

```
tf.keras.layers.Lambda(lambda x: tf.abs(x))
```

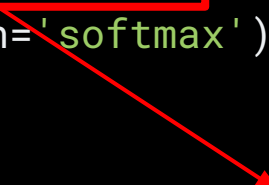
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model = tf.keras.models.Sequential([
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```
if(x>0):  
    return x  
else:  
    return 0
```

Epoch 1/5  
1875/1875 [=====] - 4s 2ms/step - loss: 0.2591 -  
accuracy: 0.9262

Epoch 2/5  
1875/1875 [=====] - 4s 2ms/step - loss: 0.1157 -  
accuracy: 0.9662

Epoch 3/5  
1875/1875 [=====] - 4s 2ms/step - loss: 0.0801 -  
accuracy: 0.9760

Epoch 4/5  
1875/1875 [=====] - 4s 2ms/step - loss: 0.0601 -  
accuracy: 0.9820

Epoch 5/5  
1875/1875 [=====] - 4s 2ms/step - loss: 0.0456 -  
accuracy: 0.9862

313/313 [=====] - 0s 1ms/step - loss: 0.0757 -  
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1875/1875 [=====] - 3s 2ms/step - loss: 0.3568 -

accuracy: 0.8984

Epoch 2/5

1875/1875 [=====] - 4s 2ms/step - loss: 0.2988 -

accuracy: 0.9170

Epoch 3/5

1875/1875 [=====] - 4s 2ms/step - loss: 0.2880 -

accuracy: 0.9192

Epoch 4/5

1875/1875 [=====] - 4s 2ms/step - loss: 0.2821 -

accuracy: 0.9205

Epoch 5/5

1875/1875 [=====] - 3s 2ms/step - loss: 0.2763 -

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313/313 [=====] - 0s 1ms/step - loss: 0.3031 -

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Epoch 1/5

1875/1875 [=====] - 4s 2ms/step - loss: 0.2229 -

accuracy: 0.9377

Epoch 2/5

1875/1875 [=====] - 3s 2ms/step - loss: 0.0908 -

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Epoch 3/5

1875/1875 [=====] - 3s 2ms/step - loss: 0.0636 -

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Epoch 4/5

1875/1875 [=====] - 4s 2ms/step - loss: 0.0471 -

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Epoch 5/5

1875/1875 [=====] - 4s 2ms/step - loss: 0.0396 -

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    return K.maximum(0.0, x)  
  
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# Some commonly used layers

## Convolutional

Conv1D/Conv2D/Conv3D

SeparableConv2D

DepthwiseConv2D

## Recurrent

LSTM

GRU

## Pooling

MaxPooling2D

AveragePooling2D

GlobalAveragePooling2D

## Merge

Add

Subtract

Multiply

## Activations (Advanced)

LeakyReLU

PReLU

ELU

## Core

Activation

Lambda

Input

Dense

Dropout

BatchNormalization

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## Core

Activation

Lambda

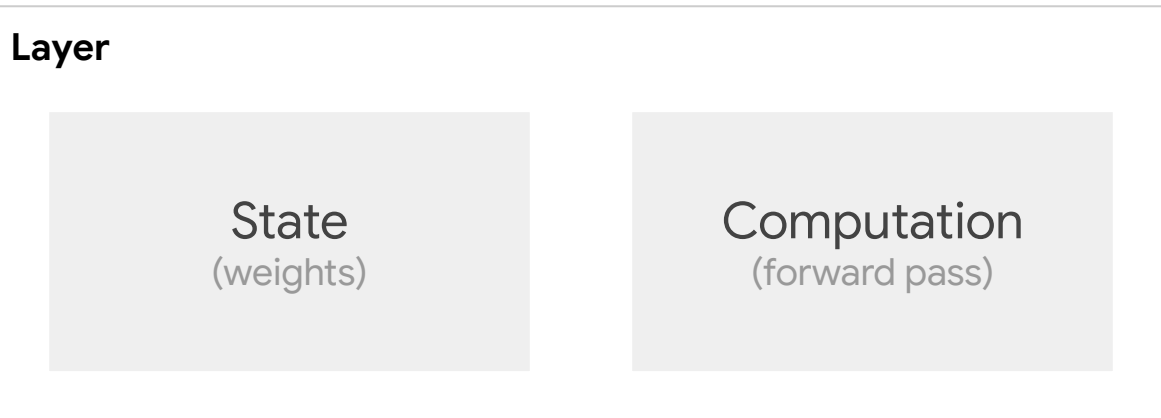
Input

Dense

Dropout

BatchNormalization

# What is a Layer?



# What is a Layer?

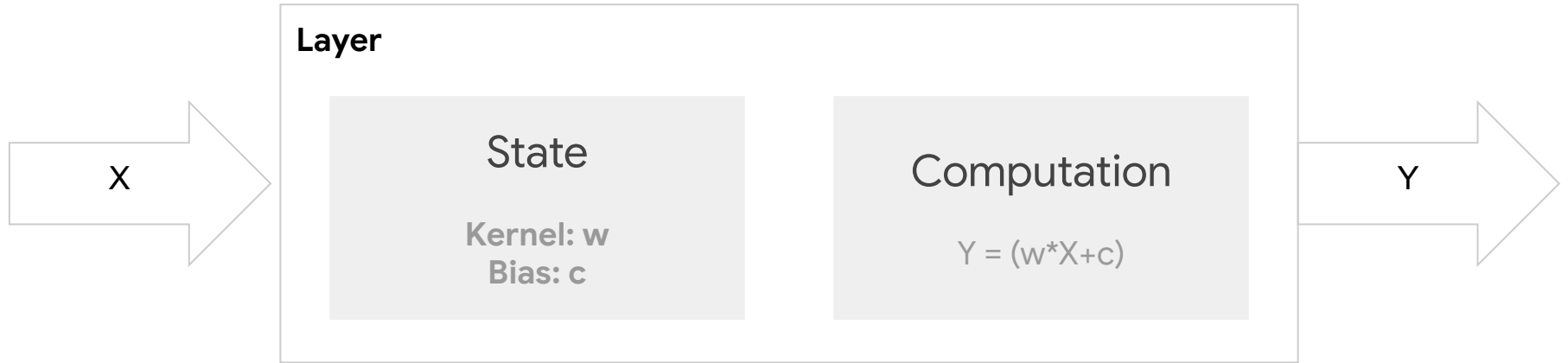


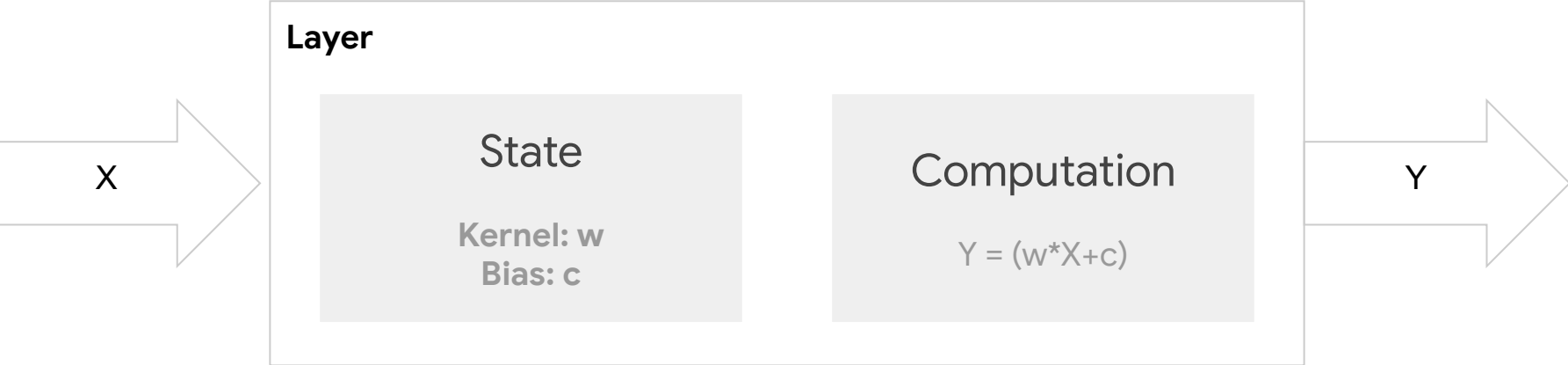


# What is a Layer?



# Simple Dense Layer





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class SimpleDense(Layer):

    def __init__(self, units=32):
        super(SimpleDense, self).__init__()
        self.units = units

    def build(self, input_shape): # Create the state of the layer (weights)
        w_init = tf.random_normal_initializer()
        self.w = tf.Variable(name="kernel",
                             initial_value=w_init(shape=(input_shape[-1], self.units), dtype='float32'),
                             trainable=True)

        b_init = tf.zeros_initializer()
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my_dense = SimpleDense(units=1)
x = tf.ones((1, 1))
y = my_dense(x)
print(my_dense.variables)
```

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[<tf.Variable 'simple_dense_7/kernel:0' shape=(1, 1)
dtype=float32, numpy=array([[0.03688493]], dtype=float32)>,
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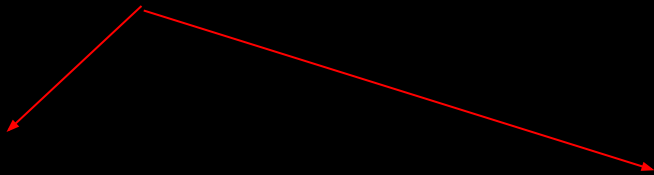
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import numpy as np

xs = np.array([-1.0, 0.0, 1.0, 2.0, 3.0, 4.0], dtype=float)
ys = np.array([-3.0, -1.0, 1.0, 3.0, 5.0, 7.0], dtype=float)

model = tf.keras.Sequential([SimpleDense(units=1)])
model.compile(optimizer='sgd', loss='mean_squared_error')
model.fit(xs, ys, epochs=500, verbose=0)
print(model.predict([10.0]))
```



Expected Answer: 19 ( $y=2x-1$ )

Actual Answer: 0.36

( $W = 0.036, B=0 \Rightarrow Y=0.036 * 10 + 0 = 0.36$ )

Epoch 1/500

1/1 [=====] - 0s 1ms/step - loss: 14.8152

Epoch 2/500

1/1 [=====] - 0s 3ms/step - loss: 11.8951

Epoch 3/500

1/1 [=====] - 0s 1ms/step - loss: 9.5928

Epoch 498/500

1/1 [=====] - 0s 2ms/step - loss: 4.1124e-05

Epoch 499/500

1/1 [=====] - 0s 2ms/step - loss: 4.0279e-05

Epoch 500/500

1/1 [=====] - 0s 1ms/step - loss: 3.9452e-05



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`[[ 18.981468 ]]`

```
[<tf.Variable  
'sequential_15/simple_dense_19/kernel:0' shape=(1, 1)  
dtype=float32, numpy=array([[1.9972587]],  
dtype=float32)>, <tf.Variable  
'sequential_15/simple_dense_19/bias:0' shape=(1,)   
dtype=float32, numpy=array([-0.991501],  
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class SimpleDense(Layer):

    def __init__(self, units=32):
        super(SimpleDense, self).__init__()
        self.units = units

    def build(self, input_shape): # Create the state of the layer (weights)
        w_init = tf.random_normal_initializer()
        self.w = tf.Variable(name="kernel",
                              initial_value=w_init(shape=(input_shape[-1], self.units), dtype='float32'),
                              trainable=True)

        b_init = tf.zeros_initializer()
        self.b = tf.Variable(name="bias",
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        self.activation = tf.keras.activations.get(activation)  
  
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