

- V1: 3.3v power supply
- V2: 5v power supply
- V3: 9v power supply
- RPI: raspberry pi
- P1: potentiometer
- K1: push button
- R1: $R220\Omega$
- R2: $R10K\Omega$
- R3: $R10K\Omega$
- S1: anemometer (windsensor)
- S2: LDR photoresistor
- S3: NTC thermoresistor
- M1: unipolair stepper motor
- IC1: PCF8574
- IC2: MCP3008
- IC3: ULN2003A
- LCD: LCD display