

STAT 330 - MATHEMATICAL STATISTICS

FANTASTIC THEOREMS AND HOW TO PROVE THEM

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# Chapter 1

## Random Variables

**Definition 1.1.** A **sample space**  $S$  is the set of all possible outcomes in an experiment. In an experiment one, and only one, outcome can occur (that is, they are mutually disjoint). An event  $A$  is a subset of the sample space  $A \subseteq S$ .

**Definition 1.2.** Let  $S$  be a sample space with power set  $\mathcal{P}(S)$ . The collection of sets  $\mathcal{B} \subseteq \mathcal{P}(S)$  is called a  $\sigma$ -field (or  $\sigma$ -algebra) on  $S$  if:

1.  $\emptyset \in \mathcal{B}$  and  $S \in \mathcal{B}$
2.  $\mathcal{B}$  is closed under complementation
3.  $\mathcal{B}$  is closed under countable unions

The pair  $(S, \mathcal{B})$  is called a **measurable space**.

**Definition 1.3.** Let  $S$  be a sample space with a sigma field  $\mathcal{B} = \{A_1, A_2, \dots\}$ . A **probability set function** or **probability measure** is a function  $P : \mathcal{B} \rightarrow [0, 1]$  that satisfies:

1.  $P(A) \geq 0, \forall A \in \mathcal{B}$
2.  $P(S) = 1$
3. If  $A_1, A_2, \dots \in \mathcal{B}$  are disjoint events, then

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i)$$

We call the triple  $(S, \mathcal{B}, P)$  a **probability space**.

**Definition 1.4.** Consider the probability space  $(S, \mathcal{B}, P)$ . The function  $X : S \rightarrow \mathbb{R}$  is called a **random variable** if

$$P(X \leq x) = P(\{\omega \in S : X(\omega) \leq x\})$$

is defined for all  $x \in \mathbb{R}$ .

**Definition 1.5.** The **cumulative distribution function** of a random variable  $X$  is defined as

$$F(x) = P(X \leq x)$$

for all  $x \in \mathbb{R}$ .

**Definition 1.6.**  $X$  is said to be a **discrete random variable** if its domain of values form a countable set  $D(X) = \{x_1, x_2, \dots\}$  and its probability function is defined as:

$$f(x) := P(X = x) = F(x) - \lim_{\epsilon \rightarrow 0^+} F(x - \epsilon)$$

The set  $A = \{x : f(x) > 0\}$  is called the **support** of  $X$  and

$$\sum_{x \in A} f(x) = \sum_{i=1}^{\infty} f(x_i) = 1$$

**Definition 1.7.** A random variable  $X$  is said to be **continuous** if its cumulative distribution function is a continuous function on  $\mathbb{R}$  and is differentiable everywhere except possibly at countably many points. The set  $\{x : f(x) > 0\}$  is called the **support** of  $X$  and

$$\int_{x \in A} f(x) dx = 1$$

If  $X$  is continuous then the probability density function is defined to be

$$f(x) = \frac{d}{dx} F(x)$$

**Definition 1.8.** The **gamma function** is defined as

$$\Gamma(s) = \int_0^\infty x^{s-1} e^{-x} dx$$

**Theorem 1.9.** If  $X$  and  $Y = h(X)$  are both discrete random variables, then the probability distribution of  $Y$  is given by

$$P(Y = y) = \sum_{\{x: h(x)=y\}} P(X = x)$$

**Theorem 1.10.** If  $X$  is continuous and  $Y$  is discrete with  $A = \{x : h(x) = y\}$ , then

$$P(Y = y) = \int_{x \in A} f(x) dx$$

**Theorem 1.11.** If  $X$  and  $Y = h(X)$  are both continuous, then

$$F_Y(y) = P(Y \leq y) = P(h(X) \leq y)$$

**Theorem 1.12.** Suppose  $h$  is a monotone differentiable function on the support of  $X$ , with continuous random variables  $X$  and  $Y = h(X)$ . Then,

$$f_Y(y) = f_X(h^{-1}(y)) \left| \frac{d}{dy} h^{-1}(y) \right|$$

**Definition 1.13.** If  $X$  is a discrete random variable with p.m.f.  $f(x)$  and support  $A$ , then the **expectation** or **expected value** of  $X$  is defined by:

$$E(X) = \sum_{x \in A} x f(x)$$

provided that the sum converges absolutely; that is,  $E(|X|) < \infty$ . Otherwise, we say that  $E(X)$  does not exist.

**Definition 1.14.** If  $X$  is a continuous random variable with p.d.f.  $f(x)$  and support  $A$ , then the **expectation** or **expected value** of  $X$  is defined by:

$$E(X) = \int_{x \in A} x f(x)$$

provided that the integral converges absolutely; that is,  $E(|X|) < \infty$ .

**Theorem 1.15. Probability Integral Transformation.** Suppose  $X$  is continuous random variable with c.d.f.  $F$ . Then  $Y = F(X) \sim \text{Unif}(0, 1)$ .

*Proof.* Since  $X$  is continuous, then  $F$  is a monotonically increasing continuous function, and is thus injective. It is thus surjective onto its range, and thus bijective and an inverse  $F^{-1}$  exists. Thus, we have,

$$P(Y \leq y) = P(F(X) \leq y) = P(X \leq F^{-1}(y)) = F(F^{-1}(y)) = y$$

Now, we may obtain the pmf by taking the derivative

$$\frac{d}{dy}(y) = 1$$

Since this holds over  $0 \leq y \leq 1$  it follows that  $Y$  follows a uniform distribution on the desired range. ■

**Theorem 1.16.** Suppose  $X$  is a nonnegative continuous random variable with c.d.f.  $F(x)$  and finite expectation. Then

$$E(X) = \int_0^{\infty} [1 - F(x)] dx$$

If  $X$  is a discrete random variable with finite expectation, where  $R(X) = \{1, 2, 3, \dots\}$ , then

$$E(X) = \sum_{i=1}^{\infty} P(X \geq i)$$

**Theorem 1.17.** Suppose that  $h(X)$  is a real-valued function.

1. If  $X$  is a discrete random variable with p.m.f.  $f(x)$  and support  $A$ , then

$$E(h(X)) = \sum_{x \in A} h(x)f(x)$$

provided that the sum converges absolutely.

2. If  $X$  is a continuous random variable with p.d.f.  $f(x)$ , then

$$E(h(X)) = \int_{-\infty}^{\infty} h(x)f(x)dx$$

provided that the integral converges absolutely.

*Proof.* This is the law of the unconscious statistician. It is left as an exercise for all statisticians who used it without proof. ■

**Theorem 1.18.** Expectation is linear.

*Proof.* Follows trivially from the fact that summation and integration are linear. ■

**Example 1.19.** Although expectation is linear, it usually does not commute as an operator with transformations. That is, in general  $E(g(X)) \neq g(E(X))$

**Definition 1.20.** The following are special cases of the expectation of transformations of  $X$ :

1. The **variance** of  $X$  is  $\text{Var}(X) = E[(X - \mu)^2] = E(X^2) - E(X)^2$ .
2. The  **$k$ -th moment** of  $X$  is  $E(X^k)$ .
3. The  **$k$ -th moment about the mean** is  $E[(X - \mu)^k]$ .
4. The  **$k$ -th factorial moment about the mean** is  $E[X(X - 1) \dots (X - k + 1)] = E(X^{(k)}) = E\left[\frac{X!}{(X-k)!}\right]$ .

**Theorem 1.21.** Suppose  $X$  is a random variable, then  $\text{Var}(aX + b) = a^2 \text{Var}(X)$ .

*Proof.* Follows from the definition of variance. ■

**Example 1.22.** If  $X \sim \text{Po}(\theta)$  then  $E(X^{(k)}) = \theta^k$ . The calculation is as follows:

$$\begin{aligned} E[X^{(k)}] &= \sum_k^{\infty} \frac{x!}{(x-k)!} \frac{e^{-\theta} \theta^x}{x!} \\ &= \theta^k \sum_k^{\infty} \frac{x!}{(x-k)!} \frac{e^{-\theta} \theta^{(x-k)}}{x!} \\ &= \theta^k \end{aligned}$$

**Theorem 1.23.** If  $X$  is a random variable and  $u(X)$  is a nonnegative real-valued function such that  $E[u(X)]$  exists, then for any positive constant  $c > 0$ ,

$$P[u(X) \geq c] \leq \frac{E[u(X)]}{c}$$

*Proof.* We argue as follows:

$$\begin{aligned} E[u(X)] &= \int_{x \in A} u(x)f(x)dx + \int_{x \notin A} u(x)f(x) \\ &\geq \int_{x \in A} u(x)f(x)dx \\ &\geq \int_{x \in A} cf(x)dx \\ &= c \int_{x \in A} f(x)dx \\ &= cP(X \in A) \\ &= cP(u(X) \geq c) \end{aligned}$$

Which completes the proof. ■

**Theorem 1.24. Markov's Inequality.** Suppose that  $X$  is a random variable and  $k > 0$  is a constant. Then

$$P(|X| \geq c) \leq \frac{E[|X|^k]}{c^k}$$

*Proof.* Follows from Theorem 1.23. ■

**Theorem 1.25. Chebyshev's Inequality.** Suppose  $X$  is a random variable with a finite mean  $\mu$  and finite variance  $\sigma^2$ . Then for any  $k > 0$ ,

$$P(|X - \mu| \geq k\sigma) \leq \frac{1}{k^2}$$

or, equivalently,

$$P(|X - \mu| \geq k) \leq \frac{\sigma^2}{k^2}$$

*Proof.* Follows from Markov's Inequality. ■

**Definition 1.26.** If  $X$  is a random variable then the moment generating function of  $X$  is given by

$$M_X(t) = E[e^{tX}]$$

provided that this expectation exists for all  $t \in (-h, h)$  for some  $h > 0$ .

**Example 1.27.** Let  $X \sim \Gamma(\alpha, \beta)$ . Then, after some algebraic mumbo-jumbo, we can find that  $M_X(t) = (1 - t\beta)^{-\alpha}$  for  $t < \beta^{-1}$ .

**Theorem 1.28.** Some properties of the moment generating function of  $X$ :

1.  $M_X(0) = 1$
2. If the m.g.f. exists, then the  $k$ -th moment is given by  $E[X^k] = M_X^{(k)}(0)$

*Proof strategy.* The first property is trivial. The second property can be proven by taking a Taylor expansion of  $e^{tX}$ , taking the  $k$ -th derivative of  $E[e^{tX}]$ , using the Lebesgue Dominated Convergence Theorem to commute the differentiation and summation operators, and observe that when evaluating the expression at  $t = 0$ , we obtain the expectation of the  $k$ -th moment. I might post a complete proof at a later date. ■

**Theorem 1.29.** Suppose the random variable  $X$  has m.g.f.  $M_X(t)$  defined for  $t \in (-h, h)$ . Let  $Y = aX + b$  where  $a, b \in \mathbb{R}$ . Then,

$$M_Y(t) = e^{bt} M_X(at) \quad |t| < \frac{h}{|a|}$$

*Proof.* Follows from the definition of moment generating functions. ■

**Theorem 1.30. Uniqueness theorem.** Suppose that  $X$  and  $Y$  have the same moment generating function over the same domain. Then  $X$  and  $Y$  have the same distribution, modulo a set of Lebesgue measure zero.

*Proof.* Stay tuned for PMATH 352!

**Example 1.31.** Suppose  $X \sim \text{Unif}(0, 1)$  and let  $Y = -2 \log X$ . Then using the uniqueness theorem, we can prove that  $Y \sim \chi_2^2$ .

## Chapter 2

# Joint Distributions

**Definition 2.1.** Suppose  $X$  and  $Y$  are random variables defined on a sample space  $S$ . Then  $(X, Y)$  is a **random vector** whose **joint cdf** is

$$F(x, y) = P(X \leq x, Y \leq y) = P[X \leq x \cap Y \leq y] \quad (x, y) \in \mathbb{R}^2$$

**Theorem 2.2.** *The following are cool facts of life related to joint cdfs:*

1. For fixed  $x$ ,  $F$  is non-decreasing in  $y$ .
2. For fixed  $y$ ,  $F$  is non-decreasing in  $x$ .
3.  $\lim_{x \rightarrow -\infty} F(x, y) = 0$  and  $\lim_{y \rightarrow -\infty} F(x, y) = 0$
4.  $\lim_{(x, y) \rightarrow (-\infty, -\infty)} F(x, y) = 0$  and  $\lim_{(x, y) \rightarrow (\infty, \infty)} F(x, y) = 1$

*Proof.* Each of these follows using properties of cdfs. ■

**Definition 2.3.** The **marginal cdf** of  $X$  given a joint cdf  $F(x, y)$  is

$$F_X(x) = P(X \leq x) = \lim_{y \rightarrow \infty} F(x, y) \quad x \in \mathbb{R}$$

**Definition 2.4.** Two random variables  $X$  and  $Y$  are said to be **jointly continuous** if there exists a function  $f(x, y)$  such that the joint c.d.f. of  $X$  and  $Y$  can be written as

$$F(x, y) = \int_{-\infty}^x \int_{-\infty}^y f(t_1, t_2) dt_2 dt_1 \quad \forall (x, y) \in \mathbb{R}^2$$

We define the **joint p.d.f.** as

$$\frac{\partial^2}{\partial x \partial y} F(x, y)$$

**Definition 2.5.** Suppose  $X$  and  $Y$  are both continuous random variables with joint p.d.f.  $f(x, y)$ . The **marginal p.d.f.** of  $X$  is given by

$$f_X(x) = \int_{-\infty}^{\infty} f(x, y) dy$$

and the marginal p.d.f. of  $Y$  is

$$f_Y(y) = \int_{-\infty}^{\infty} f(x, y) dx$$

**Definition 2.6.** Two random variables  $X$  and  $Y$  with joint c.d.f.  $F(x, y)$  are **independent** if and only if

$$F(x, y) = F_X(x)F_Y(y)$$

Equivalently, two continuous random variables  $X$  and  $Y$  with p.d.f.  $f_X(x)$  and  $f_Y(y)$  are independent if and only if

$$f(x, y) = f_X(x)f_Y(y) \quad \forall (x, y) \in \text{Supp}(x, y)$$

**Remark.** A necessary, but not sufficient, condition for independence is that the support set be a rectangle.

**Theorem 2.7. Factorisation theorem for independence.** Suppose  $X$  and  $Y$  are random variables with joint p.m.f./p.d.f.  $f(x, y)$  and marginal distributions  $f_X(x)$  and  $f_Y(y)$ , respectively. Suppose also that  $A = \{(x, y) : f(x, y) > 0\}$  is the support of  $(X, Y)$ ,  $A_X = \{x : f_X(x) > 0\}$  is the support of  $X$ , and  $A_Y = \{y : f_Y(y) > 0\}$  is the support of  $Y$ .

Then  $X$  and  $Y$  are independent if and only if  $A = A_X \times A_Y$  and there exist non-negative functions  $g(x)$  and  $h(y)$  such that  $f(x, y) = g(x)h(y)$  for all  $(x, y) \in A_X \times A_Y$ .

*Proof.* The result follows from a standard result in calculus where the integral of the product is the product of the integral in a hyperrectangle, as a consequence of Fubini's theorem allowing us to switch the order of integration<sup>1</sup>. ■

**Definition 2.8.** The **conditional distribution** of  $X$  given  $Y = y$  is

$$f(x|y) = \frac{f(x, y)}{f_Y(y)}$$

**Theorem 2.9.** If  $X$  and  $Y$  are independent, then  $f(x|y) = f_X(x)$ .

*Proof.* Duh. ■

**Theorem 2.10.** Suppose  $X$  and  $Y$  are two random variables with joint p.m.f./p.d.f.  $f(x, y)$  and  $a_i, b_i, i = 1, \dots, n$  are constants, and  $g_i(x, y)$  are real valued functions. Then,

$$E \left[ \sum_{i=1}^n (a_i g_i(X, Y) + b_i) \right] = \sum_{i=1}^n (a_i E[g_i(X, Y)]) + \sum_{i=1}^n b_i$$

provided each  $E[g_i(X, Y)]$  exist.

*Proof.* We prove the existence of the linear combination of the expectation using the triangle inequality. The remainder follows from linearity of summation and integration. ■

**Theorem 2.11.** If  $X$  and  $Y$  are independent random variables and  $g(x)$  and  $h(y)$  are real valued functions, then

$$E[g(X)h(Y)] = E[g(X)] E[h(Y)]$$

*Proof.* It follows by a simple manipulation of the integral:

$$\begin{aligned} E[g(X)h(Y)] &= \int \int_S g(x)h(y)f(x, y)dxdy \\ &= \int \int_S g(x)h(y)f_X(x)f_Y(y)dxdy \\ &= \int h(y)f_Y(y) \int g(x)f_X(x)dxdy \\ &= E[g(X)] E[h(Y)] \end{aligned}$$

**Definition 2.12.** In general, for  $X_1, \dots, X_n$  we say they are **mutually independent** if

$$f(x_1, \dots, x_n) = f(x_1) \dots f(x_n)$$

**Remark.** Mutual independence implies pairwise independence, but the converse is not true. See Hogg p.122 for a counterexample.

<sup>1</sup>See Wade's Introduction to Analysis, Chapter 12.3, Problem 6a, page 418.



**Theorem 2.13.** If  $X_1, \dots, X_n$  are independent random variables and  $h_1, \dots, h_n$  are real valued functions, then

$$\mathbb{E} \left[ \prod_{i=1}^n h_i(X_i) \right] = \prod_{i=1}^n \mathbb{E} [h_i(X_i)]$$

**Definition 2.14.** The **covariance** of random variables  $X$  and  $Y$  is given by

$$\text{Cov}(X, Y) = \mathbb{E}[(X - \mu_X)(Y - \mu_Y)] = \mathbb{E}[XY] - \mu_X \mu_Y$$

where  $\mu_X = \mathbb{E}[X]$  and  $\mu_Y = \mathbb{E}[Y]$ . If  $\text{Cov}(X, Y) = 0$  we say  $X$  and  $Y$  are **uncorrelated**. Note that  $\text{Cov}(X, X) = \text{Var}(X)$ .

**Theorem 2.15.** If  $X$  and  $Y$  are independent random variables, then  $\text{Cov}(X, Y) = 0$ . The converse is not true.

*Proof.*  $\text{Cov}(X, Y) = \mathbb{E}[XY] - \mathbb{E}[X]\mathbb{E}[Y] = \mathbb{E}[Y]\mathbb{E}[X] - \mathbb{E}[X]\mathbb{E}[Y] = 0$ . For a counterexample to the converse,  $Y = X^2$  over a symmetric support probably works.

**Theorem 2.16.** Suppose  $X$  and  $Y$  are random variables and  $a, b, c$  are real constants. Then:

$$\text{Var}(aX + bY + c) = a^2 \text{Var}(X) + b^2 \text{Var}(Y) + 2ab \text{Cov}(X, Y)$$

*Proof.* It follows from the definition of variance. ■

**Theorem 2.17.** Suppose  $X_1, \dots, X_n$  are random variables with  $\text{Var}(X_i) = \sigma_i^2$ , and  $a_1, a_2, \dots, a_n$  are real constants. Then

$$\text{Var} \left( \sum_{i=1}^n a_i X_i \right) = \sum_{i=1}^n a_i^2 \sigma_i^2 + 2 \sum_{i=1}^{n-1} \sum_{j=i+1}^n a_i a_j \text{Cov}(X_i, X_j)$$

*Proof.* Follows from the Binomial Theorem. ■

**Definition 2.18.** The **correlation coefficient** of random variables  $X$  and  $Y$  is given by

$$\rho(X, Y) = \frac{\text{Cov}(X, Y)}{\sigma_X \sigma_Y}$$

where  $\sigma_X = \sqrt{\text{Var}(X)}$  and  $\sigma_Y = \sqrt{\text{Var}(Y)}$ .

**Theorem 2.19.** The following are properties of the correlation coefficient:

1.  $-1 \leq \rho(X, Y) \leq 1$ .
2.  $\rho(X, Y) = 1 \iff Y = aX + b$  for some  $a > 0$ .
3.  $\rho(X, Y) = -1 \iff Y = aX + b$  for some  $a < 0$ .

*Proof.* Exercise. ■