Command line arguments
  -h or --help: display this message
  -rand \<n\>: set random seed to 'n'
  -null: disable graphics

Commands to change modes
  g: desi(g)n mode
  v: evol(v)e mode
  h: c(h)amp mode

Commands to switch viewpoint
  y: side view
  o: t(o)p view
  b: (b)ack view

Commands in "Design" mode
  [: switch to previous active element
  ]: switch to next active element
  -: raise selection level (robot, object, or environment)
  +: lower selection level (robot, object, or environment)
  c: copy
  X: delete
  w: forward; W: forward fast
  a: left;   A: left fast
  s: backward; S: backward fast
  d: right;   D: right fast
  e: up;E: up fast
  z: down;   Z: down fast
  J: increase object 1st size dimension;   j: reduce
  K: increase object 2nd size dimension;   k: reduce
  L: increase object 3rd size dimension;   l: reduce
  P: rotate 30 degrees in x;   p: rotate 3 degrees in x
  Q: rotate 30 degrees in y;   q: rotate 3 degrees in y
  R: rotate 30 degrees in z;   r: rotate 3 degrees in z
  (: mark an object;   ): unmark
  @: connect active joint to marked objects
  >: increase joint range for joints;   <: reduce

Commands in "evolve" mode
  M: increase mutation probability; m: decrease
  T: increase evaluation period;   t: decrease

Other commands
  f: load environment from next saved file (design mode only)
  F: save environment to a file
  i: start or stop recording a mov(i)e