && next[i] != this)
     18
     19.
                          delete next[i];
         }
     20.
     21.
         } * root;
         void buildtrie(char dictionary[][MX], int n) // processing th
          e dictionarytionary
     23.
     24.
              root = new NODE();
     25
              /*usual trie part*/
     26.
              for (int i = 0; i < n; i++) {
     27.
                  NODE * p = root;
                 for (int j = 0; dictionary[i][j]; j++) {
     28
                      char c = dictionary[i][j] - 'a' + 1;
     29
     30
                      if (!p - > next[c])
     31.
                          p - > next[c] = new NODE();
                      p = p - > next[c];
     32
     33
                  }
     34
     35
              /* Pushing the nodes adjacent to root into queue */
              queue < NODE * > a;
     36.
              for (int i = 0; i < 27; i++) {
     37.
     38.
                 if (!root - > next[i])
     39
                      root - > next[i] = root;
     40
                  else
     41.
                     q. push(root - > next[i]);
                     root - > next[i] - > next[0] = root; // -
     42.
          >next[0] = back Pointer
     43
         }
     44.
     45.
            /* Building Aho-Corasick tree */
     46
              while (!q. empty()) {
                NODE * u = q. front(); //parent node
     47
     48.
                  g. pop();
     49.
                  for (int i = 1; i < 27; i++) {
                  if (u - > next[i]) {
     50.
                          NODE * v = u -  next[i]; // child node
     51
                          NODE * w = u -  next[0]; // back pointer of
     52.
     53
                          while (!w - > next[i]) // Until the char(i+'a
          '-1) child is found
     54.
                            w = w -  next[0]; // go up and up to bac
          k pointer.
```

```
v - > next[0] = w = w - > next[i]; // back po
          inter of v will be found child above.
     56.
                         w - > out.push back(v); // out will be used i
          n dfs step.
     57.
                          // here w is the new found match node.
     58.
                         a. push (v): // Push v into queue.
     59.
     60.
     61.
     62.
          void aho_corasick(NODE * p, char * word) // Third step, proce
          ssing the text.
     64
          {
              for (int i = 0; word[i]; i++) {
     65
                  char c = word[i] - 'a' + 1;
     67.
                  while (!p - > next[c])
     68
                     p = p - > next[0];
     69
                  p = p - > next[c];
     70.
                  p - > cnt++;
     71.
     72 }
     73. int dfs(NODE * p) // DFS for counting.
     74. {
     75.
             if (p - > vis) return p - > cnt;
              for (int i = 0; i  out.size(); i++)
     76
     77.
              p - > cnt += dfs(p - > out[i]);
     78
              p - > vis = true;
     79.
              return p - > cnt;
     80 }
     81. char query[1000100];
          char dictionary[MX][MX];
     83. int main() {
     84
              int t, tc, y, z;
     85.
              int i, j, k, l, h;
     86.
              char ch;
              scanf("%d", & tc);
     87
     88
              for (t = 1; t <= tc; t++) {
     89
              int n:
                  scanf("%d", & n);
     90.
     91
                  scanf("%s", query);
     92
                  for (int i = 0; i < n; ++i) {
     93
                     scanf("%s", dictionary[i]);
     94
     95
                  buildtrie(dictionary, n);
     96
                  aho corasick (root query):
     97
                  printf("Case %d:\frac{\frac{1}{2}}{2}n", t);
     ٩R
                  for (int i = 0; i < n; i++) {
     gg
                     NODE * p = root;
     100.
                      for (int i = 0; dictionary[i][i]; i++) {
     101
                         char c = dictionary[i][j] - 'a' + 1;
     102
                          p = p - > next[c];
     103
                     printf("%d\f", dfs(p));
     104
     106.
                  delete root;
     107
     108. }
SUFFIX ARRAY:
         #define MAX_N 100010 // second approach: 0(n log n)
     2. char T[MAX_N]; // the input string, up to 100K characters
          int n; // the length of input string
     4. int RA[MAX_N], tempRA[MAX_N]; // rank array and temporary ran
          k array
          int SA[MAX_N], tempSA[MAX_N]; // suffix array and temporary s
     6. int c[MAX_N]; // for counting/radix sort
          char P[MAX_N]; // the pattern string (for string matching)
     8. int m; // the length of pattern string
          int Phi[MAX_N]; // for computing longest common prefix
     10. int PLCP[MAX_N];
     11. int LCP[MAX_N]; // LCP[i] stores the LCP between previous suf
          fix T+SA[i-1]
        // and current suffix T+SA[i]
```

```
13. bool cmp(int a, int b) {
14.
    return strcmp(T + a, T + b) < 0;
15.
        } // compare
    void constructSA_slow() { // cannot go beyond 1000 characters
17.
        for (int i = 0; i < n; i++) SA[i] = i; // initial SA: \{0, ..., -1\}
     1, 2, \ldots, n-1
        sort(SA, SA + n, cmp); // sort: O(n log n) * compare: O(n
18.
    ) = 0(n^2 \log n)
19.
20. void countingSort(int k) { // O(n)
21.
        int i, sum, \max i = \max(300, n); // up to 255 ASCII chars
     or length of n
    memset(c, 0, sizeof c); // clear frequency table
22
23.
        for (i = 0; i < n; i++) // count the frequency of each in
           c[i + k < n ? RA[i + k] : 0]++;
24
25
         for (i = sum = 0; i < maxi; i++) {
26.
        int t = c[i];
            c[i] = sum;
27.
28.
            sum += t:
29
30
    for (i = 0; i < n; i++) // shuffle the suffix array if ne
            tempSA[c[SA[i] + k < n ? RA[SA[i] + k] : 0]++] = SA[i
31.
    1:
32
        for (i = 0; i < n; i++) // update the suffix array SA
33.
            SA[i] = tempSA[i];
34
   }
    void constructSA() { // this version can go up to 100000 char
35.
36.
    int i, k, r;
        for (i = 0; i < n; i++) RA[i] = T[i]; // initial rankings
37.
38.
        for (i = 0; i < n; i++) SA[i] = i; // initial SA: {0, 1,}
    2, ..., n-1}
       for (k = 1; k < n; k <<= 1) { // repeat sorting process |
39
     og n times
40.
           countingSort(k); // actually radix sort: sort based o
     n the second item
41
           countingSort(0); // then (stable) sort based on the f
     irst item
42.
           tempRA[SA[0]] = r = 0; // re-
     ranking; start from rank r = 0
           for (i = 1; i < n; i++) // compare adjacent suffixes
43
               tempRA[SA[i]] = // if same pair => same rank r; o
44.
     therwise, increase r
                (RA[SA[i]] == RA[SA[i-1]] \&\& RA[SA[i]+k] == R
45
     A[SA[i - 1] + k])? r : ++r;
46.
     for (i = 0; i < n; i++) // update the rank array RA
47
                RA[i] = tempRA[i];
48.
            if (RA[SA[n-1]] == n-1) break; // nice optimizati
    on trick
49.
        }
50
    }
51.
    void computeLCP_slow() {
52.
     LCP[0] = 0; // default value
53.
        for (int i = 1; i < n; i++) { // compute LCP by definitio
54
            int L = 0; // always reset L to 0
           while (T[SA[i] + L] == T[SA[i - 1] + L]) L++; // same
    L-th char, L++
    LCP[i] = L;
56
57.
    }
58.
59
    void computeLCP() {
60
    int i I:
61
        Phi[SA[0]] = -1; // default value
        for (i = 1; i < n; i++) // compute Phi in O(n)
62.
63
           Phi[SA[i]] = SA[i - 1]; // remember which suffix is b
     ehind this suffix
```

```
64.
      for (i = L = 0; i < n; i++) { // compute Permuted LCP in}
     0 (n)
65.
             if (Phi[i] == -1) {
66.
                PLCP[i] = 0;
67.
                 continue:
68.
             } // special case
             while (T[i + L] == T[Phi[i] + L]) L++; // L increased
70.
            PLCP[i] = L;
             L = max(L - 1, 0); // L decreased max n times
71.
72.
73.
         for (i = 0; i < n; i++) // compute LCP in O(n)
74
            LCP[i] = PLCP[SA[i]]; // put the permuted LCP to the
     correct position
75.
     }
   pii stringMatching() { // string matching in 0(m log n)
            int lo = 0, hi = n - 1, mid = lo; // valid matching =
     Γ0. . n-1]
78.
     while (lo < hi) { // find lower bound
79
                mid = (lo + hi) / 2; // this is round down
                int res = strncmp(T + SA[mid], P, m); // try to f
80
     ind P in suffix 'mid'
81
                 if (res >= 0) hi = mid; // prune upper half (noti
     ce the >= sign)
22
                else lo = mid + 1; // prune lower half including
     mid
             } // observe `=' in "res >= 0" above
83
84.
            if (strncmp(T + SA[Io], P, m) != 0) return pii(-1, -
     1); // if not found
85
             pii ans;
             ans.first = lo;
87
             lo = 0;
88
            hi = n - 1;
89
             mid = lo;
90.
             while (Io < hi) \{ // if lower bound is found, find up
     per bound
91
                mid = (lo + hi) / 2;
92
                int res = strncmp(T + SA[mid], P, m);
93.
                 if (res > 0) hi = mid; // prune upper half
94
                else lo = mid + 1; // prune lower half including
     mid
             } // (notice the selected branch when res == 0)
95
96.
            if (strncmp(T + SA[hi], P, m) != 0) hi--
     ; // special case
97
             ans second = hi:
98
            return ans;
99
        } // return lower/upperbound as first/second item of the
     pair, respectively
100. pii LRS() { // returns a pair (the LRS length and its index)
101
         int i, idx = 0, maxLCP = -1;
         for (i = 1; i < n; i++) // 0(n), start from i = 1
102
             if (LCP[i] > maxLCP)
103
                maxLCP = LCP[i], idx = i;
105.
         return pii(maxLCP, idx);
106. }
107. int owner (int idx) {
108.
      return (idx < n - m - 1) ? 1 : 2;
109. }
110. pii LCS() { // returns a pair (the LCS length and its index)
         int i, idx = 0, maxLCP = -1;
112.
         for (i = 1; i < n; i++) // 0(n), start from i = 1
113
             if (owner(SA[i]) != owner(SA[i - 1]) && LCP[i] > maxL
114.
              maxLCP = LCP[i], idx = i;
115.
         return pii(maxLCP, idx);
116. }
117. int main() {
        //printf("Enter a string T below, we will compute its Suf
  fix Array:¥n");
         strcpy(T, "GATAGACA");
119
120. n = (int) strlen(T);
```

```
T[n++] = ' ;
         121.
          122. // if '\f' is read, uncomment the next line
          123.
                          //T[n-1] = '$'; T[n] = 0;
                        constructSA_slow(); // O(n^2 log n)
          124.
                          printf("The Suffix Array of string T = '%s' is shown belo
         125
                   w (0(n^2 \log n) \text{ version}): \text{$\forall n'', T$};
         126. printf("i\text{i}\text{tSA[i]\text{i}\text{suffix\text{in"}}};
                          for (int i = 0; i < n; i++) printf("%2d\tag{2}t\tag{2}d\tag{4}t\tag{8}s\tag{4}n", i, S
                  A[i], T + SA[i]);
          128. constructSA(); // 0(n log n)
                          printf("\forall nThe Suffix Array of string T = '%s' is shown be
                   low (0 (n log n) version) : \forall n'', T);
                  printf("i\tSA[i]\tSuffix\text{\text{yn"}};
         130.
                          for (int i = 0; i < n; i++) printf("%2d\tag{2}t\%2d\tag{4}t\%s\tag{n}", i, S
         131.
                  A[i], T + SA[i]);
          132. computeLCP(); // 0(n)
         133
                           // LRS demo
         134
                          pii ans = LRS(); // find the LRS of the first input strin
                 g
          135
                           char Irsans[MAX_N];
                   strncpy(Irsans, T + SA[ans.second], ans.first);
         136
                          printf("\forall nThe LRS is '\%s' with length = \%d\forall n\forall n", Irsans,
                  ans first):
         138. // stringMatching demo
                          //printf("\footnote\n\now, enter a string P below, we will try to f
                   ind P in T:\u00e4n");
          140. strcpy(P, "A");
          141.
                          m = (int) strlen(P);
                  // if '\f' is read, uncomment the next line
         142
                          //P[m-1] = 0; m--;
         143
         144.
                      pii pos = stringMatching();
         145
                           if (pos.first !=-1 && pos. second !=-1) {
                                 printf("%s is found SA[%d..%d] of %s\u00e4n", P, pos.first
         146
                  , pos. second, T);
                                  printf("They are:\footsymbol\text{yn"});
          147.
                                  for (int i = pos. first; i <= pos. second; i++)</pre>
          148.
                                         printf(" %s\forall n", T + SA[i]);
         149
         150. } else printf("%s is not found in %s\u00e4n", P, T);
          151.
          152. // LCS demo
                          //printf("\footnote n = '\%s'\footnote n = '\%s'\footnote n = '\note n = '\no
         153
                  P:\f', T);
          154.
                   // T already has '$' at the back
                          strcpy(P, "CATA");
         155
                   m = (int) strlen(P);
         156
          157
                          // if '\f' is read, uncomment the next line
         158
                       //P[m-1] = 0; m--;
          159
                          strcat(T, P); // append P
          160.
                          strcat(T, "#"); // add '$' at the back
          161
                          n = (int) strlen(T): // update n
         162
                           // reconstruct SA of the combined strings
         163
                      constructSA(); // O(n log n)
         164.
                          computeLCP(); // 0(n)
         166.
                          printf("\formation of 'T+P' = '\s':\formation, T);
                           printf("i\tankletsA[i]\tankletsLCP[i]\tankletsOwner\tankletsUffix\tankletn");
         167
          168
                          for (int i = 0; i < n; i++)
                                 printf("%2d\t%2d\t%2d\t%2d\t%s\text{\n"}, i, SA[i], LCP[i],
                   owner(SA[i]), T + SA[i]);
         170
                        ans = LCS(); // find the longest common substring between
                 T and P
          171.
                          char lcsans[MAX_N];
         172
                          strncpy(Icsans, T + SA[ans.second], ans.first);
         173
                          printf("\frac{\text{"YnThe LCS}}{\text{ is '\text{"s'}}} \text{with length} = \text{\text{MdYn"}}, \text{ Icsans, an}
                  s. first);
         174.
                        return 0;
         175.
GEOMETRY:
Misc Geometric Formula:
        Triangle
                                        Circum Radius = a*b*c/(4*area)
                                         In Radius = area/s, where s = (a+b+c)/2
                                         length of median to side c = sqrt(2*(a*a+b*b) -
```

c*c)/2

length of bisector of angle C =

trifiasco | 22 sqrt(ab[(a+b)*(a+b)-c*c])/(a+b)Ellipse Area = PI*a*b Circumference = 4a *int(0, PI/2) {sqrt(1-(k*sint)*(k*sint))}dt = 2*PI*sqrt((a*a+b*b)/2) approx where k = sqrt((a*a-b*b)/a)= PI*(3*(r1+r2)sqrt[(r1+3*r2)*(3*r1+r2)])Spherical cap V = (1/3)*PI*h*h*(3*r-h)Surface Area = 2*PI*r*h V = (2/3) *PI *r *r *hSpherical Sector Spherical V = (1/6) *PI *h * (3*a*a+3*b*b+h*h)Segment V = 2*PI*PI*R*r*rTorus Truncated V = (1/3) *PI *h * (a*a+a*b+b*b)Surface Area = PI*(a+b)*sqrt(h*h+(b-a)*(b-a))Conic = PI*(a+b)*IPyramidal (1/3)*h*(A1+A2+sqrt(A1*A2))frustum Misc Trigonometric Functions and Formulas: tan A/2= + sqrt((1-cos A)/(1+cos A))= sin A / (1+cos A) = (1-cos A) / sin A = cosec A - cot A $\sin 3A = 3*\sin A - 4*sincube A$ cos 3A = 4*coscube A - 3*cos Atan 3A = (3*tan A-tancube A)/(1-3*tansq A)sin 4A = 4*sin A*cos A - 8*sincube A*cos A $\cos 4A = 8*\cos^4 A - 8*\cos^4 A + 1$ $[r*(cost+i*sint)]^p = r^p*(cos pt+i*sin pt)$ $\mathbf{a}\cos\mathbf{x} + \mathbf{b}\sin\mathbf{x} = \mathbf{c}$, $\mathbf{x} = 2n\pi + \alpha \pm \beta$, where $\cos \alpha = a / (\operatorname{sqrt}(a^2+b^2)), \cos \beta = c / (\operatorname{sqrt}(a^2+b^2));$ $2\sin A\cos B = \sin (A+B) + \sin (A-B)$ $2\cos A \sin B = \sin (A+B) - \sin (A-B)$ $2\cos A\cos B = \cos (A-B) + \cos (A+B)$ 2sinAsinB = cos(A-B) - cos(A+B)sinC + sinD = 2sin[(C+D)/2]cos[(C-D)/2]sinC - sinD = 2cos[(C+D)/2]sin[(C-D)/2]cosD + cosC = 2cos[(C+D)/2]cos[(C-D)/2]cosD - cosC = 2sin[(C+D)/2]sin[(C-D)/2]Misc Integration Formula: $a^x \Rightarrow a^x/\ln(a)$

 $1/sqrt(x*x+a*a) \Rightarrow In(x+sqrt(x*x+a*a))$ $1/sqrt(x*x-a*a) \Rightarrow ln(x+sqrt(x*x-a*a))$ 1/(x*sqrt(x*x+a*a) = -(1/a)*ln([a+sqrt(x*x+a*a)]/x) $\frac{1}{(x*sqrt(a*a-x*x))} \Rightarrow -(\frac{1}{a})*ln([a+sqrt(a*a-x*x)]/x)$

Misc Differentiation Formula:

acos x => -1/sqrt(1-x*x)asin $x \Rightarrow 1/sqrt(1-x*x)$ atan x => 1/(1+x*x)acot x => -1/(1+x*x)asec $x \Rightarrow 1/[x*sqrt(x*x-1)]$ acosec $x \Rightarrow -1/[x*sqrt(x*x-1)]$ $a^x \Rightarrow a^x + \ln(x)$ $\cot x \Rightarrow$ $sec x \Rightarrow sec x * tan x$ cosec x => -cosec x

* cot x Mirror point(mx, my) of a point(x, y) w.r.to a line(ax+by+c=0):

void mirrorPoint(double a, double b, double c, double x, doub le y, double & mx, double & my) { mx = x * (a * a - b * b) - 2.0 * a * b * y - 2.0 * a * c;mx /= (a * a + b * b);my = y * (a * a - b * b) - 2.0 * a * b * x - 2.0 * b * c;4. my /= (a * a + b * b);

Determining if a point lies on the interior of a 3D convex polygon:

- 1. // To determine whether a point is on the interior of a conve x polygon in 3D, one
- // might be tempted to first determine whether the point is o n the plane, then
- // determine its interior status. Both of these can be accomp lished at once by
- // computing the sum of the angles between the test point (q below) and every pair of

```
// edge points p[i]-
                                                                                                                          39. } //two numbers are equal
                                                                                                                   Distance (Point, Point):
              >p[i+1]. This sum will only be twopi if both the point is on
                                                                                                                                   inline double Distance(point a, point b) {
              \ensuremath{//} plane of the polygon AND on the interior. The angle sum wi
                                                                                                                                        return sqrt((a. x - b. x) * (a. x - b. x) + (a. y - b. y) * (a. x - b. x) + (a. y - b. y) * (a. y - b. y) 
              II tend to 0 the further
                                                                                                                                  y - b. y));
                                                                                                                          3. }
            // away from the polygon point q becomes. The following code
                                                                                                                   Distance ^ 2 (Point, Point):
              snippet returns the angle
                                                                                                                                  inline double sq_Distance(point a, point b) {
       8. // sum between the test point q and all the vertex pairs. The
                                                                                                                                     return (a. x - b. x) * (a. x - b. x) + (a. y - b. y) * (a. y - b
              angle sum is in radians.
                                                                                                                                  . y);
              #define EPSILON 0.0000001
       10. #define MODULUS(p) (sqrt(p. x * p. x + p. y * p. y + p. z * p. z))
                                                                                                                          3
                                                                                                                   Distance (Point, Line):
              const double TWOPI = 6.283185307179586476925287,

    inline double Distance(point P, line L) {

       12.
                    RTOD = 57.2957795:
                                                                                                                           2
                                                                                                                                        return fabs (L. a * P. x + L. b * P. y + L. c) / sqrt (L. a * L. a
       13. double CalcAngleSum(point3D q, point3D * p, int n) {
                                                                                                                                  + | h * | h):
       14.
             double m1, m2, anglesum = 0, costheta;
                                                                                                                           3
                     point3D p1, p2;
                                                                                                                   Distance (Point, Segment):
              for (int i = 0; i < n; i++) {</pre>
       16
                                                                                                                                inline double Distance(point P segment S) {
       17
                           p1.x = p[i].x - q.x;
                                                                                                                           2. line L1 = line(S.A, S.B), L2;
        18.
                         p1. y = p[i]. y - q. y;
                                                                                                                                        point P1;
                           p1.z = p[i].z - q.z;
       19.

 L2 = findPerpendicularLine(L1, P);

                          p2. x = p[(i + 1) \% n]. x - q. x;
       20.
                                                                                                                                        if (intersection(L1, L2, P1))
       21
                           p2. y = p[(i + 1) \% n]. y - q. y;
                                                                                                                                              if (eq(Distance(S. A, P1) + Distance(S. B, P1), Distanc
       22
                           p2. z = p[(i + 1) \% n]. z - q. z;
                                                                                                                                  e(S.A, S.B)))
                           m1 = MODULUS(p1), m2 = MODULUS(p2);
       23.
                                                                                                                                                    return Distance(P, L1);
                          \textbf{if} \hspace{0.1cm} (\texttt{m1} * \texttt{m2} \mathrel{<=} \texttt{EPSILON}) \hspace{0.1cm} \textbf{return} \hspace{0.1cm} (\texttt{TWOPI}) \hspace{0.1cm} ; \hspace{0.1cm} // \hspace{0.1cm} \texttt{We} \hspace{0.1cm} \texttt{are} \hspace{0.1cm} \texttt{on}
       24
                                                                                                                                        return min(Distance(S. A, P), Distance(S. B, P));
                                                                                                                           8.
              a node, consider this inside
       25
                          else costheta = (p1. x * p2. x + p1. y * p2. y + p1. z * p
                                                                                                                    IS Left Function:
              2. z) / (m1 * m2);
                                                                                                                           1.
                                                                                                                                 inline double isleft(point p0, point p1, point p2) {
       26.
                       anglesum += acos(costheta);
                                                                                                                                        return ((p1. x - p0. x) * (p2. y - p0. y) - (p2. x - p0. x) * (
       27
                                                                                                                                  p1. y - p0. y));
       28.
              return (anglesum);
                                                                                                                          3
                                                                                                                                }
       29. }
                                                                                                                    Intersection (Line, Line):
MISC GEOMETRY:
                                                                                                                           1. inline bool intersection(line L1, line L2, point & p) {
              const double eps = 1e-11, pi = 2 * acos(0.0);
                                                                                                                               double det = L1. a * L2. b - L1. b * L2. a;
       2.
              struct point { // Creates normal 2D point
                                                                                                                                         if (eq(det, 0)) return false;
                    double x. v.
       3
                                                                                                                                        p. x = (L1.b * L2.c - L2.b * L1.c) / det;
       4
                point() {}
                                                                                                                                        p. y = (L1. c * L2. a - L2. c * L1. a) / det;
                     point(double xx, double yy) {
                                                                                                                           6
                                                                                                                                       return true:
       6.
                           x = xx, y = yy;
                                                                                                                          7
                                                                                                                    Intersection (Segment, Segment):
             };
       8.
                                                                                                                           1. inline bool intersection(segment L1, segment L2, point & p) {
              struct point3D { // Creates normal 3D point
       10.
                    double x, y, z;
                                                                                                                                if (!intersection(line(L1. A, L1. B), line(L2. A, L2. B), p))
       11 }:
                                                                                                                                  {
       12. struct line \{ // \text{ Creates a line with equation ax + by + c = 0 } \}
                                                                                                                           3.
                                                                                                                                              return false; // can lie on another, just check their
       13.
                     double a. b. c;
                                                                                                                                   equations, and check overlap
       14
                 line() {}
       15
                     line(point p1, point p2) {
                                                                                                                                        return (eq(Distance(L1. A, p) + Distance(L1. B, p), Distanc
       16
                    a = p1.y - p2.y;
                                                                                                                                   e(L1. A. L1. B)) &&
       17
                          b = p2. x - p1. x;
                                                                                                                           6.
                                                                                                                                              eq(Distance(L2.A, p) + Distance(L2.B, p), Distance(L2
                  c = p1.x * p2.y - p2.x * p1.y;
       18.
                                                                                                                                  .A, L2.B)));
       19.
                                                                                                                          7.
       20. };
                                                                                                                   Perpendicular Line of a Given Line Through a Point:
       21. struct circle { // Creates a circle with point 'center' as ce

    inline line findPerpendicularLine(line L, point P) {

              nter and r as radius
                                                                                                                           2.
                                                                                                                                       line res; //line perpendicular to L, and intersects with
       22.
              point center;
       23.
                     double r
                                                                                                                                        res. a = L. b, res. b = -L. a;
              circle() {}
       24.
                                                                                                                           4.
                                                                                                                                        res. c = -res. a * P. x - res. b * P. y;
                     circle(point P, double rr) {
       25
                                                                                                                           5
                                                                                                                                        return res:
       26
                  center = P;
                                                                                                                          6.
       27.
                           r = rr;
                                                                                                                   Area of a 2 D Polygon:
       28.
                                                                                                                                  double areaPolygon(point P[], int n) {
       29. };
                                                                                                                                double area = 0;
             struct segment { // Creates a segment with two end points -
       30
                                                                                                                                        for (int i = 0, j = n - 1; i < n; j = i++) area += P[j].x
              > A. B
                                                                                                                                   * P[i].y - P[j].y * P[i].x;
       31.
                     point A, B;
                                                                                                                           4.
                                                                                                                                     return fabs(area) / 2;
       32
                   segment() {}
                     segment(point P1, point P2) {
       33
                                                                                                                   Point Inside Polygon:
       34.
                          A = P1. B = P2;

    bool insidePoly(point & p, point P[], int n) {

       35
                     }
                                                                                                                           bool inside = false;
       36 }:
                                                                                                                                        for (int i = 0, j = n - 1; i < n; j = i++)
       37
              inline bool eq(double a, double b) {
                                                                                                                                if (((P[i].x < p.x) ^ (P[j].x < p.x)) &&</pre>
               return fabs(a - b) < eps;
       38.
```

```
(P[i].y - P[j].y) * abs(p.x - P[j].x) < (p.y - P[
                                                                                                                                                           (B. y - A. y) * (C. x * C. x + C. y * C. y - A. x * A. x - A.
                [].y) * abs(P[i].x - P[j].x))
                                                                                                                                                 v * A. y));
        6.
                                   inside = linside:
                                                                                                                                                       c. center. x /= den;
                       return inside;
                                                                                                                                                       c. center. y = ((B. x - A. x) * (C. x * C. x + C. y * C. y - A. x)
        8. }
                                                                                                                                                 * A. x - A. y * A. y) -
Intersection - Circle, Line:
                                                                                                                                        9.
        1. inline bool intersection(circle C, line L, point & p1, point
                                                                                                                                                 y * A. y));
                & p2) {

    c. center. y /= den;

        2.
               if (Distance(C. center, L) > C.r + eps) return false;
                                                                                                                                         11.
                       double a, b, c, d, x = C. center. x, y = C. center. y;
                                                                                                                                         12.
        3.
                                                                                                                                                       return c:
        4.
                       d = C.r * C.r - x * x - y * y;
                                                                                                                                         13. }
        5
                       if (eq(L. a, 0)) {
                        p1. y = p2. y = -L. c / L. b;
        6.
                              a = 1:
                                                                                                                                                       point Q;
        7
        8.
                             b = 2 * x;
        Q
                              c = p1.y * p1.y - 2 * p1.y * y - d;
                                                                                                                                        4
        10.
                            d = b * b - 4 * a * c;
                                                                                                                                        5.
                                                                                                                                                       return 0:
        11
                              d = sqrt(fabs(d));
                                                                                                                                        6
                                                                                                                                Convex Hull (Graham Scan) 0 (nlogn):
        12.
                              p1. x = (b + d) / (2 * a);
                             p2. x = (b - d) / (2 * a);
        13
                                                                                                                                        2 point Firstpoint:
        14
                       } else {
                                                                                                                                                 int cmp (const void * a,
        15
                              a = L. a * L. a + L. b * L. b;
                                                                                                                                        4. const void * b) {
                              b = 2 * (L.a * L.a * y - L.b * L.c - L.a * L.b * x);
        16.
                                                                                                                                                       double x. v;
                                                                                                                                        5.
                                                                                                                                        6.
                                                                                                                                                    point aa. bb;
        17
                              c = |c * | c + 2 * | a * | c * x - | a * | a * d
        18.
                              d = b * b - 4 * a * c;
        19.
                              d = sqrt(fabs(d));
                                                                                                                                        8
                              p1. y = (b + d) / (2 * a);
        20
                              p2. y = (b - d) / (2 * a);
        21.
                                                                                                                                         11.
                              p1. x = (-L. b * p1. y - L. c) / L. a;
                                                                                                                                         12
        23
                              p2. x = (-L. b * p2. y - L. c) / L. a;
                                                                                                                                         13
        24
                 }
                                                                                                                                         14.
        25.
                       return true:
        26. }
                                                                                                                                         15
                                                                                                                                                       return 1:
Find Points that are r1 unit away from A, and r2 unit away from B:
                                                                                                                                         16.
        1. inline bool findpointAr1Br2(point A, double r1, point B, doub
                le r2, point & p1, point & p2) {
             line L;
        2
                       circle C:
        3
        4.
                     L. a = 2 * (B. x - A. x);
                       L.b = 2 * (B.y - A.y);
        6.
                     L. c = A. x * A. x + A. y * A. y - B. x * B. x - B. y * B. y + r2
                                                                                                                                        21
               * r2 - r1 * r1:
                                                                                                                                        22
                       C. center = A;
                                                                                                                                                ]. x > P[pos]. x + eps))
                   C.r = r1;
                                                                                                                                        23
        8.
                                                                                                                                                                    pos = i;
        Q
                       return intersection (C. L. pl. p2);
                                                                                                                                        24
                                                                                                                                                       swap(P[pos], P[0]);
        10. }
                                                                                                                                        25.
                                                                                                                                                       Firstpoint = P[0]:
Intersection Area between Two Circles:
                                                                                                                                        26
               inline double intersectionArea2C(circle C1, circle C2) {
                                                                                                                                        27.
                                                                                                                                                       C[0] = P[0];
              C2. center. x = Distance(C1. center, C2. center);
                                                                                                                                        28
                                                                                                                                                       C[1] = P[1];
                       C1. center. x = C1. center. y = C2. center. y = 0;
                                                                                                                                                       i = 2, j = 1;
                                                                                                                                        29.
        4.
                    if (C1. r < C2. center. x - C2. r + eps) return 0;
                                                                                                                                                       while (i < nP) {
        5.
                       if (-
                                                                                                                                        31.
                C1.r + eps > C2.center.x - C2.r) return pi * C1.r * C1.r;
                                                                                                                                                 eps) C[++j] = P[i++];
        6.
                    if (C1.r + eps > C2.center.x + C2.r) return pi * C2.r * C
                                                                                                                                        32. else j--;
               2. r;
                                                                                                                                        33.
                       double c, CAD, CBD, res;
                                                                                                                                        34.
                                                                                                                                                       nC = j + 1;
        8. c = C2. center. x;
                                                                                                                                        35 }
                                                                                                                                Angle between Vectors:
        9.
                     CAD = 2 * acos((C1.r * C1.r + c * c - C2.r * C2.r) / (2 * 
                C1.r * c));
                                                                                                                                                  { // vector OA to OB
        10
                       CBD = 2 * acos((C2.r * C2.r + c * c - C1.r * C1.r) / (2 *
                C2.r * c));
                                                                                                                                        2.
                                                                                                                                                       point t1. t2:
         11.
                     res = C1.r * C1.r * (CAD - sin(CAD)) + C2.r * C2.r * (CBD)
                                                                                                                                                       t1. x = A. x - 0. x;
                  - sin(CBD));
                                                                                                                                                       t1. y = A. y - 0. y;
        12. return . 5 * res;
                                                                                                                                                       t2. x = B. x - 0. x;
        13.
                                                                                                                                                       t2. y = B. y - 0. y;
Circle Through Thee Points:
        1. circle CircleThrough3points(point A, point B, point C) {
               double den;
        2.
                                                                                                                                        9
                                                                                                                                                       return theta:
                                                                                                                                        10.
              den = 2.0 * ((B.x - A.x) * (C.y - A.y) - (B.y - A.y) * (C.y - A.y) + (
                                                                                                                                MISC:
        4.
                                                                                                                                FORMULA:
               (x - A(x));
                       c. center. x = ((C.y - A.y) * (B.x * B.x + B.y * B.y - A.x)
```

* A. x - A. y * A. y) -

```
(C. x - A. x) * (B. x * B. x + B. y * B. y - A. x * A. x - A.
              c.r = Distance(c.center, A);
Rotating a Point anticlockwise by 'theta' radian w.r.t Origin:
         inline point rotate2D(double theta, point P) {
              Q. x = P. x * cos(theta) - P. y * sin(theta);
              Q.y = P.x * sin(theta) + P.y * cos(theta);
     1 // compare Function for gsort in convex hull
              aa = * (point *) a;
             bb = * (point * ) b;
              x = isleft(Firstpoint, aa, bb);
          if (x > eps) return -1;
              else if (x < -eps) return 1;
             x = sq Distance(Firstpoint, aa);
              y = sq_Distance(Firstpoint, bb);
             if (x + eps < y) return -1;
     17. // 'P' contains all the points, 'C' contains the convex hull
     18. // 'nP' = total points of 'P', 'nC' = total points of 'C'
     19. void ConvexHull(point P[], point C[], int & nP, int & nC) {
              int i, j, pos = 0; // Remove duplicate points if necesary
              for (i = 1; i < nP; i++)
               if (P[i].y < P[pos].y || (eq(P[i].y, P[pos].y) && P[i</pre>
              gsort(P + 1, nP - 1, sizeof(point), cmp);
                 if (isleft(C[j - 1], C[j], P[i]) > -
         inline double angleBetweenVectors(point 0, point A, point B)
              double theta = (atan2(t2. y, t2. x) - atan2(t1. y, t1. x));
              if (theta < 0) theta += 2 * pi;
```

- 1. Cayley's Formula: There are n^{n-2} spanning trees of a complete graph with n labeled vertices. Example: UVa 10843 Anne's game.
- 2. Derangement: A permutation of the elements of a set such that none of the elements appear in their original position. The number of derangements der(n) can be computed as follow: $der(n) = (n-1) \times (der(n-1) + der(n-2))$ where der(0) = 1 and der(1) = 0. A basic problem involving derangement is UVa 12024 Hats (see Section 5.6).
- 3. Erdős Gallai's Theorem gives a necessary and sufficient condition for a finite sequence of natural numbers to be the degree sequence of a simple graph. A sequence of nonnegative integers $d_1 \geq d_2 \geq \ldots \geq d_n$ can be the degree sequence of a simple graph on n vertices iff $\sum_{i=1}^n d_i$ is even and $\sum_{i=1}^k d_i \leq k \times (k-1) + \sum_{i=k+1}^n \min(d_i,k)$ holds for $1 \leq k \leq n$. Example: UVa 10720 Graph Construction.
- 4. Euler's Formula for Planar Graph⁶: V-E+F=2, where F is the number of faces⁷ of the Planar Graph. Example: UVa 10178 Count the Faces.
- 5. Moser's Circle: Determine the number of pieces into which a circle is divided if n points on its circumference are joined by chords with no three internally concurrent. Solution: $g(n) = {}^{n}C_{4} + {}^{n}C_{2} + 1$. Example: UVa 10213 How Many Pieces of Land?
- 6. Pick's Theorem8: Let I be the number of integer points in the polygon, A be the area of the polygon, and b be the number of integer points on the boundary, then $A=i+\frac{b}{2}-1$. Example: UVa 10088 Trees on My Island.
- 7. The number of spanning tree of a complete bipartite graph $K_{n,m}$ is $m^{n-1} \times n^{m-1}$. Example: UVa 11719 - Gridlands Airport.

CATALAN NUMBER PROPERTIES:

1. Cat(n) counts the number of distinct binary trees with n vertices, e.g. for n=3:



- 2. Cat(n) counts the number of expressions containing n pairs of parentheses which are correctly matched, e.g. for n=3, we have: ()()(), ()(()), ((())), ((())), and (()()).
- 3. Cat(n) counts the number of different ways n+1 factors can be completely parenthesized, e.g. for n=3 and 3+1=4 factors: $\{a,b,c,d\}$, we have: (ab)(cd), a(b(cd)), a(bc)(d), and a((bc)d).
- 4. Cat(n) counts the number of ways a convex polygon (see Section 7.3) of n+2 sides can be triangulated. See Figure 5.1, left.
- 5. Cat(n) counts the number of monotonic paths along the edges of an $n \times n$ grid, which do not pass above the diagonal. A monotonic path is one which starts in the lower left corner, finishes in the upper right corner, and consists entirely of edges pointing rightwards or upwards. See Figure 5.1, right and also see Section 4.7.1.



Figure 5.1: Left: Triangulation of a Convex Polygon, Right: Monotonic Paths

Nth Permutation:

```
const int NX = 30:
     Long fact[NX], nth_value;
2.
     int freq[NX];
4.
     char inp[NX];
     void ini() {
5
6.
         fact[0] = 1;
7.
8.
         for (i = 1; i \le 25; i++) fact[i] = (fact[i - 1] * i);
9
    }
10
    Long occurence (int len) {
11.
         Long now = fact[len];
         int it
12
         for (i = 0; i < 26; i++) now /= fact[freq[i]];
13
14.
         return now;
15.
    }
16
     void solve(int sz) {
17.
         while (sz) {
18.
             Long upto = 0;
19
             bool found = 0;
             int i:
20.
             for (i = 0; i < 26 \&\& !found; i++) {
21.
22
                 if (freq[i] == 0) continue;
23
                 freq[i]--;
24
                 Long now = occurrence (sz - 1);
25.
                 if (now + upto >= nth value) {
26.
                      nth_value -= upto;
27.
                      found = 1;
                      printf("%c", i + 'a');
28
29.
                      sz--;
                   else {
30
31.
                      upto += now;
```

```
32
                            freq[i]++;
     33.
     34.
                        // printf("i :: %c sz :: %d now :: %lld upto :: %
           IId nth :: %IId \underset{\underset{\underset{\underset}{1}}} n", i+'a', sz, now, upto, nth_value);
     35
     36
     37.
                    if (!found) break;
     38.
     39
               puts ("");
     40.
          }
     41.
           int main() {
     42.
               int cs, t;
     43
               getI(t)
     44
               ini():
               for (cs = 1; cs <= t; cs++) {
     46
                   scanf("%s %IId", inp, & nth_value);
     47
                   ms(freq, 0);
     48.
                   int sz = strlen(inp);
                   // rep(i, sz) printf("integer :: %d \undermath{\text{Yn}}\", inp[i]-
     49
           'a');
                   rep(i, sz) freq[inp[i] - 'a']++;
     50.
     51
                   long need = occurence(sz):
     52
                   printf("Case %d: ", cs);
     53.
                    if (need < nth_value) puts("Impossible");</pre>
     54
                   else solve(sz):
     55.
     56.
BACKTRACKING (N QUEEN PROBLEM):
           int board[8][8];
     1.
           int soln[100][8];
     3
           int tot = 0;
     4
           bool isSafe(int row, int col) {
     5.
               int i. i.
               for (i = 0; i < 8; i++) {
     6.
     7.
                    if (board[row][i] && i != col)
     8
                        return false:
     9
     10.
               for (int i = 0; i < 8; i++) {
     11
                    if (i == row) continue;
      12
                   for (int j = 0; j < 8; j++) {
      13.
                        if (j == col) continue;
      14
                        if (abs(row - i) == abs(col - j) \&\& board[i][j])
     15
                             return false:
     16.
     17.
     18
               return true:
     19.
           }
     20.
           void solveNQUtil(int col) {
     21.
               if (col == 8) {
     22
                   for (int i = 0; i < 8; i++) {
     23.
                        for (int j = 0; j < 8; j++) {
     24
                            if (board[i][j])
     25
                                 soln[tot][i] = j;
     26
     27.
                   }
     28.
                   tot++;
     29
                    return
     30
     31.
               for (int i = 0; i < 8; i++) {
     32
                    if (isSafe(i, col)) {
     33
                        board[i][col] = 1;
     34
                        solveNQUtil(col + 1);
     35.
                        board[i][col] = 0;
     36.
     37
     38
STRTOK:
           int main ()
           {
     2
               char str[] ="- This, a sample string.";
     3.
               char * pch;
```

```
int joseph(int n, int k) {
    if (n == 1) return 0;
3.
        return ((joseph(n - 1, k) + k) % n);
4
```

SOME NOTES:

- Gray Code □ □□ □□□ □ change হয় তার পর 1000···. থাক
- Segment tree এর সময় 2 পাশরে tree এর marge check করত হয়।
- BIT সংক্রান্ত কছি হল TRIE কনাি দখেত হেব
- Central Bionomial Coefficient = (2n, n) = (n!) / ((n-k)! * (k!)) $N \rightarrow 3 = 20, 4 = 70, 5 = 252, 6 = 924, 7 = 3432$

mamun4122:

- 1. /* Given a number N, let d be a divisor of N. Then the number of pairs $\{a,N\}$, where $1 \le a \le N$ and $\gcd(a,N) = d$, is $\phi(N/d)$
- ** Approximate number of primes under $n=(n/\ln(n))$
- ** Approximate upper limit of number of divisor =2³/N
- ** Diphonite eqn gulai negative number niye hisab korte hbe

- ** Once we find a pair (x, y) using ext_gcd, we can generate i nfinite pairs of Bezout coefficients using the formula: (x+(k *b)/gcd(a, b), y-(k*a)/gcd(a, b))
- 6. ** Goldbach's Conjecture: For any integer n (n \geq 4) there ex ist two prime numbers p1 and p2 such that p1 + p2 = n.
- 7. ** For a given positive integer n (0 \le n \le 231) we need to fi nd the number of such m that $1 \le m \le n$, GCD(m, n) $\ne 1$ and GC $D(m, n) \neq m$
- 8. $n \phi(n) (a1 + 1) * (a2 + 1) * \cdots * (ak + 1) + 1 */$

dipta007:

- /*Area of a triangle :
- 2. Let K be the triangle's area and let a, b and c, be the lengt hs of its sides. By Heron's Formula, the area of the trian gle is K = sqrt(s * (s-a) * (s-b) * (s -c)).
- where S is the semiperimeter s = (a+b+c)/2.
- 4. ** length of median to side c = sqrt(2*(a*a+b*b)-c*c)/2
- 5 ** length of hisector of angle C = sort(ab[(a+b)*(a+b)c*c1)/(a+b)
- 6. ** Radius of a In
 - cicle: The radius of the incircle is r = (2*k)/P = sqrt((sa)*(s-b)*(s-
 - c)/s). Thus, the area K of a triangle may be found by multipl ying the inradius by the semiperimeter: K = rs.
- 7. ** Angle : For a regular convex ngon, each interior angle has a measure of: (n-2)*180/n degrees.
- 8. ** Apothem: The apothem of a regular polygon is a line segmen t from the center to the midpoint of one of its sides. Equival ently, it is the line drawn from the center of the polygon th at is perpendicular to one of its sides.
- ** Circumradius: The circumradius from the center of a regula r polygon to one of the vertices is related to the side lengt h s or to the apothem a by r = s/(2sin(PI/n)) = a/(cos(PI/n))
- 10. ** Area : The area A of a convex regular nsided polygon having Side s, circumradius r, apothem a, and p erimeter p is given by */

 $A = \frac{1}{2}nsa = \frac{1}{2}pa = \frac{1}{4}ns^2 \cot \frac{\pi}{n} = na^2 \tan \frac{\pi}{n} = \frac{1}{2}nr^2 \sin \frac{2\pi}{n}$

howcum:

- /* Hockeystick pattern: $(2c2 * 3c2 * \cdots * (n+1)c2) = (n+2)$ c(2+1)
- ** Equation for the angle of the hour hand: angle_hour= (½) * (60H + M)
- 3 ** Equation for the angle of the minute hand: angle minute =
- ** Equation for the angle of the both hand : angle = abs(angl e hour - angle minute) */

PALINDROMIC INDEX:

1. /* The position of a palindrome within the sequence can be de termined almost without calculation: If the palindrome has an even number of digits, prepend a 1 to the front half of the p alindrome's digits. If the number of digits is odd, prepend t he value of front digit + 1 to the digits from position 2 ... central digit. Examples: 98766789=a(19876), 515=a(61), 820602 8=a (9206), 9230329=a (10230). */

TERNARY SEARCH:

```
double ts() {
        double min = 0;
        int c = 100; //for higher precision have to increase
         double k, l, f, g;
        while (c--) {
            f = min + (max - min) / (double) 3.0;
            g = min + (double) 2.0 * ((max - min) / (double) 3.0)
            k = fun(f);
10.
            I = fun(g);
            if (k < 1) {
11.
                max = g;
```

```
13. } else {
14. min = f;
15. }
16. }
17. return (min + max) / 2.0;
18. }
```

TEMPLATE:

```
#pragma comment(linker, "/stack:640000000")
2
    #include <algorithm>
3
4. #include <bitset>
    #include <cassert>
6. #include <cctype>
   #include <climits>
8. #include <cmath>
Q
   #include <cstdio>
10. #include <cstdlib>
11
   #include <cstring>
12. #include <fstream>
13 #include <iostream>
14. #include <iomanip>
15. #include <iterator>
16. #include <list>
17. #include <map>
18. #include <numeric>
    #include <queue>
20. #include <set>
21. #include <sstream>
22. #include <stack>
23. #include <string>
24. #include <utility>
25
   #include <vector>
26. using namespace std;
27.
28.
    const double EPS = 1e-9;
    const int INF = 0x7f7f7f7f:
29
30. const double PI=acos (-1.0):
31.
32. \#define READ(f) freopen(f, "r", stdin)
              WRITF(f)
                              freopen(f, "w", stdout)
33
   #define
34. #define
              MP(x, y)
                              make_pair(x, y)
35.
    #define
              PB(x)
                               push back(x)
36.
   #define
             rep(i,n)
                              for (int i = 1 ; i \le (n) ; i++)
                               for (int i = 0; i < (n); i++)
    #define
37
              repl(i.n)
38. #define FOR(i, L, R) for (int i = L; i \le R; i++)
   #define
              R0F (i. L. R)
                              for (int i = L: i >= R: i--)
40. #define FOREACH(i,t) for (typeof(t.begin()) i=t.begin
    (); i!=t. end(); i++)
41.
    #define
              ALL (p)
                              p. begin (), p. end ()
42.
   #define
              ALLR(p) p. rbegin(), p. rend()
43.
   #define
              SET (p)
                              memset(p, -1, sizeof(p))
44. #define CLR(p) memset(p, 0, sizeof(p))
45. #define
              MEM(p, v)
                              memset(p, v, sizeof(p))
46. #define getI(a) scanf("%d", &a)
47. #define
              getII(a,b)
                              scanf("%d%d", &a, &b)
48. #define getIII(a, b, c) scanf("%d%d%d", &a, &b, &c)
49.
    #define
              getL(a)
                              scanf("%||d",&a)
              getLL(a,b) scanf("%||d%||d",&a,&b)
50. #define
                              scanf("%||d%||d%||d", &a, &b, &c)
51
   #define
              getLLL (a, b, c)
52. #define getC(n) scanf("%c", &n)
              getF(n)
53. #define
                              scanf("%If", &n)
54. #define getS(n) scanf("%s",n)
55
   #define
              bitCheck(a, k)
                              ((bool) (a&(1<<(k))))
   #define
              bitOff(a,k)
                             (a&(~(1<<(k))))
56.
57.
    #define
              bitOn(a,k)
                               (a | (1<<(k)))
              iseq(a,b)
58.
    #define
                              (fabs (a-b) <EPS)
              vi vector < int >
59
    #define
60. #define vii vector < vector < int > >
61. #define
              pii pair< int, int >
62. #define ff first
   #define
63
              SS
                   second
   #define || long long
64.
65.
    #define
              ull unsigned long long
66.
67. template < class T > inline T _abs(T n) { return ((n) < 0 ? -
    (n) : (n)); }
68. template< class T > inline T _max(T a, T b) { return (!((a)<(
    b))?(a):(b)); }
```

```
69. template< class T > inline T _min(T a, T b) { return (((a)<(b
     ))?(a):(b)); }
    template < class T > inline T _swap(T &a, T &b) { a=a^b;b=a^b;
71. template \langle class T \rangle inline T gcd(T a, T b) \{ return (b) == 0 \}
     ? (a) : gcd((b), ((a) % (b))); }
72. template < class T > inline T | cm(T a, T b)  { return ((a) / gc
    d((a), (b)) * (b)); }
73. template <typename T> string NumberToString ( T Number ) { os
    tringstream ss; ss << Number; return ss.str(); }</pre>
      #define debug(args...) {cerr<<"*: "; dbg,args; cerr<<end</pre>
76.
78. #define debug(args...) // Just strip off all debug token
79 #endif
80.
81.
     struct debugger {
82
    template<typename T> debugger& operator , (const T& v) {
83
            cerr<<v<<" ";
84.
           return *this;
85
86. } dbg;
87. ///************** template ends here **********
88. int t, n, m;
89.
90. int main() {
        ///check for 0 or -1 if input not specified
91
        #ifdef CSE13
93. //
              READ ("in. txt");
94. //
            WRITE("out. txt");
95.
        #endif // mamun
96. }
97. //
          clock_t begin, end;
98. // double time_spent;
99. //
          begin = clock();
100. //
101. //
          end = clock();
102. // time_spent = (double)(end - begin) / CLOCKS_PER_SEC;
103. // cerr<<"Time spent = "<<time_spent<<endl;
```