

CoSA: Scheduling by Constrained Optimization for Spatial Accelerators

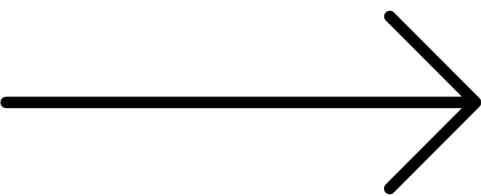
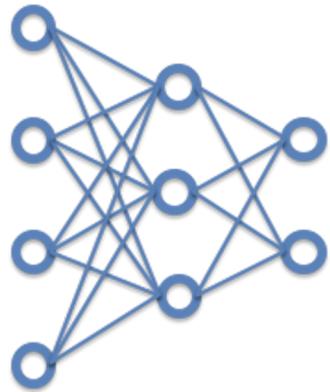
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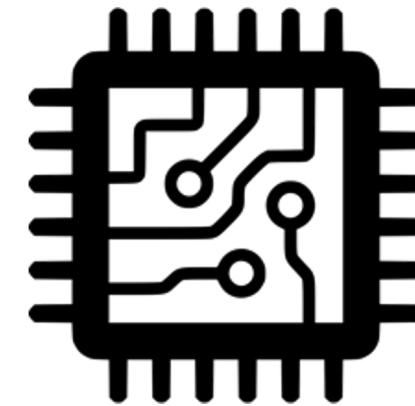
Scheduling is required everywhere



Scheduling

- Algorithm

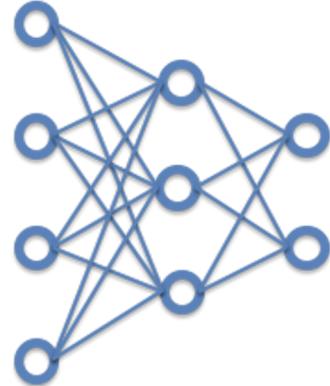
algorithmic states
to be run



- Hardware

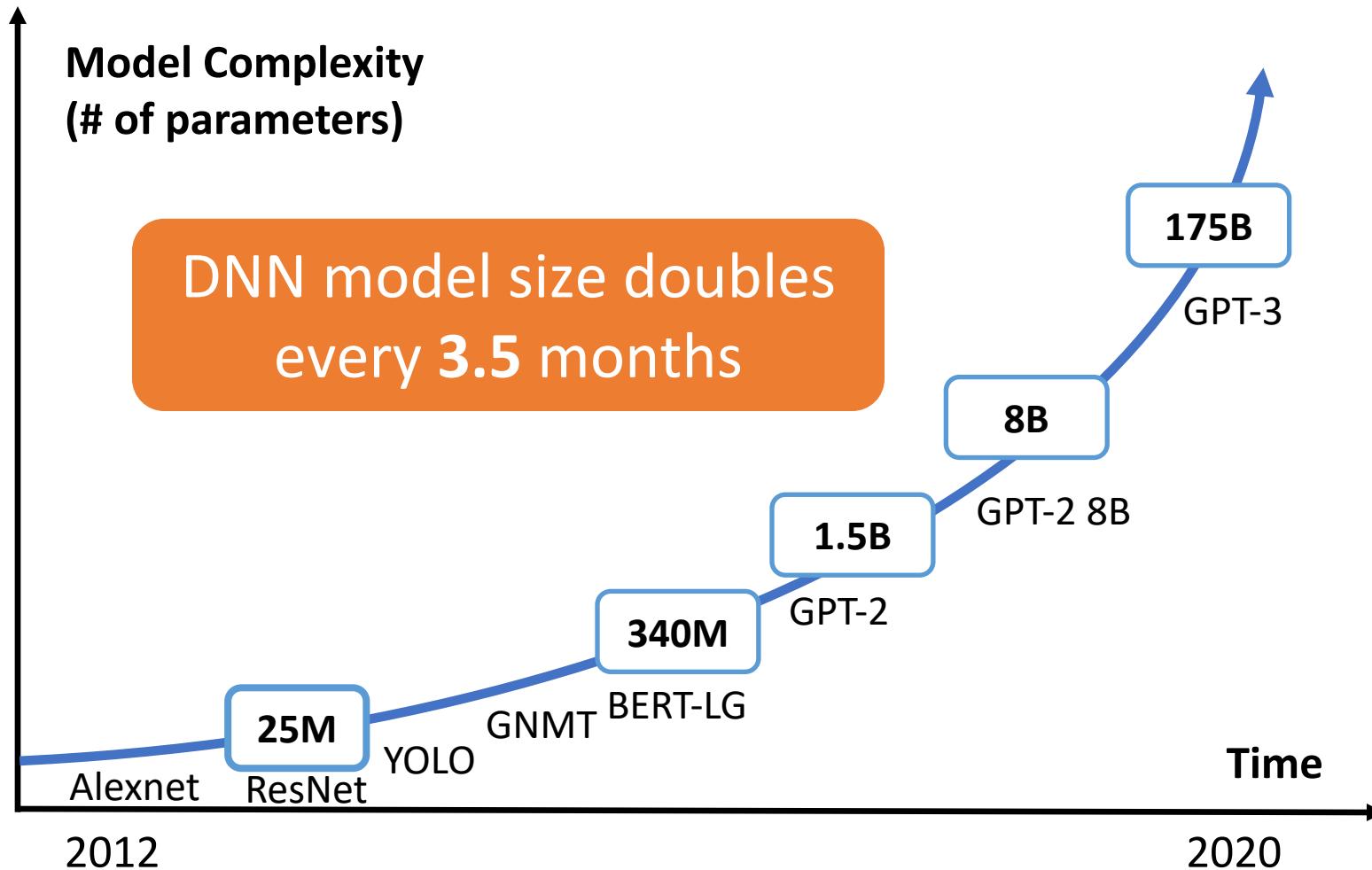
hardware resources
to be allocated

Scheduling is a big challenge

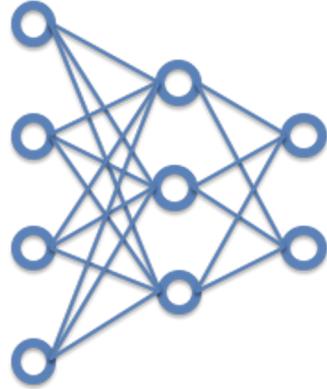


- Algorithm
 1. Exponentially growing algorithm complexity

Exponentially growing algorithm complexity

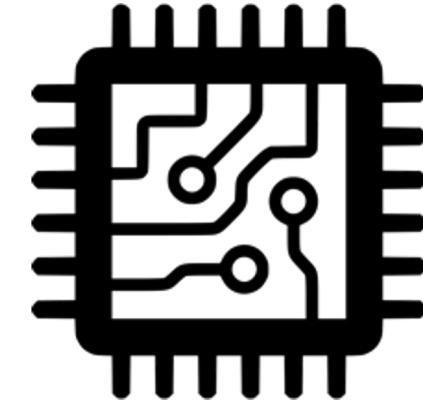


Scheduling is a big challenge



- Algorithm

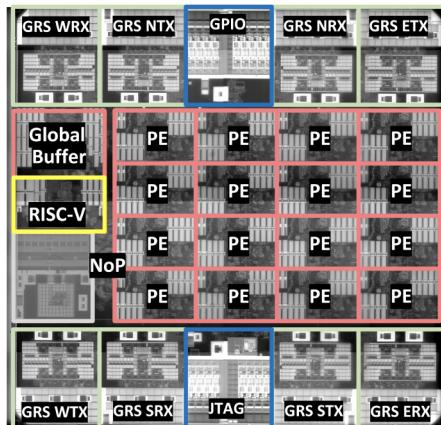
- 1. Exponentially growing algorithm complexity**
- 2. Rapidly increasing hardware capacity**



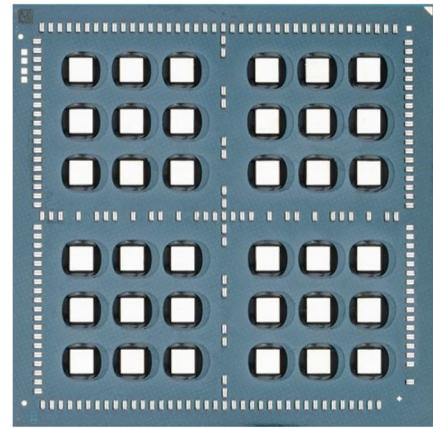
- Hardware

Rapidly increasing hardware capacity

NoC/NoP Chip



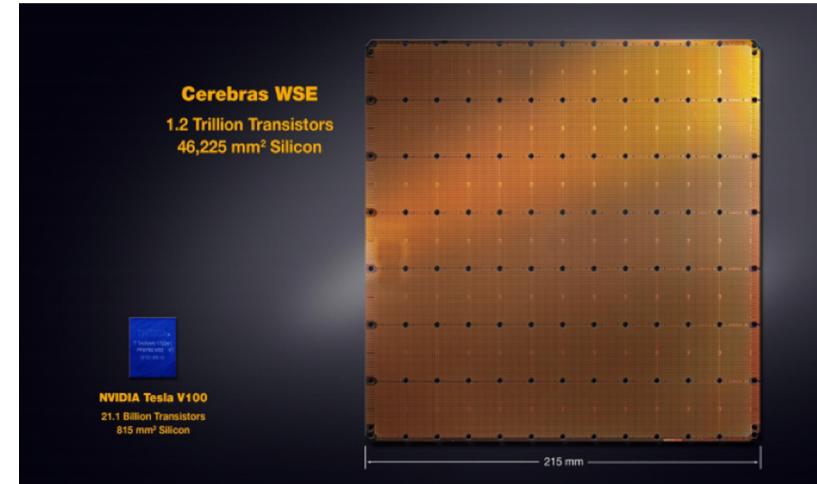
(a) Simba chiplet



(b) Simba package

Simba¹
16PEs x 36 Chiplets

Wafer-scale Chip

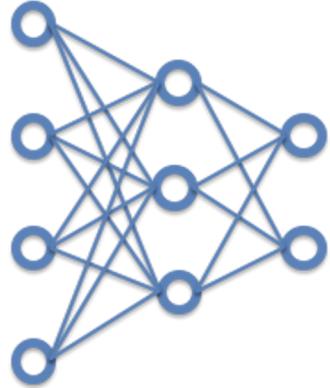


Cerebras²
84 Interconnected Chips

¹ Shao, Yakun Sophia, and et al. "Simba: Scaling Deep-Learning Inference with Multi-Chip-Module-Based Architecture." 2019 MICRO.

² "Wafer-Scale Deep Learning", <https://cerebras.net/blog/wafer-scale-deep-learning-hot-chips-2019-presentation/>

Scheduling is a big challenge

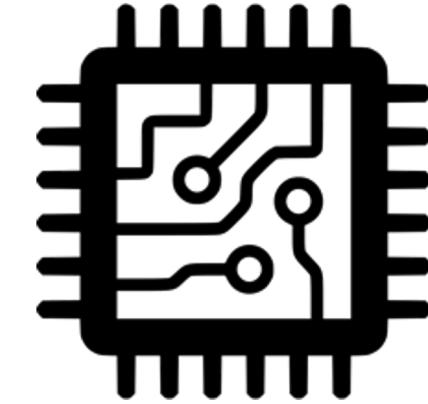


- Algorithm

Intractable scheduling space



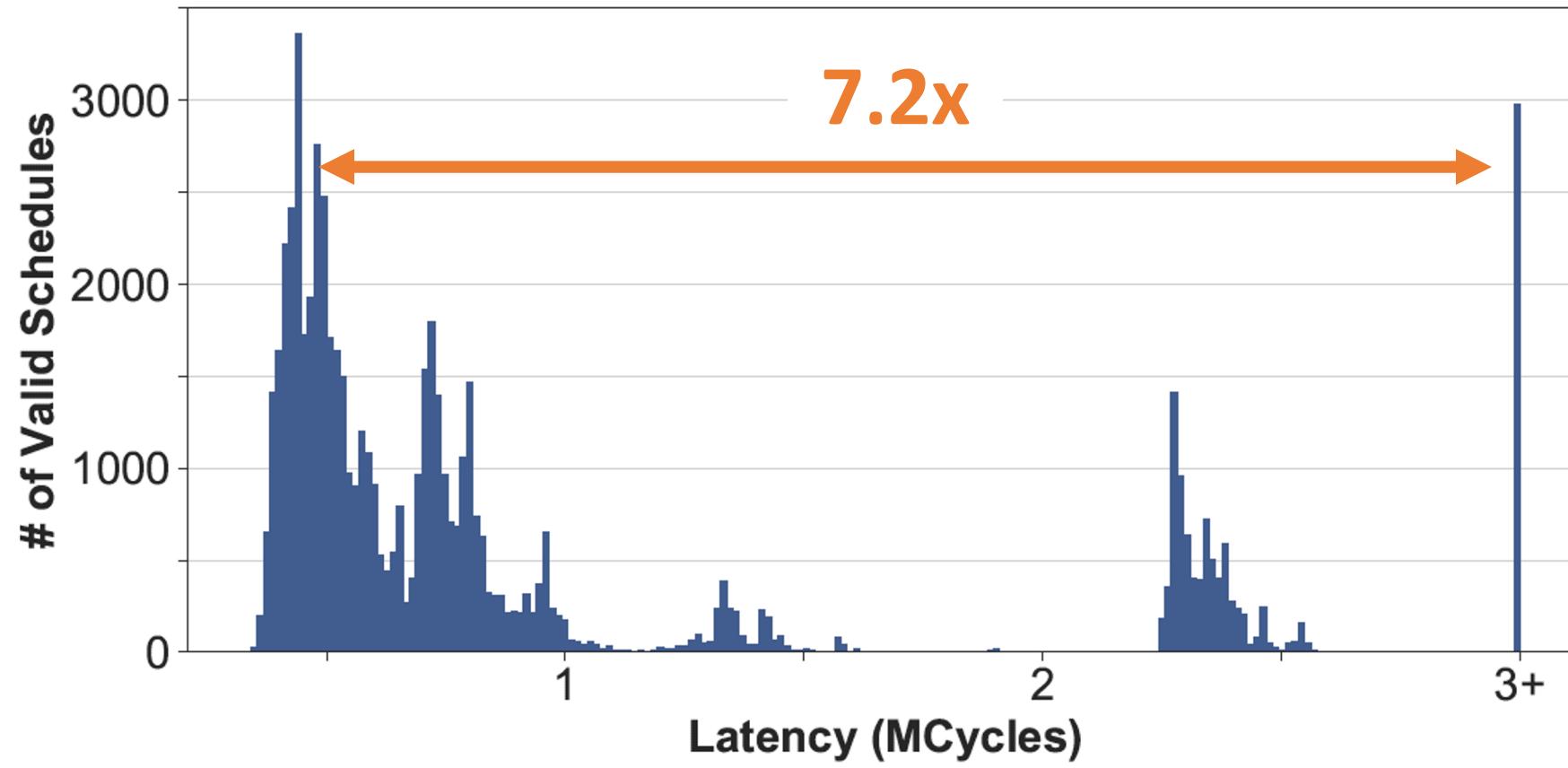
Scheduling



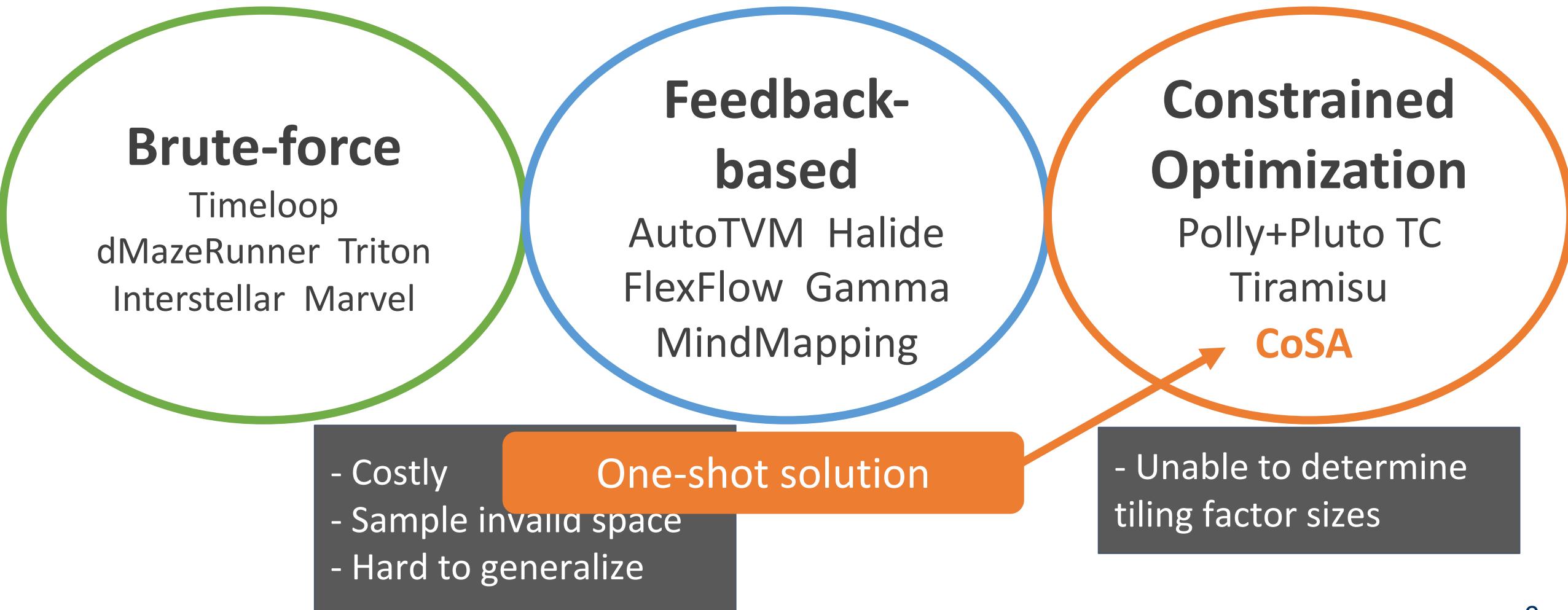
- Hardware

1. Exponentially growing algorithm complexity
2. Rapidly increasing hardware capacity

Scheduling significantly affects performance



State-of-the-art DNN accelerator schedulers



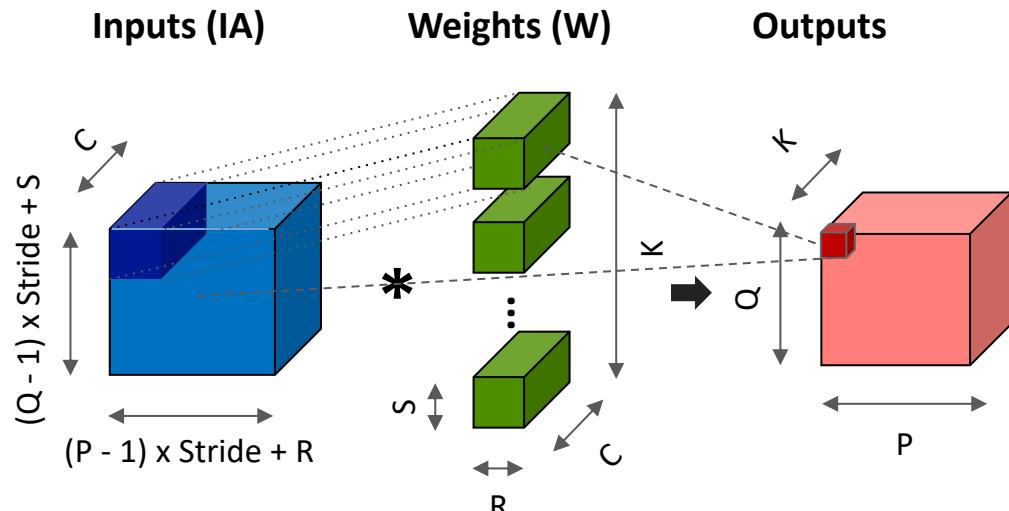
Opportunities

Workload
Regularity

Hardware
Regularity

Explicit Data
Movement

Target Workload



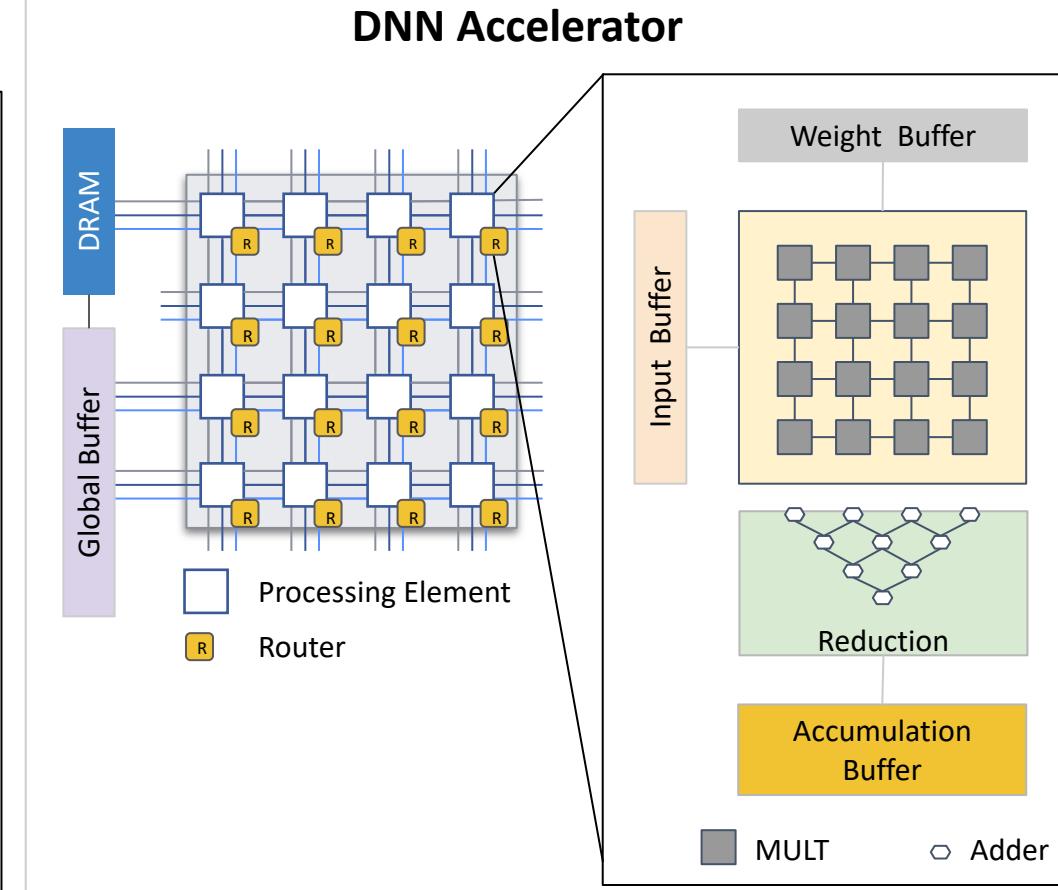
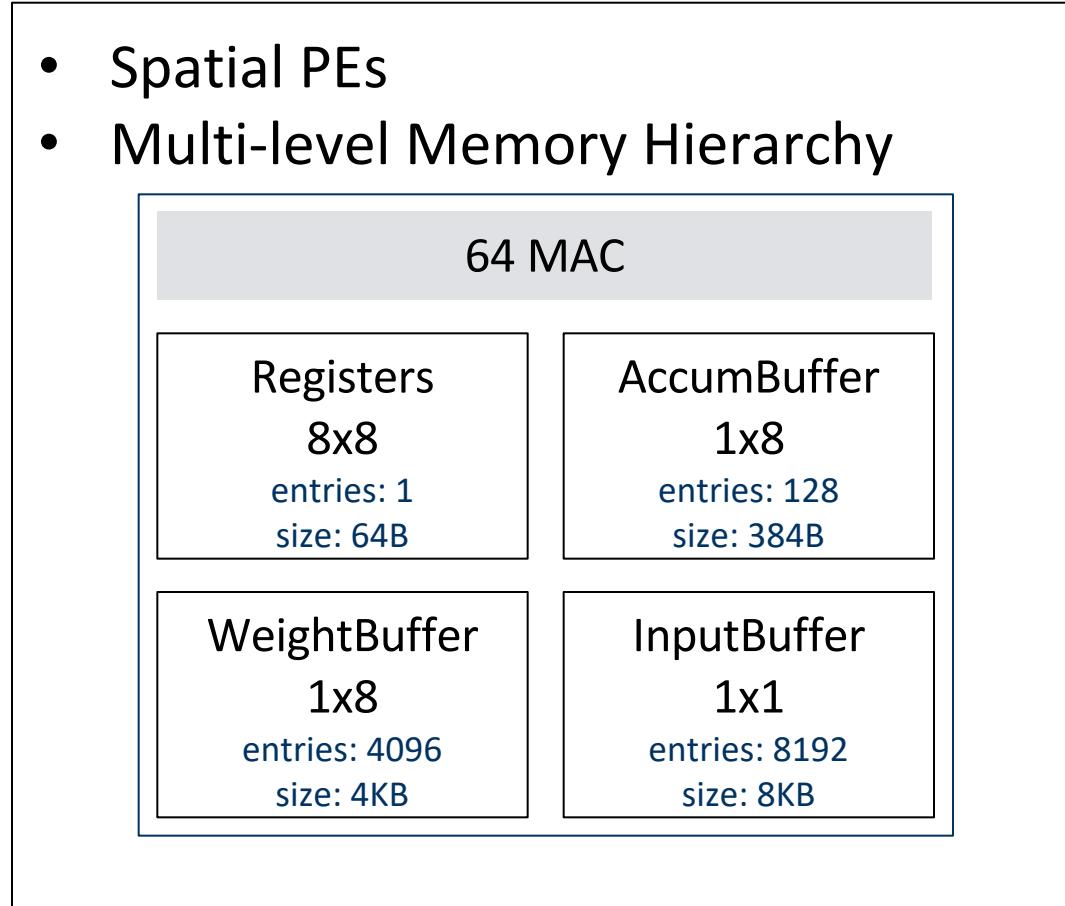
R, S: weight width and height
P, Q: output width and height
C: input channel size
K: output channel size
N: batch size

DNN Layer :

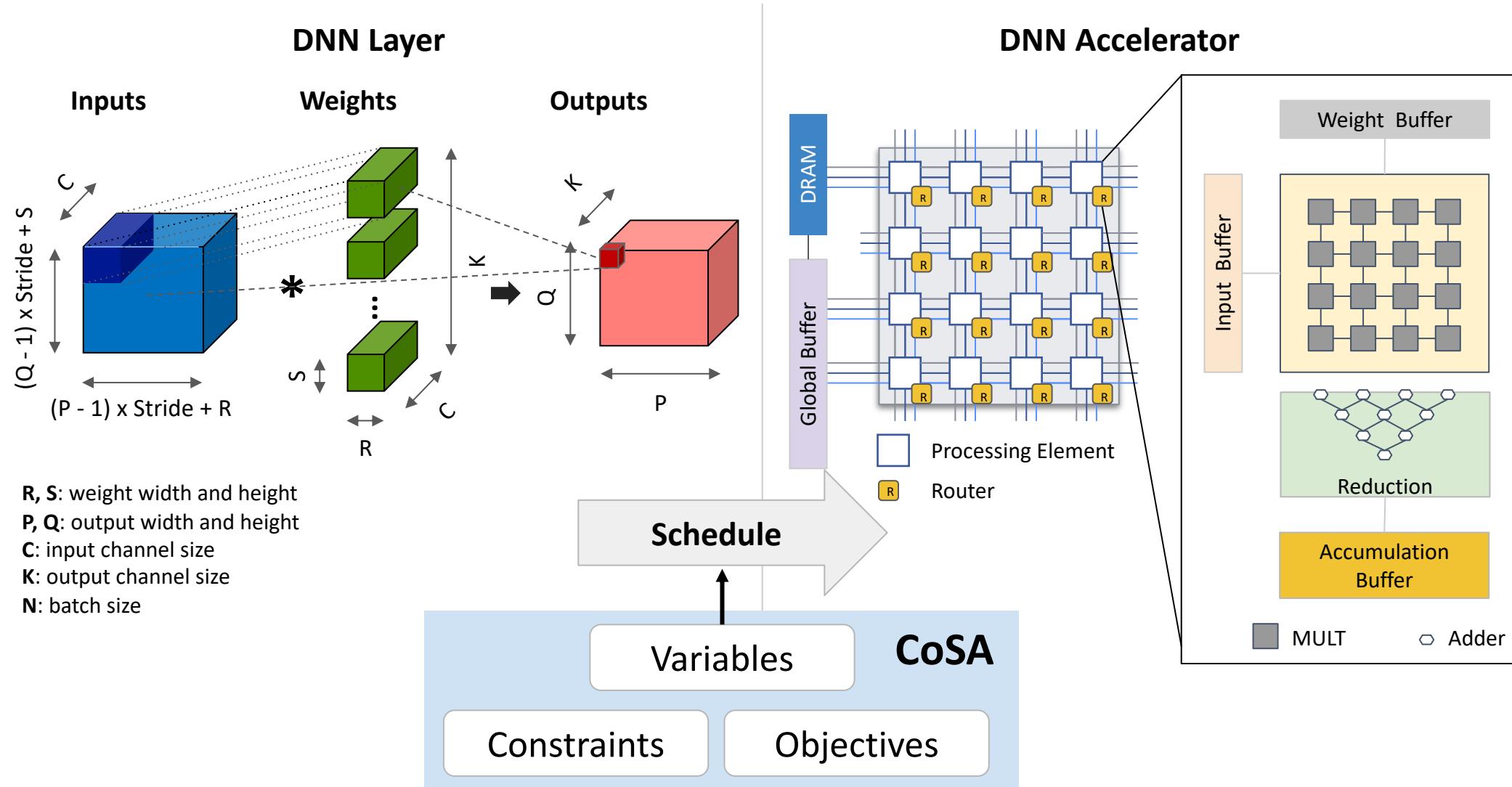
```
for n in [0:N)
    for k in [0:K)
        for c in [0:C)
            for p in [0:P)
                for q in [0:Q)
                    for r in [0:R)
                        for s in [0:S)
                            OA[n, p, q, k] +=
                                IA[n, p+r-(R-1)/2, q+s-(S-1)/2, c]
                                × W[r, s, c, k]
```

Target Architecture

- Spatial PEs
- Multi-level Memory Hierarchy



DNN scheduling problem formulation with CoSA



Three scheduling decisions

DRAM level

```
for q2 = [0 : 2) :
```

Global Buffer level

```
for q1 = [0 : 7) :
```

```
  for n0 = [0 : 3) :
```

```
    spatial_for r0 = [0 : 3) :
```

```
    spatial_for k1 = [0 : 2) :
```

Input Buffer level

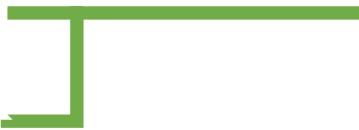
```
      for c1 = [0 : 2) :
```

```
        for p1 = [0 : 2) :
```

Weight Buffer level

```
          for p0 = [0 : 2) :
```

```
            spatial_for k0 = [0 : 2) :
```



1. Tiling Factors



2. Spatial / Temporal



3. Loop Permutation

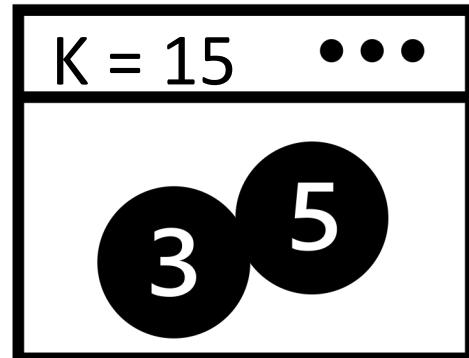
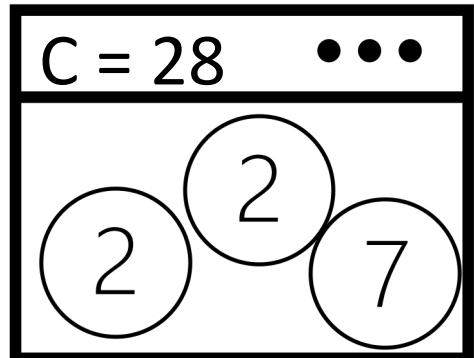
...

Key idea: prime factor allocation problem

Matrix-vector mult:

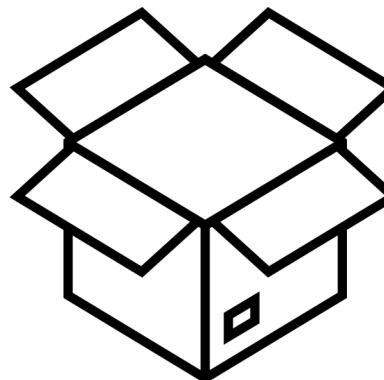
```
for c in [0:C) // C = 28  
    for k in [0:K) // K = 15  
        OA[k] += IA[c] × W[c,k]
```

Prime factor items:

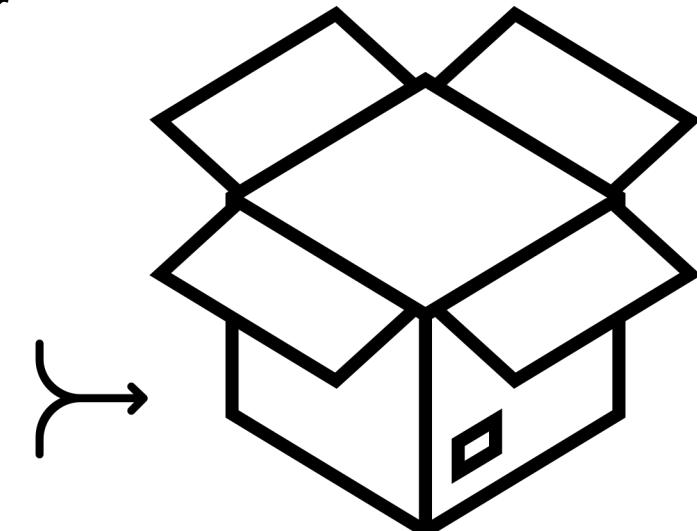


Local buffers:

- Weight buffer
- Global buffer



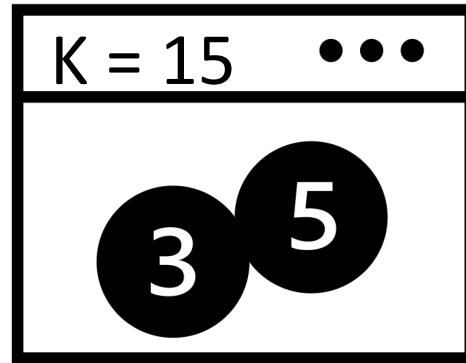
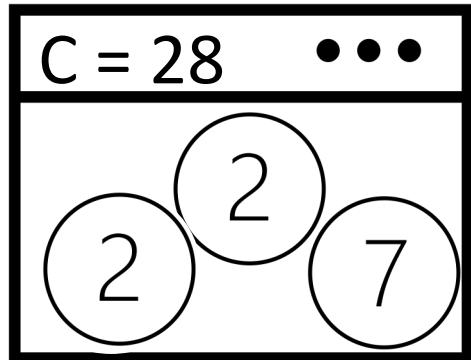
Weight Buffer
(Size = 4)



Global Buffer
(Size = 20)

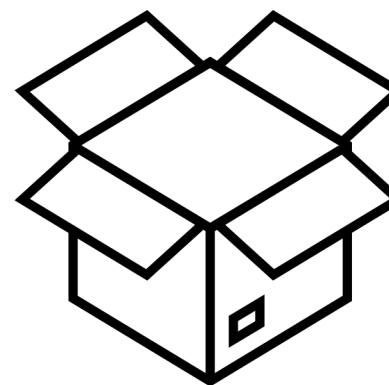
CoSA Variable X – Tiling Factors

Prime factor items :



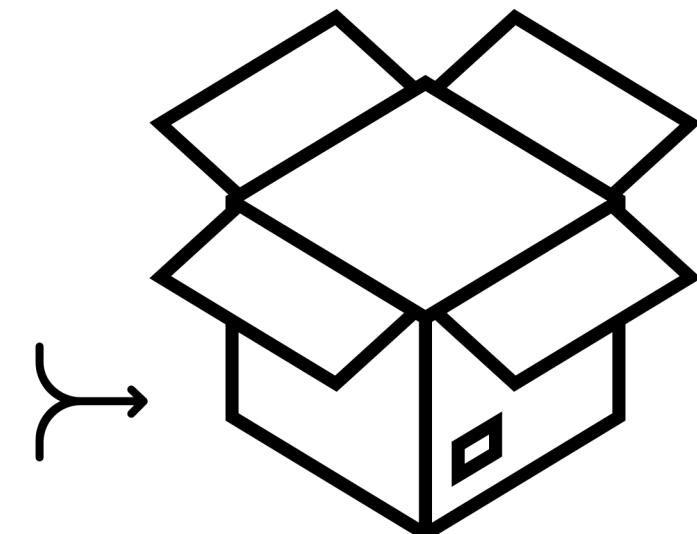
Local buffers:

Utilized: 2



Weight Buffer
(Size = 4)

Utilized:
 $(2 \times 3 \times 5) \times (2) = 60$



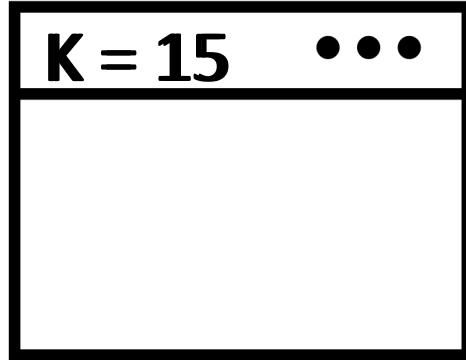
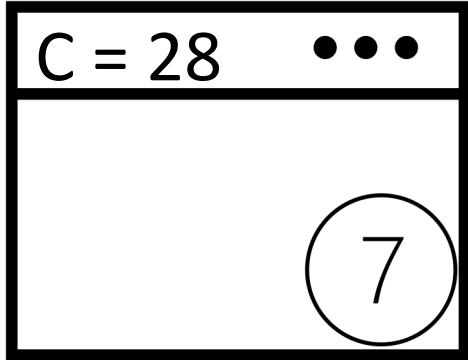
Global Buffer
(Size = 80)

Binary allocation var X:

	C=28			K=15	
Prime Factors	2	2	7	3	5
WeightBuf	✓				
GlobalBuf			✓	✓	✓
DRAM			✓		

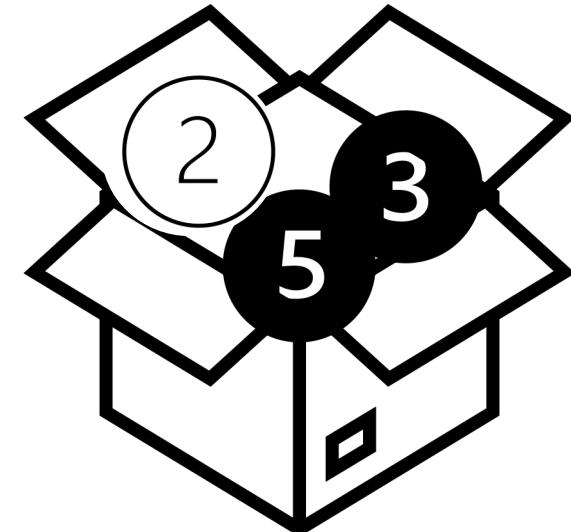
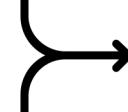
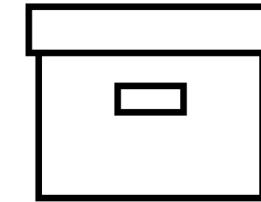
CoSA Variable X – Spatial/Temporal Mapping

Prime factor items :



4 PEs in the accelerator:

Spatial Factors
(Limit=4)



Temporal Factors



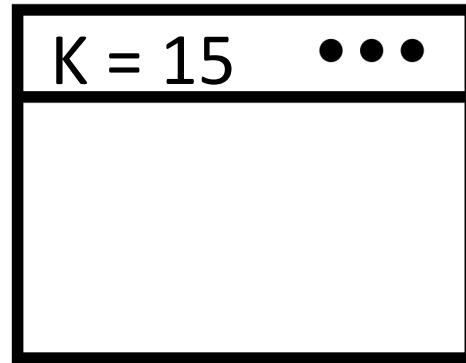
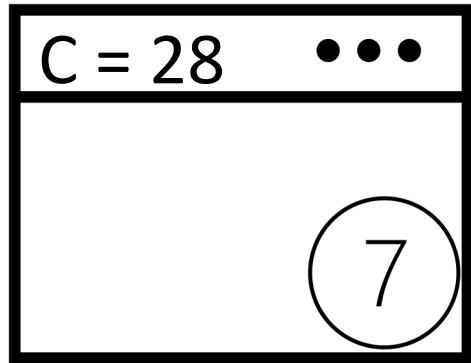
GlobalBuf

	C=28			K=15	
Prime Factors	2	2	7	3	5
Spatial				✓	
Temporal	✓				✓

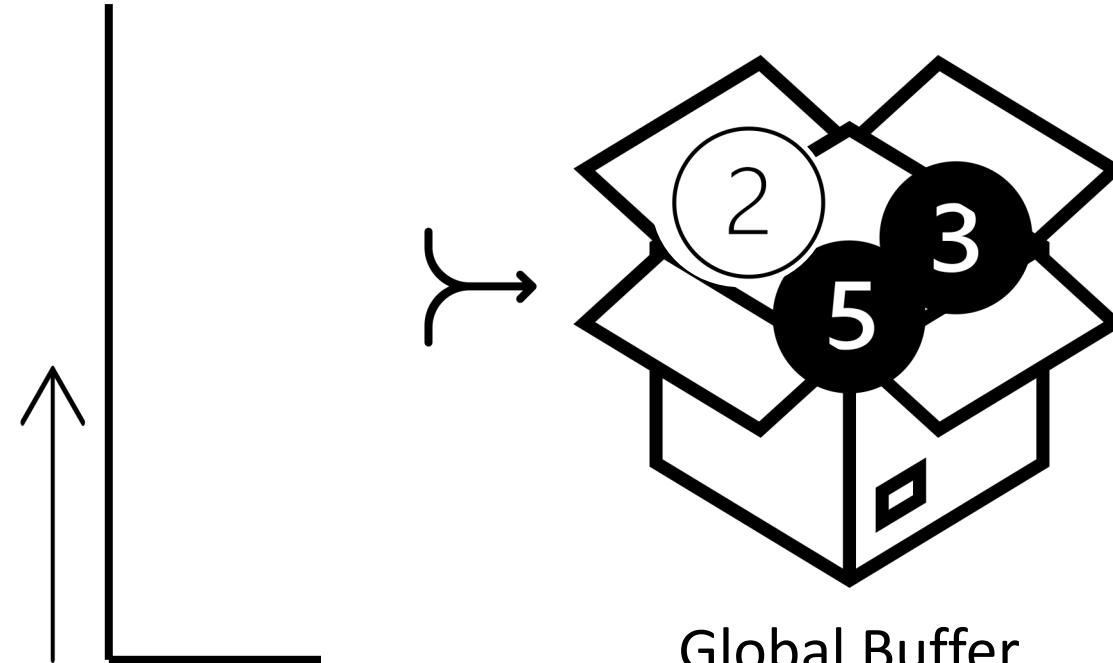
Global Buffer
(Size = 80)

CoSA Variable X – Loop Permutation

Prime factor items :



Rank in global buf:



Binary allocation var X:

	C=28			K=15	
Prime Factors	2	2	7	3	5
rank0	✓				
rank1					✓
rank2					
rank3					
rank4					

CoSA Variable X – Putting it altogether

	Memory	Perm	C=28			K=15	
Prime Factors			2	2	7	3	5
WeightBuf	...	t					
GlobalBuf	rank0		t				
	rank1					t	
	rank2						
	rank3						
	rank4						
DRAM	...			t			

s - Spatial, t - Temporal

DRAM level

```
for c2 = [0 : 7) :
```

Global Buffer level

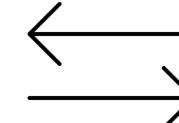
```
for k1 = [0 : 5) :
```

```
  for c1 = [0 : 2) :
```

```
    spatial_for k0 = [0 : 3) :
```

Weight Buffer level

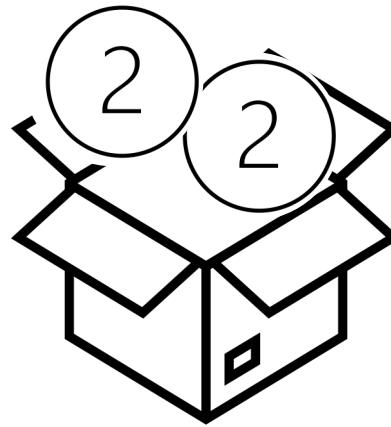
```
      for c0 = [0 : 2) :
```



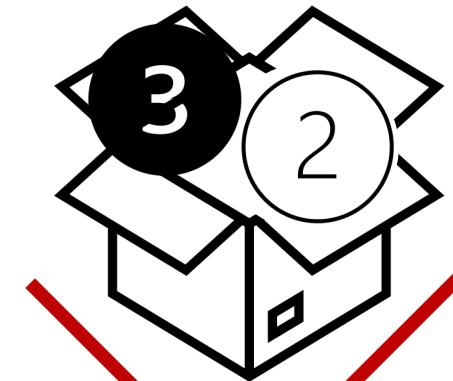
CoSA Constraints: Buffer Utilization



Weight Buffer
(Size = 4)

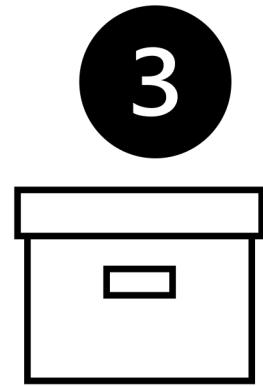


Weight Buffer
(Size = 4)

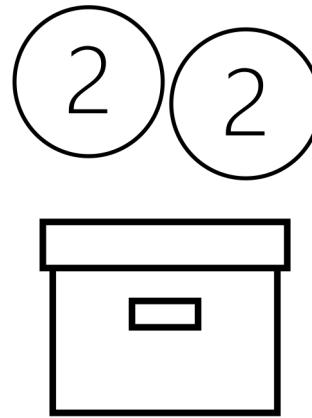


Weight Buffer
(Size = 4)

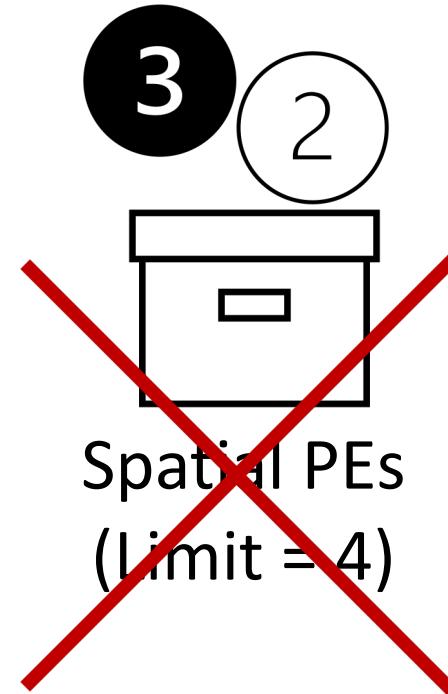
CoSA Constraints: Spatial Resources



Spatial PEs
(Limit = 4)

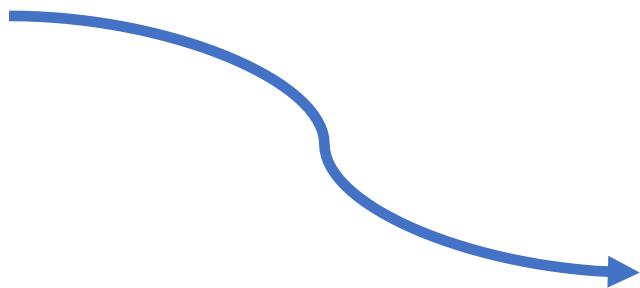
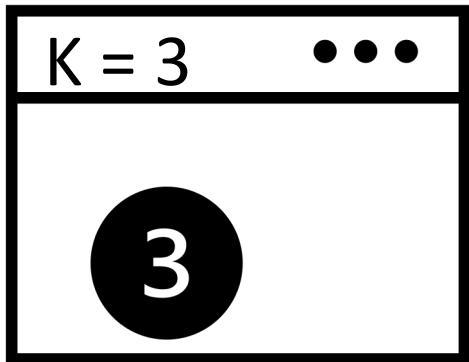


Spatial PEs
(Limit = 4)



Spatial PEs
(Limit = 4)

CoSA Binary Constants A and B



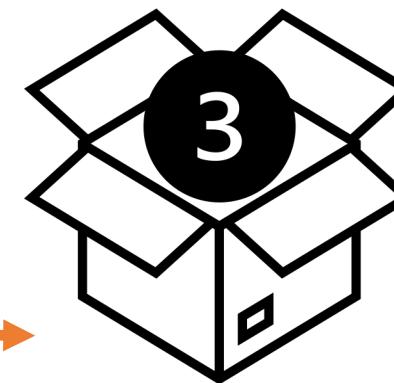
	Related			idx v
	W	IA	OA	
R	✓	-	-	
S	✓	-	-	
P	-	✓	✓	
Q	-	✓	✓	
C	✓	✓	-	
K	✓	-	✓	
N	-	✓	✓	

j

	Related			idx
	W	IA	OA	v
Register	✓	✓	✓	
AccBuf	-	-	✓	
WBuf	✓	-	-	i
InputBuf	-	✓	-	
GlobalBuf	✓	✓	-	
DRAM	✓	✓	✓	

Constant B

Constant A



Weight Buffer
(Utilization = 3)

CoSA Constraints

A. Buffer Utilization

$$U_{I,v} = \prod_{i=0}^{I-1} \prod_{j=0}^6 \prod_{k=0}^1 \begin{cases} prime_factor_{j,n}, & X_{(j,n),i,k} A_{v,j} B_{v,I} = 1 \\ 1, & \text{otherwise} \end{cases} \quad (1)$$

Not a linear function of X

Log trick: turning products into linear sums

- Non-linear formula:

$$\circ \quad \begin{cases} 3, & \text{if } X_{3_0} = 1 \\ 1, & \text{otherwise} \end{cases} \times \begin{cases} 2, & \text{if } X_{2_0} = 1 \\ 1, & \text{otherwise} \end{cases} \times \begin{cases} 2, & \text{if } X_{2_1} = 1 \\ 1, & \text{otherwise} \end{cases} \leq 4$$

- X_{p_i} represents the i th prime factor with value p

- Linear formula:

- $\log(3)X_{3_0} + \log(2)X_{2_0} + \log(2)X_{2_1} \leq \log(4)$

↓ Taking log

CoSA Constraints

A. Buffer Utilization

$$U_{I,v} = \prod_{i=0}^{I-1} \prod_{j=0}^6 \prod_{k=0}^1 \begin{cases} prime_factor_{j,n}, & X_{(j,n),i,k} A_{v,j} B_{v,I} = 1 \\ 1, & \text{otherwise} \end{cases} \quad (1)$$

Not a linear function of X

$$\begin{aligned} U_{I,v} &= \sum_{i=0}^{I-1} \sum_{j=0}^{6,N} \sum_{k=0}^1 \log(f_{j,n}) A_{v,j} B_{v,I} X_{(j,n),i,k} \\ &\leq \log(M_{I,v}), \forall I \end{aligned} \quad (2)$$

Taking
log

Linear function of X

CoSA Constraints

B. Spatial Resources

- 1) each problem factor can only be mapped to either spatial or temporal execution

$$\sum_{k=0}^1 X_{(j,n),i,k} == 1, \forall (j,n), i \quad (3)$$

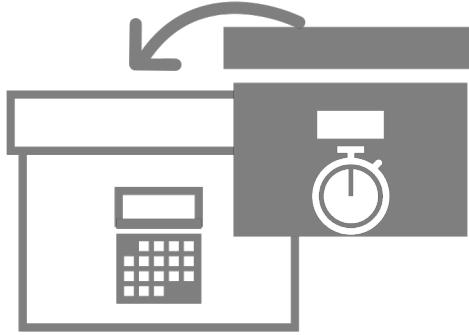
- 2) Spatially-mapped factors do not exceed the resource limit

$$\sum_{j=0, n=0}^{6, N} \log(prime_factor_{j,n}) X_{(j,n),I,0} \leq \log(S_I), \forall I \quad (4)$$

CoSA Objectives



- Utilization-driven

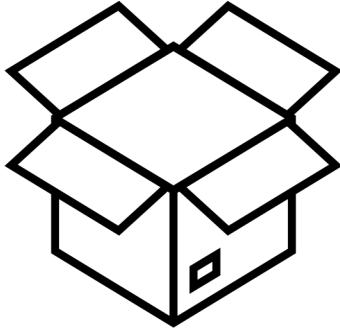


- Compute-driven

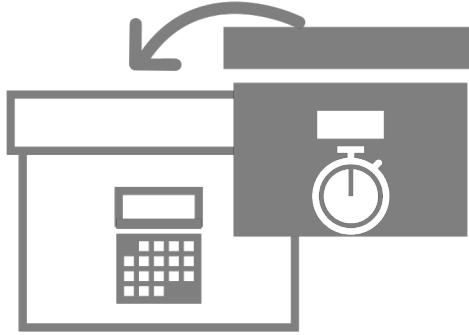


- Traffic-driven

CoSA Objectives



- Utilization-driven



- Compute-driven

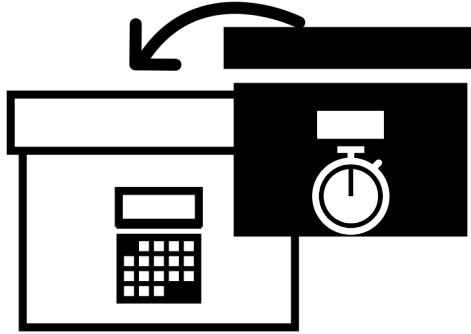


- Traffic-driven

CoSA Objectives



- Utilization-driven



- Compute-driven

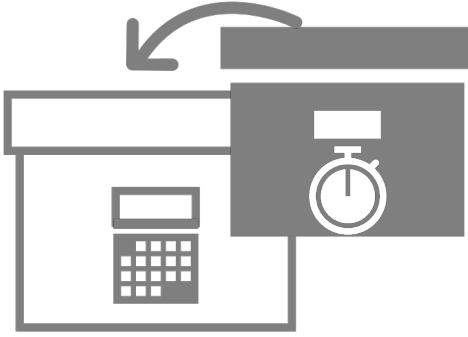


- Traffic-driven

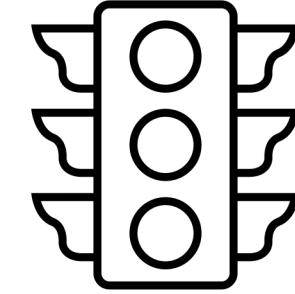
CoSA Objectives



- Utilization-driven



- Compute-driven



- Traffic-driven

CoSA Traffic-driven Objective

DRAM level

```
for c2 = [0 : 7) :
```

Global Buffer level

```
for k1 = [0 : 5) :
```

```
for c1 = [0 : 2) :
```

```
spatial_for k0 = [0 : 3) :
```

Weight Buffer level

```
for c0 = [0 : 2) :
```

S – Temporal iteration

L – Unicast/multicast traffic

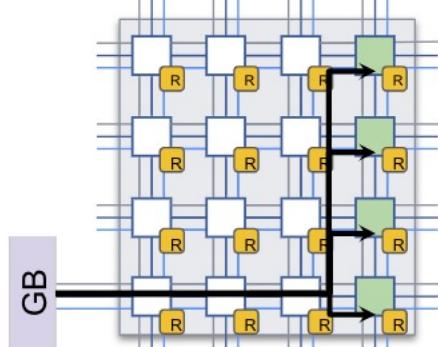
D – Data transfer size

$$\text{Overall Traffic} = S \times L \times D$$

Constant A Implied NoC Traffic Patterns

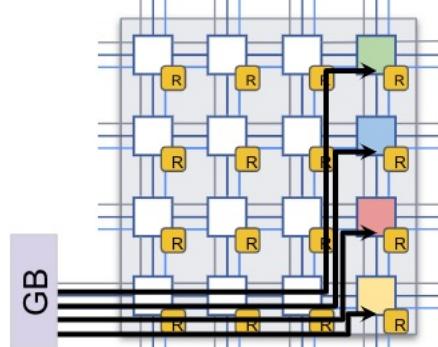
Global Buffer to NoC Traffic:

a. Multicast: $A_{P,W} = 0$



P is mapped spatially across colored PEs

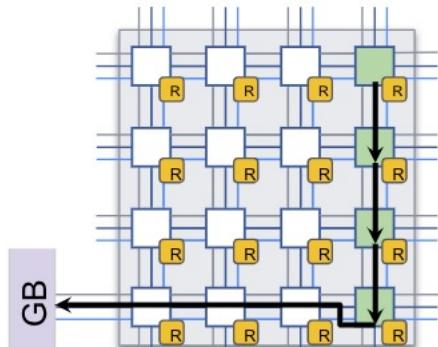
b. Unicast: $A_{C,W} = 1$



C is mapped spatially across colored PEs

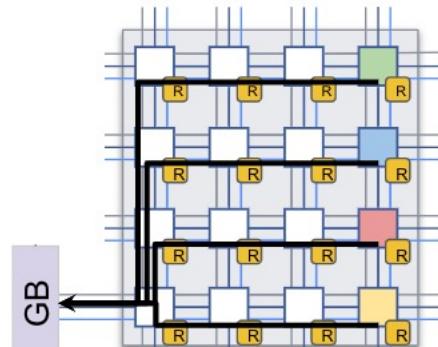
NoC to Global Buffer Traffic:

c. Reduction: $A_{C,OA} = 0$



C is mapped spatially across colored PEs

d. Unicast: $A_{P,OA} = 1$



P is mapped spatially across colored PEs

The variable **X** and constant **A** determine the traffic types of different data tensors from global buffer to PEs:

- Multicast
- Unicast
- Reduction

CoSA Objective Functions

1. Utilization-Driven Objective

$$\hat{U} = \sum_{i=0}^I \sum_{v=0}^2 U_{i,v} \quad (5)$$

CoSA Objective Functions

2. Compute-Driven Objective

$$\hat{C} = \sum_{i=0}^I \sum_{j=0, n=0}^{6, N} \log(prime_factor_{j,n}) X_{(j,n), i, 1} \quad (11)$$

Temporal Mapping

CoSA Objective Functions

3. Traffic-Driven Objective

- a. Data size for each NoC transfer

$$D_v = \sum_{i=0}^{I-1} \sum_{j=0, n=0}^{6, N} \sum_{k=0}^1 \log(prime_factor_{j,n}) A_{v,j} X_{(j,n), i, k} \quad (6)$$

- b. Spatial factors to indicate the NoC traffic patterns

$$L_v = \sum_{j=0, n=0}^{6, N} \log(prime_factor_{j,n}) X_{(j,n), I, 0} A_{v,j} \quad (7)$$

- c. Temporal iteration count for different tensors to indicate data reuse

$$R_v = \sum_{p=0}^{P-1} \sum_{j=0, n=0}^{6, N} \log((prime_factor_{j,n}) Y_{p,v} X(j, n), p, 1) \quad (9)$$

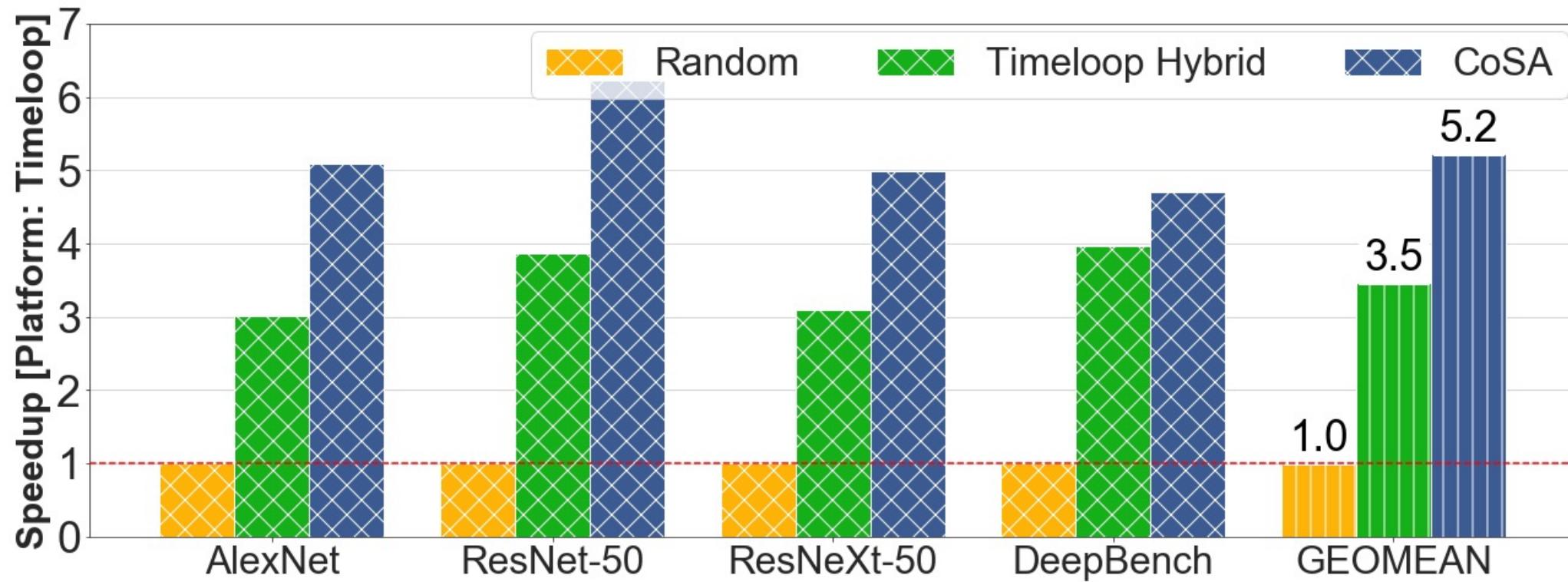
- d. Overall

$$\hat{T} = \sum_{v=0}^2 D_v + L_v + R_v \quad (10)$$

CoSA Evaluation

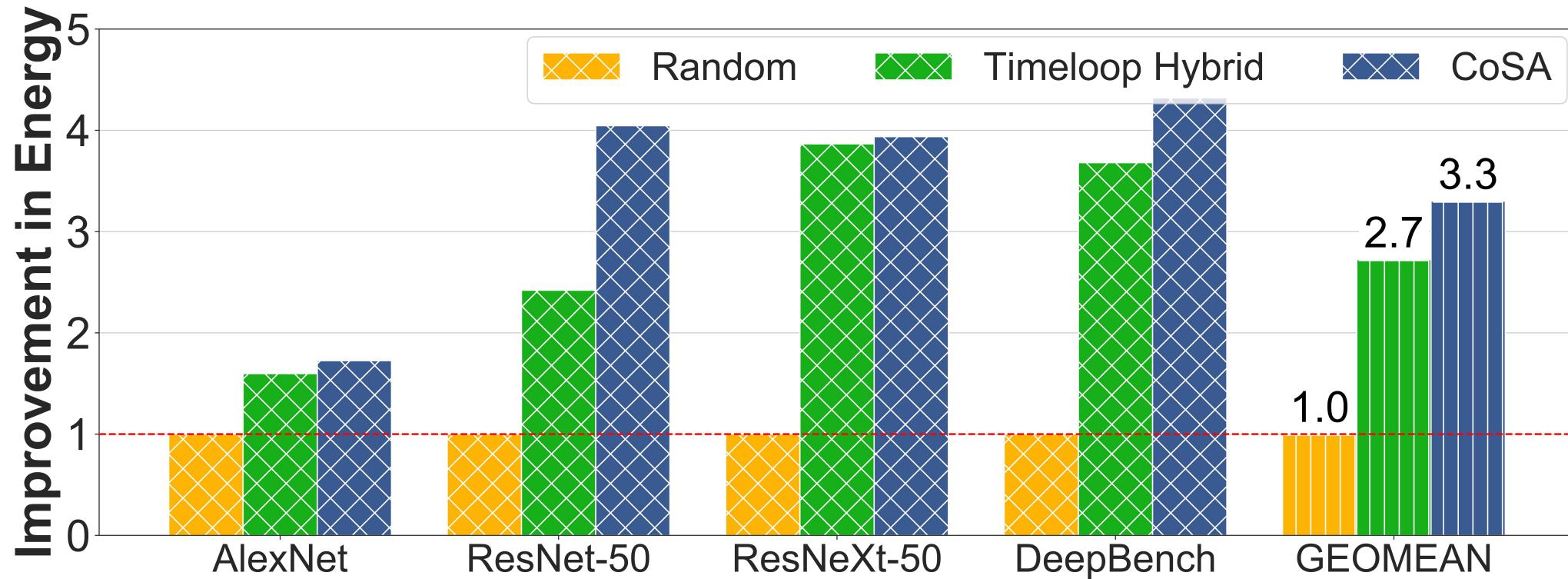
- Baselines:
 - Random (best out of 5 valid schedules)
 - Timeloop Hybrid (best out of 16K valid schedules)
- DNN workloads:
 - AlexNet, ResNet-50, ResNext-50, DeepBench
- Platforms:
 - Timeloop Simulator
 - SystemC NoC Simulator
 - GPU

1.5x latency speedup



- 5.2x better than Random
- 1.5x better than Timeloop Hybrid

1.2x better energy efficiency



- 3.3x better than Random
- 1.2x better than Timeloop Hybrid

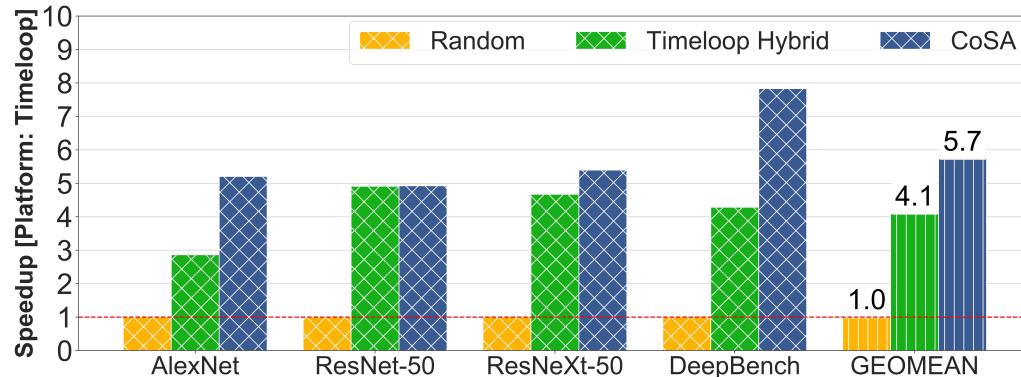
90x faster time-to-solution with CoSA

	CoSA	Random	Timeloop Hybrid
Runtime / Layer	4.2s	4.6s (1.1x)	379.9s (90.5x)
Samples / Layer	1	20K	67M
Evaluations/ Layer	1	5	16K

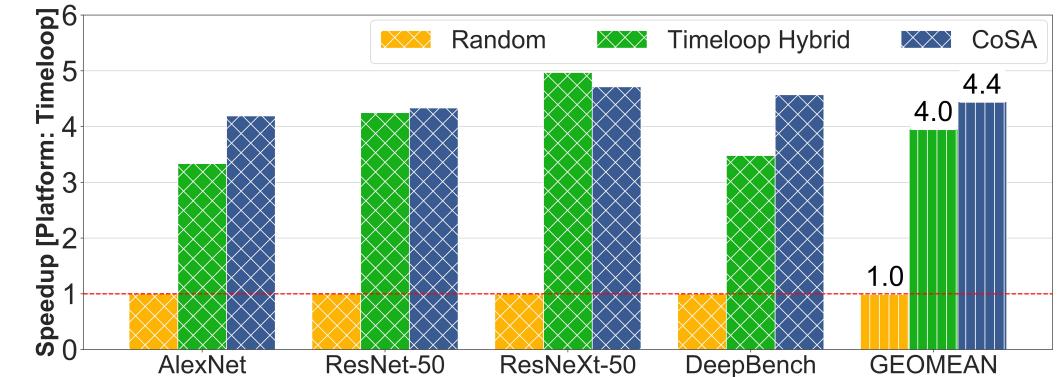
- Generates schedules within seconds
- Significantly reduces the number of samples and evaluations

CoSA generalizes to different architectures

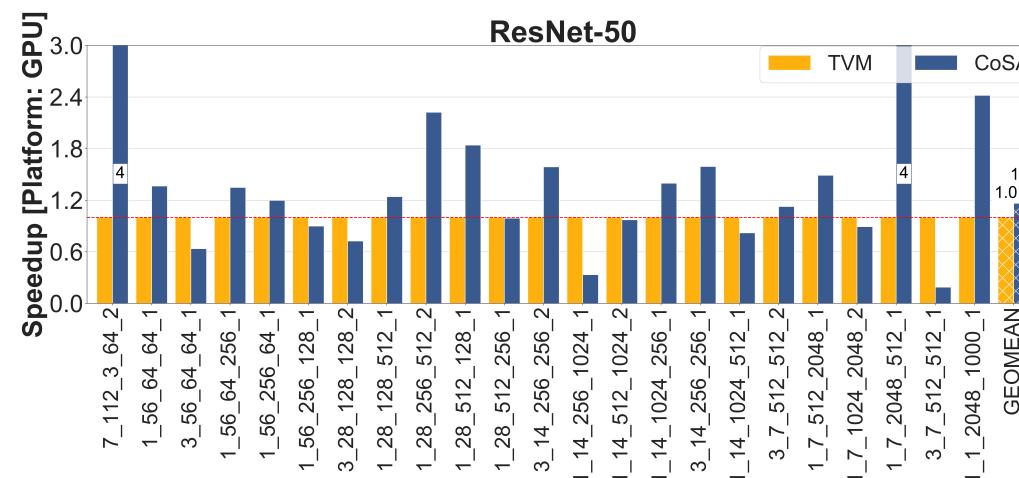
- Larger Buffers – 1.4x speedup



- 8x8 PEs – 1.1x speedup



- GPU – 1.2x speedup, 2500x faster time-to-solution over TVM (50 samples)



Conclusion

- We formulate DNN accelerator scheduling as a constrained optimization that can be solved in ***one shot***.
- We take a ***communication-oriented*** approach in the formulation and exposes the cost through clearly-defined objective functions.
- We demonstrate that CoSA can ***quickly*** generate ***high-performance*** schedules outperforming state-of-the-art approaches.

Github: <https://github.com/ucb-bar/cosa>

Questions?

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