## Statistical Process Control (SPC)

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## Agenda

- > What is SPC?
- > Introduction to SPC Charts
- > Examples
- > Diagnostics

#### What is SPC?

- > To detect out of control process:
  - Significant change in mean
  - Significant change in variance
- > Examples:
  - Smartphone battery life
  - Particulate filtration efficiency
- > Quality control
  - Six Sigma standards





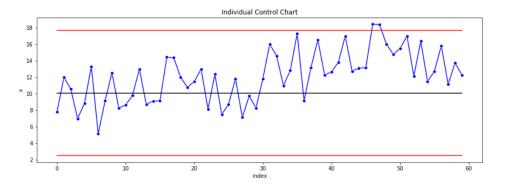
# Introduction to SPC Charts

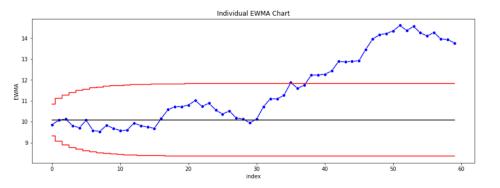
## Types of SPC Charts

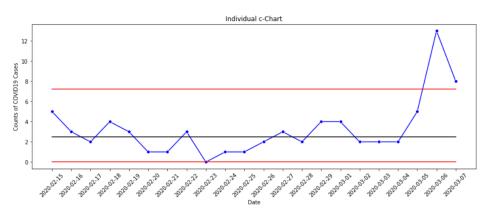
- > Variable
  - Continuous data
- > Time Weighted
  - Increased sensitivity to out of control process
- > Attribute
  - Counts data

#### **Assumptions**

- Independence
- Normally distributed







## Summary of SPC charts

#### Variable

- $\bar{x}$ , s
- $\bar{x}$ , R
- x, R
- S
- $s^2$
- R

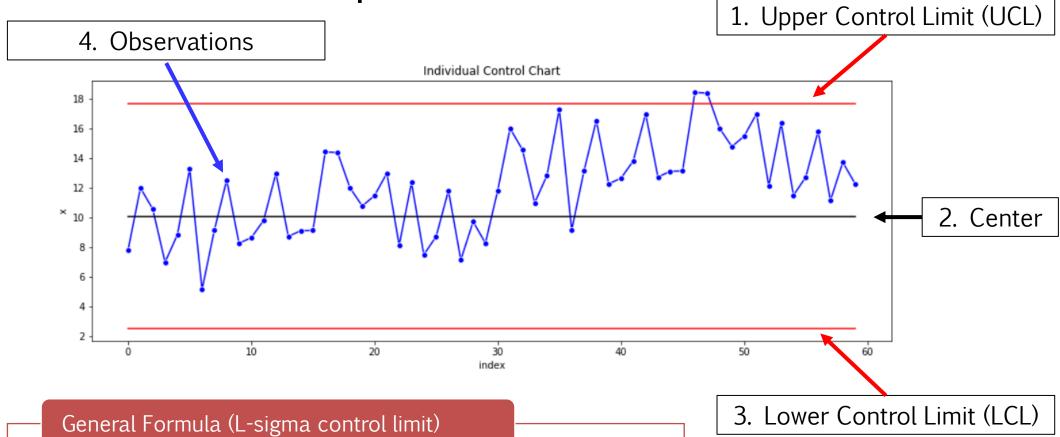
### Time Weighted

- EWMA
- TabularCusum

#### Attribute

- p-chart
- np-chart
- c-chart
- u-chart

## SPC Chart Components



- UCL =  $\mu_0 + L\hat{\sigma}$
- Center =  $\mu_0$
- LCL =  $\mu_0 L\hat{\sigma}$

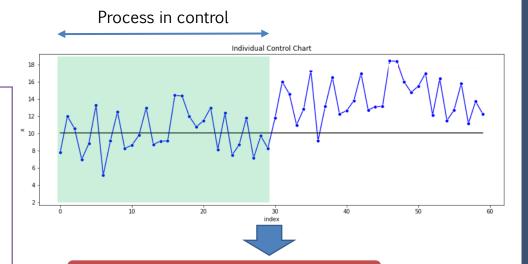
## Setting Up SPC Charts

#### Phase I

- Get process under control or select a period where process is under control
- · Estimate required parameters from in control data
- · Construct SPC chart

#### Phase II

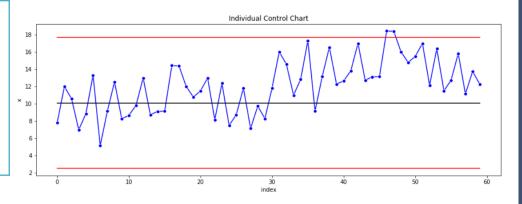
- Use SPC chart to monitor process
- Determine assignable cause when process signals out of control



#### General Formula (L-sigma control limit)

- UCL =  $\mu_0 + L\hat{\sigma}$
- Center =  $\mu_0$
- LCL =  $\mu_0 L\hat{\sigma}$





# Variable Control Charts: *x*, *R* Chart

- Individual observation chart (x)
- > Parameter Estimation

$$\mu_0 = \bar{x}$$

• 
$$\hat{\sigma} = \overline{MR}/1.128$$

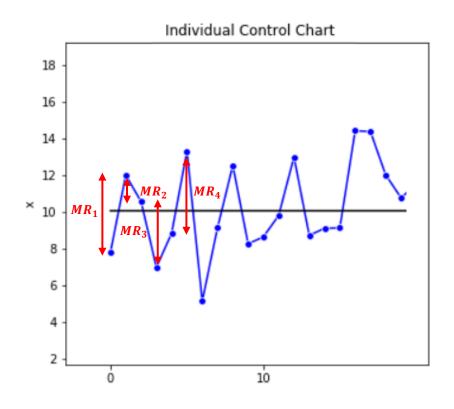
Moving Range:

$$\blacksquare MR_i = |x_{i+1} - x_i|$$

$$\blacksquare \overline{MR} = \frac{1}{m-1} \sum_{i=1}^{m-1} MR_i$$

#### Chart Parameters (L-sigma control limit)

- UCL =  $\mu_0 + L\hat{\sigma} = \mu_0 + L * \overline{MR}/1.128$
- Center =  $\mu_0$
- LCL =  $\mu_0 L\hat{\sigma} = \mu_0 L * \overline{MR}/1.128$



#### Note:

 $W=R/\sigma$  is the relative range statistic. When  $X{\sim}N(\mu,\sigma^2)$  and n=2, then  $E(R)=\sigma E(W)=1.128\sigma$ , So estimate  $\widehat{\sigma}$  by  $\overline{MR}/1.128$ 

## Time Weighted Control Charts - EWMA

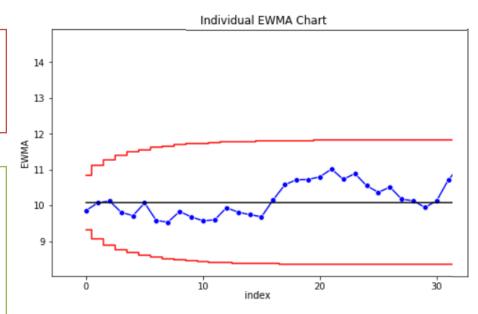
- > Exponentially Weighted Moving Average (EWMA)
  - Better detection of small changes in mean
- > Parameter Estimation
  - $\mu_0 = \bar{x}$
  - $\hat{\sigma} = \overline{MR}/1.128$

#### **EWMA Formula**

- $z_0 = \mu_0$
- $z_i = \lambda x_i + (1 \lambda)z_{i-1}$ ,  $0 < \lambda < 1$ , i = 1, 2, ...

#### Chart Parameters (L-sigma control limit)

- UCL<sub>i</sub> =  $\mu_0 + L * \sigma \sqrt{\frac{\lambda}{2-\lambda} [1 (1-\lambda)^{2i}]}$
- Center =  $\mu_0$
- LCL<sub>i</sub> =  $\mu_0 L * \sigma \sqrt{\frac{\lambda}{2-\lambda}} [1 (1-\lambda)^{2i}]$



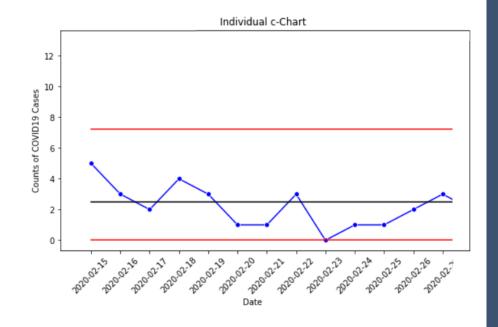
Note: Typically choose  $\lambda = 0.1$ 

### Attribute Control Charts - c-chart

- > Useful for counts data
- > Suppose  $Y \sim Poisson(\mu_0)$ , then  $E(Y) = \mu_0$  and  $Var(Y) = \mu_0$
- > Parameter Estimation

$$\mu_0 = \bar{x}$$

- Non-zero lower limit
  - If LCL < 0, set LCL = 0



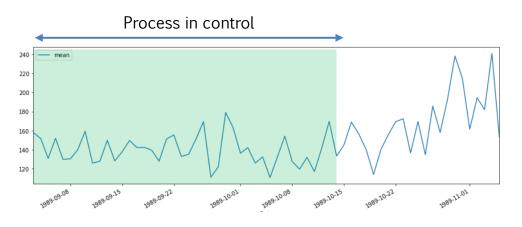
#### Chart Parameters (L-sigma control limit)

- UCL =  $\mu_0 + L\hat{\sigma} = \mu_0 + L * \sqrt{\mu_0}$
- Center =  $\mu_0$
- LCL =  $\mu_0 L\hat{\sigma} = \mu_0 L * \sqrt{\mu_0}$

## Examples

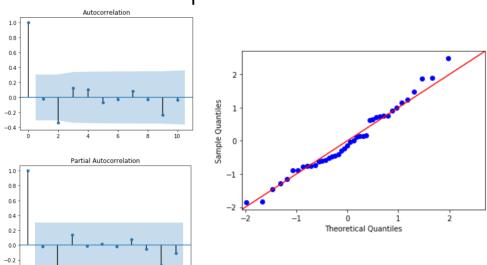
## Individual Blood Glucose Tracking (1/2)

#### 1. Select in-control data



- SPC Chart: Individual control chart
- Period selected: 1989-09-01 to 1989-10-14
- $\mu_0$  is set to  $\bar{x}$
- $\hat{\sigma}$  estimated by moving range

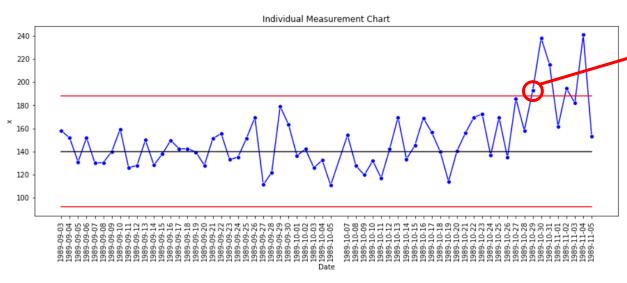
#### 2. Check Assumptions



- Ljung-Box Test: No significant autocorrelation up to lag 10
- Jarque-Bera Test: Distribution is not significantly different from Gaussian

## Individual Blood Glucose Tracking (2/2)

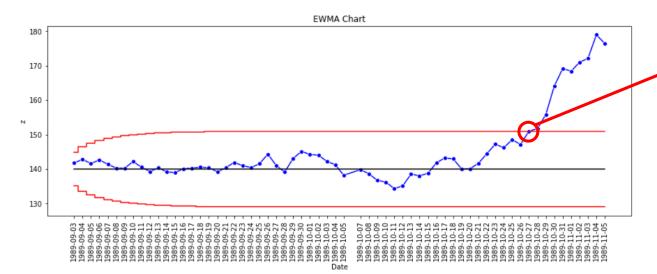
#### 3. Construct Individual Control chart



Process first signals out of control on 1989-10-29

EWMA detects out of control mean 2 days earlier!

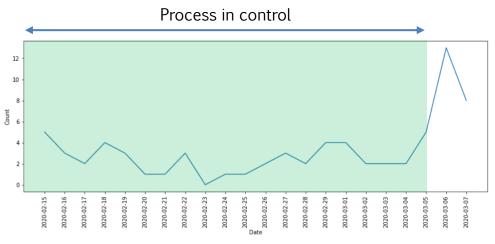
#### 4. Construct EWMA Chart



Process first signals out of control on 1989-10-27

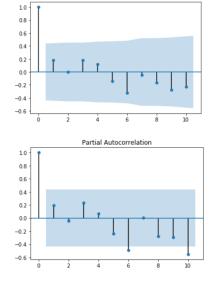
## Singapore COVID-19 Cases (1/2)

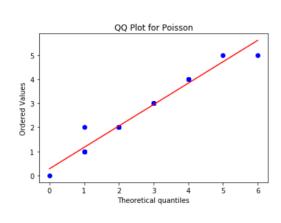
#### 1. Select in-control data



- SPC Chart: c-chart
- Period selected: 2020-02-15 to 2020-03-05
- $\mu_0$  is set to  $\bar{x}$
- $\hat{\sigma}$  is set as  $\sqrt{\bar{x}}$

#### 2. Check Assumptions

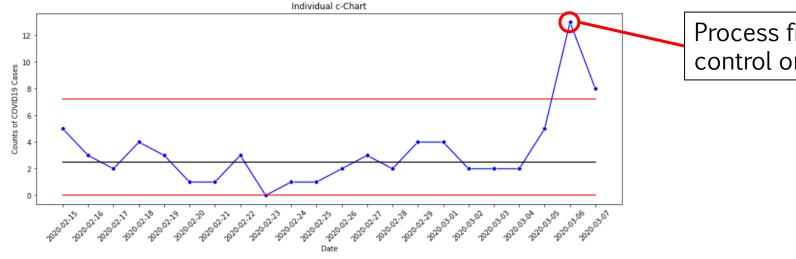




- Ljung-Box Test: No significant autocorrelation up to lag 10
- Chi-sq Goodness of fit Test:
   Distribution is not significantly different from Poisson

## Singapore COVID-19 Cases (2/2)

#### 3. Construct Individual Control chart



Process first signals out of control on 2020-03-06

## Diagnostics

### Violations of Assumptions

- > Violation of Normality
  - Skewed distributions
  - Heavy-tailed distributions
- > Violation of Independence
  - Autocorrelated process

#### **Properties of Normal Distribution**

- Skewness = 0
- Kurtosis = 3

## Skewed distributions (1/3)

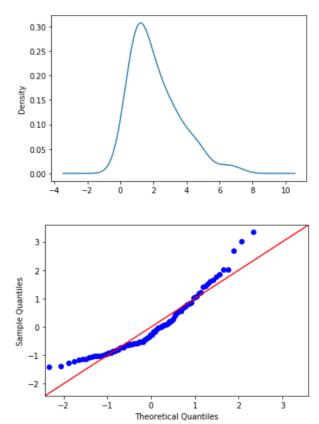
- > Results in false positives
- Can be transformed into approximately Gaussian using the Yeo-Johnson Transformation
- The Yeo-Johnson transformation is defined as:

$$x_i^{(\lambda)} = egin{cases} [(x_i+1)^{\lambda}-1]/\lambda & ext{if } \lambda 
eq 0, x_i \geq 0, \ \ln{(x_i+1)} & ext{if } \lambda = 0, x_i \geq 0 \ -[(-x_i+1)^{2-\lambda}-1]/(2-\lambda) & ext{if } \lambda 
eq 2, x_i < 0, \ -\ln{(-x_i+1)} & ext{if } \lambda = 2, x_i < 0 \end{cases}$$

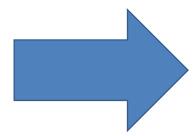
- > Build individual control chart based on transformed data
- > Reverse transform control limits and transformed data

# Skewed distributions (2/3) Gamma Distribution (Right Skewed)

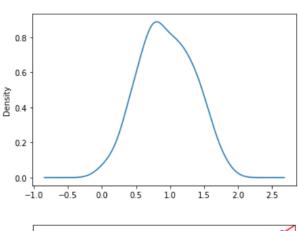
KDE and QQnorm for Gamma Distribution

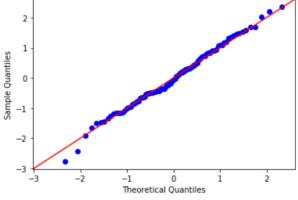


Yeo-Johnson Transformation

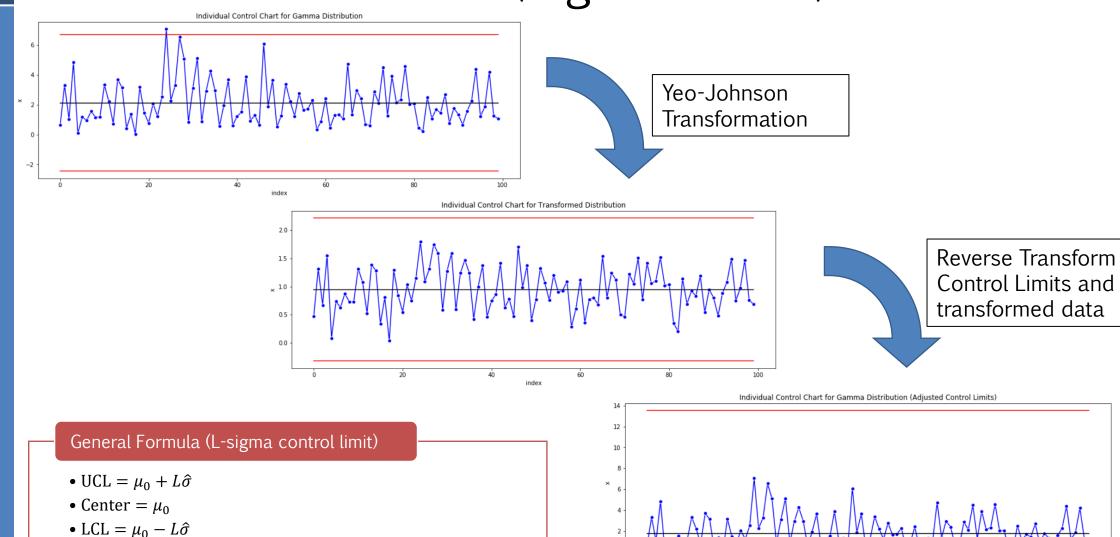


KDE and QQnorm for Transformed Distribution

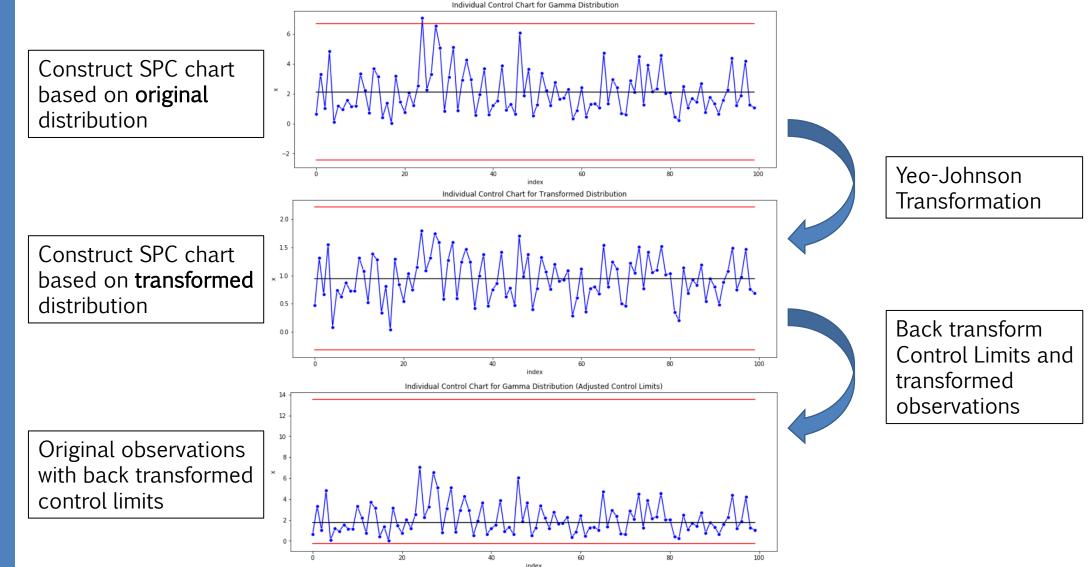




# Skewed distributions (3/3) Gamma Distribution (Right Skewed)

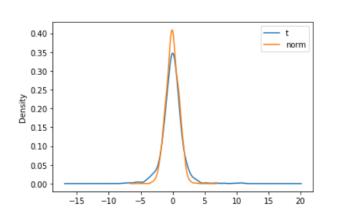


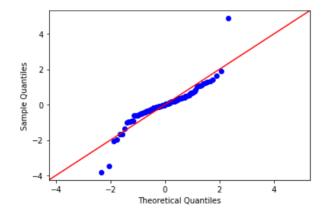
# Skewed distributions (3/3) Gamma Distribution (Right Skewed)



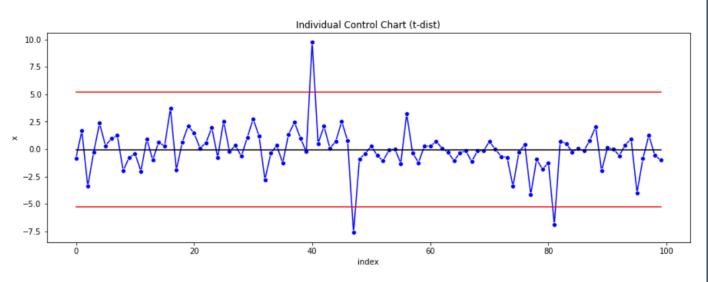
# Heavy-tailed distributions (1/2) Student's t-distribution







#### Individual Control Chart

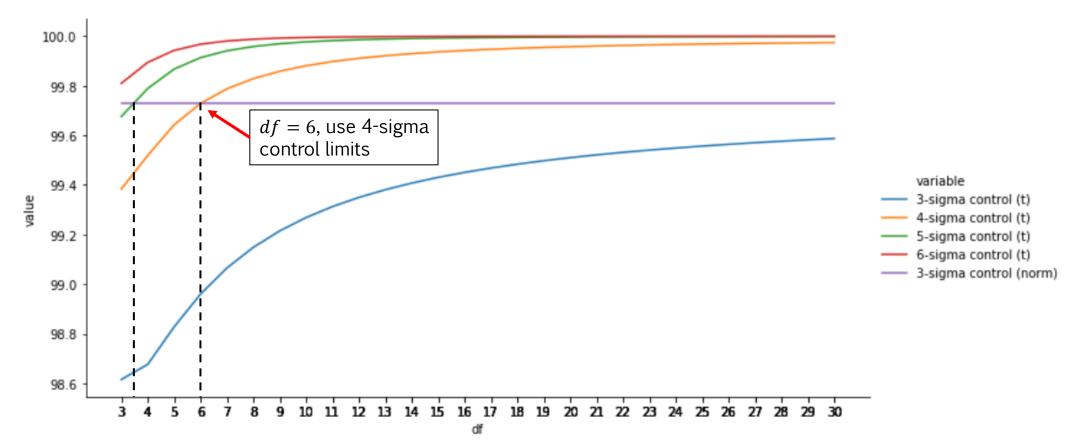


#### Remedies

- · Live with additional false positives
- · Increase control limit

### Heavy-tailed distributions (2/2) Student's t-distribution

L-sigma Coverage for t-dist and normal dist



# Autocorrelated Process (1/2) AR1 Simulation

- > Results in false positives
- > Fit an Auto-Regressive (AR) model to remove autocorrelation.
- > In general, fit an AR1 model:

$$X_t = \beta_0 + \beta_1 X_{t-1} + \epsilon_t, \quad \epsilon_t \sim N(0, \sigma^2)$$

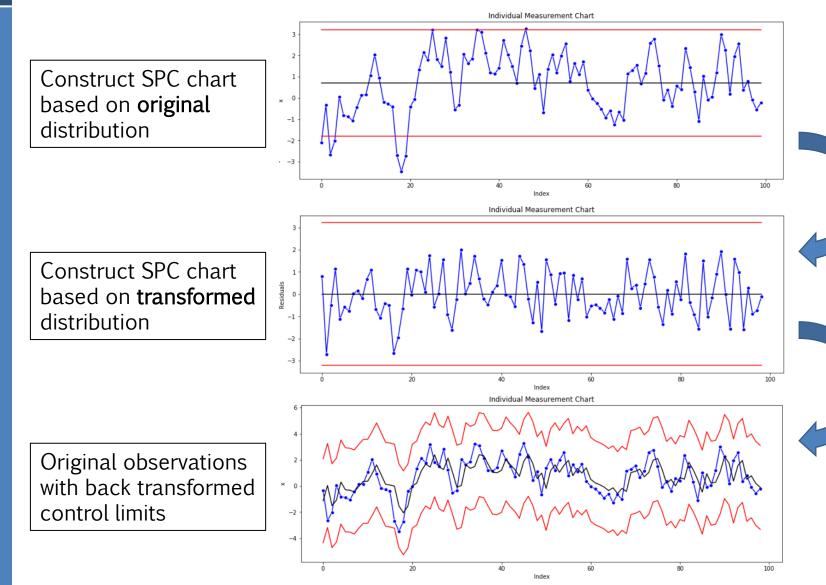
> Calculate residuals:

$$e_t = X_t - \hat{X}_t$$
, where  $\hat{X}_t = b_0 + b_1 X_{t-1}$ 

- > Build individual control chart based on residuals
- Reverse transform control limits and residuals by adding the predicted values to all the chart parameters

> E.g: 
$$e_t + \hat{X}_t = X_t - \hat{X}_t + \hat{X}_t = X_t$$

# Autocorrelated Process (2/2) AR1 Simulation



Fit AR1 model and calculate residuals

Back transform Control Limits and residuals

Thank You!

## Appendix