

SWEN 563 Real-Time and Embedded Systems

Project 2b Demo

Student names: _____

Section: _____

1. Each servo can be manually positioned to 6 approximately even positions (using the left and right commands).
2. User commands work correctly for both servos:
 - p for pause
 - c for continue
 - r for right when paused
 - l for left when paused
 - n for do nothing
 - b for begin again (restart)
3. Demonstrate independent recipe operation for the two servos (servos obviously doing different recipes).
4. Includes required test recipe snippets in demo.

Default time delay
Default loop behavior

9.3 second delay
Verify moves to all possible positions